# Post-processing smoothness prior reconstructions using CNNs

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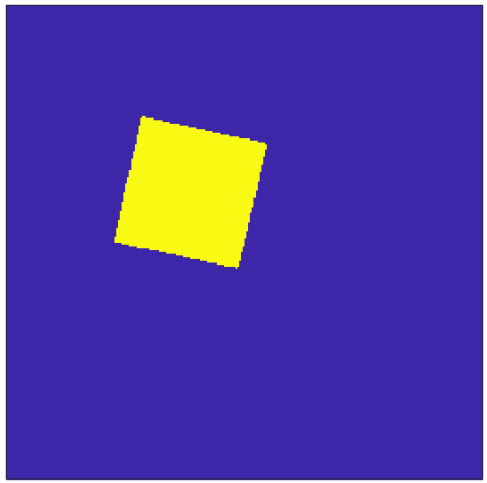
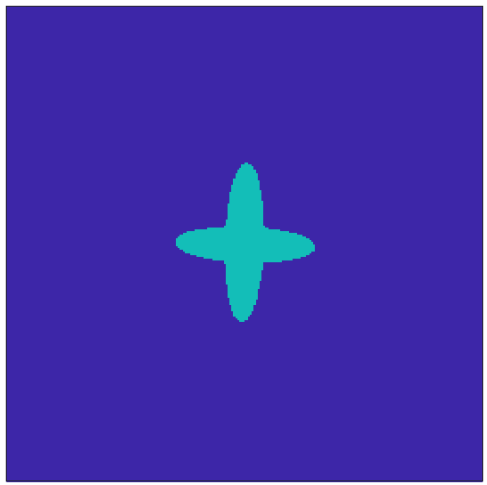
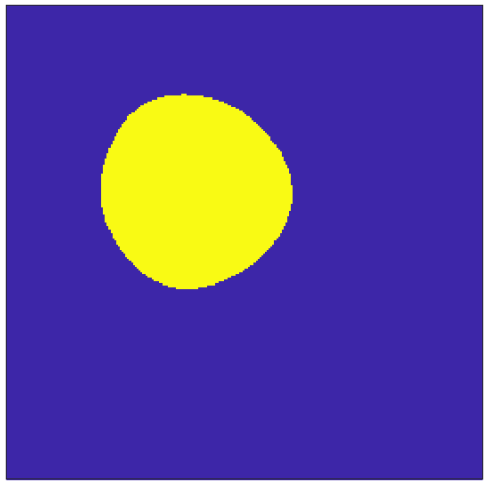
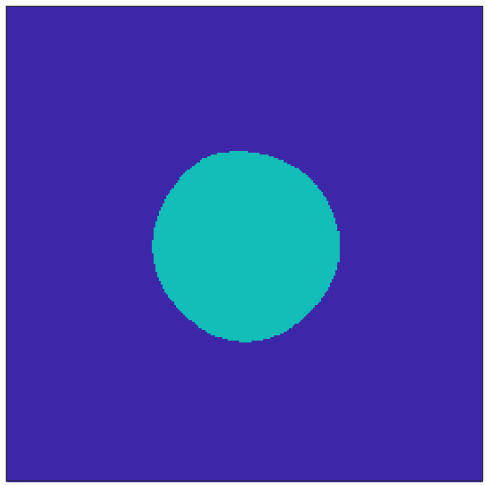
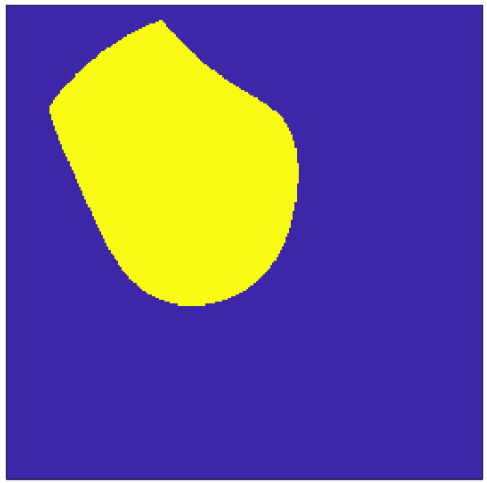
# Github repository

These slides are related to the code available at
https://github.com/robert-abc/KTC2023-ABC1/
to join the Kuopio Tomography Challenge 2023
https://www.fips.fi/KTC2023.php

# KTC example code (Smoothness Prior) [1]

**One-step reconstruction**: $\Delta\sigma = (\mathbf{J}^T\Gamma_n\mathbf{J} + \mathbf{L}^T\mathbf{L})^{-1}\mathbf{J}^T\Gamma_n\Delta\mathbf{v}$

Ground truth | Level 1 | Level 7

# We submitted two proposals:

1. Post-processing the Smoothness Prior reconstruction to extract meaningful information
   - github.com/robert-abc/KTC2023-ABC1/
   - Score: 12.75
2. Deep Image Prior with total variation regularization
   - github.com/robert-abc/KTC2023-ABC2/
   - Score: 11.25

In this slides, we illustrate the first proposal (Matlab version)

# Proposal Summary (Matlab Version)

There are six steps to reconstruct and segment the results:

1. Reconstruction with smoothness prior
2. Soft thresholding
3. Denoising and deblurring using a CNN
4. Thresholding
5. Opening (morphological filter)
6. Segmentation using Otsu's method

This is the original version, as submitted to KTC2023.

# Step-by-step visualization

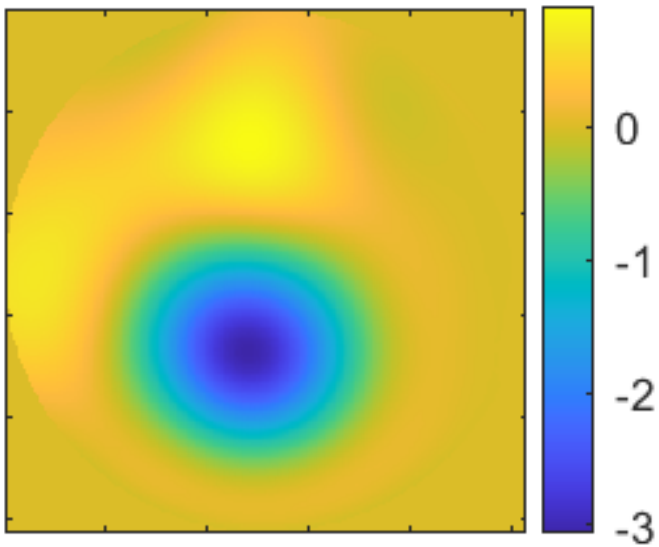
Next slides: Case 2, level 7 from the training set.

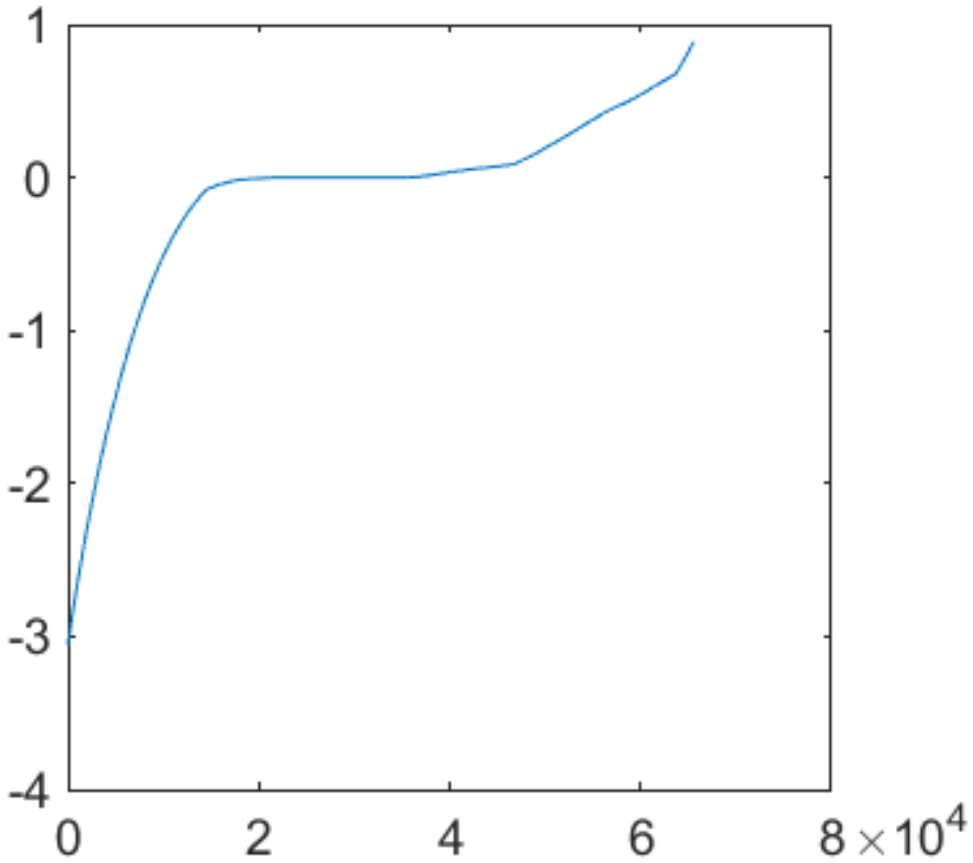
The figures on the left are the outputs of each step.

The figures on the right are the sorted visualizations, in ascending order, of the pixel values from the figures on the left.

# Step 1/6: Smoothness Prior

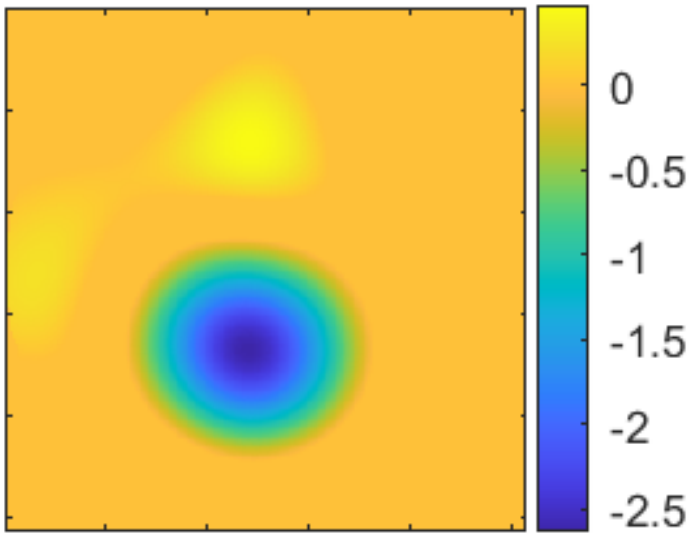
**One-step reconstruction**: $\Delta\sigma = (\mathbf{J}^T\Gamma_n\mathbf{J} + \mathbf{20}\mathbf{L}^T\mathbf{L})^{-1}\mathbf{J}^T\Gamma_n\Delta\mathbf{v}$

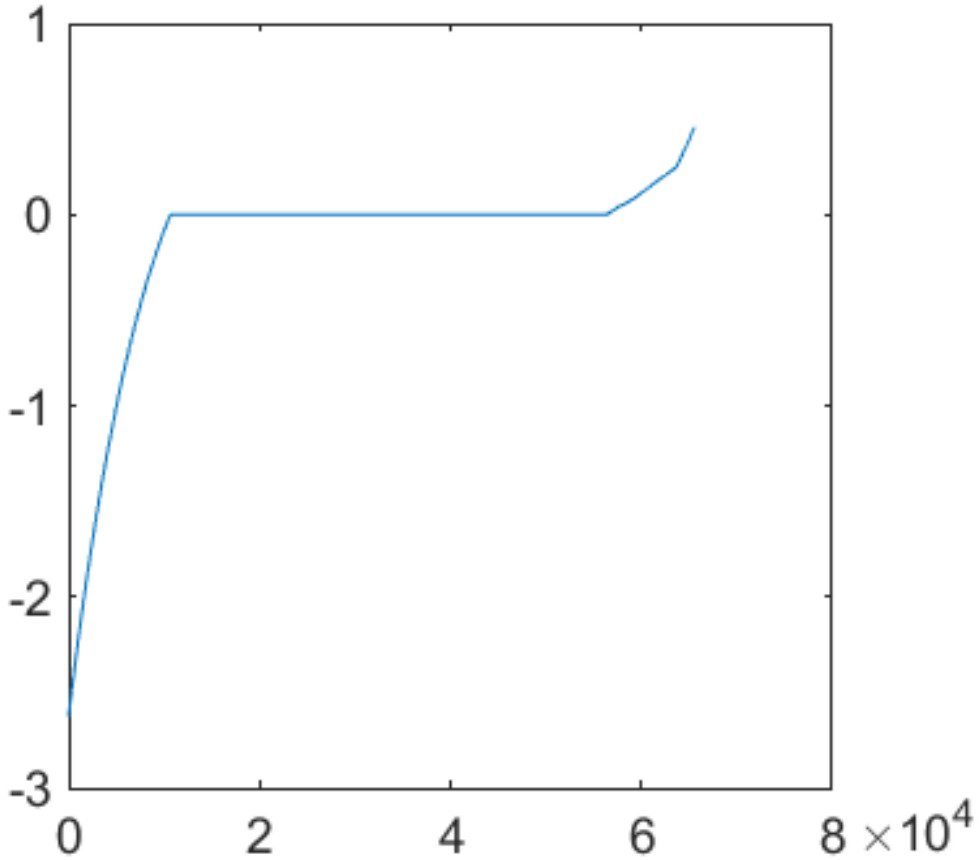


# Step 2/6: Soft thresholding

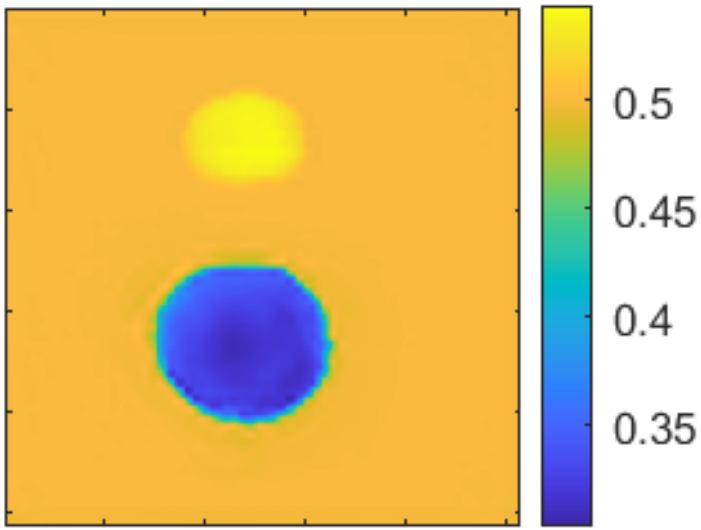
**Threshold value**: Proportional to the highest value of $\Delta\sigma$ from Step 1:
$T = max(abs(\Delta\sigma)) * 0.14$

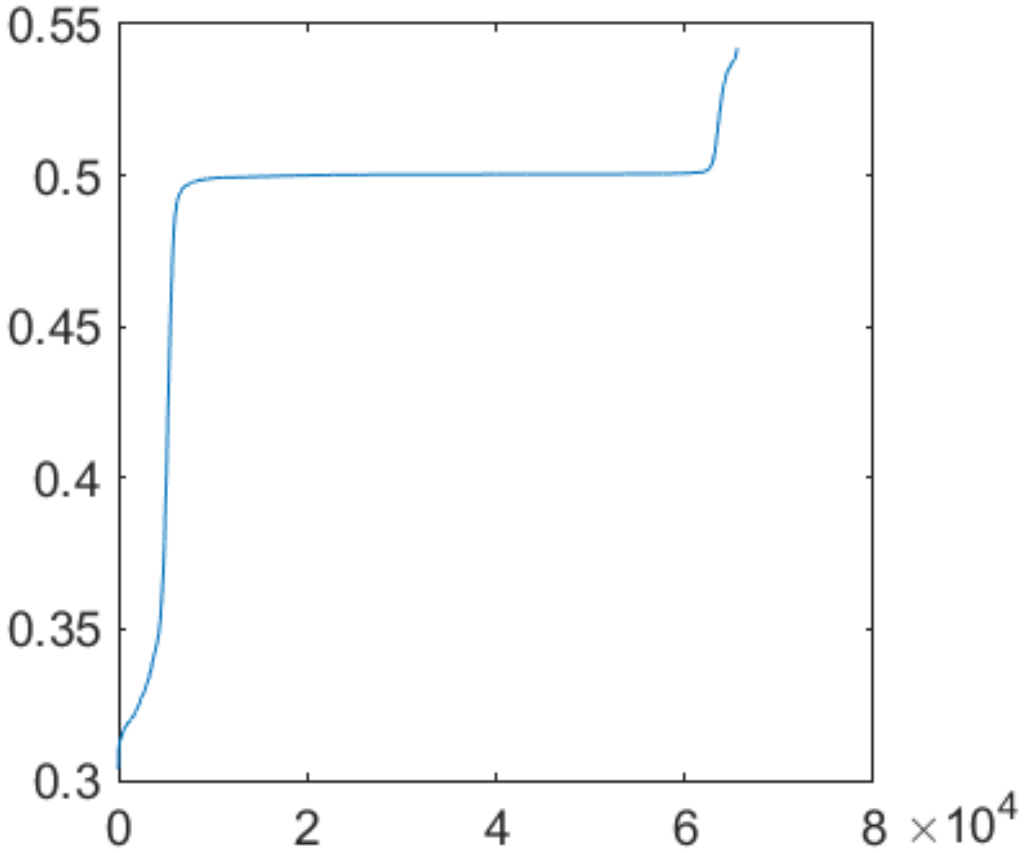


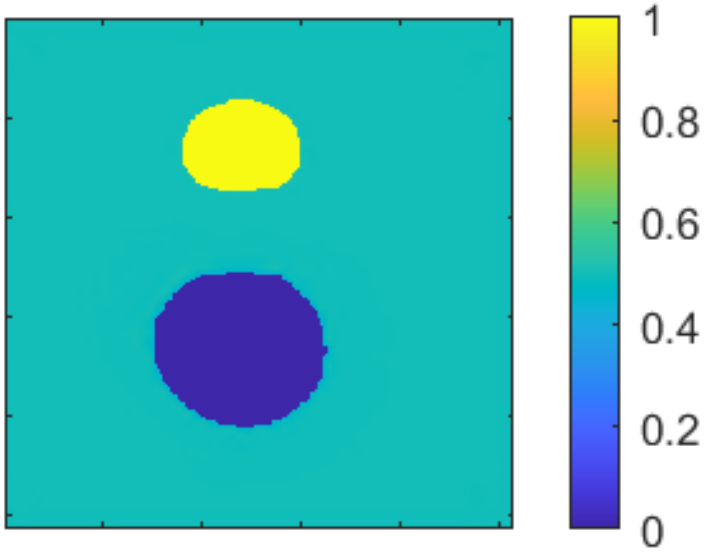
# Step 3/6: Denoising and deblurring using a CNN

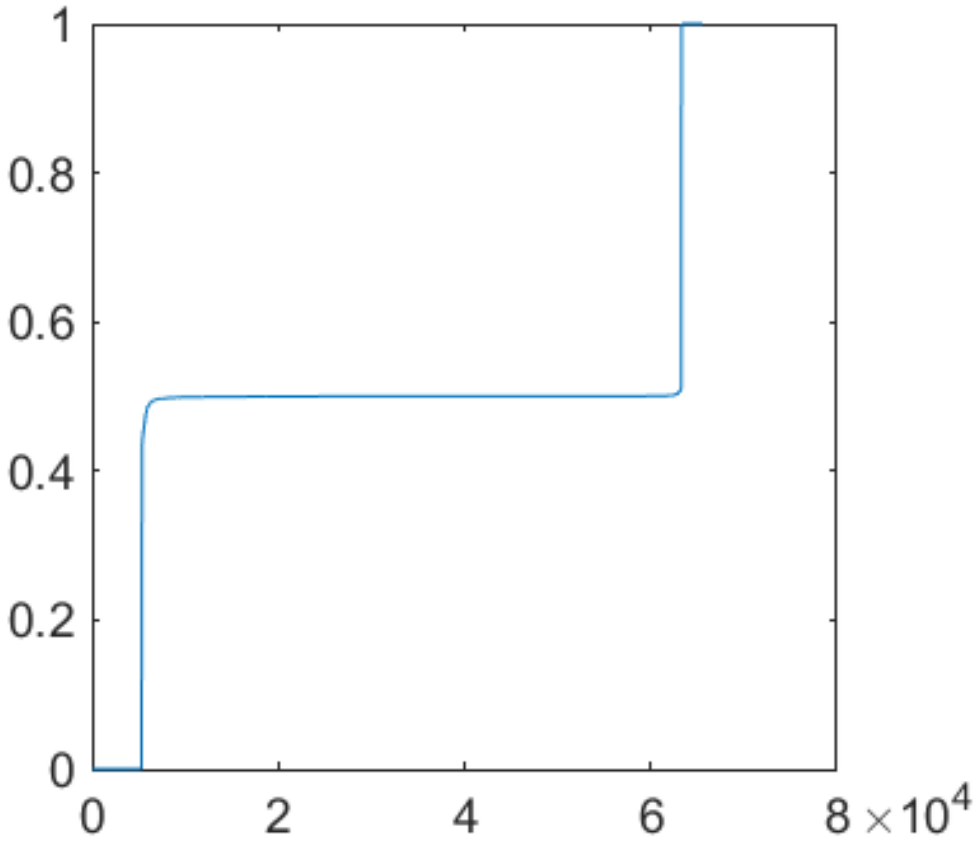
See slides 13-20 for CNN details



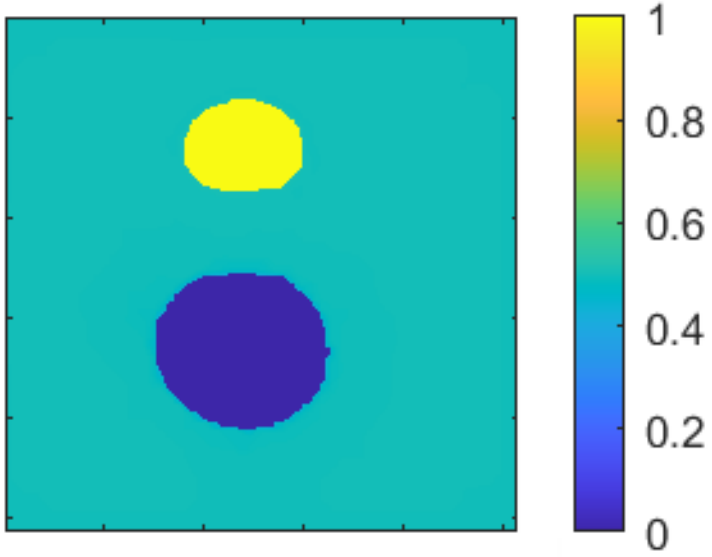
# Step 4/6: New thresholding

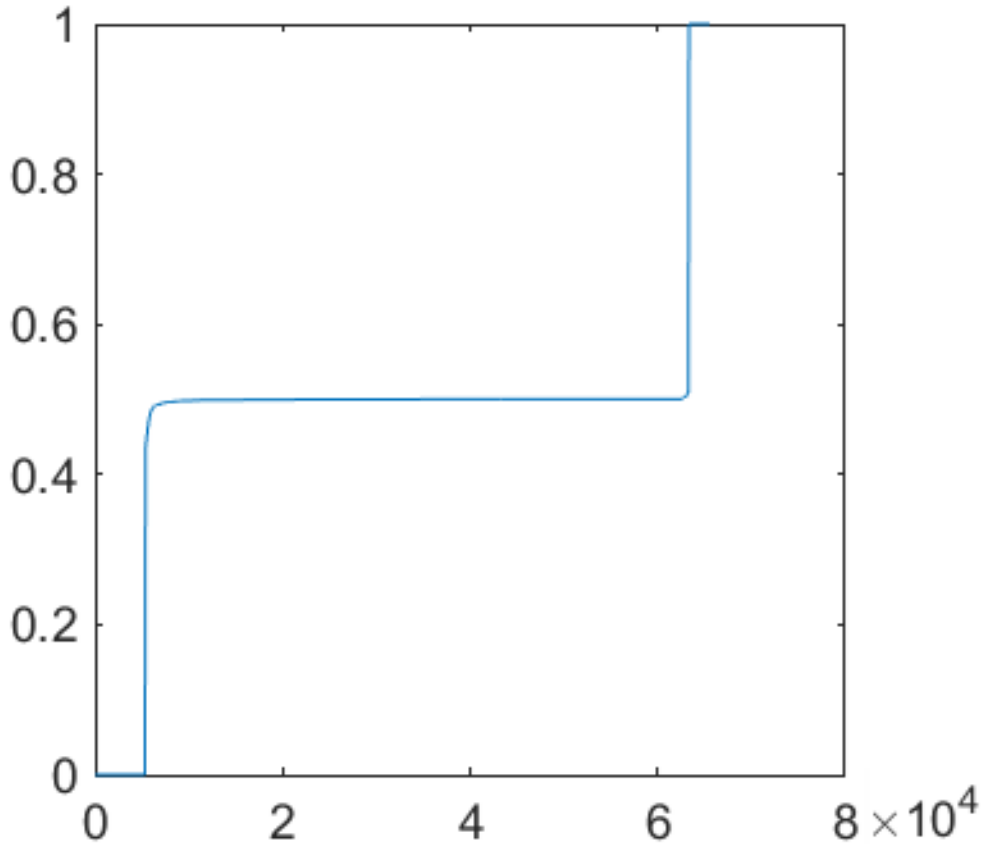



- c1 = (max($\Delta\sigma$) - 0.50)./4;
- $\Delta\sigma(\Delta\sigma > 0.5 + \text{c1}) = 1$;
- c2 = (min($\Delta\sigma$) - 0.50)./4;
- $\Delta\sigma(\Delta\sigma < 0.48 + \text{c2}) = 0$;

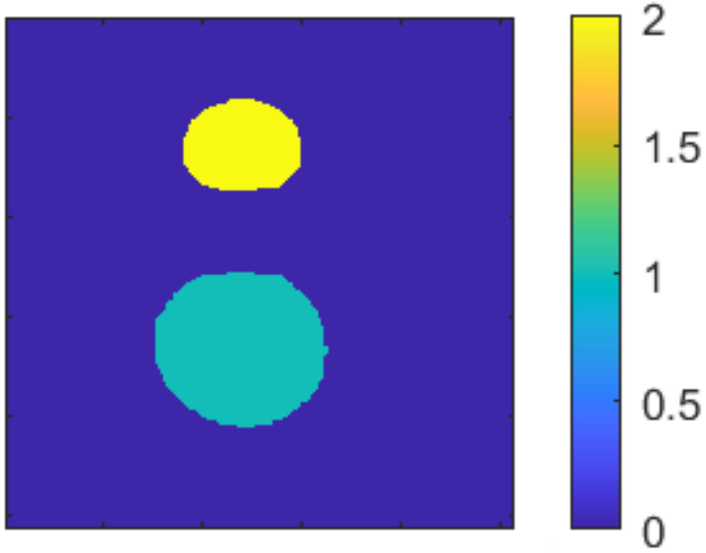
# Step 5/6: Opening morphological filter

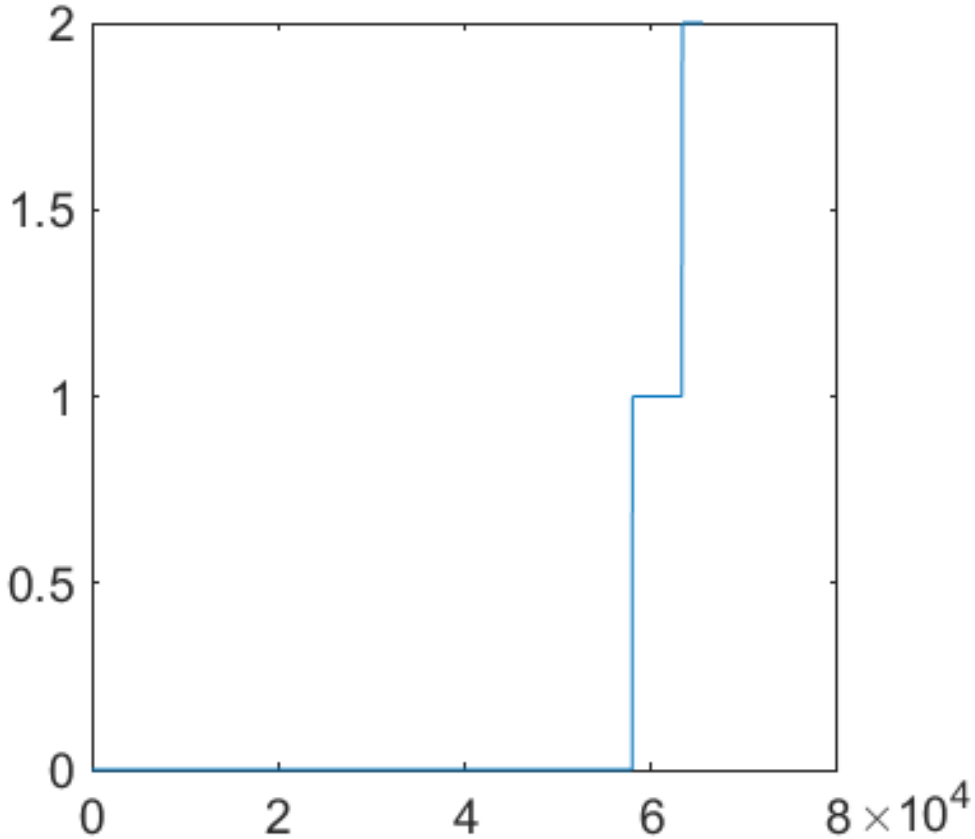


# Step 6/6: Segmentation using Otsu's method

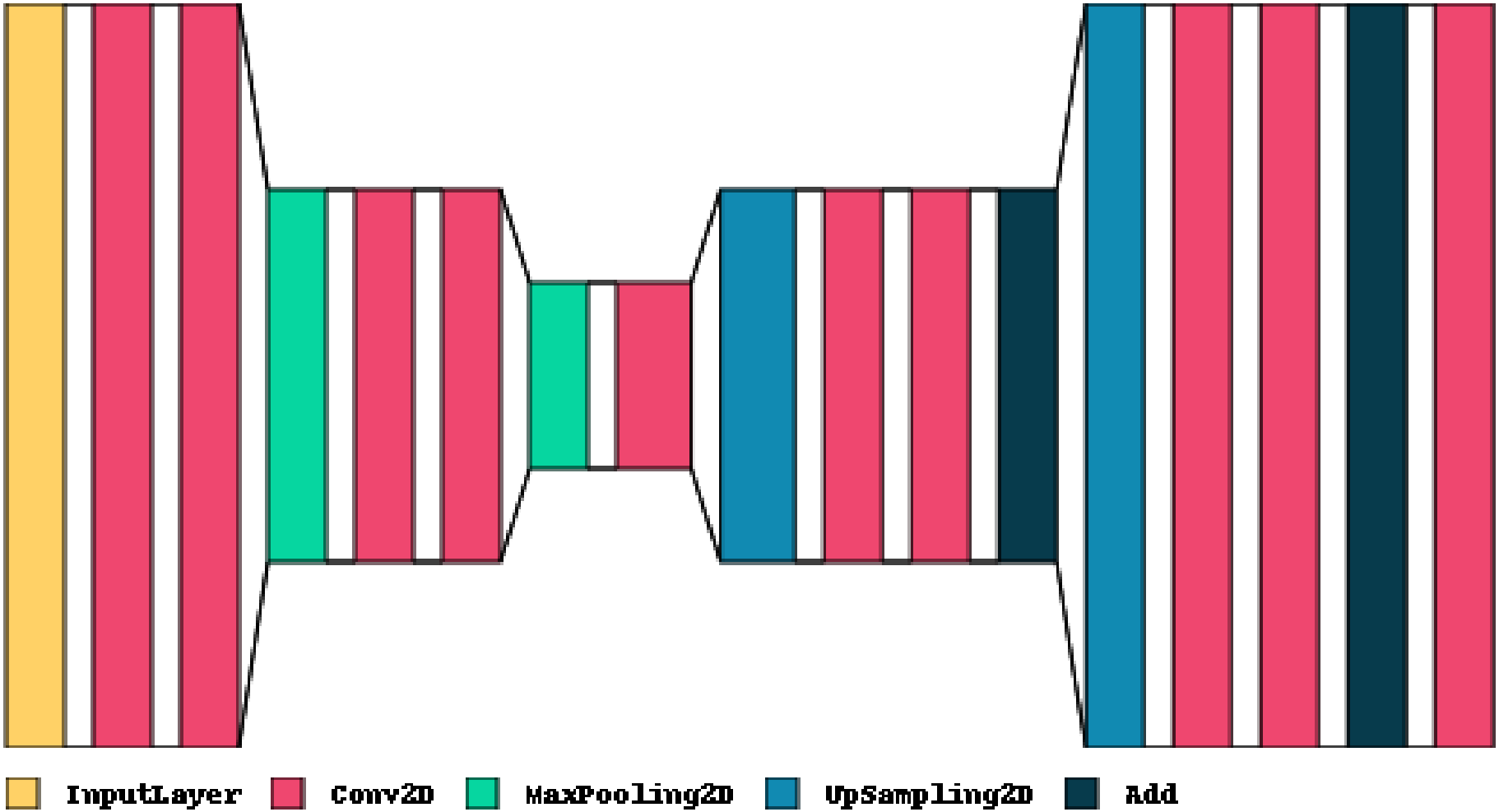
After the segmentation, the class are attributed to the targets (2 for conductive, 1 for resistive).



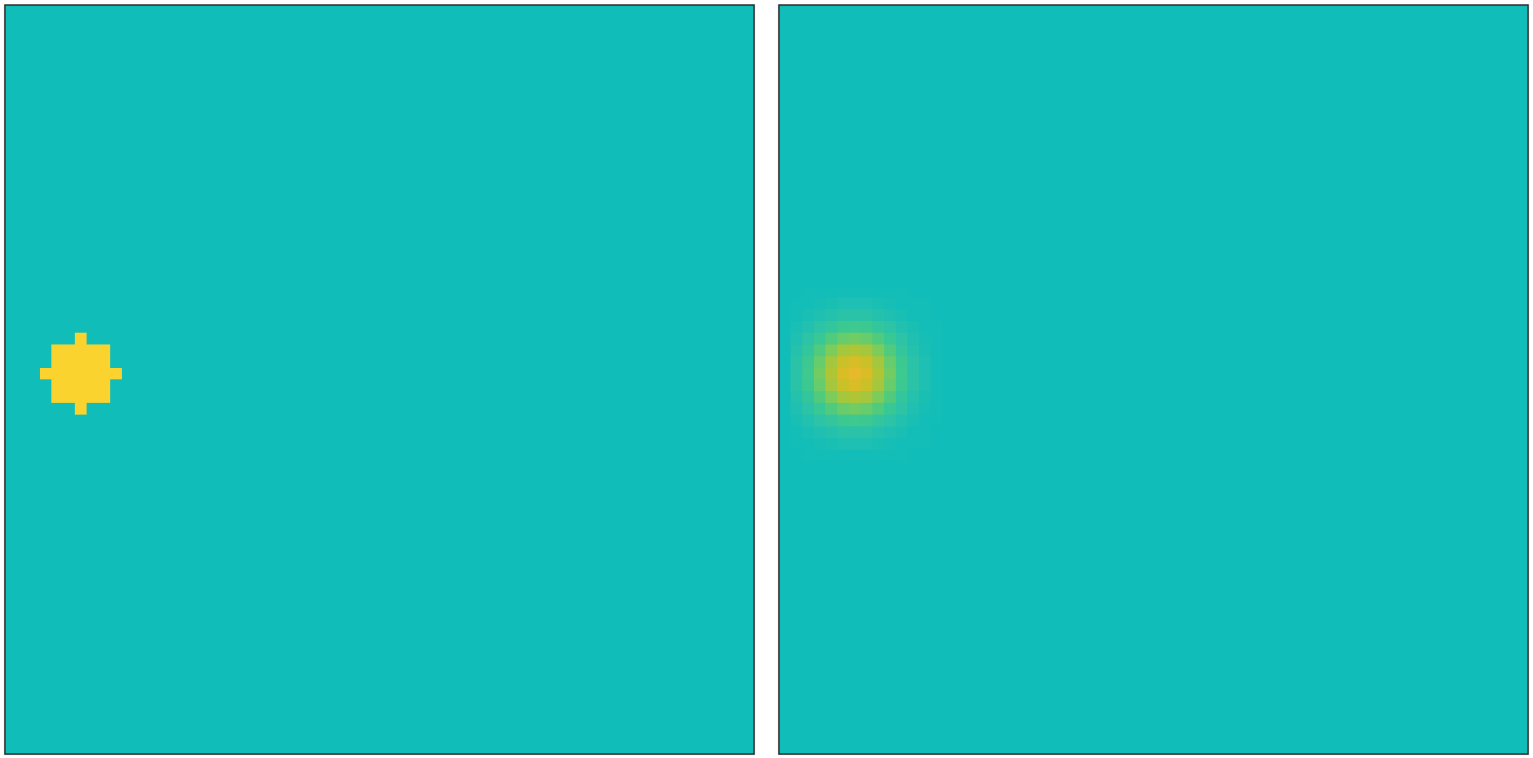
# CNN details

# CNN architecture (See [2] for more information)



# CNN training set: Samples (Available at [2])

Pair: Ground truth (left). Blurred (right)

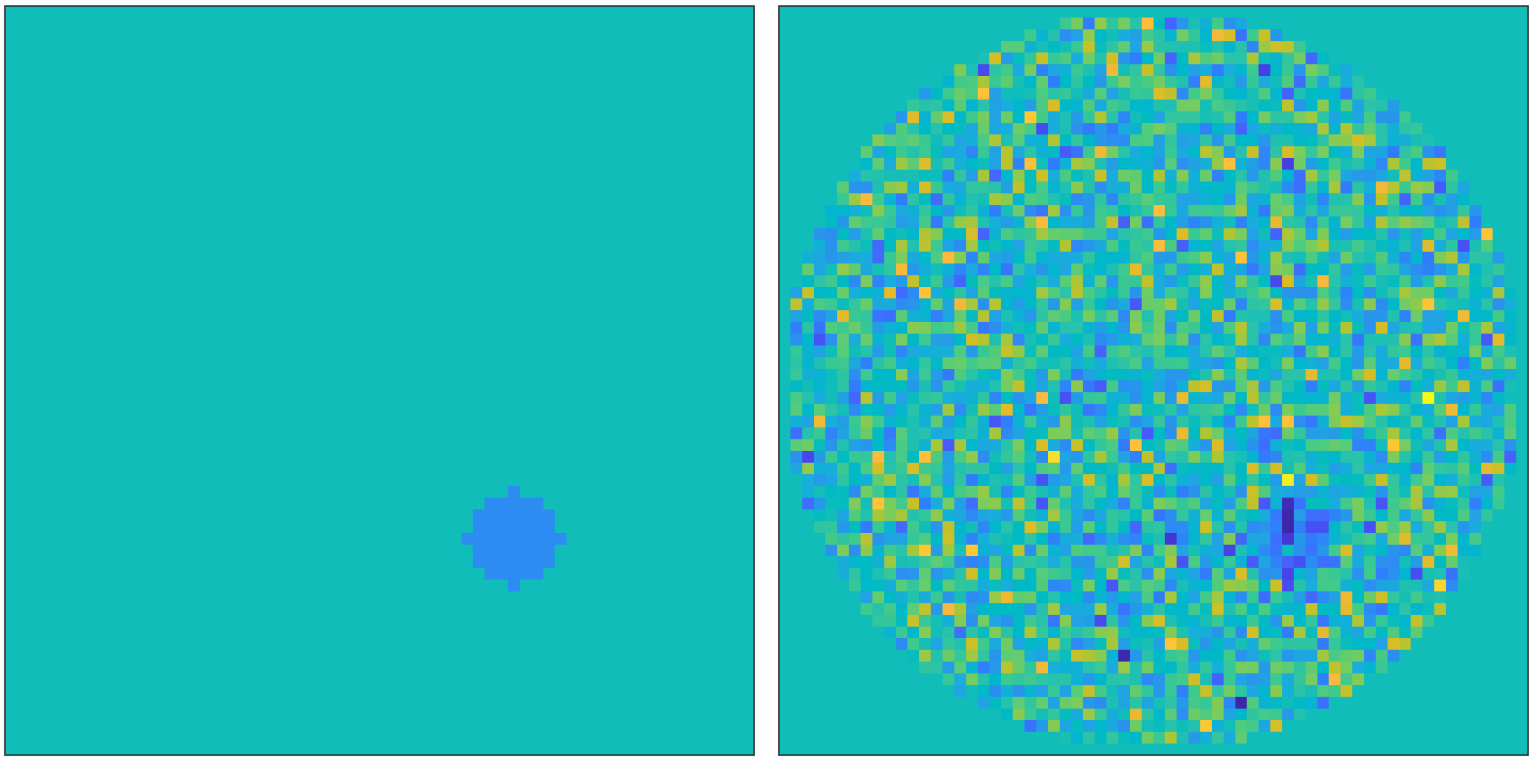


(a) $\Delta\boldsymbol{\sigma}_1$ (b) $\mathbf{h}_g * \Delta\boldsymbol{\sigma}_1$

where $\mathbf{h}_g$ is a Gaussian kernel.

# CNN training set: Samples (Available at [2])

Pair: Ground truth (left). Noisy (right)

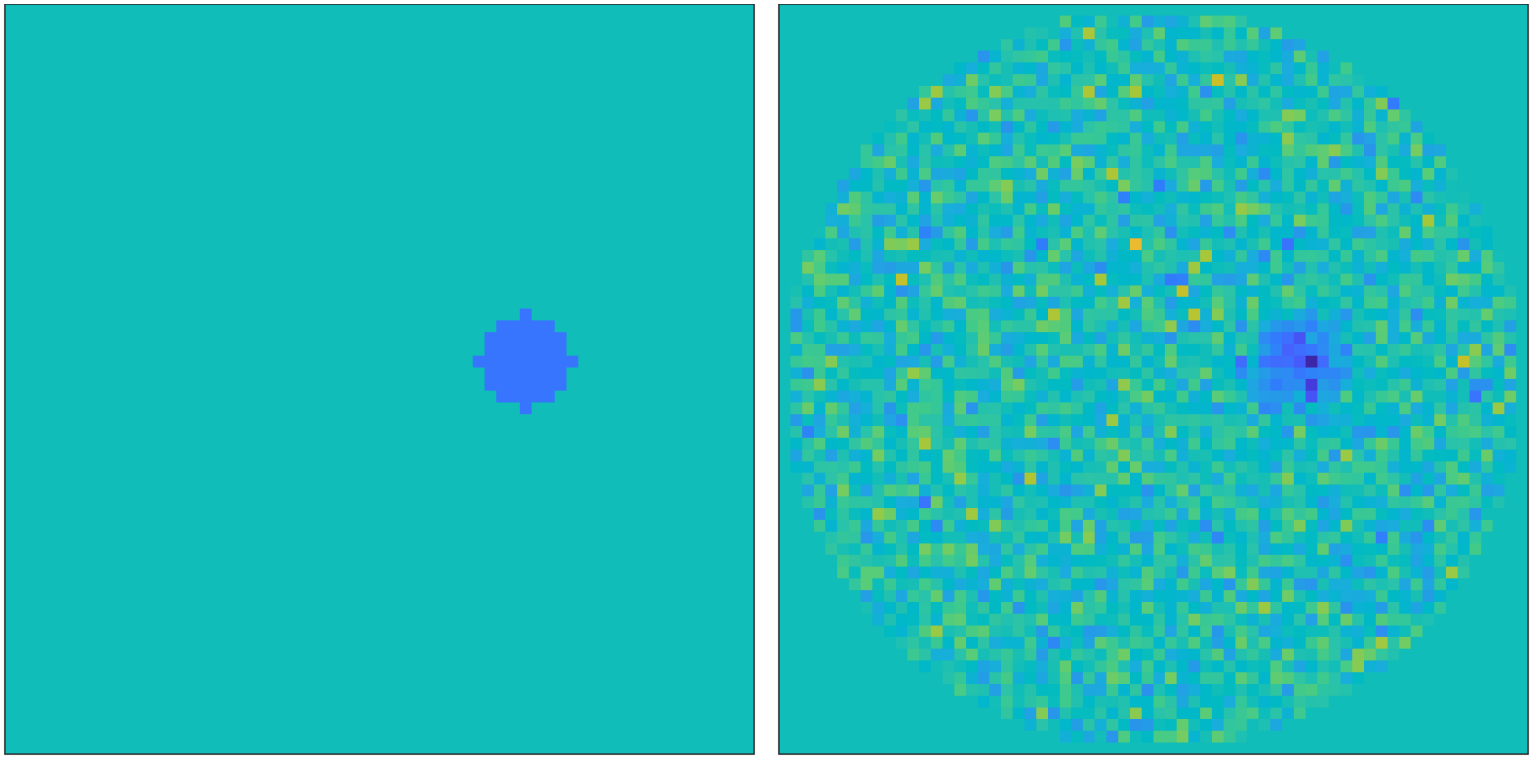


(a) $\Delta\boldsymbol{\sigma}_2$ (b) $\Delta\boldsymbol{\sigma}_2 + \boldsymbol{\delta}$

where $\boldsymbol{\delta}$ is a Gaussian noise.

# CNN training set: Samples (Available at [2])

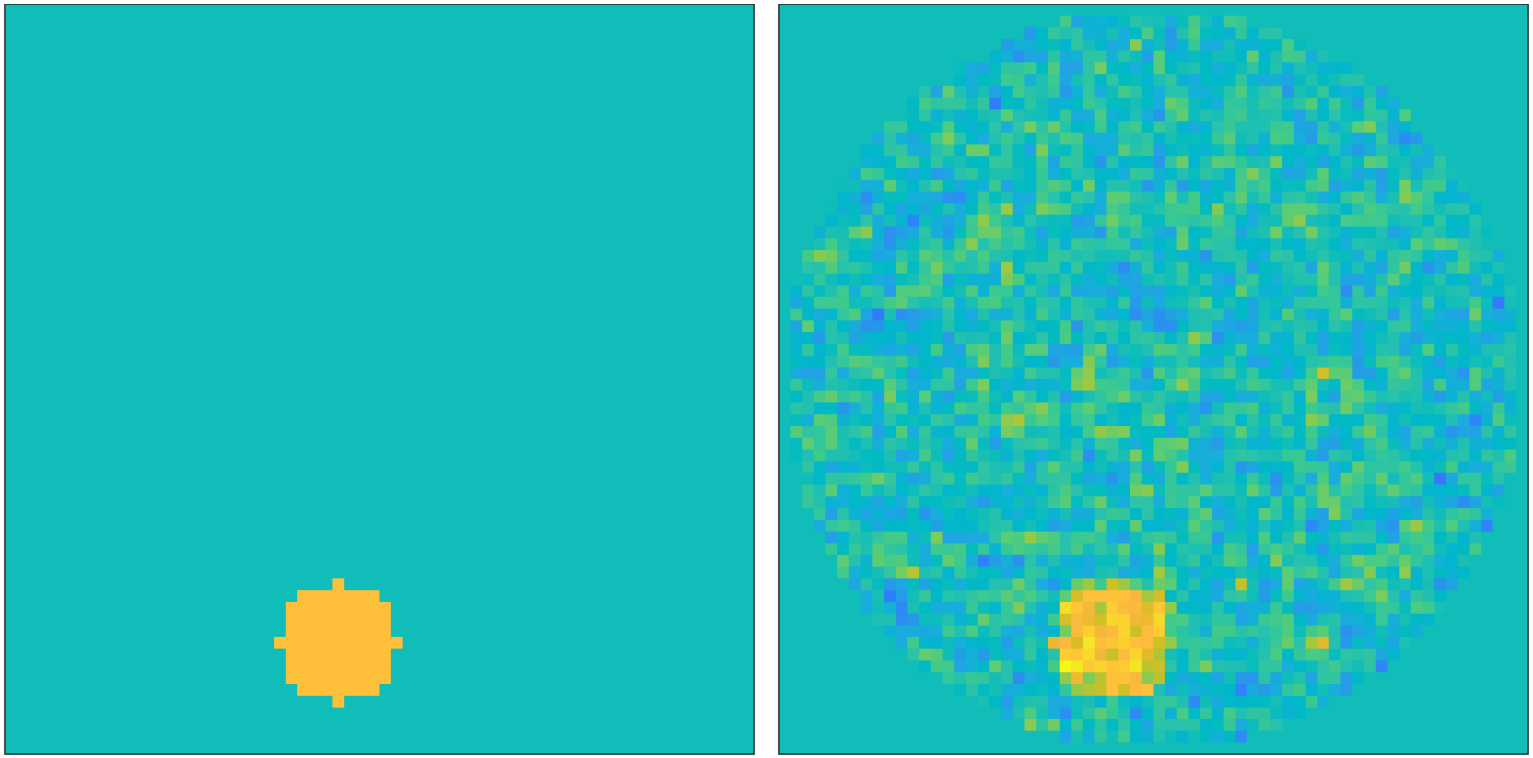
Pair: Ground truth (left). Noisy and blurred (right)



(a) $\Delta\boldsymbol{\sigma}_3$ (b) $(\mathbf{h}_g * \Delta\boldsymbol{\sigma}_3) + \boldsymbol{\delta}$

# CNN training set: Samples (Available at [2])

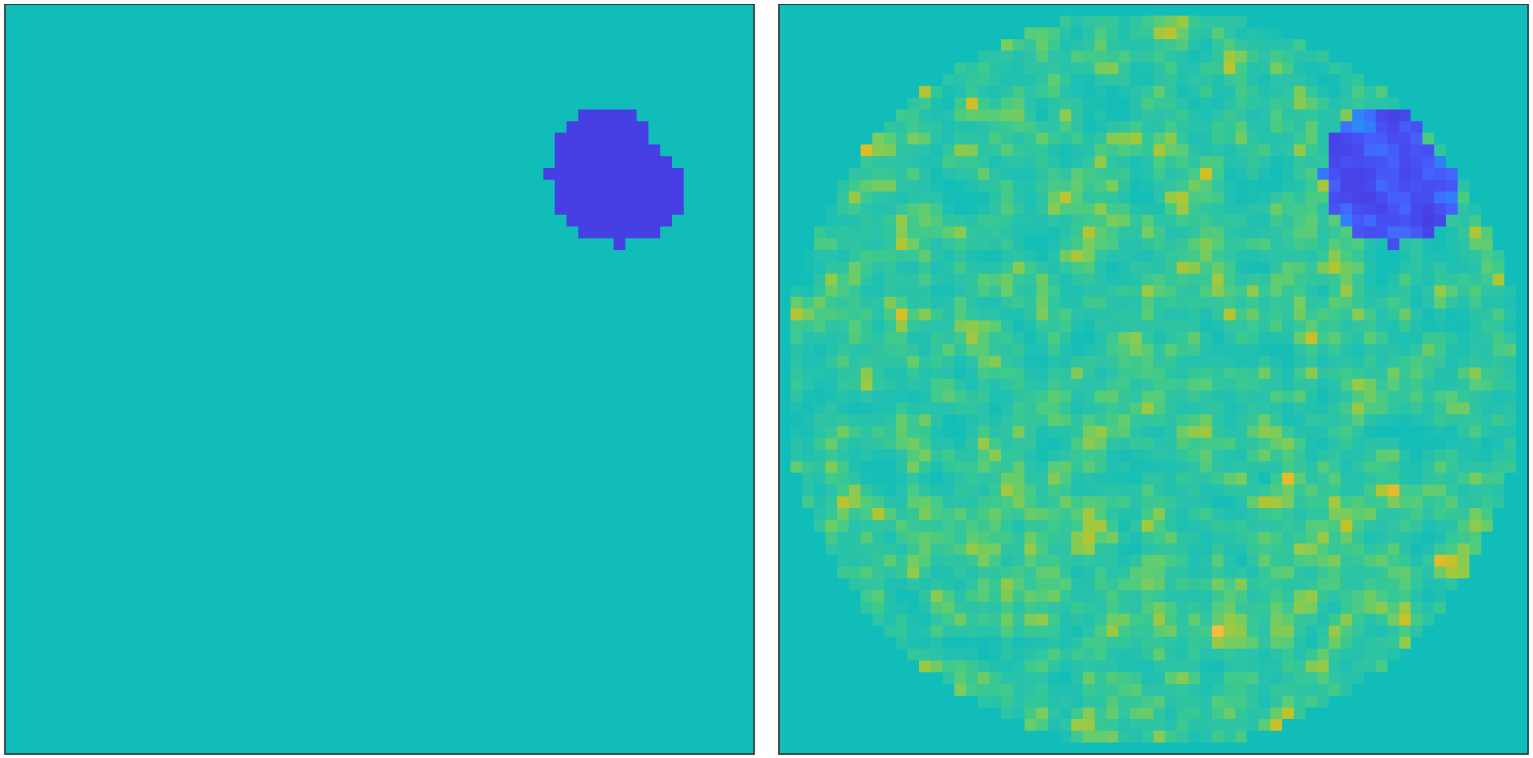
Pair: Ground truth (left). Noisy and blurred (right)



(a) $\Delta\boldsymbol{\sigma}_4$ (b) $\mathbf{h}_g * (\Delta\boldsymbol{\sigma}_4 + \boldsymbol{\delta})$

# CNN training set: Samples (Available at [2])

Pair: Ground truth (left). Noisy and blurred (right)



(a) $\Delta\boldsymbol{\sigma}_5$ (b) $\Delta\boldsymbol{\sigma}_5 + (\mathbf{h}_g * \boldsymbol{\delta})$

# How did we normalize the input of the CNN?

**Scale conversion**: Let $C = 2.5 * max(abs(\Delta\sigma))$. Then,

| **Value** | **Scale 0-1** [U.A] | **Aux. scale** $[\Omega m]$ |
|---|---|---|
| Maximum | $\Delta\rho_N = 1$ | $\Delta\rho_C = C$ |
| Conductive | $0.5 < \Delta\rho_N < 1$ | $0 < \Delta\rho_C < C$ |
| No variation | $\Delta\rho_N = 0.5$ | $\Delta\rho_C = 0$ |
| Resistive | $0 < \Delta\rho_N < 0.5$ | $-C < \Delta\rho_C < 0$ |
| Minimum | $\Delta\rho_N = 0$ | $\Delta\rho_C = -C$ |

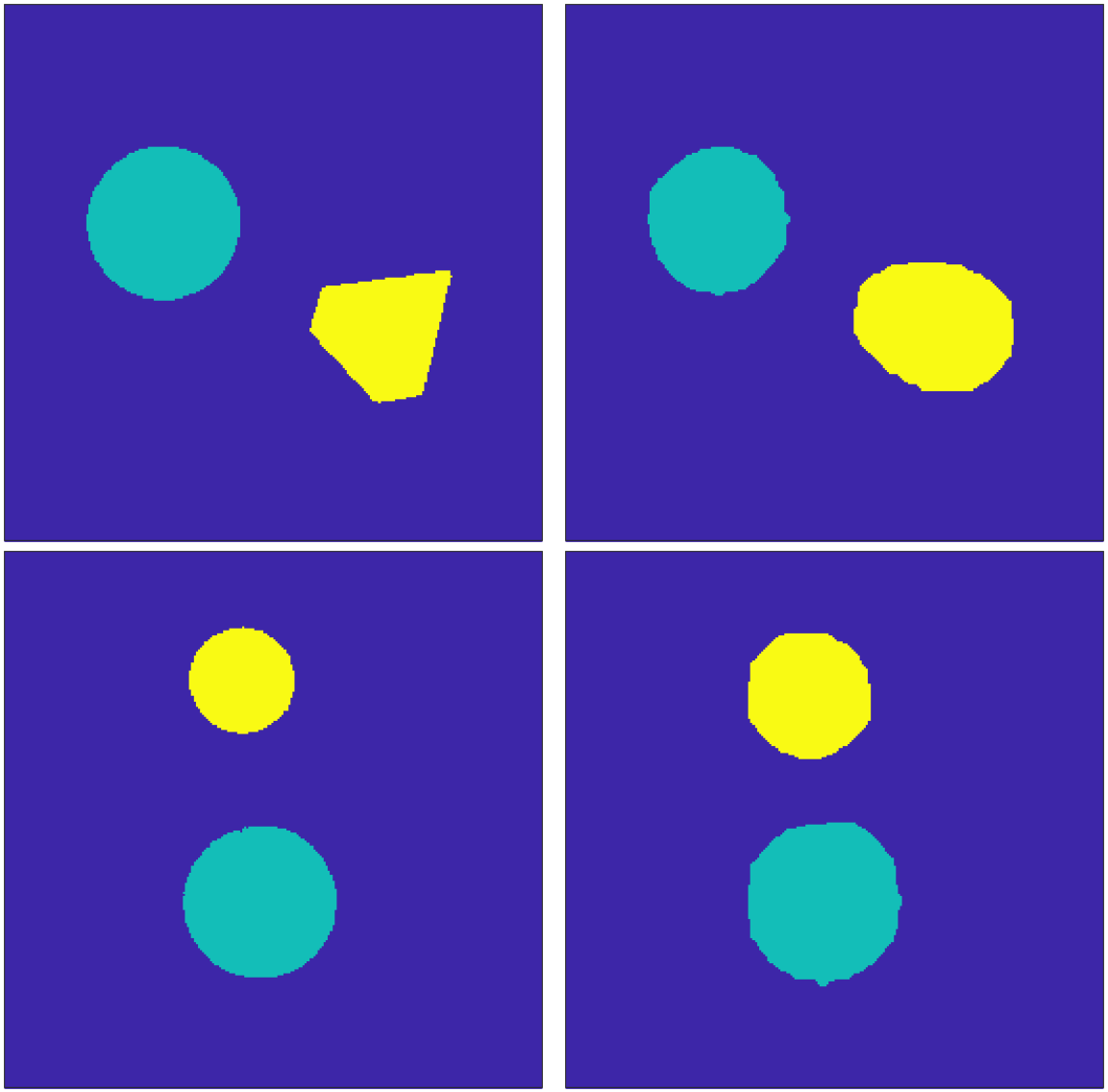
- This choice of $C$ accumulates values closer to 0.5;
- Empirical results show that higher values of $C$ eliminate more information from the image.

# Observation: Normalization

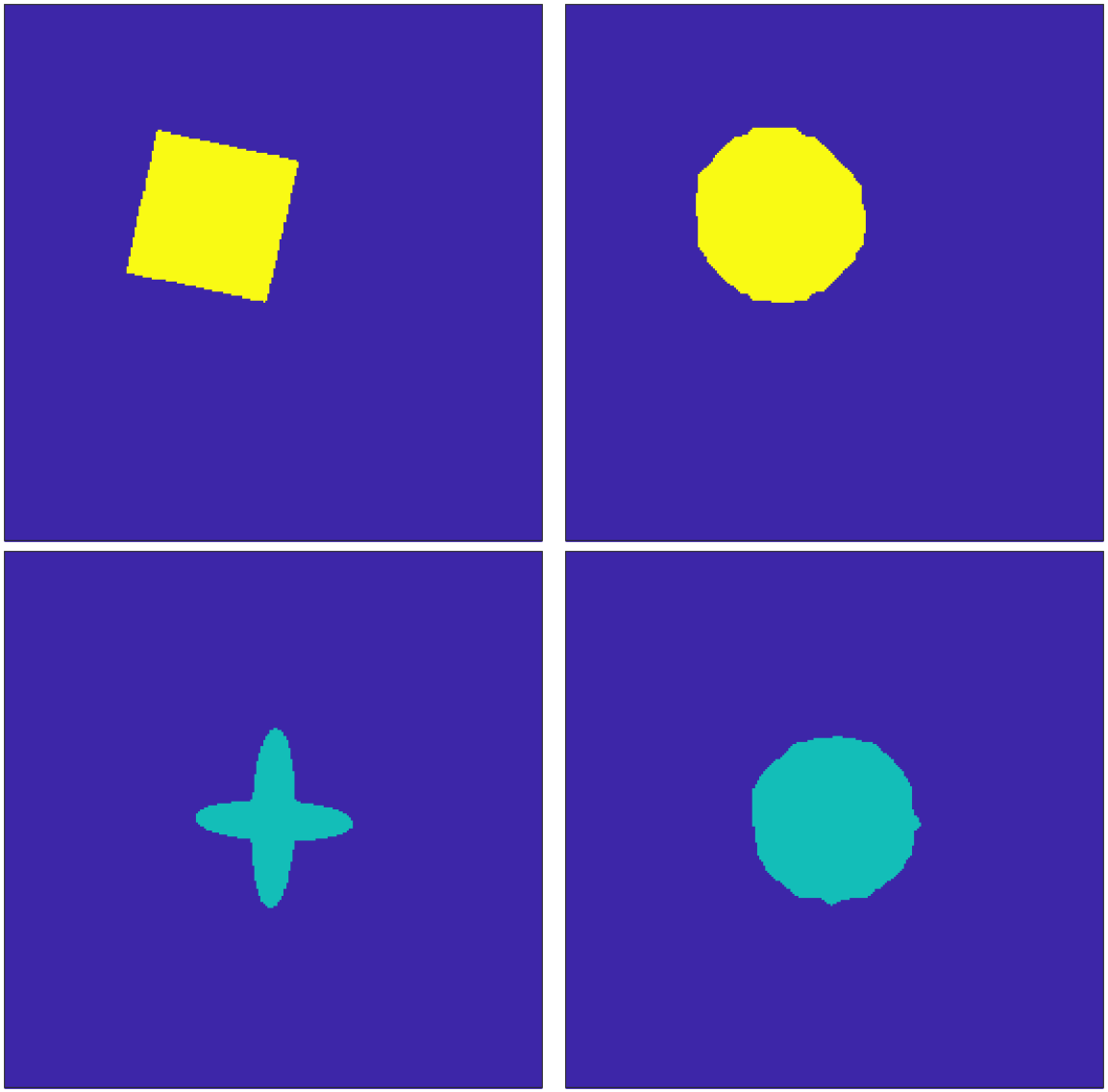
- By the rules, the expected result was the segmented result.
- At each stage of this proposal, it was not necessary to worry about the amplitude of the original conductivity, as we did not have to convert the CNN output back to conductivity units.
- If it was an iterative algorithm, with one application of the CNN per iteration, greater attention would be needed to the signal amplitudes

# Proposal results (training set)

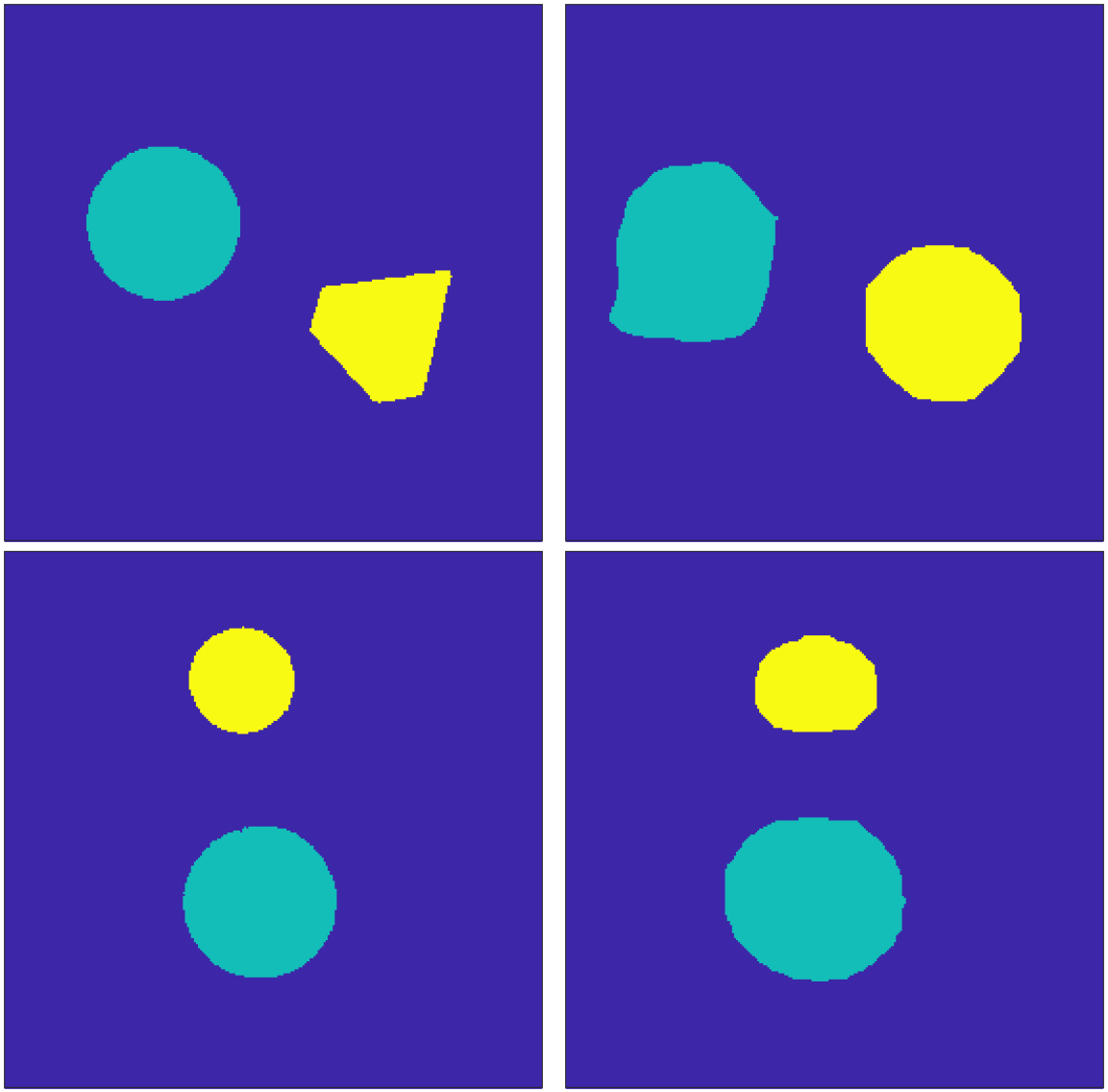
# Level 1 (Score = 0.81)



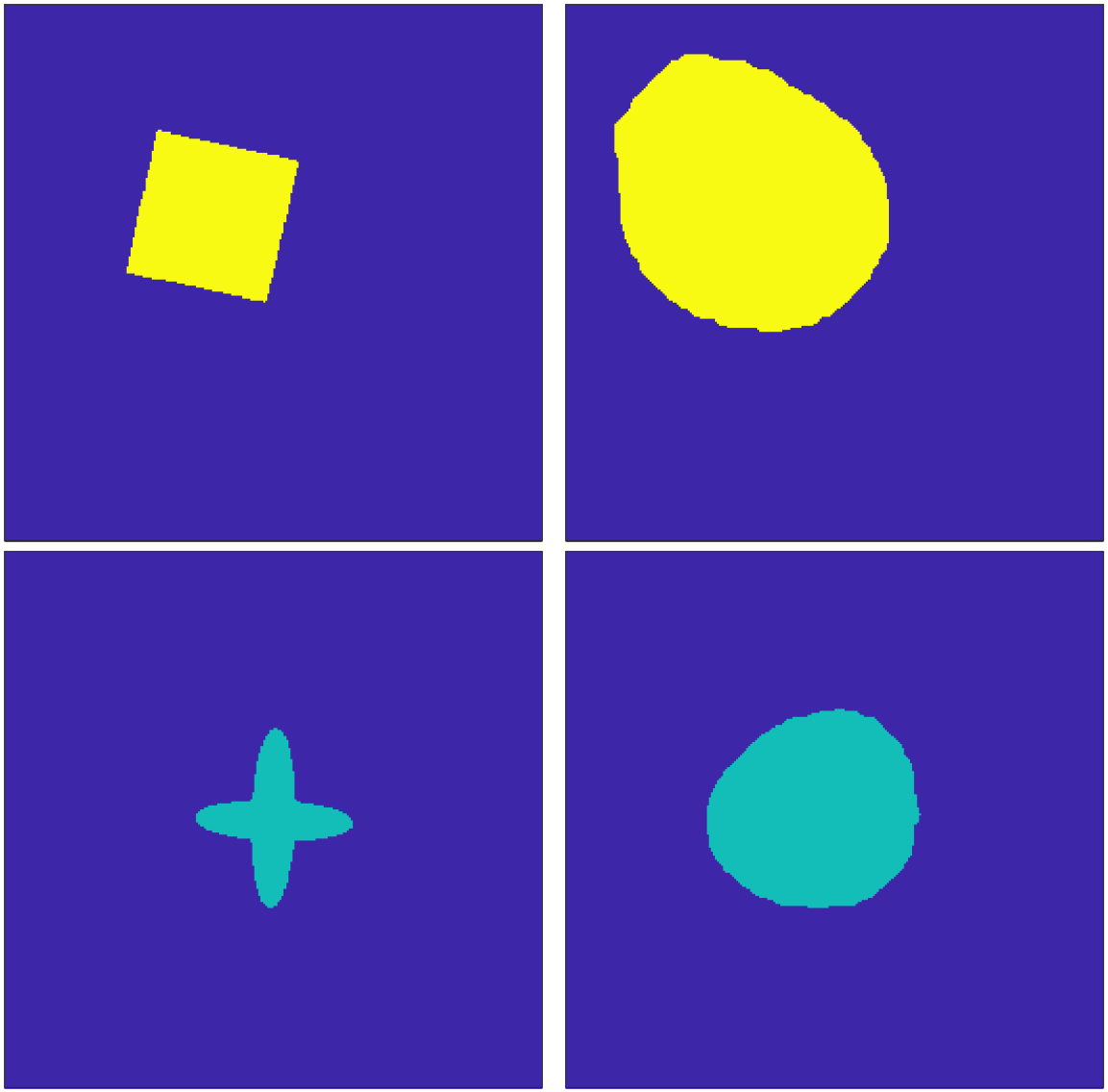
# Level 1 (Score = 0.81)



# Level 7 (Score = 0.69)



# Level 7 (Score = 0.69)



# Final comments

# Proposal drawbacks

- Each result is very dependent on the initial reconstruction
- We didn't correct shape deformation (SSIM $< 1$)
- CNN training and inference on $64 \times 64$ images
- Cases that could cause problems include:
  - Small targets
  - Several targets close to each other
  - Targets with small conductivity variation in relation to the water
  - Non-convex, complex target shapes
- With many parameters to adjust, it was not possible to guarantee that the original proposal would be suitable for the test set

# Conclusions

- The proposal uses the KTC code base and additional post-processing steps to help segmentation
- It uses a CNN trained with a simulated database consisting of 5000 blurred and noisy circular targets
- Training was fast and only a single training was necessary (same CNN weights at all levels)
- Given the trained CNN, the reconstruction is fast
- In the end, even with circular reconstructed targets, the score did not drop much at the higher levels

[1] M. Räsänen *et al.*
Kuopio tomography challenge 2023 open electrical impedance tomographic dataset (ktc 2023) (Zenodo).
DOI 10.5281/zenodo.8252369, 2024.

[2] R. G. Beraldo *et al.*
Simulated EIT circular targets with noise and blur (Zenodo).
DOI 10.5281/zenodo.10801591, 2024.