

Lista 1 - Instrumentação de Controle

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1a) Histograma na Figura 1. Dados gerados ao final do relatório (Apêndice).

b) $\hat{\mu} = 227,271 \quad \hat{\sigma} = 3,043$

Os valores obtidos de $\hat{\mu}$ e $\hat{\sigma}$ diferem de μ e σ , pois foi tomada uma amostra finita da variável aleatória. Espera-se que $\hat{\mu}$ e $\hat{\sigma}$ converjam para μ e σ quando o número de amostras tender ao infinito.

c) O valor de $\sigma = 3V$ se explica também pela própria variância da tensão RMS da rede, para além daquela do voltímetro. Nesse sentido, pode-se inferir que o comportamento probabilístico da rede introduz mais variância ao sistema que o instrumento de medição.

2.

a) $f(x) = \begin{cases} \frac{1}{10}, & \text{se } 0 \leq x \leq 10 \\ 0, & \text{caso contrário} \end{cases}$

Poderemos verificar o resultado para a função distribuição acumulada $F(x) = \int_{-\infty}^x f(x) dx$ para a qual esperamos

$$F(\infty) = \lim_{x \rightarrow \infty} F(x) = 1$$

$$F(\infty) = \int_{-\infty}^{\infty} f(x) dx = \int_0^{10} \frac{1}{10} dx = \left[\frac{1}{10} \cdot x \right]_0^{10} = 1$$

b) Histograma na Figura 2.b.

Não, a forma do histograma não é idêntica à função do item "a". Para que isso ocorresse, a frequência relativa de cada intervalo do histograma deveria ser igual. Como foram tomados 1000 somostros, espera-se que haja, de fato, um desrepônia em relação à função do item "a".

c) Observa-se, no histograma, que os valores se limitaram aos intervalos $[4,56, 5,59]$. Isto é natural, uma vez que se tomou o valor médio de uma variável aleatória contínua uniformemente distribuída no intervalo $[0, 10]$, cujo valor intermediário é 5.

3.

a) 0,5 mm. A incerteza na medição não pode ser maior, já que a resolução corresponde à menor mensuração que se pode fazer.

$$b) \bar{X} = 162,25 \pm 0,25 \text{ mm}$$

Incerteza: 0,25 mm. Resolução: 0,5 mm

A diferença entre a resolução e a incerteza se deve ao fato de que o instrumento de medição último (régua) é comológico. Com isso,

c) O paquímetro indicaria uma medida entre 1,60 mm e 1,65 mm, pois ele tem menor divisão em décimos de milímetro.
Resolução = 0,1 mm. Incerteza = 0,05 mm

O motivo é o mesmo do item b).

- d) A resolução e a incerteza permanecem inalteradas
e) A lente altera o valor medido. O paquímetro, a resolução

$$4. O(I) = KI + a + N(I)$$

Da definição de sensibilidade:

$$\frac{dO}{dI} = K + \frac{dN}{dI} \quad (I)$$

Pela condição imposta:

$$\frac{d\Omega}{dI} = K \quad (\text{II})$$

Igualando (I) e (II), temos:

$$\frac{dN}{dI} + K = K \Rightarrow \frac{dN}{dI} = 0 \quad (\text{III})$$

De (III) concluímos que $N(I)$ assume um valor de máximo.

5. $\bar{K} = 3,1 \cdot 10^6 \Omega$; $\bar{\beta} = -2254,473 \text{ K}$; $\sigma_K = 1,2 \cdot 10^5 \Omega$; $\sigma_\beta = 11,94 \text{ K}$

a) $R(\theta) = K \exp\left(\frac{\beta}{\theta}\right)$; $I_{\min} = -55^\circ\text{C} = 218 \text{ K}$; $\theta_{\max}^{I_{\max}} = 120^\circ\text{C} = 393 \text{ K}$; $Q_{\min} = 100 \Omega$; $Q_{\max} = 10 \text{ k}\Omega$

$$K = (Q_{\max} - Q_{\min}) / (I_{\max} - I_{\min}) = 56,57 \Omega \text{ K}^{-1}$$

$$a = Q_{\min} - K \cdot I_{\min} = -1,22 \cdot 10^4 \Omega$$

$$\Rightarrow \Omega(I) = 56,57 \cdot I - 1,22 \cdot 10^4$$

b)

$$R_{\text{ideal}}(\theta) = 56,57 \theta - 1,22 \cdot 10^4$$

$$N(\theta) = R(\theta) - R_{\text{ideal}}(\theta) = K \exp\left(\frac{\beta}{\theta}\right) - 56,57 \theta + 1,22 \cdot 10^4$$

Note que:

$$\frac{dN}{d\theta}(\theta) = -\frac{K\beta \exp(\beta/\theta)}{\theta^2} - 56,57 = \frac{6,99 \cdot 10^9}{\theta^2} \exp\left(-\frac{2254}{\theta}\right) - 56,57$$

$$\frac{d^2N}{d\theta^2} = \frac{(1,58 \cdot 10^{13}) \cdot \exp(-2254/\theta)}{\theta^4} - \frac{1,39}{\theta^2} \exp(-2254/\theta)$$

Observe que $\frac{d^2N}{d\theta^2} > 0 \quad \forall \theta \in [218, 393 \text{ K}]$

Com isso, verifica-se que a função é monótona, portanto o valor máximo absoluto é único.

c) Resolvendo $\frac{dN(\theta)}{d\theta} = 0$, temos:

$$\hat{\theta}_N = 316,9 \text{ K}$$

$$\hat{N} = -3173 \Omega$$

$$\hat{N}_{\% \text{ fsd}} = \frac{\hat{N}}{R_{\max} - R_{\min}} \cdot 100\% = -31,73\%$$

d) $R = K \cdot \exp(\beta/\theta) = 3,1 \cdot 10^6 \cdot \exp(-2254/\theta)$

$$\dot{R}(0) = \frac{dR(0)}{d\theta} = \frac{6,989}{\theta^2} \cdot \exp(-2254/\theta)$$

$$\dot{R}(\hat{\theta}_N) = \dot{R}(316,9) = 56,57 \Omega \text{ K}^{-1}$$

Este é, com efeito, o valor calculado no item a), com esperávomos pela questão 4.

e) $\sigma_R = \sqrt{\frac{\partial R^2}{\partial \beta} \sigma_\beta^2 + \frac{\partial R^2}{\partial K} \sigma_K^2}$

$$\sigma_K = 1,2 \cdot 10^5 \Omega \quad \sigma_\beta = 11,94 \text{ K}$$

$$\frac{\partial R}{\partial \beta} = \frac{1}{\theta} \cdot \exp(\bar{\beta}/\bar{\theta}) \quad \frac{\partial R}{\partial K} = \exp(\bar{\beta}/\bar{\theta})$$

Para $\bar{\theta} = 100^\circ\text{C} = 373 \text{ K}$: $\frac{\partial R}{\partial \beta} = 19,71 \quad \frac{\partial R}{\partial K} = 0,0024$

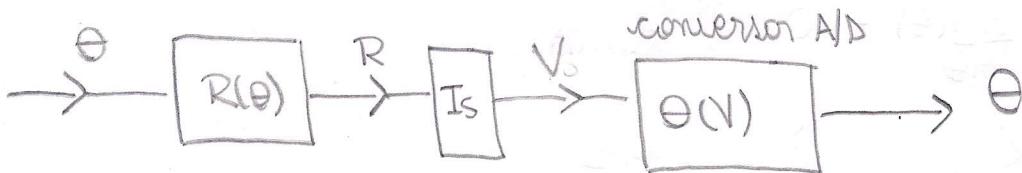
$$\therefore \sigma_R = 369,30 \Omega$$

Para $\bar{\theta} = \hat{\theta}_N = 316,9 \text{ K}$: $\frac{\partial R}{\partial \beta} = 7,951 \quad \frac{\partial R}{\partial K} = 8,13 \cdot 10^{-4}$

$$\therefore \sigma_R = 136,09 \Omega$$

f) Ver Figura 5 f na seção de figuras.

g) O conversor AD pode funcionar como elemento compensador de não linearidade.



$$\Theta(V) = \frac{V}{I_S} \cdot \bar{R}^{-1}(\Theta)$$

$$\text{Note que } R(\Theta) \cdot \bar{R}^{-1}(\Theta) = \Theta$$

h) Introduz-se uma nova fonte de variação no sistema.

Observe que $R(373) = 7352 \Omega$ Para $I_S = 0,1 \text{ mA}$, temos:

$$V = R \cdot I_S = 7,352 \Omega \cdot 0,1 \text{ mA} = 0,7352 \text{ V.}$$

No entanto, a saída do conversor é 0,7352V e a aproximação para 0,7V (perda de informação) levará a uma descrença na temperatura medida.

$$6. R_T = R_0 (1 + \alpha T)$$

$$\bar{R}_0 = 100, \bar{\alpha} = 3,91 \cdot 10^3, \bar{T} = 37^\circ\text{C}, \sigma_{R_0} = 0,29, \sigma_\alpha = 2,94 \cdot 10^{-5}$$

$$\bar{R}_T = \bar{R}_0 (1 + \bar{\alpha} \bar{T}) = 114,5 \Omega$$

$$\frac{\partial R_T}{\partial R_0} = 1 + \bar{\alpha} \bar{T} = 1,145 \quad \frac{\partial R}{\partial \alpha} = \bar{R} \bar{T} = 3700$$

$$\Rightarrow \sigma_{R_T} = \sqrt{\frac{\partial R_T^2}{\partial R_0} \cdot \sigma_{R_0}^2 + \frac{\partial R_T^2}{\partial \alpha} \cdot \sigma_\alpha^2} = 0,3493$$

$$V = V_s \cdot r \left(\frac{R_T}{R_1} - 1 \right) \text{ com: } \begin{cases} \bar{V}_s = 10 & \bar{R}_1 = 100 & \bar{r} = 0,01 \\ \sigma_{V_s} = 0 & \sigma_{R_1} = 0,89 & \sigma_r = 1,94 \cdot 10^{-4} \end{cases}$$

$$\bar{V} = \bar{V}_s \bar{r} \left(\frac{\bar{R}_T}{\bar{R}_1} - 1 \right) = 0,0145$$

$$\frac{\partial V}{\partial R_1} = - \bar{V}_s \bar{r} \frac{\bar{R}_T}{(\bar{R}_1)^2} = -0,0011 \quad \frac{\partial V}{\partial r} = \bar{V}_s \left(\frac{\bar{R}_T}{\bar{R}_1} - 1 \right) = 0,0144 \quad \frac{\partial V}{\partial R_T} = \bar{V}_s \bar{r} = 0,0144$$

$$\sigma_V = \sqrt{\frac{\partial V^2}{\partial R_1} \cdot \sigma_{R_1}^2 + \frac{\partial V^2}{\partial r} \cdot \sigma_r^2 + \frac{\partial V^2}{\partial R_T} \cdot \sigma_{R_T}^2} = 0,0011$$

$$n = K_1 V + b_1 \quad K_1 = 6522 \quad \sigma_{K_1} = 0 \quad b_1 = 0 \quad \sigma_{b_1} = 0,5$$

$$\sigma_{b_1} = \sigma_{b_1} / \sqrt{3} = 0,289$$

$$\bar{n}_b = [\bar{K}_1 \bar{N} + \bar{b}_1] = 94 \text{ (com arredondamento)}$$

$$\frac{\partial n}{\partial b_1} = 1 \quad \frac{\partial n}{\partial V} = 6522$$

$$\sigma_n = \sqrt{\frac{\partial n^2}{\partial b_1} \cdot \sigma_{b_1}^2 + \frac{\partial n^2}{\partial V} \cdot \sigma_V^2} = 3,270$$

$$\Rightarrow \sigma_n = 3,264$$

$$T_m = K_2 n + b_2 \quad \bar{K}_2 = 0,391; \bar{b}_2 = 0; \sigma_{K_2} = \sigma_{b_2} = 0$$

$$\bar{T}_m = \bar{K}_2 \bar{n} + \bar{b}_2 = 36,75$$

$$\frac{\partial T_m}{\partial n} = \bar{K}_2 \quad \sigma_{T_m} = \sqrt{\frac{\partial T_m^2}{\partial n} \cdot \sigma_n^2} = 2,840$$

$$\epsilon = T - \bar{T}_m = 36,75 - 37 = -0,25^\circ C$$

$$\sigma_\epsilon = \sigma_{T_m} = 2,840^\circ C$$

b) $[\bar{T}_m - 3\sigma, \bar{T}_m + 3\sigma] = [28,23^\circ C, 45,28^\circ C]$

Sim, o valor verdadeiro está neste intervalo. No entanto, o sistema de medição não é adequado. Basta olhar o intervalo de confiança ($\approx 99,7\%$) acima para concluir que ele é longo demais para a aplicação.

c) σ_V na fórmula simplificada ($V = V_S R_d T$)

$$\sigma_V = \sqrt{\frac{\partial V^2}{\partial V_S} \cdot \sigma_{V_S}^2 + \frac{\partial V^2}{\partial r} \cdot \sigma_r^2 + \frac{\partial V^2}{\partial T} \cdot \sigma_T^2}$$

σ_V na fórmula original:

$$\sigma_V = \sqrt{\frac{\partial V^2}{\partial V_S} \cdot \sigma_{V_S}^2 + \frac{\partial V^2}{\partial r} \cdot \sigma_r^2 + \frac{\partial V^2}{\partial R_T} \cdot \sigma_{R_T}^2 + \frac{\partial V^2}{\partial R_1} \cdot \sigma_{R_1}^2}$$

Observa-se que a primeira expressão não leva em conta os desvios-padrões de R_0 e R_1 . A segunda leva, pois V é função de R_0 e R_1 é função de R_0 .

d) Entrada de Interferência

7.a) Graficamente, podemos obter:

$$T_p = 1,05 \text{ s} \quad M_p = 38,4\% = 0,384$$

Com isso, calculamos ζ e w_n

$$\zeta = -\frac{\ln(M_p)}{\sqrt{\pi^2 + (\ln(M_p))^2}} = 0,2916$$

$$\omega_d = \frac{\pi}{T_p} = 2,992 \text{ rad/s}$$

$$w_n = \frac{\omega_d}{\sqrt{1-\zeta^2}} = 3,128 \text{ rad/s}$$

$$G(s) = \frac{w_n^2}{s^2 + 2\zeta w_n s + w_n^2} = \frac{9,784}{s^2 + 18,24s + 9,784}$$

b) A Figura 7.b mostra o gráfico da função estimada.

Observa-se que ela se ajusta bem aos dados originais.

S.

a) $G_C(s) = K \quad G(s) = \frac{1}{\tau s + 1} \quad H(s) = \frac{1}{\tau_f s + 1}$

Pelo método da álgebra de blocos, escrevemos C/R:

$$\frac{C(s)}{R(s)} = \frac{G_C(s) \cdot G(s)}{1 + G_C(s) \cdot G(s) H(s)} = \frac{K \tilde{\tau}_F s + K}{\tilde{\tau} \cdot \tilde{\tau}_F s^2 + (\tilde{\tau} + \tilde{\tau}_F) s + K + 1}$$

$$E(s) = R(s) - C(s) = R(s) \left[1 - \frac{K \tilde{\tau}_F s + K}{\tilde{\tau} \cdot \tilde{\tau}_F s^2 + (\tilde{\tau} + \tilde{\tau}_F) s + K + 1} \right]$$

b) Pelo Teo do Valor final:

$$e(\infty) := \lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} (s E(s))$$

$$\lim_{S \rightarrow 0} SE(s) = \lim_{S \rightarrow 0} S \cdot \frac{\tilde{C} \tilde{C}_F s^2 + (\tilde{C} + \tilde{C}_F - K \tilde{C}_F) s + 1}{\tilde{C} \cdot \tilde{C}_F \cdot s^3 + (\tilde{C} + \tilde{C}_F) s^2 + (K+1)s}$$

$$= \frac{1}{K+1} = 0,01 \Rightarrow K = 99$$

c) $\frac{C(s)}{R(s)} = \frac{K \tilde{C}_F s + K}{\tilde{C} \tilde{C}_F s^2 + (\tilde{C} + \tilde{C}_F) s + K+1}$

Para $R(s)$ de grau unitário:

$$C(s) = \frac{1}{s} \cdot \frac{K \tilde{C}_F s + K}{\tilde{C} \tilde{C}_F s^2 + (\tilde{C} + \tilde{C}_F) s + K+1}$$

Ganho em regime permanente (A):

$$A = \lim_{S \rightarrow 0} S C(s) = \frac{K}{K+1}$$

Da expressão $(Y(s)/R(s))$ podemos encontrar ξ e ω_n :

$$\omega_n^2 = \frac{K+1}{\tilde{C} \tilde{C}_F} \quad \xi = \frac{1}{2\omega_n} \cdot \frac{\tilde{C} + \tilde{C}_F}{\tilde{C} \tilde{C}_F}$$

Para $\tilde{C} = 10 \text{ s rad}^{-1}$, $\tilde{C}_F = 2 \text{ s rad}^{-1}$ e $K = 99$, temos:

$$\omega_n = 2,236 \text{ rad/s} \quad \xi = 0,1342$$

d) $C(s) = \frac{1}{s} \cdot \frac{\frac{K}{\tilde{C}} s + \frac{K}{\tilde{C} \tilde{C}_F}}{s^2 + 2\xi \omega_n s + \omega_n^2} = \frac{1}{s} \left[\frac{\omega_n^2}{s^2 + 2\xi \omega_n s + \omega_n^2} + \frac{\frac{K}{\tilde{C}} s - \frac{1}{\tilde{C} \tilde{C}_F}}{s^2 + 2\xi \omega_n s + \omega_n^2} \right]$

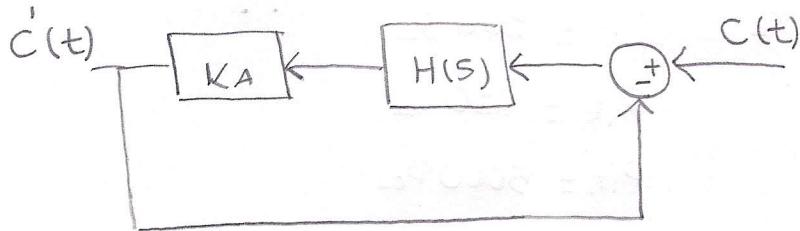
$$C(t) = \mathcal{L}^{-1}\{C(s)\} = 1 - \frac{1}{\sqrt{1-\xi^2}} \cdot e^{-\xi \omega_n t} \cdot \sin(\omega_n \sqrt{1-\xi^2} t + \phi_1) + \\ + \frac{1}{\tilde{C} \tilde{C}_F \omega_n^2} + \frac{1}{\omega_n \sqrt{1-\xi^2}} \cdot \frac{(\frac{1}{\tilde{C} \tilde{C}_F} - \xi \omega_n)^2 + \omega_n^2(1-\xi^2)}{\omega_n^2} e^{-\xi \omega_n t} \sin(\omega_n \sqrt{1-\xi^2} t + \phi_2)$$

Gráficamente podemos encontrar M_p e T_p da resposta $c(t)$:

$$M_p = 3,5$$

$$T_p = 0,72$$

e) Abaixo, o recorte do sistema de medição



$$\frac{C'(s)}{C(s)} = H_2(s) = \frac{K_A H(s)}{1 + K_A H(s)} = \frac{K_A}{\tilde{\tau}_F s + K_A + 1}$$

$$\frac{C(s)}{R(s)} = \frac{G_C(s) G(s)}{1 + G_C(s) G(s) H_2(s)} = \frac{K \tilde{\tau}_F s + K + K K_A}{\tilde{\tau}^2 \tilde{\tau}_F s + (\tilde{\tau} + \tilde{\tau}_F + K_A \tilde{\tau}) s + K_A + K K_A + 1}$$

Nova constante de tempo:

$$H_2(s) = \frac{K_A}{\tilde{\tau}_F s + K_A + 1} = \frac{\frac{K_A}{K_A + 1}}{\frac{\tilde{\tau}_F}{K_A + 1} s + 1} \Rightarrow \tilde{\tau}_{F\text{ novo}} = \frac{\tilde{\tau}_F}{K_A + 1}$$

Nova sensibilidade:

$$\lim_{s \rightarrow 0} H_2(s) = \lim_{s \rightarrow 0} \left[\frac{K_A}{\tilde{\tau}_F s + K_A + 1} \right] = \frac{K_A}{K_A + 1}$$

$$f) \tilde{\tau}_{F\text{ novo}} = \frac{\tilde{\tau}_F}{K_A + 1} = \frac{2}{K_A + 1} = 0,2 \Rightarrow K_A = 9$$

Com isso, a resposta transitoria fica mais rápida, como vemos:

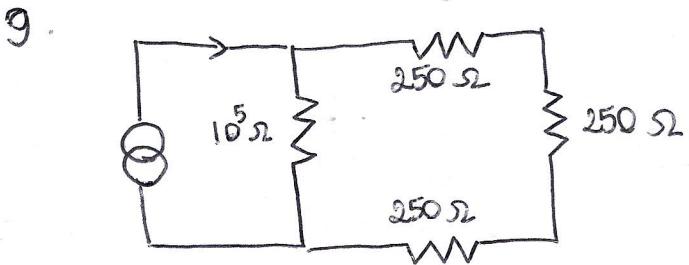
	ζ	ω_n	Mp%	Tp
Sistema antigo	0,134	2,24	353%	0,703
Sistema novo	0,380	6,71	59,9%	0,307

Erro em regime permanente:

$$e(\infty) = \lim_{s \rightarrow 0} s E(s) = \lim_{s \rightarrow 0} s \left[\frac{1}{s} - \frac{K \tilde{\tau}_F s + K + K K_A}{\tilde{\tau} \cdot \tilde{\tau}_F^2 + (\tilde{\tau} + \tilde{\tau}_F + K_A \tilde{\tau}) s + K_A + K K_A + 1} \right]$$

$$= 1 - \frac{K + K K_A}{K_A + K K_A + 1} = -0,0988$$

g) Rode-se projeto um compensador em avanco-atraso.



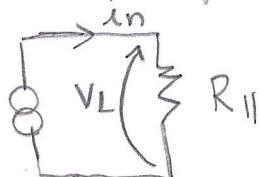
$$R_N = 10^5 \Omega$$

$$R_C = 500 \Omega$$

$$R_R = 250 \Omega$$

$$P_{in} = 5000 \text{ Pa}$$

Circuito equivalente



$$R_{II} = (R_C + R_R) \parallel R_N$$

$$\Rightarrow R_{II} = \frac{R_N (R_C + R_R)}{R_N + R_C + R_R}$$

Divisor de tensão:

$$V_R = \frac{R_R R_{II} \cdot V_L}{R_C + R_R + R_{II}} = \frac{R_R}{R_C + R_R} \cdot R_{II} \cdot i_{in} = \frac{R_N}{R_N + R_C + R_R} \cdot R_R i_{in}$$

Substituindo os valores: $V_R = 0,9926 \cdot \bar{V}$, onde $\bar{V} = R_R i_{in}$

Equação do transmissor:

$$K_L = (20 \text{ mA} - 4 \text{ mA}) / 10^4 \text{ Pa} = 1,6 \cdot 10^3 \text{ mA/Pa}$$

$$a_1 = 4 \text{ mA}$$

$$i = K_L \cdot P_{in} + a_1 = 1,6 \cdot 10^6 \cdot 5 \cdot 10^3 + 4 \cdot 10^3 = 0,012 \text{ A}$$

Equação indicador

$$K_2 = 10^4 / (5-1) = 2500 \text{ Pa/V}$$

$$a_2 = -2500 \cdot 1 = -2500 \text{ Pa}$$

Tensão verdadeira:

$$\bar{V} = R_R \cdot i = 250 \cdot 0,012 = 3 \text{ V} \Rightarrow \bar{P} = K_2 \bar{V} + a_2 = 2500 \cdot 3 - 2500$$

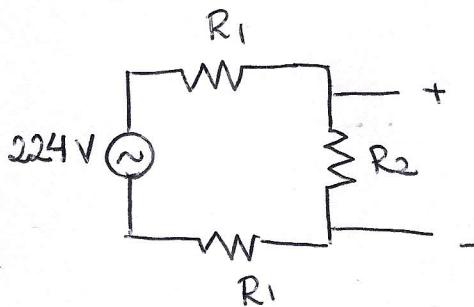
$$= 5000 \text{ Pa}$$

Tensão medida:

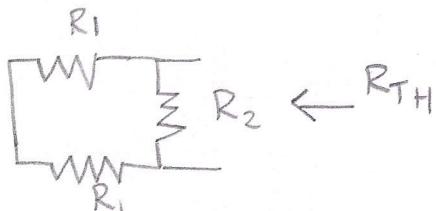
$$V_R = 0,9926 \bar{V} = 2,978 \text{ V} \Rightarrow P_m = K_2 V_R + a_2 = 4,944 \cdot 10^3 \text{ Pa}$$

$$\epsilon = P_m - \bar{P} = 4,944 \cdot 10^3 - 5 \cdot 10^3 = -56 \text{ Pa}$$

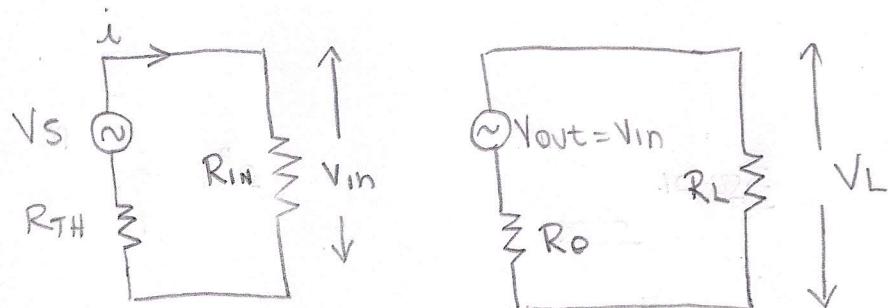
10.



a)



$$R_{TH} = 2R_1 \parallel R_2 = \frac{2R_1 R_2}{2R_1 + R_2}$$



$$V_{in} = \frac{R_{IN}}{R_{TH} + R_{IN}} \cdot V_s \quad V_L = \frac{R_L}{R_o + R_L} \cdot V_{in}$$

$$\Rightarrow V_L = \frac{R_{IN}}{R_{TH} + R_{IN}} \cdot \frac{R_L}{R_o + R_L} \cdot V_{in}$$

b)

$$\frac{\frac{10^9}{R_{TH} + 10^9} \cdot \frac{10^4}{100 + 10^4} \cdot 224}{2,5} \Rightarrow R_{TH} = 8,77 \cdot 10^9 \Omega$$

Corrente no transmissor: $i = V_s / R_{TH} = 5,17 \cdot 10^{-9} A$

Escolhendo $P_{R2} = 5W \Rightarrow R_2 = 5/i^2 = 1,87 \cdot 10^7 \Omega$

$$R_{TH} = 8,77 \cdot 10^9 = \frac{2 \cdot R_1 R_2}{2R_1 + R_2} \Rightarrow R_1 = 4,34 \cdot 10^{10} \Omega$$

$$P_{R2} = 1,157 \cdot 10^{-6} W < 1/8 W$$

Figuras

Figura 1

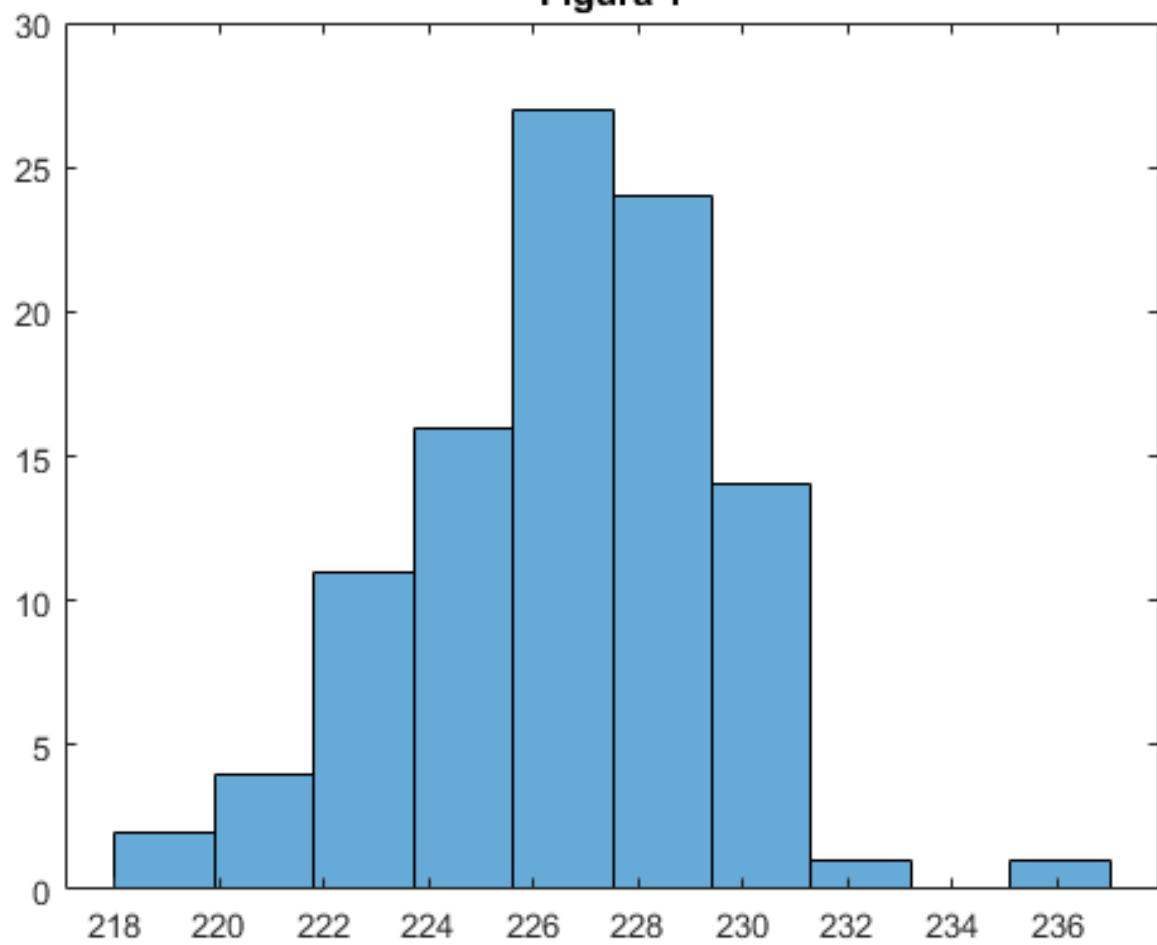


Figura 2 b)

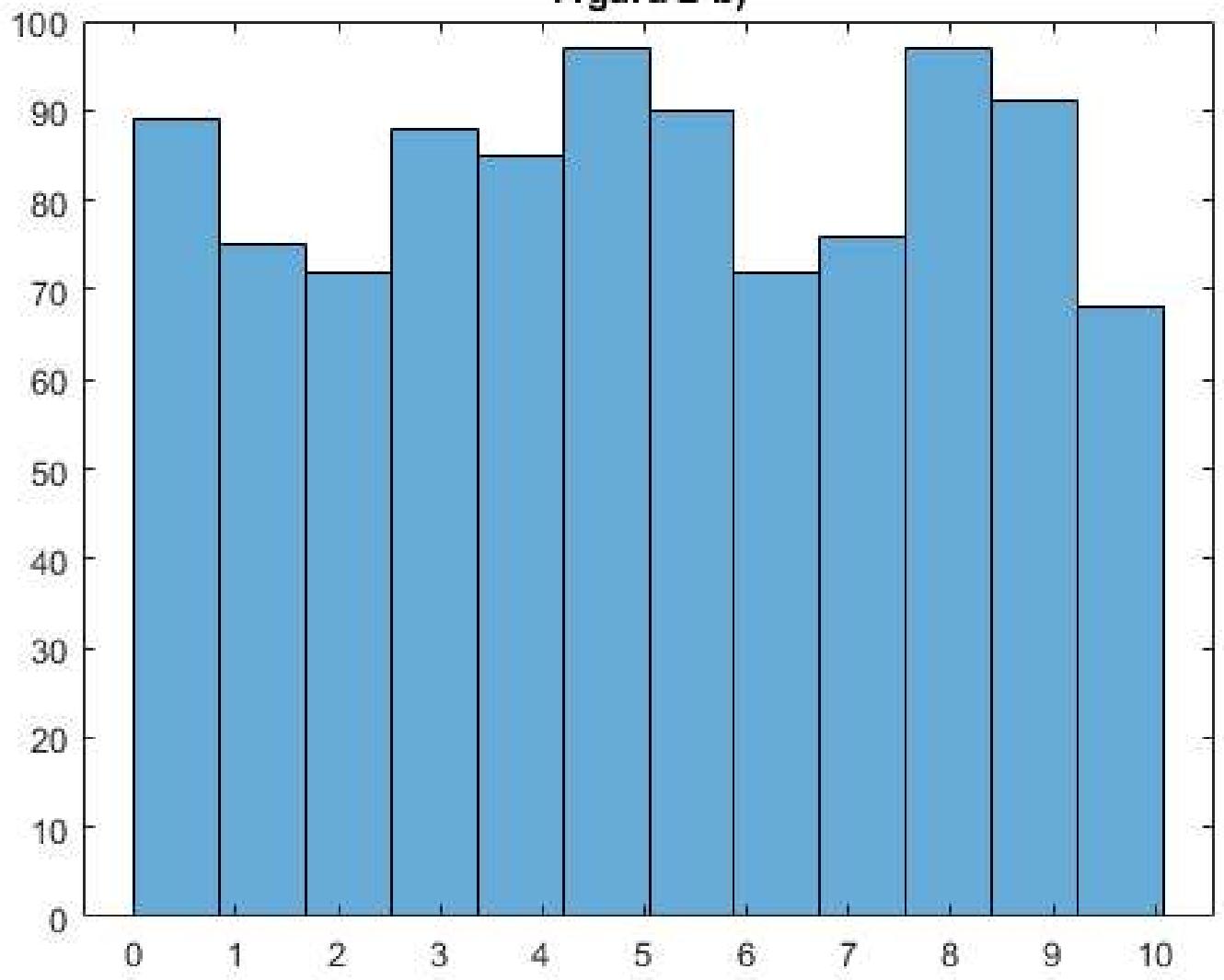


Figura 2 c)

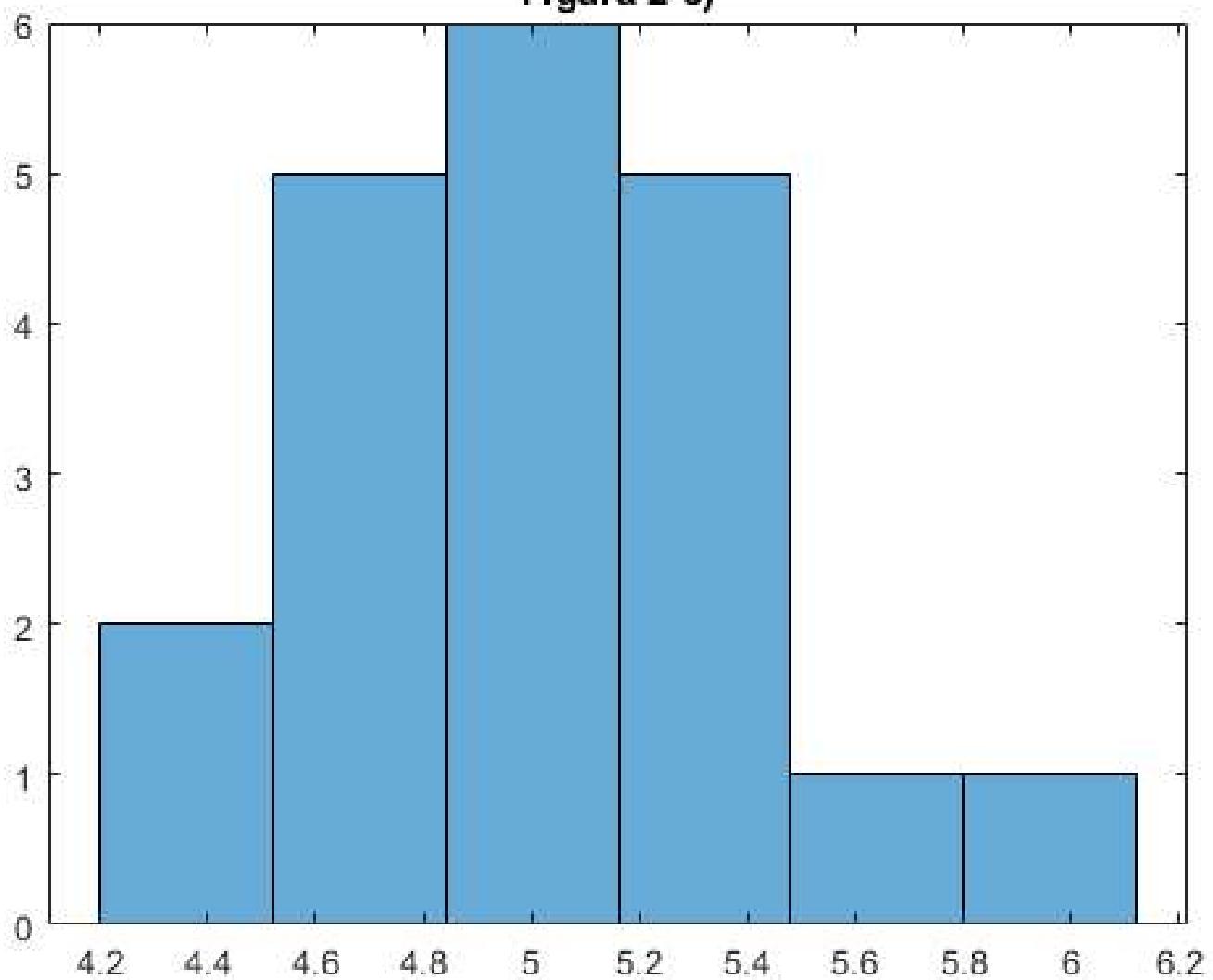


Figura 5 f

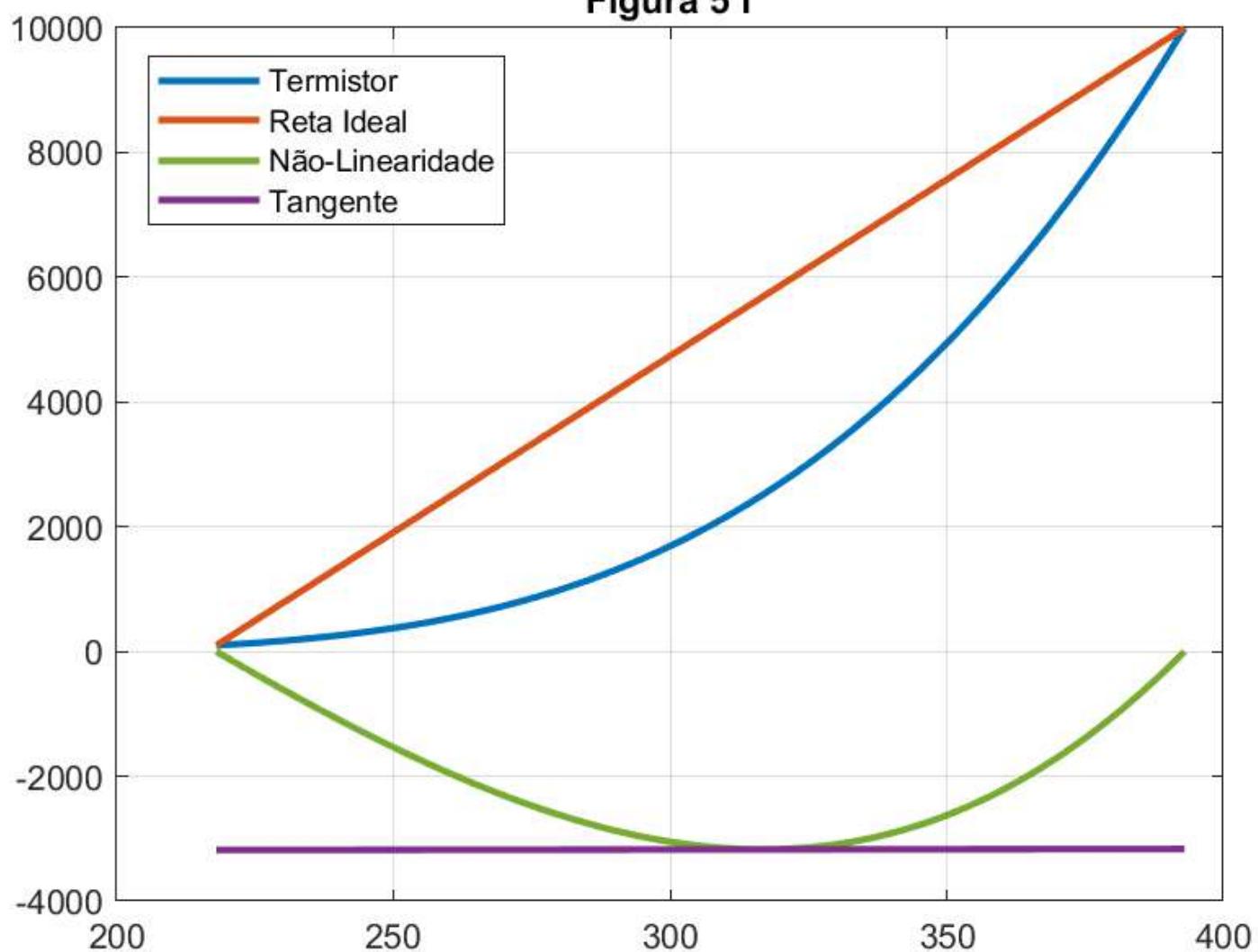
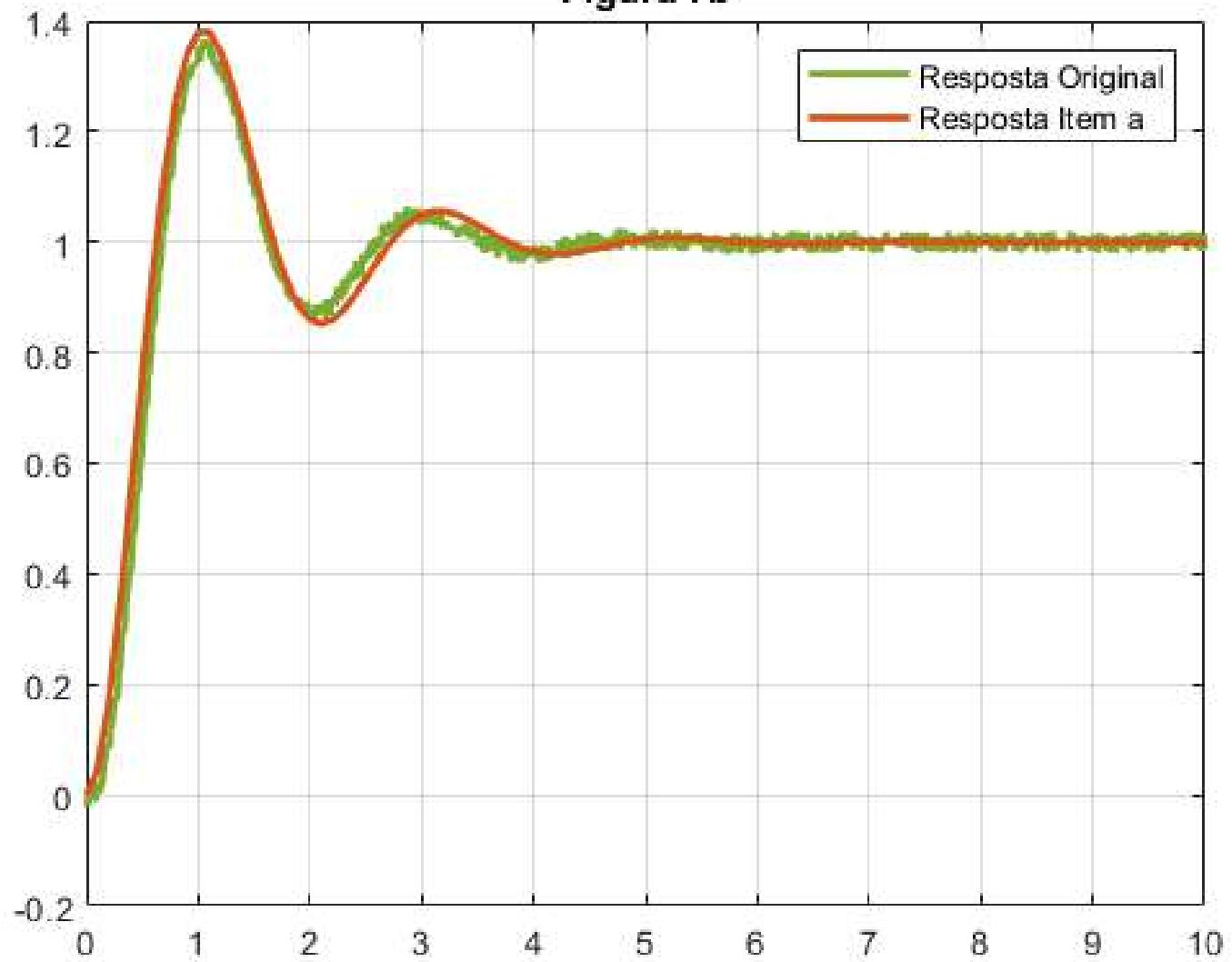


Figura 7b



APÊNDICE

Dados do Item 1 a)

Número	Tensão (em Volts)
1	221,3646
2	225,728
3	229,3317
4	224,8582
5	231,7539
6	224,3351
7	233,4225
8	224,9235
9	227,2979
10	231,3049
11	230,7002
12	224,7271
13	229,2157
14	223,6569
15	221,8824
16	228,9835
17	221,8111
18	220,5858
19	226,8199
20	231,1571
21	230,6534
22	222,5148

23	227,1118
24	229,4086
25	229,9216
26	231,6822
27	231,7587
28	229,5689
29	222,7266
30	227,1191
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