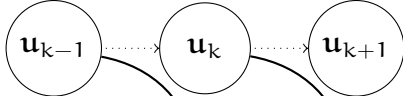
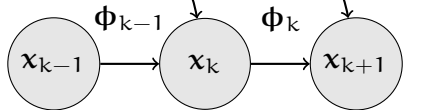


Input



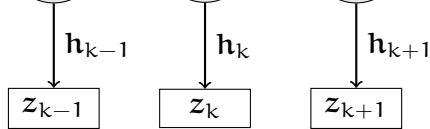
State



$\mathbf{h}_{k-1}$

$\mathbf{h}_k$

$\mathbf{h}_{k+1}$



Observation