view_frames Result Recorded at time: 1474673889.686 base_link Broadcaster: /robot_state_publisher Average rate: 20.106 Hz Most recent transform: 1474673889.681 (0.006 sec old) Buffer length: 4.924 sec geoJoint1 Broadcaster: /robot_state_publisher Average rate: 20.106 Hz Most recent transform: 1474673889.681 (0.006 sec old) Buffer length: 4.924 sec geoJoint2 Broadcaster: /robot_state_publisher Average rate: 20.106 Hz Most recent transform: 1474673889.681 (0.006 sec old) Buffer length: 4.924 sec geoJoint3 Broadcaster: /robot_state_publisher Average rate: 20.106 Hz Most recent transform: 1474673889.681 (0.006 sec old) Buffer length: 4.924 sec geoJoint4 Broadcaster: /robot_state_publisher Average rate: 20.106 Hz Most recent transform: 1474673889.681 (0.006 sec old) Buffer length: 4.924 sec geoJoint5 Broadcaster: /robot_state_publisher Average rate: 20.106 Hz Most recent transform: 1474673889.681 (0.006 sec old) Buffer length: 4.924 sec geoJoint6 Broadcaster: /robot_state_publisher Average rate: 50.205 Hz Most recent transform: 1474673890.178 (-0.492 sec old) Buffer length: 4.940 sec gripperBody Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.106 Hz Average rate: 20.106 Hz Most recent transform: 1474673889.681 (0.006 sec old) Most recent transform: 1474673889.681 (0.006 sec old) Buffer length: 4.924 sec Buffer length: 4.924 sec gripperFinger1 gripperFinger2