Light Play Arduino firmware commands for use with iPad

Version 0.2 of the Light Play hardware can control 3 rainbow lights and 1 motor. The board has two inputs for resistive sensors.

Light Commands

set [all lights, light 1, light 2, light 3] **color to** [12-bit RGBW values]
off [all lights, light 1, light 2, light 3]
fade [all lights, light 1, light 2, light 3] **to** [12-bit RGBW values]
fade out [all lights, light 1, light 2, light 3]
set brightness [all lights, light 1, light 2, light 3] [8-bit value]
set fade speed [8-bit value]

Motor Commands

on thisway
on thatway
off
set motor speed [8-bit value]

Sensor Reporting

tbd

Byte Codes

All light and motor commands are encoded in a single byte sent from Scratch to Arduino, according to the following scheme:

Command format

[u u u x x y y y]
upper bits set command type:
000 = light commands
001 = motor commands
010 = other

light commands

[0 0 0 x x y y y]

the *x* bits select which light:

- 0 0 = all lights
- 0 1 = light 1
- 1 0 = light 2
- 1 1 = light 3

the *y* bits select which light command:

- 0 0 0 = **set lightcolor to (RGBW values follow in next 8 bytes)**
- 0 0 1 = **turn off light**
- 0 1 0 = **fade lightcolor to (RGBW values follow in next 8 bytes)**
- 0 1 1 = **fade out light**
- 1 0 0 = **set brightness (value follows in next byte)**

1 0 1 - **set fade speed (value follows in next byte)**

Motor commands

[0 0 1 x x y y y]

the *x* bits are set to zero (it's important to avoid sending byte 0x2B, which is ASCII '+', since this is used by the Adafruit BTLE UART to switch to command mode)

the *y* bits select which motor command:

0 0 0 = **turn on motor thisway**
0 0 1 = **turn on motor thatway**
0 1 0 = **motor off**
0 1 1 = **set motor speed (value follows in next byte)**

Other commands

reset state variables

[0 1 0 0 0 0 0 0]

stop

[0 1 0 0 0 0 0 1]

Reporting

Arduino can stream sensor values at ~ 10 Hz using a protocol to be determined. We'll also have to figure out a way to support the Arduino reporting "fade complete" in a way that's distinguishable from the sensor values.