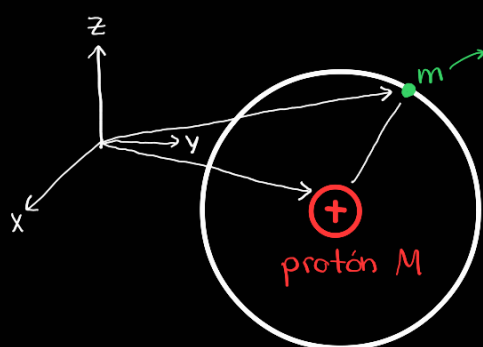


# Átomo de Hidrógeno



carga protón  $+e$

carga electrón  $-e$

$$e = 1.6 \times 10^{-19} \text{ C}, \quad e = 4.8 \times 10^{-10} \text{ esu}$$

$$m = 9.1 \times 10^{-28} \text{ g}$$

$$M \approx 1830m$$

$$M \gg m$$

6-dimensiones

(6 grados de libertad)

$$\begin{array}{cccccc} p_{Nx} & p_{Ny} & p_{Nz} & p_{ex} & p_{ey} & p_{ez} \\ x_N & y_N & z_N & x_e & y_e & z_e \end{array}$$

$$H = \frac{\vec{p}_N^2}{2M} + \frac{\vec{p}_e^2}{2m} + \frac{(e)(-e)}{|\vec{r}_N - \vec{r}_e|}$$

$$H = \frac{\vec{p}_N^2}{2M} + \frac{\vec{p}_e^2}{2m} - \frac{(e)(-e)}{|\vec{r}_N - \vec{r}_e|} \quad \dots (1)$$

interacción Coulombiana

$$\frac{dx_e}{dt} = \frac{\partial H}{\partial p_x} = \frac{p_{ex}}{m}, \quad \frac{dp_{ex}}{dt} = -\frac{\partial H}{\partial x_e} = +\frac{\partial}{\partial x_e} \frac{e^2}{|\vec{r}_N - \vec{r}_e|} + \frac{1}{2} \frac{2(x_N - x_e)}{(|\vec{r}_N - \vec{r}_e|)^{3/2}}$$

$$|\vec{r}_N - \vec{r}_e| = \sqrt{(x_N - x_e)^2 + (y_N - y_e)^2 + (z_N - z_e)^2}$$

Relativa

$$\vec{r} = \vec{r}_e - \vec{r}_N$$

$$\frac{1}{\mu} = \frac{1}{m} + \frac{1}{M} \quad \text{relativa}$$

$$\mu = \frac{mM}{m+M}$$

$$\vec{R} = \frac{m\vec{r}_e + M\vec{r}_N}{m+M}$$

$$M_T = m + M \quad \text{Total}$$

$$\vec{p} = \mu \dot{\vec{r}}$$

relativo

$$\vec{P} = M_T \dot{\vec{R}}$$

total

$$\vec{p} = \mu \dot{\vec{r}}_e - \mu \dot{\vec{r}}_N = \frac{\mu}{m} m \dot{\vec{r}}_e - \frac{\mu}{M} M \dot{\vec{r}}_N$$

$$\Rightarrow \vec{p} = \left( \frac{M}{m+M} \right) \vec{p}_e - \left( \frac{m}{m+M} \right) \vec{p}_N$$

$$\Rightarrow \vec{p} = M_T \left( \frac{m \dot{\vec{r}}_e + M \dot{\vec{r}}_N}{M_T} \right) = \vec{p}_e + \vec{p}_N$$

$$\vec{p}_e = \frac{m}{M_T} \vec{P} + \vec{p}$$

$$\vec{p}_N = \frac{M}{M_T} \vec{P} - \vec{p}$$

$$\begin{aligned} \therefore H &= \frac{1}{2M} \left( \frac{M}{M_T} \vec{P} - \vec{p} \right)^2 + \frac{1}{2m} \left( \frac{m}{M_T} \vec{P} + \vec{p} \right)^2 - \frac{e^2}{|\vec{r}|} \\ &= \frac{1}{2M} \left( \frac{M^2}{M_T^2} \vec{P}^2 - 2 \frac{M}{M_T} \vec{P} \cdot \vec{p} + \vec{p}^2 \right) + \frac{1}{2m} \left( \frac{m^2}{M_T^2} \vec{P}^2 + 2 \frac{m}{M_T} \vec{P} \cdot \vec{p} + \vec{p}^2 \right) - \frac{e^2}{|\vec{r}|} \end{aligned}$$

$$\Rightarrow H = \underbrace{\frac{\vec{P}^2}{2M}}_{CM} + \underbrace{\frac{\vec{p}^2}{2\mu}}_{\text{relativo}} - \frac{e^2}{|\vec{r}|} \quad \text{iNo depende de } \vec{R}!$$

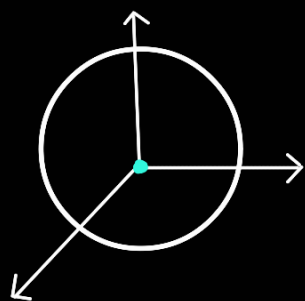
Note que,

$$\dot{\vec{p}} = -\frac{\partial H}{\partial \vec{R}} = -\nabla_{\vec{R}} H = -\left( \frac{\partial H}{\partial x}, \frac{\partial H}{\partial y}, \frac{\partial H}{\partial z} \right) \xrightarrow{0} \quad \text{i.e. el momento se conserva}$$

$$\dot{\vec{R}} = \frac{\partial H}{\partial \vec{p}} = \nabla_{\vec{p}} H = \frac{\vec{p}}{M}, \quad \vec{R} = (x, y, z)$$

$\therefore \vec{p} = M \dot{\vec{R}}$ . Es decir, como  $\dot{\vec{p}} = \frac{d\vec{p}}{dt} = 0$  con  $\vec{p} = \vec{p}_0$  cte y  $\dot{\vec{R}} = \frac{\vec{p}_0}{M}$  tiene vel constante el sistema no depende de la posición del centro de masa.

Más aún, como  $M \gg m$  entonces  $M \approx M_T$ ,  $\frac{m}{M} \ll 1 \Rightarrow \frac{m}{M_T} \ll 1$ . Consecuentemente,  $\mu = \frac{mM}{M+m} \approx \frac{mM}{M} = m$ . Además,  $\frac{m}{M} \ll 1 \Rightarrow \vec{R} \approx \vec{r}_N$ . Esto último reduce nuestro hamiltoniano a



$$H = \frac{\vec{p}^2}{2m} - \frac{e^2}{r}, \quad \vec{r} = (x, y, z)$$

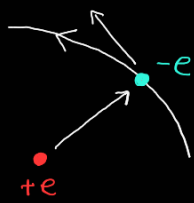
dados cond. inicial  $\vec{p}_0, \vec{r}_0$ .

$$\Rightarrow \vec{E} = \frac{\vec{p}_0^2}{2m} - \frac{e^2}{r_0} = \frac{\vec{p}^2}{2m} - \frac{e^2}{r}, \quad \frac{dE}{dt} = 0$$

similar al problema del Sol y Tierra

## Momento angular

$$\vec{L} = \vec{r} \times \vec{p}$$



$$\frac{d\vec{r}}{dt} = \frac{\partial H}{\partial \vec{p}} = \frac{\vec{p}}{m}$$

$$L = \vec{r}_0 \times \vec{p}_0 = L_0, \text{ ¡constante!}$$

$$\frac{d\vec{p}}{dt} = -\frac{\partial H}{\partial \vec{r}} = -\frac{e^2}{r^2} \hat{r}, \quad \hat{r} = \frac{\vec{r}}{r}$$

Es decir de forma clásica  $\vec{p} = m \frac{d\vec{r}}{dt}$ ,  $\vec{r} = r \hat{r}$

$$\frac{dL}{dt} = 0$$

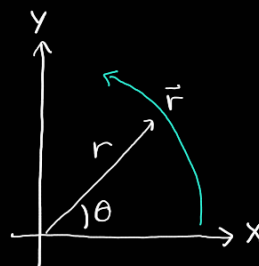
$$\frac{d\vec{r}}{dt} = \frac{dr}{dt} \hat{r} + r \frac{d\hat{r}}{dt}$$

Demuestre que  $\frac{\vec{p}^2}{2m} = \frac{1}{2} m \left( \frac{dr}{dt} \right)^2 + \frac{L^2}{2mr^2}$

$$L = mr^2 \frac{d\theta}{dt} \quad \text{velocidad angular } \omega = \frac{d\theta}{dt}$$

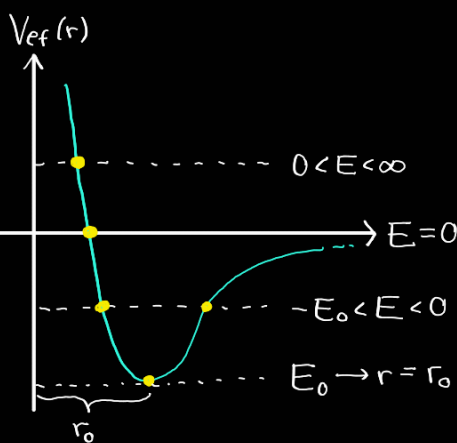
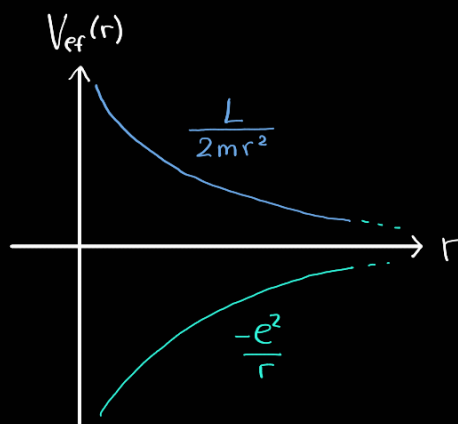
$$\alpha \rightarrow \frac{d\theta}{dt} = \frac{L}{mr^2}$$

Por lo tanto, para el Hamiltoniano del sistema será dado por



$$H = \frac{\vec{p}_r^2}{2m} + \left[ \frac{L^2}{2mr^2} + \frac{e^2}{r} \right] = T + V_{\text{ef}}(r) \rightsquigarrow \text{1 partícula en 1D } r: 0 \rightarrow \infty$$

donde  $p_r = m \frac{dr}{dt}$  es la proyección en  $r$  de  $\vec{p}$ .



órbita hiperbólica

órbita parabólica

órbita elíptica

órbita círculo

Pero hay un caso más, aquel en que las órbitas precesan