

Artificial Neural Network

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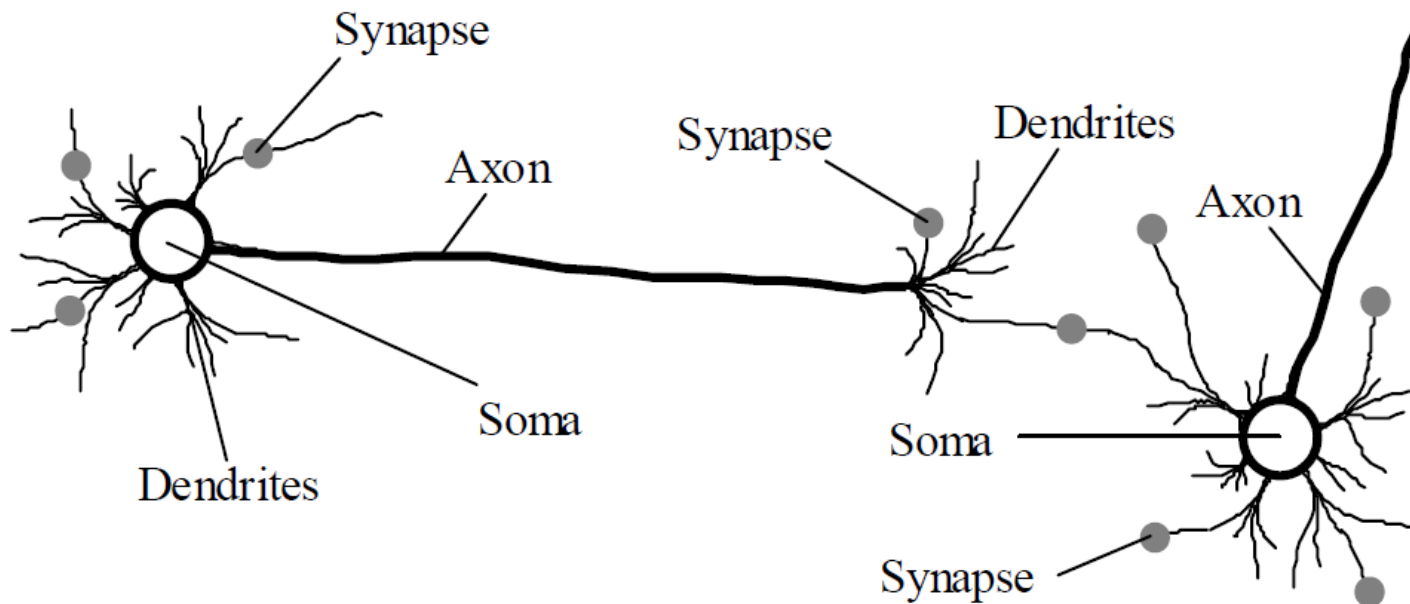


Discussion Points

- How brain works
- Similarity between brain and artificial neural network
- Perceptron learning
 - AND
 - OR
 - XOR
- Multilayer Perceptron
- Use case- Face Recognition

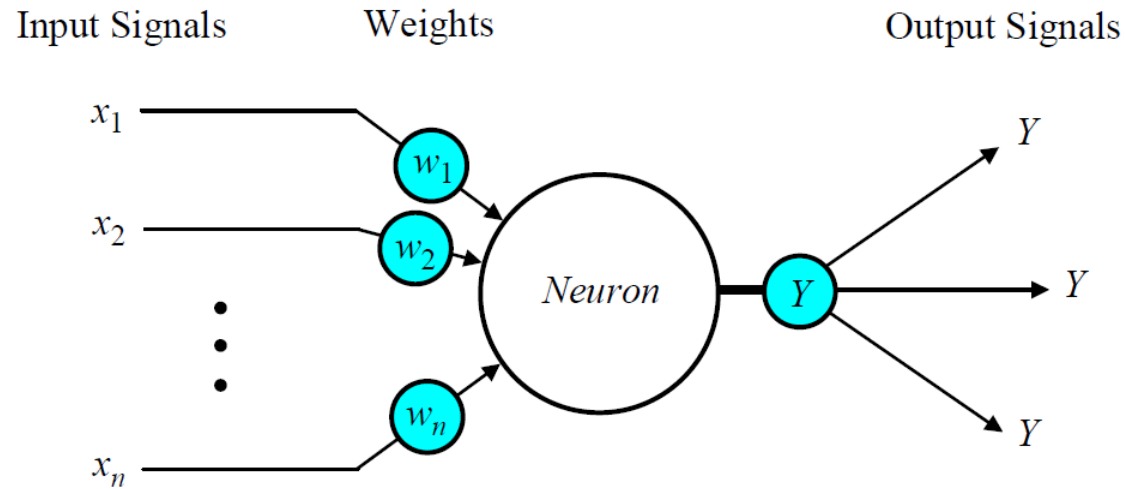
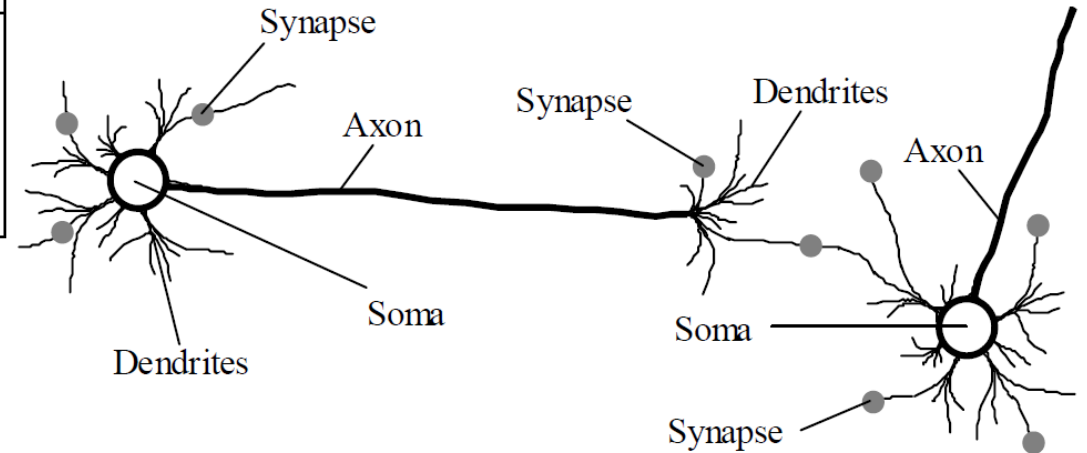
How Brain Works

- The human brain incorporates nearly 10 billion neurons and 60 trillion connections, synapses, between them.
- A neuron consists of a cell body, soma, a number of fibers called dendrites, and a single long fiber called the axon.

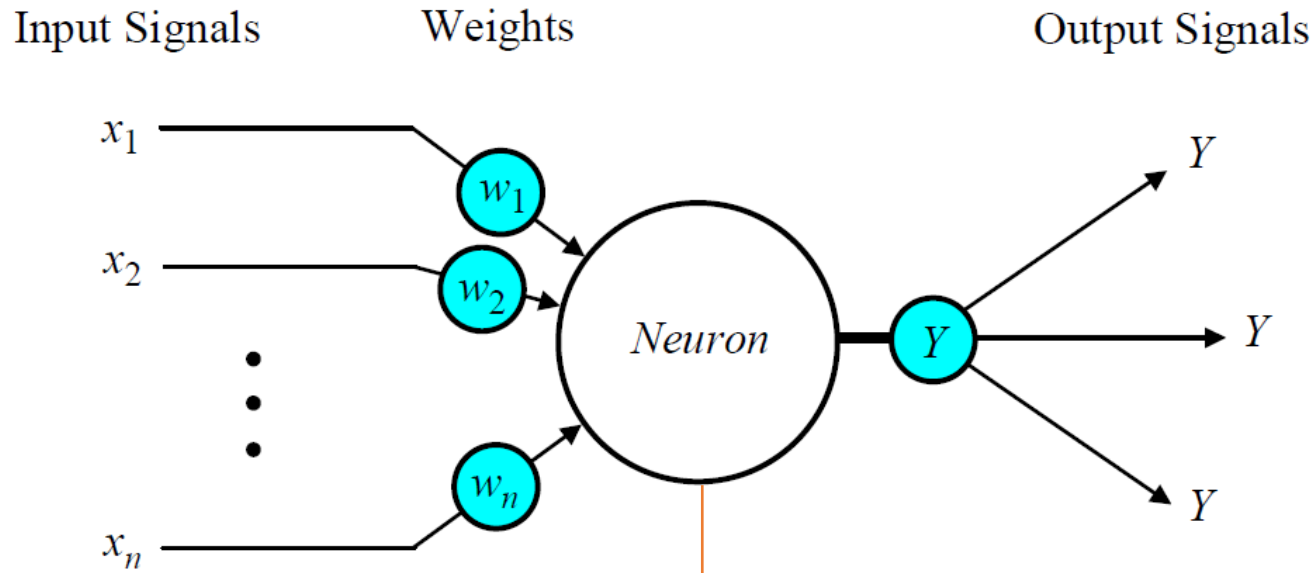


Similarity between brain and ANN

| <i>Biological Neural Network</i> | <i>Artificial Neural Network</i> |
|----------------------------------|----------------------------------|
| Soma | Neuron |
| Dendrite | Input |
| Axon | Output |
| Synapse | Weight |



Perceptron Learning



1

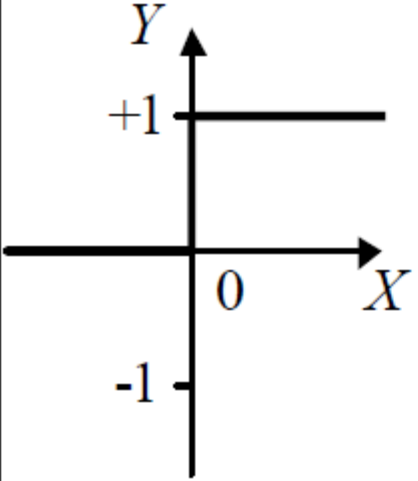
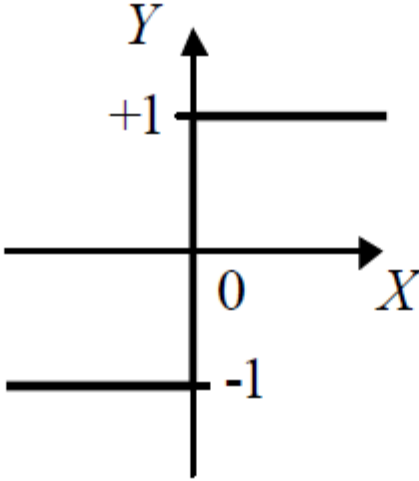
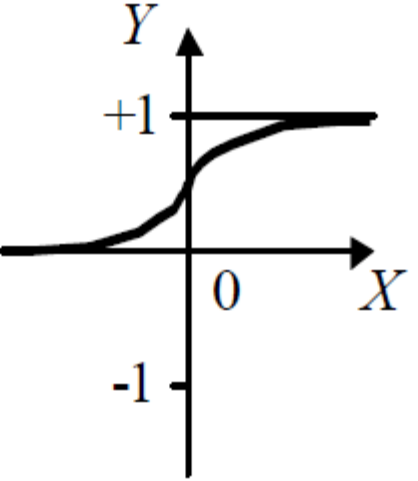
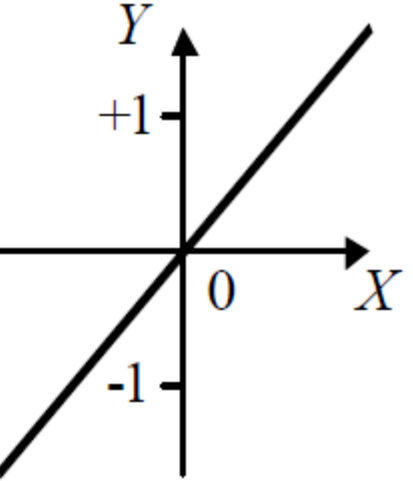
$$X = \sum_{i=1}^n x_i w_i$$

2

$$Y = \begin{cases} +1, & \text{if } X \geq \theta \\ -1, & \text{if } X < \theta \end{cases}$$

Sign Function

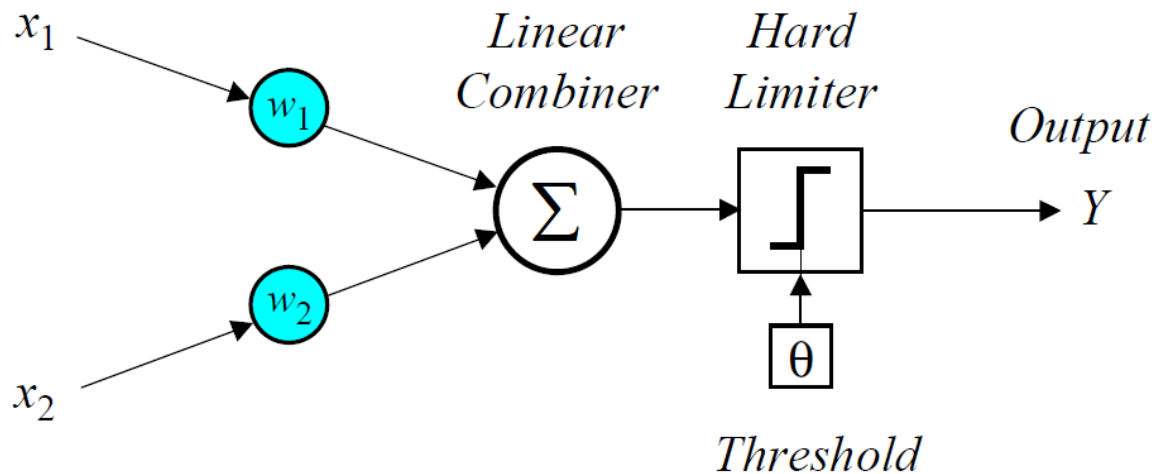
Activation Functions

| <i>Step function</i> | <i>Sign function</i> | <i>Sigmoid function</i> | <i>Linear function</i> |
|--|--|--|--|
|  |  |  |  |
| $Y^{step} = \begin{cases} 1, & \text{if } X \geq 0 \\ 0, & \text{if } X < 0 \end{cases}$ | $Y^{sign} = \begin{cases} +1, & \text{if } X \geq 0 \\ -1, & \text{if } X < 0 \end{cases}$ | $Y^{sigmoid} = \frac{1}{1 + e^{-X}}$ | $Y^{linear} = X$ |

How a perceptron learns

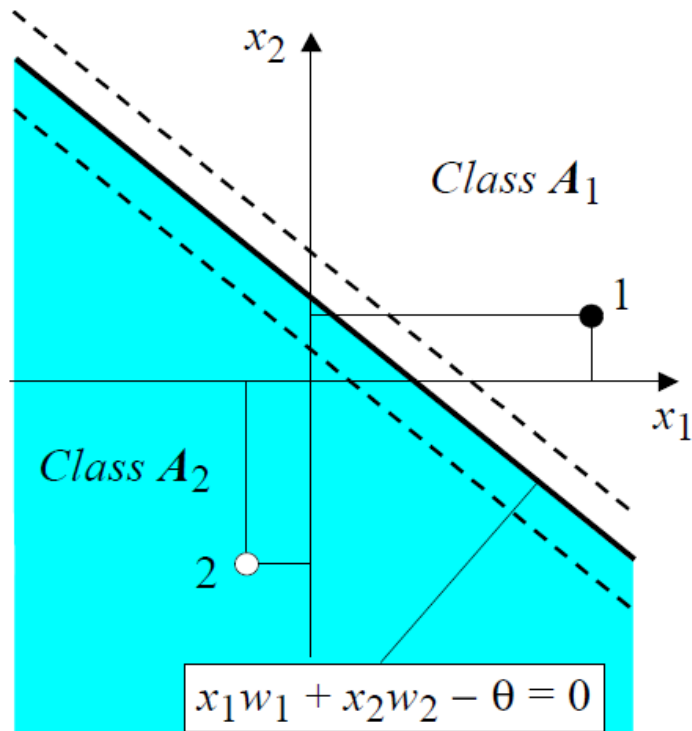
- In 1958, Frank Rosenblatt introduced a training algorithm that provided the first procedure for training a simple ANN: a perceptron, inspired by **McCulloch and Pitts neuron model**

Inputs

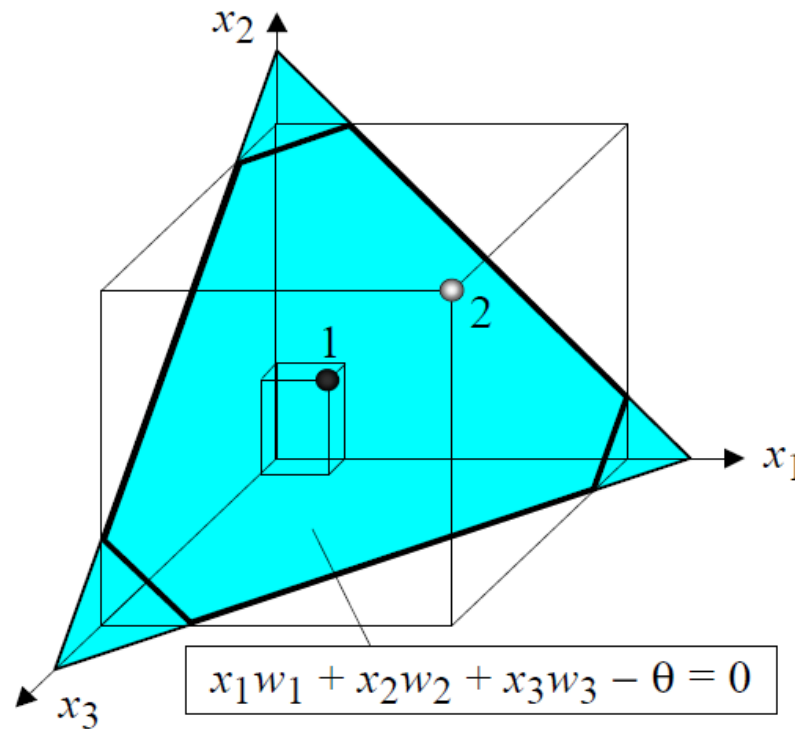


How a perceptron learns

- Decision boundary



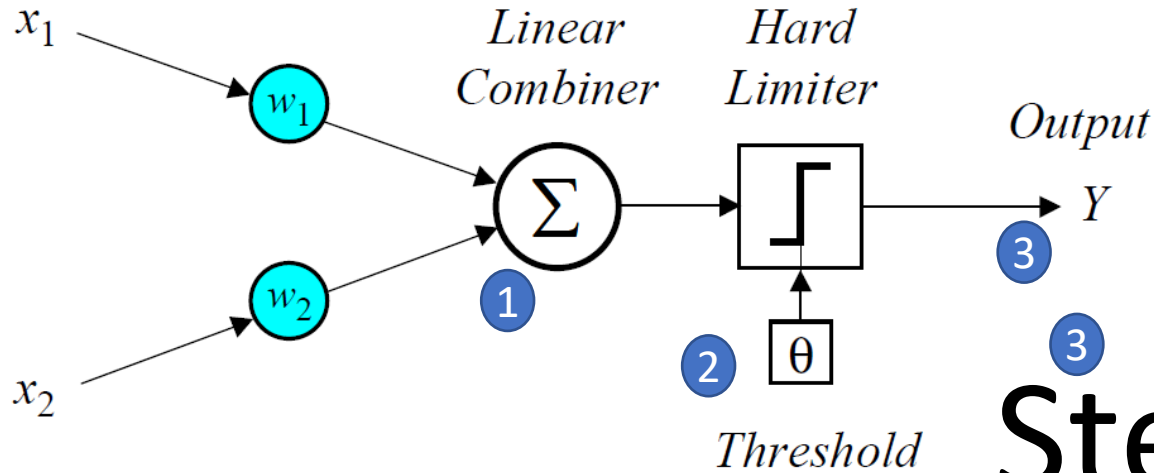
(a) Two-input perceptron.



(b) Three-input perceptron.

How a perceptron learns

Inputs



AND Problem

| x_1 | x_2 | y_d | w_1 | w_2 | y_a |
|-------|-------|-------|-------|-------|-------|
| 0 | 0 | 0 | 0.3 | -0.1 | |
| 0 | 1 | 0 | | | |
| 1 | 0 | 0 | | | |
| 1 | 1 | 1 | | | |

1

$$X = \sum_{i=1}^n x_i w_i$$

2

$$\sum_{i=1}^n x_i w_i - \theta = 0$$

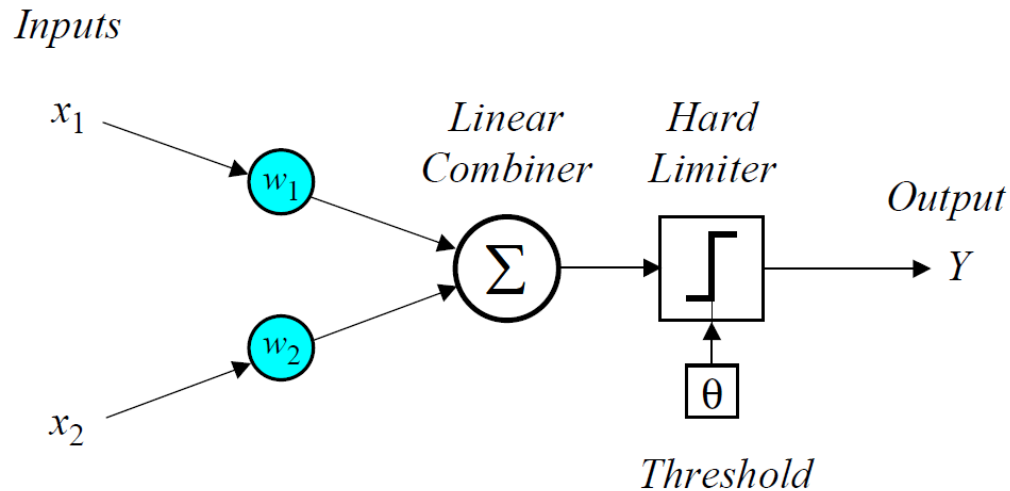
3

$$\text{Step}\left(\sum_{i=1}^n x_i w_i - \theta = 0\right)$$

Threshold: $\theta = 0.2$; learning rate : $\alpha = 0.1$; activation function : step

How a perceptron learns

| x_1 | x_2 | y_d | w_1 | w_2 | y_a | Error | w_1^{new} | w_2^{new} |
|-------|-------|-------|-------|-------|-------|-------|-------------|-------------|
| 0 | 0 | 0 | 0.3 | -0.1 | | | | |
| 0 | 1 | 0 | | | | | | |
| 1 | 0 | 0 | | | | | | |
| 1 | 1 | 1 | | | | | | |



Weight Updation

$$w_i(p+1) = w_i(p) + \Delta w_i(p)$$

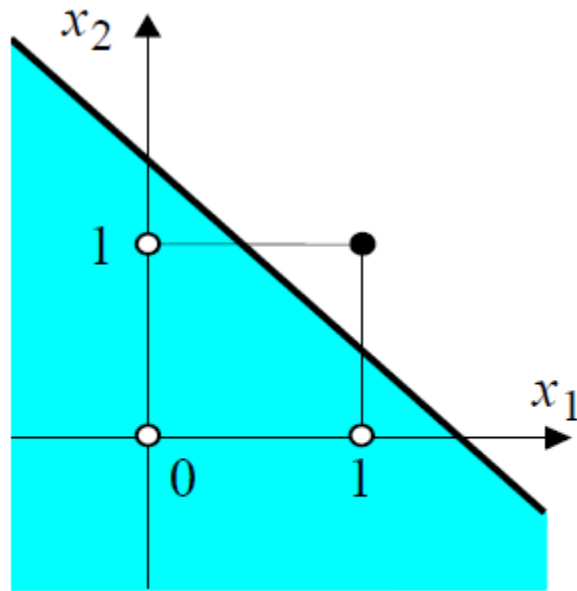
$$\Delta w_i(p) = \alpha \cdot x_i(p) \cdot e(p)$$

Threshold: $\theta = 0.2$; learning rate : $\alpha = 0.1$; activation function : step

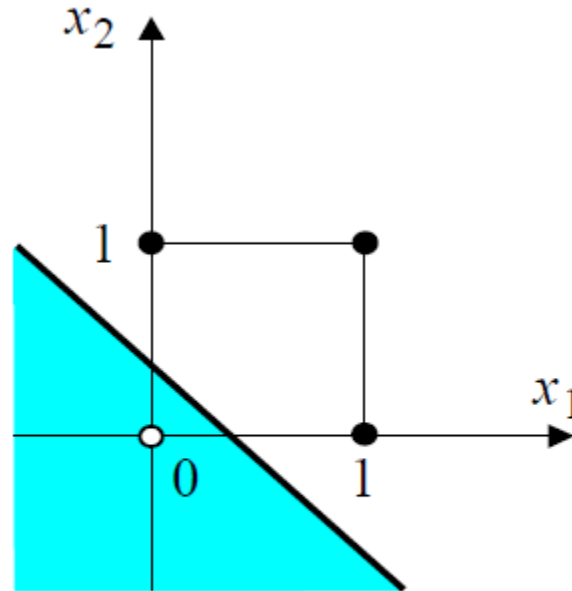
How a perceptron learns

| Epoch | x_1 | x_2 | y_d | w_1 | w_2 | y_a | Error | w_1^{new} | w_2^{new} | MSE |
|-------|-------|-------|-------|-------|-------|-------|-------|-------------|-------------|-----|
| 1 | 0 | 0 | 0 | 0.3 | -0.1 | | | | | |
| | 0 | 1 | 0 | | | | | | | |
| | 1 | 0 | 0 | | | | | | | |
| | 1 | 1 | 1 | | | | | | | |
| 2 | 0 | 0 | 0 | | | | | | | |
| | 0 | 1 | 0 | | | | | | | |
| | 1 | 0 | 0 | | | | | | | |
| | 1 | 1 | 1 | | | | | | | |
| 3 | 0 | 0 | 0 | | | | | | | |
| | 0 | 1 | 0 | | | | | | | |
| | 1 | 0 | 0 | | | | | | | |
| | 1 | 1 | 1 | | | | | | | |

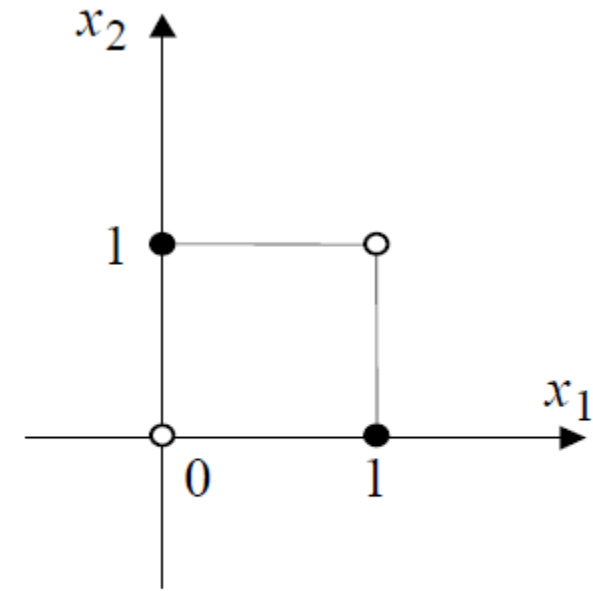
How a perceptron learns : Decision Boundary



(a) *AND* ($x_1 \cap x_2$)

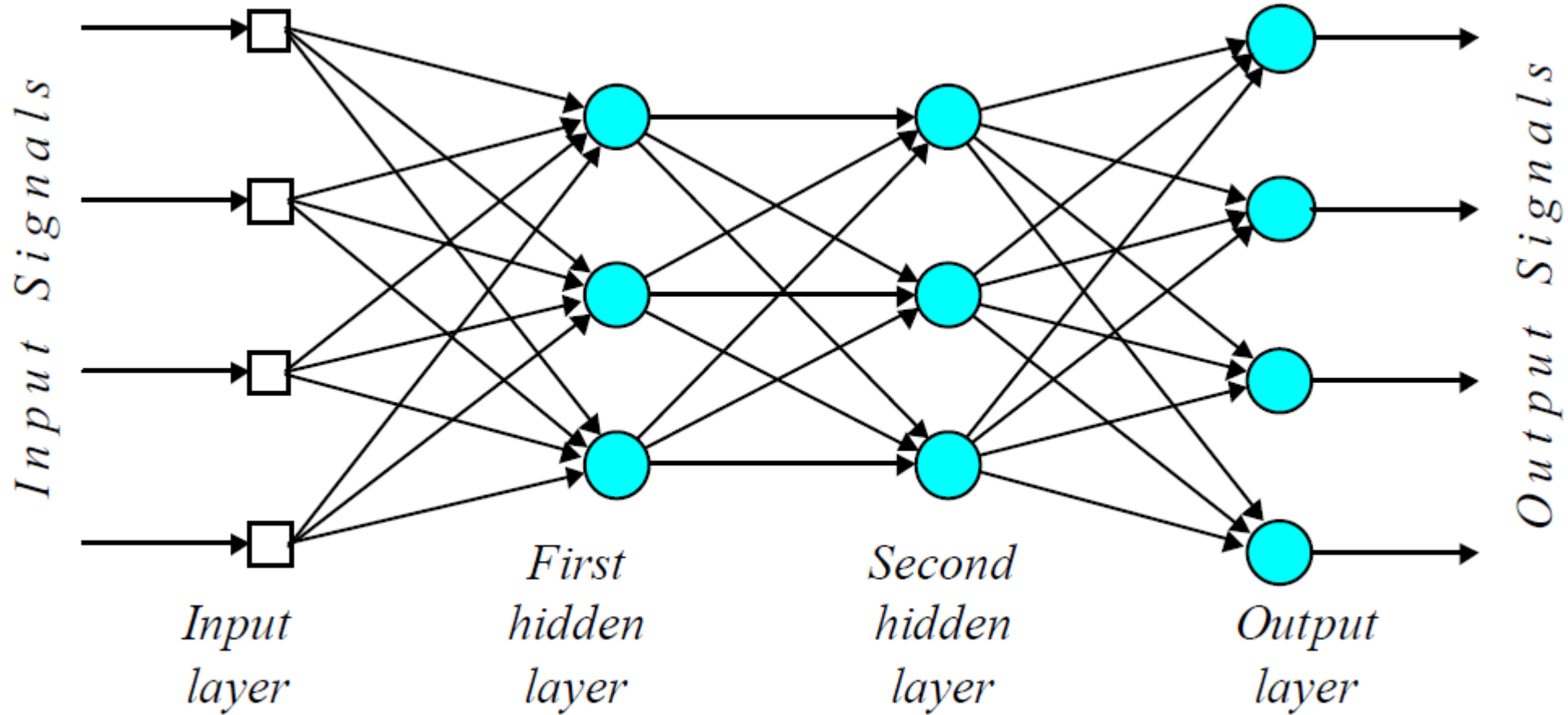


(b) *OR* ($x_1 \cup x_2$)



(c) *Exclusive-OR*
($x_1 \oplus x_2$)

Multi Layer Perceptron



Multi Layer Perceptron: Weight Updation

Neuron out at layer “k”

$$y_k(p) = \text{sigmoid} \left[\sum_{j=1}^m x_{jk}(p) \cdot w_{jk}(p) - \theta_k \right]$$

Error at layer “k”

$$e_k(p) = y_{d,k}(p) - y_k(p)$$

Error gradient at layer “k”

$$\delta_k(p) = y_k(p) \cdot [1 - y_k(p)] \cdot e_k(p)$$

Change in weight

$$\Delta w_{jk}(p) = \alpha \cdot y_j(p) \cdot \delta_k(p)$$

Weight Updation

$$w_{jk}(p+1) = w_{jk}(p) + \Delta w_{jk}(p)$$

Error gradient at layer “j”

$$\delta_j(p) = y_j(p) \cdot [1 - y_j(p)] \cdot \sum_{k=1}^l \delta_k(p) w_{jk}(p)$$

Change in weight

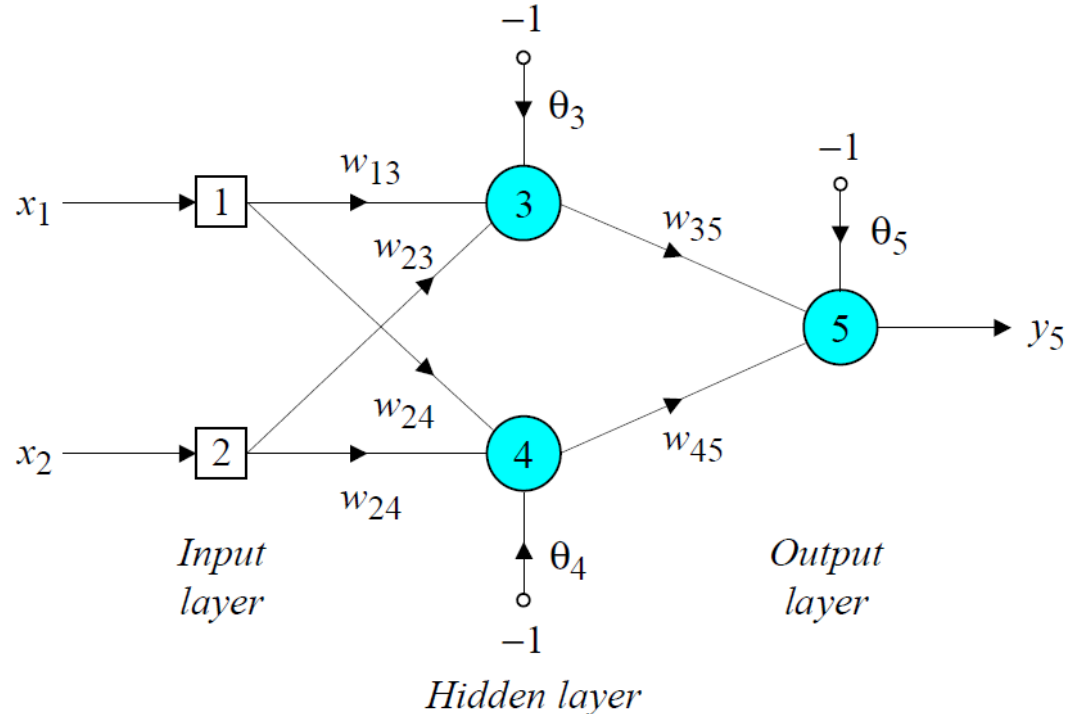
$$\Delta w_{ij}(p) = \alpha \cdot x_i(p) \cdot \delta_j(p)$$

Weight Updation

$$w_{ij}(p+1) = w_{ij}(p) + \Delta w_{ij}(p)$$

XOR Problem

| x_1 | x_2 | w_{13} | w_{23} | θ_3 | y_3 | w_{14} | w_{24} | θ_4 | y_4 | w_{35} | w_{45} | θ_5 | y_d | y_5 | E | w_{13}' | w_{23}' | θ_4' | w_{14}' | w_{24}' | θ_4' | w_{35}' | w_{45}' | θ_5' |
|-------|-------|----------|----------|------------|-------|----------|----------|------------|-------|----------|----------|------------|-------|-------|-----|-----------|-----------|-------------|-----------|-----------|-------------|-----------|-----------|-------------|
| 1 | 1 | 0.5 | 0.4 | 0.8 | | 0.9 | 1.0 | -0.1 | | -1.2 | 1.1 | 0.3 | 0 | | | | | | | | | | | |
| 0 | 1 | | | | | | | | | | | | 1 | | | | | | | | | | | |
| 1 | 0 | | | | | | | | | | | | 1 | | | | | | | | | | | |
| 0 | 0 | | | | | | | | | | | | 0 | | | | | | | | | | | |



$$y_3 = \text{sigmoid}(x_1 w_{13} + x_2 w_{23} - \theta_3) = 1 / \left[1 + e^{-(1 \cdot 0.5 + 1 \cdot 0.4 - 0.8)} \right] = 0.5250$$

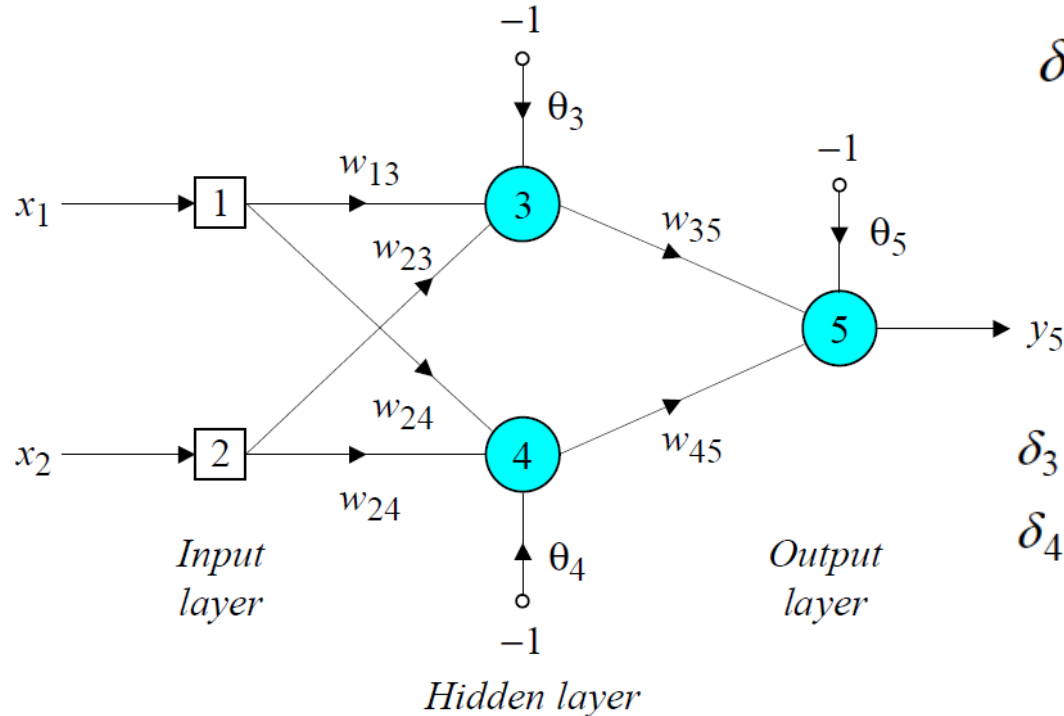
$$y_4 = \text{sigmoid}(x_1 w_{14} + x_2 w_{24} - \theta_4) = 1 / \left[1 + e^{-(1 \cdot 0.9 + 1 \cdot 1.0 - 0.1)} \right] = 0.8808$$

$$y_5 = \text{sigmoid}(y_3 w_{35} + y_4 w_{45} - \theta_5) = 1 / \left[1 + e^{-(0.5250 \cdot 1.2 + 0.8808 \cdot 1.1 - 0.3)} \right] = 0.5097$$

$$e = y_{d,5} - y_5 = 0 - 0.5097 = -0.5097$$

XOR Problem

| x_1 | x_2 | w_{13} | w_{23} | θ_3 | y_3 | w_{14} | w_{24} | θ_4 | y_4 | w_{35} | w_{45} | θ_5 | y_d | y_5 | E | w_{13}' | w_{23}' | θ_4' | w_{14}' | w_{24}' | θ_4' | w_{35}' | w_{45}' | θ_5' |
|-------|-------|----------|----------|------------|-------|----------|----------|------------|-------|----------|----------|------------|-------|-------|------|-----------|-----------|-------------|-----------|-----------|-------------|-----------|-----------|-------------|
| 1 | 1 | 0.5 | 0.4 | 0.8 | 0.52 | 0.9 | 1.0 | -0.1 | 0.88 | -1.2 | 1.1 | 0.3 | 0 | 0.50 | -0.5 | | | | | | | | | |
| 0 | 1 | | | | | | | | | | | | 1 | | | | | | | | | | | |
| 1 | 0 | | | | | | | | | | | | 1 | | | | | | | | | | | |
| 0 | 0 | | | | | | | | | | | | 0 | | | | | | | | | | | |



$$\delta_5 = y_5 (1 - y_5) e = 0.5097 \cdot (1 - 0.5097) \cdot (-0.5097) = -0.1274$$

$$\Delta w_{35} = \alpha \cdot y_3 \cdot \delta_5 = 0.1 \cdot 0.5250 \cdot (-0.1274) = -0.0067$$

$$\Delta w_{45} = \alpha \cdot y_4 \cdot \delta_5 = 0.1 \cdot 0.8808 \cdot (-0.1274) = -0.0112$$

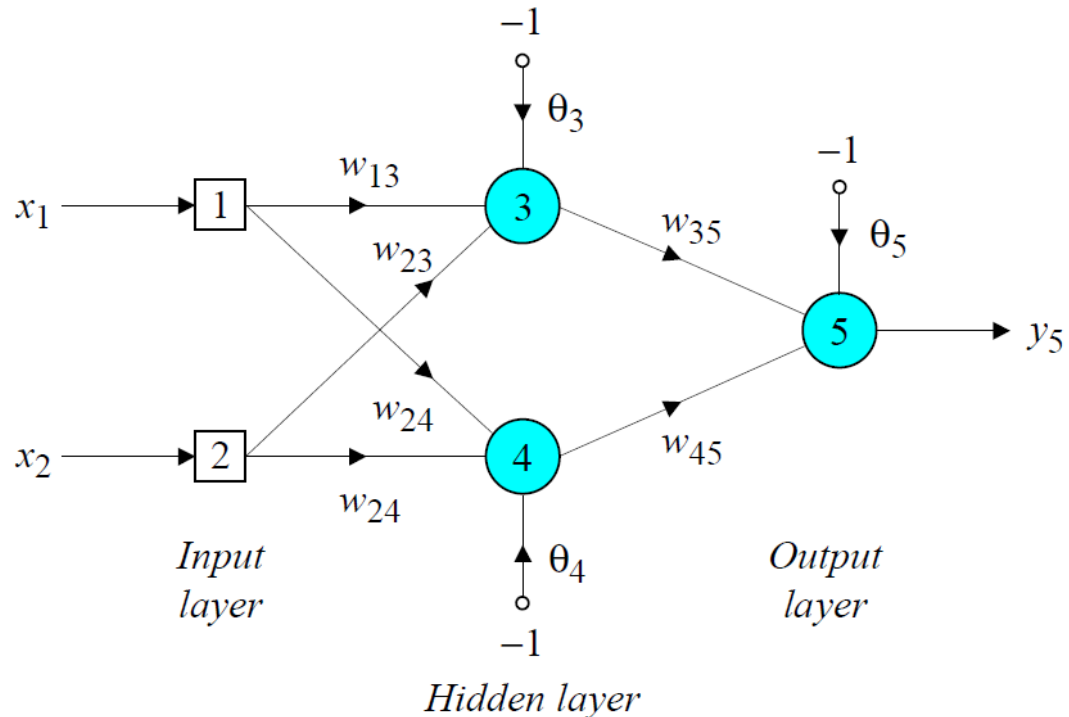
$$\Delta \theta_5 = \alpha \cdot (-1) \cdot \delta_5 = 0.1 \cdot (-1) \cdot (-0.1274) = -0.0127$$

$$\delta_3 = y_3 (1 - y_3) \cdot \delta_5 \cdot w_{35} = 0.5250 \cdot (1 - 0.5250) \cdot (-0.1274) \cdot (-1.2) = 0.0381$$

$$\delta_4 = y_4 (1 - y_4) \cdot \delta_5 \cdot w_{45} = 0.8808 \cdot (1 - 0.8808) \cdot (-0.1274) \cdot 1.1 = -0.0147$$

XOR Problem

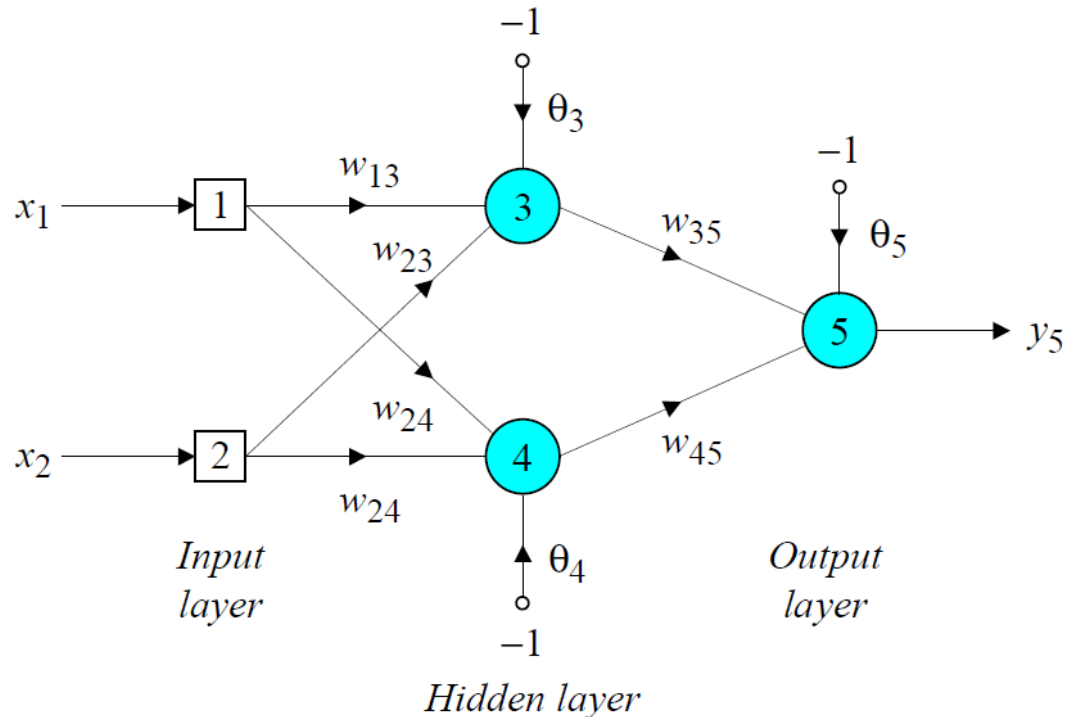
| x_1 | x_2 | w_{13} | w_{23} | θ_3 | y_3 | w_{14} | w_{24} | θ_4 | y_4 | w_{35} | w_{45} | θ_5 | y_d | y_5 | E | w_{13}' | w_{23}' | θ_4' | w_{14}' | w_{24}' | θ_4' | w_{35}' | w_{45}' | θ_5' |
|-------|-------|----------|----------|------------|-------|----------|----------|------------|-------|----------|----------|------------|-------|-------|------|-----------|-----------|-------------|-----------|-----------|-------------|-----------|-----------|-------------|
| 1 | 1 | 0.5 | 0.4 | 0.8 | 0.52 | 0.9 | 1.0 | -0.1 | 0.88 | -1.2 | 1.1 | 0.3 | 0 | 0.50 | -0.5 | | | | | | | | | |
| 0 | 1 | | | | | | | | | | | | 1 | | | | | | | | | | | |
| 1 | 0 | | | | | | | | | | | | 1 | | | | | | | | | | | |
| 0 | 0 | | | | | | | | | | | | 0 | | | | | | | | | | | |



$$\begin{aligned}\Delta w_{13} &= \alpha \cdot x_1 \cdot \delta_3 = 0.1 \cdot 1 \cdot 0.0381 = 0.0038 \\ \Delta w_{23} &= \alpha \cdot x_2 \cdot \delta_3 = 0.1 \cdot 1 \cdot 0.0381 = 0.0038 \\ \Delta \theta_3 &= \alpha \cdot (-1) \cdot \delta_3 = 0.1 \cdot (-1) \cdot 0.0381 = -0.0038 \\ \Delta w_{14} &= \alpha \cdot x_1 \cdot \delta_4 = 0.1 \cdot 1 \cdot (-0.0147) = -0.0015 \\ \Delta w_{24} &= \alpha \cdot x_2 \cdot \delta_4 = 0.1 \cdot 1 \cdot (-0.0147) = -0.0015 \\ \Delta \theta_4 &= \alpha \cdot (-1) \cdot \delta_4 = 0.1 \cdot (-1) \cdot (-0.0147) = 0.0015\end{aligned}$$

XOR Problem

| x_1 | x_2 | w_{13} | w_{23} | θ_3 | y_3 | w_{14} | w_{24} | θ_4 | y_4 | w_{35} | w_{45} | θ_5 | y_d | y_5 | E | w_{13}' | w_{23}' | θ_3' | w_{14}' | w_{24}' | θ_4' | w_{35}' | w_{45}' | θ_5' |
|-------|-------|----------|----------|------------|-------|----------|----------|------------|-------|----------|----------|------------|-------|-------|------|-----------|-----------|-------------|-----------|-----------|-------------|-----------|-----------|-------------|
| 1 | 1 | 0.5 | 0.4 | 0.8 | 0.52 | 0.9 | 1.0 | -0.1 | 0.88 | -1.2 | 1.1 | 0.3 | 0 | 0.50 | -0.5 | 0.50 | 0.40 | 0.79 | 0.89 | 0.99 | -0.09 | -1.2 | 1.08 | 0.31 |
| 0 | 1 | | | | | | | | | | | | 1 | | | | | | | | | | | |
| 1 | 0 | | | | | | | | | | | | 1 | | | | | | | | | | | |
| 0 | 0 | | | | | | | | | | | | 0 | | | | | | | | | | | |



$$w_{13} = w_{13} + \Delta w_{13} = 0.5 + 0.0038 = 0.5038$$

$$w_{14} = w_{14} + \Delta w_{14} = 0.9 - 0.0015 = 0.8985$$

$$w_{23} = w_{23} + \Delta w_{23} = 0.4 + 0.0038 = 0.4038$$

$$w_{24} = w_{24} + \Delta w_{24} = 1.0 - 0.0015 = 0.9985$$

$$w_{35} = w_{35} + \Delta w_{35} = -1.2 - 0.0067 = -1.2067$$

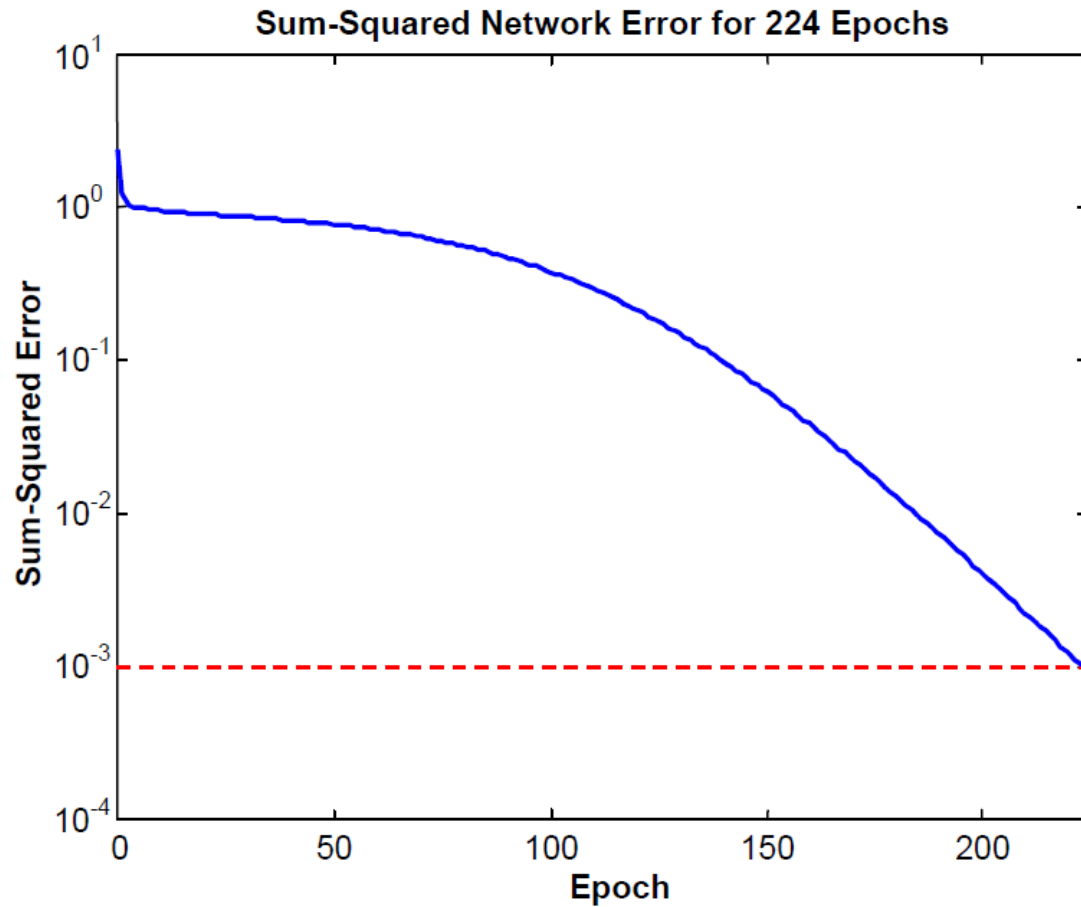
$$w_{45} = w_{45} + \Delta w_{45} = 1.1 - 0.0112 = 1.0888$$

$$\theta_3 = \theta_3 + \Delta \theta_3 = 0.8 - 0.0038 = 0.7962$$

$$\theta_4 = \theta_4 + \Delta \theta_4 = -0.1 + 0.0015 = -0.0985$$

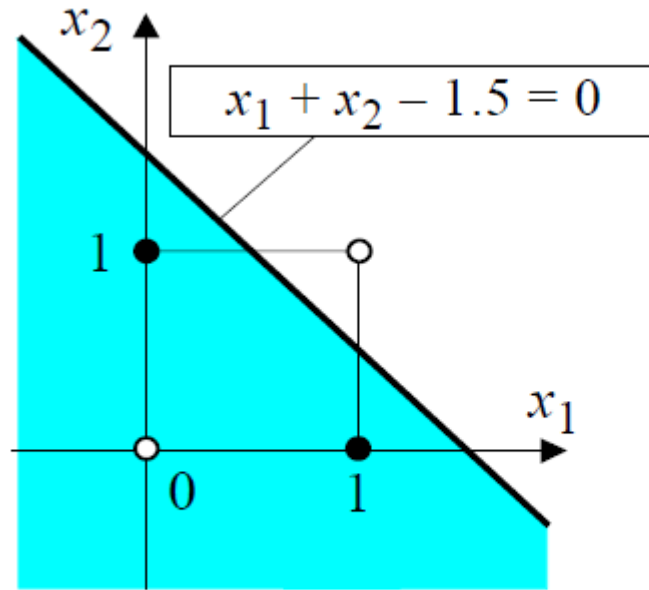
$$\theta_5 = \theta_5 + \Delta \theta_5 = 0.3 + 0.0127 = 0.3127$$

XOR Problem

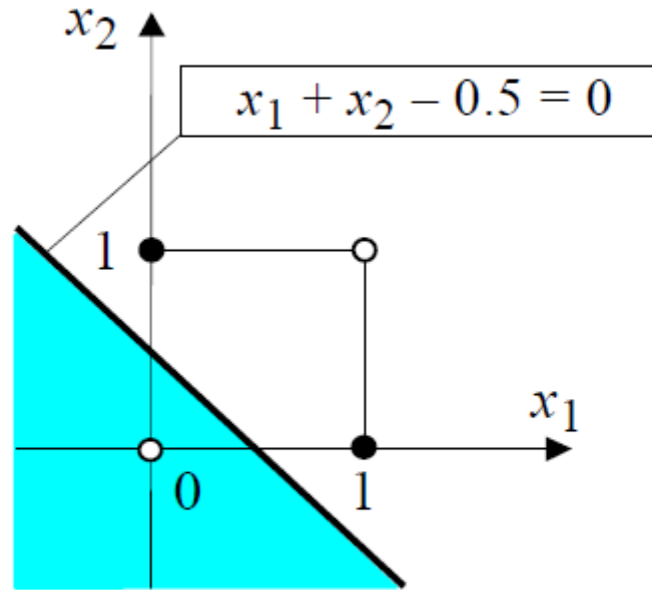


| Inputs | | Desired output | Actual output | Error | Sum of squared errors |
|--------|-------|----------------|---------------|---------|-----------------------|
| x_1 | x_2 | y_d | y_5 | e | |
| 1 | 1 | 0 | 0.0155 | -0.0155 | 0.0010 |
| 0 | 1 | 1 | 0.9849 | 0.0151 | |
| 1 | 0 | 1 | 0.9849 | 0.0151 | |
| 0 | 0 | 0 | 0.0175 | -0.0175 | |

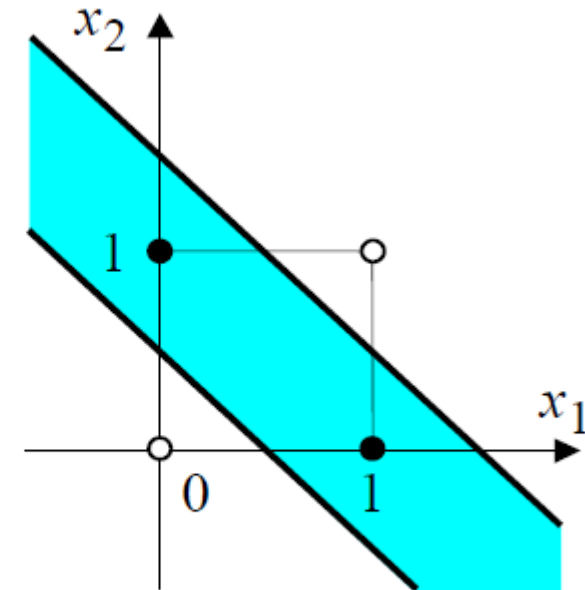
XOR Problem



(a)



(b)



(c)

- a) Decision boundary created by hidden neuron 3
- b) Decision boundary created by hidden neuron 4
- c) Decision boundary created by output neuron 5

