

# Rushi Notaria

(847) 532-4488 | rnotaria776@gmail.com | github.com/rnotaria | rushinotaria.com

## WORK EXPERIENCE

---

### Raytheon Technologies: Collins Aerospace

July 2019 – Present

*Software Engineer*

- Developed backend software using C to decode and parse real-time satellite data and integrate it for use on multi-function displays in search and rescue helicopters
- Saved the company hundreds of man-hours per year by automating several tests using Python image comparison techniques between a golden image and the screen capture of the display unit using a new software build
- Refined a fail-safe method of determining helicopter position using motion sensors in case of GPS malfunction which was activated in a recent rescue mission saving two lives

## PROJECT HIGHLIGHTS

---

### Vehicle Maintenance Tracker

- Designed an interactive React web app with over 100 users that simplifies vehicle maintenance tracking with features such as upcoming services, instructions, and the ability to add custom tasks
- Users can save records on services done to their individual accounts in order to maintain a detailed vehicle history

### Arbitrage Trading Bot

- Developed code to detect price variations among different cryptocurrency exchanges and simultaneously buy and sell assets leading to a net profit of 60% in just six months

### Machine Learning: Satellite Image Classification

- Trained a neural network using TensorFlow to predict the location of a Google Maps satellite image taken within the United States with an accuracy of 44% proving this concept is feasible with enough training data and computational power

### UAV Navigation and Control Project

- Implemented a C++ controller for a quadrotor that simulates a firefighting drone by autonomously tracking an object and transporting it to a desired location while demonstrating collision avoidance

## RESEARCH EXPERIENCE

---

### University of Illinois at Urbana-Champaign

September 2018 – January 2019

*Graduate Research – Reinforcement Learning*

- Applied reinforcement learning and dynamics of soft robotics to control the motion of a robotic “snake” consisting of numerous independent links

### University of Illinois at Urbana-Champaign

April 2017 – September 2017

*Undergraduate Research – Numerical Analysis*

- Used numerical methods to study and simplify computationally heavy problems using model order reduction techniques

## EDUCATION

---

### University of Illinois at Urbana-Champaign

May 2019

*M.S. in Aerospace Engineering (Computer Science Focus)*

### University of Illinois at Urbana-Champaign

May 2018

*B.S. in Aerospace Engineering (Computer Science Focus)*

---

**Programming Languages:** C/C++ | Python | Java | Ada | SQL | JavaScript (React.js)

**Technical Skills:** Git | Subversion | Agile | Jira | Machine Learning | AWS (S3, EC2, Lambda)