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1 Basic

1.1 Default Code [d41d8c]

```
#include <bits/stdc++.h>

using namespace std;
using ll = long long;

const int Mod = 1E9 + 7;
int add(int a, int b) { a += b; if (a >= Mod) a -= Mod; return a; }
int sub(int a, int b) { a -= b; if (a < 0) a += Mod; return a; }
int mul(int a, int b) { return 1LL * a * b % Mod; }
int power(int a, ll b) {
    int ans = 1;
    for (; b > 0; b >>= 1, a = mul(a, a))
        if (b & 1) ans = mul(ans, a);
    return ans;
}

void solve() {
}

int main() {
    ios::sync_with_stdio(false);
    cin.tie(nullptr);
    auto s = chrono::high_resolution_clock::now();
    int t = 1;
    cin >> t;
    while (t--) {
        solve();
    }
    auto e = chrono::high_resolution_clock::now();
    cerr << chrono::duration_cast<chrono::milliseconds>(e - s).count() << " ms\n";
}
```

```
return 0;
}
```

1.2 Debug [66f9cf]

```
CODE1="a"
CODE2="brute"
set -e
g++ $CODE1.cpp -o $CODE1
g++ $CODE2.cpp -o $CODE2
for ((i=0;;i++))
do
    echo "$i"
    g++ gen.cpp -o gen
    ./gen > input
    # python3 gen.py > input
    ./CODE1 < input > $CODE1.out
    ./CODE2 < input > $CODE2.out
    cmp $CODE1.out $CODE2.out || break
done
```

1.3 Compare Fuction [d41d8c]

```
// 1. sort, 二分搜刻在函式內 lambda 就好
// 2. priority queue 小到大是 >, set 是 <
// 3. set 不能 =, multiset 必須 =
// 4. 確保每個成員都要比到
// 5. pbds_multiset 不要用 lower_bound
// 6. 如果要用 find, 插入 inf 後使用 upper_bound
// 7. multiset 可以跟 set 一樣使用, 但請注意第 3、4 點
auto cmp = [](int i, int j) { return i > j; };
priority_queue<int, vector<int>, decltype(cmp)> pq(cmp);
```

```
vector<int> a {1, 2, 5, 4, 3}; // 小心不要改到 a
auto cmp = [&a](int i, int j) { return a[i] > a[j]; };
priority_queue<int, vector<int>, decltype(cmp)> pq(cmp);
```

1.4 Pbds [d41d8c]

```
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace __gnu_pbds;
template<class T>
using pbds_set = tree<T, null_type,
    less<T>, rb_tree_tag, tree_order_statistics_node_update>;
template<class T>
using pbds_multiset = tree<T, null_type, less_equal<T>, rb_tree_tag, tree_order_statistics_node_update>;
```

1.5 Double [85f18f]

```
struct D {
    double x;
    D(double x = 0.0) : x{x} {}
    constexpr static double eps = 1E-12;
    explicit operator double() const { return x; }
    D operator-() const { return D(-x); }
    D &operator+=(D b) & { x += b.x; return *this; }
    D &operator-=(D b) & { x -= b.x; return *this; }
    D &operator*=(D b) & { x *= b.x; return *this; }
    D &operator/=(D b) & {
        assert(fabs(b.x) > eps);
        x /= b.x; return *this;
    }
    friend D operator+(D a, D b) { return a + b; }
    friend D operator-(D a, D b) { return a - b; }
    friend D operator*(D a, D b) { return a * b; }
    friend D operator/(D a, D b) { return a / b; }
    friend istream &operator>>(istream &is, D &a) {
        double v; is >> v; a = D(v); return is;
    }
    friend ostream &operator<<(ostream &os, const D &a) {
        return os << fixed << setprecision(9) << a.x + (a.x > 0 ? eps : a.x < 0 ? -eps : 0);
    } // eps should < precision
    friend bool operator<(D lhs, D rhs) {
        return lhs.x - rhs.x < -eps;
    }
    friend bool operator>(D lhs, D rhs) {
        return lhs.x - rhs.x > eps;
    }
    friend bool operator==(D lhs, D rhs) {
        return fabs(lhs.x - rhs.x) < eps;
    }
};
D abs(D a) { return a < 0 ? -a : a; }
```

1.6 Int128 [85923a]

```
using i128 = __int128_t; // 1.7E38
istream &operator>>(istream &is, i128 &a) {
    i128 sgn = 1; a = 0;
    string s; is >> s;
    for (auto c : s) {
        if (c == '-') {
            sgn = -1;
        } else {
            a = a * 10 + c - '0';
        }
    }
}
```

```

    a *= sgn;
    return is;
}
ostream &operator<<(ostream &os, i128 a) {
    string res;
    if (a < 0) os << '- ', a = -a;
    while (a) {
        res.push_back(a % 10 + '0');
        a /= 10;
    }
    reverse(res.begin(), res.end());
    os << res;
    return os;
}

```

1.7 Rng [401544]

```

mt19937_64 rng
    (chrono::steady_clock::now().time_since_epoch().count());
ll x = rng();
shuffle(a.begin(), a.end(), rng);

```

2 Graph

2.1 DFS And BFS [1f02d8]

```

void dfsBfs() {
    int n;
    vector<vector<int>> adj(n);
    // dfs_graph
    vector<bool> vis(n);
    auto dfs = [&](auto self, int u) -> void {
        if (vis[u]) return;
        vis[u] = true;
        for (auto v: adj[u]) {
            self(self, v);
        }
    };
    dfs(dfs, 0);
    // bfs
    vector<int> dep(n, -1);
    auto bfs = [&](auto self, int s) -> void {
        queue<int> que;
        dep[s] = 0, que.push(s);
        while (!que.empty()) {
            int u = que.front(); que.pop();
            for (auto v: adj[u]) {
                if (dep[v] == -1) {
                    dep[v] = dep[u] + 1;
                    que.push(v);
                }
            }
        }
    };
    bfs(bfs, 0);
}

```

2.2 Prim [cefbbf]

```

auto prim =
    [&](int n, vector<vector<pair<int, int>>> &adj) -> bool {
        int sz = 0; ll ans = 0;
        priority_queue<pair<int, int>,
            vector<pair<int, int>>, greater<pair<int, int>>> pq;
        pq.emplace(0, 0); // w, vertex
        vector<bool> vis(n);
        while (!pq.empty()) {
            auto [w, u] = pq.top(); pq.pop();
            if (vis[u]) continue;
            vis[u] = true;
            ans += w, sz++;
            for (auto [v, w]: g[u])
                if (!vis[v])
                    pq.emplace(w, v);
        }
        if (sz == n) return true;
        return false;
    };

```

2.3 Bellman-Ford [430de2]

```

// 用 Bellman Ford 找負環
void bellmanFord() {
    int n, m; cin >> n >> m;
    vector<array<int, 3>> e;
    for (int i = 0; i < m; i++) {
        int u, v, w; cin >> u >> v >> w;
        u--, v--; e.push_back({u, v, w});
    }
    vector<ll> dis(n, inf), par(n);
    int t = -1; dis[0] = 0;
    for (int i = 1; i <= n; i++) {
        for (auto [u, v, w]: e) {
            if (dis[v] > dis[u] + w) {
                dis[v] = dis[u] + w;
                par[v] = u;
                if (i == n) t = v;
            }
        }
    }
    if (t == -1) { cout << "NO\n"; return; }
}

```

```

for (int i = 1; i < n; i++) t = par[t];
vector<int> ans {t};
int i = t;
do {
    i = par[i];
    ans.push_back(i);
} while (i != t);
reverse(ans.begin(), ans.end());
cout << "YES\n";
for (auto x: ans) cout << x + 1 << " ";
}

```

2.4 Floyd-Warshall [db13dd]

```

const ll inf = 1E18;
void floydWarshall(int n, int m) {
    int n, m; cin >> n >> m;
    vector<vector<int>> dis(n, vector<int>(n, inf));
    for (int i = 0; i < m; i++) {
        int u, v, w; cin >> u >> v >> w;
        dis[u][v] = min(dis[u][v], w);
        dis[v][u] = min(dis[v][u], w);
    }
    for (int i = 0; i < n; i++) dis[i][i] = 0;
    for (int k = 0; k < n; k++)
        for (int i = 0; i < n; i++)
            for (int j = 0; j < n; j++)
                dis[i][j] = min(dis[i][j], dis[i][k] + dis[k][j]);
}

const int N = 500; // Floyd 封包
void floyd(int n, vector<bitset<N>> &dp) {
    for (int k = 0; k < n; k++)
        for (int i = 0; i < n; i++)
            if (dp[i][k]) dp[i] |= dp[k];
}

```

2.5 Euler [4177dc]

```

// 1. 無向圖是歐拉圖：
// 非零度頂點是連通的
// 頂點的度數都是偶數

// 2. 無向圖是半歐拉圖(有路沒有環)：
// 非零度頂點是連通的
// 恰有 2 個奇度頂點

// 3. 有向圖是歐拉圖：
// 非零度頂點是強連通的
// 每個頂點的入度和出度相等

// 4. 有向圖是半歐拉圖(有路沒有環)：
// 非零度頂點是弱連通的
// 至多一個頂點的出度與入度之差為 1
// 至多一個頂點的入度與出度之差為 1
// 其他頂點的入度和出度相等
vector<int> ans;
auto dfs = [&](auto &self, int u) -> void {
    while (g[u].size()) {
        int v = *g[u].begin();
        g[u].erase(v);
        self(self, v);
    }
    ans.push_back(u);
};
dfs(dfs, 0);
reverse(ans.begin(), ans.end());

```

2.6 DSU [6bd5f4]

```

struct DSU {
    int n;
    vector<int> f, siz;
    DSU(int n): n(n), f(n), siz(n, 1) {
        iota(f.begin(), f.end(), 0);
    }
    int find(int x) {
        if (f[x] == x) return x;
        return f[x] = find(f[x]);
    }
    bool same(int x, int y) {
        return find(x) == find(y);
    }
    bool merge(int x, int y) {
        x = find(x); y = find(y);
        if (x == y) return false;
        if (siz[x] < siz[y]) swap(x, y);
        siz[x] += siz[y];
        f[y] = x;
        n--;
        return true;
    }
    int size(int x) {
        return siz[find(x)];
    }
};

struct DSU {
    int n;

```

```

vector<int> f, siz, stk;
DSU(int n) : n(n), f(n), siz(n, 1) {
    iota(f.begin(), f.end(), 0);
    stk.clear();
}
int find(int x) {
    return x == f[x] ? x : find(f[x]);
}
bool same(int x, int y) {
    return find(x) == find(y);
}
bool merge(int x, int y) {
    x = find(x); y = find(y);
    if (x == y) return false;
    if (siz[x] < siz[y]) swap(x, y);
    siz[x] += siz[y];
    f[y] = x;
    n--;
    stk.push_back(y);
    return true;
}
void undo(int x) {
    while (stk.size() > x) {
        int y = stk.back();
        stk.pop_back();
        n++;
        siz[f[y]] -= siz[y];
        f[y] = y;
    }
}
int size(int x) {
    return siz[find(x)];
}
};

```

2.7 SCC [3ac1cb]

```

struct SCC {
    int n, cur, cnt;
    vector<vector<int>> adj;
    vector<int> stk, dfn, low, bel;
    SCC(int n) : n(n), cur
        (0), cnt(0), adj(n), dfn(n, -1), low(n), bel(n, -1) {}
    void addEdge(int u, int v) { adj[u].push_back(v); }
    void dfs(int x) {
        dfn[x] = low[x] = cur++;
        stk.push_back(x);
        for (auto y : adj[x]) {
            if (dfn[y] == -1) {
                dfs(y);
                low[x] = min(low[x], low[y]);
            } else if (bel[y] == -1) {
                low[x] = min(low[x], dfn[y]);
            }
        }
        if (dfn[x] == low[x]) {
            int y;
            do {
                y = stk.back();
                bel[y] = cnt;
                stk.pop_back();
            } while (y != x);
            cnt++;
        }
    }
    vector<int> work() {
        for (int i = 0; i < n; i++)
            if (dfn[i] == -1) dfs(i);
        return bel;
    }
}

struct Graph {
    int n;
    vector<pair<int, int>> edges;
    vector<int> siz, cnte;
};

Graph compress() {
    Graph g;
    g.n = cnt;
    g.siz.resize(cnt);
    g.cnte.resize(cnt);
    for (int i = 0; i < n; i++) {
        g.siz[bel[i]]++;
        for (auto j : adj[i]) {
            if (bel[i] != bel[j]) {
                g.edges.emplace_back(bel[i], bel[j]);
            } else {
                g.cnte[bel[i]]++;
            }
        }
    }
    return g;
}
};

```

2.8 VBCC [95997d]

```

struct VBCC {
    int n, cur, cnt;
    vector<vector<int>> adj, bcc;
    vector<int> stk, dfn, low;
    vector<bool> ap;
    VBCC(int n) : n(n), cur(0),
        cnt(0), adj(n), bcc(n), ap(n), low(n), dfn(n, -1) {}
}

```

```

void addEdge(int u, int v) {
    adj[u].push_back(v);
    adj[v].push_back(u);
}

void dfs(int x, int p) {
    dfn[x] = low[x] = cur++;
    stk.push_back(x);
    int ch = 0;
    for (auto y : adj[x]) {
        if (y == p) continue;
        if (dfn[y] == -1) {
            dfs(y, x), ch++;
            low[x] = min(low[x], low[y]);
            if (low[y] >= dfn[x]) {
                int v;
                do {
                    v = stk.back();
                    bcc[v].push_back(cnt);
                    stk.pop_back();
                } while (v != y);
                bcc[x].push_back(cnt);
                cnt++;
            }
            if (low[y] >= dfn[x] && p != -1)
                ap[x] = true;
        } else {
            low[x] = min(low[x], dfn[y]);
        }
    }
    if (p == -1 && ch > 1) ap[x] = true;
}

vector<bool> work() {
    for (int i = 0; i < n; i++)
        if (dfn[i] == -1) dfs(i, -1);
    return ap;
}

struct Graph {
    int n;
    vector<pair<int, int>> edges;
    vector<int> bel, siz, cnte;
};

Graph compress() {
    Graph g; // 壓完是一棵樹，但不一定每個 bel 都有節點
    g.bel.resize(n);
    g.siz.resize(cnt);
    g.cnte.resize(cnt);
    for (int u = 0; u < n; u++) {
        if (ap[u]) {
            g.bel[u] = cnt++;
            g.siz.emplace_back();
            g.cnte.emplace_back();
            for (auto v : bcc[u]) {
                g.edges.emplace_back(g.bel[u], v);
            }
        } else if (bcc[u].size() == 1) {
            g.bel[u] = bcc[u][0];
        }
        g.siz[g.bel[u]]++;
    }
    g.n = cnt;
    for (int i = 0; i < n; i++)
        for (auto j : adj[i])
            if (g.bel[i] == g.bel[j] && i < j)
                g.cnte[g.bel[i]]++;
    return g;
}
};

```

2.9 EBCC [12a170]

```

struct EBCC { // CF/contest/1986/pF
    int n, cur, cnt;
    vector<vector<int>> adj;
    vector<int> stk, dfn, low, bel;
    vector<pair<int, int>> bridges; // 關鍵邊
    EBCC(int n) : n(n), cur
        (0), cnt(0), adj(n), low(n), dfn(n, -1), bel(n, -1) {}
    void addEdge(int u, int v) {
        adj[u].push_back(v);
        adj[v].push_back(u);
    }
    void dfs(int x, int p) {
        dfn[x] = low[x] = cur++;
        stk.push_back(x);
        for (auto y : adj[x]) {
            if (y == p) continue;
            if (dfn[y] == -1) {
                dfs(y, x);
                low[x] = min(low[x], low[y]);
                if (low[y] > dfn[x]) {
                    bridges.emplace_back(x, y);
                }
            } else if (bel[y] == -1) {
                low[x] = min(low[x], dfn[y]);
            }
        }
        if (dfn[x] == low[x]) {
            int y;
            do {
                y = stk.back();
                bel[y] = cnt;
                stk.pop_back();
            } while (y != x);
            cnt++;
        }
    }
}

```

```

    } while (y != x);
    cnt++;
}
}
vector<int> work() { // not connected
    for (int i = 0; i < n; i++)
        if (dfn[i] == -1) dfs(i, -1);
    return bel;
}
struct Graph {
    int n;
    vector<pair<int, int>> edges;
    vector<int> siz, cnte;
};
Graph compress() {
    Graph g;
    g.n = cnt;
    g.siz.resize(cnt);
    g.cnte.resize(cnt);
    for (int i = 0; i < n; i++) {
        g.siz[bel[i]]++;
        for (auto j : adj[i]) {
            if (bel[i] < bel[j]) {
                g.edges.emplace_back(bel[i], bel[j]);
            } else if (i < j) {
                g.cnte[bel[i]]++;
            }
        }
    }
    return g;
}
};

```

2.10 2-SAT [28688f]

```

struct TwoSat {
    int n; vector<vector<int>> e;
    vector<bool> ans;
    TwoSat(int n) : n(n), e(2 * n), ans(n) {}
    void addClause(int u, bool f, int v, bool g) {
        e[2 * u + !f].push_back(2 * v + g);
        e[2 * v + !g].push_back(2 * u + f);
    }
    void ifThen(int u, bool f, int v, bool g) {
        // 必取 A: not A -> A
        e[2 * u + !f].push_back(2 * v + g);
    }
    bool satisfiable() {
        vector<int>
            > id(2 * n, -1), dfn(2 * n, -1), low(2 * n, -1);
        vector<int> stk;
        int now = 0, cnt = 0;
        function<void(int)> tarjan = [&](int u) {
            stk.push_back(u);
            dfn[u] = low[u] = now++;
            for (auto v : e[u]) {
                if (dfn[v] == -1) {
                    tarjan(v);
                    low[u] = min(low[u], low[v]);
                } else if (id[v] == -1) { // in stk
                    low[u] = min(low[u], dfn[v]);
                }
            }
            if (dfn[u] == low[u]) {
                int v;
                do {
                    v = stk.back();
                    stk.pop_back();
                    id[v] = cnt;
                } while (v != u);
                ++cnt;
            }
        };
        for (int i = 0; i < 2 * n; ++i) if (dfn[i] == -1) tarjan(i);
        for (int i = 0; i < n; ++i) {
            if (id[2 * i] == id[2 * i + 1]) return false;
            ans[i] = id[2 * i] > id[2 * i + 1];
        }
        return true;
    }
    vector<bool> answer() { return ans; }
};

```

2.11 Functional Graph [c314e3]

```

const int N = 2E5;
const int Lg = __lg(N); // __lg(max(n, qi)), [0, Lg]
int cht[N][Lg];
struct FunctionalGraph {
    int n, cnt;
    vector<int> g, bel, id, cycsz, in, top, hei;
    FunctionalGraph(const vector<int> &g) : n(g.size()), cnt(0) {
        g(g), bel(n, -1), id(n), in(n), top(n, -1), hei(n) {}
        for (int i = 0; i < n; i++)
            cht[i][0] = g[i], in[g[i]]++;
        for (int i = 1; i <= Lg; i++)
            for (int u = 0; u < n; u++) {
                int nxt = cht[u][i - 1];
                cht[u][i] = cht[nxt][i - 1];
            }
        for (int i = 0; i < n; i++)

```

```

        if (in[i] == 0) label(i);
        for (int i = 0; i < n; i++)
            if (top[i] == -1) label(i);
    }
    void label(int u) {
        vector<int> p; int cur = u;
        while (top[cur] == -1) {
            top[cur] = u;
            p.push_back(cur);
            cur = g[cur];
        }
        auto s = find(p.begin(), p.end(), cur);
        vector<int> cyc(s, p.end());
        p.erase(s, p.end()); p.push_back(cur);
        for (int i = 0; i < (int)cyc.size(); i++)
            bel[cyc[i]] =
                cnt, id[cyc[i]] = i, hei[cyc[i]] = cyc.size();
        if (!cyc.empty())
            ++cnt, cycsz.push_back(cyc.size());
        for (int i = p.size() - 1; i > 0; i--)
            id[p[i - 1]]
                = id[p[i]] - 1, hei[p[i - 1]] = hei[p[i]] + 1;
    }
    int jump(int u, int k) {
        for (int b = 0; k > 0; b++) {
            if (k & 1) u = cht[u][b];
            k >>= 1;
        }
        return u;
    }
};

```

3 Data Structure

3.1 Segment Tree [d41d8c]

```

template<class Info, class Tag = bool()>
struct SegmentTree { // [l, r), uncomment /**/ to lazy
    int n;
    vector<Info> info;
    /**
     * vector<Tag> tag;
     */
    template<class T>
    SegmentTree(const vector<T> &init) {
        n = init.size();
        info.assign(4 << __lg(n), Info());
        /**
         * tag.assign(4 << __lg(n), Tag());
         */
        function<void(
            int, int, int)> build = [&](int p, int l, int r) {
            if (r - l == 1) {
                info[p] = init[l];
                return;
            }
            int m = (l + r) / 2;
            build(2 * p, l, m);
            build(2 * p + 1, m, r);
            pull(p);
        };
        build(1, 0, n);
    }
    void pull(int p) {
        info[p] = info[2 * p] + info[2 * p + 1];
    }
    /**
     * void apply(int p, int l, int r, const Tag &v) {
     *     info[p].apply(l, r, v);
     *     tag[p].apply(v);
     * }
     * void push(int p, int l, int r) {
     *     int m = (l + r) / 2;
     *     if (r - l >= 1) {
     *         apply(2 * p, l, m, tag[p]);
     *         apply(2 * p + 1, m, r, tag[p]);
     *     }
     *     tag[p] = Tag();
     * }
     */
    void modify(int p, int l, int r, int x, const Info &v) {
        if (r - l == 1) {
            info[p] = v;
            return;
        }
        int m = (l + r) / 2;
        /**
         * push(p, l, r);
         */
        if (x < m) {
            modify(2 * p, l, m, x, v);
        } else {
            modify(2 * p + 1, m, r, x, v);
        }
        pull(p);
    }
    void modify(int p, const Info &i) {
        modify(1, 0, n, p, i);
    }
    Info query(int p, int l, int r, int ql, int qr) {
        if (qr <= l || ql >= r) return Info();
        if (ql <= l && r <= qr) return info[p];
    }
};

```

```

    int m = (l + r) / 2;
    /*
    push(p, l, r);
    */
    return query(2 *
        p, l, m, ql, qr) + query(2 * p + 1, m, r, ql, qr);
}
Info query(int ql, int qr) {
    return query(1, 0, n, ql, qr);
}
/*
void rangeApply
(int p, int l, int r, int ql, int qr, const Tag &v) {
    if (qr <= l || ql >= r) return;
    if (ql <= l && r <= qr) {
        apply(p, l, r, v);
        return;
    }
    int m = (l + r) / 2;
    push(p, l, r);
    rangeApply(2 * p, l, m, ql, qr, v);
    rangeApply(2 * p + 1, m, r, ql, qr, v);
    pull(p);
}
void rangeApply(int l, int r, const Tag &v) {
    rangeApply(1, 0, n, l, r, v);
}
*/
template<class F> // 尋找區間內，第一個符合條件的
int findFirst
(int p, int l, int r, int x, int y, F &&pred) {
    if (l >= y || r <= x) return -1;
    if (l >= x && r <= y && !pred(info[p])) return -1;
    if (r - l == 1) return l;
    int m = (l + r) / 2;
    /*
    push(p, l, r);
    */
    int res = findFirst(2 * p, l, m, x, y, pred);
    if (res == -1)
        res = findFirst(2 * p + 1, m, r, x, y, pred);
    return res;
}
template<class F> // 若要找 last，先右子樹遞迴即可
int findFirst(int l, int r, F &&pred) {
    return findFirst(1, 0, n, l, r, pred);
}
};
// 有些 Tag 不用 push 例如 sweepLine
/*
struct Tag {
    int setVal = 0;
    int add = 0;
    void apply(const Tag &t) & {
        if (t.setVal) {
            setVal = t.setVal;
            add = t.add;
        } else {
            add += t.add;
        }
    }
};
*/
struct Info {
    ll sum = 0;
    /*
    void apply(int l, int r, const Tag &t) & {
        if (t.setVal) {
            sum = (r - l) * t.setVal;
        }
        sum += (r - l) * t.add;
    }
    */
    // 部分 assignment 使用
    // Info &operator=(const Info &rhs) & {
    //     return *this;
    // }
    Info &operator=(const ll &rhs) & {
        sum = rhs;
        return *this;
    }
};
Info operator+(const Info &a, const Info &b) {
    Info c;
    c.sum = a.sum + b.sum;
    return c;
}

```

3.2 Persistent Segment Tree [d41d8c]

```

template<class Info>
struct PST {
    struct Node {
        Info info = Info();
        int lc = 0, rc = 0;
    };
    int n;
    vector<Node> nd;
    vector<int> rt;
    template<class T>
    PST(const vector<T> &init) {

```

```

        n = init.size();
        nd.assign(1, Node());
        rt.clear();
        function<int(int, int)> build = [&](int l, int r) {
            int id = nd.size();
            nd.emplace_back();
            if (r - l == 1) {
                nd[id].info = init[l];
                return id;
            }
            int m = (l + r) >> 1;
            nd[id].lc = build(l, m);
            nd[id].rc = build(m, r);
            pull(nd[id]);
            return id;
        };
        rt.push_back(build(0, n));
    }
    void pull(Node &t) {
        t.info = nd[t.lc].info + nd[t.rc].info;
    }
    int copy(int t) { // copy 一個 node
        nd.push_back(nd[t]);
        return nd.size() - 1;
    }
    int generate() { // 創立新的 node
        nd.emplace_back();
        return nd.size() - 1;
    }
    int modify(int t, int l, int r, int x, const Info &v) {
        t = t ? copy(t) : generate();
        if (r - l == 1) {
            nd[t].info = v;
            return t;
        }
        int m = (l + r) / 2;
        if (x < m) {
            nd[t].lc = modify(nd[t].lc, l, m, x, v);
        } else {
            nd[t].rc = modify(nd[t].rc, m, r, x, v);
        }
        pull(nd[t]);
        return t;
    }
    void modify(int ver, int p, const Info &i) {
        if ((int)(rt.size()) <= ver) rt.resize(ver + 1);
        rt[ver] = modify(rt[ver], 0, n, p, i);
    }
    Info query(int t, int l, int r, int ql, int qr) {
        if (l >= qr || r <= ql) return Info();
        if (ql <= l && r <= qr) return nd[t].info;
        int m = (l + r) / 2;
        return query(nd[t].lc, l, m, ql, qr) + query(nd[t].rc, m, r, ql, qr);
    }
    Info query(int ver, int ql, int qr) {
        return query(rt[ver], 0, n, ql, qr);
    }
    void createVersion(int ori_ver) {
        rt.push_back(copy(rt[ori_ver]));
    }
    void reserve(int n, int q) {
        nd.reserve(n + q * (2 * __lg(n) + 1));
        rt.reserve(q + 1);
    }
    void resize(int n) { rt.resize(n); }
};
struct Info {
    ll sum = 0;
};
Info operator+(const Info &a, const Info &b) {
    return { a.sum + b.sum };
}

```

3.3 Static Kth-element [d41d8c]

```

template<class T>
struct StaticKth : PST<int> {
    int dct(T x) {
        return lower_bound(s.begin(), s.end(), x) - s.begin();
    }
    vector<T> v, s; // array, sorted
    map<T, int> cnt;
    StaticKth(const vector<T> &v_) {
        s = v = v_;
        sort(s.begin(), s.end());
        s.resize(unique(s.begin(), s.end()) - s.begin());
        init(s.size());
        for (int i = 0; i < v.size(); i++) {
            createVersion(i);
            int d = dct(v[i]);
            modify(i + 1, d, ++cnt[d]);
        }
    }
    int work(int a, int b, int l, int r, int k) {
        if (r - l == 1) return l;
        int x = nd[nd[b].lc].info - nd[nd[a].lc].info;
        int m = (l + r) / 2;
        if (x >= k) {
            return work(nd[a].lc, nd[b].lc, l, m, k);
        } else {
            return work(nd[a].rc, nd[b].rc, m, r, k - x);
        }
    }
};

```

```

    }
}
int work(int l, int r, int k) { // [l, r), k > 0
    return s[work(rt[l], rt[r], 0, n, k)];
}
};

```

3.4 Dynamic Kth-element [d41d8c]

```

// Fenwick(rt-indexed) 包線段樹
template<class T>
struct DynamicKth : PST<int> {
    int dct(T x) {
        return lower_bound(s.begin(), s.end(), x) - s.begin();
    }
    vector<T> v, s; // array, sorted
    DynamicKth(const vector<T> &v_, const vector<T> &s_)
        : PST<int>(vector<int>(s_.size(), 0)) {
        assert(!s_.sorted(s_.begin(), s_.end()));
        v = v_, s = s_;
        rt.resize(v.size());
        for (int i = 0; i < v.size(); i++) add(i, dct(v[i]), 1);
    }
    int modify(int t, int l, int r, int x, int v) {
        t = t ? t : generate();
        if (r - l == 1) {
            nd[t].info += v;
            return t;
        }
        int m = (l + r) / 2;
        if (x < m) {
            nd[t].lc = modify(nd[t].lc, l, m, x, v);
        } else {
            nd[t].rc = modify(nd[t].rc, m, r, x, v);
        }
        pull(nd[t]);
        return t;
    }
    void add(int p, int x, int val) {
        for (int i = p + 1; i <= rt.size(); i += i & -i)
            rt[i - 1] = modify(rt[i - 1], 0, s.size(), x, val);
    }
    void modify(int p, int y) {
        add(p, dct(v[p]), -1);
        v[p] = y;
        add(p, dct(v[p]), 1);
    }
    int work(
        vector<int> &a, vector<int> &b, int l, int r, int k) {
        if (r - l == 1) return l;
        int m = (l + r) / 2;
        int res = 0;
        for (auto x : a) res -= nd[nd[x].lc].info;
        for (auto x : b) res += nd[nd[x].lc].info;
        if (res >= k) {
            for (auto &x : a) x = nd[x].lc;
            for (auto &x : b) x = nd[x].lc;
            return work(a, b, l, m, k);
        } else {
            for (auto &x : a) x = nd[x].rc;
            for (auto &x : b) x = nd[x].rc;
            return work(a, b, m, r, k - res);
        }
    }
    int work(int l, int r, int k) { // [l, r), k > 0
        vector<int> a, b;
        for (int i = l; i > 0; i -= i & -i)
            a.push_back(rt[i - 1]);
        for (int i = r; i > 0; i -= i & -i)
            b.push_back(rt[i - 1]);
        return s[work(a, b, 0, s.size(), k)];
    }
};

```

3.5 Fenwick [d41d8c]

```

template<class T>
struct Fenwick {
    int n; vector<T> a;
    Fenwick(int n) : n(n), a(n) {}
    void add(int x, const T &v) {
        for (int i = x + 1; i <= n; i += i & -i)
            a[i - 1] = a[i - 1] + v;
    }
    T sum(int x) {
        T ans{};
        for (int i = x; i > 0; i -= i & -i)
            ans = ans + a[i - 1];
        return ans;
    }
    T rangeSum(int l, int r) {
        return sum(r) - sum(l);
    }
    int select(const T &k, int start = 0) {
        // 找到最小的 x, 使得 sum(x + 1) - sum(start) > k
        int x = 0; T cur = -sum(start);
        for (int i = 1 <= __lg(n); i /= 2) {
            if (x + i <= n && cur + a[x + i - 1] <= k) {
                x += i;
                cur = cur + a[x - 1];
            }
        }
    }
};

```

```

    }
    return x;
}
};
template<class T>
struct TwoDFenwick {
    int nx, ny; // row, col 個數
    vector<vector<T>> a;
    TwoDFenwick(int nx, int ny) : nx(nx), ny(ny) {
        a.assign(nx, vector<T>(ny, T{}));
    }
    void add(int x, int y, const T &v) {
        for (int i = x + 1; i <= nx; i += i & -i)
            for (int j = y + 1; j <= ny; j += j & -j)
                a[i - 1][j - 1] = a[i - 1][j - 1] + v;
    }
    T sum(int x, int y) {
        T ans{};
        for (int i = x; i > 0; i -= i & -i)
            for (int j = y; j > 0; j -= j & -j)
                ans = ans + a[i - 1][j - 1];
        return ans;
    }
    T rangeSum(int lx, int ly, int rx, int ry) {
        return sum(
            rx, ry) - sum(lx, ry) - sum(rx, ly) + sum(lx, ly);
    }
};

```

3.6 Range Fenwick [d41d8c]

```

template<class T>
struct RangeFenwick { // 全部以 0 based 使用
    int n;
    vector<T> d, di;
    RangeFenwick(int n) : n(n), d(n), di(n) {}
    void add(int x, const T &v) {
        T vi = v * (x + 1);
        for (int i = x + 1; i <= n; i += i & -i) {
            d[i - 1] = d[i - 1] + v;
            di[i - 1] = di[i - 1] + vi;
        }
    }
    void rangeAdd(int l, int r, const T &v) {
        add(l, v); add(r, -v);
    }
    T sum(int x) { // 左閉右開查詢
        T ans{};
        for (int i = x; i > 0; i -= i & -i) {
            ans = ans + T(x + 1) * d[i - 1];
            ans = ans - di[i - 1];
        }
        return ans;
    }
    T rangeSum(int l, int r) { // 左閉右開查詢
        return sum(r) - sum(l);
    }
    int select(const T &k, int start = 0) {
        // 找到最小的 x, 使得 sum(x + 1) - sum(start) > k
        int x = 0; T cur = -sum(start);
        for (int i = 1 <= __lg(n); i /= 2) {
            if (x + i <= n) {
                T val = T(
                    x + i + 1) * d[x + i - 1] - di[x + i - 1];
                if (cur + val <= k) {
                    x += i;
                    cur = cur + val;
                }
            }
        }
        return x;
    }
};

```

```

};
template<class T>
struct RangeTwoDFenwick { // 全部以 0 based 使用
    int nx, ny; // row, col 個數
    vector<vector<T>> d, di, dj, dij;
    RangeTwoDFenwick(int x, int y) : nx(x), ny(y) {
        d.assign(nx, vector<T>(ny, T{}));
        di.assign(nx, vector<T>(ny, T{}));
        dj.assign(nx, vector<T>(ny, T{}));
        dij.assign(nx, vector<T>(ny, T{}));
    }
    void add(int x, int y, const T &v) {
        T vi = v * (x + 1);
        T vj = v * (y + 1);
        T vij = v * (x + 1) * (y + 1);
        for (int i = x + 1; i <= nx; i += i & -i) {
            for (int j = y + 1; j <= ny; j += j & -j) {
                d[i - 1][j - 1] = d[i - 1][j - 1] + v;
                di[i - 1][j - 1] = di[i - 1][j - 1] + vi;
                dj[i - 1][j - 1] = dj[i - 1][j - 1] + vj;
                dij[i - 1][j - 1] = dij[i - 1][j - 1] + vij;
            }
        }
    }
    void rangeAdd(int lx, int ly, int rx, int ry, const T &v) {
        add(rx, ry, v);
        add(lx, ry, -v);
        add(rx, ly, -v);
        add(lx, ly, v);
    }
};

```



```

}
T sum(int x, int y) { // 左開右開查詢
    T ans{};
    for (int i = x; i > 0; i -= i & -i) {
        for (int j = y; j > 0; j -= j & -j) {
            ans = ans
                + T(x * y + x + y + 1) * d[i - 1][j - 1];
            ans = ans - T(y + 1) * di[i - 1][j - 1];
            ans = ans - T(x + 1) * dj[i - 1][j - 1];
            ans = ans + dij[i - 1][j - 1];
        }
    }
    return ans;
}
T rangeSum
    (int lx, int ly, int rx, int ry) { // 左開右開查詢
    return sum(
        rx, ry) - sum(lx, ry) - sum(rx, ly) + sum(lx, ly);
}
};

```

3.7 KDTree [d41d8c]

```

template<class Info>
struct KDTree {
    static constexpr int DIM = Info::DIM;
    vector<Info> info;
    vector<int> rt, l, r, p;
    int n = 0, lg;
    KDTree(int n) : info(1), lg(__lg(n)), l(n + 1), r(n + 1) {
        rt.resize(lg + 1);
    }
    void pull(int p) {
        info[p].L = info[p].R = info[p].x;
        info[p].pull(info[l[p]], info[r[p]]);
        for (int ch : {l[p], r[p]}) {
            if (!ch) continue;
            for (int k = 0; k < DIM; k++) {
                info[p]
                    .L[k] = min(info[p].L[k], info[ch].L[k]);
                info[p]
                    .R[k] = max(info[p].R[k], info[ch].R[k]);
            }
        }
    }
    int rebuild(int l, int r, int dep = 0) {
        if (r == l) return 0;
        int m = (l + r) / 2;
        nth_element
            (p.begin() + l, p.begin() + m, p.begin() + r,
             [&](int x, int y) {
                 { return info[x].x[dep] < info[y].x[dep]; });
        int x = p[m];
        this->l[x] = rebuild(l, m, (dep + 1) % DIM);
        this->r[x] = rebuild(m + 1, r, (dep + 1) % DIM);
        pull(x);
        return x;
    }
    void append(int &x) {
        if (!x) return;
        p.push_back(x);
        append(l[x]);
        append(r[x]);
        x = 0;
    }
    void addNode(const Info &i) {
        p.assign(1, info.size());
        info.push_back(i);
        for (int j = 0; j++; j++) {
            if (!rt[j]) {
                rt[j] = rebuild(0, p.size());
                break;
            } else {
                append(rt[j]);
            }
        }
    }
    Info query(int p,
        const array<int, DIM> &l, const array<int, DIM> &r) {
        if (!p) return Info();
        bool inside = true;
        for (int k = 0; k < DIM; k++) {
            inside &= (
                l[k] <= info[p].L[k] && info[p].R[k] <= r[k]);
        }
        if (inside) return info[p];
        for (int k = 0; k < DIM; k++) {
            if (info[p].R[k] < l[k] || r[k] < info[p].L[k]) {
                return Info();
            }
        }
        Info ans;
        inside = true;
        for (int k = 0; k < DIM; k++) {
            inside &= (
                l[k] <= info[p].x[k] && info[p].x[k] <= r[k];
            )
        }
        if (inside) ans = info[p];
        ans.pull(
            query(this->l[p], l, r), query(this->r[p], l, r));
        return ans;
    }
};

```

```

Info query
    (const array<int, DIM> &l, const array<int, DIM> &r) {
    Info res;
    for (int i = 0; i <= lg; i++) {
        res.pull(res, query(rt[i], l, r));
    }
    return res;
}
};
struct Info {
    static constexpr int DIM = 2;
    array<int, DIM> x, l, r;
    int v = 0, sum = 0;
    void pull(const Info &l, const Info &r) {
        sum = v + l.sum + r.sum;
    }
};

```

3.8 Treap [d41d8c]

```

template<class Info, class Tag = bool>
struct Treap { // 0 -> initial root
    vector<Info> info;
    // vector<Tag> tag;
    vector<int> siz, par, rev, pri;
    vector<array<int, 2>> ch;
    Treap(int n) : info(n + 1), siz(n
        + 1), par(n + 1), rev(n + 1), pri(n + 1), ch(n + 1) {
        // tag.resize(n + 1);
        for (int i = 1; i <= n; i++)
            siz[i] = 1, pri[i] = rand();
    }
    // void apply(int t, const Tag &v) {
    //     info[t].apply(siz[t], v);
    //     tag[t].apply(v);
    // }
    void push(int t) {
        if (rev[t]) {
            swap(ch[t][0], ch[t][1]);
            if (ch[t][0]) rev[ch[t][0]] ^= 1;
            if (ch[t][1]) rev[ch[t][1]] ^= 1;
            rev[t] = 0;
        }
        // apply(ch[t][0], tag[t]);
        // apply(ch[t][1], tag[t]);
        // tag[t] = Tag();
    }
    void pull(int t) {
        siz[t] = 1 + siz[ch[t][0]] + siz[ch[t][1]];
        info[t].pull(info[ch[t][0]], info[ch[t][1]]);
    }
    int merge(int a, int b) {
        if (!a || !b) return a ? a : b;
        push(a), push(b);
        if (pri[a] > pri[b]) {
            ch[a][1] = merge(ch[a][1], b);
            pull(a); return a;
        } else {
            ch[b][0] = merge(a, ch[b][0]);
            pull(b); return b;
        }
    }
    pair<int, int> split(int t, int k) {
        if (!t) return {0, 0};
        push(t);
        if (siz[ch[t][0]] >= k) {
            auto [a, b] = split(ch[t][0], k);
            ch[t][0] = b, pull(t);
            return {a, t};
        } else {
            auto [a
                , b] = split(ch[t][1], k - siz[ch[t][0]] - 1);
            ch[t][1] = a, pull(t);
            return {t, b};
        }
    }
};
template<class F> // 尋找區間內，第一個符合條件的
int findFirst(int t, F &&pred) {
    if (!t) return 0;
    push(t);
    if (!pred(info[t])) return 0;
    int idx = findFirst(ch[t][0], pred);
    if (!idx) idx
        = 1 + siz[ch[t][0]] + findFirst(ch[t][1], pred);
    return idx;
}
int getPos(int rt, int t) { // get t's index in array
    int res = siz[t] + 1;
    while (t != rt) {
        int p = par[t];
        if (ch[p][1] == t) res += siz[ch[p][0]] + 1;
        t = p;
    }
    return res;
}
void getArray(int t, vector<Info> &a) {
    if (!t) return;
    push(t);
    getArray(ch[t][0], a);
    a.push_back(info[t]);
    getArray(ch[t][1], a);
}

```

```

};
struct Tag {
    int setVal; ll add;
    void apply(const Tag &t) {
        if (t.setVal) {
            setVal = t.setVal;
            add = t.add;
        } else {
            add += t.add;
        }
    }
};
struct Info {
    ll val, sum;
    void apply(int siz, const Tag &t) {
        if (t.setVal) {
            val = t.setVal;
            sum = 1LL * siz * t.setVal;
        }
        val += t.add;
        sum += 1LL * siz * t.add;
    }
    void pull(const Info &l, const Info &r) {
        sum = val + l.sum + r.sum;
    }
};

```

3.9 RMQ [d41d8c]

```

template<class T, class F = less<T>>
struct RMQ { // [l, r]
    int n;
    F cmp = F();
    vector<vector<T>> g;
    RMQ() {}
    RMQ(const vector<T> &a, F cmp = F()) : cmp(cmp) {
        init(a);
    }
    void init(const vector<T> &a) {
        n = a.size();
        int lg = __lg(n);
        g.resize(lg + 1);
        g[0] = a;
        for (int j = 1; j <= lg; j++) {
            g[j].resize(n - (1 << j) + 1);
            for (int i = 0; i <= n - (1 << j); i++)
                g[j][i] = min(g[j - 1][i], g[j - 1][i + (1 << (j - 1))], cmp);
        }
    }
    T operator()(int l, int r) {
        assert(0 <= l && l < r && r <= n);
        int lg = __lg(r - l);
        return min(g[lg][l], g[lg][r - (1 << lg)], cmp);
    }
};

```

3.10 Mo [d41d8c]

```

struct Query { int id, l, r; };
void mo(vector<Query> &q) {
    int blk = sqrt(q.size());
    sort(q.begin(), q.end(), [&](const Query &a, const Query &b) {
        int x = a.l / blk, y = b.l / blk;
        return x == y ? a.r < b.r : x < y;
    });
    int nl = 0, nr = -1;
    for (auto [id, l, r] : q) {
        while (nr < r) nr++, addR();
        while (l < nl) nl--, addL();
        while (r < nr) delR(), nr--;
        while (nl < l) delL(), nl++;
    }
}

```

4 Flow Matching

4.1 Dinic [d41d8c]

```

template<class T>
struct Dinic {
    struct Edge {
        int to;
        T f, cap; // 流量跟容量
    };
    int n, m, s, t;
    const T INF_FLOW = numeric_limits<T>::max();
    vector<vector<int>> g;
    vector<Edge> e;
    vector<int> h, cur;
    Dinic(int n) : n(n), m(0), g(n), h(n), cur(n) {}
    void addEdge(int u, int v, T cap) {
        e.push_back({v, 0, cap});
        e.push_back({u, 0, 0});
        g[u].push_back(m++);
        g[v].push_back(m++);
    }
    bool bfs() {
        fill(h.begin(), h.end(), -1);
        h[s] = 0; queue<int> q;
    }
};

```

```

q.push(s);
while (!q.empty()) {
    int u = q.front(); q.pop();
    for (int id : g[u]) {
        auto [v, f, cap] = e[id];
        if (f == cap) continue;
        if (h[v] == -1) {
            h[v] = h[u] + 1;
            if (v == t) return true;
            q.push(v);
        }
    }
    return false;
}
T dfs(int u, T flow) {
    if (flow == 0) return 0;
    if (u == t) return flow;
    for (int &i = cur[u]; i < g[u].size(); i++) {
        int j = g[u][i];
        auto [v, f, cap] = e[j];
        if (h[u] + 1 != h[v]) continue;
        if (f == cap) continue;
        T mn = dfs(v, min(flow, cap - f));
        if (mn > 0) {
            e[j].f += mn;
            e[j ^ 1].f -= mn;
            return mn;
        }
    }
    return 0;
}
T work(int s_, int t_) {
    s = s_; t = t_; T f = 0;
    while (bfs()) {
        fill(cur.begin(), cur.end(), 0);
        while (true) {
            T res = dfs(s, INF_FLOW);
            if (res == 0) break;
            f += res;
        }
    }
    return f;
}
void reuse(int n_) { // 走殘留網路, res += f
    while (n < n_) {
        g.emplace_back();
        h.emplace_back();
        cur.emplace_back();
        n += 1;
    }
}
};

```

4.2 Min Cut [d41d8c]

```

void minCut(int n, int m, Dinic<int> d) {
    int ans = d.work(0, n - 1);
    vector<int> vis(n);
    auto dfs = [&](auto self, int u) -> void {
        if (vis[u]) continue;
        vis[u] = 1;
        for (int id : d.g[u]) {
            auto [to, f, cap] = d.e[id];
            if (cap - f > 0) self(self, to);
        }
    };
    dfs(dfs, 0);
    for (int i = 0; i < n; i++) {
        if (!vis[i]) continue;
        for (int id : d.g[i]) {
            if (id & 1) continue;
            auto e = d.e[id];
            if (!vis[e.to])
                cout << i + 1 << " " << e.to + 1 << " | n";
        }
    }
}

```

4.3 MCMF [d41d8c]

```

template<class Tf, class Tc>
struct MCMF {
    struct _Edge {
        int to;
        Tf f, cap; // 流量跟容量
        Tc cost;
    };
    int n, m, s, t;
    const Tf INF_FLOW = numeric_limits<Tf>::max();
    const Tc INF_COST = numeric_limits<Tc>::max();
    vector<_Edge> e;
    vector<vector<int>> g;
    vector<Tc> dis;
    vector<int> rt, inq;
    MCMF(int n) : n(n), m(0), g(n) {}
    void addEdge(int u, int v, Tf cap, Tc cost) {
        e.push_back({v, 0, cap, cost});
        e.push_back({u, 0, 0, -cost});
        g[u].push_back(m++);
        g[v].push_back(m++);
    }
};

```



```

bool spfa() {
    dis.assign(n, INF_COST);
    rt.assign(n, -1); inq.assign(n, 0);
    queue<int> q; q.push(s);
    dis[s] = 0;
    while (!q.empty()) {
        int u = q.front(); q.pop();
        inq[u] = 0;
        for (int id : g[u]) {
            auto [v, f, cap, cost] = e[id];
            Tc ndis = dis[u] + cost;
            if (f < cap && dis[v] > ndis) {
                dis[v] = ndis; rt[v] = id;
                if (!inq[v])
                    q.push(v), inq[v] = 1;
            }
        }
    }
    return dis[t] != INF_COST;
}

// 限定 flow, 最小化 cost
pair<Tf, Tc> workFlow(int s_, int t_, Tf need) {
    s = s_, t = t_;
    Tf flow{}; Tc cost{};
    while (spfa()) {
        Tf f = need;
        for (int i = t; i != s; i = e[rt[i] ^ 1].to)
            f = min(f, e[rt[i]].cap - e[rt[i]].f);
        for (int i = t; i != s; i = e[rt[i] ^ 1].to)
            e[rt[i]].f += f, e[rt[i] ^ 1].f -= f;
        flow += f, need -= f;
        cost += f * dis[t];
        if (need == 0) break;
    }
    return {flow, cost};
}

// 限定 cost, 最大化 flow
pair<Tf, Tc> workBudget(int s_, int t_, Tc budget) {
    s = s_, t = t_;
    Tf flow{}; Tc cost{};
    while (spfa()) {
        Tf f = budget / dis[t];
        for (int i = t; i != s; i = e[rt[i] ^ 1].to)
            f = min(f, e[rt[i]].cap - e[rt[i]].f);
        for (int i = t; i != s; i = e[rt[i] ^ 1].to)
            e[rt[i]].f += f, e[rt[i] ^ 1].f -= f;
        flow += f, budget -= f * dis[t];
        cost += f * dis[t];
        if (budget == 0 || f == 0) break;
    }
    return {flow, cost};
}

void reset() {
    for (int i = 0; i < m; i++) e[i].f = 0;
}
};

```

4.4 Hungarian [d41d8c]

```

struct Hungarian { // 0-based, O(VE)
    int n, m;
    vector<vector<int>> adj;
    vector<int> used, vis;
    vector<pair<int, int>> match;
    Hungarian(int n, int m) : n(n), m(m) {
        adj.assign(n + m, {});
        used.assign(n + m, -1);
        vis.assign(n + m, 0);
    }
    void addEdge(int u, int v) {
        adj[u].push_back(n + v);
        adj[n + v].push_back(u);
    }
    bool dfs(int u) {
        int sz = adj[u].size();
        for (int i = 0; i < sz; i++) {
            int v = adj[u][i];
            if (vis[v] == 0) {
                vis[v] = 1;
                if (used[v] == -1 || dfs(used[v])) {
                    used[v] = u;
                    return true;
                }
            }
        }
        return false;
    }
    vector<pair<int, int>> work() {
        match.clear();
        used.assign(n + m, -1);
        vis.assign(n + m, 0);
        for (int i = 0; i < n; i++) {
            fill(vis.begin(), vis.end(), 0);
            dfs(i);
        }
        for (int i = n; i < n + m; i++)
            if (used[i] != -1)
                match.emplace_back(used[i], i - n);
        return match;
    }
};

```

4.5 Theorem [d41d8c]

```

// 有向無環圖：
// 最小不相交路徑覆蓋：
// 最小路徑數 = 頂點數 - 最大匹配數
// 最小相交路徑覆蓋：
// 先用
//      Floyd 求傳遞封包，有連邊就建邊，然後再套最小不相交路徑覆蓋
// 二分圖：
// 最小點
//      覆蓋：選出一些點，讓所有邊至少有一個端點在點集中的最少數量
// 最小點覆蓋 = 最大匹配數
// 還原解，flow 的作法是從源點開始 dfs，只走 cap - flow > 0
// 的邊，最後挑選左邊還沒被跑過的點和右邊被跑過的點當作覆蓋的點
// 最少邊覆蓋：選出一些邊，讓所有點都覆蓋到的最少數量
// 最少邊覆蓋 = 點數 - 最大匹配數
// 最大獨立集：選出一些點，使這些點兩兩沒有邊連接的最大數量
// 最大獨立集 = 點數 - 最大匹配數

```

5 String

5.1 Hash [234076]

```

const int D = 59;
vector<int> rollingHash(string &s) {
    vector<int> a {0};
    for (auto c : s)
        a.push_back(mul(a.back(), D) + (c - 'A' + 1));
    return a;
}

int qryHash(vector<int> &h, int l, int r) { // [l, r)
    return sub(h[r], mul(h[l], power(D, r - l)));
}

```

5.2 KMP [e3717b]

```

struct KMP {
    string sub;
    vector<int> fail;
    // fail 存匹配失敗時，移去哪
    // 也就是 sub(0, i) 的最長共同前後綴長度
    // ex : a b c a b c
    //      -1 -1 -1 0 1 2
    KMP(const string &sub_) { build(sub_); }
    vector<int> build(const string &sub_) {
        sub = sub_, fail.resize(sub.size(), -1);
        for (int i = 1; i < sub.size(); i++) {
            int now = fail[i - 1];
            while (now != -1 && sub[now + 1] != sub[i])
                now = fail[now];
            if (sub[now + 1] == sub[i])
                fail[i] = now + 1;
        }
        return fail;
    }
    vector<int> match(const string &s) {
        vector<int> match;
        for (int i = 0, now = -1; i < s.size(); i++) {
            while (s[i] != sub[now + 1] && now != -1)
                now = fail[now];
            if (s[i] == sub[now + 1]) now++;
            if (now + 1 == sub.size()) {
                match.push_back(i - now);
                now = fail[now];
            }
        }
        return match;
    }
};

```

5.3 Z Function [5b63dc]

```

// z[i] 表示 s 和 s[i, n - 1] (以 s[i] 開頭的后綴)
// 的最長公共前綴 (LCP) 的長度
vector<int> Z(const string &s) {
    int n = s.size();
    vector<int> z(n);
    z[0] = n; // lcp(s, s), -1 or n
    for (int i = 1, j = 1; i < n; i++) {
        z[i] = max(0, min(j + z[j] - i, z[i - j]));
        while (i + z[i] < n && s[z[i]] == s[i + z[i]]) z[i]++;
        if (i + z[i] > j + z[j]) j = i;
    }
    return z;
}

```

5.4 Manacher [1eb30d]

```

// 找到對於每個位置的迴文半徑
vector<int> manacher(const string &s) {
    string t = "#";
    for (auto c : s) t = t + c + '#';
    int n = t.size();
    vector<int> r(n);
    for (int i = 0,
        j = 0; i < n; i++) { // i 是中心, j 是最長回文字串中心
        if (2 * j - i >= 0 && j + r[j] > i)

```

```

    r[i] = min(r[2 * j - i], j + r[j] - i);
    while (i - r[i] >=
        0 && i + r[i] < n && t[i - r[i]] == t[i + r[i]])
        r[i] += 1;
    if (i + r[i] > j + r[j]) j = i;
}
return r;
}
// # a # b # a #
// 1 2 1 4 1 2 1
// # a # b # b # a #
// 1 2 1 2 5 2 1 2 1
// 值 -1 代表原回文字串長度
// (id - val + 1) / 2 可得原字串回文開頭

```

5.5 Trie [6c7186]

```

const int N = 1E7; // 0 -> initial state
const int ALPHABET_SIZE = 26;
int tot = 0;
int trie[N][ALPHABET_SIZE], cnt[N];
void reset() {
    tot = 0, fill_n(trie[0], ALPHABET_SIZE, 0);
}
int newNode() {
    int x = ++tot;
    cnt[x] = 0, fill_n(trie[x], ALPHABET_SIZE, 0);
    return x;
}
void add(const string &s) {
    int p = 0;
    for (auto c : s) {
        int &q = trie[p][c - 'a'];
        if (!q) q = newNode();
        p = q;
    }
    cnt[p] += 1;
}
int find(const string &s) {
    int p = 0;
    for (auto c : s) {
        int q = trie[p][c - 'a'];
        if (!q) return 0;
        p = q;
    }
    return cnt[p];
}

```

5.6 SA [b04578]

```

struct SuffixArray {
    int n;
    vector<int> sa, rk, lc;
    // n: 字串長度
    // sa: 後綴數組, sa[i] 表示第 i 小的後綴的起始位置
    // rk: 排名數組, rk[i] 表示從位置 i 開始的後綴的排名
    // lc: LCP
    // 數組, lc[i] 表示 sa[i] 和 sa[i + 1] 的最長公共前綴長度
    SuffixArray(const string &s) {
        n = s.length();
        sa.resize(n);
        lc.resize(n - 1);
        rk.resize(n);
        iota(sa.begin(), sa.end(), 0);
        sort(sa.begin(), sa.end(), [&](int a, int b) { return s[a] < s[b]; });
        rk[sa[0]] = 0;
        for (int i = 1; i < n; i++)
            rk[sa[i]] = rk[sa[i - 1]] + (s[sa[i]] != s[sa[i - 1]]);
        int k = 1;
        vector<int> tmp, cnt(n);
        tmp.reserve(n);
        while (rk[sa[n - 1]] < n - 1) {
            tmp.clear();
            for (int i = 0; i < k; i++) tmp.push_back(n - k + i);
            for (auto i : sa) if (i >= k) tmp.push_back(i - k);
            fill(cnt.begin(), cnt.end(), 0);
            for (int i = 0; i < n; i++) cnt[rk[i]]++;
            for (int i = 1; i < n; i++) cnt[i] += cnt[i - 1];
            for (int i = n - 1; i >= 0; i--) sa[--cnt[rk[tmp[i]]]] = tmp[i];
            swap(rk, tmp); rk[sa[0]] = 0;
            for (int i = 1; i < n; i++) rk[sa[i]] = rk[sa[i - 1]] +
                (tmp[sa[i - 1]] < tmp[sa[i]] || sa[i - 1] + k
                 == n || tmp[sa[i - 1] + k] < tmp[sa[i] + k]);
            k *= 2;
        }
        for (int i = 0, j = 0; i < n; i++) {
            if (rk[i] == 0) {
                j = 0;
            } else {
                for (j -=
                    j > 0; i + j < n && sa[rk[i] - 1] + j < n
                    && s[i + j] == s[sa[rk[i] - 1] + j]; j++);
                lc[rk[i] - 1] = j;
            }
        }
    }
}

```

```

};
RMQ<int> rmq(sa.lc);
auto lcp = [&](int i, int j) { // [i, j]
    i = sa.rk[i], j = sa.rk[j];
    if (i > j) swap(i, j);
    assert(i != j);
    return rmq(i, j);
};

```

5.7 SAM [50a2d0]

```

struct SAM {
    // 0 -> initial state
    static constexpr int ALPHABET_SIZE = 26;
    // node -> strings with the same endpos set
    // link -> longest suffix with different endpos set
    // len -> state's longest suffix
    // fpos -> first endpos
    // strlen range -> [len(link) + 1, len]
    struct Node {
        int len, link = -1, fpos;
        array<int, ALPHABET_SIZE> next;
    };
    vector<Node> t;
    SAM() : t(1) {}
    int newNode() {
        t.emplace_back();
        return t.size() - 1;
    }
    int extend(int p, int c) {
        int cur = newNode();
        t[cur].len = t[p].len + 1;
        t[cur].fpos = t[cur].len - 1;
        while (p != -1 && !t[p].next[c]) {
            t[p].next[c] = cur;
            p = t[p].link;
        }
        if (p == -1) {
            t[cur].link = 0;
        } else {
            int q = t[p].next[c];
            if (t[p].len + 1 == t[q].len) {
                t[cur].link = q;
            } else {
                int r = newNode();
                t[r].len = t[q].len;
                t[r].link = t[p].len + 1;
                while (p != -1 && t[p].next[c] == q) {
                    t[p].next[c] = r;
                    p = t[p].link;
                }
                t[q].link = t[cur].link = r;
            }
        }
        return cur;
    }
};

void solve(int n, string s, ll k) { // Substring Order II
    vector<int> last(n + 1);
    SAM sam;
    for (int i = 0; i < n; i++)
        last[i + 1] = sam.extend(last[i], s[i] - 'a');
    int sz = sam.t.size();

    vector<int> cnt(sz); // endpos size
    for (int i = 1; i <= n; i++) cnt[last[i]]++;
    vector<vector<int>> g(sz);
    for (int i = 1; i < sz; i++)
        g[sam.t[i].link].push_back(i);
    auto dfs = [&](auto self, int u) -> void {
        for (auto v : g[u])
            self(self, v), cnt[u] += cnt[v];
    }; dfs(dfs, 0);

    vector<ll> dp(sz, -1);
    // for any path from root
    // , how many substring's prefix is the the path string
    auto rec = [&](auto self, int u) -> ll {
        if (dp[u] != -1) return dp[u];
        dp[u] = cnt[u]; // distinct = 1
        for (int c = 0; c < SAM::ALPHABET_SIZE; c++) {
            int v = sam.t[u].next[c];
            if (v) dp[u] += self(self, v);
        }
        return dp[u];
    };
    rec(rec, 0);

    int p = 0; string ans;
    while (k > 0) { // 1-based
        for (int c = 0; c < SAM::ALPHABET_SIZE; c++) {
            int v = sam.t[p].next[c];
            if (v) {
                if (k > dp[v]) {
                    k -= dp[v];
                } else {
                    ans.push_back('a' + c);
                    k -= cnt[v]; // distinct: --
                    p = v; break;
                }
            }
        }
    }
}

```

```
    } cout << ans << "\n";
}
```

5.8 Palindrome Tree [e5a1ed]

```
struct PAM {
    // 0 -> even root, 1 -> odd root
    static constexpr int ALPHABET_SIZE = 26;
    // fail -> longest prefix(suffix) palindrome
    // number end at i = end at link[last[i]] + 1
    struct Node {
        int len, fail, cnt;
        array<int, ALPHABET_SIZE> next;
        Node() : len{}, fail{}, next{} {}
    };
    vector<int> s;
    vector<Node> t;
    PAM() {
        t.assign(2, Node());
        t[0].len = 0, t[0].fail = 1;
        t[1].len = -1;
    }
    int newNode() {
        t.emplace_back();
        return t.size() - 1;
    }
    int getFail(int p, int i) {
        while (i - t[p].len < 1 || s[i - t[p].len - 1] != s[i])
            p = t[p].fail;
        return p;
    }
    int extend(int p, int c) {
        int i = s.size();
        s.push_back(c);
        p = getFail(p, i);
        if (!t[p].next[c]) {
            int r = newNode();
            int v = getFail(t[p].fail, i);
            t[r].len = t[p].len + 2;
            t[r].fail = t[v].next[c];
            t[p].next[c] = r;
        }
        return p = t[p].next[c];
    }
};

void solve() {
    string s; cin >> s;
    int n = s.length();
    vector<int> last(n + 1);
    last[0] = 1;
    PAM pam;
    for (int i = 0; i < n; i++)
        last[i + 1] = pam.extend(last[i], s[i] - 'a');
    int sz = pam.t.size();
    vector<int> cnt(sz);
    for (int i = 1; i <= n; i++)
        cnt[last[i]]++; // 去重 = 1
    for (int i = sz - 1; i > 1; i--)
        cnt[pam.t[i].fail] += cnt[i];
}
```

5.9 Duval [aed467]

```
// duval_algorithm
// 將字串分解成若干個非嚴格遞減的非嚴格遞增字串
vector<string> duval(string s) {
    int i = 0, n = s.size();
    vector<string> res;
    while (i < n) {
        int k = i, j = i + 1;
        while (s[k] <= s[j] && j < n) {
            if (s[k] < s[j]) k = i;
            else k++;
            j++;
        }
        while (i <= k) {
            res.push_back(s.substr(i, j - k));
            i += j - k;
        }
    }
    return res;
}

// 最小旋轉字串
string minRound(string s) {
    s += s;
    int i = 0, n = s.size(), start = i;
    while (i < n / 2) {
        start = i;
        int k = i, j = i + 1;
        while (s[k] <= s[j] && j < n) {
            if (s[k] < s[j]) k = i;
            else k++;
            j++;
        }
        while (i <= k) i += j - k;
    }
    return s.substr(start, n / 2);
}
```

6 Math

6.1 Mint [5e2f37]

```
ll mul(ll a, ll b, ll p) {
    ll res = a * b - ll(1.L * a * b / p) * p;
    res %= p;
    if (res < 0) res += p;
    return res;
}

// 改 MLong: getMod() < (1ULL << 31), 會爆用 mul
template<class T>
constexpr T power(T a, ll b) {
    T res {1};
    for (; b > 0; b >= 1, a *= a)
        if (b & 1) res *= a;
    return res;
}

template<int P>
struct Mint {
    // Dynamic Mint, not necessary
    static int Mod;
    static int getMod() {
        return P > 0 ? P : Mod;
    }
    static void setMod(int Mod_) {
        Mod = Mod_;
    }

    ll x;
    Mint(ll x = 0) : x {norm(x % getMod())} {}
    ll norm(ll x) const {
        if (x < 0) x += getMod();
        if (x >= getMod()) x -= getMod();
        return x;
    }
    explicit operator int() const { return x; }
    Mint operator-() const {
        return Mint(norm(getMod() - x));
    }
    Mint inv() const {
        return power(*this, getMod() - 2);
    }
    Mint &operator+=(Mint rhs) & {
        x = norm(x + rhs.x);
        return *this;
    }
    Mint &operator-=(Mint rhs) & {
        x = norm(x - rhs.x);
        return *this;
    }
    Mint &operator*=(Mint rhs) & {
        x = x * rhs.x % getMod();
        return *this;
    }
    Mint &operator/=(Mint rhs) & {
        return *this *= rhs.inv();
    }
    friend Mint operator+(Mint lhs, Mint rhs) {
        return lhs += rhs;
    }
    friend Mint operator-(Mint lhs, Mint rhs) {
        return lhs -= rhs;
    }
    friend Mint operator*(Mint lhs, Mint rhs) {
        return lhs *= rhs;
    }
    friend Mint operator/(Mint lhs, Mint rhs) {
        return lhs /= rhs;
    }
    friend istream &operator>>(istream &is, Mint &a) {
        ll v; is >> v; a = Mint(v); return is;
    }
    friend ostream &operator<<(ostream &os, const Mint &a) {
        return os << a.x;
    }
    // following operators are not necessary
    friend bool operator==(Mint lhs, Mint rhs) {
        return lhs.x == rhs.x;
    }
    friend bool operator!=(Mint lhs, Mint rhs) {
        return lhs.x != rhs.x;
    }
    friend bool operator<(Mint lhs, Mint rhs) {
        return lhs.x < rhs.x;
    }
};

template<>
int Mint<0>::Mod = 998244353;
constexpr int P = 1E9 + 7;
using Z = Mint<P>;
```

6.2 Combination [f12983]

```
// C(m, n) = C(m, n - 1) * (m - n + 1) / n
struct Comb {
    int n;
    vector<Z> _fac, _invfac, _inv;
    Comb() : n{0}, _fac{1}, _invfac{1}, _inv{0} {}
    Comb(int n) : Comb() { init(n); }
    void init(int m) {
        m = min(m, Z::getMod() - 1);
        if (m <= n) return;
        _fac.resize(m + 1);
        _invfac.resize(m + 1);
        _inv.resize(m + 1);
    }
};
```

```

    for (int i = n + 1; i <= m; i++) {
        _fac[i] = _fac[i - 1] * i;
    }
    _invfac[m] = _fac[m].inv();
    for (int i = m; i > n; i--) {
        _invfac[i - 1] = _invfac[i] * i;
        _inv[i] = _invfac[i] * _fac[i - 1];
    }
    n = m;
}
Z fac(int m) {
    if (m > n) init(2 * m);
    return _fac[m];
}
Z invfac(int m) {
    if (m > n) init(2 * m);
    return _invfac[m];
}
Z inv(int m) {
    if (m > n) init(2 * m);
    return _inv[m];
}
Z binom(int n, int m) {
    if (n < m || m < 0) return 0;
    return fac(n) * invfac(m) * invfac(n - m);
}
Z lucas(int n, int m) { // Mod 要在 1E5 左右
    if (m == 0) return 1;
    return binom(n % Z::getMod(), m % Z::getMod()) *
        lucas(n / Z::getMod(), m / Z::getMod());
}
} comb; // 若要換模數需重新宣告

```

6.3 Sieve [37ae54]

```

vector<int> primes, minp;
void sieve(int n) {
    minp.assign(n + 1, 0);
    primes.clear();
    // minp[i] == i, 質數
    for (int i = 2; i <= n; i++) {
        if (minp[i] == 0) {
            minp[i] = i;
            primes.push_back(i);
        }
        for (auto p : primes) {
            if (i * p > n) break;
            minp[i * p] = p;
            if (p == minp[i]) break;
        }
    }
    // a ^ (m-1) = 1 (Mod m)
    // a ^ (m-2) = 1/a (Mod m)
    // Exp2: cout << power(x, power(y, p, Mod - 1), Mod)
    // Num = (x+1) * (y+1) * (z+1)...
    // Sum = (a^0 + a^1 + ... + a^x) * (b^0 + ... + b^y)
    // Mul = N * (x+1) * (y+1) * (z+1) / 2
}

```

6.4 Miller Rabin Pollard Rho [394cfb]

```

ll mul(ll a, ll b, ll p) {
    ll res = a * b - ll(1.L * a * b / p) * p;
    res %= p;
    if (res < 0) res += p;
    return res;
}
ll power(ll a, ll b, ll p) {
    ll res {1};
    for (; b; b /= 2, a = mul(a, a, p))
        if (b & 1) res = mul(res, a, p);
    return res;
}
vector<ll>
> chk {2, 325, 9375, 28178, 450775, 9780504, 1795265022};
bool check(ll a, ll d, int s, ll n) {
    a = power(a, d, n);
    if (a <= 1) return 1;
    for (int i = 0; i < s; i++, a = mul(a, a, n)) {
        if (a == 1) return 0;
        if (a == n - 1) return 1;
    }
    return 0;
}
bool isPrime(ll n) {
    if (n < 2) return 0;
    if (n % 2 == 0) return n == 2;
    ll d = n - 1, s = 0;
    while (d % 2 == 0) d /= 2, s++;
    for (ll i : chk)
        if (!check(i, d, s, n)) return 0;
    return 1;
}
const vector<ll> small = {2, 3, 5, 7, 11, 13, 17, 19};
ll findFactor(ll n) {
    if (isPrime(n)) return 1;
    for (ll p : small)
        if (n % p == 0) return p;
    ll x, y = 2, d, t = 1;
    auto f = [&](ll a) {
        return (mul(a, a, n) + t) % n;
    };
}

```

```

};
for (int l = 2; ; l *= 2) {
    x = y;
    int m = min(l, 32);
    for (int i = 0; i < l; i += m) {
        d = 1;
        for (int j = 0; j < m; j++)
            y = f(y), d = mul(d, abs(x - y), n);
        ll g = __gcd(d, n);
        if (g == n) {
            l = 1, y = 2, ++t;
            break;
        }
        if (g != 1) return g;
    }
}
}
map<ll, int> res;
void pollardRho(ll n) {
    if (n == 1) return;
    if (isPrime(n)) {
        res[n]++;
        return;
    }
    ll d = findFactor(n);
    pollardRho(n / d), pollardRho(d);
}

```

6.5 CRT [6b1b59]

```

ll exgcd(ll a, ll b, ll &x, ll &y) {
    if (!b) {
        x = 1, y = 0;
        return a;
    }
    ll g = exgcd(b, a % b, y, x);
    y -= a / b * x;
    return g;
}
ll inv(ll x, ll m) {
    ll a, b;
    exgcd(x, m, a, b);
    a %= m;
    if (a < 0) a += m;
    return a;
}
// gcd(mod) = 1, res % mod_i = remain_i
// a: remain, mod
ll CRT(vector<pair<ll, ll>> &a) {
    ll s = 1, res = 0;
    for (auto [r, m] : a) s *= m;
    for (auto [r, m] : a) {
        ll t = s / m;
        res += r * t % s * inv(t, m) % s;
        if (res >= s) res -= s;
    }
    return res;
}

```

6.6 Matrix [2856cb]

```

template<class T>
vector<vector<T>>> operator*(
    const vector<vector<T>>> &a, const vector<vector<T>>> &b) {
    int n = a.size(), k = a[0].size(), m = b[0].size();
    assert(k == b.size());
    vector<vector<T>>> res(n, vector<T>(m));
    for (int i = 0; i < n; i++)
        for (int j = 0; j < m; j++)
            for (int l = 0; l < k; l++)
                res[i][j] += a[i][l] * b[l][j];
    return res;
}
template<class T>
vector<vector<T>>> unit(int n) {
    vector<vector<T>>> res(n, vector<T>(n));
    for (int i = 0; i < n; i++) res[i][i] = 1;
    return res;
}
template<class T>
vector<vector<T>>> power(vector<vector<T>>> a, ll b) {
    int n = a.size();
    assert(n == a[0].size());
    auto res = unit<T>(n);
    for (; b; b /= 2, a = a * a)
        if (b & 1) res = res * a;
    return res;
}
using Matrix = vector<vector<Z>>>;

```

6.7 Mex [00904e]

```

template<class T>
T mex(vector<T> &v) {
    unordered_set<T> s;
    for (auto e : v) s.insert(e);
    for (T i = 0; ; i++)
        if (s.find(i) == s.end()) return i;
}

```

6.8 Game Theorem

- sg 值為 0 代表先手必敗
- 當前 sg 值 = 可能的後繼狀態的 mex (例如拿一個或拿兩個, 就等於兩者的 sg 值 mex), 若有互相依賴就兩個後繼狀態 xor 當作一組 sg 值 (例如切開成兩半, 只算一次)
- 單組基礎 nim 的 sg 值為本身的原因: $f(0) = 0, f(1) = mex(f(0)) = 1, f(2) = mex(f(0), f(1)) = 2, \dots$, 都是自己
- 多組賽局可以把 sg 值 xor 起來, 當成最後的 sg 值, nim 也是一樣, 且由於 xor 性質, 如果可以快速知道 $sg(1)g(2)\dots g(n)$, 就可以用 xor 性質處理不連續組合

6.9 Fraction [48bf6b]

```
template<class T>
struct Fraction {
    T n, d;
    void reduce() {
        T g = gcd(abs(n), abs(d));
        n /= g, d /= g;
        if (d < 0) n = -n, d = -d;
    }
    Fraction(T n_ = 0, T d_ = 1) : n(n_), d(d_) {
        assert(d != 0); reduce();
    }
    Fraction(const string &str) {
        istringstream ss(str);
        char slash;
        if (str.find('/') != -1) {
            ss >> n >> slash >> d;
        } else {
            ss >> n;
            d = 1;
        }
        Fraction(n, d);
    }
    Fraction operator+=(Fraction rhs) & {
        n = n * rhs.d + rhs.n * d;
        d *= rhs.d;
        reduce();
        return *this;
    }
    Fraction operator-=(Fraction rhs) & {
        n = n * rhs.d - rhs.n * d;
        d *= rhs.d;
        reduce();
        return *this;
    }
    Fraction operator*=(Fraction rhs) & {
        n *= rhs.n, d *= rhs.d;
        reduce();
        return *this;
    }
    Fraction operator/=(Fraction rhs) & {
        assert(rhs.n != 0);
        n *= rhs.d, d *= rhs.n;
        reduce();
        return *this;
    }
    friend Fraction operator+(Fraction lhs, Fraction rhs) {
        return lhs += rhs;
    }
    friend Fraction operator-(Fraction lhs, Fraction rhs) {
        return lhs -= rhs;
    }
    friend Fraction operator*(Fraction lhs, Fraction rhs) {
        return lhs *= rhs;
    }
    friend Fraction operator/(Fraction lhs, Fraction rhs) {
        return lhs /= rhs;
    }
    friend istream &operator>>(istream &is, Fraction &f) {
        string s; is >> s;
        f = Fraction(s);
        return is;
    }
    friend
        ostream &operator<<(ostream &os, const Fraction &f) {
            if (f.d == 1) os << f.n;
            else os << f.n << "/" << f.d;
            return os;
        }
    friend bool operator==(Fraction lhs, Fraction rhs) {
        return lhs.n * rhs.d == rhs.n * lhs.d;
    }
    friend bool operator!=(Fraction lhs, Fraction rhs) {
        return lhs.n * rhs.d != rhs.n * lhs.d;
    }
    friend bool operator<(Fraction lhs, Fraction rhs) {
        return lhs.n * rhs.d < rhs.n * lhs.d;
    }
};
```

6.10 Gaussian Elimination [5d1aa7]

```
// 找反矩陣
// 就開 2n * 右邊放單位矩陣, 做完檢查左半是不是單位, 回傳右半
// 0 : no solution
// -1 : infinity solution
// 1 : one solution
template<class T>
```

```
tuple<T,
    vector<T>> gaussianElimination(vector<vector<T>> a) {
    T det = 1;
    bool zeroDet = false;
    int n = a.size(), m = a[0].size(), rk = 0, sgn = 1;
    for (int c = 0; c < n; c++) {
        int p = -1;
        for (int r = rk; r < n; r++) {
            if (a[r][c] != 0) {
                p = r;
                break;
            }
        }
        if (p == -1) {
            zeroDet = true;
            continue;
        }
        if (p != rk) swap(a[rk], a[p]), sgn *= -1;
        det *= a[rk][c];
        T inv = 1 / a[rk][c];
        for (int j = c; j < m; j++) a[rk][j] *= inv;
        for (int r = 0; r < n; r++) {
            if (r == rk || a[r][c] == 0) continue;
            T fac = a[r][c];
            for (int j = c; j < m; j++)
                a[r][j] -= fac * a[rk][j];
        }
        rk++;
    }
    det = (zeroDet ? 0 : det * sgn);
    for (int r = rk; r < n; r++)
        if (a[r][m - 1] != 0) return {det, 0, {}};
    if (rk < n) return {det, -1, {}};
    vector<T> ans(n);
    for (int i = 0; i < n; i++) ans[i] = a[i][m - 1];
    return {det, 1, ans};
}

template<class T>
tuple<int, vector<T>, vector<vector<T>>> findBasis(vector<vector<T>> a) {
    int n = a.size(), m = a[0].size(), rk = 0;
    vector<int> pos(m - 1, -1);
    for (int c = 0; c < m - 1; c++) {
        int p = -1;
        for (int r = rk; r < n; r++) {
            if (a[r][c] != 0) {
                p = r;
                break;
            }
        }
        if (p == -1) continue;
        if (p != rk) swap(a[rk], a[p]);
        pos[c] = rk;
        T inv = 1 / a[rk][c];
        for (int j = c; j < m; j++) a[rk][j] *= inv;
        for (int r = 0; r < n; r++) {
            if (r == rk || a[r][c] == 0) continue;
            T fac = a[r][c];
            for (int j = c; j < m; j++)
                a[r][j] -= fac * a[rk][j];
        }
        rk++;
    }
    vector<T> sol(m - 1);
    vector<vector<T>> basis;
    for (int r = rk; r < n; r++)
        if (a[r][m - 1] != 0)
            return {-1, sol, basis};
    for (int c = 0; c < m - 1; c++)
        if (pos[c] != -1)
            sol[c] = a[pos[c]][m - 1];
    for (int c = 0; c < m - 1; c++)
        if (pos[c] == -1) {
            vector<T> v(m - 1);
            v[c] = 1;
            for (int j = 0; j < m - 1; j++)
                if (pos[j] != -1)
                    v[j] = -a[pos[j]][c];
            basis.push_back(v);
        }
    return {rk, sol, basis};
}

template<class T>
using Matrix = vector<vector<T>>;
```

6.11 Integer Partition [83bc9d]

```
// CSES_Sum_of_Divisors
const int Mod = 1E9 + 7;
const int inv_2 = 500000004;
// n / 1 * 1 + n / 2 * 2 + n / 3 * 3 + ... + n / n * n
void integerPartition() {
    ll ans = 0, n; cin >> n;
    for (ll l = 1, r; l <= n; l = r + 1) {
        r = n / (n / l);
        ll val = n / l; // n / l 到 n / r 一樣的值
        ll sum = (((l + r) % Mod)
            * ((r - l + 1) % Mod)) % Mod * inv_2; // l 加到 r
        val %= Mod; sum %= Mod;
        ans += val * sum;
        ans %= Mod;
    }
}
```

```
cout << ans << " |n";
}
```

6.12 Mobius Theorem

- 數論分塊可以快速計算一些含有除法向下取整的和式，就是像 $\sum_{i=1}^n f(i)g(\lfloor \frac{n}{i} \rfloor)$ 的和式。當可以在 $O(1)$ 內計算 $f(r) - f(l)$ 或已經預處理出 f 的前綴和時，數論分塊就可以在 $O(\sqrt{n})$ 的時間內計算上述和式的值。
- 迪利克雷捲積 $h(x) = \sum_{d|x} f(d)g(\frac{x}{d})$

• 積性函數

– 莫比烏斯函數

1. 定義

$$\mu(d) = \begin{cases} 1 & \text{for } n=1 \\ 0 & \text{for } n \neq 1 \end{cases}$$

2. μ 是常數函數 1 的反元素

$\Rightarrow \mu * 1 = \epsilon$ ， $\epsilon(n)$ 只在 $n=1$ 時為 1，其餘情況皆為 0。

– ϕ 歐拉函數: x 以下與 x 互質的數量

$$\begin{aligned} \phi * 1 &= \sum_{d|n} \phi\left(\frac{n}{d}\right) \text{ 質因數分解} \\ &= \sum_{i=1}^c \phi(p^i) \\ &= 1 + p^0(p-1) + p^1(p-1) + \dots + p^{c-1}(p-1) \\ &= p^c \\ &= id \end{aligned}$$

• 莫比烏斯反演公式

$$f(n) = \sum_{d|n} g(d) \Leftrightarrow g(n) = \sum_{d|n} \mu(d) f\left(\frac{n}{d}\right)$$

$$f(n) = \sum_{n|d} g(d) \Leftrightarrow g(n) = \sum_{n|d} \mu\left(\frac{d}{n}\right) f(d)$$

• 例子

$$\begin{aligned} &\sum_{i=a}^b \sum_{j=c}^d [gcd(i, j) = k] \\ &\Rightarrow \sum_{i=1}^{\lfloor \frac{b}{k} \rfloor} \sum_{j=1}^{\lfloor \frac{d}{k} \rfloor} [gcd(i, j) = k] \\ &= \sum_{i=1}^{\lfloor \frac{b}{k} \rfloor} \sum_{j=1}^{\lfloor \frac{d}{k} \rfloor} \epsilon(gcd(i, j)) \\ &= \sum_{i=1}^{\lfloor \frac{b}{k} \rfloor} \sum_{j=1}^{\lfloor \frac{d}{k} \rfloor} \sum_{d|gcd(i, j)} \mu(d) \\ &= \sum_{d=1}^{\infty} \mu(d) \sum_{i=1}^{\lfloor \frac{b}{kd} \rfloor} [d|i] \sum_{j=1}^{\lfloor \frac{d}{kd} \rfloor} [d|j] \text{ } d \text{ 可整除 } i \text{ 時為 } 1 \\ &= \sum_{d=1}^{\min(\lfloor \frac{b}{k} \rfloor, \lfloor \frac{d}{k} \rfloor)} \mu(d) \lfloor \frac{x}{kd} \rfloor \lfloor \frac{y}{kd} \rfloor \end{aligned}$$

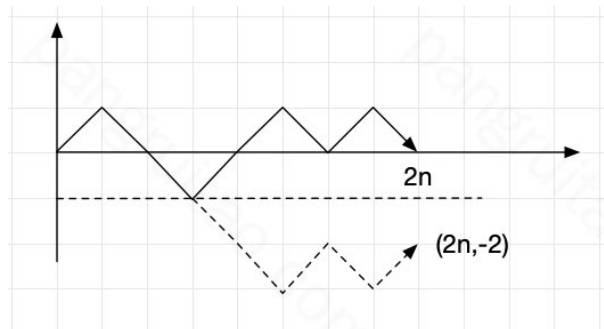
6.13 Mobius Inverse [d41d8c]

```
const int N = 2E5;
ll pref[N];
void init() {
    pref[1] = 1;
    vector<ll> wei(N); // wei = 0 代表是質數, -1 代表可被平方數整除
    for (ll i = 2; i < N; i++) {
        if (wei[i] == -1) {
            pref[i] = pref[i - 1];
            continue; // 包含平方
        }
        if (wei[i] == 0) {
            wei[i] = 1;
            for (ll j = 2; i * j < N; j++) {
                if (j % i == 0) wei[i * j] = -1;
                else if (wei[i * j] != -1) wei[i * j]++;
            }
        }
        pref[i] = pref[i - 1] + (wei[i] % 2 == 0 ? 1 : -1);
    }
}

void solve() {
    ll a, b, c, d, k; cin >> a >> b >> c >> d >> k;
    auto cal = [&](ll x, ll y) -> int {
        int res = 0;
        for (int l = 1, r; l <= min(x, y); l = r + 1) {
            r = min(x / (x / l), y / (y / l));
            res += (pref[r] - pref[l - 1]) * (x / l) * (y / l); // 代推出來的式子
        }
    };
}
```

```
    }
    return res;
};
cout << cal
    (b / k, d / k) - cal((a - 1) / k, d / k) - cal(b / k,
    (c - 1) / k) + cal((a - 1) / k, (c - 1) / k) << " |n";
}
```

6.14 Catalan Theorem



- n 個往上 n 個往下，先枚舉所有情況 $\frac{(2n)!}{n!n!} = C_n^{2n}$
 - 扣掉非法的，有多少種可能讓最後的點落在 $(2n, -2)$
- 假設往上有 x 個，往下有 y 個，會有：

$$\begin{cases} x+y=2n \\ y-x=2 \end{cases} \Rightarrow \begin{cases} x=n-1 \\ y=n+1 \end{cases}$$

所以只要扣掉 C_{n-1}^{2n} 即可

6.15 Burnside's Lemma

$$|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$$

- G : 各種翻轉操作所構成的置換群
- X/G : 本質不同的方案的集合
- X^g : 對於某一種操作 g ，所有方案中，經過 g 這種翻轉後保持不變的方案
- 集合取絕對值代表集合數

7 Search and Greedy

7.1 Binary Search [d41d8c]

```
void binarySearch() {
    // 二分找上界
    // 如果無解會 = 原 lo, lo 要先 - 1
    while (lo < hi) {
        int x = (lo + hi + 1) / 2;
        if (check(x)) lo = x;
        else hi = x - 1;
    }
    cout << lo;
    // 二分找下界
    // 如果無解會 = 原 hi, hi 要先 + 1
    while (lo < hi) {
        int x = (lo + hi) / 2;
        if (check(m)) hi = x;
        else lo = x + 1;
    }
    cout << lo;
}
```

7.2 Ternary Search [d41d8c]

```
void ternarySearch() {
    int lo = 0, hi = 10;
    while (lo < hi) {
        int xl = lo + (hi - lo) / 3;
        int xr = hi - (hi - lo) / 3;
        int resl = calc(xl), resr = calc(xr);
        if (resl < resr) {
            lo = xl + 1;
        } else {
            hi = xr - 1;
        }
    }
}
```

8 Tree

8.1 Binary Lifting LCA [fdf743]

```
const int N = 2E5;
const int Lg = __lg(N); // __lg(max(n, qi)), [0, Lg]
int up[N][Lg + 1];
vector<int> dep, dfn;
void build(int n, vector<vector<int>> &g, int rt = 0) {
    dep.assign(n, 0); dfn.assign(n, 0);
    int cur = 0;
    auto dfs = [&](auto self, int x, int p) -> void {
        dfn[x] = cur++;
        up[x][0] = p;
        for (int i = 1; i <= Lg; i++) {
            int nxt = up[x][i - 1];
            if (nxt < n) self(nxt, x);
        }
    };
    dfs(rt, 0);
}
```



```

        up[x][i] = up[nxt][i - 1];
    }
    for (auto y : g[x]) {
        if (y == p) continue;
        up[y][0] = x;
        dep[y] = dep[x] + 1;
        self(self, y, x);
    }
};
dfs(dfs, rt, rt);
}
int lca(int a, int b) {
    if (dep[a] < dep[b]) swap(a, b);
    int pull = dep[a] - dep[b];
    for (int i = 0; i <= Lg; i++)
        if (pull & (1 << i)) a = up[a][i];
    if (a == b) return a;
    for (int i = Lg; i >= 0; i--)
        if (up[a][i] != up[b][i])
            a = up[a][i], b = up[b][i];
    return up[a][0];
}
int jump(int x, int k) {
    for (int i = Lg; i >= 0; i--)
        if (k >> i & 1) x = up[x][i];
    return x;
}
int dist(int a, int b) {
    return dep[a] + dep[b] - 2 * dep[lca(a, b)];
}
}

```

8.2 Centroid Decomposition [2ec4c4]

```

vector<bool> vis(n);
vector<int> siz(n), par(n, -1);
auto findSize = [&](auto self, int u, int p) -> int {
    siz[u] = 1;
    for (int v : g[u]) {
        if (v == p || vis[v]) continue;
        siz[u] += self(self, v, u);
    }
    return siz[u];
};
auto findCen = [&](auto self, int u, int p, int sz) -> int {
    for (int v : g[u]) {
        if (v == p || vis[v]) continue;
        if (siz[v] * 2 > sz) return self(self, v, u, sz);
    }
    return u;
};
auto buildCen = [&](auto self, int u, int p) -> void {
    findSize(findSize, u, p);
    int c = findCen(findCen, u, -1, siz[u]);
    vis[c] = true, par[c] = p;
    for (int v : g[c]) if (!vis[v]) self(self, v, c);
};
buildCen(buildCen, 0, -1);

```

8.3 Heavy Light Decomposition [9facc3]

```

struct HLD {
    int n, cur;
    vector<int> siz, top, dep, parent, in, out, seq;
    vector<vector<int>> adj;
    HLD(int n) : n(n), cur(0) {
        siz.resize(n); top.resize(n); dep.resize(n);
        parent.resize(n); in.resize(n); out.resize(n);
        seq.resize(n); adj.assign(n, {});
    }
    void addEdge(int u, int v) {
        adj[u].push_back(v);
        adj[v].push_back(u);
    }
    void work(int rt = 0) {
        top[rt] = rt;
        dep[rt] = 0;
        parent[rt] = -1;
        dfs1(rt); dfs2(rt);
    }
    void dfs1(int u) {
        if (parent[u] != -1)
            adj[u].erase(find(
                adj[u].begin(), adj[u].end(), parent[u]));
        siz[u] = 1;
        for (auto &v : adj[u]) {
            parent[v] = u, dep[v] = dep[u] + 1;
            dfs1(v);
            siz[u] += siz[v];
            if (siz[v] > siz[adj[u][0]]) {
                swap(v, adj[u][0]);
            } // 讓 adj[u][0] 是重子節點
        }
    }
    void dfs2(int u) {
        in[u] = cur++;
        seq[in[u]] = u; // dfn 對應的編號
        for (auto v : adj[u]) {
            top[v] = v == adj[u][0] ? top[u] : v;
            dfs2(v);
        }
        out[u] = cur;
    }
}

```

```

int lca(int u, int v) {
    while (top[u] != top[v]) {
        if (dep[top[u]] > dep[top[v]]) {
            u = parent[top[u]];
        } else {
            v = parent[top[v]];
        }
    }
    return dep[u] < dep[v] ? u : v;
}
int dist(int u, int v) {
    return dep[u] + dep[v] - 2 * dep[lca(u, v)];
}
int jump(int u, int k) {
    if (dep[u] < k) return -1;
    int d = dep[u] - k;
    while (dep[top[u]] > d) u = parent[top[u]];
    return seq[in[u] - dep[u] + d];
}
bool isAncestor(int u, int v) {
    return in[u] <= in[v] && in[v] < out[u];
}
int rootedParent(int rt, int v) {
    if (rt == v) return rt;
    if (!isAncestor(v, rt)) return parent[v];
    auto it = upper_bound(adj[v].begin(), adj[v].end(), rt,
        [&](int x, int y) {
            return in[x] < in[y];
        }) - 1;
    return *it;
}
int rootedSize(int rt, int v) {
    if (rt == v) return n;
    if (!isAncestor(v, rt)) return siz[v];
    return n - siz[rootedParent(rt, v)];
}
int rootedLca(int rt, int a, int b) {
    return lca(rt, a) ^ lca(a, b) ^ lca(b, rt);
}
}

```

8.4 Link Cut Tree [cf936b]

```

template<class Info, class Tag>
struct LinkCutTree { // 1-based
    struct Node {
        Info info = Info();
        Tag tag = Tag();
        int siz = 0, ch[2], p = 0, rev = 0;
    };
    vector<Node> nd;
    LinkCutTree(int n) : nd(n + 1) {}
    bool isrt(int t) {
        return
            nd[nd[t].p].ch[0] != t && nd[nd[t].p].ch[1] != t;
    }
    int pos(int t) { // t 是其 par 的左/右
        return nd[nd[t].p].ch[1] == t;
    }
    void applyRev(int t) {
        swap(nd[t].ch[0], nd[t].ch[1]);
        nd[t].rev ^= 1;
    }
    void apply(int t, const Tag &v) {
        nd[t].info.apply(nd[t].siz, v);
        nd[t].tag.apply(v);
    }
    void push(int t) {
        if (nd[t].rev) {
            if (nd[t].ch[0]) applyRev(nd[t].ch[0]);
            if (nd[t].ch[1]) applyRev(nd[t].ch[1]);
            nd[t].rev = 0;
        }
        if (nd[t].ch[0]) apply(nd[t].ch[0], nd[t].tag);
        if (nd[t].ch[1]) apply(nd[t].ch[1], nd[t].tag);
        nd[t].tag = Tag();
    }
    void pull(int t) {
        nd[t].siz
            = 1 + nd[nd[t].ch[0]].siz + nd[nd[t].ch[1]].siz;
        nd[t].info
            .pull(nd[nd[t].ch[0]].info, nd[nd[t].ch[1]].info);
    }
    void pushAll(int t) {
        if (!isrt(t)) pushAll(nd[t].p);
        push(t);
    }
    void rotate(int x) { // x 與其 par 交換位置
        int f = nd[x].p, r = pos(x);
        nd[f].ch[r] = nd[x].ch[!r];
        if (nd[x].ch[!r]) nd[nd[x].ch[!r]].p = f;
        nd[x].p = nd[f].p;
        if (!isrt(f)) nd[nd[f].p].ch[pos(f)] = x;
        nd[x].ch[!r] = f, nd[f].p = x;
        pull(f), pull(x);
    }
    void splay(int x) {
        pushAll(x);
        for (int f = nd[x].p; f = nd[x].p, !isrt(x); rotate(x))
            if (!isrt(f)) rotate(pos(x) == pos(f) ? f : x);
    }
    void access(int x) {

```

```

    for (int f = 0; x; f = x, x = nd[x].p)
        splay(x), nd[x].ch[1] = f, pull(x);
}
void makeRoot(int p) {
    access(p), splay(p), applyRev(p);
}
int findRoot(int x) {
    access(x), splay(x);
    while (nd[x].ch[0]) x = nd[x].ch[0];
    splay(x); return x;
}
void split(int x, int y) { // y 為根
    makeRoot(x), access(y), splay(y);
}
void link(int rt, int p) {
    makeRoot(rt), nd[rt].p = p;
}
void cut(int x, int y) {
    makeRoot(x), access(y), splay(y);
    nd[y].ch[0] = nd[nd[y].ch[0]].p = 0;
    pull(y);
}
bool neighbor(int x, int y) {
    makeRoot(x), access(y);
    if (nd[y].ch[0] != x || nd[x].ch[1]) return false;
    return true;
}
bool connected(int x, int y) {
    return findRoot(x) == findRoot(y);
}
void modify(int x, const Info &v) {
    access(x), nd[x].info = v;
}
void pathApply(int x, int y, const Tag &v) {
    assert(connected(x, y));
    split(x, y), apply(y, v);
}
Info pathQuery(int x, int y) {
    assert(connected(x, y));
    split(x, y); return nd[y].info;
}
};
const int Mod = 51061;
struct Tag {
    ll add = 0, mul = 1;
    void apply(const Tag &v) {
        mul = mul * v.mul % Mod;
        add = (add * v.mul % Mod + v.add) % Mod;
    }
};
struct Info {
    ll val = 0, sum = 0;
    void apply(int siz, const Tag &v) {
        val = (val * v.mul % Mod + v.add) % Mod;
        sum = (sum * v.mul % Mod + v.add * siz % Mod) % Mod;
    }
    void pull(const Info &l, const Info &r) {
        sum = (l.sum + r.sum + val) % Mod;
    }
};

```

8.5 Virtual Tree [c3a0b3]

// 多次詢問給某些關鍵點，虛樹可達成快速樹 DP (前處理每個點)
 // 例如這題是有權樹，給一些關鍵點，求跟 vertex 1 隔開的最小成本
 // 前處理 root 到所有點的最小邊權

```

vector<int> stk;
void insert(int key, vector<vector<int>> &vt) {
    if (stk.empty()) {
        stk.push_back(key);
        return;
    }
    int l = lca(stk.back(), key);
    if (l == stk.back()) {
        stk.push_back(key);
        return;
    }
    while (
        stk.size() > 1 && dfn[stk[stk.size() - 2]] > dfn[l]) {
        vt[stk[stk.size() - 2]].push_back(stk.back());
        stk.pop_back();
    }
    if (stk.size() < 2 || stk[stk.size() - 2] != l) {
        vt[l].push_back(stk.back());
        stk.back() = l;
    } else {
        vt[l].push_back(stk.back());
        stk.pop_back();
    }
    stk.push_back(key);
}
int work(vector<vector<int>> &vt) {
    while (stk.size() > 1) {
        vt[stk[stk.size() - 2]].push_back(stk.back());
        stk.pop_back();
    }
    int rt = stk[0];
    stk.clear();
    return rt;
}
void solve() {
    int n; cin >> n;

```

```

vector<vector<int>> g(n);
vector<vector<pair<int, int>>> wg(n);
vector<vector<int>> vt(n);
for (int i = 1; i < n; i++) {
    int u, v, w;
    cin >> u >> v >> w;
    u--, v--;
    g[u].push_back(v), g[v].push_back(u);
    wg[u].emplace_back(v, w), wg[v].emplace_back(u, w);
}
build(n, g); // build LCA
vector<int> dis(n, 1E9); // root 到各點的最小邊權
auto dfs_dis = [&](auto &&self, int x, int p) -> void {
    for (auto [y, w] : wg[x]) {
        if (y == p) continue;
        dis[y] = min(w, dis[x]);
        self(self, y, x);
    }
};
dfs_dis(dfs_dis, 0, -1);

vector<bool> isKey(n);
vector<ll> dp(n);
int q; cin >> q;
while (q--) {
    int m; cin >> m;
    vector<int> key(m);
    for (int i = 0; i < m; i++) {
        cin >> key[i];
        key[i] -= 1;
        isKey[key[i]] = true;
    }
    key.push_back(0); // 固定 0 為 root, 看題目需求
    sort(key.begin(), key.end(), [&](int a, int b) {
        return dfn[a] < dfn[b];
    }); // 要 sort 再 insert
    for (auto x : key) insert(x, vt);
    work(vt);
    auto dfs = [&](auto &&self, int x) -> void {
        for (auto y : vt[x]) {
            self(self, y);
            if (isKey[y]) { // 直接砍了
                dp[x] += dis[y];
            } else { // 不砍 or 砍
                dp[x] += min<ll>(dp[y], dis[y]);
            } // 記得 reset
            isKey[y] = dp[y] = 0;
        }
        vt[x].clear(); // 記得 reset
    };
    dfs(dfs, 0);
    cout << dp[0] << "\n";
    dp[0] = 0; // 最後 reset root
}
}

```

8.6 Dominator Tree [0cbb87]

// dom
 存起點到達此點的必經的上個節點(起點 = 自己), 無法到達 = -1

```

struct DominatorTree {
    int n, id;
    vector<vector<int>> adj, radj, bucket;
    vector<int> sdom, dom, vis, rev, pa, rt, mn, res;
    DominatorTree(int n) : n(n), id(0) {
        sdom.resize(n), rev.resize(n);
        pa.resize(n), rt.resize(n);
        mn.resize(n), res.resize(n);
        bucket.assign(n, {});
        adj.assign(n, {}), radj.assign(n, {});
        dom.assign(n, -1), vis.assign(n, -1);
    }
    void add_edge(int u, int v) { adj[u].push_back(v); }
    int query(int v, int x) {
        if (rt[v] == v) return x ? -1 : v;
        int p = query(rt[v], 1);
        if (p == -1) return x ? rt[v] : mn[v];
        if (sdom[mn[v]] > sdom[mn[rt[v]]])
            mn[v] = mn[rt[v]];
        rt[v] = p;
        return x ? p : mn[v];
    }
    void dfs(int v) {
        vis[v] = id, rev[id] = v;
        rt[id] = mn[id] = sdom[id] = id, id++;
        for (int u : adj[v]) {
            if (vis[u] == -1)
                dfs(u), pa[vis[u]] = vis[v];
            radj[vis[u]].push_back(vis[v]);
        }
    }
    vector<int> build(int s) {
        dfs(s);
        for (int i = id - 1; i >= 0; i--) {
            for (int u : radj[i])
                sdom[i] = min(sdom[i], sdom[query(u, 0)]);
            if (!bucket[sdom[i]].push_back(i))
                for (int u : bucket[i]) {
                    int p = query(u, 0);
                    dom[u] = sdom[p] == i ? i : p;
                }
        }
    }
}

```

```

    }
    if (i) rt[i] = pa[i];
}
res.assign(n, -1);
for (int i = 1; i < id; i++)
    if (dom[i] != sdom[i])
        dom[i] = dom[dom[i]];
for (int i = 1; i < id; i++)
    res[rev[i]] = rev[dom[i]];
res[s] = s;
for (int i = 0; i < n; i++)
    dom[i] = res[i];
return dom;
}
};

```

9 DP

9.1 LCS [9c3c7b]

```

string LCS(const string &a, const string &b) {
    int n = a.length(), m = b.length();
    vector<vector<int>> dp(n + 1, vector<int>(m + 1));
    for (int i = 1; i <= n; i++) {
        for (int j = 1; j <= m; j++) {
            if (a[i - 1] == b[j - 1]) {
                dp[i][j] = dp[i - 1][j - 1] + 1;
            } else {
                dp[i][j] = max(dp[i - 1][j], dp[i][j - 1]);
            }
        }
    }
    int l = dp[n][m];
    string ans(l, 0);
    while (n >= 1 && m >= 1) {
        if (a[n - 1] == b[m - 1]) {
            ans[l - 1] = a[n - 1];
            n--, m--, l--;
        } else {
            if (dp[n - 1][m] > dp[n][m - 1]) n--;
            else m--;
        }
    }
    return ans;
}

```

9.2 LIS [3018f4]

```

vector<int> LIS(const vector<int> &v) { // strictly
    int n = v.size(), L = 1;
    vector<int> dp(n); dp[0] = 1;
    vector<int> stk {v[0]};
    for (int i = 1; i < n; i++) {
        if (v[i] > stk.back()) { // >=
            stk.push_back(v[i]);
            dp[i] = ++L;
        } else { // upper
            auto it
                = lower_bound(stk.begin(), stk.end(), v[i]);
            *it = v[i];
            dp[i] = it - stk.begin() + 1;
        }
    }
    vector<int> ans;
    for (int i = n - 1; i >= 0; i--)
        if (dp[i] == L) ans.push_back(v[i]), L--;
    reverse(ans.begin(), ans.end());
    return dp;
}

```

9.3 Edit Distance [b13609]

```

void editDistance() {
    string s1, s2; cin >> s1 >> s2;
    int n1 = s1.size(), n2 = s2.size();
    vector<int> dp(n2 + 1);
    iota(dp.begin(), dp.end(), 0);
    for (int i = 1; i <= n1; i++) {
        vector<int> cur(n2 + 1); cur[0] = i;
        for (int j = 1; j <= n2; j++) {
            if (s1[i - 1] == s2[j - 1]) {
                cur[j] = dp[j - 1];
            } else {
                // s1 新增等價於 s2 砍掉
                // dp[i][j] = min(s2 新增, 修改, s1 新增);
                cur[j] = min({cur[j - 1], dp[j - 1], dp[j]} + 1;
            }
        }
        swap(dp, cur);
    }
    cout << dp[n2] << "\n";
}

```

9.4 Bitmask [60bdb9]

```

void hamiltonianPath() {
    int n, m; cin >> n >> m;
    vector<vector<int>> adj(n);
    for (int i = 0; i < m; i++) {
        int u, v; cin >> u >> v;

```

```

        adj[--v].push_back(--u);
    }
    // 以...為終點，走過...
    vector dp(n, vector<int>(1 << n));
    dp[0][1] = 1;
    for (int mask = 1; mask < 1 << n; mask++) {
        if ((mask & 1) == 0) continue;
        for (int i = 0; i < n; i++) {
            if ((mask >> i & 1) == 0) continue;
            if (i == n - 1 && mask != (1 << n) - 1) continue;
            int pre = mask ^ (1 << i);
            for (int j : adj[i]) {
                if ((pre >> j & 1) == 0) continue;
                dp[i][mask] = (dp[i][mask] + dp[j][pre]) % Mod;
            }
        }
    }
    cout << dp[n - 1][(1 << n) - 1] << "\n";
}

void elevatorRides() {
    int n, x; cin >> n >> x;
    vector<int> a(n);
    for (int i = 0; i < n; i++) cin >> a[i];
    vector<int> dp(1 << n), f(1 << n);
    dp[0] = 1; // 次數、已使用人數
    for (int mask = 1; mask < 1 << n; mask++) {
        dp[mask] = 2E9;
        for (int i = 0; i < n; i++) {
            if ((mask >> i & 1) == 0) continue;
            int pre = mask ^ (1 << i);
            if (f[pre] + a[i] <= x) {
                if (dp[pre] < dp[mask] || dp[pre]
                    == dp[mask] && f[pre] + a[i] < f[mask]) {
                    dp[mask] = dp[pre];
                    f[mask] = f[pre] + a[i];
                }
            } else if (dp[pre] + 1 < dp[mask] ||
                dp[pre] + 1 == dp[mask] && a[i] < f[mask]) {
                dp[mask] = dp[pre] + 1;
                f[mask] = a[i];
            }
        }
    }
    cout << dp[(1 << n) - 1] << "\n";
}

void minClique() { // 移掉一些邊，讓整張圖由最少團組成
    int n, m;
    cin >> n >> m;
    vector<bitset<N>> g(n);
    for (int i = 0; i < m; i++) {
        int u, v; cin >> u >> v;
        u--; v--; g[u][v] = g[v][u] = 1;
    }
    vector<int> dp(1 << n, inf);
    dp[0] = 1;
    for (int mask = 0; mask < 1 << n; mask++) { // 先正常 dp
        for (int i = 0; i < n; i++) {
            if (mask & (1 << i)) {
                int pre = mask ^ (1 << i);
                if (dp[pre]
                    == 1 && (g[i] & bitset<N>(pre)) == pre)
                    dp[mask] = 1; // i 有連到所有 pre
            }
        }
    }
    for (int
        mask = 0; mask < 1 << n; mask++) // 然後枚舉子集 dp
        for (int sub = mask; sub; --sub &= mask)
            dp[mask] = min(dp[mask], dp[sub] + dp[mask ^ sub]);
    cout << dp[(1 << n) - 1] << "\n";
}

```

9.5 Projects [8aa468]

```

void projects() { // 排程有權重問題，輸出價值最多且時間最少
    struct E { int from, to, w, id; };
    int n; cin >> n; vector<E> a(n + 1);
    for (int i = 1; i <= n; i++) {
        int u, v, w; cin >> u >> v >> w;
        a[i] = {u, v, w, i};
    }
    vector<array<ll, 2>> dp(n + 1); // w, time
    vector<array<int, 2>> rec(n + 1); // 有沒選，上個是誰
    sort(a.begin(), a.end());
    for (int i = 1; i <= n; i++) {
        int id = prev(
            lower_bound(all(a), {0, a[i].from}, [](E x, E y) {
                return x.to < y.to;
            }) - a.begin());
        dp[i] = dp[id - 1];
        ll nw = dp[id][0] + a[i].w;
        ll nt = dp[id][1] + a[i].to - a[i].from;
        if (dp[i][0] < nw || dp[i][0] == nw && dp[i][1] > nt) {
            dp[i] = {nw, nt};
            rec[i] = {1, id};
        }
    }
    vector<int> ans;
    for (int i = n; i != 0; i--) {
        if (rec[i][0]) {
            ans.push_back(a[i].id);

```

```

        i = rec[i][1];
    } else i--;
}
}

```

9.6 Monotonic Queue [c9ba14]

```

// 應用:  $dp(i) = h(i) + \max(A(j))$ , for  $l(i) \leq j \leq r(i)$ 
//  $A(j)$  可能包含  $dp(j)$ ,  $h(i)$  可  $O(1)$ 
void boundedKnapsack() {
    int n, k; //  $O(nk)$ 
    vector<int> w(n), v(n), num(n);
    deque<int> q;
    // 於是我們將同餘的數分在同一組
    // 每次取出連續  $num[i]$  格中最大值
    //  $g_x = \max_{k=0}^{num[i]} (g_{x-k} + v_i * k)$ 
    //  $G_x = g_{x-k} - v_i * x$ 
    //  $x$  代  $x-k \Rightarrow v_i * (x-k)$ 
    //  $g_x = \max_{k=0}^{num[i]} (G_{x-k} + v_i * x)$ 
    vector<vector<ll>> dp(2, vector<ll>(k + 1));
    for (int i = 0; i < n; i++) {
        for (int r = 0; r < w[i]; r++) { // 餘數
            q.clear(); // q 記錄在  $x = i$  時的  $dp$  有單調性
            for (int x = 0; x * w[i] + r <= k; x++) {
                while (!q.empty() && q.front() < x - num[i]) q.pop_front(); // 維護遞減
                ll nxt = dp[0][x * w[i] + r] - x * v[i];
                while (!q.empty() && dp[0][q.back()] * w[i] + r - q.back() * v[i] < nxt) q.pop_back();
                q.push_back(x);
                dp[1][x * w[i] + r] = dp[0][q.front()] * w[i] + r - q.front() * v[i] + x * v[i];
            }
            swap(dp[0], dp[1]);
        }
    }
    cout << dp[0][k] << "\n";
}

```

9.7 SOS [be203d]

```

// 使用情況: 跟 bit 與(被)包含有關, 且  $x$  在  $1E6$  左右
// 題目: 一數組, 問有多少所有數 & 起來為  $\theta$  的集合數
//  $dp[x]$  代表包含  $x$  的  $y$  個數(比  $x$  大且 bit 1 全包含  $x$  的有幾個)
// 答案應該包含在  $dp[0]$  內, 但是有重複元素, 所以考慮容斥
//  $\Rightarrow ans = \sum_{i=0}^n (-1)^{pop\_count(i)} 2^{dp[i]-1}$ 
//  $\Rightarrow$  全部為  $\theta$  的個數 - 至少一個為  $1$  的個數 + 至少兩個為  $1$  的個數
void solve() {
    int n; cin >> n; Z ans = 0;
    vector<int> a(n);
    for (int i = 0; i < n; i++) cin >> a[i];
    int m = __lg(*max_element(a.begin(), a.end())) + 1;
    // 定義  $dp[mask]$  為  $mask$  被包含於  $a[i]$  的  $i$  個數
    vector<ll> dp(1 << m);
    for (int i = 0; i < n; i++) dp[a[i]]++;
    for (int i = 0; i < m; i++) {
        for (int mask = 0; mask < 1 << m; mask++) {
            if (mask >> i & 1) {
                int pre = mask ^ (1 << i);
                dp[pre] += dp[mask];
            }
        }
    }
    for (int mask = 0; mask < 1 << m; mask++) {
        int sgn = __builtin_popcount(mask) & 1 ? -1 : 1;
        ans += sgn * (power(Z(2), dp[mask]) - 1);
    }
}
//  $x | y = x$ , 代表包含於  $x$  的  $y$  個數, 定義為  $dp[x][0]$ 
//  $x \& y = x$ , 代表包含  $x$  的  $y$  個數, 定義為  $dp[x][1]$ 
//  $x \& y \neq 0$ , 代表至少有一個位元都為  $1$  的  $y$  個數,  $= n - dp[\sim x][0]$ 
void solve() {
    int n; cin >> n;
    vector<int> a(n);
    map<int, int> mp;
    for (int i = 0; i < n; i++) {
        cin >> a[i]; mp[a[i]]++;
    }
    int m = __lg(*max_element(a.begin(), a.end())) + 1;
    vector<array<ll, 2>> dp(1 << m);
    for (int i = 0; i < n; i++) dp[a[i]][0]++, dp[a[i]][1]++;
    for (int i = 0; i < m; i++) {
        for (int mask = 0; mask < 1 << m; mask++) {
            if (mask >> i & 1) {
                int pre = mask ^ (1 << i);
                dp[mask][0] += dp[pre][0];
                dp[pre][1] += dp[mask][1];
            }
        }
    }
    for (int i = 0; i < n; i++) {
        cout << dp[a[i]][0] << " " << dp[a[i]][1] << " " << n - (dp[(1 << m) - 1] ^ a[i])[0] << "\n";
    }
}

```

9.8 CHT [ce439f]

```

// 應用:  $dp(x) = C(x) + \min/\max(A(i) * x + B(i))$ , for  $i < x$ 
struct Line { // x 盡量從 1 開始
    ll m, b;
    Line(ll m = 0, ll b = 0) : m(m), b(b) {}
    ll eval(ll x) { return m * x + b; }
};

struct CHT { // 斜率單調
    int lptr = 0, rptr = 0;
    vector<Line> hull;
    CHT(Line init = Line()) { hull.push_back(init); }
    bool frontBad(Line &l1, Line &l2, ll x) {
        // 斜率遞減、查詢遞增, 因此只要左直線的  $y \geq$  右直線的  $y$ 
        // 代表查詢的當下, 右線段的高度已經低於左線段了
        return l1.eval(x) >= l2.eval(x);
    }
    bool backBad(Line &l1, Line &l2, Line &l3) {
        // 斜率遞減、上凸包、取  $\min$ 
        // 因此只要  $l2$  跟  $l3$  的  $x$  交點  $\leq l1$  跟  $l3$  的  $x$  交點,  $l2$  就用不到了
        return (l3.b - l2.b) * (l1.m - l3.m) <= (l3.b - l1.b) * (l2.m - l3.m);
    }
    void addLine(Line l) {
        while (rptr - lptr > 0 && backBad(hull[rptr - 1], hull[rptr], l)) hull.pop_back(), rptr--;
        hull.push_back(l), rptr++;
    }
    ll query(ll x) { // 查詢沒單調性需要二分搜
        while (rptr - lptr > 0 && frontBad(hull[lptr], hull[lptr + 1], x)) lptr++;
        return hull[lptr].eval(x);
    }
};

```

9.9 DNC [9fea10]

```

// 應用: 切  $k$  段問題, 且滿足四邊形不等式
//  $w(a, c) + w(b, d) \leq (\geq) w(a, d) + w(b, c)$ 
//  $dp[k][j] = \min(dp[k-1][i] + cost[i][j])$ 
//  $cost: (i, j)$ 
constexpr int N = 3E3 + 5;
constexpr ll inf = 4E18;
ll dp[N][N]; // 1-based
ll getCost(int l, int r) {}
void rec(int k, int l, int r, int optl, int opt) {
    if (l > r) return;
    int m = (l + r) >> 1, opt = -1;
    dp[k][m] = inf;
    for (int i = max(k, optl); i <= min(m, opt); i++) {
        // 注意  $i$  的範圍、 $get\_cost$  與  $dp$  的邊界
        ll cur = dp[k-1][i] + getCost(i, m);
        if (cur < dp[k][m]) dp[k][m] = cur, opt = i;
    }
    rec(k, l, m-1, optl, opt);
    rec(k, m+1, r, opt, opt);
}
void DNC() {
    // first build cost...
    for (int i = 1; i <= n; i++) dp[1][i] = getCost(1, i);
    for (int i = 2; i <= k; i++) rec(i, 1, n, 1, n);
    cout << dp[k][n] << "\n";
}

```

9.10 LiChao Segment Tree [2a9325]

```

// 應用:  $dp(i) = h(i) + \min/\max(A(j)x(i) + B(j))$ , for  $j \leq r(i)$ 
//  $y = c + m * x + b$ 
template<class T, class F = less<ll>>
struct LiChaoSeg {
    F cmp = F();
    static const T inf = max(numeric_limits<T>::lowest() / 2, numeric_limits<T>::max() / 2, F());
    struct Line {
        T m, b;
        Line(T m = 0, T b = inf) : m(m), b(b) {}
        T eval(T x) const { return m * x + b; }
    };
    struct Node {
        Line line;
        ll l = -1, r = -1;
    };
    ll n;
    vector<Node> nd;
    LiChaoSeg(ll n) : n(n) { newNode(); }
    void addLine(Line line) { update(0, 0, n, line); }
    void rangeAddLine(Line line, ll ql, ll qr) { rangeUpdate(0, 0, n, ql, qr, line); }
    T query(ll x) { return query(x, 0, 0, n); }
private:
    int newNode() {
        nd.emplace_back();
        return nd.size() - 1;
    }
    void update(int p, ll l, ll r, Line line) {
        ll m = (l + r) / 2;
        bool left = cmp(line.eval(l), nd[p].line.eval(l));
        bool mid = cmp(line.eval(m), nd[p].line.eval(m));
        if (mid) swap(nd[p].line, line);
    }
};

```

```

    if (r - l == 1) return;
    if (left != mid) {
        if (nd[p].l == -1) nd[p].l = newNode();
        update(nd[p].l, l, m, line);
    } else {
        if (nd[p].r == -1) nd[p].r = newNode();
        update(nd[p].r, m, r, line);
    }
}

void rangeUpdate
(int p, ll l, ll r, ll ql, ll qr, Line line) {
    if (r <= ql || l >= qr) return;
    if (ql <= l && r <= qr) return update(p, l, r, line);
    if (nd[p].l == -1) nd[p].l = newNode();
    if (nd[p].r == -1) nd[p].r = newNode();
    ll m = (l + r) / 2;
    rangeUpdate(nd[p].l, l, m, ql, qr, line);
    rangeUpdate(nd[p].r, m, r, ql, qr, line);
}

T query(ll x, int p, ll l, ll r) {
    if (p == -1) return inf;
    ll m = (l + r) / 2;
    if (x < m) return min(
        nd[p].line.eval(x), query(x, nd[p].l, l, m), cmp);
    else return min(
        nd[p].line.eval(x), query(x, nd[p].r, m, r), cmp);
}
};

```

10 Geometry

10.1 Basic [d41d8c]

```

template<class T>
struct Point {
    T x, y;
    Point(const T &x_ = 0, const T &y_ = 0) : x(x_), y(y_) {}
    template<class U>
    operator Point<U>() {
        return Point<U>(U(x), U(y));
    }
    Point &operator+=(const Point &p) & {
        x += p.x; y += p.y; return *this;
    }
    Point &operator-=(const Point &p) & {
        x -= p.x; y -= p.y; return *this;
    }
    Point &operator*=(const T &v) & {
        x *= v; y *= v; return *this;
    }
    Point &operator/=(const T &v) & {
        x /= v; y /= v; return *this;
    }
    Point operator-() const {
        return Point(-x, -y);
    }
    friend Point operator+(Point a, const Point &b) {
        return a + b;
    }
    friend Point operator-(Point a, const Point &b) {
        return a - b;
    }
    friend Point operator*(Point a, const T &b) {
        return a * b;
    }
    friend Point operator/(Point a, const T &b) {
        return a / b;
    }
    friend Point operator*(const T &a, Point b) {
        return b * a;
    }
    friend bool operator==(const Point &a, const Point &b) {
        return a.x == b.x && a.y == b.y;
    }
    friend istream &operator>>(istream &is, Point &p) {
        return is >> p.x >> p.y;
    }
    friend ostream &operator<<(ostream &os, const Point &p) {
        return os << "(" << p.x << ", " << p.y << ")";
    }
};

template<class T>
T dot(const Point<T> &a, const Point<T> &b) {
    return a.x * b.x + a.y * b.y;
}

template<class T>
T cross(const Point<T> &a, const Point<T> &b) {
    return a.x * b.y - a.y * b.x;
}

template<class T>
T square(const Point<T> &p) {
    return dot(p, p);
}

template<class T>
double length(const Point<T> &p) {
    return sqrt(double(square(p)));
}

template<class T>
Point<T> normalize(const Point<T> &p) {
    return p / length(p);
}

template<class T>

```

```

Point<T> rotate(const Point<T> &a) {
    return Point(-a.y, a.x);
}

template<class T>
int sgn(const Point<T> &a) {
    return a.y > 0 || (a.y == 0 && a.x > 0) ? 1 : -1;
}

template<class T>
struct Line {
    Point<T> a;
    Point<T> b;
    Line(const Point<T> &a_ = Point<T>(),
        const Point<T> &b_ = Point<T>()) : a(a_), b(b_) {}
};

template<class T>
double length(const Line<T> &l) {
    return length(l.a - l.b);
}

template<class T>
bool parallel(const Line<T> &l1, const Line<T> &l2) {
    return cross(l1.b - l1.a, l2.b - l2.a) == 0;
}

template<class T>
double distance(const Point<T> &a, const Point<T> &b) {
    return length(a - b);
}

template<class T>
double distancePL(const Point<T> &p, const Line<T> &l) {
    return abs(cross(l.a - l.b, l.a - p)) / length(l);
}

template<class T>
double distancePS(const Point<T> &p, const Line<T> &l) {
    if (dot(p - l.a, l.b - l.a) < 0)
        return distance(p, l.a);
    if (dot(p - l.b, l.a - l.b) < 0)
        return distance(p, l.b);
    return distancePL(p, l);
}

template<class T>
bool pointOnLineLeft(const Point<T> &p, const Line<T> &l) {
    return cross(l.b - l.a, p - l.a) > 0;
}

template<class T>
Point<T>
> lineIntersection(const Line<T> &l1, const Line<T> &l2) {
    return l1.a + (l1.b - l1.a) * (cross(l2.b - l2.a, l1.a - l1.b) / cross(l2.b - l2.a, l1.a - l1.b));
}

template<class T>
bool pointOnSegment(const Point<T> &p, const Line<T> &l) {
    return cross(p - l.a, l.b - l.a) == 0 &&
        min(l.a.x, l.b.x) <= p.x && p.x <= max(l.a.x, l.b.x)
        && min(
            l.a.y, l.b.y) <= p.y && p.y <= max(l.a.y, l.b.y);
}

template<class T>
bool pointInPolygon
(const Point<T> &a, const vector<Point<T>> &p) {
    int n = p.size(), t = 0;
    for (int i = 0; i < n; i++)
        if (pointOnSegment(a, Line(p[i], p[(i + 1) % n])))
            return true;
    for (int i = 0; i < n; i++) {
        auto u = p[i];
        auto v = p[(i + 1) % n];
        if (u.x < a.x
            && v.x >= a.x && pointOnLineLeft(a, Line(v, u)))
            t ^= 1;
        if (u.x >= a.x
            && v.x < a.x && pointOnLineLeft(a, Line(u, v)))
            t ^= 1;
    }
    return t == 1;
}

// 0 : strictly outside
// 1 : on boundary
// 2 : strictly inside
template<class T>
int pointInConvexPolygon
(const Point<T> &a, const vector<Point<T>> &p) {
    int n = p.size();
    if (n == 0)
        return 0;
    else if (n <= 2) {
        return pointOnSegment(a, Line(p[0], p.back()));
    }
    if (pointOnSegment(a, Line(p[0], p[1])) || pointOnSegment(a, Line(p[0], p[n - 1])))
        return 1;
    else if (pointOnLineLeft(a, Line(p[1], p[0])) || pointOnLineLeft(a, Line(p[0], p[n - 1])))
        return 0;
    int lo = 1, hi = n - 2;
    while (lo < hi) {
        int x = (lo + hi + 1) / 2;
        if (pointOnLineLeft(a, Line(p[0], p[x])))
            lo = x;
        else
            hi = x - 1;
    }
}

```

```

    }
    if (pointOnLineLeft(a, Line(p[lo], p[lo + 1]))) {
        return 2;
    } else {
        return pointOnSegment(a, Line(p[lo], p[lo + 1]));
    }
}

template<class T>
bool lineIntersectsPolygon
(const Line<T> &l, const vector<Point<T>> &p) {
    int n = p.size();
    Point<T> a = l.a, b = l.b;
    for (int i = 0; i < n; i++) {
        Line<T> seg(p[i], p[(i + 1) % n]);
        if (cross(b - a
            , seg.a - a) == 0 || cross(b - a, seg.b - a) == 0)
            return true;
        if (cross(b
            - a, seg.a - a) > 0 ^ cross(b - a, seg.b - a) > 0)
            return true;
    }
    return false;
}

// 0 : not intersect
// 1 : strictly intersect
// 2 : overlap
// 3 : intersect at endpoint
template<class T>
tuple<int, Point<T>, Point<T>> segmentIntersection
(const Line<T> &l1, const Line<T> &l2) {
    if (max(l1.a.x, l1.b.x) < min(l2.a.x, l2.b.x))
        return {0, Point<T>(), Point<T>()};
    if (min(l1.a.x, l1.b.x) > max(l2.a.x, l2.b.x))
        return {0, Point<T>(), Point<T>()};
    if (max(l1.a.y, l1.b.y) < min(l2.a.y, l2.b.y))
        return {0, Point<T>(), Point<T>()};
    if (min(l1.a.y, l1.b.y) > max(l2.a.y, l2.b.y))
        return {0, Point<T>(), Point<T>()};
    if (cross(l1.b - l1.a, l2.b - l2.a) == 0) {
        if (cross(l1.b - l1.a, l2.a - l1.a) != 0) {
            return {0, Point<T>(), Point<T>()};
        } else {
            auto maxx1 = max(l1.a.x, l1.b.x);
            auto minx1 = min(l1.a.x, l1.b.x);
            auto maxy1 = max(l1.a.y, l1.b.y);
            auto miny1 = min(l1.a.y, l1.b.y);
            auto maxx2 = max(l2.a.x, l2.b.x);
            auto minx2 = min(l2.a.x, l2.b.x);
            auto maxy2 = max(l2.a.y, l2.b.y);
            auto miny2 = min(l2.a.y, l2.b.y);
            Point<T> p1(max(minx1, minx2), max(miny1, miny2));
            Point<T> p2(min(maxx1, maxx2), min(maxy1, maxy2));
            if (!pointOnSegment(p1, l1))
                swap(p1.y, p2.y);
            if (p1 == p2) {
                return {3, p1, p2};
            } else {
                return {2, p1, p2};
            }
        }
    }
    auto cp1 = cross(l2.a - l1.a, l2.b - l1.a);
    auto cp2 = cross(l2.a - l1.b, l2.b - l1.b);
    auto cp3 = cross(l1.a - l2.a, l1.b - l2.a);
    auto cp4 = cross(l1.a - l2.b, l1.b - l2.b);
    if ((cp1 > 0 && cp2 > 0) || (cp1 < 0 && cp2
        < 0) || (cp3 > 0 && cp4 > 0) || (cp3 < 0 && cp4 < 0))
        return {0, Point<T>(), Point<T>()};
    Point p = lineIntersection(l1, l2);
    if (cp1 != 0 && cp2 != 0 && cp3 != 0 && cp4 != 0) {
        return {1, p, p};
    } else {
        return {3, p, p};
    }
}

template<class T>
double distanceSS(const Line<T> &l1, const Line<T> &l2) {
    if (get<0>(segmentIntersection(l1, l2)) != 0)
        return 0.0;
    return min({distancePS(l1.a, l2), distancePS(l1
        .b, l2), distancePS(l2.a, l1), distancePS(l2.b, l1)});
}

template<class T>
bool segmentInPolygon
(const Line<T> &l, const vector<Point<T>> &p) {
    int n = p.size();
    if (!pointInPolygon(l.a, p)) return false;
    if (!pointInPolygon(l.b, p)) return false;
    for (int i = 0; i < n; i++) {
        auto u = p[i];
        auto v = p[(i + 1) % n];
        auto w = p[(i + 2) % n];
        auto [t, p1, p2] = segmentIntersection(l, Line(u, v));
        if (t == 1) return false;
        if (t == 0) continue;
        if (t == 2) {
            if (pointOnSegment(v, l) && v != l.a && v != l.b)
                if (cross(v - u, w - v) > 0)
                    return false;
        } else {
            if (p1 != u && p1 != v) {
                if (pointOnLineLeft(l.a, Line(v, u))

```

```

                || pointOnLineLeft(l.b, Line(v, u)))
                    return false;
            } else if (p1 == v) {
                if (l.a == v) {
                    if (pointOnLineLeft(u, l)) {
                        if (pointOnLineLeft(w, l)
                            && pointOnLineLeft(w, Line(u, v)))
                            return false;
                    } else {
                        if (pointOnLineLeft(w, l)
                            || pointOnLineLeft(w, Line(u, v)))
                            return false;
                    }
                } else if (l.b == v) {
                    if (pointOnLineLeft(u, Line(l.b, l.a))) {
                        if (pointOnLineLeft(w, Line(l.b, l.a))
                            && pointOnLineLeft(w, Line(u, v)))
                            return false;
                    } else {
                        if (pointOnLineLeft(w, Line(l.b, l.a))
                            || pointOnLineLeft(w, Line(u, v)))
                            return false;
                    }
                }
            } else {
                if (pointOnLineLeft(u, l)) {
                    if (pointOnLineLeft(w, Line(l.b, l.a))
                        || pointOnLineLeft(w, Line(u, v)))
                        return false;
                } else {
                    if (pointOnLineLeft(w, l)
                        || pointOnLineLeft(w, Line(u, v)))
                        return false;
                }
            }
        }
    }
    return true;
}

template<class T>
vector<Point<T>> convexHull(vector<Point<T>> a) {
    sort(a.begin()
        , a.end(), [](const Point<T> &l, const Point<T> &r) {
            return l.x == r.x ? l.y < r.y : l.x < r.x;
        });
    a.resize(unique(a.begin(), a.end()) - a.begin());
    if (a.size() <= 1) return a;
    vector<Point<T>> h(a.size() + 1);
    int s = 0, t = 0;
    for (int i = 0; i < 2; i++, s = --t) {
        for (Point<T> p : a) {
            while (t >= s + 2 && cross
                (h[t - 1] - h[t - 2], p - h[t - 2]) <= 0) t--;
            h[t++] = p;
        }
        reverse(a.begin(), a.end());
    }
    return {h.begin(), h.begin() + t};
}

template<class T>
vector<Point<T>> hp(vector<Line<T>> lines) {
    sort(lines.begin(), lines.end(), [&](auto l1, auto l2) {
        auto d1 = l1.b - l1.a;
        auto d2 = l2.b - l2.a;
        if (sgn(d1) != sgn(d2))
            return sgn(d1) == 1;
        return cross(d1, d2) > 0;
    });
    deque<Line<T>> ls;
    deque<Point<T>> ps;
    for (auto l : lines) {
        if (ls.empty()) {
            ls.push_back(l);
            continue;
        }
        while (!ps.empty() && !pointOnLineLeft(ps.back(), l))
            ps.pop_back(), ls.pop_back();
        while (!ps.empty() && !pointOnLineLeft(ps[0], l))
            ps.pop_front(), ls.pop_front();
        if (cross(l.b - l.a, ls.back().b - ls.back().a) == 0) {
            if (dot
                (l.b - l.a, ls.back().b - ls.back().a) > 0) {
                if (!pointOnLineLeft(ls.back().a, l)) {
                    assert(ls.size() == 1);
                    ls[0] = l;
                }
                continue;
            }
            return {};
        }
        ps.push_back(lineIntersection(ls.back(), l));
        ls.push_back(l);
    }
    while (!ps.empty() && !pointOnLineLeft(ps.back(), ls[0]))
        ps.pop_back(), ls.pop_back();
    if (ls.size() <= 2) return {};
    ps.push_back(lineIntersection(ls[0], ls.back()));
    return vector(ps.begin(), ps.end());
}

using P = Point<ll>;

```

10.2 Min Euclidean Distance [F500d2]


```
// recursive solution
void minEuclideanDistance() {
    int n; cin >> n;
    const ll inf = 8E18;
    vector<Point<ll>> a(n);
    for (int i = 0; i < n; i++) {
        ll x, y;
        cin >> x >> y;
        a[i] = Point<ll>(x, y);
    }
    struct sortY { bool operator()(const Point<ll> &a, const Point<ll> &b) const { return a.y < b.y; } };
    struct sortXY {
        bool operator
        ()(const Point<ll> &a, const Point<ll> &b) const {
            return a.x == b.x ? a.y < b.y : a.x < b.x;
        }
    };
    sort(a.begin(), a.end(), sortXY());
    vector<Point<ll>> t(n);
    auto divide = [&](auto &&self, int l, int r) -> ll {
        if (l == r) return inf;
        int m = (l + r) / 2;
        ll ans = min(self(self, l, m), self(self, m + 1, r));
        ll midval = a[m].x;
        ll p = 0;
        for (int i = l; i <= r; i++)
            if ((midval - a[i].x) * (midval - a[i].x) <= ans)
                t[p++] = a[i];
        sort(t.begin(), t.end(), sortY());
        for (int i = 0; i < p; i++) {
            for (int j = i + 1; j < p; j++) {
                ans = min(ans, square(t[i].x - t[j].x));
                if ((t[i].y - t[j].y) * (t[i].y - t[j].y) > ans) break;
            }
        }
        return ans;
    };
    cout << divide(divide, 0, n - 1) << "\n";
}

// K-D tree solution
template<class Info>
struct KDTree { // 1-indexed
    static constexpr int DIM = Info::DIM;
    int n, rt;
    vector<Info> info;
    vector<int> l, r;
    KDTree(int n, const vector
    <Info> &info) : n(n), info(info), l(n + 1), r(n + 1) {
        rt = rebuild(1, n);
    }
    void pull(int p) {
        info[p].L = info[p].R = info[p].x;
        info[p].pull(info[l[p]], info[r[p]]);
        for (int ch : {l[p], r[p]}) {
            if (!ch) continue;
            for (int k = 0; k < DIM; k++) {
                info[p]
                ].L[k] = min(info[p].L[k], info[ch].L[k]);
                info[p]
                ].R[k] = max(info[p].R[k], info[ch].R[k]);
            }
        }
    }
    int rebuild(int l, int r, int dep = 0) {
        if (r == l) return 0;
        int m = (l + r) / 2;
        double avx =
        0, avy = 0, vax = 0, vay = 0; // average variance
        for (int i = l; i < r; i++)
            avx += info[i].x[0], avy += info[i].x[1];
        avx /= (double)(r - l), avy /= (double)(r - l);
        for (int i = l; i < r; i++) {
            vax += (info[i].x[0] - avx) * (info[i].x[0] - avx);
            vay += (info[i].x[1] - avy) * (info[i].x[1] - avy);
        }
        if (vax >= vay) {
            nth_element(info.begin
            () + l, info.begin() + m, info.begin() + r,
            [&](const Info &x, const
            Info &y) { return x.x[0] < y.x[0]; });
        } else {
            nth_element(info.begin
            () + l, info.begin() + m, info.begin() + r,
            [&](const Info &x, const
            Info &y) { return x.x[1] < y.x[1]; });
        }
        this->l[m] = rebuild(l, m, (dep + 1) % DIM);
        this->r[m] = rebuild(m + 1, r, (dep + 1) % DIM);
        pull(m); return m;
    }
};

ll ans = 9E18;
ll dist(int a, int b) {
    return (info[a].x[0]
    - info[b].x[0]) * (info[a].x[0] - info[b].x[0]) +
    (info[a].x[1]
    - info[b].x[1]) * (info[a].x[1] - info[b].x[1]);
}

void query(int p, int x) {
    if (!p) return;
    if (p != x) ans = min(ans, dist(x, p));
}
```

```
ll distl = info[x].f(info[l[p]]);
ll distr = info[x].f(info[r[p]]);
if (distl < ans && distr < ans) {
    if (distl < distr) {
        query(l[p], x);
        if (distr < ans) query(r[p], x);
    } else {
        query(r[p], x);
        if (distl < ans) query(l[p], x);
    }
} else {
    if (distl < ans) query(l[p], x);
    if (distr < ans) query(r[p], x);
}
}
};

struct Info {
    static constexpr int DIM = 2;
    array<ll, DIM> x, l, r;
    ll distl, distr;
    ll f(const Info &i) {
        ll ret = 0;
        if (i.L[0]
        > x[0]) ret += (i.L[0] - x[0]) * (i.L[0] - x[0]);
        if (i.R[0]
        < x[0]) ret += (x[0] - i.R[0]) * (x[0] - i.R[0]);
        if (i.L[1]
        > x[1]) ret += (i.L[1] - x[1]) * (i.L[1] - x[1]);
        if (i.R[1]
        < x[1]) ret += (x[1] - i.R[1]) * (x[1] - i.R[1]);
        return ret;
    }
    void pull(const Info &l, const Info &r) {
        distl = f(l), distr = f(r);
    }
};

};
```

10.3 Max Euclidean Distance [4aa1f0]

```
template<class T>
tuple<T, int, int> maxEuclideanDistance(vector<Point<T>> a) {
    auto get = [&](const Point<T> &p, const Line<T> &l) -> T {
        return abs(cross(l.a - l.b, l.a - p));
    };
    T res = 0; int n = a.size(), x, y, id = 2;
    a.push_back(a.front());
    if (n <= 2) return {square(a[0] - a[1]), 0, 1};
    for (int i = 0; i < n; i++) {
        while (get(a[id], Line(a[i], a[i + 1]))
        <= get(a[(id + 1) % n], Line(a[i], a[i + 1])))
            id = (id + 1) % n;
        if (res < square(a[i] - a[id])) {
            res = square(a[i] - a[id]);
            x = i, y = id;
        }
        if (res < square(a[i + 1] - a[id])) {
            res = square(a[i + 1] - a[id]);
            x = i + 1, y = id;
        }
    }
    return {res, x, y};
}
```

10.4 Lattice Points [d50756]

```
void latticePoints() {
    // Area 求法與 Polygon 內整數點數
    int n; cin >> n;
    vector<Point<ll>> polygon(n);
    for (int i = 0; i < n; i++) cin >> polygon[i];
    ll area = 0;
    for (int i = 0; i < n; i++)
        area += cross(polygon[i], polygon[(i + 1) % n]);
    area = abs(area);
    auto countBoundaryPoints
    = [&](const vector<Point<ll>> &polygon) -> ll {
        ll res = 0;
        int n = polygon.size();
        for (int i = 0; i < n; i++) {
            ll dx = polygon[(i + 1) % n].x - polygon[i].x;
            ll dy = polygon[(i + 1) % n].y - polygon[i].y;
            res += __gcd(abs(dx), abs(dy));
        }
        return res;
    };
    ll res = countBoundaryPoints(polygon);
    ll ans = (area - res + 2) / 2;
    cout << ans << " " << res << "\n";
}
```

10.5 Min Circle Cover [9380bf]

```
template<class T>
pair<T, Point<T>> minCircleCover(vector<Point<T>> &a) {
    random_shuffle(a.begin(), a.end());
    int n = a.size();
    Point<T> c = a[0]; T r = 0;
    for (int i = 1; i < n; i++) {
        if (T(length(c - a[i]) - r) > 0.0) {
            c = a[i], r = 0;
            for (int j = 0; j < i; j++) {
                if (T(length(c - a[j]) - r) > 0.0) {

```

```

        c = (a[i] + a[j]) / 2.0;
        r = length(c - a[i]);
        for (int k = 0; k < j; k++) {
            if (T(length(c - a[k]) - r) > 0.0) {
                Point<T> p = (a[j] + a[i]) / 2;
                Point<T> q = (a[j] + a[k]) / 2;
                if (cross(a[j] - a[i],
                        a[k] - a[j]) == 0) continue;
                c = lineIntersection(Line(p,
                    p + rotate(a[j] - a[i])), Line
                    (q, q + rotate(a[k] - a[j])));
                r = length(c - a[i]);
            }
        }
    }
}
return {r, c};
}

```

10.6 Min Rectangle Cover [ede9f33]

```

template<class T>
pair<double, vector
<Point<double>>> minRectangleCover(vector<Point<T>> p) {
    if (p.size() <= 2) return {0, {}};
    auto get = [&](const Point<T> &p, const Line<T> &l) -> T {
        return abs(cross(l.a - l.b, l.a - p));
    }; // line 到 p 圍成的四邊形面積
    int n = p.size(), j = 2, l = 1, r = 1;
    p.push_back(p.front());
    double ans = 8E18;
    vector<Point<double>> ps;
    for (int i = 0; i < n; i++) {
        while (get(p[j], Line(p[i], p[i + 1]))
            <= get(p[(j + 1) % n], Line(p[i], p[i + 1])))
            j = (j + 1) % n;
        while (dot(p[i + 1] - p[i], p[r] - p[i])
            <= dot(p[i + 1] - p[i], p[(r + 1) % n] - p[i]))
            r = (r + 1) % n;
        if (i == 0) l = j;
        while (dot(p[i + 1] - p[i], p[l] - p[i])
            >= dot(p[i + 1] - p[i], p[(l + 1) % n] - p[i]))
            l = (l + 1) % n;
        double area = get(p[j], Line(p[i], p[i + 1]));
        double w = dot(p[i + 1] - p[i], p[i + 1],
            p[l] - p[i]) + dot(p[i + 1] - p[i], p[r] - p[i]);
        area *= w / square(p[i + 1] - p[i]);
        if (area < ans) {
            ps.clear(), ans = area;
            Line l1(p[i], p[i + 1]);
            for (auto u : {p[r], p[j], p[l], p[i]}) {
                if (u == l1.b) {
                    ps.push_back(u);
                    l1 = Line(u, u + rotate(l1.b - l1.a));
                } else {
                    Line l2 = Line(u, u + rotate(l1.b - l1.a));
                    Point<T> res = lineIntersection(l1, l2);
                    ps.push_back(res);
                    l1 = Line(res, u);
                }
            }
        }
    }
    return {ans, ps};
}

```

10.7 Polygon Union Area [a86535]

```

template<class T>
double polygonUnion(vector<vector<Point<T>>> ps) {
    int n = ps.size();
    for (auto &v : ps) v.push_back(v[0]);
    double res = 0;
    auto seg = [&](const Point<T>
        &o, const Point<T> &a, const Point<T> &b) -> double {
        if (b.x - a
            .x == 0) return double((o.y - a.y) / (b.y - a.y));
        return double((o.x - a.x) / (b.x - a.x));
    };
    for (int pi = 0; pi < n; pi++) {
        for (int i = 0; i + 1 < ps[pi].size(); i++) {
            vector<pair<double, int>> e;
            e.emplace_back(0, 0);
            e.emplace_back(1, 0);
            for (int pj = 0; pj < n; pj++) {
                if (pi == pj) continue;
                for (int j = 0; j + 1 < ps[pj].size(); j++) {
                    T c1 = cross(ps[pi][i + 1]
                        - ps[pi][i], ps[pj][j] - ps[pi][i]);
                    T c2 = cross(ps[pi][i + 1]
                        - ps[pi][i], ps[pj][j + 1] - ps[pi][i]);
                    if (c1 == 0 && c2 == 0) {
                        if (dot(ps[
                            pi][i + 1] - ps[pi][i], ps[pj][j + 1]
                                - ps[pj][j]) > 0 && pi > pj) {
                            e.emplace_back(seg(ps[pj][j],
                                ps[pi][i], ps[pi][i + 1]), 1);
                        }
                        e.emplace_back
                            (seg(ps[pj][j + 1], ps
                                [pi][i], ps[pi][i + 1]), -1);
                    }
                }
            }
        }
    }
}

```

```

        }
    } else {
        T s1 = cross(ps[pj][j + 1] -
            ps[pj][j], ps[pi][i] - ps[pj][j]);
        T s2 = cross(ps[pj][j + 1] - ps[pj
            ][j], ps[pi][i + 1] - ps[pj][j]);
        if (c1 >= 0 && c2 < 0)
            e.emplace_back(s1 / (s1 - s2), 1);
        else if (c1 < 0 && c2 >= 0) e
            .emplace_back(s1 / (s1 - s2), -1);
    }
}
sort(e.begin(), e.end());
double pre = clamp(e[0].first, 0.0, 1.0), sum = 0;
int cov = e[0].second;
for (int j = 1; j < e.size(); j++) {
    double now = clamp(e[j].first, 0.0, 1.0);
    if (!cov) sum += now - pre;
    cov += e[j].second;
    pre = now;
}
res +=
    double(cross(ps[pi][i], ps[pi][i + 1])) * sum;
}
return res / 2;
}

```

11 Polynomial

11.1 FFT [e258ad]

```

const double PI = acos(-1.0);
using cd = complex<double>;
vector<int> rev;
void fft(vector<cd> &a, bool inv) {
    int n = a.size();
    if (int(rev.size()) != n) {
        int k = __builtin_ctz(n) - 1;
        rev.resize(n);
        for (int i = 0; i < n; i++)
            rev[i] = rev[i >> 1] >> 1 | (i & 1) << k;
    }
    for (int i = 0; i < n; i++)
        if (rev[i] < i) swap(a[i], a[rev[i]]);
    for (int k = 1; k < n; k *= 2) {
        double ang = (inv ? -1 : 1) * PI / k;
        cd wn(cos(ang), sin(ang));
        for (int i = 0; i < n; i += 2 * k) {
            cd w(1);
            for (int j = 0; j < k; j++, w = w * wn) {
                cd u = a[i + j];
                cd v = a[i + j + k] * w;
                a[i + j] = u + v;
                a[i + j + k] = u - v;
            }
        }
        if (inv) for (auto &x : a) x /= n;
    }
}
template<class T>
vector<T> Multiple(const vector<T> &a, const vector<T> &b) {
    vector<cd> fa(a.begin(), a.end()), fb(b.begin(), b.end());
    int n = 1, tot = a.size() + b.size() - 1;
    while (n < tot) n *= 2;
    fa.resize(n), fb.resize(n);
    fft(fa, false), fft(fb, false);
    for (int i = 0; i < n; i++)
        fa[i] = fa[i] * fb[i];
    fft(fa, true);
    vector<T> res(tot);
    for (int i = 0; i < tot; i++)
        res[i] = fa[i].real(); // use llround if need
    return res;
}

```

11.2 NTT [6caf78]

```

template<int V, int P>
Mint<P> CInv = Mint<P>(V).inv();
vector<int> rev;
template<int P>
vector<Mint<P>> roots{0, 1};
template<int P>
Mint<P> findPrimitiveRoot() {
    Mint<P> i = 2;
    int k = __builtin_ctz(P - 1);
    while (true) {
        if (power(i, (P - 1) / 2) != 1) break;
        i += 1;
    }
    return power(i, (P - 1) >> k);
}
template<int P>
Mint<P> primitiveRoot = findPrimitiveRoot<P>();
template<>
Mint<998244353> primitiveRoot<998244353>{31};
template<int P>
void dft(vector<Mint<P>> &a) {
    int n = a.size();
    if (int(rev.size()) != n) {

```

```

    int k = __builtin_ctz(n) - 1;
    rev.resize(n);
    for (int i = 0; i < n; i++)
        rev[i] = rev[i >> 1] >> 1 | (i & 1) << k;
}
for (int i = 0; i < n; i++)
    if (rev[i] < i) swap(a[i], a[rev[i]]);
if (roots<P>.size() < n) {
    int k = __builtin_ctz(roots<P>.size());
    roots<P>.resize(n);
    while ((1 << k) < n) {
        auto e = power(primitiveRoot
            <P>, 1 << (__builtin_ctz(P - 1) - k - 1));
        for (int i = 1 << (k - 1); i < (1 << k); i++) {
            roots<P>[2 * i] = roots<P>[i];
            roots<P>[2 * i + 1] = roots<P>[i] * e;
        }
        k++;
    }
}
for (int k = 1; k < n; k *= 2) {
    for (int i = 0; i < n; i += 2 * k) {
        for (int j = 0; j < k; j++) {
            Mint<P> u = a[i + j];
            Mint<P> v = a[i + j + k] * roots<P>[k + j];
            a[i + j] = u + v;
            a[i + j + k] = u - v;
        }
    }
}
}
template<int P>
void idft(vector<Mint<P>> &a) {
    int n = a.size();
    reverse(a.begin() + 1, a.end());
    dft(a);
    Mint<P> inv = (1 - P) / n;
    for (int i = 0; i < n; i++) a[i] *= inv;
}
template<int P = 998244353>
struct Poly : public vector<Mint<P>> {
    using Value = Mint<P>;
    Poly() : vector<Value>() {}
    explicit Poly(int n) : vector<Value>(n) {}
    explicit Poly(const vector<Value> &a) : vector<Value>(a) {}
    Poly(const initializer_list<Value> &a) : vector<Value>(a) {}
    template<class InputIt, class = _RequireInputIter<InputIt>>
    explicit Poly(InputIt first, InputIt last) : vector<Value>(first, last) {}
    template<class F>
    explicit Poly(int n, F f) : vector<Value>(n) {
        for (int i = 0; i < n; i++)
            (*this)[i] = f(i);
    }
    Poly shift(int k) const {
        if (k >= 0) {
            auto b = *this;
            b.insert(b.begin(), k, 0);
            return b;
        } else if (this->size() <= -k) {
            return Poly();
        } else {
            return Poly(this->begin() + (-k), this->end());
        }
    }
    Poly trunc(int k) const {
        Poly f = *this;
        f.resize(k);
        return f;
    }
    friend Poly operator+(const Poly &a, const Poly &b) {
        Poly res(max(a.size(), b.size()));
        for (int i = 0; i < a.size(); i++)
            res[i] += a[i];
        for (int i = 0; i < b.size(); i++)
            res[i] += b[i];
        return res;
    }
    friend Poly operator-(const Poly &a, const Poly &b) {
        Poly res(max(a.size(), b.size()));
        for (int i = 0; i < a.size(); i++)
            res[i] += a[i];
        for (int i = 0; i < b.size(); i++)
            res[i] -= b[i];
        return res;
    }
    friend Poly operator-(const Poly &a) {
        vector<Value> res(a.size());
        for (int i = 0; i < int(res.size()); i++)
            res[i] = -a[i];
        return Poly(res);
    }
    friend Poly operator*(Poly a, Poly b) {
        if (a.size() == 0 || b.size() == 0)
            return Poly();
        if (a.size() < b.size()) swap(a, b);
        int n = 1, tot = a.size() + b.size() - 1;
        while (n < tot) n *= 2;
        if (((P - 1) & (n - 1)) != 0 || b.size() < 128) {
            Poly c(a.size() + b.size() - 1);
            for (int i = 0; i < a.size(); i++)
                for (int j = 0; j < b.size(); j++)
                    c[i + j] += a[i] * b[j];
            return c;
        }
        a.resize(n), b.resize(n);
        dft(a), dft(b);
        for (int i = 0; i < n; i++)
            a[i] *= b[i];
        idft(a);
        a.resize(tot);
        return a;
    }
    friend Poly operator/(Poly a, Value b) {
        for (int i = 0; i < int(a.size()); i++)
            a[i] /= b;
        return a;
    }
    Poly &operator+=(Poly b) {
        return (*this) = (*this) + b;
    }
    Poly &operator-=(Poly b) {
        return (*this) = (*this) - b;
    }
    Poly &operator*=(Poly b) {
        return (*this) = (*this) * b;
    }
    Poly &operator*=(Value b) {
        return (*this) = (*this) * b;
    }
    Poly &operator/=(Value b) {
        return (*this) = (*this) / b;
    }
    Poly deriv() const {
        if (this->empty()) return Poly();
        Poly res(this->size() - 1);
        for (int i = 0; i < this->size() - 1; i++)
            res[i] = (i + 1) * (*this)[i + 1];
        return res;
    }
    Poly integr() const {
        Poly res(this->size() + 1);
        for (int i = 0; i < this->size(); i++)
            res[i + 1] = (*this)[i] / (i + 1);
        return res;
    }
    Poly inv(int m) const {
        Poly x((*this)[0].inv());
        int k = 1;
        while (k < m) {
            k *= 2;
            x = (x * (Poly{2} - trunc(k) * x)).trunc(k);
        }
        return x.trunc(m);
    }
    Poly log(int m) const {
        return (deriv() * inv(m)).integr().trunc(m);
    }
    Poly exp(int m) const {
        Poly x{1};
        int k = 1;
        while (k < m) {
            k *= 2;
            x = (x * (Poly{1} - x.log(k) + trunc(k))).trunc(k);
        }
        return x.trunc(m);
    }
    Poly pow(int k, int m) const {
        int i = 0;
        while (i < this->size() && (*this)[i] == 0) i++;
        if (i == this->size() || 1LL * i * k >= m)
            return Poly(m);
        Value v = (*this)[i];
        auto f = shift(-i) * v.inv();
        return (f.log(m - i * k).exp(m - i * k).shift(i * k) * power(v, k);
    }
    Poly sqrt(int m) const {
        Poly x{1};
        int k = 1;
        while (k < m) {
            k *= 2;
            x = (x + (trunc(k) * x.inv(k)).trunc(k)) * CInv<2, P>;
        }
        return x.trunc(m);
    }
    Poly mult(Poly b) const {
        if (b.size() == 0) return Poly();
        int n = b.size();
        reverse(b.begin(), b.end());
        return ((*this) * b).shift(-(n - 1));
    }
}

```

```

vector<Value> eval(vector<Value> x) const {
    if (this->size() == 0)
        return vector<Value>(x.size(), 0);
    const int n = max(x.size(), this->size());
    vector<Poly> q(4 * n);
    vector<Value> ans(x.size());
    x.resize(n);
    function<void(
        int, int, int)> build = [&](int p, int l, int r) {
        if (r - l == 1) {
            q[p] = Poly{1, -x[l]};
        } else {
            int m = (l + r) / 2;
            build(2 * p, l, m);
            build(2 * p + 1, m, r);
            q[p] = q[2 * p] * q[2 * p + 1];
        }
    };
    build(1, 0, n);
    function<void(int, int, int, const Poly &)>
    work = [&](int p, int l, int r, const Poly &num) {
        if (r - l == 1) {
            if (l < int(ans.size()))
                ans[l] = num[0];
        } else {
            int m = (l + r) / 2;
            work(2 * p, l, m, num.mulT(q[2 * p + 1]).resize(m - l));
            work(2 * p + 1, m, r, num.mulT(q[2 * p]).resize(r - m));
        }
    };
    work(1, 0, n, mulT(q[1].inv(n)));
    return ans;
}

template<int P = 998244353>
Poly<P> berlekampMassey(const Poly<P> &s) {
    Poly<P> c, oldC;
    int f = -1;
    for (int i = 0; i < s.size(); i++) {
        auto delta = s[i];
        for (int j = 1; j <= c.size(); j++)
            delta -= c[j - 1] * s[i - j];
        if (delta == 0) continue;
        if (f == -1) {
            c.resize(i + 1);
            f = i;
        } else {
            auto d = oldC;
            d *= -1;
            d.insert(d.begin(), 1);
            Mint<P> df1 = 0;
            for (int j = 1; j <= d.size(); j++)
                df1 += d[j - 1] * s[f + 1 - j];
            assert(df1 != 0);
            auto coef = delta / df1;
            d *= coef;
            Poly<P> zeros(i - f - 1);
            zeros.insert(zeros.end(), d.begin(), d.end());
            d = zeros;
            auto temp = c;
            c += d;
            if (i - temp.size() > f - oldC.size()) {
                oldC = temp;
                f = i;
            }
        }
    }
    c *= -1;
    c.insert(c.begin(), 1);
    return c;
}

template<int P = 998244353>
Mint<P> linearRecurrence(Poly<P> p, Poly<P> q, ll n) {
    int m = q.size() - 1;
    while (n > 0) {
        auto newq = q;
        for (int i = 1; i <= m; i += 2)
            newq[i] *= -1;
        auto newp = p * newq;
        newq = q * newq;
        for (int i = 0; i < m; i++)
            p[i] = newp[i * 2 + n % 2];
        for (int i = 0; i <= m; i++)
            q[i] = newq[i * 2];
        n /= 2;
    }
    return p[0] / q[0];
}

```

12 Else

12.1 Python [fbb420]

```

from decimal import * # 無誤差浮點數
from fractions import * # 分數
from random import *
from math import *
# set decimal prec if it could overflow in precision
setcontext
(Context(prec=10, Emax=MAX_EMAX, rounding=ROUND_FLOOR))

```

```

# read and print
x = int(input())
a, b, c = list(map(Fraction, input().split()))
arr = list(map(Decimal, input().split()))
print(*arr)
# set
st = set(); st.add((a, b)); st.remove((a, b))
if not (a, b) in st:
# dict
d = dict(); d[(a, b)] = 1; del d[(a, b)]
for (a, b) in d.items():
# random
arr = [randint(l, r) for i in range(size)]
choice([8, 6, 4, 1]) # random pick one
shuffle(arr)

```

12.2 Bigint [70f2dd]

```

struct Bigint { // not support hex division
private:
    using u128 = __uint128_t;
    static const int digit = 9; // hex: 7
    static const int base = 10; // hex: 16
    static const int B = power(ll(base), digit);
    Bigint(vector<int> x, int sgn) : x(x), sgn(sgn) {}
    template<class U>
    vector<int> norm(vector<U> a) {
        if (a.empty()) return {0};
        for (int i = 0; i < a.size(); i++) {
            U c = a[i];
            a[i] = c % B;
            c /= B;
            if (c) {
                if (i == a.size() - 1) a.push_back(c);
                else a[i + 1] += c;
            }
        }
        while (a.size() > 1 && a.back() == 0) a.pop_back();
        return {a.begin(), a.end()};
    }
    void resign() {
        sgn = x.back() == 0 ? 1 : sgn;
    }
    vector<int> Add(vector<int> a, vector<int> b) {
        int n = max(a.size(), b.size());
        a.resize(n), b.resize(n);
        for (int i = 0; i < n; i++) a[i] += b[i];
        return norm(a);
    }
    vector<int> Minus(vector<int> a, vector<int> b) {
        int n = max(a.size(), b.size());
        a.resize(n), b.resize(n);
        for (int i = 0; i < n; i++) {
            a[i] -= b[i];
            if (a[i] < 0) a[i] += B, a[i + 1]--;
        }
        return norm(a);
    }
    int toInt(char c) const {
        if (isdigit(c)) return c - '0';
        else return c - 'A' + 10;
    }
    char toChar(int c) const {
        if (c < 10) return c + '0';
        else return c - 10 + 'A';
    }
public:
    int sgn = 1;
    vector<int> x; // 反著存
    Bigint() : x {0}, sgn(1) {}
    Bigint(ll a) {
        *this = Bigint(std::to_string(a));
    }
    Bigint(string s) {
        if (s.empty()) {
            *this = Bigint();
        }
        if (s[0] == '-') s.erase(s.begin()), sgn = -1;
        int add = 0, cnt = 0, b = 1;
        while (s.size()) {
            if (cnt == digit) {
                x.push_back(add), add = cnt = 0;
                b = 1;
            }
            add += toInt(s.back()) * b;
            cnt++, b *= base;
            s.pop_back();
        }
        if (add) x.push_back(add);
        x = norm(x);
    }
    int size() const { return x.size(); }
    Bigint abs() const { return Bigint(x, 1); }
    string to_string() const {
        string res;
        for (int i = 0; i < x.size(); i++) {
            string add;
            int v = x[i];
            for (int j = 0; j < digit; j++)
                add += toChar(v % base), v /= base;
            res += add;
        }
    }
}

```

```

    while (res.size() > 1 && res.back() == '0')
        res.pop_back();
    if (sgn == -1) res += '-';
    reverse(res.begin(), res.end());
    return res;
}
Bigint &operator-() const { return Bigint(x, -sgn); }
Bigint &operator+=(const Bigint &rhs) & {
    if (sgn != rhs.sgn) return *this -= (-rhs);
    x = Add(x, rhs.x), resign();
    return *this;
}
Bigint &operator-=(const Bigint &rhs) & {
    if (sgn != rhs.sgn) return *this += -rhs;
    if (abs() < rhs.abs()) return *this = -(rhs - *this);
    x = Minus(x, rhs.x), resign();
    return *this;
}
friend Bigint &operator+(Bigint lhs, Bigint rhs) {
    return lhs += rhs;
}
friend Bigint &operator-(Bigint lhs, Bigint rhs) {
    return lhs -= rhs;
}
friend istream &operator>>(istream &is, Bigint &a) {
    string v; is >> v; a = Bigint(v); return is;
}
friend ostream &operator<<(ostream &os, const Bigint &a) {
    os << a.to_string();
    return os;
}
friend bool operator<(const Bigint &a, const Bigint &b) {
    if (a.sgn != b.sgn) return a.sgn < b.sgn;
    if (a.x.size() != b.x.size()) {
        return a.x.size() < b.x.size();
    } else {
        for (int i = a.x.size() - 1; i >= 0; i--)
            if (a.x[i] != b.x[i]) return a.x[i] < b.x[i];
        return 0;
    }
}
friend bool operator>(const Bigint &a, const Bigint &b) {
    if (a.sgn != b.sgn) return a.sgn > b.sgn;
    if (a.x.size() != b.x.size()) {
        return a.x.size() > b.x.size();
    } else {
        for (int i = a.x.size() - 1; i >= 0; i--)
            if (a.x[i] != b.x[i]) return a.x[i] > b.x[i];
        return 0;
    }
}
friend bool operator==(const Bigint &a, const Bigint &b) {
    return a.sgn == b.sgn && a.x == b.x;
}
friend bool operator!=(const Bigint &a, const Bigint &b) {
    return a.sgn != b.sgn || a.x != b.x;
}
friend bool operator>=(const Bigint &a, const Bigint &b) {
    return a == b || a > b;
}
friend bool operator<=(const Bigint &a, const Bigint &b) {
    return a == b || a < b;
}
};

```

12.3 Multiple [fc8c31]

```

// Require:
// Mint, NTT ~constructor and * operator
const int P1 = 1045430273;
const int P2 = 1051721729;
const int P3 = 1053818881;
const int r12 = Mint<P2>(Mint<P1>::getMod()).inv().x;
const int r13 = Mint<P3>(Mint<P1>::getMod()).inv().x;
const int r23 = Mint<P3>(Mint<P2>::getMod()).inv().x;
const int r1323 = Mint<P3>(ll(r13) * r23).x;
const ll w1 = Mint<P1>::getMod();
const ll w2 = w1 * Mint<P2>::getMod();
// Garner's Algorithm
template <typename T>
vector<T> arbitraryMult
    (const vector<int> &a, const vector<int> &b) {
    int n = a.size(), m = b.size();
    Poly<P1> x = Poly<P1>
        >(a.begin(), a.end()) * Poly<P1>(b.begin(), b.end());
    Poly<P2> y = Poly<P2>
        >(a.begin(), a.end()) * Poly<P2>(b.begin(), b.end());
    Poly<P3> z = Poly<P3>
        >(a.begin(), a.end()) * Poly<P3>(b.begin(), b.end());
    vector<T> res(x.size());
    for (int i = 0; i < x.size(); i++) {
        ll p = x[i].x;
        ll q = (y[i].x + P2 - p) * r12 % P2;
        ll r =
            ((z[i] + P3 - p) * r1323 + (P3 - q) * r23).x % P3;
        res[i] = (T(r) * w2 + q * w1 + p);
    }
    return res;
}
private:
vector<int> Multiple(vector<int> a, vector<int> b) {
    return norm(arbitraryMult<u128>(a, b));
}

```

```

}
vector<int> smallMul(vector<int> a, int v) {
    vector<ll> res(a.begin(), a.end());
    for (auto &x : res) x *= v;
    return norm(res);
}
public:
Bigint &operator*=(const Bigint &rhs) & {
    x = rhs.size()
        == 1 ? smallMul(x, rhs.x[0]) : Multiple(x, rhs.x);
    sgn *= rhs.sgn, resign();
    return *this;
}
friend Bigint &operator*(Bigint lhs, Bigint rhs) {
    return lhs *= rhs;
}
}

```

12.4 Division [7e7c85]

```

private:
vector<int> smallDiv(vector<int> a, int v) {
    ll add = 0;
    for (int i = a.size() - 1; i >= 0; i--) {
        add = add * B + a[i];
        int q = add / v;
        a[i] = q, add %= v;
    }
    return norm(a);
}
Bigint &operator<=(int n) & {
    if (!x.empty()) {
        vector<int> add(n, 0);
        x.insert(x.begin(), add.begin(), add.end());
    }
    return *this;
}
Bigint &operator>=(int n) & {
    x = vector
        <int>(x.begin() + min(n, int(x.size())), x.end());
    x = norm(x);
    return *this;
}
friend Bigint &operator<<(Bigint lhs, int n) {
    return lhs <= n;
}
friend Bigint &operator>>(Bigint lhs, int n) {
    return lhs >= n;
}
public:
Bigint &operator/=(const Bigint &rhs) & {
    Bigint a = abs(), b = rhs.abs();
    sgn *= rhs.sgn;
    if (a < b) return *this = Bigint();
    if (b.size() == 1) {
        x = smallDiv(x, rhs.x[0]);
    } else {
        Bigint inv = 1LL * B * B / b.x.back();
        Bigint pre = 0, res = 0;
        int d = a.size() + 1 - b.size();
        int cur = 2, bcur = 1;
        while (inv != pre || bcur < b.size()) {
            bcur = min(bcur < 1, b.size());
            res.x = {b.x.end() - bcur, b.x.end()};
            pre = inv;
            inv *= ((Bigint
                (2) << (cur + bcur - 1)) - inv * res);
            cur = min(cur < 1, d);
            inv.x = {inv.x.end() - cur, inv.x.end()};
        }
        inv.x = {inv.x.end() - d, inv.x.end()};
        res = a * inv;
        res >= a.size();
        Bigint mul = res * b;
        while (mul + b <= a) res += 1, mul += b;
        x = norm(res.x);
    }
    return *this;
}
Bigint &operator%=(const Bigint &rhs) & {
    return *this = *this - (*this / rhs) * rhs;
}
friend Bigint &operator/(Bigint lhs, Bigint rhs) {
    return lhs /= rhs;
}
friend Bigint &operator%(Bigint lhs, Bigint rhs) {
    return lhs %= rhs;
}
}

```

12.5 Division-Python [110bd8]

```

from decimal import * # 無誤差浮點數
setcontext(
    Context(prec=4000000, Emax=4000000, rounding=ROUND_FLOOR))
t = int(input())
for i in range(t):
    a, b = map(Decimal, input().split())
    d, m = divmod(a, b)
    print(d, m)

```