



Overview of Deep Learning

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Artificial Intelligence (AI)

Machines exhibiting animal or human intelligence

Ants bridging algo



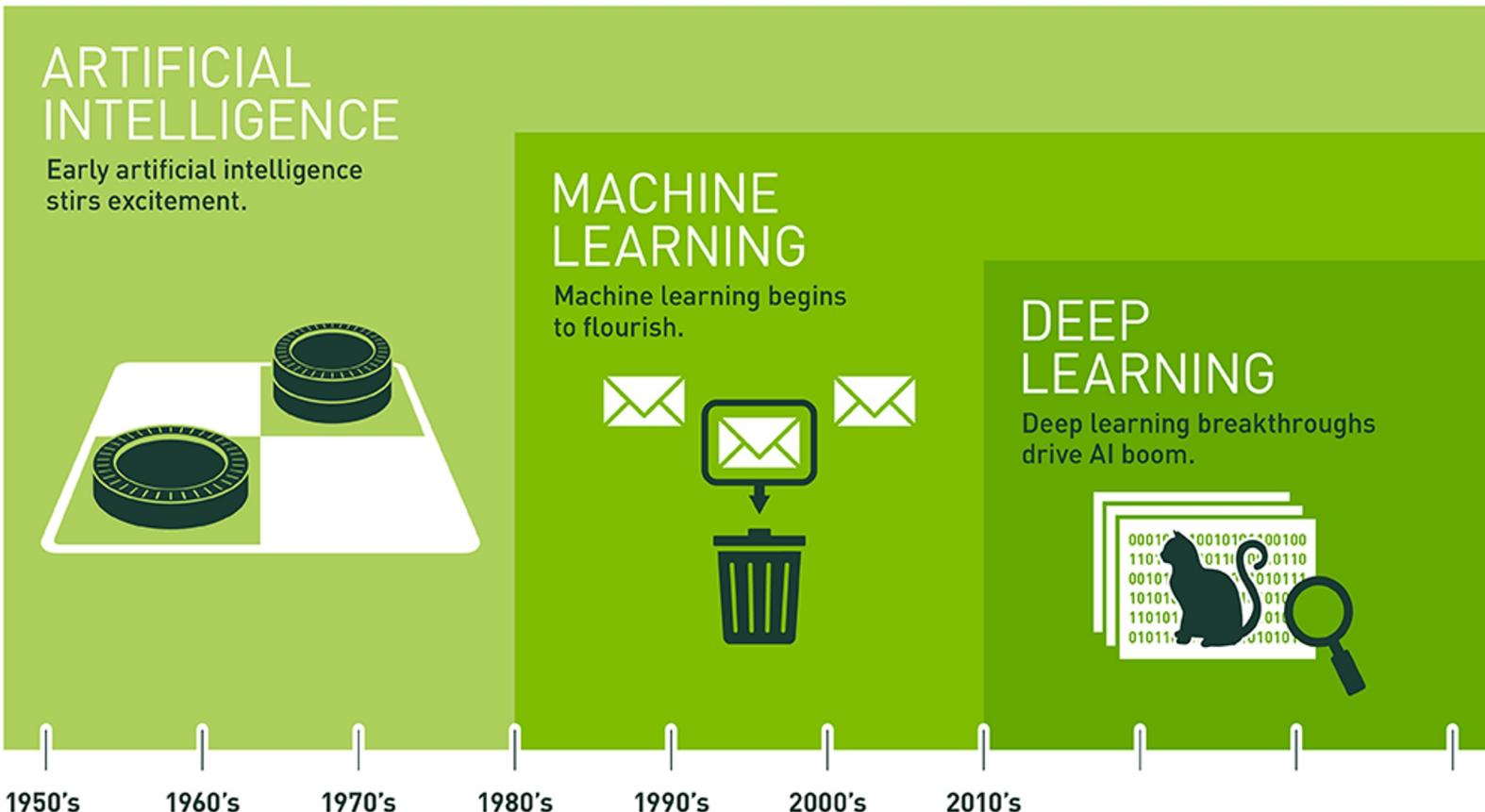
<https://www.quantamagazine.org/the-simple-algorithm-that-ants-use-to-build-bridges-20180226>

Intelligence

- A very general mental capability that among other things involves the ability to:
 - Reason
 - Plan
 - Solve problems
 - Think abstractly
 - Comprehend complex ideas
 - Learning quickly and learning from experience

Journal of Intelligence 1997 Vol 24 No 1

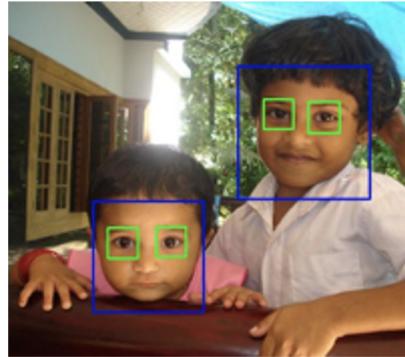
AI, Machine Learning and Deep Learning



NVIDIA

Since an early flush of optimism in the 1950s, smaller subsets of artificial intelligence – first machine learning, then deep learning, a subset of machine learning – have created ever larger disruptions.

Artificial Intelligence, Machine Learning and Deep Learning on Face Detection

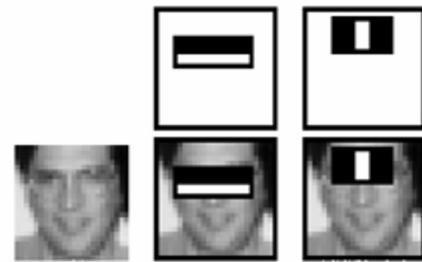


Rule-based (AI):

Detect facial features based on color/template

Apply if-else-if-else

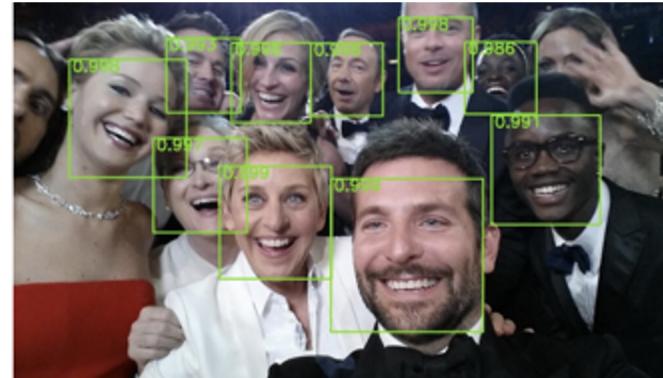
[Viola & Jones 2001]



Machine Learning:
Use Haar Cascade
Classifier

**Hand-crafted feature
detection**

YOLO, SSD, RCNN [>2012]

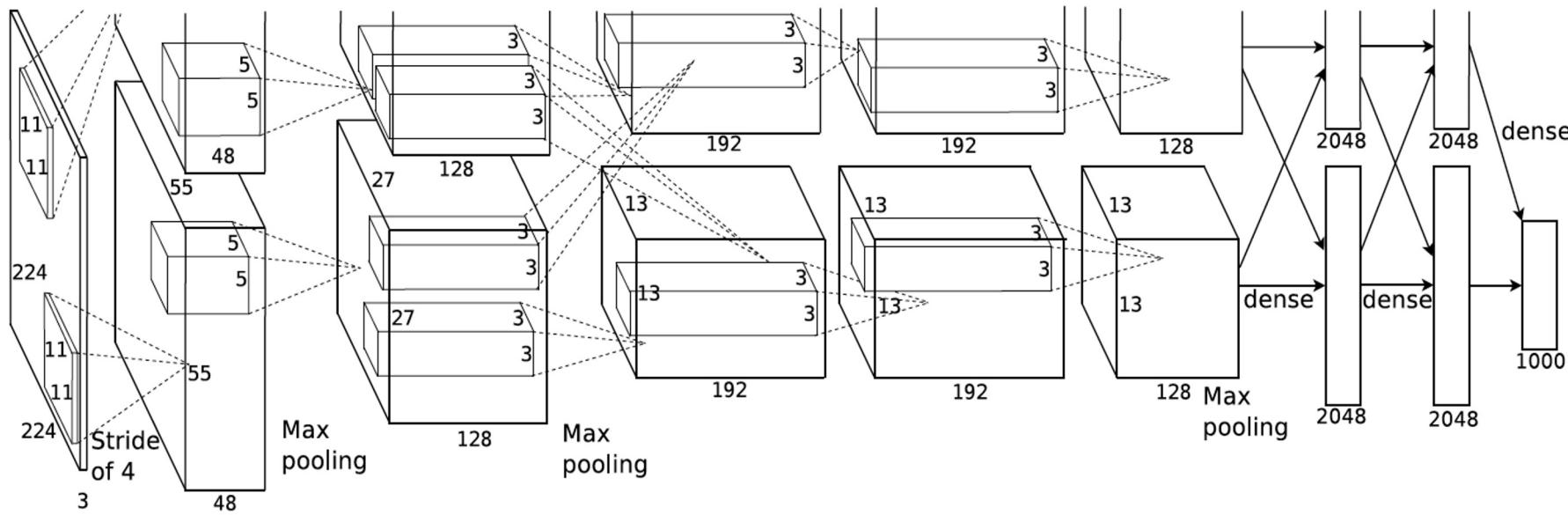


Deep Learning:
Train a network by
showing thousands of
labelled region of faces

**Automatic feature
detection**

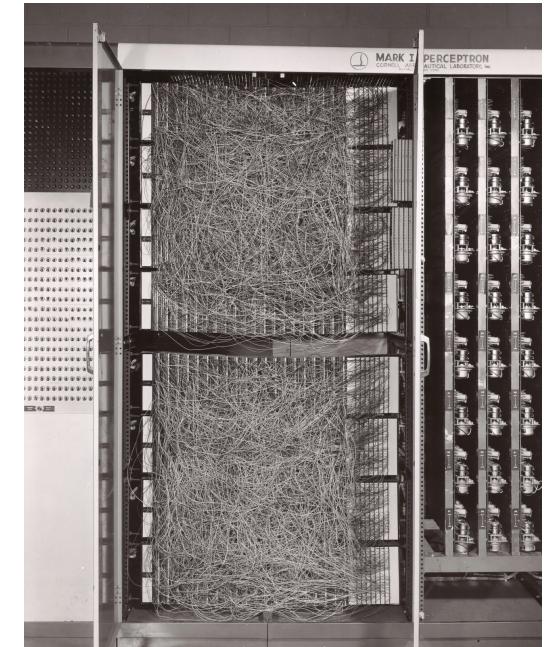
Deep Learning Moment - 2012

- AlexNet – 650,000-neuron deep neural network won 2012 ImageNet1k competition with 15% Top-5 error rate compared to 2nd place with 26%. Its top 1 accuracy is 63.3%.



Deep Learning - what made it work?

- Concepts of artificial neural network (ANN) and convolutional neural network (CNN) are old
 - Neurons in perceptron (1-layer NN) – 1958
 - Neocognitron (1980) and CNN (1989)
 - Backpropagation (1986)
- What's new?
 - Computing power – Massive number of GPU CUDA cores
 - Data – from the Internet



Perceptron is a binary classifier

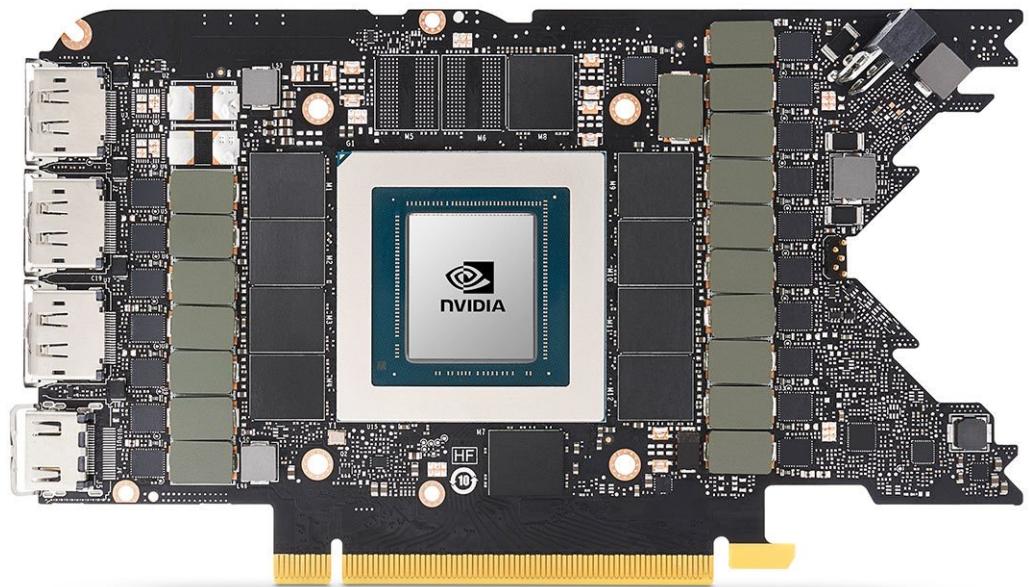
CPU (AMD Ryzen)

vs

GPU (RTX 3090)

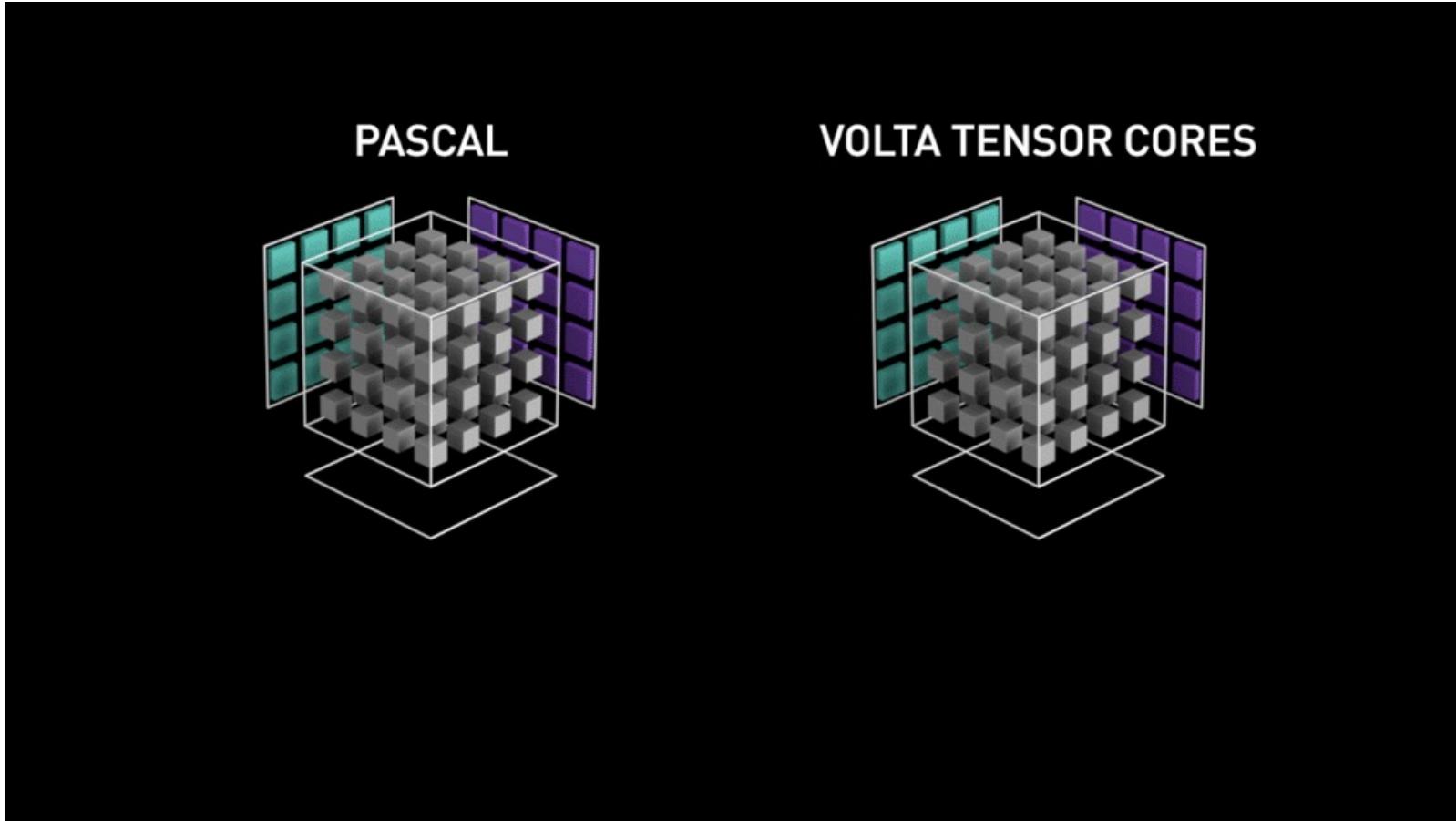


64 3.7GHz super fast cores
6.9 TFLOPS



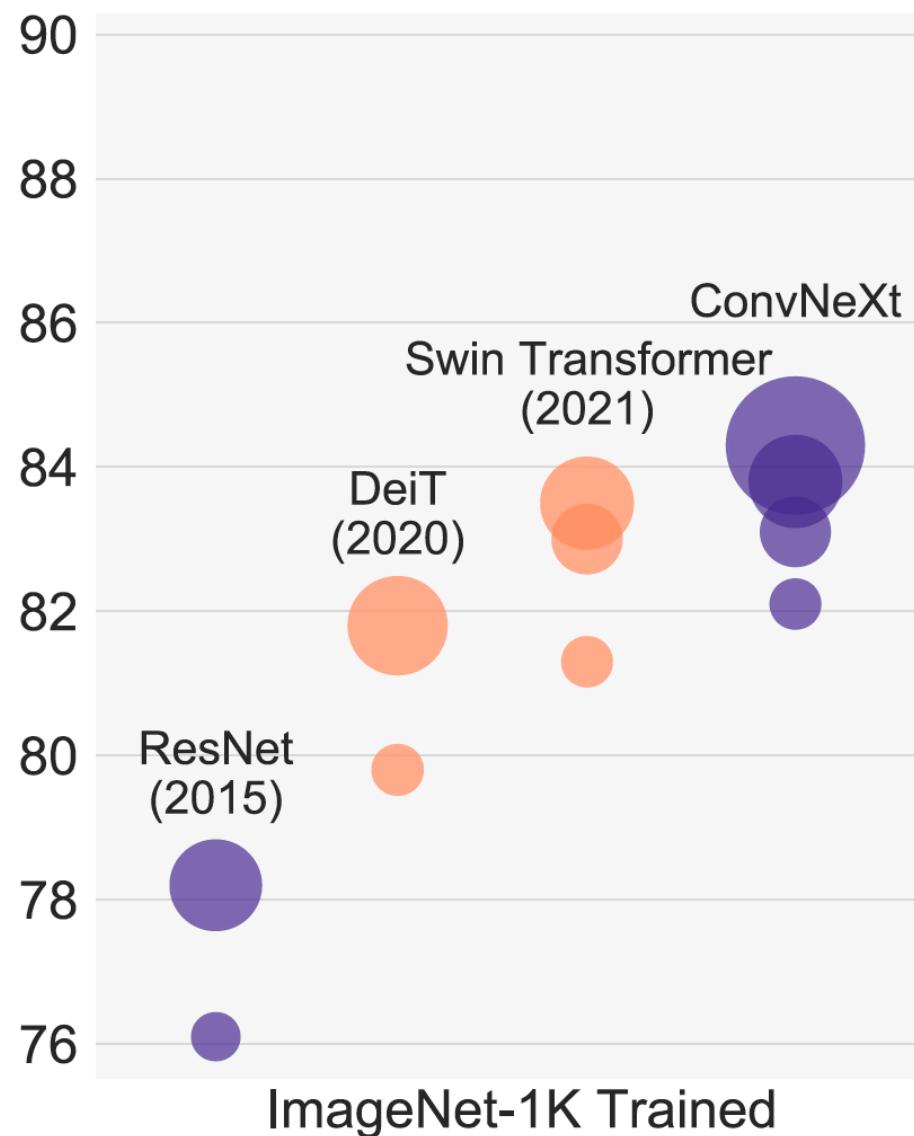
10,496 1.4GHz fast cores
35.6 TFLOPS

1D vs 2D Tensor Operation



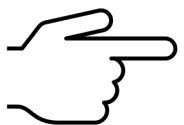
The Rest is History

ImageNet-1K Acc.



Barely scratching the surface of Artificial General Intelligence (AGI)

Starting to
move here



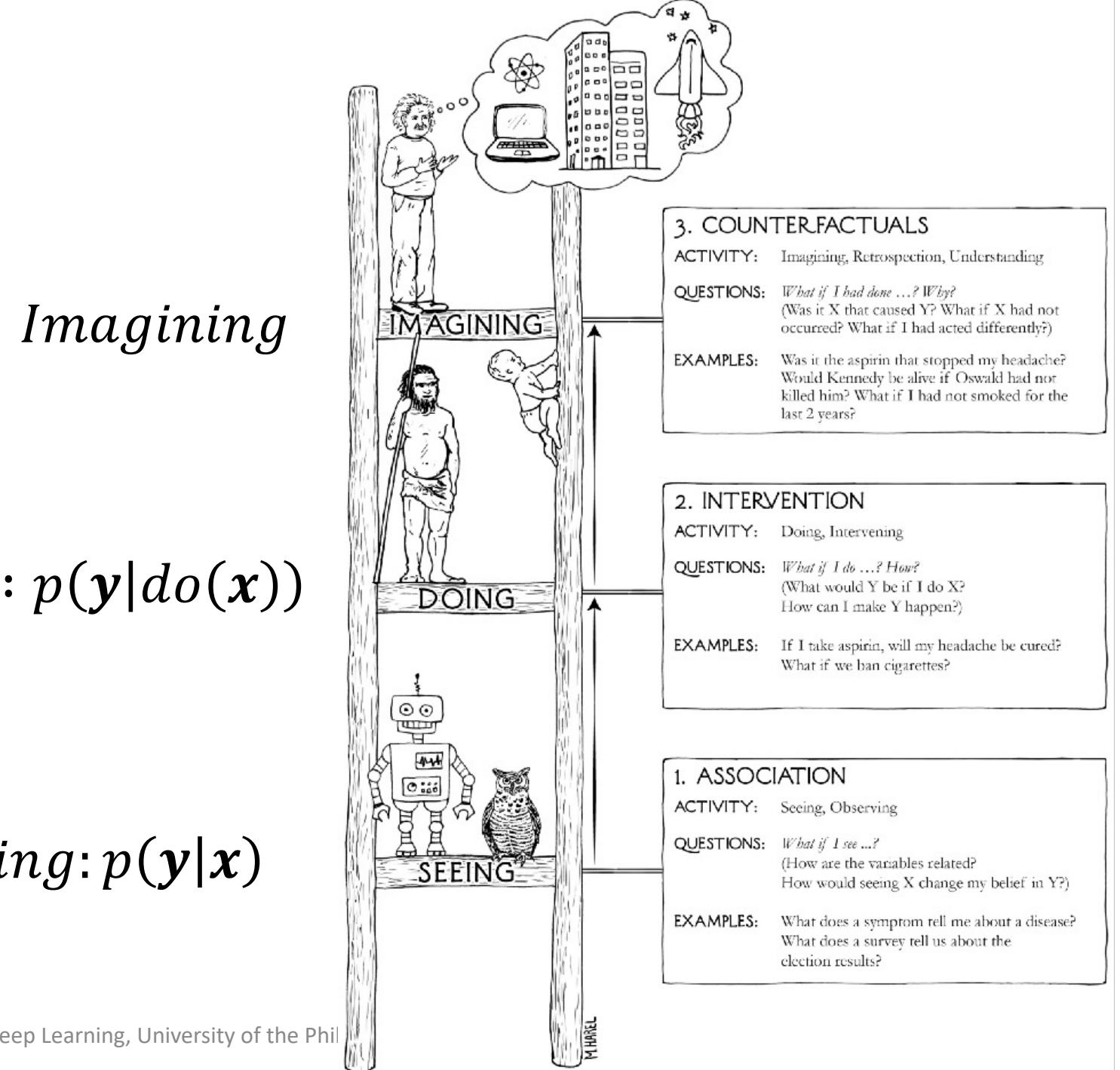
Doing : $p(y|do(x))$

We are here



Seeing: $p(y|x)$

Pearl, Book of Why



Does ChatGPT (or LLMs in general) exhibit AGI?

Do Large Language Models Perform Reasoning in Problem Solving Tasks?

Comprehensive Tests

Faith and Fate: Limits of Transformers on Compositionality

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Bill Yuchen Lin¹, Peter West^{1,2}, Chandra Bhagavatula¹, Ronan Le Bras¹, Jena D. Hwang¹,
Soumya Sanyal³, Sean Welleck^{1,2}, Xiang Ren^{1,3}, Allyson Ettinger^{1,4},
Zaid Harchaoui^{1,2}, Yejin Choi^{1,2}**

GPT4 Reasoning Test

 What is 3×567 ?

 The product of 3 and 567 is 1701.

 What is 3×5678 ?

 The product of 3 and 5678 is 17034.

 What is 3×56789 ?

 The product of 3 and 56789 is 170367.



What is 345×56789 ?



The product of 345 and 56789 is 19,577,205.



What is $345 / 56789$?



The result of 345 divided by 56789 is approximately 0.006072.



What is 4 raised to its square?



Raising a number to the power of its own square is a sizable operation. In this case, you're asking what is $4^{(4^2)}$, or 4^{16} .

4^{16} equals 18,446,744,073,709,551,616.

Failed!



```
>>> import math  
>>> math.pow(4, 16)  
4294967296.0
```

How Humans use Reasoning to Solve Tasks

- Break a problem into sub-tasks
- A sub-task is a node
- Solving a sub-task transitions it into a new sub-task
- Repeat until all sub-tasks are completely solved

Computation Graph!

Sub-task - Vertex

Solution – Edge or Operator

Computation Graph for Multiplication Algo

```
function multiply (x[1..p], y[1..q]):  
    // multiply x for each y[i]  
    for i = q to 1  
        carry = 0  
        for j = p to 1  
            t = x[j] * y[i]  
            t += carry  
            carry = t // 10  
            digits[j] = t mod 10  
            summands[i] = digits  
  
    // add partial results (computation not shown)  
    product =  $\sum_{i=1}^q$  summands[q+1-i] · 10i-1  
    return product
```

$A(\mathbf{x})$

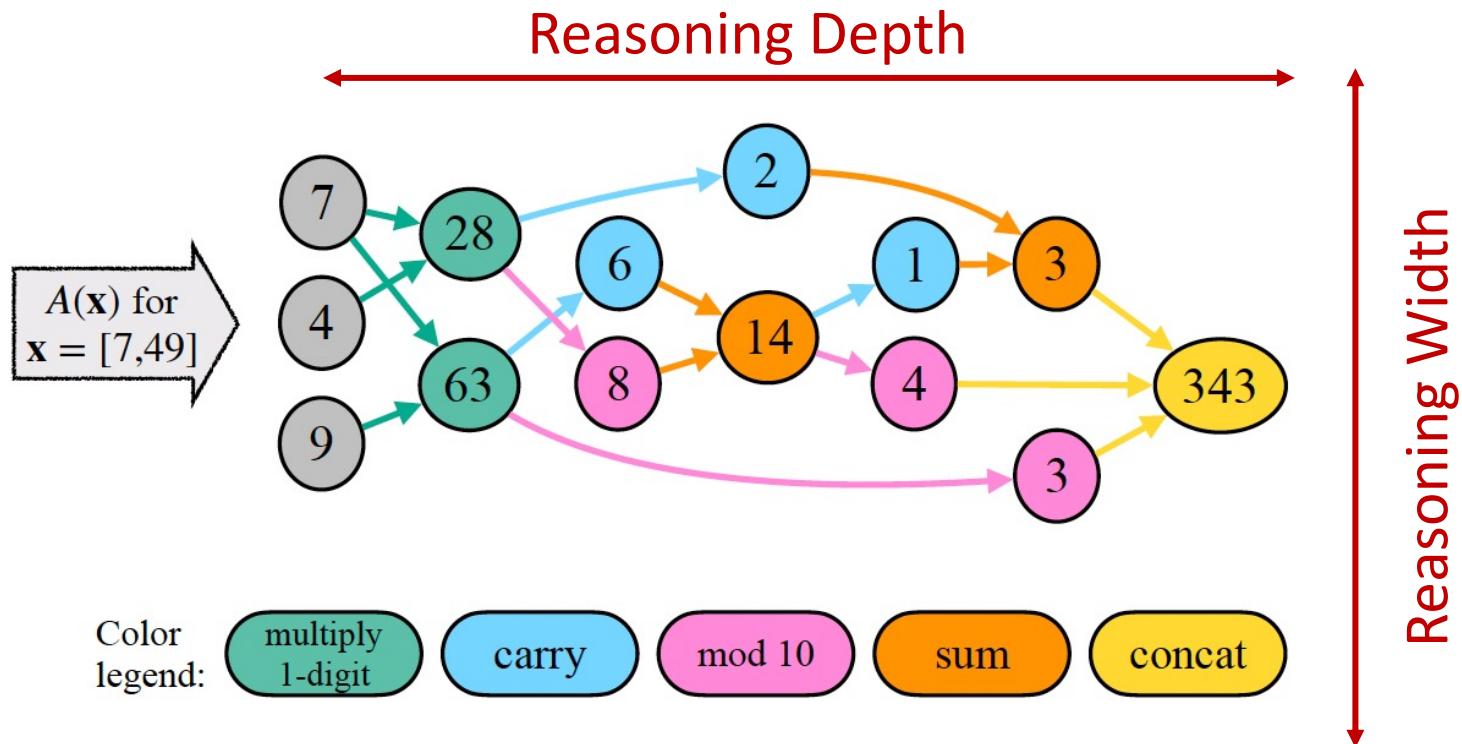
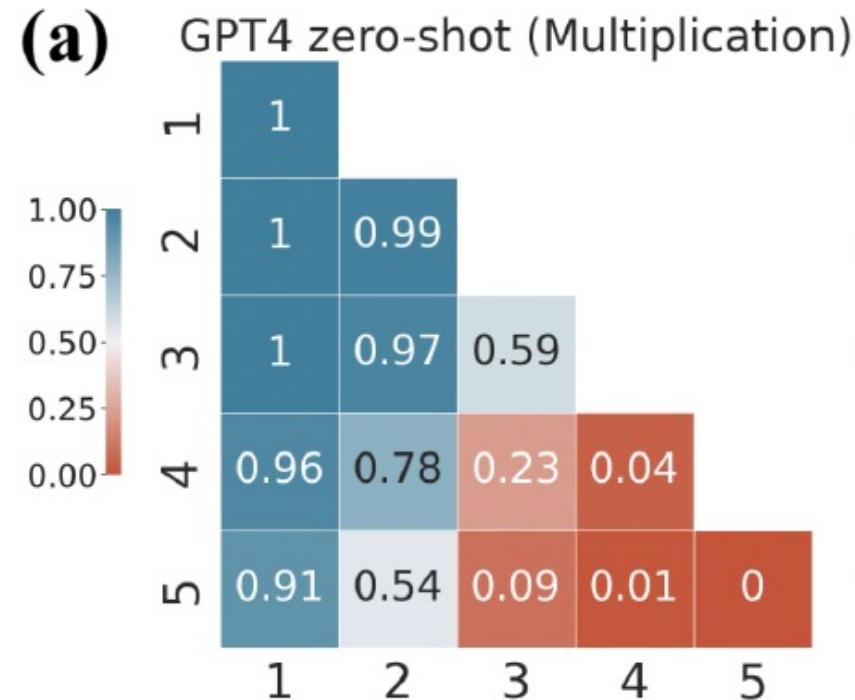


Figure 1: Transformation of an algorithm A to its computational graph $G_{A(\mathbf{x})}$. The depicted example is of long-form multiplication algorithm A , for inputs $\mathbf{x} = [7, 49]$ (i.e. computing 7×49).

GPT4 Zero-shot Multiplication



No longer applies as demonstrated in the previous slides!

Relative Information Gain (RIG)

$$\text{RelativeIG}(Y_j, X) = \frac{H(Y_j) - H(Y_j|X)}{H(Y_j)} \in [0, 1]$$

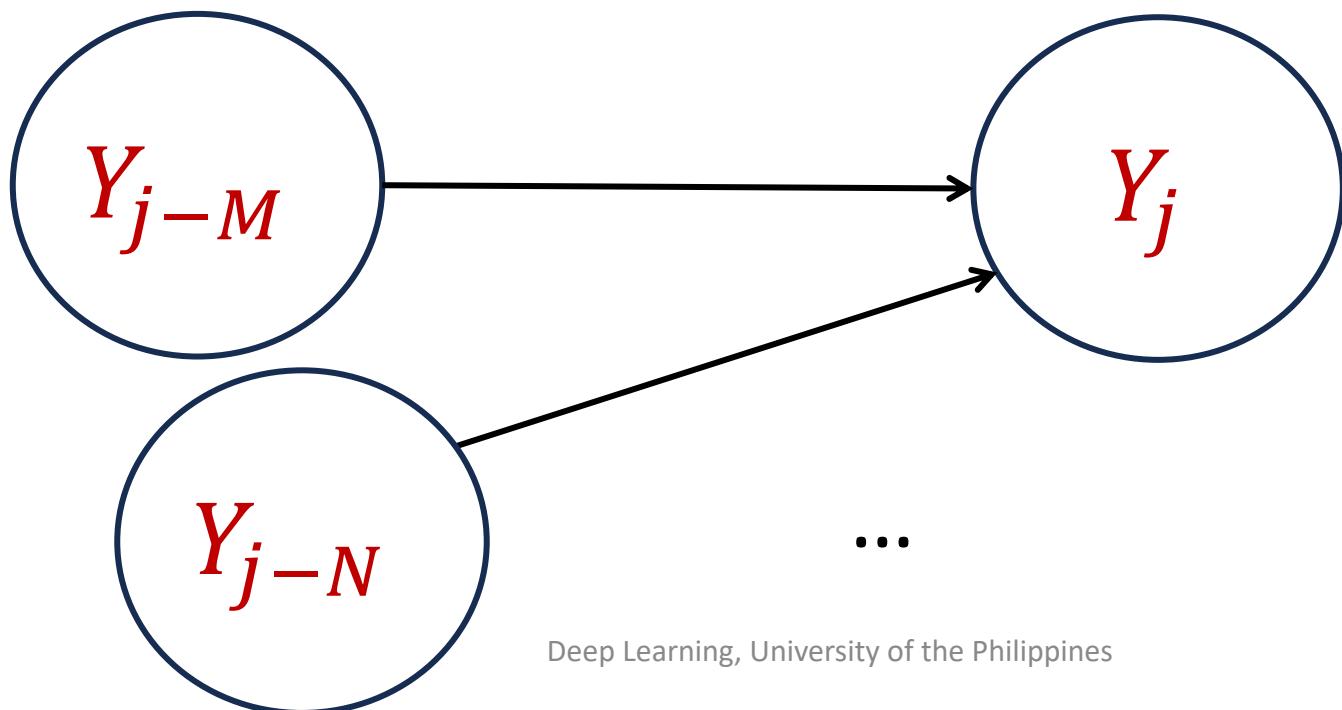
Y_j : output

X : input random variables

$H(Y) = -\mathbb{E}[\log p(Y)]$: entropy

Observation

- LLMs break down a problem into a computational graph
- LLMs can solve problems where the RIG is high between sub-tasks
- When the RIG is low, the LLM hallucinates



2 Critical Points

- Ability to break down a problem into a correct computation graph
- High RIG between sub-tasks

When do LLMs fail?

- In-correct computation graph
- A presence of low RIG between sub-tasks
 - Deep reasoning graphs can amplify errors due to error propagation

Incorrect computation graphs

- Instruction-based tuning
- Prompt engineering
- Etc

**InstructBLIP: Towards General-purpose
Vision-Language Models with Instruction Tuning**

LARGE LANGUAGE MODELS AS OPTIMIZERS

Low RIG between sub-tasks

- Higher data quality

TinyStories: How Small Can Language Models Be and Still Speak Coherent English?

LIMA: Less Is More for Alignment

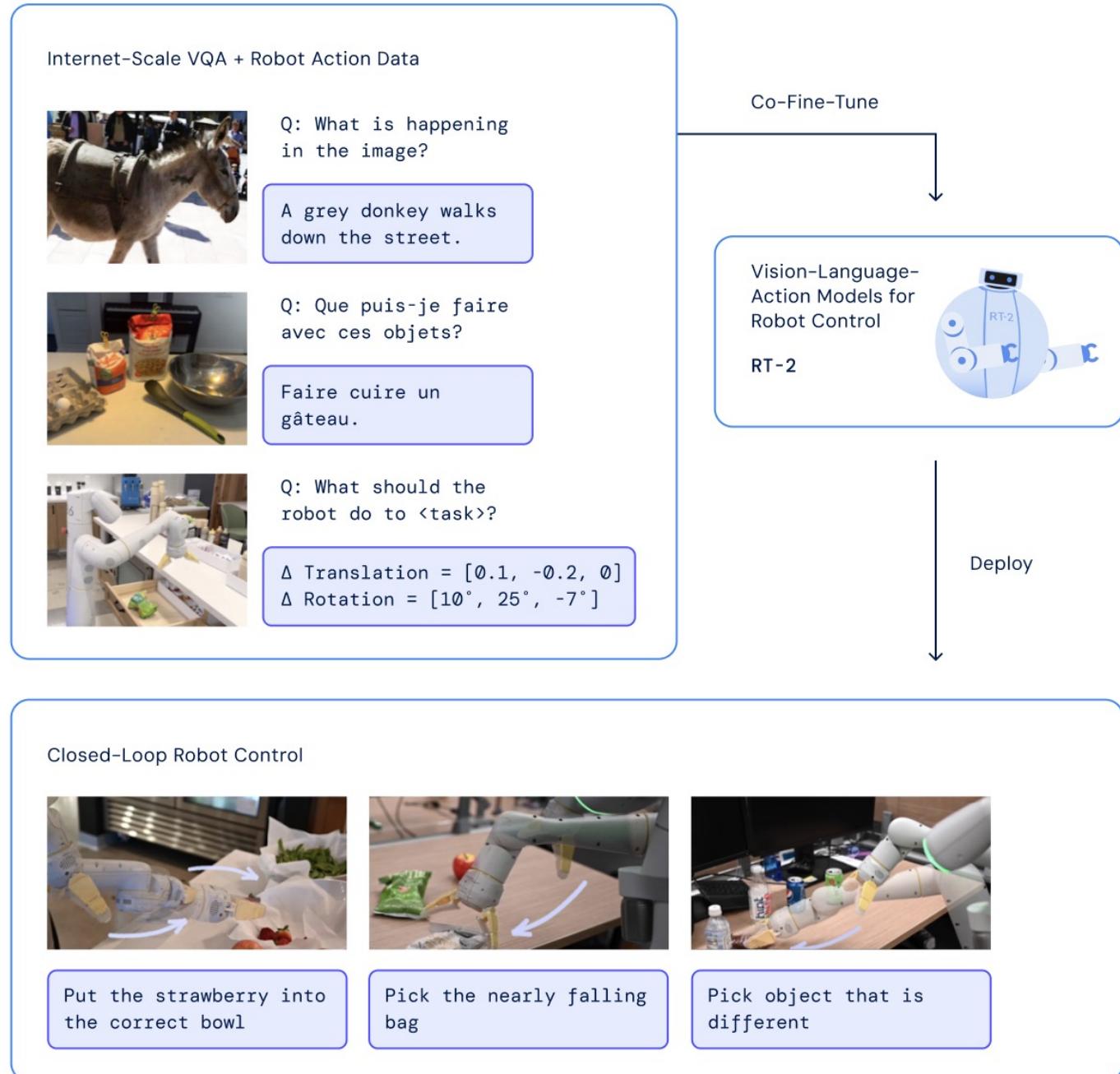
Improving Reasoning by Grounding the Language Modality

RT-2: Vision-Language-Action Models Transfer Web Knowledge to Robotic Control

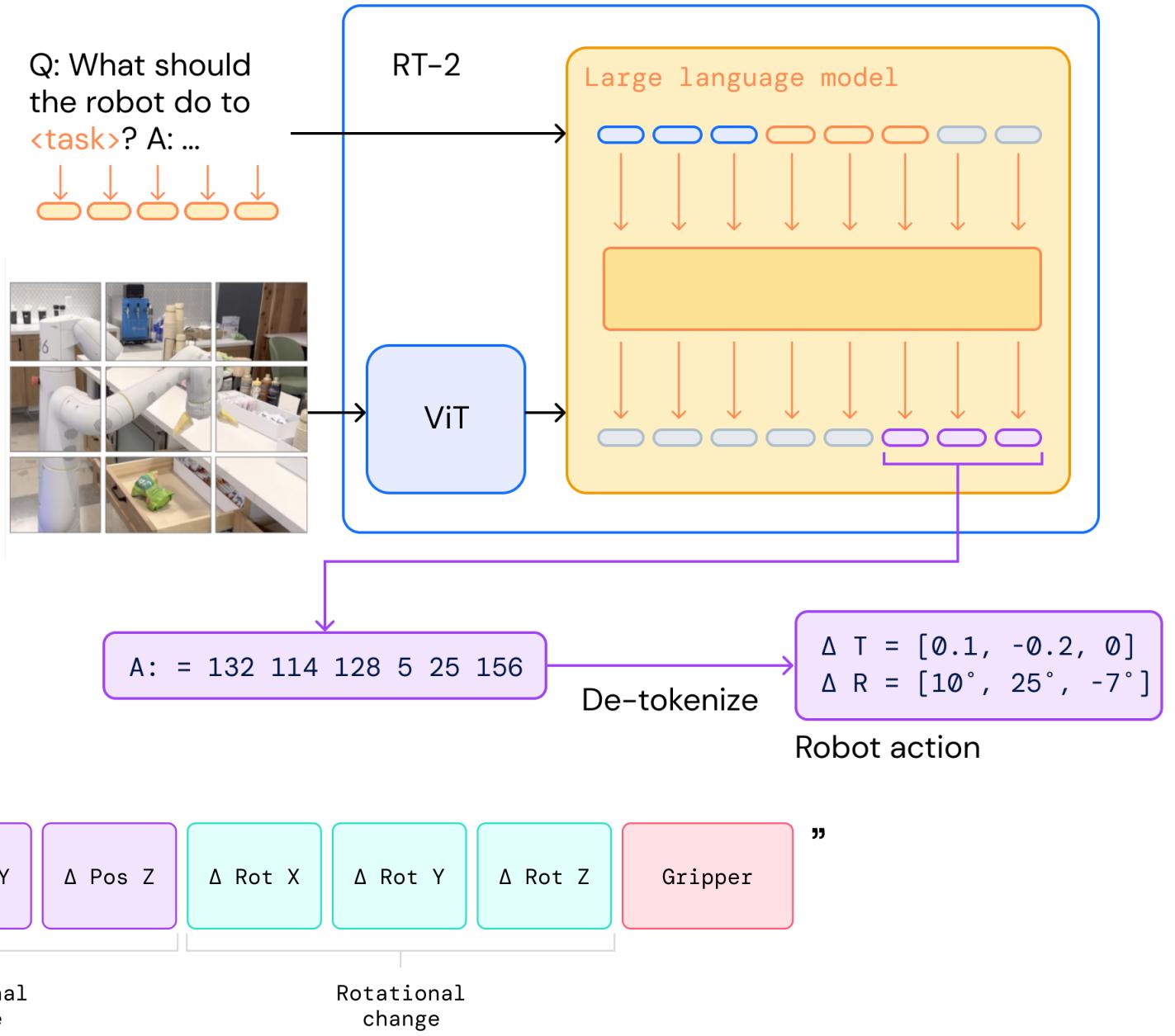
<https://robotics-transformer2.github.io/>



Pre-train on Internet scale vision-language data



Co-fine-tune with real robot data.
The robot language is used during co-fine-tuning.





LINGO-1: Exploring Natural Language for Autonomous Driving

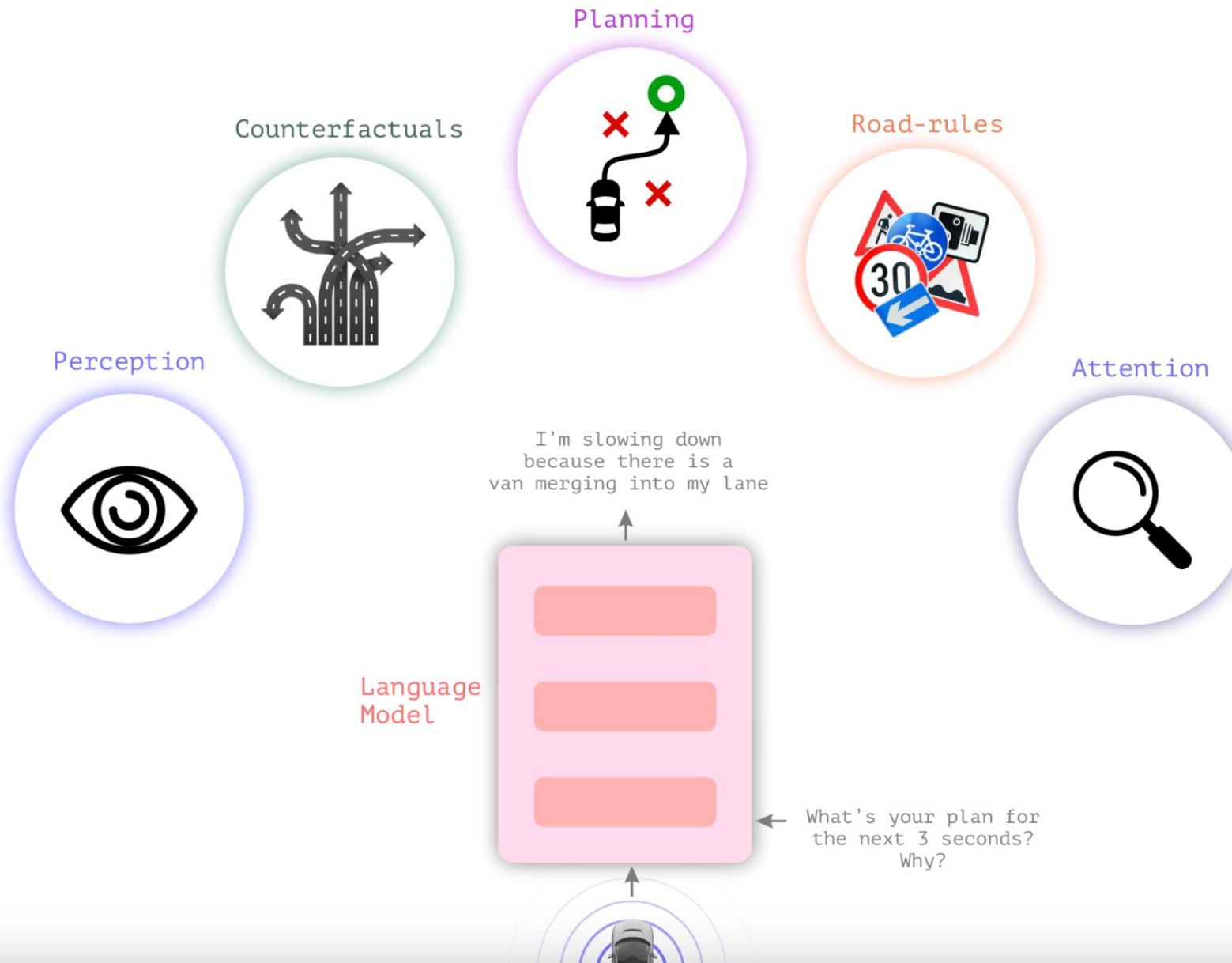
<https://wayve.ai/thinking/lingo-natural-language-autonomous-driving/>

AV2.0

Bringing the next wave of self-driving technology to market.



LINGO-1 Architecture



Lingo-1: Driver Commentator for Autonomous Driving

- slowing down for a lead vehicle or a change in traffic lights,
- changing lanes to follow a route,
- accelerating to the speed limit,
- noticing other cars coming onto the road or stopped at an intersection
- approaching hazards such as roundabouts and Give Way signs,
- parked cars, traffic lights or schools,
- actions other road users are taking, such as changing lanes or overtaking parked vehicles,
- cyclists and pedestrians waiting at zebra crossings or coming up from behind the car in a cycle lane.



WAYVE

Select another segment



London NW Route

● Ready

Close

What do you see?

Ask a new question



LINGO-1 Contributions

- Improved Reasoning due to instructions from driver commentator
- Querying next actions improve model explainability

References

Strickland, E. The Turbulent Past and Uncertain Future of Artificial Intelligence: Is there a way out of AI's boom-and-bust cycle?

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