### **Import libs**

```
In [12]: %matplotlib notebook
    from mpl_toolkits import mplot3d
    import numpy as np
    import matplotlib.pyplot as plt
    from typing import Tuple
```

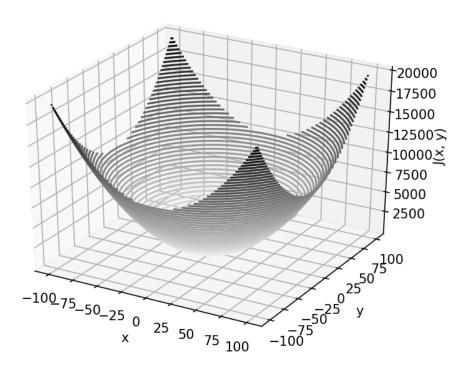
#### **Define error function**

```
In [13]: def J(x:float, y:float) -> float:
    return x**2 + y**2
```

# 3d plot of error function

```
In [15]: fig = plt.figure()
    ax = plt.axes(projection='3d')
    ax.contour3D(X, Y, Z, 50, cmap='binary')
    ax.set_xlabel('x')
    ax.set_ylabel('y')
    ax.set_zlabel('J(x, y)')
    fig.show()

# rotate the graph below by mouse
```



# **Define gradient**

```
In [16]: def grad_J(x:float, y:float) -> Tuple[float, float]:
    return 2*x, 2*y
```

## **Gradient checking**

Resursa: <a href="http://ufldl.stanford.edu/tutorial/supervised/DebuggingGradientChecking/">http://ufldl.stanford.edu/tutorial/supervised/DebuggingGradientChecking/</a>)

```
g(	heta) pprox rac{J(	heta + 	ext{EPSILON}) - J(	heta - 	ext{EPSILON})}{2 	imes 	ext{EPSILON}}.
```

#### **Define init point, learning params**

```
In [19]: x_init, y_init = 100, -60
alpha = 0.05
max_error = 1e-5
max_iters = 1000
```

#### **Gradient descent**

```
In [21]: print(f'Numarul de iteratii: {len(values)}')
```

Numarul de iteratii: 94

#### In [22]: print(values)

[13600, 11016.0, 8922.96, 7227.597600000001, 5854.354056, 4742.02678536, 384 1.0416961416004, 3111.243773874696, 2520.107456838504, 2041.287040039188, 165 3.4425024317422, 1339.288426969711, 1084.823625845466, 878.7071369348275, 71 1.7527809172104, 576.5197525429403, 466.9809995597817, 378.2546096434232, 30 6.3862338111728, 248.17284938704998, 201.02000800351047, 162.8262064828435, 1 31.88922725110325, 106.83027407339365, 86.53252199944885, 70.09134281955357, 56.77398768383839, 45.986930023909096, 37.24941331936637, 30.172024788686763, 24.439340078836274, 19.795865463857382, 16.034651025724482, 12.9880673308368 3, 10.520334537977833, 8.521470975762046, 6.902391490367256, 5.59093710719747 6, 4.528659056829956, 3.6682138360322645, 2.971253207186134, 2.40671509782076 85, 1.9494392292348222, 1.5790457756802063, 1.279027078300967, 1.036011933423 7834, 0.8391696660732644, 0.6797274295193442, 0.5505792179106688, 0.445969166 5076417, 0.3612350248711898, 0.2926003701456637, 0.2370062998179876, 0.191975 1028525699, 0.15549983331058165, 0.12595486498157113, 0.10202344063507263, 0. 08263898691440881, 0.06693757940067113, 0.05421943931454361, 0.04391774584478 032, 0.035573374134272064, 0.02881443304876037, 0.0233396907694959, 0.0189051 4952329168, 0.015313171113866264, 0.012403668602231672, 0.010046971567807653, 0.0081380469699242, 0.006591818045638601, 0.0053393726169672666, 0.0043248918 19743486, 0.0035031623739922232, 0.002837561522933701, 0.002298424833576298, 0.0018617241151968015, 0.0015079965333094092, 0.0012214771919806212, 0.000989 3965255043033, 0.0008014111856584857, 0.0006491430603833735, 0.00052580587891 05324, 0.0004259027619175313, 0.00034498123715320035, 0.00027943480209409227, 0.00022634218969621472, 0.0001833371736539339, 0.00014850311065968646, 0.0001 2028751963434602, 9.743289090382026e-05, 7.892064163209442e-05, 6.39257197219 9647e-05, 5.177983297481714e-05, 4.1941664709601886e-05]