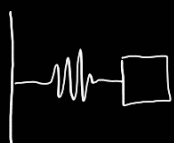


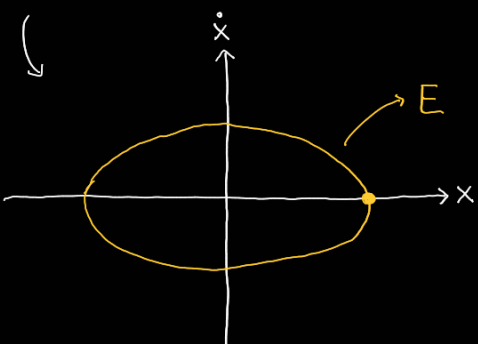
parte 420

El oscilador armónico



$$L = \frac{1}{2} m \dot{x}^2 - \frac{1}{2} k x^2 \dots (1); \quad E = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} k x^2 \dots (2)$$

Espacio fase de la energía



Si consideramos $x(0) = x_0$, $\dot{x}(0) = 0$ de modo tal que

$$E_0 = \frac{1}{2} k x_0^2$$

Más aún, nótese que de (2) tenemos

$$\dot{x} = \sqrt{\frac{2E}{m} - \frac{k}{m} x^2}$$

Si $\dot{x}_0 = 0$, entonces

$$\frac{2E}{m} = \frac{k}{m} x_0^2$$

Por otra parte, $\frac{dx}{dt} = \sqrt{\frac{k}{m} (x_0^2 - x^2)}$. Así pues,

$$\int_{x_0}^x \frac{dx}{\sqrt{x_0^2 - x^2}} = \int_0^t \omega dt \Rightarrow \arcsin\left(\frac{x}{x_0}\right) \Big|_{x_0}^x = \omega t$$

$$\Rightarrow \arcsin\left(\frac{x}{x_0}\right) - \frac{\pi}{2} = \omega t$$

$$\Rightarrow x(t) = x_0 \sin(\omega t + \frac{\pi}{2})$$

Dada una partícula de masa puntual m y un campo central $U = U(r)$ se tiene

$$\vec{F} = -\frac{\alpha}{r^2} \hat{r}$$

pero $\vec{r} = r\hat{r}$, $\vec{v} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$, $\vec{r} \times \vec{p} = mr^2\dot{\theta}\hat{k}$, de lo cual

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - U(r)$$

nótese además $\frac{d}{dt}(mr^2\dot{\theta}) = 0 \Rightarrow p_\theta = mr^2\dot{\theta} = \text{cte} \Rightarrow \dot{\theta} = p_\theta / mr^2 \dots (*)$

$$E = \frac{1}{2} m \dot{r}^2 + \frac{p_\theta^2}{2mr^2} + U(r)$$

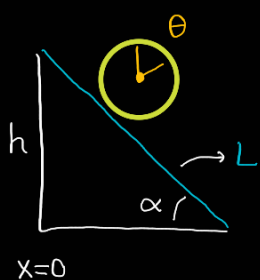
Si $\dot{r} = 0$, tenemos puntos de retorno

$$\frac{p_\theta^2}{2mr^2} + U(r) = E$$

$$\text{entonces, } \frac{dr}{dt} = \sqrt{\frac{2}{m} (E - U(r)) - \frac{p_\theta^2}{mr^2}} \Rightarrow \int dt = \int \frac{dr}{\sqrt{\frac{2}{m} (E - U(r)) - \frac{p_\theta^2}{mr^2}}} \Rightarrow t = t(r)$$

$$\text{Si consideramos por } (*) \text{ se tendría } d\theta = \frac{p_\theta dt}{mr^2} \Rightarrow \Delta\theta = \int_{r_{\min}}^{r_{\max}} \frac{p_\theta dr/r^2}{\sqrt{2m(E - U(r)) - p_\theta^2/r^2}}$$

$$\text{con } U(r) = \frac{p_\theta^2}{2mr^2} - \frac{\alpha}{r}.$$



$$T = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} I \dot{\theta}^2$$

$$\Rightarrow \mathcal{L} = \frac{1}{2} m \dot{x}^2 + \frac{I}{2a^2} \dot{x}^2 - mg(L-x)\sin\alpha$$

$$U = mg(L-x)\sin\alpha$$

$$\Rightarrow \left(m + \frac{I}{a^2}\right) \ddot{x} = mg\sin\alpha$$

Dadas las condiciones y la información que buscamos saber del sistema, podemos descartar a los multiplicadores de Lagrange λ .

$$\begin{cases} m\ddot{x} = mg\sin\alpha + \lambda \\ I\ddot{\theta} = a\lambda \\ \dot{x} = -a\dot{\theta} \end{cases}$$

Tenemos que $\mathcal{L}(q, \dot{q})$,

$$\frac{d\mathcal{L}}{dt} = \frac{\partial \mathcal{L}}{\partial q_i} \dot{q}_i + \frac{\partial \mathcal{L}}{\partial \dot{q}_i} \ddot{q}_i \Rightarrow \frac{d\mathcal{L}}{dt} = \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}_i} \right) \dot{q}_i + \frac{\partial \mathcal{L}}{\partial \dot{q}_i} \ddot{q}_i$$

$$\hookrightarrow \frac{\partial \mathcal{L}}{\partial \dot{q}_i} = \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}_i} \right) \Rightarrow \frac{d\mathcal{L}}{dt} = \frac{d}{dt} \left[\left(\frac{\partial \mathcal{L}}{\partial \dot{q}_i} \right) \dot{q}_i \right]$$

$$\Rightarrow \frac{d}{dt} \left[\frac{\partial \mathcal{L}}{\partial \dot{q}_i} \dot{q}_i - \mathcal{L} \right] = 0$$

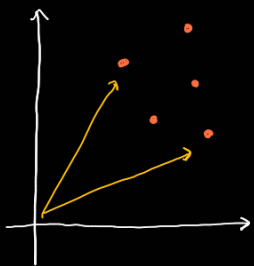
$\therefore \frac{\partial \mathcal{L}}{\partial \dot{q}_i} \dot{q}_i - \mathcal{L} = \text{cte.}$ No obstante, $\mathcal{L} = T(q, \dot{q}) - U(q)$ entonces

$$T = \frac{1}{2} \frac{\partial T}{\partial \dot{q}} \dot{q} \Rightarrow 2T = \frac{\partial \mathcal{L}}{\partial \dot{q}} \dot{q}$$

consecuentemente,

$$\frac{\partial \mathcal{L}}{\partial \dot{q}_i} \dot{q}_i - \mathcal{L} = E \Rightarrow 2T - T + U = E$$

Veamos ahora que ocurre con el momento. Considere entonces un sistema de partículas tales que serán trasladadas uniformemente por $\delta \vec{r}_\alpha$,



$$\vec{r}_\alpha \rightarrow \vec{r}_\alpha + \delta \vec{r}_\alpha, \quad \delta \vec{r}_\alpha = \vec{\epsilon}$$

$$\delta \mathcal{L} = \sum_\alpha \frac{\partial \mathcal{L}}{\partial \vec{r}_\alpha} \cdot \delta \vec{r}_\alpha; \quad \delta \mathcal{L} = 0 \Rightarrow \sum_\alpha \frac{\partial \mathcal{L}}{\partial \vec{r}_\alpha} = 0$$

$$\frac{d}{dt} \left(\sum_\alpha \frac{\partial \mathcal{L}}{\partial \dot{\vec{r}}_\alpha} \right) = \frac{\partial \mathcal{L}}{\partial \vec{r}_\alpha} = 0 \Rightarrow \vec{p} = \sum_\alpha \frac{\partial \mathcal{L}}{\partial \dot{\vec{r}}_\alpha} = \text{cte}$$

Si tuviésemos que $\mathcal{L} = \frac{1}{2} m \vec{v}_\alpha^2 - U(\vec{r}_1, \dots, \vec{r}_f)$, \nearrow f: grados de libertad

$$\vec{p} = \sum \vec{p}_\alpha = \sum \frac{\partial \mathcal{L}}{\partial \dot{\vec{r}}_\alpha} = \sum m \vec{v}_\alpha \Rightarrow \frac{\partial \mathcal{L}}{\partial \vec{r}_\alpha} = \frac{\partial U}{\partial \vec{r}_\alpha} = -\vec{F}_\alpha$$

$$\Rightarrow \vec{F}_{12} = -\vec{F}_{21} \text{ (¡recuperamos la 2da Ley!)} \quad \text{---}$$