Machine Learning Course Project

Robert W Allen

March 9, 2016

Download and Clean Testing and Training Data for Project

Download the Testing and Training Data from the web.

There are fields that have the Excel division by year indicator as a value. These need to be converted to NA.

```
train_url <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-
training.csv"
download.file(train_url, "pml-training.csv")
raw_train_data <- read.csv("pml-training.csv", na.strings = c("NA", ""))

test_url <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-
testing.csv"
download.file(test_url, "pml-testing.csv")
raw_test_data <- read.csv("pml-testing.csv", na.strings = c("NA", ""))
```

Descriptive Analysis

Before we can begin the anlaysis we need to understand the variables, especially the one one we hope to predict, classe.

```
head(raw_train_data)
```

```
##   X user_name raw_timestamp_part_1 raw_timestamp_part_2   cvtd_timestamp
## 1 1  carlitos           1323084231               788290 05/12/2011 11:23
## 2 2  carlitos           1323084231               808298 05/12/2011 11:23
## 3 3  carlitos           1323084231               820366 05/12/2011 11:23
## 4 4  carlitos           1323084232               120339 05/12/2011 11:23
## 5 5  carlitos           1323084232               196328 05/12/2011 11:23
## 6 6  carlitos           1323084232               304277 05/12/2011 11:23
##   new_window num_window roll_belt pitch_belt yaw_belt total_accel_belt
## 1         no         11      1.41       8.07    -94.4                3
## 2         no         11      1.41       8.07    -94.4                3
## 3         no         11      1.42       8.07    -94.4                3
## 4         no         12      1.48       8.05    -94.4                3
## 5         no         12      1.48       8.07    -94.4                3
## 6         no         12      1.45       8.06    -94.4                3
##   kurtosis_roll_belt kurtosis_picth_belt kurtosis_yaw_belt
## 1               <NA>                <NA>              <NA>
## 2               <NA>                <NA>              <NA>
## 3               <NA>                <NA>              <NA>
```

```
## 4               <NA>                <NA>              <NA>
## 5               <NA>                <NA>              <NA>
## 6               <NA>                <NA>              <NA>
##   skewness_roll_belt skewness_roll_belt.1 skewness_yaw_belt max_roll_belt
## 1               <NA>                <NA>              <NA>            NA
## 2               <NA>                <NA>              <NA>            NA
## 3               <NA>                <NA>              <NA>            NA
## 4               <NA>                <NA>              <NA>            NA
## 5               <NA>                <NA>              <NA>            NA
## 6               <NA>                <NA>              <NA>            NA
##   max_picth_belt max_yaw_belt min_roll_belt min_pitch_belt min_yaw_belt
## 1             NA         <NA>            NA             NA         <NA>
## 2             NA         <NA>            NA             NA         <NA>
## 3             NA         <NA>            NA             NA         <NA>
## 4             NA         <NA>            NA             NA         <NA>
## 5             NA         <NA>            NA             NA         <NA>
## 6             NA         <NA>            NA             NA         <NA>
##   amplitude_roll_belt amplitude_pitch_belt amplitude_yaw_belt
## 1                  NA                   NA               <NA>
## 2                  NA                   NA               <NA>
## 3                  NA                   NA               <NA>
## 4                  NA                   NA               <NA>
## 5                  NA                   NA               <NA>
## 6                  NA                   NA               <NA>
##   var_total_accel_belt avg_roll_belt stddev_roll_belt var_roll_belt
## 1                   NA            NA                NA            NA
## 2                   NA            NA                NA            NA
## 3                   NA            NA                NA            NA
## 4                   NA            NA                NA            NA
## 5                   NA            NA                NA            NA
## 6                   NA            NA                NA            NA
##   avg_pitch_belt stddev_pitch_belt var_pitch_belt avg_yaw_belt
## 1             NA                NA             NA           NA
## 2             NA                NA             NA           NA
## 3             NA                NA             NA           NA
## 4             NA                NA             NA           NA
## 5             NA                NA             NA           NA
## 6             NA                NA             NA           NA
##   stddev_yaw_belt var_yaw_belt gyros_belt_x gyros_belt_y gyros_belt_z
## 1              NA           NA         0.00         0.00        -0.02
## 2              NA           NA         0.02         0.00        -0.02
## 3              NA           NA         0.00         0.00        -0.02
## 4              NA           NA         0.02         0.00        -0.03
## 5              NA           NA         0.02         0.02        -0.02
## 6              NA           NA         0.02         0.00        -0.02
##   accel_belt_x accel_belt_y accel_belt_z magnet_belt_x magnet_belt_y
## 1          -21            4           22            -3           599
## 2          -22            4           22            -7           608
## 3          -20            5           23            -2           600
## 4          -22            3           21            -6           604
```

```
## 5          -21            2           24            -6           600
## 6          -21            4           21             0           603
##   magnet_belt_z roll_arm pitch_arm yaw_arm total_accel_arm var_accel_arm
## 1          -313     -128      22.5    -161              34            NA
## 2          -311     -128      22.5    -161              34            NA
## 3          -305     -128      22.5    -161              34            NA
## 4          -310     -128      22.1    -161              34            NA
## 5          -302     -128      22.1    -161              34            NA
## 6          -312     -128      22.0    -161              34            NA
##   avg_roll_arm stddev_roll_arm var_roll_arm avg_pitch_arm stddev_pitch_arm
## 1           NA              NA           NA            NA               NA
## 2           NA              NA           NA            NA               NA
## 3           NA              NA           NA            NA               NA
## 4           NA              NA           NA            NA               NA
## 5           NA              NA           NA            NA               NA
## 6           NA              NA           NA            NA               NA
##   var_pitch_arm avg_yaw_arm stddev_yaw_arm var_yaw_arm gyros_arm_x
## 1            NA          NA             NA          NA        0.00
## 2            NA          NA             NA          NA        0.02
## 3            NA          NA             NA          NA        0.02
## 4            NA          NA             NA          NA        0.02
## 5            NA          NA             NA          NA        0.00
## 6            NA          NA             NA          NA        0.02
##   gyros_arm_y gyros_arm_z accel_arm_x accel_arm_y accel_arm_z magnet_arm_x
## 1        0.00       -0.02        -288         109        -123         -368
## 2       -0.02       -0.02        -290         110        -125         -369
## 3       -0.02       -0.02        -289         110        -126         -368
## 4       -0.03        0.02        -289         111        -123         -372
## 5       -0.03        0.00        -289         111        -123         -374
## 6       -0.03        0.00        -289         111        -122         -369
##   magnet_arm_y magnet_arm_z kurtosis_roll_arm kurtosis_picth_arm
## 1          337          516              <NA>               <NA>
## 2          337          513              <NA>               <NA>
## 3          344          513              <NA>               <NA>
## 4          344          512              <NA>               <NA>
## 5          337          506              <NA>               <NA>
## 6          342          513              <NA>               <NA>
##   kurtosis_yaw_arm skewness_roll_arm skewness_pitch_arm skewness_yaw_arm
## 1             <NA>              <NA>               <NA>             <NA>
## 2             <NA>              <NA>               <NA>             <NA>
## 3             <NA>              <NA>               <NA>             <NA>
## 4             <NA>              <NA>               <NA>             <NA>
## 5             <NA>              <NA>               <NA>             <NA>
## 6             <NA>              <NA>               <NA>             <NA>
##   max_roll_arm max_picth_arm max_yaw_arm min_roll_arm min_pitch_arm
## 1           NA            NA          NA           NA            NA
## 2           NA            NA          NA           NA            NA
## 3           NA            NA          NA           NA            NA
## 4           NA            NA          NA           NA            NA
## 5           NA            NA          NA           NA            NA
```

```
## 6           NA             NA          NA           NA             NA
##   min_yaw_arm amplitude_roll_arm amplitude_pitch_arm amplitude_yaw_arm
## 1          NA                 NA                  NA                NA
## 2          NA                 NA                  NA                NA
## 3          NA                 NA                  NA                NA
## 4          NA                 NA                  NA                NA
## 5          NA                 NA                  NA                NA
## 6          NA                 NA                  NA                NA
##   roll_dumbbell pitch_dumbbell yaw_dumbbell kurtosis_roll_dumbbell
## 1      13.05217      -70.49400    -84.87394                   <NA>
## 2      13.13074      -70.63751    -84.71065                   <NA>
## 3      12.85075      -70.27812    -85.14078                   <NA>
## 4      13.43120      -70.39379    -84.87363                   <NA>
## 5      13.37872      -70.42856    -84.85306                   <NA>
## 6      13.38246      -70.81759    -84.46500                   <NA>
##   kurtosis_picth_dumbbell kurtosis_yaw_dumbbell skewness_roll_dumbbell
## 1                    <NA>                  <NA>                   <NA>
## 2                    <NA>                  <NA>                   <NA>
## 3                    <NA>                  <NA>                   <NA>
## 4                    <NA>                  <NA>                   <NA>
## 5                    <NA>                  <NA>                   <NA>
## 6                    <NA>                  <NA>                   <NA>
##   skewness_pitch_dumbbell skewness_yaw_dumbbell max_roll_dumbbell
## 1                    <NA>                  <NA>                NA
## 2                    <NA>                  <NA>                NA
## 3                    <NA>                  <NA>                NA
## 4                    <NA>                  <NA>                NA
## 5                    <NA>                  <NA>                NA
## 6                    <NA>                  <NA>                NA
##   max_picth_dumbbell max_yaw_dumbbell min_roll_dumbbell min_pitch_dumbbell
## 1                 NA             <NA>                NA                 NA
## 2                 NA             <NA>                NA                 NA
## 3                 NA             <NA>                NA                 NA
## 4                 NA             <NA>                NA                 NA
## 5                 NA             <NA>                NA                 NA
## 6                 NA             <NA>                NA                 NA
##   min_yaw_dumbbell amplitude_roll_dumbbell amplitude_pitch_dumbbell
## 1             <NA>                      NA                       NA
## 2             <NA>                      NA                       NA
## 3             <NA>                      NA                       NA
## 4             <NA>                      NA                       NA
## 5             <NA>                      NA                       NA
## 6             <NA>                      NA                       NA
##   amplitude_yaw_dumbbell total_accel_dumbbell var_accel_dumbbell
## 1                   <NA>                   37                 NA
## 2                   <NA>                   37                 NA
## 3                   <NA>                   37                 NA
## 4                   <NA>                   37                 NA
## 5                   <NA>                   37                 NA
## 6                   <NA>                   37                 NA
```

```
##   avg_roll_dumbbell stddev_roll_dumbbell var_roll_dumbbell
## 1                NA                   NA                NA
## 2                NA                   NA                NA
## 3                NA                   NA                NA
## 4                NA                   NA                NA
## 5                NA                   NA                NA
## 6                NA                   NA                NA
##   avg_pitch_dumbbell stddev_pitch_dumbbell var_pitch_dumbbell
## 1                 NA                    NA                 NA
## 2                 NA                    NA                 NA
## 3                 NA                    NA                 NA
## 4                 NA                    NA                 NA
## 5                 NA                    NA                 NA
## 6                 NA                    NA                 NA
##   avg_yaw_dumbbell stddev_yaw_dumbbell var_yaw_dumbbell gyros_dumbbell_x
## 1               NA                  NA               NA                0
## 2               NA                  NA               NA                0
## 3               NA                  NA               NA                0
## 4               NA                  NA               NA                0
## 5               NA                  NA               NA                0
## 6               NA                  NA               NA                0
##   gyros_dumbbell_y gyros_dumbbell_z accel_dumbbell_x accel_dumbbell_y
## 1            -0.02             0.00             -234               47
## 2            -0.02             0.00             -233               47
## 3            -0.02             0.00             -232               46
## 4            -0.02            -0.02             -232               48
## 5            -0.02             0.00             -233               48
## 6            -0.02             0.00             -234               48
##   accel_dumbbell_z magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z
## 1             -271              -559               293               -65
## 2             -269              -555               296               -64
## 3             -270              -561               298               -63
## 4             -269              -552               303               -60
## 5             -270              -554               292               -68
## 6             -269              -558               294               -66
##   roll_forearm pitch_forearm yaw_forearm kurtosis_roll_forearm
## 1         28.4         -63.9        -153                  <NA>
## 2         28.3         -63.9        -153                  <NA>
## 3         28.3         -63.9        -152                  <NA>
## 4         28.1         -63.9        -152                  <NA>
## 5         28.0         -63.9        -152                  <NA>
## 6         27.9         -63.9        -152                  <NA>
##   kurtosis_picth_forearm kurtosis_yaw_forearm skewness_roll_forearm
## 1                   <NA>                  <NA>                  <NA>
## 2                   <NA>                  <NA>                  <NA>
## 3                   <NA>                  <NA>                  <NA>
## 4                   <NA>                  <NA>                  <NA>
## 5                   <NA>                  <NA>                  <NA>
## 6                   <NA>                  <NA>                  <NA>
##   skewness_pitch_forearm skewness_yaw_forearm max_roll_forearm
```

```
## 1                   <NA>                 <NA>                NA
## 2                   <NA>                 <NA>                NA
## 3                   <NA>                 <NA>                NA
## 4                   <NA>                 <NA>                NA
## 5                   <NA>                 <NA>                NA
## 6                   <NA>                 <NA>                NA
##   max_picth_forearm max_yaw_forearm min_roll_forearm min_pitch_forearm
## 1                NA            <NA>               NA                NA
## 2                NA            <NA>               NA                NA
## 3                NA            <NA>               NA                NA
## 4                NA            <NA>               NA                NA
## 5                NA            <NA>               NA                NA
## 6                NA            <NA>               NA                NA
##   min_yaw_forearm amplitude_roll_forearm amplitude_pitch_forearm
## 1            <NA>                     NA                      NA
## 2            <NA>                     NA                      NA
## 3            <NA>                     NA                      NA
## 4            <NA>                     NA                      NA
## 5            <NA>                     NA                      NA
## 6            <NA>                     NA                      NA
##   amplitude_yaw_forearm total_accel_forearm var_accel_forearm
## 1                  <NA>                   36                NA
## 2                  <NA>                   36                NA
## 3                  <NA>                   36                NA
## 4                  <NA>                   36                NA
## 5                  <NA>                   36                NA
## 6                  <NA>                   36                NA
##   avg_roll_forearm stddev_roll_forearm var_roll_forearm avg_pitch_forearm
## 1               NA                  NA               NA                NA
## 2               NA                  NA               NA                NA
## 3               NA                  NA               NA                NA
## 4               NA                  NA               NA                NA
## 5               NA                  NA               NA                NA
## 6               NA                  NA               NA                NA
##   stddev_pitch_forearm var_pitch_forearm avg_yaw_forearm
## 1                   NA                NA              NA
## 2                   NA                NA              NA
## 3                   NA                NA              NA
## 4                   NA                NA              NA
## 5                   NA                NA              NA
## 6                   NA                NA              NA
##   stddev_yaw_forearm var_yaw_forearm gyros_forearm_x gyros_forearm_y
## 1                 NA              NA            0.03            0.00
## 2                 NA              NA            0.02            0.00
## 3                 NA              NA            0.03           -0.02
## 4                 NA              NA            0.02           -0.02
## 5                 NA              NA            0.02            0.00
## 6                 NA              NA            0.02           -0.02
##   gyros_forearm_z accel_forearm_x accel_forearm_y accel_forearm_z
## 1           -0.02             192             203            -215
```

```
## 2           -0.02              192              203            -216
## 3            0.00              196              204            -213
## 4            0.00              189              206            -214
## 5           -0.02              189              206            -214
## 6           -0.03              193              203            -215
##   magnet_forearm_x magnet_forearm_y magnet_forearm_z classe
## 1              -17              654              476      A
## 2              -18              661              473      A
## 3              -18              658              469      A
## 4              -16              658              469      A
## 5              -17              655              473      A
## 6               -9              660              478      A
```

```
summary(raw_train_data)
```

```
##        X            user_name    raw_timestamp_part_1 raw_timestamp_part_2
##  Min.   :    1   adelmo  :3892   Min.   :1.322e+09    Min.   :   294
##  1st Qu.: 4906   carlitos:3112   1st Qu.:1.323e+09    1st Qu.:252912
##  Median : 9812   charles :3536   Median :1.323e+09    Median :496380
##  Mean   : 9812   eurico  :3070   Mean   :1.323e+09    Mean   :500656
##  3rd Qu.:14717   jeremy  :3402   3rd Qu.:1.323e+09    3rd Qu.:751891
##  Max.   :19622   pedro   :2610   Max.   :1.323e+09    Max.   :998801
##
##           cvtd_timestamp  new_window    num_window      roll_belt
##  28/11/2011 14:14: 1498   no :19216   Min.   :  1.0   Min.   :-28.90
##  05/12/2011 11:24: 1497   yes:  406   1st Qu.:222.0   1st Qu.:  1.10
##  30/11/2011 17:11: 1440               Median :424.0   Median :113.00
##  05/12/2011 11:25: 1425               Mean   :430.6   Mean   : 64.41
##  02/12/2011 14:57: 1380               3rd Qu.:644.0   3rd Qu.:123.00
##  02/12/2011 13:34: 1375               Max.   :864.0   Max.   :162.00
##  (Other)         :11007
##    pitch_belt          yaw_belt       total_accel_belt kurtosis_roll_belt
##  Min.   :-55.8000   Min.   :-180.00   Min.   : 0.00    #DIV/0!  :   10
##  1st Qu.:  1.7600   1st Qu.: -88.30   1st Qu.: 3.00    -1.908453:    2
##  Median :  5.2800   Median : -13.00   Median :17.00    -0.016850:    1
##  Mean   :  0.3053   Mean   : -11.21   Mean   :11.31    -0.021024:    1
##  3rd Qu.: 14.9000   3rd Qu.:  12.90   3rd Qu.:18.00    -0.025513:    1
##  Max.   : 60.3000   Max.   : 179.00   Max.   :29.00    (Other)  :  391
##                                                        NA's     :19216
##  kurtosis_picth_belt kurtosis_yaw_belt skewness_roll_belt
##  #DIV/0!  :   32     #DIV/0!:  406     #DIV/0!  :    9
##  47.000000:    4     NA's   :19216     0.000000 :    4
##  -0.150950:    3                       0.422463 :    2
##  -0.684748:    3                       -0.003095:    1
##  -1.750749:    3                       -0.010002:    1
##  (Other)  :  361                       (Other)  :  389
##  NA's     :19216                       NA's     :19216
##  skewness_roll_belt.1 skewness_yaw_belt max_roll_belt     max_picth_belt
##  #DIV/0!  :   32      #DIV/0!:  406     Min.   :-94.300   Min.   : 3.00
##  0.000000 :    4      NA's   :19216     1st Qu.:-88.000   1st Qu.: 5.00
```

```
##  -2.156553:    3                         Median : -5.100   Median :18.00
##  -3.072669:    3                         Mean   : -6.667   Mean   :12.92
##  -6.324555:    3                         3rd Qu.: 18.500   3rd Qu.:19.00
##  (Other)  :  361                         Max.   :180.000   Max.   :30.00
##  NA's     :19216                         NA's   :19216     NA's   :19216
##   max_yaw_belt   min_roll_belt     min_pitch_belt   min_yaw_belt
##  -1.1   :   30   Min.   :-180.00   Min.   : 0.00   -1.1   :   30
##  -1.4   :   29   1st Qu.: -88.40   1st Qu.: 3.00   -1.4   :   29
##  -1.2   :   26   Median :  -7.85   Median :16.00   -1.2   :   26
##  -0.9   :   24   Mean   : -10.44   Mean   :10.76   -0.9   :   24
##  -1.3   :   22   3rd Qu.:   9.05   3rd Qu.:17.00   -1.3   :   22
##  (Other):  275   Max.   : 173.00   Max.   :23.00   (Other):  275
##  NA's   :19216   NA's   :19216     NA's   :19216   NA's   :19216
##  amplitude_roll_belt amplitude_pitch_belt amplitude_yaw_belt
##  Min.   :  0.000     Min.   : 0.000       #DIV/0!:   10
##  1st Qu.:  0.300     1st Qu.: 1.000       0.00   :   12
##  Median :  1.000     Median : 1.000       0.0000 :  384
##  Mean   :  3.769     Mean   : 2.167       NA's   :19216
##  3rd Qu.:  2.083     3rd Qu.: 2.000
##  Max.   :360.000     Max.   :12.000
##  NA's   :19216       NA's   :19216
##  var_total_accel_belt avg_roll_belt    stddev_roll_belt var_roll_belt
##  Min.   : 0.000       Min.   :-27.40   Min.   : 0.000   Min.   :  0.000
##  1st Qu.: 0.100       1st Qu.:  1.10   1st Qu.: 0.200   1st Qu.:  0.000
##  Median : 0.200       Median :116.35   Median : 0.400   Median :  0.100
##  Mean   : 0.926       Mean   : 68.06   Mean   : 1.337   Mean   :  7.699
##  3rd Qu.: 0.300       3rd Qu.:123.38   3rd Qu.: 0.700   3rd Qu.:  0.500
##  Max.   :16.500       Max.   :157.40   Max.   :14.200   Max.   :200.700
##  NA's   :19216        NA's   :19216    NA's   :19216    NA's   :19216
##  avg_pitch_belt    stddev_pitch_belt var_pitch_belt    avg_yaw_belt
##  Min.   :-51.400   Min.   :0.000     Min.   : 0.000   Min.   :-138.300
##  1st Qu.:  2.025   1st Qu.:0.200     1st Qu.: 0.000   1st Qu.: -88.175
##  Median :  5.200   Median :0.400     Median : 0.100   Median :  -6.550
##  Mean   :  0.520   Mean   :0.603     Mean   : 0.766   Mean   :  -8.831
##  3rd Qu.: 15.775   3rd Qu.:0.700     3rd Qu.: 0.500   3rd Qu.:  14.125
##  Max.   : 59.700   Max.   :4.000     Max.   :16.200   Max.   : 173.500
##  NA's   :19216     NA's   :19216     NA's   :19216    NA's   :19216
##  stddev_yaw_belt    var_yaw_belt        gyros_belt_x
##  Min.   :  0.000   Min.   :    0.000   Min.   :-1.040000
##  1st Qu.:  0.100   1st Qu.:    0.010   1st Qu.:-0.030000
##  Median :  0.300   Median :    0.090   Median : 0.030000
##  Mean   :  1.341   Mean   :  107.487   Mean   :-0.005592
##  3rd Qu.:  0.700   3rd Qu.:    0.475   3rd Qu.: 0.110000
##  Max.   :176.600   Max.   :31183.240   Max.   : 2.220000
##  NA's   :19216     NA's   :19216
##   gyros_belt_y       gyros_belt_z      accel_belt_x       accel_belt_y
##  Min.   :-0.64000   Min.   :-1.4600   Min.   :-120.000   Min.   :-69.00
##  1st Qu.: 0.00000   1st Qu.:-0.2000   1st Qu.: -21.000   1st Qu.:  3.00
##  Median : 0.02000   Median :-0.1000   Median : -15.000   Median : 35.00
##  Mean   : 0.03959   Mean   :-0.1305   Mean   :  -5.595   Mean   : 30.15
```

```
##  3rd Qu.: 0.11000   3rd Qu.:-0.0200   3rd Qu.:  -5.000   3rd Qu.: 61.00
##  Max.   : 0.64000   Max.   : 1.6200   Max.   :  85.000   Max.   :164.00
##
##   accel_belt_z     magnet_belt_x   magnet_belt_y   magnet_belt_z
##  Min.   :-275.00   Min.   :-52.0   Min.   :354.0   Min.   :-623.0
##  1st Qu.:-162.00   1st Qu.:  9.0   1st Qu.:581.0   1st Qu.:-375.0
##  Median :-152.00   Median : 35.0   Median :601.0   Median :-320.0
##  Mean   : -72.59   Mean   : 55.6   Mean   :593.7   Mean   :-345.5
##  3rd Qu.:  27.00   3rd Qu.: 59.0   3rd Qu.:610.0   3rd Qu.:-306.0
##  Max.   : 105.00   Max.   :485.0   Max.   :673.0   Max.   : 293.0
##
##     roll_arm         pitch_arm          yaw_arm          total_accel_arm
##  Min.   :-180.00   Min.   :-88.800   Min.   :-180.0000   Min.   : 1.00
##  1st Qu.: -31.77   1st Qu.:-25.900   1st Qu.: -43.1000   1st Qu.:17.00
##  Median :   0.00   Median :  0.000   Median :   0.0000   Median :27.00
##  Mean   :  17.83   Mean   : -4.612   Mean   :  -0.6188   Mean   :25.51
##  3rd Qu.:  77.30   3rd Qu.: 11.200   3rd Qu.:  45.8750   3rd Qu.:33.00
##  Max.   : 180.00   Max.   : 88.500   Max.   : 180.0000   Max.   :66.00
##
##  var_accel_arm     avg_roll_arm     stddev_roll_arm    var_roll_arm
##  Min.   :  0.00   Min.   :-166.67   Min.   :  0.000   Min.   :    0.000
##  1st Qu.:  9.03   1st Qu.: -38.37   1st Qu.:  1.376   1st Qu.:    1.898
##  Median : 40.61   Median :   0.00   Median :  5.702   Median :   32.517
##  Mean   : 53.23   Mean   :  12.68   Mean   : 11.201   Mean   :  417.264
##  3rd Qu.: 75.62   3rd Qu.:  76.33   3rd Qu.: 14.921   3rd Qu.:  222.647
##  Max.   :331.70   Max.   : 163.33   Max.   :161.964   Max.   :26232.208
##  NA's   :19216    NA's   :19216     NA's   :19216     NA's   :19216
##  avg_pitch_arm     stddev_pitch_arm var_pitch_arm       avg_yaw_arm
##  Min.   :-81.773   Min.   : 0.000   Min.   :   0.000   Min.   :-173.440
##  1st Qu.:-22.770   1st Qu.: 1.642   1st Qu.:   2.697   1st Qu.: -29.198
##  Median :  0.000   Median : 8.133   Median :  66.146   Median :   0.000
##  Mean   : -4.901   Mean   :10.383   Mean   : 195.864   Mean   :   2.359
##  3rd Qu.:  8.277   3rd Qu.:16.327   3rd Qu.: 266.576   3rd Qu.:  38.185
##  Max.   : 75.659   Max.   :43.412   Max.   :1884.565   Max.   : 152.000
##  NA's   :19216     NA's   :19216    NA's   :19216      NA's   :19216
##  stddev_yaw_arm     var_yaw_arm         gyros_arm_x
##  Min.   :  0.000   Min.   :    0.000   Min.   :-6.37000
##  1st Qu.:  2.577   1st Qu.:    6.642   1st Qu.:-1.33000
##  Median : 16.682   Median :  278.309   Median : 0.08000
##  Mean   : 22.270   Mean   : 1055.933   Mean   : 0.04277
##  3rd Qu.: 35.984   3rd Qu.: 1294.850   3rd Qu.: 1.57000
##  Max.   :177.044   Max.   :31344.568   Max.   : 4.87000
##  NA's   :19216     NA's   :19216
##   gyros_arm_y       gyros_arm_z       accel_arm_x       accel_arm_y
##  Min.   :-3.4400   Min.   :-2.3300   Min.   :-404.00   Min.   :-318.0
##  1st Qu.:-0.8000   1st Qu.:-0.0700   1st Qu.:-242.00   1st Qu.: -54.0
##  Median :-0.2400   Median : 0.2300   Median : -44.00   Median :  14.0
##  Mean   :-0.2571   Mean   : 0.2695   Mean   : -60.24   Mean   :  32.6
##  3rd Qu.: 0.1400   3rd Qu.: 0.7200   3rd Qu.:  84.00   3rd Qu.: 139.0
##  Max.   : 2.8400   Max.   : 3.0200   Max.   : 437.00   Max.   : 308.0
```

```
##
##   accel_arm_z       magnet_arm_x     magnet_arm_y     magnet_arm_z
##  Min.   :-636.00   Min.   :-584.0   Min.   :-392.0   Min.   :-597.0
##  1st Qu.:-143.00   1st Qu.:-300.0   1st Qu.:  -9.0   1st Qu.: 131.2
##  Median : -47.00   Median : 289.0   Median : 202.0   Median : 444.0
##  Mean   : -71.25   Mean   : 191.7   Mean   : 156.6   Mean   : 306.5
##  3rd Qu.:  23.00   3rd Qu.: 637.0   3rd Qu.: 323.0   3rd Qu.: 545.0
##  Max.   : 292.00   Max.   : 782.0   Max.   : 583.0   Max.   : 694.0
##
##  kurtosis_roll_arm kurtosis_picth_arm kurtosis_yaw_arm skewness_roll_arm
##  #DIV/0! :   78    #DIV/0! :   80     #DIV/0! :   11   #DIV/0! :   77
##  -0.02438:    1    -0.00484:    1     0.55844 :    2   -0.00051:    1
##  -0.04190:    1    -0.01311:    1     0.65132 :    2   -0.00696:    1
##  -0.05051:    1    -0.02967:    1     -0.01548:    1   -0.01884:    1
##  -0.05695:    1    -0.07394:    1     -0.01749:    1   -0.03359:    1
##  (Other) :  324    (Other) :  322     (Other) :  389   (Other) :  325
##  NA's    :19216    NA's    :19216     NA's    :19216   NA's    :19216
##  skewness_pitch_arm skewness_yaw_arm  max_roll_arm     max_picth_arm
##  #DIV/0! :   80     #DIV/0! :   11   Min.   :-73.100   Min.   :-173.000
##  -0.00184:    1     -1.62032:    2   1st Qu.: -0.175   1st Qu.:  -1.975
##  -0.01185:    1     0.55053 :    2   Median :  4.950   Median :  23.250
##  -0.01247:    1     -0.00311:    1   Mean   : 11.236   Mean   :  35.751
##  -0.02063:    1     -0.00562:    1   3rd Qu.: 26.775   3rd Qu.:  95.975
##  (Other) :  322     (Other) :  389   Max.   : 85.500   Max.   : 180.000
##  NA's    :19216     NA's    :19216   NA's   :19216     NA's   :19216
##   max_yaw_arm     min_roll_arm    min_pitch_arm      min_yaw_arm
##  Min.   : 4.00   Min.   :-89.10   Min.   :-180.00   Min.   : 1.00
##  1st Qu.:29.00   1st Qu.:-41.98   1st Qu.: -72.62   1st Qu.: 8.00
##  Median :34.00   Median :-22.45   Median : -33.85   Median :13.00
##  Mean   :35.46   Mean   :-21.22   Mean   : -33.92   Mean   :14.66
##  3rd Qu.:41.00   3rd Qu.:  0.00   3rd Qu.:   0.00   3rd Qu.:19.00
##  Max.   :65.00   Max.   : 66.40   Max.   : 152.00   Max.   :38.00
##  NA's   :19216   NA's   :19216    NA's   :19216     NA's   :19216
##  amplitude_roll_arm amplitude_pitch_arm amplitude_yaw_arm
##  Min.   :  0.000    Min.   :  0.000     Min.   : 0.00
##  1st Qu.:  5.425    1st Qu.:  9.925     1st Qu.:13.00
##  Median : 28.450    Median : 54.900     Median :22.00
##  Mean   : 32.452    Mean   : 69.677     Mean   :20.79
##  3rd Qu.: 50.960    3rd Qu.:115.175     3rd Qu.:28.75
##  Max.   :119.500    Max.   :360.000     Max.   :52.00
##  NA's   :19216      NA's   :19216       NA's   :19216
##  roll_dumbbell     pitch_dumbbell     yaw_dumbbell
##  Min.   :-153.71   Min.   :-149.59   Min.   :-150.871
##  1st Qu.: -18.49   1st Qu.: -40.89   1st Qu.: -77.644
##  Median :  48.17   Median : -20.96   Median :  -3.324
##  Mean   :  23.84   Mean   : -10.78   Mean   :   1.674
##  3rd Qu.:  67.61   3rd Qu.:  17.50   3rd Qu.:  79.643
##  Max.   : 153.55   Max.   : 149.40   Max.   : 154.952
##
##  kurtosis_roll_dumbbell kurtosis_picth_dumbbell kurtosis_yaw_dumbbell
```

```
##  #DIV/0!:    5          -0.5464:    2          #DIV/0!:  406
##  -0.2583:    2          -0.9334:    2          NA's   :19216
##  -0.3705:    2          -2.0833:    2
##  -0.5855:    2          -2.0851:    2
##  -2.0851:    2          -2.0889:    2
##  (Other):  393          (Other):  396
##  NA's   :19216          NA's   :19216
##  skewness_roll_dumbbell skewness_pitch_dumbbell skewness_yaw_dumbbell
##  #DIV/0!:    4          -0.2328:    2          #DIV/0!:  406
##  -0.9324:    2          -0.3521:    2          NA's   :19216
##  0.1110 :    2          -0.7036:    2
##  1.0312 :    2          0.1090 :    2
##  -0.0082:    1          1.0326 :    2
##  (Other):  395          (Other):  396
##  NA's   :19216          NA's   :19216
##  max_roll_dumbbell max_picth_dumbbell max_yaw_dumbbell min_roll_dumbbell
##  Min.   :-70.10    Min.   :-112.90    -0.6   :   20    Min.   :-149.60
##  1st Qu.:-27.15    1st Qu.: -66.70    0.2    :   19    1st Qu.: -59.67
##  Median : 14.85    Median :  40.05    -0.8   :   18    Median : -43.55
##  Mean   : 13.76    Mean   :  32.75    -0.3   :   16    Mean   : -41.24
##  3rd Qu.: 50.58    3rd Qu.: 133.22    -0.2   :   15    3rd Qu.: -25.20
##  Max.   :137.00    Max.   : 155.00    (Other):  318    Max.   :  73.20
##  NA's   :19216     NA's   :19216      NA's   :19216    NA's   :19216
##  min_pitch_dumbbell min_yaw_dumbbell amplitude_roll_dumbbell
##  Min.   :-147.00    -0.6   :   20    Min.   :  0.00
##  1st Qu.: -91.80    0.2    :   19    1st Qu.: 14.97
##  Median : -66.15    -0.8   :   18    Median : 35.05
##  Mean   : -33.18    -0.3   :   16    Mean   : 55.00
##  3rd Qu.:  21.20    -0.2   :   15    3rd Qu.: 81.04
##  Max.   : 120.90    (Other):  318    Max.   :256.48
##  NA's   :19216      NA's   :19216    NA's   :19216
##  amplitude_pitch_dumbbell amplitude_yaw_dumbbell total_accel_dumbbell
##  Min.   :  0.00           #DIV/0!:    5          Min.   : 0.00
##  1st Qu.: 17.06           0.00   :  401          1st Qu.: 4.00
##  Median : 41.73           NA's   :19216          Median :10.00
##  Mean   : 65.93                                  Mean   :13.72
##  3rd Qu.: 99.55                                  3rd Qu.:19.00
##  Max.   :273.59                                  Max.   :58.00
##  NA's   :19216
##  var_accel_dumbbell avg_roll_dumbbell stddev_roll_dumbbell
##  Min.   :  0.000    Min.   :-128.96   Min.   :  0.000
##  1st Qu.:  0.378    1st Qu.: -12.33   1st Qu.:  4.639
##  Median :  1.000    Median :  48.23   Median : 12.204
##  Mean   :  4.388    Mean   :  23.86   Mean   : 20.761
##  3rd Qu.:  3.434    3rd Qu.:  64.37   3rd Qu.: 26.356
##  Max.   :230.428    Max.   : 125.99   Max.   :123.778
##  NA's   :19216      NA's   :19216     NA's   :19216
##  var_roll_dumbbell  avg_pitch_dumbbell stddev_pitch_dumbbell
##  Min.   :    0.00   Min.   :-70.73     Min.   : 0.000
##  1st Qu.:   21.52   1st Qu.:-42.00     1st Qu.: 3.482
```

```
##  Median :  148.95   Median :-19.91     Median : 8.089
##  Mean   : 1020.27   Mean   :-12.33     Mean   :13.147
##  3rd Qu.:  694.65   3rd Qu.: 13.21     3rd Qu.:19.238
##  Max.   :15321.01   Max.   : 94.28     Max.   :82.680
##  NA's   :19216      NA's   :19216      NA's   :19216
##  var_pitch_dumbbell avg_yaw_dumbbell   stddev_yaw_dumbbell
##  Min.   :   0.00    Min.   :-117.950   Min.   :  0.000
##  1st Qu.:  12.12    1st Qu.: -76.696   1st Qu.:  3.885
##  Median :  65.44    Median :  -4.505   Median : 10.264
##  Mean   : 350.31    Mean   :   0.202   Mean   : 16.647
##  3rd Qu.: 370.11    3rd Qu.:  71.234   3rd Qu.: 24.674
##  Max.   :6836.02    Max.   : 134.905   Max.   :107.088
##  NA's   :19216      NA's   :19216      NA's   :19216
##  var_yaw_dumbbell   gyros_dumbbell_x    gyros_dumbbell_y
##  Min.   :    0.00   Min.   :-204.0000   Min.   :-2.10000
##  1st Qu.:   15.09   1st Qu.:  -0.0300   1st Qu.:-0.14000
##  Median :  105.35   Median :   0.1300   Median : 0.03000
##  Mean   :  589.84   Mean   :   0.1611   Mean   : 0.04606
##  3rd Qu.:  608.79   3rd Qu.:   0.3500   3rd Qu.: 0.21000
##  Max.   :11467.91   Max.   :   2.2200   Max.   :52.00000
##  NA's   :19216
##  gyros_dumbbell_z  accel_dumbbell_x  accel_dumbbell_y  accel_dumbbell_z
##  Min.   : -2.380   Min.   :-419.00   Min.   :-189.00   Min.   :-334.00
##  1st Qu.: -0.310   1st Qu.: -50.00   1st Qu.:  -8.00   1st Qu.:-142.00
##  Median : -0.130   Median :  -8.00   Median :  41.50   Median :  -1.00
##  Mean   : -0.129   Mean   : -28.62   Mean   :  52.63   Mean   : -38.32
##  3rd Qu.:  0.030   3rd Qu.:  11.00   3rd Qu.: 111.00   3rd Qu.:  38.00
##  Max.   :317.000   Max.   : 235.00   Max.   : 315.00   Max.   : 318.00
##
##  magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z  roll_forearm
##  Min.   :-643.0    Min.   :-3600     Min.   :-262.00   Min.   :-180.0000
##  1st Qu.:-535.0    1st Qu.:  231     1st Qu.: -45.00   1st Qu.:  -0.7375
##  Median :-479.0    Median :  311     Median :  13.00   Median :  21.7000
##  Mean   :-328.5    Mean   :  221     Mean   :  46.05   Mean   :  33.8265
##  3rd Qu.:-304.0    3rd Qu.:  390     3rd Qu.:  95.00   3rd Qu.: 140.0000
##  Max.   : 592.0    Max.   :  633     Max.   : 452.00   Max.   : 180.0000
##
##  pitch_forearm     yaw_forearm      kurtosis_roll_forearm
##  Min.   :-72.50   Min.   :-180.00   #DIV/0!:   84
##  1st Qu.:  0.00   1st Qu.: -68.60   -0.8079:    2
##  Median :  9.24   Median :   0.00   -0.9169:    2
##  Mean   : 10.71   Mean   :  19.21   -0.0227:    1
##  3rd Qu.: 28.40   3rd Qu.: 110.00   -0.0359:    1
##  Max.   : 89.80   Max.   : 180.00   (Other):  316
##                                     NA's   :19216
##  kurtosis_picth_forearm kurtosis_yaw_forearm skewness_roll_forearm
##  #DIV/0!:   85          #DIV/0!:  406        #DIV/0!:   83
##  -0.0073:    1          NA's   :19216        -0.1912:    2
##  -0.0442:    1                               -0.4126:    2
##  -0.0489:    1                               -0.0004:    1
```

```
##  -0.0523:    1                                -0.0013:    1
##  (Other):  317                                (Other):  317
##  NA's   :19216                                NA's   :19216
##  skewness_pitch_forearm skewness_yaw_forearm max_roll_forearm
##  #DIV/0!:   85          #DIV/0!:  406         Min.   :-66.60
##  0.0000 :    4          NA's   :19216         1st Qu.:  0.00
##  -0.6992:    2                                Median : 26.80
##  -0.0113:    1                                Mean   : 24.49
##  -0.0131:    1                                3rd Qu.: 45.95
##  (Other):  313                                Max.   : 89.80
##  NA's   :19216                                NA's   :19216
##  max_picth_forearm max_yaw_forearm min_roll_forearm  min_pitch_forearm
##  Min.   :-151.00   #DIV/0!:   84   Min.   :-72.500   Min.   :-180.00
##  1st Qu.:   0.00   -1.2   :   32   1st Qu.: -6.075   1st Qu.:-175.00
##  Median : 113.00   -1.3   :   31   Median :  0.000   Median : -61.00
##  Mean   :  81.49   -1.4   :   24   Mean   : -0.167   Mean   : -57.57
##  3rd Qu.: 174.75   -1.5   :   24   3rd Qu.: 12.075   3rd Qu.:   0.00
##  Max.   : 180.00   (Other):  211   Max.   : 62.100   Max.   : 167.00
##  NA's   :19216     NA's   :19216   NA's   :19216     NA's   :19216
##  min_yaw_forearm amplitude_roll_forearm amplitude_pitch_forearm
##  #DIV/0!:   84   Min.   :  0.000        Min.   :  0.0
##  -1.2   :   32   1st Qu.:  1.125        1st Qu.:  2.0
##  -1.3   :   31   Median : 17.770        Median : 83.7
##  -1.4   :   24   Mean   : 24.653        Mean   :139.1
##  -1.5   :   24   3rd Qu.: 39.875        3rd Qu.:350.0
##  (Other):  211   Max.   :126.000        Max.   :360.0
##  NA's   :19216   NA's   :19216          NA's   :19216
##  amplitude_yaw_forearm total_accel_forearm var_accel_forearm
##  #DIV/0!:   84         Min.   :  0.00      Min.   :  0.000
##  0.00   :  322         1st Qu.: 29.00      1st Qu.:  6.759
##  NA's   :19216         Median : 36.00      Median : 21.165
##                        Mean   : 34.72      Mean   : 33.502
##                        3rd Qu.: 41.00      3rd Qu.: 51.240
##                        Max.   :108.00      Max.   :172.606
##                                            NA's   :19216
##  avg_roll_forearm   stddev_roll_forearm var_roll_forearm
##  Min.   :-177.234   Min.   :  0.000     Min.   :    0.00
##  1st Qu.:  -0.909   1st Qu.:  0.428     1st Qu.:    0.18
##  Median :  11.172   Median :  8.030     Median :   64.48
##  Mean   :  33.165   Mean   : 41.986     Mean   : 5274.10
##  3rd Qu.: 107.132   3rd Qu.: 85.373     3rd Qu.: 7289.08
##  Max.   : 177.256   Max.   :179.171     Max.   :32102.24
##  NA's   :19216      NA's   :19216       NA's   :19216
##  avg_pitch_forearm stddev_pitch_forearm var_pitch_forearm
##  Min.   :-68.17    Min.   : 0.000       Min.   :   0.000
##  1st Qu.:  0.00    1st Qu.: 0.336       1st Qu.:   0.113
##  Median : 12.02    Median : 5.516       Median :  30.425
##  Mean   : 11.79    Mean   : 7.977       Mean   : 139.593
##  3rd Qu.: 28.48    3rd Qu.:12.866       3rd Qu.: 165.532
##  Max.   : 72.09    Max.   :47.745       Max.   :2279.617
```

```
##  NA's   :19216     NA's   :19216        NA's   :19216
##  avg_yaw_forearm   stddev_yaw_forearm var_yaw_forearm    gyros_forearm_x
##  Min.   :-155.06   Min.   :  0.000    Min.   :    0.00   Min.   :-22.000
##  1st Qu.: -26.26   1st Qu.:  0.524    1st Qu.:    0.27   1st Qu.: -0.220
##  Median :   0.00   Median : 24.743    Median :  612.21   Median :  0.050
##  Mean   :  18.00   Mean   : 44.854    Mean   : 4639.85   Mean   :  0.158
##  3rd Qu.:  85.79   3rd Qu.: 85.817    3rd Qu.: 7368.41   3rd Qu.:  0.560
##  Max.   : 169.24   Max.   :197.508    Max.   :39009.33   Max.   :  3.970
##  NA's   :19216     NA's   :19216      NA's   :19216
##  gyros_forearm_y     gyros_forearm_z    accel_forearm_x   accel_forearm_y
##  Min.   : -7.02000   Min.   : -8.0900   Min.   :-498.00   Min.   :-632.0
##  1st Qu.: -1.46000   1st Qu.: -0.1800   1st Qu.:-178.00   1st Qu.:  57.0
##  Median :  0.03000   Median :  0.0800   Median : -57.00   Median : 201.0
##  Mean   :  0.07517   Mean   :  0.1512   Mean   : -61.65   Mean   : 163.7
##  3rd Qu.:  1.62000   3rd Qu.:  0.4900   3rd Qu.:  76.00   3rd Qu.: 312.0
##  Max.   :311.00000   Max.   :231.0000   Max.   : 477.00   Max.   : 923.0
##
##  accel_forearm_z   magnet_forearm_x  magnet_forearm_y magnet_forearm_z
##  Min.   :-446.00   Min.   :-1280.0   Min.   :-896.0   Min.   :-973.0
##  1st Qu.:-182.00   1st Qu.: -616.0   1st Qu.:   2.0   1st Qu.: 191.0
##  Median : -39.00   Median : -378.0   Median : 591.0   Median : 511.0
##  Mean   : -55.29   Mean   : -312.6   Mean   : 380.1   Mean   : 393.6
##  3rd Qu.:  26.00   3rd Qu.:  -73.0   3rd Qu.: 737.0   3rd Qu.: 653.0
##  Max.   : 291.00   Max.   :  672.0   Max.   :1480.0   Max.   :1090.0
##
##  classe
##  A:5580
##  B:3797
##  C:3422
##  D:3216
##  E:3607
##
##
```

```
summary(raw_train_data$classe)
```

```
##    A    B    C    D    E
## 5580 3797 3422 3216 3607
```

There are a lot of columnss, and some look like they have a lot of missing (na) values. We will clean these up now.

```
dim(raw_train_data)
```

```
## [1] 19622   160
```

```
sum_na <- sapply(raw_train_data, function(x) {sum(is.na(x))})
rmv_columns = names(sum_na[sum_na>=10000])
clean_train_data = raw_train_data[, !names(raw_train_data) %in% rmv_columns]
```

We will also remove the frist 7 columns that just contain a lot of metadata that we will not neeed.

```
clean_train_data = clean_train_data[,-c(1:7)]
```

Now we can take our training data and partition it into a training set and test for cross validation.

```
library(caret)

## Loading required package: lattice

## Loading required package: ggplot2

inTrain = createDataPartition(y=clean_train_data$classe, p=0.7, list=FALSE)
train_data = clean_train_data[inTrain,]
test_data = clean_train_data[-inTrain,]
```

Modeling Building

Model: Random Forest

First we will build some models predicting the classe variable.
Model 1: rpart (Decision Tree)
Model 2: GBM (Boosting with Trees)
Model 3: Random Forest

```
library(randomForest)
library(e1071)
library(rpart)
library(gbm)
set.seed(1234)

mod_rpart <- train(classe~., method = "rpart", data=train_data)
plot(mod_rpart$finalModel, uniform=TRUE, main="Decision Tree")
text(mod_rpart$finalModel, use.n=TRUE, all=TRUE, cex=.8)

mod_gbm <- train(classe~., method = "gbm", data=train_data, verbose=FALSE)

mod_rf <- train(classe~., method = "rf", data=train_data)
```

Then we will use this model to predict on the testing data set and check the results. We will calculate the mean of correct answers. The first mean will be for the rpart model, the second mean will be for the gbm model and the final mean for the Random Forest model.

```
mean_rpart <- mean(predict(mod_rpart, test_data) == test_data$classe) * 100

mean_gbm <- mean(predict(mod_gbm, test_data) == test_data$classe) * 100

mean_rf <- mean(predict(mod_rf, test_data) == test_data$classe) * 100
```

Conclusion

This test shows that the Random Forest model is more accurante than the GBM model and RPART model. The random forest model has a testing error (1 - Accuracy of Testing) of 0.63%, while the GBM model has a testing error of 3.55% and the rpart model having an error of 49.92%.