Contents

1 Basic

1.1 .vimrc

```
syn on
se ai nu rnu ru cul mouse=a
se cin et ts=2 sw=2 sts=2
so $VIMRUNTIME/mswin.vim
colo desert
filet plugin indent on
no <F5> :!./a.out<CR>
no <F9> :!g++ -O2 -std=c++17 % -g -fsanitize=undefined -
    Wall -Wextra -Wshadow -Wno-unused-result<CR>
se undofile undodir=~/.vim/undodir " mkdir manually
```

1.2 hash.sh

```
#!/bin/bash
cpp -dD -P -fpreprocessed $1 | tr -d '[:space:]'| md5sum
     |cut -c-6
```

1.3 Custom Hash a296c3

```
struct custom_hash {
  static uint64_t splitmix64(uint64_t x) {
    x += 0x9e3779b97f4a7c15;
    x = (x ^ (x >> 30)) * 0xbf58476d1ce4e5b9;
    x = (x ^ (x >> 27)) * 0x94d049bb133111eb;
    return x ^ (x >> 31);
  }
  size_t operator()(uint64_t x) const {
    static const uint64_t FIXED_RANDOM = chrono::
        steady_clock::now().time_since_epoch().count();
    return splitmix64(x + FIXED_RANDOM);
  }
};
```

1.4 python-related

```
from fractions import Fraction
from decimal import Decimal, getcontext
getcontext().prec = 250 # set precision
itwo,two,N = Decimal(0.5),Decimal(2),200
def angle(cosT):
  """given cos(theta) in decimal return theta"""
  for i in range(N):
    cosT = ((cosT + 1) / two) ** itwo
  sinT = (1 - cosT * cosT) ** itwo
  return sinT * (2 ** N)
pi = angle(Decimal(-1))
```

2 flow

2.1 ISAP ab2177

```
#define SZ(c) ((int)(c).size())
struct Maxflow{
  static const int MAXV=50010;
  static const int INF =1000000;
  struct Edge{
    int v,c,r;
    Edge(int _v,int _c,int _r):v(_v),c(_c),r(_r){}
  };
  int s,t; vector<Edge> G[MAXV];
  int iter[MAXV],d[MAXV],gap[MAXV],tot;
  void init(int n,int _s,int _t){
    tot=n,s=_s,t=_t;
    for(int i=0;i<=tot;i++){
      G[i].clear(); iter[i]=d[i]=gap[i]=0;
    }
  }
  void add_edge(int u,int v,int c){
    G[u].push_back(Edge(v,c,SZ(G[v])));
    G[v].push_back(Edge(u,0,SZ(G[u])-1));
  }
  int DFS(int p,int flow){
    if(p==t) return flow;
```

```
    for(int &i=iter[p];i<SZ(G[p]);i++){
      Edge &e=G[p][i];
      if(e.c>0&&d[p]==d[e.v]+1){
        int f=DFS(e.v,min(flow,e.c));
        if(f){ e.c-=f; G[e.v][e.r].c+=f; return f; }
      }
    }
    if((--gap[d[p]])==0) d[s]=tot;
    else{ d[p]++; iter[p]=0; ++gap[d[p]]; }
    return 0;
  }
  int flow(){
    int res=0;
    for(res=0,gap[0]=tot;d[s]<tot;res+=DFS(s,INF));
    return res;
  }
} flow;
```

2.2 MinCostFlow 8b28ab

```
struct zkwflow{
  static const int maxN=10000;
  struct Edge{ int v,f,re; ll w;};
  int n,s,t,ptr[maxN]; bool vis[maxN]; ll dis[maxN];
  vector<Edge> E[maxN];
  void init(int _n,int _s,int _t){
    n=_n,s=_s,t=_t;
    for(int i=0;i<n;i++) E[i].clear();
  }
  void add_edge(int u,int v,int f,ll w){
    E[u].push_back({v,f,(int)E[v].size(),w});
    E[v].push_back({u,0,(int)E[u].size()-1,-w});
  }
  bool SPFA(){
    fill_n(dis,n,LLONG_MAX); fill_n(vis,n,false);
    queue<int> q; q.push(s); dis[s]=0;
    while (!q.empty()){
      int u=q.front(); q.pop(); vis[u]=false;
      for(auto &it:E[u]){
        if(it.f>0&&dis[it.v]>dis[u]+it.w){
          dis[it.v]=dis[u]+it.w;
          if(!vis[it.v]){
            vis[it.v]=true; q.push(it.v);
    } } } }
    return dis[t]!=LLONG_MAX;
  }
  int DFS(int u,int nf){
    if(u==t) return nf;
    int res=0; vis[u]=true;
    for(int &i=ptr[u];i<(int)E[u].size();i++){
      auto &it=E[u][i];
      if(it.f>0&&dis[it.v]==dis[u]+it.w&&!vis[it.v]){
        int tf=DFS(it.v,min(nf,it.f));
        res+=tf,nf-=tf,it.f-=tf;
        E[it.v][it.re].f+=tf;
        if(nf==0){ vis[u]=false; break; }
      }
    }
    return res;
  }
  pair<int,ll> flow(){
    int flow=0; ll cost=0;
    while (SPFA()){
      fill_n(ptr,n,0);
      int f=DFS(s,INT_MAX);
      flow+=f; cost+=dis[t]*f;
    }
    return{ flow,cost };
  }
} flow;
```

2.3 Dinic aa63d9

```
struct Dinic{
  static const int MXN = 10000;
  struct Edge{ int v,f,re; };
  int n,s,t,level[MXN]; vector<Edge> E[MXN];
  void init(int _n, int _s, int _t){
    n = _n; s = _s; t = _t;
    for (int i=0; i<n; i++) E[i].clear();
  }
  void add_edge(int u, int v, int f){
    E[u].push_back({v,f,(int)E[v].size()});
    E[v].push_back({u,0,(int)E[u].size()-1});
  }
  bool BFS(){
    for (int i=0; i<n; i++) level[i] = -1;
    queue<int> que; que.push(s); level[s] = 0;
    while (!que.empty()){
      int u = que.front(); que.pop();
      for (auto &it : E[u]){
        if (it.f > 0 && level[it.v] == -1){
          level[it.v] = level[u]+1; que.push(it.v);
    } } }
    return level[t] != -1;
  }
  int DFS(int u, int nf){
    if (u == t) return nf;
    int res = 0;
    for (auto &it : E[u]){
      if (it.f > 0 && level[it.v] == level[u]+1){
        int tf = DFS(it.v, min(nf,it.f));
        res += tf; nf -= tf; it.f -= tf;
        E[it.v][it.re].f += tf;
        if (nf == 0) return res;
      }
    }
    if (!res) level[u] = -1;
    return res;
  }
  int flow(int res=0){
    while ( BFS() ) res += DFS(s,2147483647);
    return res;
  }
}flow;
```

2.4 Kuhn Munkres e807c8

```
struct KM{ // max weight,for min negate the weights
  static const int MXN=2001;// 1-based
  static const ll INF=0x3f3f3f3f;
  int n,mx[MXN],my[MXN],pa[MXN]; bool vx[MXN],vy[MXN];
  ll g[MXN][MXN],lx[MXN],ly[MXN],sy[MXN];
  void init(int _n){
    n=_n; for(int i=1;i<=n;i++) fill(g[i],g[i]+n+1,0);
  }
  void addEdge(int x,int y,ll w){ g[x][y]=w; }
  void augment(int y){
    for(int x,z;y;y=z) x=pa[y],z=mx[x],my[y]=x,mx[x]=y;
  }
  void bfs(int st){
    for(int i=1;i<=n;++i) sy[i]=INF,vx[i]=vy[i]=0;
    queue<int> q;q.push(st);
    for(;;){
      while(q.size()){
        int x=q.front();q.pop();vx[x]=1;
        for(int y=1;y<=n;++y) if(!vy[y]){
          ll t=lx[x]+ly[y]-g[x][y];
          if(t==0){
            pa[y]=x;
            if(!my[y]){ augment(y); return; }
            vy[y]=1,q.push(my[y]);
          }else if(sy[y]>t) pa[y]=x,sy[y]=t;
        }
      }
      ll cut=INF;
      for(int y=1;y<=n;++y)
        if(!vy[y]&&cut>sy[y]) cut=sy[y];
      for(int j=1;j<=n;++j){
        if(vx[j]) lx[j]-=cut;
        if(vy[j]) ly[j]+=cut;
        else sy[j]-=cut;
      }
      for(int y=1;y<=n;++y) if(!vy[y]&&sy[y]==0){
        if(!my[y]){ augment(y); return; }
        vy[y]=1,q.push(my[y]);
  } } }
  ll solve(){
    fill(mx,mx+n+1,0);fill(my,my+n+1,0);
    fill(ly,ly+n+1,0);fill(lx,lx+n+1,-INF);
    for(int x=1;x<=n;++x) for(int y=1;y<=n;++y)
      lx[x]=max(lx[x],g[x][y]);
    for(int x=1;x<=n;++x) bfs(x);
    ll ans=0;
```

```
    for(int y=1;y<=n;++y) ans+=g[my[y]][y];
    return ans;
  }
}graph;
```

2.5 SW min-cut 9beb62

```
const int INF=0x3f3f3f3f;
template<typename T>
struct stoer_wagner{// 0-base
  static const int MAXN=501;
  T g[MAXN][MAXN],dis[MAXN]; int nd[MAXN],n,s,t;
  void init(int _n){
    n=_n;
    for(int i=0;i<n;++i) for(int j=0;j<n;++j )g[i][j]=0;
  }
  void add_edge(int u,int v,T w){ g[u][v]=g[v][u]+=w; }
  T min_cut(){
    T ans=INF;
    for(int i=0;i<n;++i) nd[i]=i;
    for(int ind,tn=n;tn>1;--tn){
      for(int i=1;i<tn;++i)dis[nd[i]]=0;
      for(int i=1;i<tn;++i){
        ind=i;
        for(int j=i;j<tn;++j){
          dis[nd[j]]+=g[nd[i-1]][nd[j]];
          if(dis[nd[ind]]<dis[nd[j]])ind=j;
        }
        swap(nd[ind],nd[i]);
      }
      if(ans>dis[nd[ind]])
        ans=dis[t=nd[ind]],s=nd[ind-1];
      for(int i=0;i<tn;++i)
        g[nd[ind-1]][nd[i]]=g[nd[i]][nd[ind-1]]
                            +=g[nd[i]][nd[ind]];
    }
    return ans;
  }
};
```

2.6 Max Cost Circulation 932772

```
struct MaxCostCirc {
  static const int MAXN=33;
  struct Edge { int v,w,c,r; };
  vector<Edge> g[MAXN];
  int dis[MAXN],prv[MAXN],prve[MAXN];
  int n,m,ans; bool vis[MAXN];
  void init(int _n,int _m) : n(_n),m(_m) {}
  void adde(int u,int v,int w,int c) {
    g[u].push_back({v,w,c,(int)g[v].size()});
    g[v].push_back({u,-w,0,(int)g[u].size()-1});
  }
  bool poscyc() {
    fill(dis,dis+n+1,0); fill(prv,prv+n+1,0);
    fill(vis,vis+n+1,0); int tmp=-1;
    for(int t=0;t<=n;t++) {
      for(int i=1;i<=n;i++) {
        for(int j=0;j<(int)g[i].size();j++) {
          Edge& e=g[i][j];
          if(e.c&&dis[e.v]<dis[i]+e.w) {
            dis[e.v]=dis[i]+e.w;
            prv[e.v]=i; prve[e.v]=j;
            if(t==n) { tmp=i; break; }
          } } } }
    if(tmp==-1) return 0;
    int cur=tmp;
    while(!vis[cur]) { vis[cur]=1; cur=prv[cur]; }
    int now=cur,cost=0,df=100000;
    do{
      Edge &e=g[prv[now]][prve[now]];
      df=min(df,e.c); cost+=e.w; now=prv[now];
    }while(now!=cur);
    ans+=df*cost; now=cur;
    do{
      Edge &e=g[prv[now]][prve[now]];
      Edge &re=g[now][e.r];
      e.c-=df; re.c+=df; now=prv[now];
    }while(now!=cur);
    return 1;
  }
} circ;
```

2.7 Gomory-Hu Tree 796cf8

```
//n,Dinic::flow must be filled
//result:e[u][v]=u-v mincut;p[u]:u's parent on cut tree
int n,e[MXN][MXN],p[MXN];
void gomory_hu(){
  fill(p,p+n,0); fill(e[0],e[n],INF);
  for(int s=1;s<n;s++){
    int t=p[s]; Dinic F; F.init(n,s,t);
    copy(flow.E,flow.E+MXN,F.E); int tmp=F.flow();
    for(int i=0;i<s;i++)
      e[s][i]=e[i][s]=min(tmp,e[t][i]);
    for(int i=s+1;i<n;i++)
      if(p[i]==t&&F.level[i]!=-1) p[i]=s;
  }
}
```

2.8 Max flow with lower/upper bound cee539

```
// Max flow with lower/upper bound on edges
// use with ISAP
int in[N],out[N],l[M],r[M],a[M],b[M];
int solve(int n, int m, int s, int t){
  flow.init(n);
  for(int i=0;i<m;i ++){
    in[r[i]]+=a[i]; out[l[i]]+=a[i];
    flow.addEdge(l[i],r[i],b[i]-a[i]);
    // flow from l[i] to r[i] must in [a[i], b[i]]
  }
  int nd=0;
  for(int i=0;i <= n;i ++){
    if(in[i]<out[i]){
      flow.addEdge(i,flow.t,out[i]-in[i]);
      nd+=out[i]-in[i];
    }
    if(out[i]<in[i])
      flow.addEdge(flow.s,i,in[i]-out[i]);
  }
  // original sink to source
  flow.addEdge(t,s,INF);
  if( flow.solve() != nd ) return -1; // no solution
  int ans=flow.G[s].back().c; // source to sink
  flow.G[s].back().c=flow.G[t].back().c=0;
  // take out super source and super sink
  for(size_ti=0;i<flow.G[flow.s].size();i++){
    flow.G[flow.s][i].c=0;
    Maxflow::Edge &e=flow.G[flow.s][i];
    flow.G[e.v][e.r].c=0;
  }
  for(size_ti=0;i<flow.G[flow.t].size();i++){
    flow.G[flow.t][i].c=0;
    Maxflow::Edge &e=flow.G[flow.t][i];
    flow.G[e.v][e.r].c=0;
  }
  flow.addEdge(flow.s,s,INF);
  flow.addEdge(t,flow.t,INF);
  flow.reset(); // set iter,d,gap to 0
  return ans + flow.solve();
}
```

2.9 HLPPA 719919

```
template <int MAXN, class T = int>
struct HLPP {
  const T INF = numeric_limits<T>::max();
  struct Edge { int to, rev; T f; };
  int n, s, t; T ef[MAXN]; vector<Edge> adj[MAXN];
  deque<int> lst[MAXN]; vector<int> gap[MAXN];
  int ptr[MAXN],h[MAXN],cnt[MAXN],work,hst=0; // highest
  void init(int _n, int _s, int _t) {
    n=_n+1; s = _s; t = _t;
    for(int i=0;i<n;i++) adj[i].clear();
  }
  void add_edge(int u,int v,T f,bool isDir = true){
    adj[u].push_back({v,adj[v].size(),f});
    adj[v].push_back({u,adj[u].size()-1,isDir?0:f});
  }
  void updHeight(int v, int nh) {
    work++;
    if(h[v] != n) cnt[h[v]]--;
    h[v] = nh;
```

```
    if(nh == n) return;
    cnt[nh]++, hst = nh; gap[nh].push_back(v);
    if(ef[v]>0) lst[nh].push_back(v), ptr[nh]++;
  }
  void globalRelabel() {
    work = 0; fill(h, h+n, n); fill(cnt, cnt+n, 0);
    for(int i=0; i<=hst; i++)
      lst[i].clear(), gap[i].clear(), ptr[i] = 0;
    queue<int> q({t}); h[t] = 0;
    while(!q.empty()) {
      int v = q.front(); q.pop();
      for(auto &e : adj[v])
        if(h[e.to] == n && adj[e.to][e.rev].f > 0)
          q.push(e.to), updHeight(e.to, h[v] + 1);
      hst = h[v];
    }
  }
  void push(int v, Edge &e) {
    if(ef[e.to] == 0)
      lst[h[e.to]].push_back(e.to), ptr[h[e.to]]++;
    T df = min(ef[v], e.f);
    e.f -= df, adj[e.to][e.rev].f += df;
    ef[v] -= df, ef[e.to] += df;
  }
  void discharge(int v) {
    int nh = n;
    for(auto &e : adj[v]) {
      if(e.f > 0) {
        if(h[v] == h[e.to] + 1) {
          push(v, e);
          if(ef[v] <= 0) return;
        }
        else nh = min(nh, h[e.to] + 1);
      }
    }
    if(cnt[h[v]] > 1) updHeight(v, nh);
    else {
      for(int i = h[v]; i < n; i++) {
        for(auto j : gap[i]) updHeight(j, n);
        gap[i].clear(), ptr[i] = 0;
  } } }
  T flow() {
    fill(ef, ef+n, 0); ef[s] = INF, ef[t] = -INF;
    globalRelabel();
    for(auto &e : adj[s]) push(s, e);
    for(; hst >= 0; hst--) {
      while(!lst[hst].empty()) {
        int v=lst[hst].back(); lst[hst].pop_back();
        discharge(v);
        if(work > 4 * n) globalRelabel();
      }
    }
    return ef[t] + INF;
  }
};
```

2.10 Flow Method

```
Maximize c^T x subject to Ax ≤ b, x ≥ 0;
with the corresponding symmetric dual problem,
Minimize b^T y subject to A^T y ≥ c, y ≥ 0.

Maximize c^T x subject to Ax ≤ b;
with the corresponding asymmetric dual problem,
Minimize b^T y subject to A^T y = c, y ≥ 0.

Maximize \sum x subject to x_i + x_j ≤ Aij, x ≥ 0;
=> Maximize \sum x subject to x_i + x_j ≤ A_ij;
=> Minimize A^T y subject to for all v, \sum_{i=v or j=v
    } y_ij = 1, y_ij = {0, 1}
=> possible optimal solution: y_ij = {0, 0.5, 1}
=> y'=2y: \sum_{i=v or j=v} y'_ij = 2, y'_ij = {0, 1, 2}
=> Minimum Bipartite perfect matching/2 (V1=X,V2=X,E=A)

General Graph:
|Max Ind. Set| + |Min Vertex Cover| = |V|
|Max Ind. Edge Set| + |Min Edge Cover| = |V|
Bipartite Graph:
|Max Ind. Set| = |Min Edge Cover|
|Max Ind. Edge Set| = |Min Vertex Cover|

To reconstruct the minimum vertex cover, dfs from each
unmatched vertex on the left side and with unused edges
only. Equivalently, dfs from source with unused edges
only and without visiting sink. Then, a vertex is
chosen iff. it is on the left side and without visited
or on the right side and visited through dfs.

Minimum Weighted Bipartite Edge Cover:
Construct new bipartite graph with n+m vertices on each
    side:
for each vertex u, duplicate a vertex u' on the other
    side
for each edge (u,v,w), add edges (u,v,w) and (v',u',w)
for each vertex u, add edge (u,u',2w) where w is min
    edge connects to u
then the answer is the minimum perfect matching of the
    new graph (KM)

Maximum density subgraph ( \sum{W_e}+ \sum{W_v} ) / |V|
Binary search on answer:
For a fixed D, construct a Max flow model as follow:
Let S be Sum of all weight( or inf)
1. from source to each node with cap = S
2. For each (u,v,w) in E, (u->v,cap=w), (v->u,cap=w)
3. For each node v, from v to sink with cap = S + 2 * D
    - deg[v] - 2 * (W of v)
where deg[v] = \sum weight of edge associated with v
If maxflow < S * |V|, D is an answer.

Requiring subgraph: all vertex can be reached from
    source with
edge whose cap > 0.

Maximum closed subgraph
1. connect source with positive weighted vertex(capacity
    =weight)
2. connect sink with negitive weighted vertex(capacity=-
    weight)
3. make capacity of the original edges = inf
4. ans = sum(positive weighted vertex weight) - (max
    flow)

Minimum Path Cover of DAG
1. For each vertex v, split it to v_in and v_out.
2. For each edge (u->v), add an edge between u_out and
    v_in
3. |Minimum Path Cover| = |V| - |Maximum Matching| of
    the new bipartite graph
```

3 Math

3.1 FFT 094e48

```
const int MXN=262144;// (must be 2^k)
// before any usage,run pre_fft() first
typedef long double ld;
typedef complex<ld> cplx;
const ld PI=acosl(-1); const cplx I(0,1);
cplx omega[MXN+1];
void pre_fft(){
  for(int i=0;i<=MXN;i++)
    omega[i]=exp(i*2*PI/MXN*I);
}
// n must be 2^k
void fft(int n,cplx a[],bool inv=false){
  int basic=MXN/n,theta=basic;
  for(int m=n;m>=2;m>>=1) {
    int mh=m>>1;
    for(int i=0;i<mh;i++) {
      cplx w=omega[inv?MXN-(i*theta%MXN):i*theta%MXN];
      for(int j=i;j<n;j+=m) {
        int k=j+mh; cplx x=a[j]-a[k];
        a[j]+=a[k]; a[k]=w*x;
      }
    }
    theta=(theta*2)%MXN;
  }
  int i=0;
  for(int j=1;j<n-1;j++) {
    for(int k=n>>1;k>(i^=k);k>>=1);
    if(j<i) swap(a[i],a[j]);
  }
  if(inv) for(i=0;i<n;i++) a[i]/=n;
```

```
}
```

3.2 NTT 65f1a7

```
/* p=a*2^k+1
   p                    a      k      root
   998244353            119    23     3
   1107296257           33     25     10
   2013265921           15     27     31
   2061584302081        15     37     7
   2748779069441        5      39     3
   1945555039024054273  27     56     5 */
template<ll P,ll root,int MAXK,int MAXN>
struct NTT{
  static ll powi(ll a,ll b){
    ll ret=1;
    for(;b;b>>=1,a=mul(a, a, P)){
      if(b&1) ret=mul(ret, a, P);
    }
    return ret;
  }
  static ll inv(ll a,ll b){
    if(a==1) return 1;
    return (((a-inv(b%a,a))*b+1)/a)%b; // overflow
  }
  ll omega[MAXK+1],inv_omega[MAXK+1];
  NTT(){
    omega[MAXK]=powi(root,(P-1)>>MAXK);
    for(int i=MAXK-1;i>=0;i--)
      omega[i]=mul(omega[i+1], omega[i+1], P);
    for(int i=0;i<=MAXK;i++)
      inv_omega[i]=inv(omega[i],P);
  }
  void tran(int n,ll a[],bool inv_ntt=false){//n=2^i
    for(int i=1,j=0;i<n;i++){
      for(int k=n>>1;!((j^=k)&k);k>>=1);
      if(i<j) swap(a[i],a[j]);
    }
    ll *G=(inv_ntt?inv_omega:omega);
    for(int k=2,t=1;k<=n;k<<=1){
      int k2=k>>1;ll dw=G[t++];
      for(int j=0;j<n;j+=k){
        ll w=1;
        for(int i=j;i<j+k2;i++){
          ll x=a[i],y=mul(a[i+k2], w, P);
          a[i]=x+y; if(a[i]>=P) a[i]-=P;
          a[i+k2]=x-y; if(a[i+k2]<0) a[i+k2]+=P;
          w=mul(w, dw, P);
    } } }
    if(inv_ntt){
      ll inv_n=inv(n,P);
      for(int i=0;i<n;i++) a[i]=mul(a[i], inv_n, P);
    }
  }
};
const int MAXN=4194304,MAXK=22; //MAXN=2^k
const ll P=2013265921,root=31;
NTT<P,root,MAXK,MAXN> ntt;
```

3.3 Fast Walsh Transform c77328

```
/* xor convolution:
*x=(x0,x1),y=(y0,y1)
*z=(x0y0+x1y1,x0y1+x1y0)
*=>
*x'=(x0+x1,x0-x1),y'=(y0+y1,y0-y1)
*z'=((x0+x1)(y0+y1),(x0-x1)(y0-y1))
*z=(1/2)*z''
*or convolution:
*x=(x0,x0+x1),inv=(x0,x1-x0) w/o final div
*and convolution:
*x=(x0+x1,x1),inv=(x0-x1,x1) w/o final div
*ternery xor convolution:
*x=(x0+x1+x2,x0+x1w+x2w^2,x0+x1w^2+x2w)
*inv=(1/3)*(x0+x1+x2,x0+x1w^2+x2w,x0+x1w+x2w^2)
*where w^3=1 and w^2=-w-1 */
typedef long long ll;
const int MAXN=(1<<20)+10; const ll MOD=1e9+7;
inline ll pw(ll x,ll k) {
  ll res=1;
  for(ll bs=x;k;k>>=1,bs=(bs*bs)%MOD)
    if(k&1) res=(res*bs) % MOD;
  return res;
}
inline ll invf(ll x) { return pw(x,MOD-2); }
inline void fwt(ll x[MAXN],int N,bool inv=0) {
  for(int d=1;d<N;d<<=1) {
    int d2=d<<1;
    for(int s=0;s<N;s+=d2)
      for(int i=s,j=s+d;i<s+d;i++,j++){
        ll ta=x[i],tb=x[j]; x[i]=ta+tb; x[j]=ta-tb;
        if(x[i]>=MOD) x[i]-=MOD;
        if(x[j]<0) x[j]+=MOD;
      }
  }
  ll invN=invf(N);
  if(inv)
    for(int i=0;i<N;i++) { x[i] *= invN; x[i] %= MOD; }
}
```

3.4 Poly operator d70dd4

```
struct PolyOp {
#define FOR(i,c) for (int i=0; i<(c); ++i)
  NTT<P,root,MAXK,MAXN> ntt;
  static int nxt2k(int x) {
    int i=1; for (; i<x; i <<= 1); return i;
  }
  void Mul(int n,ll a[],int m,ll b[],ll c[]) {
    static ll aa[MAXN],bb[MAXN]; int N=nxt2k(n+m);
    copy(a,a+n,aa); fill(aa+n,aa+N,0);
    copy(b,b+m,bb); fill(bb+m,bb+N,0);
    ntt.tran(N,aa); ntt.tran(N,bb);
    FOR(i,N) c[i]=aa[i]*bb[i]%P;
    ntt.tran(N,c,1);
  }
  void Inv(int n,ll a[],ll b[]) {
    // ab=aa^-1=1 mod x^(n/2)
    // (b-a^-1)^2=0 mod x^n
    // bb+a^-2-2 ba^-1=0
    // bba+a^-1-2b=0
    // a^-1=2b-bba
    static ll tmp[MAXN];
    if(n == 1) { b[0]=ntt.inv(a[0],P); return; }
    Inv((n+1)/2,a,b); int N=nxt2k(n*2);
    copy(a,a+n,tmp); fill(tmp+n,tmp+N,0);
    fill(b+n,b+N,0); ntt.tran(N,tmp); ntt.tran(N,b);
    FOR(i,N) {
      ll t1=(2-b[i]*tmp[i])%P;
      if(t1<0) t1+=P;
      b[i]=b[i]*t1%P;
    }
    ntt.tran(N,b,1); fill(b+n,b+N,0);
  }
  void Div(int n,ll a[],int m,ll b[],ll d[],ll r[]){
    // Ra=Rb*Rd mod x^(n-m+1)
    // Rd=Ra*Rb^-1 mod
    static ll aa[MAXN],bb[MAXN],ta[MAXN],tb[MAXN];
    if(n<m) { copy(a,a+n,r); fill(r+n,r+m,0); return; }
    // d: n-1-(m-1)=n-m (n-m+1 terms)
    copy(a,a+n,aa); copy(b,b+m,bb);
    reverse(aa,aa+n); reverse(bb,bb+m);
    Inv(n-m+1,bb,tb); Mul(n-m+1,ta,n-m+1,tb,d);
    fill(d+n-m+1,d+n,0); reverse(d,d+n-m+1);
    // r: m-1-1=m-2 (m-1 terms)
    Mul(m,b,n-m+1,d,ta);
    FOR(i,n) { r[i]=a[i]-ta[i]; if(r[i]<0) r[i]+=P; }
  }
  void dx(int n,ll a[],ll b[]){
    for(int i=1;i<=n-1;i++) b[i-1]=i*a[i]%P;
  }
  void Sx(int n,ll a[],ll b[]) {
    b[0]=0; FOR(i,n) b[i+1]=a[i]*ntt.inv(i+1,P)%P;
  }
  void Ln(int n,ll a[],ll b[]) {
    // Integral a' a^-1 dx
    static ll a1[MAXN],a2[MAXN],b1[MAXN];
    int N=nxt2k(n*2); dx(n,a,a1); Inv(n,a,a2);
    Mul(n-1,a1,n,a2,b1); Sx(n+n-1-1,b1,b);
    fill(b+n,b+N,0);
  }
  void Exp(int n,ll a[],ll b[]) {
    // Newton method to solve g(a(x))=ln(b(x))-a(x)=0
    // b'=b-g(b(x)) / g'(b(x))
```

```
    // b'=b (1-lnb+a)
    static ll lnb[MAXN],c[MAXN],tmp[MAXN];
    assert(a[0] == 0); // dont know exp(a[0]) mod P
    if(n == 1) { b[0]=1; return; }
    Exp((n+1)/2,a,b); fill(b+(n+1)/2,b+n,0);
    Ln(n,b,lnb); fill(c,c+n,0); c[0]=1;
    FOR(i,n) {
      c[i]+=a[i]-lnb[i]; if(c[i]<0) c[i]+=P;
      if(c[i]>=P) c[i]-=P;
    }
    Mul(n,b,n,c,tmp); copy(tmp,tmp+n,b);
  }
  bool Sqrt(int n,ll a[],ll b[]){
    // Square root of a : b*b=a ( mod x^n )
    // bb=a  mod x^(n/2)
    // ( bb-a )^2=0 mod x^n
    // ( bb+a )^2=4 bba
    // ( ( bb+a ) / 2b )^2=a
    // sqrt(a)=b / 2+a / 2b
    static ll c[MAXN]; int ind=0,x,y,p=1;
    while(a[ind]==0) ind++;
    for(int i=0;i<n;i++) a[i]=a[i+ind];
    if((ind&1)||!dsqrt(a[0],mod,x,y)) // discrete sqrt
      return 0;
    b[0]=min(x,y);
    while(p<n) p<<=1;
    for(int t=2;t<=p;t<<=1){
      Inv(t,b,c); Mul(t,a,t,c,c);
      for(int i=0;i<t;i++)
        b[i]=(b[i]+c[i])*inv(2)%mod;
    }
    if(ind){
      for(int i=p-1;i>=ind/2;i--) b[i]=b[i-ind/2];
      for(int i=0;i<ind/2;i++) b[i]=0;
      for(int i=p-1;i>=ind;i--) a[i]=a[i-ind];
      for(int i=0;i<ind;i++) a[i]=0;
    }
  }
} polyop;
```

3.5 Linear Recurrence 29d614

```
// Usage: linearRec({0, 1}, {1, 1}, k) //k'th fib
typedef vector<ll> Poly;
ll linearRec(Poly&& S, Poly&& tr, ll k) {
  int n=tr.size();
  auto combine=[&](Poly& a, Poly& b) {
    Poly res(n*2+1);
    for(int i=0;i<=n;i++) for(int j=0;j<=n;j++)
      res[i+j]=(res[i+j]+a[i]*b[j])%mod;
    for(int i=2*n;i>n;--i) for(int j=0;j<n;j++)
      res[i-1-j]=(res[i-1-j]+res[i]*tr[j])%mod;
    res.resize(n+1);
    return res;
  }; // combine: a * b mod (x^n-tr)
  Poly pol(n+1), e(pol);
  pol[0]=e[1]=1;
  for (++k;k;k/=2) {
    if(k%2) pol=combine(pol,e);
    e=combine(e,e);
  }
  ll res=0;
  for(int i=0;i<n;i++) res=(res+pol[i+1]*S[i])%mod;
  return res;
}
```

3.6 BerlekampMassey 868031

```
// find shortest linear recurrence relation O(n^2)
// example: BM({1,1,2,3,5,8,13,21})
// 2*len terms for uniqueness
inline vector<ll> BM(const vector<ll> &x) {
  vector<ll> ls, cur; int lf; ll ld;
  for(int i=0;i<x.size();++i) {
    ll t=0;
    for(int j=0;j<cur.size();++j)
      t=(t+x[i-j-1]*cur[j])%mod;
    if((t-x[i])%mod==0) continue;
    if(!cur.size()) {
      cur.resize(i+1); lf=i; ld=(t-x[i])%mod; continue;
    }
    ll k=-(x[i]-t)*inv(ld, mod)%mod;
    vector<ll> c(i-lf-1); c.push_back(k);
    for(auto j:ls) c.push_back(-j*k%mod);
    if(c.size()<cur.size()) c.resize(cur.size());
    for(int j=0;j<cur.size();++j)c[j]=(c[j]+cur[j])%mod;
    if(i-lf+(int)ls.size()>=(int)cur.size())
      ls=cur,lf=i,ld=(t-x[i])%mod;
    cur=move(c);
  }
  for(auto& xx:cur) xx=(xx%mod+mod)%mod;
  return cur;
}
```

3.7 Miller Rabin d99ee6

```
// n < 4,759,123,141        3 :  2, 7, 61
// n < 1,122,004,669,633    4 :  2, 13, 23, 1662803
// n < 3,474,749,660,383          6 :  pirmes <= 13
// n < 2^64                       7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
bool witness(ll a,ll n,ll u,int t){
  if(!a) return 0;
  ll x=mypow(a,u,n);
  for(int i=0;i<t;i++) {
    ll nx=mul(x,x,n);
    if(nx==1&&x!=1&&x!=n-1) return 1;
    x=nx;
  }
  return x!=1;
}
bool miller_rabin(ll n,int s=100) {
  // iterate s times of witness on n
  // return 1 if prime, 0 otherwise
  if(n<2) return 0;
  if(!(n&1)) return n == 2;
  ll u=n-1; int t=0;
  while(!(u&1)) u>>=1, t++;
  while(s--){
    ll a=randll()%(n-1)+1;
    if(witness(a,n,u,t)) return 0;
  }
  return 1;
}
```

3.8 Simplex c2c23c

```
/*target:
  max \sum_{j=1}^n A_{0,j}*x_j
condition:
  \sum_{j=1}^n A_{i,j}*x_j<=A_{i,0} |i=1~m
  x_j >= 0 |j=1~n
VDB=vector<double>*/
template<class VDB>
VDB simplex(int m,int n,vector<VDB> a){
  vector<int> left(m+1),up(n+1);
  iota(left.begin(),left.end(),n);
  iota(up.begin(),up.end(),0);
  auto pivot=[&](int x,int y){
    swap(left[x],up[y]);
    auto k=a[x][y];a[x][y]=1; vector<int> pos;
    for(int j=0;j<=n;++j){
      a[x][j]/=k;
      if(a[x][j]!=0) pos.push_back(j);
    }
    for(int i=0;i<=m;++i){
      if(a[i][y]==0||i==x) continue;
      k=a[i][y],a[i][y]=0;
      for(int j:pos) a[i][j] -= k*a[x][j];
    }
  };
  for(int x,y;;){
    for(int i=x=1;i<=m;++i) if(a[i][0]<a[x][0]) x=i;
    if(a[x][0]>=0) break;
    for(int j=y=1;j<=n;++j) if(a[x][j]<a[x][y]) y=j;
    if(a[x][y]>=0) return VDB(); // infeasible
    pivot(x,y);
  }
  for(int x,y;;){
    for(int j=y=1;j<=n;++j) if(a[0][j]>a[0][y]) y=j;
    if(a[0][y]<=0) break;
    x=-1;
    for(int i=1;i<=m;++i) if(a[i][y]>0)
      if(x==-1||a[i][0]/a[i][y]<a[x][0]/a[x][y]) x=i;
```

```
    if(x==-1) return VDB(); // unbounded
    pivot(x,y);
  }
  VDB ans(n + 1);
  for(int i=1;i<=m;++i)
    if(left[i]<=n) ans[left[i]]=a[i][0];
  ans[0]=-a[0][0];
  return ans;
}
```

3.9 Faulhaber 862da1

```
/* faulhaber' s formula -
 * cal power sum formula of all p=1~k in O(k^2) */
#define MAXK 2500
const int mod = 1000000007;
int b[MAXK],inv[MAXK+1]; // bernoulli number,inverse
int cm[MAXK+1][MAXK+1]; // combinatorics
int co[MAXK][MAXK+2]; // coeeficient of x^j when p=i
inline int getinv(int x) {
  int a=x,b=mod,a0=1,a1=0,b0=0,b1=1;
  while(b) {
    int q,t; q=a/b; t=b; b=a-b*q; a=t;
    t=b0; b0=a0-b0*q; a0=t; t=b1; b1=a1-b1*q; a1=t;
  }
  return a0<0?a0+mod:a0;
}
inline void pre() {
  for(int i=0;i<=MAXK;i++) {
    cm[i][0]=cm[i][i]=1;
    for(int j=1;j<i;j++)
      cm[i][j]=add(cm[i-1][j-1],cm[i-1][j]);
  }
  for(int i=1;i<=MAXK;i++) inv[i]=getinv(i);
  b[0]=1; b[1]=getinv(2); // with b[1] = 1/2
  for(int i=2;i<MAXK;i++) {
    if(i&1) { b[i]=0; continue; }
    b[i]=1;
    for(int j=0;j<i;j++)
      b[i]=sub(b[i],mul(cm[i][j],mul(b[j],inv[i-j+1])));
  }
  /* faulhaber */
  // sigma_x=1~n {x^p} =
  //   1/(p+1) * sigma_j=0~p {C(p+1,j)*Bj*n^(p-j+1)}
  for(int i=1;i<MAXK;i++) {
    co[i][0]=0;
    for(int j=0;j<=i;j++)
      co[i][i-j+1]=mul(inv[i+1],mul(cm[i+1][j],b[j]));
  }
}
/* sample usage: return f(n,p) = sigma_x=1~n (x^p) */
inline int solve(int n,int p) {
  int sol=0,m=n;
  for(int i=1;i<=p+1;i++) {
    sol=add(sol,mul(co[p][i],m)); m=mul(m, n);
  }
  return sol;
}
```

3.10 Chinese Remainder 94874a

```
ll crt(ll x1, ll m1, ll x2, ll m2) {
  ll g = __gcd(m1, m2); // or std::gcd
  if((x2 - x1) % g) return -1;// no sol
  m1 /= g; m2 /= g;
  pair<ll,ll> p = gcd(m1, m2);
  ll lcm = m1 * m2 * g;
  ll res=p.first*(x2-x1)%lcm*m1%lcm+x1; // overflow m^3
  return (res % lcm + lcm) % lcm;
}
```

3.11 Pollard Rho 76826e

```
// does not work when n is prime
ll f(ll x, ll mod){ return add(mul(x,x,mod),1,mod); }
ll pollard_rho(ll n) {
  if(!(n&1)) return 2;
  while(true){
    ll y=2, x=rand()%(n-1)+1, res=1;
    for(int sz=2; res==1; sz*=2) {
      for(int i=0; i<sz && res<=1; i++) {
        x = f(x, n); res = __gcd(abs(x-y), n);
      }
      y = x;
    }
    if (res!=0 && res!=n) return res;
  }
}
```

3.12 ax+by=gcd 5a651f

```
pair<ll,ll> gcd(ll a, ll b){
  if(b == 0) return {1, 0};
  pair<ll,ll> q = gcd(b, a % b);
  return {q.second, q.first - q.second * (a / b)};
}
```

3.13 Discrete sqrt 40104b

```
void calcH(int &t,int &h,const int p){
  int tmp=p-1; for(t=0;(tmp&1)==0;tmp/=2) t++; h=tmp;
}
// solve equation x^2 mod p=a where p is a prime
bool dsqrt(int a,int p,int &x,int &y){
  if(p==2){ x=y=1; return true; }
  int p2=p/2,tmp=mypow(a,p2,p);
  if(tmp==p-1) return false;
  if((p+1)%4==0){
    x=mypow(a,(p+1)/4,p); y=p-x; return true;
  } else{
    int t,h,b,pb; calcH(t,h,p);
    if(t>=2){
      do{ b=rand()%(p-2)+2; }while(mypow(b,p/2,p)!=p-1);
      pb=mypow(b,h,p);
    }
    int s=mypow(a,h/2,p);
    for(int step=2; step<=t; step++){
      int ss=(((ll)(s*s)%p)*a)%p;
      for(int i=0;i<t-step;i++) ss=mul(ss,ss,p);
      if(ss+1==p) s=(s*pb)%p;
      pb=((ll)pb*pb)%p;
    }
    x=((ll)s*a)%p; y=p-x;
  }
  return true;
}
```

3.14 Romberg 6dc94c

```
// Estimates the definite integral of \int_a^b f(x) dx
template<class T>
double romberg(T& f,double a,double b,double eps=1e-8){
  vector<double>t; double h=b-a,last,curr; int k=1,i=1;
  t.push_back(h*(f(a)+f(b))/2);
  do{ last=t.back(); curr=0; double x=a+h/2;
    for(int j=0;j<k;j++) curr+=f(x), x+=h;
    curr=(t[0]+h*curr)/2; double k1=4.0/3.0,k2=1.0/3.0;
    for(int j=0;j<i;j++){ double temp=k1*curr-k2*t[j];
      t[j]=curr; curr=temp; k2/=4*k1-k2; k1=k2+1;
    }
    t.push_back(curr); k*=2; h/=2; i++;
  }while( fabs(last-curr)>eps);
  return t.back();
}
```

3.15 Simpson 3fec8d

```
template<class F>
ld quad(ld a,ld b,F f,const int n=1000) {
    ld h=(b-a)/2/n,v=f(a)+f(b);
    for(int i=1;i<n*2;++i) v+=f(a+i*h)*(i&1?4:2);
    return v*h/3;
}
```

3.16 Prefix Inverse 9e8ee9

```
void solve(int m){
  inv[1]=1;
  for(int i=2;i<m;i++) inv[i]=((ll)(m-m/i)*inv[m%i])%m;
}
```

3.17 Roots of Polynomial 20a9c9

```
const double eps=1e-12,inf=1e+12;
double a[10],x[10]; // a[0..n](coef) must be filled
int n; // degree of polynomial must be filled
int sign(double x){ return (x<-eps)?(-1):(x>eps); }
double f(double a[],int n,double x){
  double tmp=1,sum=0;
  for(int i=0;i<=n;i++) { sum=sum+a[i]*tmp; tmp=tmp*x; }
  return sum;
}
double binary(double l,double r,double a[],int n){
  int sl=sign(f(a,n,l)),sr=sign(f(a,n,r));
  if(sl==0) return l; if(sr==0) return r;
  if(sl*sr>0) return inf;
  while(r-l>eps){
    double mid=(l+r)/2; int ss=sign(f(a,n,mid));
    if(ss==0) return mid;
    if(ss*sl>0) l=mid; else r=mid;
  }
  return l;
}
void solve(int n,double a[],double x[],int &nx){
  if(n==1){ x[1]=-a[0]/a[1]; nx=1; return; }
  double da[10],dx[10]; int ndx;
  for(int i=n;i>=1;i--) da[i-1]=a[i]*i;
  solve(n-1,da,dx,ndx); nx=0;
  if(ndx==0){
    double tmp=binary(-inf,inf,a,n);
    if(tmp<inf) x[++nx]=tmp;
    return;
  }
  double tmp=binary(-inf,dx[1],a,n);
  if(tmp<inf) x[++nx]=tmp;
  for(int i=1;i<=ndx-1;i++){
    tmp=binary(dx[i],dx[i+1],a,n);
    if(tmp<inf) x[++nx]=tmp;
  }
  tmp=binary(dx[ndx],inf,a,n);
  if(tmp<inf) x[++nx]=tmp;
} // roots are stored in x[1..nx]
```

3.18 Primes and μ function d79d2b

```
/* 12721, 13331, 14341, 75577, 123457, 222557, 556679
* 999983, 1097774749, 1076767633, 100102021, 999997771
* 1001010013, 1000512343, 987654361, 999991231
* 999888733, 98789101, 987777733, 999991921, 1010101333
* 1010102101, 1000000000039, 1000000000000037
* 2305843009213693951, 4611686018427387847
* 9223372036854775783, 18446744073709551557 */
int mu[N],p_tbl[N]; // mobius, min prime factor
vector<int> primes;
void sieve() { // calculate multiplicative function f
  mu[1]=p_tbl[1]=1;
  for(int i=2;i<N;i++){
    if(!p_tbl[i]){
      p_tbl[i]=i; primes.push_back(i);
      mu[i]=-1; // f(i)=... where i is prime
    }
    for(int p:primes){
      int x=i*p;
      if(x>=N) break;
      p_tbl[x]=p; mu[x]=-mu[i];
      if(i%p==0){ // f(x)=f(i)/f(p^(k-1))*f(p^k)
        mu[x]=0; break;
      } // else f(x)=f(i)*f(p) where gcd(i,p)=1
} } }
vector<int> factor(int x){
  vector<int> fac{ 1 };
  while(x > 1){
    int fn=fac.size(),p=p_tbl[x],pos=0;
    while(x%p==0){
      x/=p;
      for(int i=0;i<fn;i++) fac.push_back(fac[pos++]*p);
    }
  }
  return fac;
}
```

3.19 Subset Convolution 84a3e0

```
// h(s)=\sum_{s' \subseteq s} f(s')g(s\backslash s')
vector<int> SubsetConv(int n,const vector<int> &f,const
    vector<int> &g){
  const int m=1<<n;
  vector<vector<int>> a(n+1,vector<int>(m)),b=a;
  for(int i=0;i<m;++i){
    a[__builtin_popcount(i)][i]=f[i];
    b[__builtin_popcount(i)][i]=g[i];
  }
  for(int i=0;i<=n;++i){
    for(int j=0;j<n;++j){
      for(int s=0;s<m;++s){
        if(s>>j&1){
          a[i][s]+=a[i][s^(1<<j)];
          b[i][s]+=b[i][s^(1<<j)];
  } } } }
  vector<vector<int>> c(n+1,vector<int>(m));
  for(int s=0;s<m;++s){
    for(int i=0;i<=n;++i){
      for(intj=0;j<=i;++j) c[i][s]+=a[j][s]*b[i-j][s];
  } }
  for(int i=0;i<=n;++i){
    for(int j=0;j<n;++j){
      for(int s=0;s<m;++s){
        if(s>>j&1) c[i][s]-=c[i][s^(1<<j)];
  } } }
  vector<int> res(m);
  for(int i=0;i<m;++i)
    res[i]=c[__builtin_popcount(i)][i];
  return res;
}
```

3.20 Result fd0b69

- Lucas' Theorem :
  For $n, m \in \mathbb{Z}^*$ and prime P, $C(m,n)$ mod $P = \Pi(C(m_i, n_i))$ where m_i is the i-th digit of m in base P.
- 1st Stirling Numbers(permutation $|P| = n$ with k cycles):
  $S(n,k)$ = coefficient of x^k in $\Pi_{i=0}^{n-1}(x+i)$
  $S(n+1,k) = nS(n,k) + S(n,k-1)$
- 2nd Stirling Numbers(Partition n elements into k non-empty set):
  $S(n,k) = \frac{1}{k!}\sum_{j=0}^{k}(-1)^{k-j}\binom{k}{j}j^n$
  $S(n+1,k) = kS(n,k) + S(n,k-1)$
- Calculate $f(x+n)$ where $f(x) = \sum_{i=0}^{n-1} a_i x^i$:
  $f(x+n) = \sum_{i=0}^{n-1} a_i(x+n)^i = \sum_{i=0}^{n-1} x^i \cdot \frac{1}{i!}\sum_{j=i}^{n-1}\frac{a_j}{j!}\cdot\frac{n^{j-i}}{(j-i)!}$
- Calculate $c[i-j] += a[i] \times b[j]$ for $a[n], b[m]$
  1. a=reverse(a); c=mul(a,b); c=reverse(c[:n]);
  2. b=reverse(b); c=mul(a,b); c=rshift(c,m-1);
- Eulerian number(permutation $1 \sim n$ with m $a[i] > a[i-1]$):
  $A(n,m) = \sum_{i=0}^{m}(-1)^i\binom{n+1}{i}(m+1-i)^n$
  $A(n,m) = (n-m)A(n-1,m-1) + (m+1)A(n-1,m)$
- Derangement:
  $D(n) = (n-1)(D(n-1)+D(n-2)) = nD(n-1)+(-1)^n$
- Pick's Theorem : $A = i + b/2 - 1$
- Euler Characteristic:
  planar graph: $V - E + F - C = 1$
  convex polyhedron: $V - E + F = 2$
  V, E, F, C: number of vertices, edges, faces(regions), and components
- Kirchhoff's theorem :
  - number of spanning tree of undirected graph:
  degree matrix $D_{ii} = deg(i)$, $D_{ij} = 0$
  adjacency matrix $G_{ij} = \#\,of\ (i,j) \in E$, $G_{ii} = 0$,
  let $A = D - G$, delete any one row, one column, and cal $det(A')$
  - number of spanning tree of directed graph:
  in-degree matrix $D^{in}_{ii} = indeg(i)$, $D^{in}_{ij} = 0$
  out-degree matrix $D^{out}_{ii} = outdeg(i)$, $D^{out}_{ij} = 0$
  let $L^{in} = D^{in} - G$, $L^{out} = D^{out} - G$, delete the i-th row and column
  $det(L^{in}_i)$ and $det(L^{out}_i)$ is the number of spanning tree from/to root i
- Burnside Lemma: $|X/G| = \frac{1}{|G|}\sum_{g\in G}|X^g|$
- Polya theorem: $|Y^x/G| = \frac{1}{|G|}\sum_{g\in G} m^{c(g)}$
  $m = |Y|$: num of colors, c(g) : num of cycle
- Anti SG (the person who has no strategy wins) :
  first player wins iff either
  1. SG value of ALL subgame ≤ 1 and SG value of the game $= 0$
  2. SG value of some subgame > 1 and SG value of the game $\neq 0$

- Möbius inversion formula :
  $g(n)=\sum_{d|n} f(d)$ for every integer $n\geq 1$, then
  $f(n)=\sum_{d|n}\mu(d)g(\frac{n}{d})=\sum_{d|n}\mu(\frac{n}{d})g(d)$ for every integer $n\geq 1$
  Dirichlet convolution : $f*g=g*f=\sum_{d|n} f(d)g(\frac{n}{d})=\sum_{d|n} f(\frac{n}{d})g(d)$
  $g=f*1\Leftrightarrow f=g*\mu,\ \epsilon=\mu*1,\ Id=\phi*1,\ d=1*1,\ \sigma=Id*1=\phi*d,$
  $\sigma_k=Id_k*1$ where $\epsilon(n)=[n=1],\ 1(n)=1,\ Id(n)=n,\ Id_k(n)=n^k,$
  $d(n)=\#(divisor),\ \sigma(n)=\sum divisor,\ \sigma_k(n)=\sum divisor^k$
- Find a Primitive Root of n:
  n has primitive roots iff $n=2,4,p^k,2p^k$ where p is an odd prime.
  1. Find $\phi(n)$ and all prime factors of $\phi(n)$, says $P=\{p_1,...,p_m\}$
  2. $\forall g\in[2,n)$, if $g^{\frac{\phi(n)}{p_i}}\neq 1,\forall p_i\in P$, then g is a primitive root.
  3. Since the smallest one isn't too big, the algorithm runs fast.
  4. n has exactly $\phi(\phi(n))$ primitive roots.
- Sum of Two Squares Thm (Legendre):
  For a given positive integer N, let
  $D1=$(# of $d\in N$ dividing N that $d=1$ (mod 4))
  $D3=$(# of $d\in N$ dividing N that $d=3$ (mod 4))
  then N can be written as a sum of two squares in exactly $R(N)=4(D1-D3)$ ways.
- Difference of $D1-D3$ Thm:
  let $N=2^t\times[p_1^{e_1}\times...\times p_r^{er}]\times[q_1^{f_1}\times...\times q_s^{fs}]$
  where $p_i\in mod\ 4=1\ prime$, $q_i\in mod\ 4=3\ prime$
  then $D1-D3=\begin{cases}(e1+1)(e2+1)...(er+1) & if\ f_i\ all\ even\\ 0 & if\ any\ f_i\ is\ odd\end{cases}$
- Sherman-Morrison formula:
  suppose $A\in\mathbb{R}^{n\times n}$ is invertible and $u,v\in\mathbb{R}^n$
  $A+uv^T$ is invertible if and only if $1+v^TA^{-1}u\neq 0$
  $(A+uv^T)^{-1}=A^{-1}-\frac{A^{-1}uv^TA^{-1}}{1+v^TA^{-1}u}$
- Pohlig-Hellman algorithm (discrete log):
  Given an order n group, generator g, element h, find x s.t. $g^x=h$.
  If $n=p^e$:
  * let $x_0=0$, $\gamma=g^{p^{e-1}}$ where γ has order p.
  * for $k=0\sim e-1$:
  1. let $h_k=(g^{-x_k}h)^{p^{e-1-k}}$ whose order divide $p\implies h_k\in\langle\gamma\rangle$.
  2. find d_k s.t. $\gamma^{d_k}=h_k$ with baby-step giant-step in $O(\sqrt{p})$.
  3. set $x_{k+1}=x_k+p^kd_k$
  * return x_e in total time complexity $O(e\sqrt{p})$
  If $n=\Pi_{i=1}^r p_i^{e_i}$:
  * for each $i=1\sim r$:
  1. let $g_i=g^{n/p_i^{e_i}}$ having order $p_i^{e_i}$, $h_i=h^{n/p_i^{e_i}}$ where $h_i\in\langle g_i\rangle$.
  2. find x_i s.t. $g_i^{x_i}=h_i$ using above algorithm.
  * return $x=CRT(\{x_i \mod p_i^{e_i}\})$

4 Geometry

4.1 Intersection of 2 lines 3db65e

```
Pt LLIntersect(Line a, Line b) {
  Pt p1 = a.s, p2 = a.e, q1 = b.s, q2 = b.e;
  ld f1 = (p2-p1)^(q1-p1),f2 = (p2-p1)^(p1-q2),f;
  if(dcmp(f=f1+f2) == 0)
    return dcmp(f1)?Pt(NAN,NAN):Pt(INFINITY,INFINITY);
  return q1*(f2/f) + q2*(f1/f);
}
```

4.2 halfPlaneIntersection 1d54e0

```
// for point or line solution,change > to >=
bool onleft(Line L,Pt p) {
  return dcmp(L.v^(p-L.s)) > 0;
}
// assume that Lines intersect
vector<Pt> HPI(vector<Line>& L) {
  sort(L.begin(),L.end()); // sort by angle
  int n=L.size(),fir,las; Pt *p=new Pt[n];
  vector<Line> q(n); q[fir=las=0]=L[0];
  for(int i=1;i<n;i++) {
    while(fir<las&&!onleft(L[i],p[las-1])) las--;
    while(fir<las&&!onleft(L[i],p[fir])) fir++;
    q[++las]=L[i];
    if(dcmp(q[las].v^q[las-1].v) == 0) {
      las--;
      if(onleft(q[las],L[i].s)) q[las]=L[i];
    }
    if(fir<las) p[las-1]=LLIntersect(q[las-1],q[las]);
  }
  while(fir<las&&!onleft(q[fir],p[las-1])) las--;
  if(las-fir<=1) return {};
  p[las]=LLIntersect(q[las],q[fir]);
  int m=0; vector<Pt> ans(las-fir+1);
  for(int i=fir;i<=las;i++) ans[m++]=p[i];
  return ans;
}
```

4.3 Intersection of 2 segments b7e393

```
bool onseg(Pt p, Line L) {
  Pt x = L.s-p, y = L.e-p;
  return dcmp(x^y) == 0 && dcmp(x*y) <= 0;
} // inseg: dcmp(x^y)==0&&dcmp(x*y)<0
// assume a.s != a.e != b.s != b.e
Pt SSIntersect(Line a, Line b) {
  Pt p = LLIntersect(a, b);
  if(isinf(p.x)&&(onseg(a.s,b)||onseg(a.e,b)||onseg(b.s,
      a)||onseg(b.e,a))) return p; // overlap
  if(isfinite(p.x)&&onseg(p,a)&&onseg(p,b)) return p;
  return {NAN,NAN}; // non-intersect
}
```

4.4 Banana de5c4e

```
int ori(const Pt& o,const Pt& a,const Pt& b){
  ll ret=(a-o)^(b-o);
  return (ret>0)-(ret<0);
}
// p1==p2||q1==q2 need to be handled
bool banana(const Pt& p1,const Pt& p2,
            const Pt& q1,const Pt& q2){
  if(((p2-p1)^(q2-q1))==0){ // parallel
    if(ori(p1,p2,q1)) return false;
    return ((p1-q1)*(p2-q1))<=0||((p1-q2)*(p2-q2))<=0||
           ((q1-p1)*(q2-p1))<=0||((q1-p2)*(q2-p2))<=0;
  }
  return (ori(p1,p2,q1)*ori(p1,p2,q2)<=0)&&
         (ori(q1,q2,p1)*ori(q1,q2,p2)<=0);
}
```

4.5 Intersection of circle and line 73c7f5

```
vector<Pt> CLInter(const Line &a,const Circle &c){
    Pt p=a.s+(c.o-a.s)*a.v/norm2(a.v)*a.v;
    ld d=c.r*c.r-norm2(c.o-p);
    if(d<-eps) return {};
    if(d<eps) return {p};
    Pt v=a.v/norm(a.v)*sqrt(d);
    return {p+v,p-v};
}
```

4.6 Intersection of polygon and circle 868772

```
ld PCInter(vector<Pt> v, Circle cir) {
  for(int i=0;i<(int)v.size();++i) v[i]=v[i]-cir.o;
  ld ans=0,r=cir.r; int n=v.size();
  for(int i=0;i<n;++i) {
    Pt pa=v[i],pb=v[(i+1)%n];
    if(norm(pa)<norm(pb)) swap(pa,pb);
    if(dcmp(norm(pb))==0) continue;
    ld s,h,theta,a=norm(pb),b=norm(pa),c=norm(pb-pa);
    ld cosB=(pb*(pb-pa))/a/c,B=acos(cosB);
    if(cosB>1) B=0; else if(cosB<-1) B=PI;
    ld cosC=(pa*pb)/a/b,C=acos(cosC);
    if(cosC>1) C=0; else if(cosC<-1) C=PI;
    if(a>r){
      s=(C/2)*r*r; h=a*b*sin(C)/c;
      if(h<r&&B<PI/2) s-=acos(h/r)*r*r-h*sqrt(r*r-h*h);
    }
    else if(b>r) {
      theta=PI-B-asin(sin(B)/r*a);
      s=0.5*a*r*sin(theta)+(C-theta)/2*r*r;
    }
    else s=0.5*sin(C)*a*b;
    ans+=abs(s)*dcmp(v[i]^v[(i+1)%n]);
  }
  return abs(ans);
}
```

4.7 Intersection of 2 circles 57edf8

```
vector<Pt> CCinter(Circle& a, Circle& b){
  Pt o1=a.o,o2=b.o; ld r1=a.r,r2=b.r;
  if(norm(o1-o2)>r1+r2) return {};
  if(norm(o1-o2)<max(r1,r2)-min(r1,r2)) return {};
  ld d2=(o1-o2)*(o1-o2),d=sqrt(d2);
  if(d>r1+r2) return {};
  Pt u=(o1+o2)*0.5+(o1-o2)*((r2*r2-r1*r1)/(2*d2));
  ld A=sqrt((r1+r2+d)*(r1-r2+d)*(r1+r2-d)*(-r1+r2+d));
  Pt v=Pt(o1.y-o2.y,-o1.x+o2.x)*A/(2*d2);
  return {u+v,u-v};
}
```

4.8 Circle cover 4b4772

```
#define N 1021
struct CircleCover{            // overlap
  int C; Circle c[N]; bool g[N][N],over[N][N];
  // Area[i] : area covered by at least i circles
  ld Area[N];
  void init(int _C){ C=_C;}
  struct Teve {
    Pt p;ld ang;int add;
    Teve() {}
    Teve(Pt _a,ld _b,int _c):p(_a),ang(_b),add(_c){}
    bool operator<(const Teve &a) const
    { return ang<a.ang;}
  }eve[N*2];
  // strict: x=0,otherwise x=-1
  bool disjunct(Circle& a,Circle &b,int x)
  { return sign(norm(a.o-b.o)-a.r-b.r)>x; }
  bool contain(Circle& a,Circle &b,int x)
  { return sign(a.r-b.r-norm(a.o-b.o))>x; }
  bool contain(int i,int j){
    /* c[j] is non-strictly in c[i]. */
    return (sign(c[i].r-c[j].r)>0||(sign(c[i].r-c[j].r)
        ==0&&i<j))&&contain(c[i],c[j],-1);
  }
  void solve(){
    for(int i=0;i<=C+1;i++) Area[i]=0;
    for(int i=0;i<C;i++) for(int j=0;j<C;j++)
        over[i][j]=contain(i,j);
    for(int i=0;i<C;i++) for(int j=0;j<C;j++)
        g[i][j]=!(over[i][j]||over[j][i]||disjunct(c[i],
            c[j],-1));
    for(int i=0;i<C;i++){
      int E=0,cnt=1;
      for(int j=0;j<C;j++) if(j!=i&&over[j][i]) cnt++;
      for(int j=0;j<C;j++)
        if(i!=j && g[i][j]){
          vector<Pt> v=CCinter(c[i],c[j]);
          ld A=atan2(v[0].y-c[i].o.y,v[0].x-c[i].o.x);
          ld B=atan2(v[1].y-c[i].o.y,v[1].x-c[i].o.x);
          eve[E++]=Teve(v[1],B,1);
          eve[E++]=Teve(v[0],A,-1);
          if(B>A) cnt++;
        }
      if(E==0) Area[cnt]+=pi*c[i].r*c[i].r;
      else{
        sort(eve,eve+E); eve[E]=eve[0];
        for(int j=0;j<E;j++){
          cnt+=eve[j].add;
          Area[cnt]+=(eve[j].p^eve[j+1].p)*.5;
          ld theta=eve[j+1].ang-eve[j].ang;
          if(theta<0) theta+=2.*pi;
          Area[cnt]+=(theta-sin(theta))*c[i].r*c[i].r/2;
} } } } };
```

4.9 Li Chao Segment Tree 549a4b

```
struct LiChao_min{
  struct line{
    ll m,c;
    line(ll _m=0,ll _c=0) { m=_m; c=_c; }
    ll eval(ll x) { return m*x+c; }
  };
  struct node{
    node *l,*r; line f;
    node(line v) { f=v; l=r=NUll; }
  };
  typedef node* pnode;
  pnode root; int sz;
#define mid ((l+r)>>1)
  void insert(line &v,int l,int r,pnode &nd){
    if(!nd) { nd=new node(v); return; }
    ll trl=nd->f.eval(l),trr=nd->f.eval(r);
    ll vl=v.eval(l),vr=v.eval(r);
    if(trl<=vl&&trr<=vr) return;
    if(trl>vl&&trr>vr) { nd->f=v; return; }
    if(trl>vl) swap(nd->f,v);
    if(nd->f.eval(mid)<v.eval(mid))
      insert(v,mid+1,r,nd->r);
    else swap(nd->f,v),insert(v,l,mid,nd->l);
  }
  ll query(int x,int l,int r,pnode &nd){
    if(!nd) return LLONG_MAX;
    if(l==r) return nd->f.eval(x);
    if(mid>=x)
      return min(nd->f.eval(x),query(x,l,mid,nd->l));
    return min(nd->f.eval(x),query(x,mid+1,r,nd->r));
  }
  /* -sz<=ll query_x<=sz */
  void init(int _sz){ sz=_sz+1; root=NUll; }
  void add_line(ll m,ll c){
    line v(m,c); insert(v,-sz,sz,root);
  }
  ll query(ll x) { return query(x,-sz,sz,root); }
};
```

4.10 Convex Hull trick 66a3a1

```
/* Given a convexhull,answer querys in O(\lg N)
CH should not contain identical points,the area should
be>0,min pair(x,y) should be listed first */
double det(const Pt& p1,const Pt& p2)
{ return p1.x*p2.y-p1.y*p2.x;}
struct Conv{
  int n;vector<Pt> a,upper,lower;
  Conv(vector<Pt> _a):a(_a){
    n=a.size();int ptr=0;
    for(int i=1;i<n;++i) if(a[ptr]<a[i]) ptr=i;
    for(int i=0;i<=ptr;++i) lower.push_back(a[i]);
    for(int i=ptr;i<n;++i) upper.push_back(a[i]);
    upper.push_back(a[0]);
  } // sign: modify when changing to double
  int sign(ll x){ return x<0?-1:x>0; }
  pair<ll,int> get_tang(vector<Pt> &conv,Pt vec){
    int l=0,r=(int)conv.size()-2;
    while(l+1<r){
      int mid=(l+r)/2;
      if(sign(det(conv[mid+1]-conv[mid],vec))>0) r=mid;
      else l=mid;
    }
    return max(make_pair(det(vec,conv[r]),r),
               make_pair(det(vec,conv[0]),0));
  }
  void upd_tang(const Pt &p,int id,int &i0,int &i1){
    if(det(a[i0]-p,a[id]-p)>0) i0=id;
    if(det(a[i1]-p,a[id]-p)<0) i1=id;
  }
  void bi_search(int l,int r,Pt p,int &i0,int &i1){
    if(l==r) return;
    upd_tang(p,l%n,i0,i1);
    int sl=sign(det(a[l%n]-p,a[(l+1)%n]-p));
    while(l+1<r){
      int mid=(l+r)/2;
      int smid=sign(det(a[mid%n]-p,a[(mid+1)%n]-p));
      if(smid==sl) l=mid; else r=mid;
    }
    upd_tang(p,r%n,i0,i1);
  }
  int bi_search(Pt u,Pt v,int l,int r){
    int sl=sign(det(v-u,a[l%n]-u));
    while(l+1<r){
      int mid=(l+r)/2,smid=sign(det(v-u,a[mid%n]-u));
      if(smid==sl) l=mid; else r=mid;
    }
    return l%n;
  }
  // 1. whether a given point is inside the CH
  bool contain(Pt p){
    if(p.x<lower[0].x||p.x>lower.back().x) return 0;
```

```
    int id=lower_bound(lower.begin(),lower.end(),Pt(p.x
        ,-INF))-lower.begin();
    if(lower[id].x==p.x){
      if(lower[id].y>p.y) return 0;
    }else if(det(lower[id-1]-p,lower[id]-p)<0) return 0;
    id=lower_bound(upper.begin(),upper.end(),Pt(p.x,INF)
        ,greater<Pt>())-upper.begin();
    if(upper[id].x==p.x){
      if(upper[id].y<p.y) return 0;
    }else if(det(upper[id-1]-p,upper[id]-p)<0) return 0;
    return 1;
  }
  // 2. Find 2 tang pts on CH of a given outside point
  // return true with i0,i1 as index of tangent points
  // return false if inside CH
  bool get_tang(Pt p,int &i0,int &i1){
    if(contain(p)) return false;
    i0=i1=0;
    int id=lower_bound(lower.begin(),lower.end(),p)-
        lower.begin();
    bi_search(0,id,p,i0,i1);
    bi_search(id,(int)lower.size(),p,i0,i1);
    id=lower_bound(upper.begin(),upper.end(),p,greater<
        Pt>())-upper.begin();
    bi_search((int)lower.size()-1,(int)lower.size()-1+id
        ,p,i0,i1);
    bi_search((int)lower.size()-1+id,(int)lower.size()
        -1+(int)upper.size(),p,i0,i1);
    return true;
  }
  // 3. Find tangent points of a given vector
  // ret the idx of vertex has max cross value with vec
  int get_tang(Pt vec){
    pair<ll,int> ret=get_tang(upper,vec);
    ret.second=(ret.second+(int)lower.size()-1)%n;
    ret=max(ret,get_tang(lower,vec));
    return ret.second;
  }
  // 4. Find intersection point of a given line
  // return 1 and intersection is on edge (i,next(i))
  // return 0 if no strictly intersection
  bool get_intersection(Pt u,Pt v,int &i0,int &i1){
   int p0=get_tang(u-v),p1=get_tang(v-u);
   if(sign(det(v-u,a[p0]-u))*sign(det(v-u,a[p1]-u))<0){
     if(p0>p1) swap(p0,p1);
     i0=bi_search(u,v,p0,p1); i1=bi_search(u,v,p1,p0+n);
     return 1;
   }
   return 0;
  }
};
```

4.11 Tangent line of two circles a45324

```
vector<Line> go(const Circle& c1,const Circle& c2,int
    sign1){
  // sign1=1 for outer tang,-1 for inter tang
  vector<Line> ret;
  double d_sq=norm2(c1.o-c2.o);
  if(d_sq<eps) return ret;
  double d=sqrt(d_sq); Pt v=(c2.o-c1.o)/d;
  double c=(c1.r-sign1*c2.r)/d;
  if(c*c>1) return ret;
  double h=sqrt(max(0.0,1.0-c*c));
  for(int sign2=1;sign2>=-1;sign2-=2){
    Pt n={v.x*c-sign2*h*v.y, v.y*c+sign2*h*v.x};
    Pt p1=c1.o+n*c1.r,p2=c2.o+n*(c2.r*sign1);
    if(fabs(p1.x-p2.x)<eps and fabs(p1.y-p2.y)<eps)
      p2=p1+perp(c2.o-c1.o);
    ret.push_back({p1,p2});
  }
  return ret;
}
```

4.12 Tangent line of point and circle 35a7bf

```
vector<Line> PCTangent(const Circle& C,const Pt& P){
  vector<Line> ans; Pt u=C.o-P; double dist=norm(u);
  if(dist<C.r) return ans;
  else if(abs(dist)<eps){
    ans.push_back({P,P+rotate(u,M_PI/2)});
    return ans;
  }
  else{
    double ang=asin(C.r/dist);
    ans.push_back({P,P+rotate(u,-ang)});
    ans.push_back({P,P+rotate(u,+ang)});
    return ans;
  }
}
```

4.13 Min distance of two convex 55abcb

```
double TwoConvexHullMinDis(Pt P[],Pt Q[],int n,int m){
  int mn=0,mx=0; double tmp,ans=1e9;
  for(int i=0;i<n;++i) if(P[i].y<P[mn].y) mn=i;
  for(int i=0;i<m;++i) if(Q[i].y>Q[mx].y) mx=i;
  P[n]=P[0]; Q[m]=Q[0];
  for (int i=0;i<n;++i) {
    while(tmp=((Q[mx+1]-P[mn+1])^(P[mn]-P[mn+1]))>((Q[mx
        ]-P[mn+1])^(P[mn]-P[mn+1]))) mx=(mx+1)%m;
    if(tmp<0) // pt to segment distance
      ans=min(ans,dis(Line(P[mn],P[mn+1]),Q[mx]));
    else // segment to segment distance
      ans=min(ans,dis(Line(P[mn],P[mn+1]),Line(Q[mx],Q[
          mx+1])));
    mn=(mn+1)%n;
  }
  return ans;
}
```

4.14 Poly Union 7a6b24

```
struct PY{
  int n; Pt pt[5]; double area;
  Pt& operator[](const int x){ return pt[x]; }
  void init(){ //n,pt[0~n-1] must be filled
    area=pt[n-1]^pt[0];
    for(int i=0;i<n-1;i++) area+=pt[i]^pt[i+1];
    if((area/=2)<0)reverse(pt,pt+n),area=-area;
  }
};
PY py[500]; pair<double,int> c[5000];
inline double segP(Pt &p,Pt &p1,Pt &p2){
  if(dcmp(p1.x-p2.x)==0) return (p.y-p1.y)/(p2.y-p1.y);
  return (p.x-p1.x)/(p2.x-p1.x);
}
double polyUnion(int n){ //py[0~n-1] must be filled
  int i,j,ii,jj,ta,tb,r,d; double z,w,s,sum=0,tc,td;
  for(i=0;i<n;i++) py[i][py[i].n]=py[i][0];
  for(i=0;i<n;i++){
    for(ii=0;ii<py[i].n;ii++){
      r=0;
      c[r++]=make_pair(0.0,0); c[r++]=make_pair(1.0,0);
      for(j=0;j<n;j++){
        if(i==j) continue;
        for(jj=0;jj<py[j].n;jj++){
          ta=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj]));
          tb=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj+1])
              );
          if(ta==0 && tb==0){
            if((py[j][jj+1]-py[j][jj])*(py[i][ii+1]-py[i
                ][ii])>0&&j<i){
              c[r++]=make_pair(segP(py[j][jj],py[i][ii],
                  py[i][ii+1]),1);
              c[r++]=make_pair(segP(py[j][jj+1],py[i][ii
                  ],py[i][ii+1]),-1);
            }
          }else if(ta>=0 && tb<0){
            tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
            td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
            c[r++]=make_pair(tc/(tc-td),1);
          }else if(ta<0 && tb>=0){
            tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
            td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
            c[r++]=make_pair(tc/(tc-td),-1);
      } } }
      sort(c,c+r);
      z=min(max(c[0].first,0.0),1.0); d=c[0].second; s
          =0;
      for(j=1;j<r;j++){
        w=min(max(c[j].first,0.0),1.0);
        if(!d) s+=w-z;
```

```
        d+=c[j].second; z=w;
      }
      sum+=(py[i][ii]^py[i][ii+1])*s;
    }
  }
  return sum/2;
}
```

4.15 Lower Concave Hull dd665b

```
const ll is_query=-(1LL<<62);
struct Line {
  ll m, b;
  mutable function<const Line*()> succ;
  bool operator<(const Line& rhs) const {
    if (rhs.b!=is_query) return m<rhs.m;
    const Line* s=succ();
    return s?b-s->b<(s->m-m)*rhs.m:0;
  }
}; // maintain upper hull for maximum
struct HullDynamic:public multiset<Line> {
  bool bad(iterator y) {
    auto z=next(y);
    if (y==begin()) {
      if (z==end()) return 0;
      return y->m==z->m&&y->b<=z->b;
    }
    auto x=prev(y);
    if(z==end()) return y->m==x->m&&y->b<=x->b;
    return
      (x->b-y->b)*(z->m-y->m)>=(y->b-z->b)*(y->m-x->m);
  }
  void insert_line(ll m, ll b) {
    auto y=insert({m, b});
    y->succ=[=]{ return next(y)==end()?0:&*next(y); };
    if(bad(y)) { erase(y); return; }
    while(next(y)!=end()&&bad(next(y))) erase(next(y));
    while(y!=begin()&&bad(prev(y))) erase(prev(y));
  }
  ll eval(ll x) {
    auto l=*lower_bound((Line) { x, is_query });
    return l.m*x + l.b;
  }
};
```

4.16 Delaunay Triangulation 8ee9b3

```
/* Delaunay Triangulation:
Given a sets of points on 2D plane, find a
triangulation such that no points will strictly
inside circumcircle of any triangle.

find: return a triangle contain given point
add_point: add a point into triangulation

A Triangle is in triangulation iff. its has_chd is 0.
Region of triangle u: iterate each u.edge[i].tri,
each points are u.p[(i+1)%3], u.p[(i+2)%3]

Voronoi diagram: for each triangle in triangulation,
the bisector of all its edges will split the region.
nearest point will belong to the triangle containing it
*/
typedef double T;     // T is integer: eps=0
const int N=100000+5; const T inf=1e9, eps=1e-8;
T sqr(T x) { return x*x; }
// return p4 is in circumcircle of tri(p1,p2,p3)
bool in_cc(const Pt& p1, const Pt& p2, const Pt& p3,
    const Pt& p4){
  T u11=p1.x-p4.x; T u21=p2.x-p4.x; T u31=p3.x-p4.x;
  T u12=p1.y-p4.y; T u22=p2.y-p4.y; T u32=p3.y-p4.y;
  T u13=sqr(p1.x)-sqr(p4.x)+sqr(p1.y)-sqr(p4.y);
  T u23=sqr(p2.x)-sqr(p4.x)+sqr(p2.y)-sqr(p4.y);
  T u33=sqr(p3.x)-sqr(p4.x)+sqr(p3.y)-sqr(p4.y);
  T det=-u13*u22*u31+u12*u23*u31+u13*u21*u32
        -u11*u23*u32-u12*u21*u33+u11*u22*u33;
  return det > eps;
}
T side(const Pt& a, const Pt& b, const Pt& p)
{ return (b-a)^(p-a); }
typedef int SdRef; struct Tri; typedef Tri* TriRef;
struct Edge {
  TriRef tri; SdRef side;
  Edge():tri(0), side(0){}
  Edge(TriRef _tri, SdRef _side):tri(_tri), side(_side)
      {}
};
struct Tri {
  Pt p[3]; Edge edge[3]; TriRef chd[3];
  Tri() {}
  Tri(const Pt& p0, const Pt& p1, const Pt& p2) {
    p[0]=p0; p[1]=p1; p[2]=p2; chd[0]=chd[1]=chd[2]=0;
  }
  bool has_chd() const { return chd[0]!=0; }
  int num_chd() const {
    return chd[0]==0?0:(chd[1]==0?1:chd[2]==0?2:3);
  }
  bool contains(Pt const& q) const {
    for(int i=0;i<3;i++)
      if(side(p[i],p[(i+1)%3],q)<-eps) return false;
    return true;
  }
} pool[N*10], *tris;
void edge(Edge a, Edge b){
  if(a.tri) a.tri->edge[a.side]=b;
  if(b.tri) b.tri->edge[b.side]=a;
}
struct Trig { // Triangulation
  void init(){ // Tri should at least contain all points
    the_root=new(tris++)Tri(Pt(-inf,-inf),Pt(+inf+inf,-
        inf),Pt(-inf,+inf+inf));
  }
  TriRef find(Pt p)const{ return find(the_root,p); }
  void add_point(const Pt& p)
  { add_point(find(the_root,p),p); }
  TriRef the_root;
  static TriRef find(TriRef root, const Pt& p) {
    while(true){
      if(!root->has_chd()) return root;
      for(int i=0;i<3&&root->chd[i];++i)
        if (root->chd[i]->contains(p)) {
          root=root->chd[i]; break;
        }
    }
    assert(false); // "point not found"
  }
  void add_point(TriRef root, Pt const& p) {
    TriRef tab,tbc,tca; // split it into three triangles
    tab=new(tris++) Tri(root->p[0],root->p[1],p);
    tbc=new(tris++) Tri(root->p[1],root->p[2],p);
    tca=new(tris++) Tri(root->p[2],root->p[0],p);
    edge(Edge(tab,0), Edge(tbc,1));
    edge(Edge(tbc,0), Edge(tca,1));
    edge(Edge(tca,0), Edge(tab,1));
    edge(Edge(tab,2), root->edge[2]);
    edge(Edge(tbc,2), root->edge[0]);
    edge(Edge(tca,2), root->edge[1]);
    root->chd[0]=tab;root->chd[1]=tbc;root->chd[2]=tca;
    flip(tab,2); flip(tbc,2); flip(tca,2);
  }
  void flip(TriRef tri, SdRef pi) {
    TriRef trj=tri->edge[pi].tri; if (!trj) return;
    int pj=tri->edge[pi].side;
    if (!in_cc(tri->p[0],tri->p[1],tri->p[2],trj->p[pj])
        ) return;
    /* flip edge between tri,trj */
    TriRef trk=new(tris++) Tri(tri->p[(pi+1)%3],trj->p[
        pj],tri->p[pi]);
    TriRef trl=new(tris++) Tri(trj->p[(pj+1)%3],tri->p[
        pi],trj->p[pj]);
    edge(Edge(trk,0),Edge(trl,0));
    edge(Edge(trk,1),tri->edge[(pi+2)%3]);
    edge(Edge(trk,2),trj->edge[(pj+1)%3]);
    edge(Edge(trl,1),trj->edge[(pj+2)%3]);
    edge(Edge(trl,2),tri->edge[(pi+1)%3]);
    tri->chd[0]=trk; tri->chd[1]=trl; tri->chd[2]=0;
    trj->chd[0]=trk; trj->chd[1]=trl; trj->chd[2]=0;
    flip(trk,1); flip(trk,2); flip(trl,1); flip(trl,2);
  }
}tri; // the triangulation structure
vector<TriRef> triang; // vector of all triangle
set<TriRef> vst;
void go(TriRef now){ // store all tri into triang
  if(vst.find(now)!=vst.end()) return;
```

```
  vst.insert(now);
  if(!now->has_chd()){
    triang.push_back(now); return;
  }
  for(int i=0;i<now->num_chd();i++) go(now->chd[i]);
}
void build(int n,Pt* ps){ // build triangulation
  tris=pool; triang.clear(); vst.clear();
  random_shuffle(ps,ps+n); tri.init();
  for(int i=0;i<n;++i) tri.add_point(ps[i]);
  go(tri.the_root);
}
```

4.17 Min Enclosing Circle 0de93f

```
struct Mec{ // return pair of center and r
  static const int N=101010;
  int n; Pt p[ N ], cen; double r2;
  void init(int _n,Pt _p[]){
    n=_n; memcpy(p,_p,sizeof(Pt)*n);
  }
  double sqr(double a){ return a*a; }
  Pt center(Pt p0, Pt p1, Pt p2){
    Pt a=p1-p0,b=p2-p0;
    double c1=norm2(a)*0.5,c2=norm2(b)*0.5,d=a^b;
    double x=p0.x+(c1*b.y-c2*a.y)/d;
    double y=p0.y+(a.x*c2-b.x*c1)/d;
    return Pt(x,y);
  }
  pair<Pt,double> solve(){
    random_shuffle(p,p+n); r2=0;
    for (int i=0; i<n; i++){
      if (norm2(cen-p[i])<=r2) continue;
      cen=p[i]; r2=0;
      for (int j=0; j<i; j++){
        if (norm2(cen-p[j])<=r2) continue;
        cen=Pt((p[i].x+p[j].x)/2,(p[i].y+p[j].y)/2);
        r2=norm2(cen-p[j]);
        for (int k=0; k<j; k++){
          if (norm2(cen-p[k])<=r2) continue;
          cen=center(p[i],p[j],p[k]);r2=norm2(cen-p[k]);
    } } }
    return {cen,sqrt(r2)};
  }
}mec;
```

4.18 Min Enclosing Ball 64186c

```
// Pt:{x,y,z}
#define N 202020
int n,nouter; Pt pt[N],outer[4],res; double radius,tmp;
double det(double m[3][3]){
  return m[0][0]*m[1][1]*m[2][2]+m[0][1]*m[1][2]*m[2][0]
    +m[0][2]*m[2][1]*m[1][0]-m[0][2]*m[1][1]*m[2][0]
    -m[0][1]*m[1][0]*m[2][2]-m[0][0]*m[1][2]*m[2][1];
}
void ball(){
  Pt q[3]; double m[3][3],sol[3],L[3],d;
  int i,j; res.x=res.y=res.z=radius=0;
  switch(nouter){
    case 1: res=outer[0]; break;
    case 2:
      res=(outer[0]+outer[1])/2;
      radius=norm2(res,outer[0]); break;
    case 3:
      for(i=0;i<2;++i) q[i]=outer[i+1]-outer[0];
      for(i=0;i<2;++i)
        for(j=0;j<2;++j) m[i][j]=(q[i]*q[j])*2;
      for(i=0;i<2;++i) sol[i]=(q[i]*q[i]);
      if(fabs(d=m[0][0]*m[1][1]-m[0][1]*m[1][0])<eps)
        return;
      L[0]=(sol[0]*m[1][1]-sol[1]*m[0][1])/d;
      L[1]=(sol[1]*m[0][0]-sol[0]*m[1][0])/d;
      res=outer[0]+q[0]*L[0]+q[1]*L[1];
      radius=norm2(res,outer[0]); break;
    case 4:
      for(i=0;i<3;++i)
        q[i]=outer[i+1]-outer[0],sol[i]=(q[i]*q[i]);
      for(i=0;i<3;++i)
        for(j=0;j<3;++j) m[i][j]=(q[i]*q[j])*2;
      d=det(m); if(fabs(d)<eps) return;
      for(j=0;j<3;++j){
        for(i=0;i<3;++i) m[i][j]=sol[i];
        L[j]=det(m)/d;
        for(i=0;i<3;++i) m[i][j]=(q[i]*q[j])*2;
      }
      res=outer[0]; for(i=0;i<3;++i) res=res+q[i]*L[i];
      radius=norm2(res,outer[0]);
  }
}
void minball(int n){
  ball();
  if(nouter<4) for(int i=0;i<n;i++)
    if(norm2(res,pt[i])-radius>eps){
      outer[nouter++]=pt[i]; minball(i); --nouter;
      if(i>0){ Pt Tt=pt[i];
        memmove(&pt[1],&pt[0],sizeof(Pt)*i); pt[0]=Tt;
} } }
double solve(){ // n points in pt
  random_shuffle(pt,pt+n); radius=-1;
  for(int i=0;i<n;i++) if(norm2(res,pt[i])-radius>eps)
    nouter=1,outer[0]=pt[i],minball(i);
  return sqrt(radius);
}
```

4.19 Minkowski sum 3ce748

```
vector<Pt> minkowski(vector<Pt> p, vector<Pt> q){
  int n=p.size(),m=q.size(); Pt c=Pt(0,0);
  for(int i=0;i<m;i++) c=c+q[i];
  c=c/m; int cur=-1;
  for(int i=0;i<m;i++) q[i]=q[i]-c;
  for(int i=0;i<m;i++) if((q[i]^(p[0]-p[n-1]))>-eps)
      if(cur==-1||(q[i]^(p[0]-p[n-1]))>
          (q[cur]^(p[0]-p[n-1]))) cur=i;
  vector<Pt> h; p.push_back(p[0]);
  for(int i=0;i<n;i++)
    while(true){
      h.push_back(p[i]+q[cur]);
      int nxt=(cur+1==m ? 0:cur+1);
      if((q[cur]^(p[i+1]-p[i]))<-eps) cur=nxt;
      else if((q[nxt]^(p[i+1]-p[i]))>
                (q[cur]^(p[i+1]-p[i]))) cur=nxt;
      else break;
    }
  for(auto &&i:h) i=i+c;
  return convex_hull(h);
}
```

4.20 Min dist on Cuboid 95b46d

```
typedef ll T; T r;
void turn(T i,T j,T x,T y,T z,T x0,T y0,T L,T W,T H){
  if (z==0){ T R=x*x+y*y; if (R<r) r=R; return; }
  if(i>=0&&i<2)
    turn(i+1,j,x0+L+z,y,x0+L-x,x0+L,y0,H,W,L);
  if(j>=0&&j<2)
    turn(i,j+1,x,y0+W+z,y0+W-y,x0,y0+W,L,H,W);
  if(i<=0&&i>-2) turn(i-1,j,x0-z,y,x-x0,x0-H,y0,H,W,L);
  if(j<=0&&j>-2) turn(i,j-1,x,y0-z,y-y0,x0,y0-H,L,H,W);
}
T solve(T L,T W,T H,T x1,T y1,T z1,T x2,T y2,T z2){
  if(z1!=0&&z1!=H){
    if(y1==0||y1==W) swap(y1,z1),swap(y2,z2),swap(W,H);
    else swap(x1,z1),swap(x2,z2),swap(L,H);
  }
  if (z1==H) z1=0,z2=H-z2;
  r=INF; turn(0,0,x2-x1,y2-y1,z2,-x1,-y1,L,W,H);
  return r;
}
```

4.21 Heart of Triangle 4da867

```
Pt inCenter(Pt &A,Pt &B,Pt &C) { // 內心
  double a=norm(B-C),b=norm(C-A),c=norm(A-B);
  return (A*a+B*b+C*c)/(a+b+c);
}
Pt circumCenter(Pt &a,Pt &b,Pt &c) { // 外心
  Pt bb=b-a,cc=c-a;
  double db=norm2(bb),dc=norm2(cc),d=2*(bb^cc);
  return a-Pt(bb.Y*dc-cc.Y*db,cc.X*db-bb.X*dc)/d;
}
Pt othroCenter(Pt &a,Pt &b,Pt &c) { // 垂心
  Pt ba=b-a,ca=c-a,bc=b-c;
```

```
  double Y=ba.Y*ca.Y*bc.Y,A=ca.X*ba.Y-ba.X*ca.Y,
    x0=(Y+ca.X*ba.Y*b.X-ba.X*ca.Y*c.X)/A,
    y0=-ba.X*(x0-c.X)/ba.Y+ca.Y;
  return Pt(x0, y0);
}
```

5 Graph

5.1 DominatorTree c642b6

```
const int MAXN=100010;
struct DominatorTree{
#define REP(i,s,e) for(int i=(s);i<=(e);i++)
#define REPD(i,s,e) for(int i=(s);i>=(e);i--)
  int n,m,s; vector<int> g[MAXN],pred[MAXN],cov[MAXN];
  int dfn[MAXN],nfd[MAXN],ts,par[MAXN];
  int sdom[MAXN],idom[MAXN],mom[MAXN],mn[MAXN];
  inline bool cmp(int u,int v){ return dfn[u] <dfn[v]; }
  int eval(int u){
    if(mom[u]==u) return u;
    int res=eval(mom[u]);
    if(cmp(sdom[mn[mom[u]]],sdom[mn[u]]))
      mn[u]=mn[mom[u]];
    return mom[u]=res;
  }
  void init(int _n,int _m,int _s){
    ts=0; n=_n; m=_m; s=_s;
    REP(i,1,n) g[i].clear(),pred[i].clear();
  }
  void addEdge(int u,int v){
    g[u].push_back(v); pred[v].push_back(u);
  }
  void dfs(int u){
    ts++; dfn[u]=ts; nfd[ts]=u;
    for(int v:g[u]) if(dfn[v]==0){ par[v]=u; dfs(v); }
  }
  void build(){
    REP(i,1,n){
      dfn[i]=nfd[i]=0; cov[i].clear();
      mom[i]=mn[i]=sdom[i]=i;
    }
    dfs(s);
    REPD(i,n,2){
      int u=nfd[i];
      if(u==0) continue;
      for(int v:pred[u]) if(dfn[v]){
        eval(v);
        if(cmp(sdom[mn[v]],sdom[u]))sdom[u]=sdom[mn[v]];
      }
      cov[sdom[u]].push_back(u); mom[u]=par[u];
      for(int w:cov[par[u]]){
        eval(w);
        if(cmp(sdom[mn[w]],par[u])) idom[w]=mn[w];
        else idom[w]=par[u];
      }
      cov[par[u]].clear();
    }
    REP(i,2,n){
      int u=nfd[i];
      if(u==0) continue;
      if(idom[u]!=sdom[u]) idom[u]=idom[idom[u]];
    }
  }
} domT;
```

5.2 Directed MST(ElogE) 4b46a2

```
struct RollbackUF {
  vi e; vector<pii> st;
  RollbackUF(int n):e(n,-1) {}
  int size(int x) { return -e[find(x)]; }
  int find(int x) { return e[x]<0?x:find(e[x]); }
  int time() { return st.size(); }
  void rollback(int t) {
    for(int i=time();i-->t;)e[st[i].first]=st[i].second;
    st.resize(t);
  }
  bool join(int a,int b) {
    a=find(a),b=find(b);
    if(a==b) return false;
    if(e[a]>e[b]) swap(a,b);
    st.push_back({a,e[a]}); st.push_back({b,e[b]});
    e[a]+=e[b]; e[b]=a;
    return true;
  }
};
struct Edge {int a,b; ll w;};
struct Node { // lazy skew heap node
  Edge key; Node *l,*r; ll d;
  void prop() {
    key.w+=d; if(l) l->d+=d; if(r) r->d+=d; d=0;
  }
  Edge top() { prop(); return key; }
};
Node *merge(Node *a,Node *b) {
  if(!a||!b) return a?a:b;
  a->prop();b->prop();
  if(a->key.w>b->key.w) swap(a,b);
  swap(a->l,(a->r=merge(b,a->r)));
  return a;
}
void pop(Node*& a){ a->prop(); a=merge(a->l,a->r); }
pair<ll,vi> dmst(int n,int r,vector<Edge>& g){
  RollbackUF uf(n); vector<Node*> pq(n);
  for(Edge e:g) pq[e.b]=merge(pq[e.b],new Node{e});
  ll res=0; vi seen(n,-1),path(n),par(n); seen[r]=r;
  vector<Edge> Q(n),in(n,{-1,-1});
  deque<tuple<int,int,vector<Edge>>> cycs;
  for(int s=0;s<n;s++){
    int u=s,qi=0,w;
    while(seen[u]<0){
      if(!pq[u]) return {-1,{}};
      Edge e=pq[u]->top(); pq[u]->d-=e.w,pop(pq[u]);
      Q[qi]=e,path[qi++]=u,seen[u]=s;
      res+=e.w,u=uf.find(e.a);
      if(seen[u]==s) { // found cycle,contract
        Node* cyc=0; int end=qi,t=uf.time();
        do cyc=merge(cyc,pq[w=path[--qi]]);
        while(uf.join(u,w));
        u=uf.find(u),pq[u]=cyc,seen[u]=-1;
        cycs.push_front({u,t,{&Q[qi],&Q[end]}});
      }
    }
    for(int i=0;i<qi;i++) in[uf.find(Q[i].b)]=Q[i];
  }
  for(auto& [u,t,comp]:cycs) { // restore sol
    uf.rollback(t); Edge inEdge=in[u];
    for(auto& e:comp) in[uf.find(e.b)]=e;
    in[uf.find(inEdge.b)]=inEdge;
  }
  for(int i=0;i<n;i++) par[i]=in[i].a;
  return {res,par};
}
```

5.3 MaximalClique 9f3d6c

```
#define N 80
struct MaxClique{ // 0-base
  typedef bitset<N> Int;
  Int lnk[N],v[N]; int n;
  void init(int _n){
    n=_n;
    for(int i=0;i<n;i++){
      lnk[i].reset(); v[i].reset();
    }
  }
  void addEdge(int a,int b) { v[a][b]=v[b][a]=1; }
  int ans,stk[N],id[N],di[N],deg[N]; Int cans;
  void dfs(int elem_num,Int candi,Int ex){
    if(candi.none()&&ex.none()){
      cans.reset();
      for(int i=0;i<elem_num;i++) cans[id[stk[i]]]=1;
      ans=max(ans,elem_num); // cans is a maximal clique
      return;
    }
    int pivot=(candi|ex)._Find_first();
    Int smaller_candi=candi&(~lnk[pivot]);
    while(smaller_candi.count()){
      int nxt=smaller_candi._Find_first();
      candi[nxt]=smaller_candi[nxt]=0;
      ex[nxt]=1; stk[elem_num]=nxt;
      dfs(elem_num+1,candi&lnk[nxt],ex&lnk[nxt]);
    }
  }
```

```
  int solve(){
    for(int i=0;i<n;i++){id[i]=i; deg[i]=v[i].count();}
    sort(id,id+n,[&](int id1,int id2)
        { return deg[id1]>deg[id2]; });
    for(int i=0;i<n;i++) di[id[i]]=i;
    for(int i=0;i<n;i++) for(int j=0;j<n;j++)
        if(v[i][j]) lnk[di[i]][di[j]]=1;
    ans=0; cans.reset(); cans[0]=1;
    dfs(0,Int(string(n,'1')),0);
    return ans;
  }
} solver;
```

5.4 MaxCliqueDyn e0119d

```
#define N 150
struct MaxClique{ // Maximum Clique
  bitset<N> a[N],cs[N]; int ans,sol[N],q,cur[N],d[N],n;
  void init(int _n){
    n=_n; for(int i=0;i<n;i++) a[i].reset();
  }
  void addEdge(int u,int v){ a[u][v]=a[v][u]=1; }
  void csort(vector<int> &r,vector<int> &c){
    int mx=1,km=max(ans-q+1,1),t=0,m=r.size();
    cs[1].reset(); cs[2].reset();
    for(int i=0;i<m;i++){
      int p=r[i],k=1;
      while((cs[k]&a[p]).count()) k++;
      if(k>mx){ mx++; cs[mx+1].reset(); }
      cs[k][p]=1; if(k<km) r[t++]=p;
    }
    c.resize(m); if(t) c[t-1]=0;
    for(int k=km;k<=mx;k++){
      for(int p=cs[k]._Find_first();p<N;p=cs[k].
          _Find_next(p)){
        r[t]=p; c[t]=k; t++;
  } } }
  void dfs(vector<int> &r,vector<int> &c,int l,bitset<N>
       mask){
    while(!r.empty()){
      int p=r.back(); r.pop_back(); mask[p]=0;
      if(q+c.back()<=ans) return;
      cur[q++]=p;
      vector<int> nr,nc; bitset<N> nmask=mask&a[p];
      for(int i:r) if(a[p][i]) nr.push_back(i);
      if(!nr.empty()){
        if(l<4){
          for(int i:nr) d[i]=(a[i]&nmask).count();
          sort(nr.begin(),nr.end(),
              [&](int x,int y){return d[x]>d[y];});
        }
        csort(nr,nc); dfs(nr,nc,l+1,nmask);
      }
      else if(q>ans){ ans=q; copy(cur,cur+q,sol); }
      c.pop_back(); q--;
    }
  }                  // vertex mask
  int solve(bitset<N> mask=bitset<N>(string(N,'1'))){
    vector<int> r,c; ans=q=0;
    for(int i=0;i<n;i++) if(mask[i]) r.push_back(i);
    for(int i=0;i<n;i++) d[i]=(a[i]&mask).count();
    sort(r.begin(),r.end(),
        [&](int i,int j){return d[i]>d[j];});
    csort(r,c); dfs(r,c,1,mask);
    return ans; // vertices set: sol[0 ~ ans-1]
  }
}graph;
```

5.5 Strongly Connected Component 10c233

```
void dfs(int i){
  V[i]=low[i]=++ts,stk[top++]=i,instk[i]=1;
  for(auto x:E[i]){
    if(!V[x])dfs(x),low[i]=min(low[i],low[x]);
    else if(instk[x])low[i]=min(low[i],V[x]);
  }
  if(V[i]==low[i]){
    int j;
    do{j=stk[--top],instk[j]=0,scc[j]=i;
    }while(j!=i);
  }
}
```

5.6 Dynamic MST 21e59f

```
/* Dynamic MST O( Q lg^2 Q )
 n nodes, m edges, Q query
 (u[i], v[i], w[i])->edge
 (qid[i], qw[i])->chg weight of edge No.qid[i] to qw[i]
 delete an edge: (i, \infty)
 add an edge: change from \infty to specific value */
const int M=1e5,MXQ=1e5,SZ=M+3*MXQ; int a[N],*tz;
int find(int x){ return x==a[x]?x:a[x]=find(a[x]); }
bool cmp(int aa,int bb){ return tz[aa]<tz[bb]; }
int kx[N],ky[N],kt,vd[N],id[M],app[M],cur;
long long answer[MXQ]; // answer after ith query
bool extra[M];
void solve(int *qx,int *qy,int Q,int n,int *x,int *y,int
     *z,int m1,long long ans){
  if(Q==1){
    for(int i=1;i<=n;i++) a[i]=0;
    z[qx[0]]=qy[0]; tz=z;
    for(int i=0;i<m1;i++) id[i]=i;
    sort(id,id+m1,cmp); int ri,rj;
    for(int i=0;i<m1;i++){
      ri=find(x[id[i]]); rj=find(y[id[i]]);
      if(ri!=rj){ ans+=z[id[i]]; a[ri]=rj; }
    }
    answer[cur++]=ans; return;
  }
  int ri,rj,tm=0,n2=0; kt=0;
  //contract
  for(int i=1;i<=n;i++) a[i]=0;
  for(int i=0;i<Q;i++){
    ri=find(x[qx[i]]); rj=find(y[qx[i]]);
    if(ri!=rj) a[ri]=rj;
  }
  for(int i=0;i<m1;i++) extra[i]=true;
  for(int i=0;i<Q;i++) extra[qx[i]]=false;
  for(int i=0;i<m1;i++) if(extra[i]) id[tm++]=i;
  tz=z; sort(id,id+tm,cmp);
  for(int i=0;i<tm;i++){
    ri=find(x[id[i]]); rj=find(y[id[i]]);
    if(ri!=rj){
      a[ri]=rj; ans+=z[id[i]];
      kx[kt]=x[id[i]]; ky[kt]=y[id[i]]; kt++;
    }
  }
  for(int i=1;i<=n;i++) a[i]=0;
  for(int i=0;i<kt;i++) a[find(kx[i])]=find(ky[i]);
  for(int i=1;i<=n;i++) if(a[i]==0) vd[i]=++n2;
  for(int i=1;i<=n;i++) if(a[i]) vd[i]=vd[find(i)];
  int m2=0,*Nx=x+m1,*Ny=y+m1,*Nz=z+m1;
  for(int i=0;i<m1;i++) app[i]=-1;
  for(int i=0;i<Q;i++) if(app[qx[i]]==-1){
    Nx[m2]=vd[x[qx[i]]]; Ny[m2]=vd[y[qx[i]]];
    Nz[m2]=z[qx[i]]; app[qx[i]]=m2; m2++;
  }
  for(int i=0;i<Q;i++){z[qx[i]]=qy[i];qx[i]=app[qx[i]];}
  for(int i=1;i<=n2;i++) a[i]=0;
  for(int i=0;i<tm;i++){
    ri=find(vd[x[id[i]]]); rj=find(vd[y[id[i]]]);
    if(ri!=rj){
      a[ri]=rj; Nx[m2]=vd[x[id[i]]];
      Ny[m2]=vd[y[id[i]]]; Nz[m2]=z[id[i]]; m2++;
    }
  }
  int mid=Q/2;
  solve(qx,qy,mid,n2,Nx,Ny,Nz,m2,ans);
  solve(qx+mid,qy+mid,Q-mid,n2,Nx,Ny,Nz,m2,ans);
} // fill these variables and call work()
int u[SZ],v[SZ],w[SZ],qid[MXQ],qw[MXQ],n,m,Q;
void work(){if(Q) cur=0,solve(qid,qw,Q,n,u,v,w,m,0);}
```

5.7 Maximum General graph Matching a15e63

```
// should shuffle vertices and edges
const int N=100005,E=(2e5)*2+40;
struct Graph{
  int to[E],bro[E],head[N],e,lnk[N],vis[N],stp,n;
  void init(int _n){
    stp=0; e=1; n=_n;
    for(int i=1;i<=n;i++) head[i]=lnk[i]=vis[i]=0;
  }
  void add_edge(int u,int v){
```

```
    to[e]=v,bro[e]=head[u],head[u]=e++;
    to[e]=u,bro[e]=head[v],head[v]=e++;
  }
  bool dfs(int x){
    vis[x]=stp;
    for(int i=head[x];i;i=bro[i]){
      int v=to[i];
      if(!lnk[v]){ lnk[x]=v,lnk[v]=x; return true; }
    }
    for(int i=head[x];i;i=bro[i]){
      int v=to[i];
      if(vis[lnk[v]]<stp){
        int w=lnk[v]; lnk[x]=v,lnk[v]=x,lnk[w]=0;
        if(dfs(w)) return true;
        lnk[w]=v,lnk[v]=w,lnk[x]=0;
      }
    }
    return false;
  }
  int solve(){
    int ans=0;
    for(int i=1;i<=n;i++) if(!lnk[i]) stp++,ans+=dfs(i);
    return ans;
  }
}graph;
```

5.8 Minimum General Weighted Matching 91b293

```
struct Graph {
  // Minimum General Weighted Matching (Perfect Match)
  static const int MXN=105;
  int n,edge[MXN][MXN],match[MXN],dis[MXN],onstk[MXN];
  vector<int> stk;
  void init(int _n) {
    n=_n;
    for(int i=0;i<n;i++)
      for(int j=0;j<n;j++) edge[i][j]=0;
  }
  void add_edge(int u,int v,int w)
  { edge[u][v]=edge[v][u]=w; }
  bool SPFA(int u){
    if(onstk[u]) return true;
    stk.push_back(u); onstk[u]=1;
    for(int v=0;v<n;v++){
      if(u!=v&&match[u]!=v&&!onstk[v]){
        int m=match[v];
        if(dis[m]>dis[u]-edge[v][m]+edge[u][v]){
          dis[m]=dis[u]-edge[v][m]+edge[u][v];
          onstk[v]=1; stk.push_back(v);
          if(SPFA(m)) return true;
          stk.pop_back(); onstk[v]=0;
    } } }
    onstk[u]=0; stk.pop_back();
    return false;
  }
  int solve() { // find a match
    for(int i=0;i<n;i+=2){ match[i]=i+1;match[i+1]=i; }
    while(true){
      int found=0;
      for(int i=0;i<n;i++) onstk[i]=dis[i]=0;
      for(int i=0;i<n;i++){
        stk.clear();
        if(!onstk[i]&&SPFA(i)){
          found=1;
          while((int)stk.size()>=2){
            int u=stk.back();stk.pop_back();
            int v=stk.back();stk.pop_back();
            match[u]=v;match[v]=u;
      } } }
      if(!found) break;
    }
    int ret=0;
    for(int i=0;i<n;i++) ret+=edge[i][match[i]];
    return ret/2;
  }
}graph;
```

5.9 Maximum General Weighted Matching 0baee5

```
struct WeightGraph {
  static const int INF=INT_MAX,N=514;
  struct edge{
    int u,v,w; edge(){}
    edge(int ui,int vi,int wi):u(ui),v(vi),w(wi){}
  };
  int n,n_x,lab[N*2],match[N*2],slack[N*2],st[N*2];
  int pa[N*2],flo_from[N*2][N+1],S[N*2],vis[N*2];
  edge g[N*2][N*2]; vector<int> flo[N*2]; queue<int> q;
  int e_delta(const edge &e){
    return lab[e.u]+lab[e.v]-g[e.u][e.v].w*2;
  }
  void update_slack(int u,int x){
    if(!slack[x]||e_delta(g[u][x])<
        e_delta(g[slack[x]][x])) slack[x]=u;
  }
  void set_slack(int x){
    slack[x]=0;
    for(int u=1;u<=n;++u)
      if(g[u][x].w>0&&st[u]!=x&&S[st[u]]==0)
        update_slack(u,x);
  }
  void q_push(int x){
    if(x<=n) q.push(x);
    else for(size_t i=0;i<flo[x].size();i++)
        q_push(flo[x][i]);
  }
  void set_st(int x,int b){
    st[x]=b;
    if(x>n) for(size_t i=0;i<flo[x].size();++i)
        set_st(flo[x][i],b);
  }
  int get_pr(int b,int xr){
    int pr=find(flo[b].begin(),flo[b].end(),xr)-flo[b].
        begin();
    if(pr%2==1){
      reverse(flo[b].begin()+1,flo[b].end());
      return (int)flo[b].size()-pr;
    }else return pr;
  }
  void set_match(int u,int v){
    match[u]=g[u][v].v; if(u<=n) return; edge e=g[u][v];
    int xr=flo_from[u][e.u],pr=get_pr(u,xr);
    for(int i=0;i<pr;++i)
      set_match(flo[u][i],flo[u][i^1]);
    set_match(xr,v); rotate(flo[u].begin(),flo[u].begin
        ()+pr,flo[u].end());
  }
  void augment(int u,int v){
    for(;;){
      int xnv=st[match[u]]; set_match(u,v);
      if(!xnv) return;
      set_match(xnv,st[pa[xnv]]); u=st[pa[xnv]],v=xnv;
    }
  }
  int get_lca(int u,int v){
    static int t=0;
    for(++t;u||v;swap(u,v)){
      if(u==0) continue; if(vis[u]==t) return u;
      vis[u]=t; u=st[match[u]]; if(u) u=st[pa[u]];
    }
    return 0;
  }
  void add_blossom(int u,int lca,int v){
    int b=n+1; while(b<=n_x&&st[b])++b; if(b>n_x)++n_x;
    lab[b]=0,S[b]=0; match[b]=match[lca];
    flo[b].clear(); flo[b].push_back(lca);
    for(int x=u,y;x!=lca;x=st[pa[y]])
      flo[b].push_back(x),
        flo[b].push_back(y=st[match[x]]),q_push(y);
    reverse(flo[b].begin()+1,flo[b].end());
    for(int x=v,y;x!=lca;x=st[pa[y]])
      flo[b].push_back(x),
        flo[b].push_back(y=st[match[x]]),q_push(y);
    set_st(b,b);
    for(int x=1;x<=n_x;++x) g[b][x].w=g[x][b].w=0;
    for(int x=1;x<=n;++x) flo_from[b][x]=0;
    for(size_t i=0;i<flo[b].size();++i){
      int xs=flo[b][i];
      for(int x=1;x<=n_x;++x)
        if(g[b][x].w==0||e_delta(g[xs][x])<e_delta(
            g[b][x])) g[b][x]=g[xs][x],g[x][b]=g[x][xs];
```

```
    for(int x=1;x<=n;++x)
      if(flo_from[xs][x])flo_from[b][x]=xs;
  }
  set_slack(b);
}
void expand_blossom(int b){
  for(size_t i=0;i<flo[b].size();++i)
    set_st(flo[b][i],flo[b][i]);
  int xr=flo_from[b][g[b][pa[b]].u],pr=get_pr(b,xr);
  for(int i=0;i<pr;i+=2){
    int xs=flo[b][i],xns=flo[b][i+1];
    pa[xs]=g[xns][xs].u; S[xs]=1,S[xns]=0;
    slack[xs]=0,set_slack(xns); q_push(xns);
  }
  S[xr]=1,pa[xr]=pa[b];
  for(size_t i=pr+1;i<flo[b].size();++i){
    int xs=flo[b][i]; S[xs]=-1,set_slack(xs);
  }
  st[b]=0;
}
bool on_found_edge(const edge &e){
  int u=st[e.u],v=st[e.v];
  if(S[v]==-1){
    pa[v]=e.u,S[v]=1; int nu=st[match[v]];
    slack[v]=slack[nu]=0; S[nu]=0,q_push(nu);
  }else if(S[v]==0){
    int lca=get_lca(u,v);
    if(!lca) return augment(u,v),augment(v,u),true;
    else add_blossom(u,lca,v);
  }
  return false;
}
bool matching(){
  memset(S+1,-1,sizeof(int)*n_x);
  memset(slack+1,0,sizeof(int)*n_x); q=queue<int>();
  for(int x=1;x<=n_x;++x)
    if(st[x]==x&&!match[x])pa[x]=0,S[x]=0,q_push(x);
  if(q.empty()) return false;
  for(;;){ while(q.size()){
      int u=q.front();q.pop();if(S[st[u]]==1)continue;
      for(int v=1;v<=n;++v)
        if(g[u][v].w>0&&st[u]!=st[v]){
          if(e_delta(g[u][v])==0){
            if(on_found_edge(g[u][v])) return true;
          }else update_slack(u,st[v]);
        }
    }
    int d=INF;
    for(int b=n+1;b<=n_x;++b)
      if(st[b]==b&&S[b]==1) d=min(d,lab[b]/2);
    for(int x=1;x<=n_x;++x) if(st[x]==x&&slack[x]){
        if(S[x]==-1) d=min(d,e_delta(g[slack[x]][x]));
        else if(S[x]==0)
          d=min(d,e_delta(g[slack[x]][x])/2);
      }
    for(int u=1;u<=n;++u){ if(S[st[u]]==0){
        if(lab[u]<=d) return 0; lab[u]-=d;
      }else if(S[st[u]]==1) lab[u]+=d;
    }
    for(int b=n+1;b<=n_x;++b) if(st[b]==b){
        if(S[st[b]]==0) lab[b]+=d*2;
        else if(S[st[b]]==1) lab[b]-=d*2;
      }
    q=queue<int>();
    for(int x=1;x<=n_x;++x)
      if(st[x]==x&&slack[x]&&st[slack[x]]!=x&&e_delta(
          g[slack[x]][x])==0)
        if(on_found_edge(g[slack[x]][x])) return true;
    for(int b=n+1;b<=n_x;++b) if(st[b]==b&&S[b]==1&&
        lab[b]==0) expand_blossom(b);
  }
  return false;
}
pair<long long,int> solve(){
  memset(match+1,0,sizeof(int)*n); n_x=n;
  int n_matches=0,w_max=0; long long tot_weight=0;
  for(int u=0;u<=n;++u) st[u]=u,flo[u].clear();
  for(int u=1;u<=n;++u) for(int v=1;v<=n;++v){
      flo_from[u][v]=(u==v?u:0);
      w_max=max(w_max,g[u][v].w);
    }
  for(int u=1;u<=n;++u) lab[u]=w_max;
  while(matching()) ++n_matches;
  for(int u=1;u<=n;++u) if(match[u]&&match[u]<u)
      tot_weight+=g[u][match[u]].w;
  return make_pair(tot_weight,n_matches);
}
void add_edge(int ui,int vi,int wi)
{ g[ui][vi].w=g[vi][ui].w=wi; }
void init(int _n){
  n=_n;
  for(int u=1;u<=n;++u) for(int v=1;v<=n;++v)
      g[u][v]=edge(u,v,0);
}
}graph;
```

5.10 Minimum Steiner Tree 837386

```
// Minimum Steiner Tree O(V 3^T+V^2 2^T)
// shortest_path() should be called before solve()
// w:vertex weight, default 0
const int V=66,T=10; const ll INF=1023456789;
struct SteinerTree{
  int n,dst[V][V],dp[1<<T][V],tdst[V],w[V];
  void init(int _n){
    n=_n; fill(w,w+n,0);
    for(int i=0;i<n;i++){
      for(int j=0;j<n;j++) dst[i][j]=INF;
      dst[i][i]=0;
    }
  }
  void add_edge(int ui,int vi,int wi){
    dst[ui][vi]=min(dst[ui][vi],wi);
    dst[vi][ui]=min(dst[vi][ui],wi);
  }
  void shortest_path(){
    for(int i=0;i<n;i++) for(int j=0;j<n;j++)
        if(i!=j&&dst[i][j]!=INF) dst[i][j]+=w[i];
    for(int k=0;k<n;k++) for(int i=0;i<n;i++)
        for(int j=0;j<n;j++)
          dst[i][j]=min(dst[i][j],dst[i][k]+dst[k][j]);
    for(int i=0;i<n;i++) for(int j=0;j<n;j++)
        if(dst[i][j]!=INF) dst[i][j]+=w[j];
  }
  int solve(const vector<int>& ter){
    int t=(int)ter.size();
    for(int i=0;i<(1<<t);i++)
      for(int j=0;j<n;j++) dp[i][j]=INF;
    for(int i=0;i<n;i++) dp[0][i]=0;
    for(int msk=1;msk<(1<<t);msk ++){
      if(msk==(msk&(-msk))){
        int who=__lg(msk);
        for(int i=0;i<n;i++)dp[msk][i]=dst[ter[who]][i];
        continue;
      }
      for(int i=0;i<n;i++)
        for(int submsk=(msk-1)&msk;submsk;submsk=(submsk
            -1)&msk)
          dp[msk][i]=min(dp[msk][i],dp[submsk][i]+dp[msk
              ^submsk][i]-w[i]);
      for(int i=0;i<n;i++){
        tdst[i]=INF;
        for(int j=0;j<n;j++) tdst[i]=
          min(tdst[i],dp[msk][j]+dst[j][i]-w[j]);
      }
      for(int i=0;i<n;i++) dp[msk][i]=tdst[i];
    }
    int ans=INF;
    for(int i=0;i<n;i++) ans=min(ans,dp[(1<<t)-1][i]);
    return ans;
  }
} solver;
```

5.11 BCC based on vertex 4ea1ac

```
struct BccVertex{
  int n,nBcc,step,dfn[MXN],low[MXN],top,stk[MXN];
  vector<int> E[MXN],bccv[MXN];
  // vector<pair<int,int>> bcce[MXN];
  // pair<int,int> estk[MXM];// max edge number
  // int etop,id[MXN],pos[MXN];
  void init(int _n){
    n=_n;nBcc=step=0; for(int i=0;i<n;i++) E[i].clear();
  }
```

```
  void addEdge(int u,int v)
  { E[u].push_back(v);E[v].push_back(u);}
  void DFS(int u,int f){
    dfn[u]=low[u]=step++; stk[top++]=u;
    for(auto v:E[u]){
      if(v == f) continue;
      if(dfn[v] == -1){
        // estk[etop++]={u,v};
        DFS(v,u); low[u]=min(low[u],low[v]);
        if(low[v]>=dfn[u]){
          int z;bccv[nBcc].clear();//bcce[nBcc].clear();
          // pair<int,int> ez;
          // do{
          //   ez=estk[--etop];bcce[nBcc].push_back(ez);
          // }while(ez.first!=u);
          do{
            z=stk[--top]; bccv[nBcc].push_back(z);
            // id[z]=nBcc;pos[z]=bccv[nBcc].size();
          }while(z!=v);
          bccv[nBcc++].push_back(u);
        }
      }else{
        low[u]=min(low[u],dfn[v]);
        // if(dfn[v]<dfn[u]) estk[etop++]={u,v};
  } } }
  vector<vector<int>> solve(){
    vector<vector<int>> res;
    for(int i=0;i<n;i++) dfn[i]=low[i]=-1;
    for(int i=0;i<n;i++) if(dfn[i] == -1){
        top=0; DFS(i,i); // etop=0;
      }
    for(int i=0;i<nBcc;i++) res.push_back(bccv[i]);
    return res;
  }
  /* bccv[.first][{.second.first,.second.second}]=={u,v}
  pair<int,pair<int,int>> getpos(int u,int v){
    if(dfn[u]>dfn[v]) swap(u,v);
    int cid=id[v];
    if(id[u]==cid) return{cid,{pos[v],pos[u]}};
    else return{cid,pos[v],{bccv[cid].size()-1}};
  } */
}graph;
```

5.12 Min Mean Cycle f5f8be

```
/* minimum mean cycle O(VE) */
const int E=101010,V=1021;
const double inf=1e9,eps=1e-8;
struct MMC{
  struct Edge{ int v,u; double c; };
  int n,m,prv[V][V],prve[V][V],vst[V]; Edge e[E];
  vector<int> edgeID,cycle,rho; double d[V][V];
  void init(int _n){ n=_n; m=0; }
  // WARNING: TYPE matters
  void addEdge(int vi,int ui,double ci)
  { e[m++]={vi,ui,ci}; }
  void bellman_ford(){
    for(int i=0;i<n;i++) d[0][i]=0;
    for(int i=0;i<n;i++){
      fill(d[i+1],d[i+1]+n,inf);
      for(int j=0;j<m;j++){
        int v=e[j].v,u=e[j].u;
        if(d[i][v]<inf&&d[i+1][u]>d[i][v]+e[j].c){
          d[i+1][u]=d[i][v]+e[j].c;
          prv[i+1][u]=v; prve[i+1][u]=j;
  } } } }
  double solve(){
    // returns inf if no cycle,mmc otherwise
    double mmc=inf; int st=-1; bellman_ford();
    for(int i=0;i<n;i++){
      double avg=-inf;
      for(int k=0;k<n;k++){
        if(d[n][i]<inf-eps)
          avg=max(avg,(d[n][i]-d[k][i])/(n-k));
        else avg=max(avg,inf);
      }
      if(avg<mmc) tie(mmc,st)=tie(avg,i);
    }
    if(st==-1) return inf;
    FZ(vst); edgeID.clear(); cycle.clear(); rho.clear();
    for(int i=n;!vst[st];st=prv[i--][st]){
      vst[st]++; edgeID.push_back(prve[i][st]);
      rho.push_back(st);
    }
    while(vst[st]!=2){
      int v=rho.back(); rho.pop_back();
      cycle.push_back(v); vst[v]++;
    }
    reverse(ALL(edgeID));
    edgeID.resize((int)cycle.size());
    return mmc;
  }
}mmc;
```

5.13 Directed Graph Min Cost Cycle c448cd

```
const int N=5010,M=200010; const ll INF=(1ll<<55);
struct edge{
  int to; ll w;
  edge(int a=0,ll b=0):to(a),w(b){}
};
struct node{
  ll d; int u,next;
  node(ll a=0,int b=0,int c=0): d(a),u(b),next(c){}
}b[M];
struct DirectedGraphMinCycle{ // works in O(NM)
  vector<edge> g[N],grev[N]; ll dp[N][N],p[N],d[N],mu;
  bool inq[N]; int n,bn,bsz,hd[N];
  void b_insert(ll d,int u){
    int i=d/mu; if(i>=bn) return;
    b[++bsz]=node(d,u,hd[i]); hd[i]=bsz;
  }
  void init(int _n){
    n=_n; for(int i=1;i<=n;i++) g[i].clear();
  }
  void addEdge(int ai,int bi,ll ci)
  { g[ai].push_back(edge(bi,ci)); }
  ll solve(){
    fill(dp[0],dp[0]+n+1,0);
    for(int i=1;i<=n;i++){
      fill(dp[i]+1,dp[i]+n+1,INF);
      for(int j=1;j<=n;j++) if(dp[i-1][j]<INF){
        for(int k=0;k<(int)g[j].size();k++)
          dp[i][g[j][k].to]=min(dp[i][g[j][k].to],dp[i
              -1][j]+g[j][k].w);
      }
    }
    mu=INF; ll bunbo=1;
    for(int i=1;i<=n;i++) if(dp[n][i]<INF){
      ll a=-INF,b=1;
      for(int j=0;j<=n-1;j++) if(dp[j][i]<INF){
        if(a*(n-j)<b*(dp[n][i]-dp[j][i])){
          a=dp[n][i]-dp[j][i]; b=n-j;
        }
      }
      if(mu*b>bunbo*a) mu=a,bunbo=b;
    }
    if(mu<0) return -1; // negative cycle
    if(mu==INF) return INF; // no cycle
    if(mu==0) return 0;
    for(int i=1;i<=n;i++)
      for(int j=0;j<(int)g[i].size();j++)
        g[i][j].w*=bunbo;
    memset(p,0,sizeof(p)); queue<int> q;
    for(int i=1;i<=n;i++){ q.push(i); inq[i]=true; }
    while(!q.empty()){
      int i=q.front(); q.pop(); inq[i]=false;
      for(int j=0;j<(int)g[i].size();j++){
        if(p[g[i][j].to]>p[i]+g[i][j].w-mu){
          p[g[i][j].to]=p[i]+g[i][j].w-mu;
          if(!inq[g[i][j].to]){
            q.push(g[i][j].to); inq[g[i][j].to]=true;
    } } } }
    for(int i=1;i<=n;i++) grev[i].clear();
    for(int i=1;i<=n;i++)
      for(int j=0;j<(int)g[i].size();j++){
        g[i][j].w+=p[i]-p[g[i][j].to];
        grev[g[i][j].to].push_back(edge(i,g[i][j].w));
      }
    ll mldc=n*mu;
    for(int i=1;i<=n;i++){
      bn=mldc/mu,bsz=0; memset(hd,0,sizeof(hd));
      fill(d+i+1,d+n+1,INF); b_insert(d[i]=0,i);
      for(int j=0;j<=bn-1;j++)
```

```
        for(int k=hd[j];k;k=b[k].next){
          int u=b[k].u; ll du=b[k].d;
          if(du>d[u]) continue;
          for(int l=0;l<(int)g[u].size();l++)
            if(g[u][l].to>i){
              if(d[g[u][l].to]>du+g[u][l].w){
                d[g[u][l].to]=du+g[u][l].w;
                b_insert(d[g[u][l].to],g[u][l].to);
        }   } }
      for(int j=0;j<(int)grev[i].size();j++)
        if(grev[i][j].to>i)
          mldc=min(mldc,d[grev[i][j].to]+grev[i][j].w);
    }
    return mldc/bunbo;
  }
} graph;
```

5.14 K-th Shortest Path 355040

```
// time: O(|E| \lg |E|+|V| \lg |V|+K)
// memory: O(|E| \lg |E|+|V|)
struct KSP{ // 1-base
  struct nd{
    int u,v; ll d;
    nd(int ui=0,int vi=0,ll di=INF){ u=ui; v=vi; d=di; }
  };
  struct heap{ nd* edge; int dep; heap* chd[4]; };
  static int cmp(heap* a,heap* b)
  { return a->edge->d > b->edge->d; }
  struct node{
    int v; ll d; heap* H; nd* E;
    node(){}
    node(ll _d,int _v,nd* _E){ d =_d; v=_v; E=_E; }
    node(heap* _H,ll _d){ H=_H; d=_d; }
    friend bool operator<(node a,node b)
    { return a.d>b.d; }
  };
  int n,k,s,t,dst[N]; nd *nxt[N];
  vector<nd*> g[N],rg[N]; heap *nullNd,*head[N];
  void init(int _n,int _k,int _s,int _t){
    n=_n; k=_k; s=_s; t=_t;
    for(int i=1;i<=n;i++){
      g[i].clear(); rg[i].clear();
      nxt[i]=NULL; head[i]=NULL; dst[i]=-1;
    }
  }
  void addEdge(int ui,int vi,ll di){
    nd* e=new nd(ui,vi,di);
    g[ui].push_back(e); rg[vi].push_back(e);
  }
  queue<int> dfsQ;
  void dijkstra(){
    while(dfsQ.size()) dfsQ.pop();
    priority_queue<node> Q; Q.push(node(0,t,NULL));
    while (!Q.empty()){
      node p=Q.top(); Q.pop(); if(dst[p.v]!=-1)continue;
      dst[p.v]=p.d; nxt[p.v]=p.E; dfsQ.push(p.v);
      for(auto e:rg[p.v]) Q.push(node(p.d+e->d,e->u,e));
    }
  }
  heap* merge(heap* curNd,heap* newNd){
    if(curNd==nullNd) return newNd;
    heap* root=new heap;memcpy(root,curNd,sizeof(heap));
    if(newNd->edge->d<curNd->edge->d){
      root->edge=newNd->edge;
      root->chd[2]=newNd->chd[2];
      root->chd[3]=newNd->chd[3];
      newNd->edge=curNd->edge;
      newNd->chd[2]=curNd->chd[2];
      newNd->chd[3]=curNd->chd[3];
    }
    if(root->chd[0]->dep<root->chd[1]->dep)
      root->chd[0]=merge(root->chd[0],newNd);
    else root->chd[1]=merge(root->chd[1],newNd);
    root->dep=max(root->chd[0]->dep,
              root->chd[1]->dep)+1;
    return root;
  }
  vector<heap*> V;
  void build(){
    nullNd=new heap; nullNd->dep=0; nullNd->edge=new nd;
    fill(nullNd->chd,nullNd->chd+4,nullNd);
    while(not dfsQ.empty()){
      int u=dfsQ.front(); dfsQ.pop();
      if(!nxt[u]) head[u]=nullNd;
      else head[u]=head[nxt[u]->v];
      V.clear();
      for(auto&& e:g[u]){
        int v=e->v;
        if(dst[v]==-1) continue;
        e->d+=dst[v]-dst[u];
        if(nxt[u]!=e){
          heap* p=new heap;fill(p->chd,p->chd+4,nullNd);
          p->dep=1; p->edge=e; V.push_back(p);
        }
      }
      if(V.empty()) continue;
      make_heap(V.begin(),V.end(),cmp);
#define L(X) ((X<<1)+1)
#define R(X) ((X<<1)+2)
      for(size_t i=0;i<V.size();i++){
        if(L(i)<V.size()) V[i]->chd[2]=V[L(i)];
        else V[i]->chd[2]=nullNd;
        if(R(i)<V.size()) V[i]->chd[3]=V[R(i)];
        else V[i]->chd[3]=nullNd;
      }
      head[u]=merge(head[u],V.front());
    }
  }
  vector<ll> ans;
  void first_K(){
    ans.clear(); priority_queue<node> Q;
    if(dst[s]==-1) return;
    ans.push_back(dst[s]);
    if(head[s]!=nullNd)
      Q.push(node(head[s],dst[s]+head[s]->edge->d));
    for(int _=1;_<k and not Q.empty();_++){
      node p=Q.top(),q; Q.pop(); ans.push_back(p.d);
      if(head[p.H->edge->v]!=nullNd){
        q.H=head[p.H->edge->v]; q.d=p.d+q.H->edge->d;
        Q.push(q);
      }
      for(int i=0;i<4;i++)
        if(p.H->chd[i]!=nullNd){
          q.H=p.H->chd[i];
          q.d=p.d-p.H->edge->d+p.H->chd[i]->edge->d;
          Q.push(q);
  } }   }
  void solve(){ // ans[i] stores the i-th shortest path
    dijkstra(); build();
    first_K(); // ans.size() might less than k
  }
} solver;
```

5.15 Chordal Graph a96ac6

```
struct Chordal{
  static const int MXN=100010;
  vector<int> E[MXN],V[MXN];
  int n,f[MXN],rk[MXN],order[MXN],stk[MXN],nsz[MXN];
  bool vis[MXN],isMaximalClique[MXN];
  void init(int _n){
    n=_n;
    for(int i=0;i<=n;++i){
      E[i].clear(),V[i].clear();
      f[i]=rk[i]=order[i]=vis[i]=0;
    }
  }
  void addEdge(int x,int y){
    E[x].push_back(y),E[y].push_back(x);
  }
  void mcs(){
    for(int i=1;i<=n;++i) V[0].push_back(i);
    for(int i=n,M=0;i>=1;--i){
      for(;;){
        while(V[M].size()&&vis[V[M].back()])
          V[M].pop_back();
        if(V[M].size()) break; else M--;
      }
      auto x=V[M].back();order[i]=x;rk[x]=i;vis[x]=1;
      for(auto y:E[x]) if(!vis[y])
        f[y]++,V[f[y]].push_back(y),M=max(M,f[y]);
    }
  }
```

```
  bool isChordal(){
    for(int i=0;i<=n;++i) vis[i]=stk[i]=0;
    for(int i=n;i>=1;--i){
      int top=0,cnt=0,m=n+1;
      for(auto x:E[order[i]]) if(rk[x] > i)
        stk[top++]=x,vis[x]=1,m=min(m,rk[x]);
      if(m==n+1) continue;
      for(auto x:E[order[m]]) if(vis[x]) ++cnt;
      for(int j=0;j<top;++j) vis[stk[j]]=0;
      if(cnt+1!=top) return 0;
    }
    return 1;
  }
  void getMaximalClique(){
    for(int i=n;i>=1;--i){
      int M=n+1,w=order[i],v=0;
      nsz[w]=0;isMaximalClique[w]=1;
      for(auto x:E[w]) if(rk[x]>i){
        nsz[w]++; if(rk[x]<M) M=rk[x],v=x;
      }
      if(v) isMaximalClique[v]&=nsz[v]+1>nsz[w];
    }
  }
  int getMaximumClique(){
    int res=0;
    for(int i=1;i<=n;++i) res=max(res,f[i]+1);
    return res;
  }
  int getMaximumIndependentSet(){
    for(int i=0;i<=n;++i) vis[i]=0;
    int res=0;
    for(int i=1;i<=n;++i) if(!vis[order[i]]){
      res++,vis[order[i]]=1;
      for(auto x:E[order[i]]) vis[x]=1;
    }
    return res;
  }
};
```

5.16 Matroid Intersection d1fe1e

```
/* Matroid Definition:
 * 1. Empty set is ind. 2. Subset of ind. set is ind.
 * 3. If set A, B are ind. and |A| < |B|,
 *    there exists x in B\A s.t. A U {x} is ind.
 * Max Weighted Matroid Intersection: (memorize testInd)
 * Let vertex weight l(x) = (x is chosen ? w(x) : -w(x))
 * Find shortest aug. path with SPFA, based on minimize
 * tie(sum of l(x),number of edges) on the path. */
struct MatroidIntersection {
  int n;           // Elem: bool chosen, int p, info...
  vector<Elem> GS; // Ground Set.
  vector<int> indSet; // Current chosen ind. set
  bool testInd1(int add){} // indSet U {a}
  bool testInd1(int add,int removed){} // ind\{r}U{a}
  bool testInd2(int add){}
  bool testInd2(int add,int removed){}
  bool augment(){ // prepareInd1(), prepareInd2();
    for(auto &x:GS) x.p=-2; // init l,dis,len,inque
    int ep=-3;queue<int> q;
    for(int i=0;i<n;++i) if(!GS[i].chosen&&testInd1(i))
      GS[i].p=-1,q.push(i);
    while(!q.empty()){ // bfs -> SPFA
      int cur=q.front(); q.pop();
      if(GS[cur].chosen){ // SPFA dont check .p != -2
        for(int nxt=0;nxt<n;++nxt){
          if(GS[nxt].chosen or GS[nxt].p!=-2) continue;
          if(!testInd1(nxt,cur)) continue;
          GS[nxt].p=cur; q.push(nxt);
        }
      }else{ // SPFA record nearest ep, dont break
        if(testInd2(cur)){ ep=cur; break; }
        for(auto nxt:indSet){
          if(GS[nxt].p!=-2 or !testInd2(cur,nxt))
            continue;
          GS[nxt].p=cur;q.push(nxt);
    } } }
    if(ep==-3) return false;
    do{ GS[ep].chosen^=1; ep=GS[ep].p; } while(ep!=-1);
    indSet.clear();
    for(int i=0;i<n;i++) if(GS[i].chosen)
        indSet.push_back(i);
    return true;
  }
  void solve(){ n=GS.size(); while(augment()); }
}MI;
```

5.17 Graph Hash

$$F_t(i) = (F_{t-1}(i) \times A + \sum_{i \to j} F_{t-1}(j) \times B + \sum_{j \to i} F_{t-1}(j) \times C + D \times (i = a)) \bmod P$$

for each node i, iterate t times. t, A, B, C, D, P are hash parameter

5.18 Graph Method

```
Manhattan MST
For each point, consider the points that surround it(8
    octants). Then, connect it with the closest point.
    For example, consider 45~90. For each point p, the
    closest point is min{x+y | x-y >= p.x-p.y, x >= p.x
    }. Finally, the answer is this new graphs(E=4N) MST.
```

6 String

6.1 PalTree 7280a6

```
const int MXN = 1000010;
struct PalT{
  int nxt[MXN][26],fail[MXN],len[MXN];
  int tot,lst,n,state[MXN],cnt[MXN],num[MXN];
  int diff[MXN],sfail[MXN],fac[MXN],dp[MXN];
  char s[MXN]={-1};
  int newNode(int l,int f){
    len[tot]=l,fail[tot]=f,cnt[tot]=num[tot]=0;
    memset(nxt[tot],0,sizeof(nxt[tot]));
    diff[tot]=(l>0?l-len[f]:0);
    sfail[tot]=(l>0&&diff[tot]==diff[f]?sfail[f]:f);
    return tot++;
  }
  int getfail(int x){
    while(s[n-len[x]-1]!=s[n]) x=fail[x];
    return x;
  }
  int getmin(int v){
    dp[v]=fac[n-len[sfail[v]]-diff[v]];
    if(diff[v]==diff[fail[v]])
        dp[v]=min(dp[v],dp[fail[v]]);
    return dp[v]+1;
  }
  int push(){
    int c=s[n]-'a',np=getfail(lst);
    if(!(lst=nxt[np][c])){
      lst=newNode(len[np]+2,nxt[getfail(fail[np])][c]);
      nxt[np][c]=lst; num[lst]=num[fail[lst]]+1;
    }
    fac[n]=n;
    for(int v=lst;len[v]>0;v=sfail[v])
        fac[n]=min(fac[n],getmin(v));
    return ++cnt[lst],lst;
  }
  void init(const char *_s){
    tot=lst=n=0; newNode(0,1),newNode(-1,1);
    for(;_s[n];) s[n+1]=_s[n],++n,state[n-1]=push();
    for(int i=tot-1;i>1;i--) cnt[fail[i]]+=cnt[i];
  }
}palt;
```

6.2 SAIS 4379c7

```
const int N=300010;
struct SA{
#define REP(i,n) for(int i=0;i<int(n);i++)
#define REP1(i,a,b) for(int i=(a);i<=int(b);i++)
  bool _t[N*2]; int _s[N*2],_sa[N*2];
  int _c[N*2],x[N],_p[N],_q[N*2],hei[N],r[N];
  int operator [](int i){ return _sa[i]; }
  void build(int *s,int n,int m){
    memcpy(_s,s,sizeof(int)*n);
    sais(_s,_sa,_p,_q,_t,_c,n,m); mkhei(n);
  }
  void mkhei(int n){
    REP(i,n) r[_sa[i]]=i; hei[0]=0;
    REP(i,n) if(r[i]) {
```

```
      int ans=i>0?max(hei[r[i-1]]-1,0):0;
      while(_s[i+ans]==_s[_sa[r[i]-1]+ans]) ans++;
      hei[r[i]]=ans;
    }
  }
  void sais(int *s,int *sa,int *p,int *q,bool *t,int *c,
      int n,int z){
    bool uniq=t[n-1]=true,neq;
    int nn=0,nmxz=-1,*nsa=sa+n,*ns=s+n,lst=-1;
#define MS0(x,n) memset((x),0,n*sizeof(*(x)))
#define MAGIC(XD) MS0(sa,n);\
memcpy(x,c,sizeof(int)*z); XD;\
memcpy(x+1,c,sizeof(int)*(z-1));\
REP(i,n) if(sa[i]&&!t[sa[i]-1]) sa[x[s[sa[i]-1]]++]=sa[i
    ]-1;\
memcpy(x,c,sizeof(int)*z);\
for(int i=n-1;i>=0;i--) if(sa[i]&&t[sa[i]-1]) sa[--x[s[
    sa[i]-1]]]=sa[i]-1;
    MS0(c,z); REP(i,n) uniq&=++c[s[i]]<2;
    REP(i,z-1) c[i+1]+=c[i];
    if(uniq) { REP(i,n) sa[--c[s[i]]]=i; return; }
    for(int i=n-2;i>=0;i--)
      t[i]=(s[i]==s[i+1]?t[i+1]:s[i]<s[i+1]);
    MAGIC(REP1(i,1,n-1) if(t[i]&&!t[i-1]) sa[--x[s[i]]]=
        p[q[i]=nn++]=i);
    REP(i,n) if(sa[i]&&t[sa[i]]&&!t[sa[i]-1]){
      neq=lst<0||memcmp(s+sa[i],s+lst,(p[q[sa[i]]+1]-sa[
          i])*sizeof(int));
      ns[q[lst=sa[i]]]=nmxz+=neq;
    }
    sais(ns,nsa,p+nn,q+n,t+n,c+z,nn,nmxz+1);
    MAGIC(for(int i=nn-1;i>=0;i--) sa[--x[s[p[nsa[i
        ]]]]]=p[nsa[i]]);
  }
}sa;
int H[N],SA[N],RA[N];
void suffix_array(int* ip,int len){
  // should padding a zero in the back
  // ip is int array, len is array length
  // ip[0..n-1] != 0, and ip[len]=0
  ip[len++]=0; sa.build(ip,len,128);
  memcpy(H,sa.hei+1,len<<2); memcpy(SA,sa._sa+1,len<<2);
  for(int i=0;i<len;i++) RA[i]=sa.r[i]-1;
  // resulting height, sa array \in [0,len)
}
```

6.3 SuffixAutomata 815370

```
// any path start from root forms a substring of S
// occurrence of P: iff SAM can run on input word P
// number of different substring: ds[1]-1
// total length of all different substring: dsl[1]
// max/min length of state i: mx[i]/mx[mom[i]]+1
// assume a run on input word P end at state i:
// number of occurrences of P: cnt[i]
// first occurrence position of P: fp[i]-|P|+1
// all position: !clone nodes in dfs from i through rmom
const int MXM=1000010;
struct SAM{
  int tot,root,lst,mom[MXM],mx[MXM]; // ind[MXM]
  int nxt[MXM][33]; // cnt[MXM],ds[MXM],dsl[MXM],fp[MXM]
  // bool v[MXM],clone[MXN]
  int newNode(){
    int res=++tot; fill(nxt[res],nxt[res]+33,0);
    mom[res]=mx[res]=0; // cnt=ds=dsl=fp=v=clone=0
    return res;
  }
  void init(){ tot=0;root=newNode();lst=root; }
  void push(int c){
    int p=lst,np=newNode(); // cnt[np]=1,clone[np]=0
    mx[np]=mx[p]+1; // fp[np]=mx[np]-1
    for(;p&&nxt[p][c]==0;p=mom[p]) nxt[p][c]=np;
    if(p==0) mom[np]=root;
    else{
      int q=nxt[p][c];
      if(mx[p]+1==mx[q]) mom[np]=q;
      else{
        int nq=newNode(); // fp[nq]=fp[q],clone[nq]=1
        mx[nq]=mx[p]+1;
        for(int i=0;i<33;i++) nxt[nq][i]=nxt[q][i];
        mom[nq]=mom[q]; mom[q]=nq; mom[np]=nq;
        for(;p&&nxt[p][c]==q;p=mom[p]) nxt[p][c]=nq;
      }
    }
    lst=np;
  }
  void calc(){
    calc(root); iota(ind,ind+tot,1);
    sort(ind,ind+tot,[&](int i,int j){return mx[i]<mx[j
        ];});
    for(int i=tot-1;i>=0;i--)
      cnt[mom[ind[i]]]+=cnt[ind[i]];
  }
  void calc(int x){
    v[x]=ds[x]=1;dsl[x]=0; // rmom[mom[x]].push_back(x);
    for(int i=0;i<26;i++){
      if(nxt[x][i]){
        if(!v[nxt[x][i]]) calc(nxt[x][i]);
        ds[x]+=ds[nxt[x][i]];
        dsl[x]+=ds[nxt[x][i]]+dsl[nxt[x][i]];
  } } }
  void push(char *str){
    for(int i=0;str[i];i++) push(str[i]-'a');
  }
} sam;
```

6.4 Z Value 391d23

```
void z_value(const char *s,int len,int *z){
  z[0]=len;
  for(int i=1,l=0,r=0;i<len;i++){
    z[i]=i<r?(i-l+z[i-l]<z[l]?z[i-l]:r-i):0;
    while(i+z[i]<len&&s[i+z[i]]==s[z[i]]) ++z[i];
    if(i+z[i]>r) l=i,r=i+z[i];
  }
}
```

6.5 BWT f8c84c

```
const int SIGMA=26; const char BASE='a';
struct BurrowsWheeler{
  vector<int> v[SIGMA];
  void BWT(char* ori,char* res){
    // make ori -> ori+ori and then build suffix array
  }
  void iBWT(char* ori,char* res){
    for(int i=0;i<SIGMA;i++) v[i].clear();
    int len=strlen(ori); vector<int> a;
    for(int i=0;i<len;i++) v[ori[i]-BASE].push_back(i);
    for(int i=0,ptr=0;i<SIGMA;i++)
      for(auto j:v[i]){
        a.push_back(j); ori[ptr++]=BASE+i;
      }
    for(int i=0,ptr=0;i<len;i++){
      res[i]=ori[a[ptr]]; ptr=a[ptr];
    }
    res[len]=0;
  }
}bwt;
```

6.6 ZValue Palindrome 44a8c2

```
void z_value_pal(char *s,int len,int *z){
  len=(len<<1)+1; z[0]=1;
  for(int i=len-1;i>=0;i--) s[i]=i&1?s[i>>1]:'@';
  for(int i=1,l=0,r=0;i<len;i++){
    z[i]=i<r?min(z[l+l-i],r-i):1;
    while(i-z[i]>=0&&i+z[i]<len&&s[i-z[i]]==s[i+z[i]])
      ++z[i];
    if(i+z[i]>r) l=i,r=i+z[i];
  }
}
```

6.7 Smallest Rotation 28fe26

```
//rotate(begin(s),begin(s)+minRotation(s),end(s))
int minRotation(string s) {
  int a = 0, N = s.size(); s += s;
  rep(b,0,N) rep(k,0,N) {
    if(a+k == b || s[a+k] < s[b+k])
      {b += max(0, k-1); break;}
    if(s[a+k] > s[b+k]) {a = b; break;}
  } return a;
}
```

6.8 Cyclic LCS bcba38

```
const int L=0,LU=1,U=2,mov[3][2]={0,-1,-1,-1,-1,0};
int al,bl,dp[MAXL*2][MAXL];
char a[MAXL*2],b[MAXL*2],pred[MAXL*2][MAXL]; // 0-based
inline int lcs_length(int r) {
  int i=r+al,j=bl,l=0;
  while(i>r){
    char dir=pred[i][j]; if(dir==LU) l++;
    i+=mov[dir][0]; j+=mov[dir][1];
  }
  return l;
}
inline void reroot(int r){ // r = new base row
  int i=r,j=1;
  while(j<=bl&&pred[i][j]!=LU) j++;
  if(j>bl) return;
  pred[i][j]=L;
  while(i<2*al&&j<=bl){
    if(pred[i+1][j]==U){ i++; pred[i][j]=L; }
    else if(j<bl&&pred[i+1][j+1]==LU){
      i++; j++; pred[i][j]=L;
    } else j++;
  }
}
int cyclic_lcs(){
  // a, b, al, bl should be properly filled
  // note: a WILL be altered in process
  //       -- concatenated after itself
  char tmp[MAXL];
  if(al>bl){
    swap(al,bl);strcpy(tmp,a);strcpy(a,b);strcpy(b,tmp);
  }
  strcpy(tmp,a); strcat(a,tmp);
  // basic lcs
  for(int i=0;i<=2*al;i++){ dp[i][0]=0; pred[i][0]=U; }
  for(int j=0;j<=bl;j++){ dp[0][j]=0; pred[0][j]=L; }
  for(int i=1;i<=2*al;i++){ for(int j=1;j<=bl;j++){
      if(a[i-1]==b[j-1]) dp[i][j]=dp[i-1][j-1]+1;
      else dp[i][j]=max(dp[i-1][j],dp[i][j-1]);
      if(dp[i][j-1]==dp[i][j]) pred[i][j]=L;
      else if(a[i-1]==b[j-1]) pred[i][j]=LU;
      else pred[i][j]=U;
    }
  }
  int clcs=0; // do cyclic lcs
  for(int i=0;i<al;i++){
    clcs=max(clcs,lcs_length(i)); reroot(i+1);
  }
  a[al]='\0'; // recover a
  return clcs;
}
```

7 Data Structure

7.1 Link-Cut Tree f3eedd

```
const int MEM=100005;
struct Splay {
  static Splay nil,mem[MEM],*pmem; Splay *ch[2],*f;
  int val,rev,size; // int sum,vir,tot;
  Splay(int _val=-1):val(_val),rev(0),size(1)
  { f=ch[0]=ch[1]=&nil; }
  bool isr(){ return f->ch[0]!=this&&f->ch[1]!=this; }
  int dir(){ return f->ch[0]!=this; }
  void setCh(Splay *c,int d){
    ch[d]=c; if(c!=&nil) c->f=this; pull();
  }
  void push(){
    if(!rev) return; swap(ch[0],ch[1]);
    if(ch[0]!=&nil) ch[0]->rev^=1;
    if(ch[1]!=&nil) ch[1]->rev^=1;
    rev=0;
  }
  void pull(){
    size=ch[0]->size+ch[1]->size+1;
    // sum={ch[0]->sum,ch[1]->sum,val}; tot={sum,vir};
    if(ch[0]!=&nil) ch[0]->f=this;
    if(ch[1]!=&nil) ch[1]->f=this;
  }
}Splay::nil,Splay::mem[MEM],*Splay::pmem=Splay::mem;
Splay *nil=&Splay::nil; vector<Splay*> splayVec;
void rotate(Splay *x){
  Splay *p=x->f; int d=x->dir();
  if(!p->isr()) p->f->setCh(x,p->dir()); else x->f=p->f;
  p->setCh(x->ch[!d],d); x->setCh(p,!d);
}
void splay(Splay *x){
  splayVec.clear();
  for(Splay *q=x;; q=q->f){
    splayVec.push_back(q);
    if(q->isr()) break;
  }
  reverse(begin(splayVec),end(splayVec));
  for(auto it:splayVec) it->push();
  while(!x->isr()){
    if(x->f->isr()) rotate(x);
    else if(x->dir()==x->f->dir())
      rotate(x->f),rotate(x);
    else rotate(x),rotate(x);
  }
}
int id(Splay *x){ return x-Splay::mem+1; }
Splay* access(Splay *x){
  Splay *q=nil;
  for(;x!=nil;x=x->f){
    splay(x); // x->vir+={x->ch[0]->tot}-{q->tot};
    x->setCh(q,1); q=x;
  }
  return q;
}
void chroot(Splay *x){ access(x); splay(x); x->rev^=1; }
void link(Splay *x,Splay *y){
  chroot(y); access(x); splay(x); y->f=x;
  // x->vir+={y->tot};
}
void cut_p(Splay *y){
  access(y);splay(y); y->ch[0]=y->ch[0]->f=nil;
}
void cut(Splay *x,Splay *y){ chroot(x); cut_p(y); }
Splay* get_root(Splay *x) {
  x=access(x);
  for(;x->ch[0]!=nil;x=x->ch[0]) x->push();
  splay(x); return x;
}
bool conn(Splay *x,Splay *y){
  return get_root(x)==get_root(y);
}
Splay* lca(Splay *x,Splay *y){
  access(x); return access(y);
}
/* query(Splay *x,Splay *y){ // path
  setroot(y),x=access(x); return x->size; // x->sum;
} */
/* query(Splay *x,Splay *y){ // path
  Splay *p=lca(x,y);
  return 1+p->ch[1]->size+(x!=p?x->size:0);
  // {p->val,p->ch[1]->sum,x!=p?x->sum:0};
} */
/* query(Splay *x){ // subtree
  access(x); return {x->val,x->vir};
} */
```

8 Others

8.1 Find max tangent(x,y is increasing) 8fea15

```
const int MAXN=100010;
Pt sum[MAXN],pnt[MAXN],ans,calc;
inline bool cross(Pt a,Pt b,Pt c){
  return (c.y-a.y)*(c.x-b.x)>(c.x-a.x)*(c.y-b.y);
} // pt[0]=(0,0);pt[i]=(i,pt[i-1].y+dy[i-1]),i=1~n;dx>=l
double find_max_tan(int n,int l,LL dy[]){
  int np,st,ed,now; sum[0].x=sum[0].y=np=st=ed=0;
  for(int i=1,v;i<=n;i++)
    sum[i].x=i,sum[i].y=sum[i-1].y+dy[i-1];
  ans.x=now=1,ans.y=-1;
  for(int i=0;i<=n-l;i++){
    while(np>1&&cross(pnt[np-2],pnt[np-1],sum[i])) np--;
    if(np<now&&np!=0) now=np;
    pnt[np++]=sum[i];
    while(now<np&&!cross(pnt[now-1],pnt[now],sum[i+l]))
```

```
      now++;
    calc=sum[i+l]-pnt[now-1];
    if(ans.y*calc.x<ans.x*calc.y)
      ans=calc,st=pnt[now-1].x,ed=i+l;
  }
  return (double)(sum[ed].y-sum[st].y)/(sum[ed].x-sum[st
      ].x);
}
```

8.2 Exact Cover Set 91d0af

```
// given n*m 0-1 matrix, find a set of rows s.t.
// for each column, there's exactly one 1
const int N=1024,M=1024,NM=((N+2)*(M+2)) // row,col
bool A[N][M]; // n*m 0-1 matrix
bool used[N]; // answer: the row used
int id[N][M];
int L[NM],R[NM],D[NM],U[NM],C[NM],S[NM],ROW[NM];
void remove(int c){
  L[R[c]]=L[c]; R[L[c]]=R[c];
  for(int i=D[c];i!=c;i=D[i])
    for(int j=R[i];j!=i;j=R[j]){
      U[D[j]]=U[j]; D[U[j]]=D[j]; S[C[j]]--;
    }
}
void resume(int c){
  for(int i=D[c];i!=c;i=D[i])
    for(int j=L[i];j!=i;j=L[j]){
      U[D[j]]=D[U[j]]=j; S[C[j]]++;
    }
  L[R[c]]=R[L[c]]=c;
}
bool dfs(){
  if(R[0]==0) return 1;
  int md=100000000,c;
  for(int i=R[0];i!=0;i=R[i]) if(S[i]<md){md=S[i]; c=i;}
  if(md==0) return 0;
  remove(c);
  for(int i=D[c];i!=c;i=D[i]){
    used[ROW[i]]=1;
    for(int j=R[i];j!=i;j=R[j]) remove(C[j]);
    if(dfs()) return 1;
    for(int j=L[i];j!=i;j=L[j]) resume(C[j]);
    used[ROW[i]]=0;
  }
  resume(c); return 0;
}
bool exact_cover(int n,int m){
  for(int i=0;i<=m;i++){
    R[i]=i+1; L[i]=i-1; U[i]=D[i]=i; S[i]=0; C[i]=i;
  }
  R[m]=0; L[0]=m; int t=m+1;
  for(int i=0;i<n;i++){
    int k=-1;
    for(int j=0;j<m;j++){
      if(!A[i][j]) continue;
      if(k==-1) L[t]=R[t]=t;
      else{ L[t]=k; R[t]=R[k]; }
      k=t; D[t]=j+1; U[t]=U[j+1];
      L[R[t]]=R[L[t]]=U[D[t]]=D[U[t]]=t;
      C[t]=j+1; S[C[t]]++; ROW[t]=i; id[i][j]=t++;
    }
  }
  for(int i=0;i<n;i++) used[i]=0;
  return dfs();
}
```

8.3 Binary Next Permutation b7a40a

```
ull next_perm(ull v){
  ull t=v|(v-1);
  return (t+1)|(((~t&-~t)-1)>>(__builtin_ctzll(v)+1));
}
```

8.4 Hilbert Curve 15d26a

```
long long hilbert(int n,int x,int y){
  long long res=0;
  for(int s=n/2;s;s>>=1){
    int rx=(x&s)>0,ry=(y&s)>0; res+=s*1ll*s*((3*rx)^ry);
    if(ry==0){ if(rx==1) x=s-1-x,y=s-1-y; swap(x,y); }
  }
  return res;
}
```