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IS 160

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# Lab 10 Reinforcement Learning

## Checkers:

**Agent**: the black and red pieces moving on the board **Action**: the act of each piece moving once per turn **Environment**: the board and the black and red pieces

State: after each turn or movement the system would capture the endturn state

Reward: there would probably be a point system around reducing the amount of pieces the

opposing color has and maintaining their own.

#### States:

- 1. Black moves first. Moving within the defined constraints
  - a. The environment changes due to discovery and new agent placement
- 2. Red moves: each movement has no points just yet
- 3. Black moves: as they approach each other they get closer to finding the points
- 4. Red moves: hypothetically eats a black piece
  - a. Red finds the first reward; and black finds the first punishment
- 5. Black moves: find no red near
- 6. Red moves: finds no black that are 'edible'
- 7. Black moves: eats the red
  - a. Black gains its first reward
- 8. Red moves: finds no black pieces
- 9. Black moves: finds no red pieces
- 10. Red moves: finds no black pieces

Its hard to say whether or not our state value are too small and that we should capture it by a game by game basis and not a move by move. But theres always a trial and error, and in this case i think it just might be an error.

Maze:

Agent: the entity moving inside the maze

Action: the act of moving around inside the maze

**Environment**: the maze and entity

State: after each movement or after each unsuccessful trial period

**Reward**: The reward would need to incentivise movement towards an exit and away from the initial starting location. So points for exploring and point for distance away from starting. I could already see problems with point reduction everytime it needs to turn back and make a different turn since it doesn't want to lose points. Then there's the possibility that maybe there is a path that maximizes more points by just going through to the other corner of the maze instead of exiting.

## States:

- 1. The ai does not move
  - a. It does not know what moving is
- 2. The ai moves in a straight line into the wall
  - In this case in order to reset positions/states walls are now lethal and touching them rests the position
- 3. The ai probably has not learnt to avoid the wall just yet as it gains a few points every times it just moves forward
- 4. The ai learns to turn into a different corridor
- 5. Ai learns that turning generates more points and turns often
- 6. Ai traps itself into the same deadend
  - a. Repeats the same exact movements
- 7. Ai learns a new path with more point generation
- 8. Ai reaches another deadend
- 9. Ai learns that walls are the biggest punishment by taking away all its points
- 10. Ai learns to identify walls and turn back away from them

In this case the states are on a much bigger scale and would take less storage space recalling each state. However, depending on the complexity of a maze this type of learning is far too slow even with my generous learning pace that i gave it. A better solution would be to implement multiple entities roaming the maze in one generation/iteration.

Crow/Raven Training:

**Agent**: a crow or raven (any other smart bird), human(s)

**Action**: flying, perching, observing, picking-up trash, depositing trash,

**Environment**: A whole city, crows, treat dispenser

**State**: The days counting after placing the treat dispenser

**Reward**: a tasty treat

## States:

1. Day 1: Trash litters the park, crows flying by, and a newly installed treat dispenser

- 2. Day 2: human displaying how to use the treat dispenser
- 3. Day 3: curious crows comes to see the machine
- 4. Day 4: some crows tries testing rocks
  - a. Machine is designed to only take trash
- 5. Day 5: a crow manages to pick up a piece of trash and returns it for some treat
- 6. Day 6: crows are better able to identify trash versus other objects
  - a. The flow of treats/rewards increases
- 7. Day 7: crows are smart enough to exploit the system and steal not-yet-trash from the hands of humans
- 8. Day 8: There is noticeably less trash littering the park, but also because there are less people. Both because of the crows
- 9. Day 9: the treat dispenser is removed
- 10. Day 10: the people return and so did the trash, and some of the crow behavior of stealing remains

I don't know if this is a good example that you're looking for, but it was based **loosely** on an experiment that researchers were doing to reduce litter through nature. The crows are the agent whose natural curiosity and bright mind was utilized to minimize the need to facilitate direct teaching. Kind of like a reinforcement learning ai. I think that it has some of the quirks that an ai would have as well. Namely, the ability to even see that trash is a very loose term and exploit it for a quicker reward farm. Sometimes in an effort to not be punished, refuses to do anything.

**Drone Delivery Service** 

**Agent**: A delivery drone optimizing its route to deliver packages.

**Action**: Delivering packages in a city

**Environment**: A city with different neighborhoods and package delivery locations.

**State**: specific locations or conditions within the city environment where the drone must

navigate and make decisions

**Reward**: encourages the drone to learn and select the most beneficial route to ensure a successful delivery

## States:

- 1. Starting Point: The drone begins its delivery route.
- 2. Residential Area A: A neighborhood in the city.
- 3. Residential Area B: Another neighborhood in the city.
- 4. Office Park A: Business district with delivery locations.
- 5. Office Park B: Another business district with delivery locations.
- 6. Package Delivery 1: Specific delivery location in Office Park A.
- 7. Package Delivery 2: Specific delivery location in Office Park B.
- 8. Empty Space 1: Area with no delivery locations in Residential Area A.
  - The drone can use this opportunity to scan for alternative routes
- 9. Empty Space 2: Area with no delivery locations in Residential Area B.
  - The drone can use this opportunity to scan for alternative routes
- 10. Final Delivery Point: Last delivery location before completion.

In this example, the delivery drone navigates through different states within the city, making decisions at each state to optimize its delivery route and maximize the total reward by efficiently delivering packages while learning the most valuable actions in various situations.

Patient treatment in the healthcare industry

**Agent**: A healthcare AI system managing patient treatment

Action: Initiate the correct treatments/procedures depending on the patient's condition

**Environment**: A hospital setting with various patient conditions.

**State**: phases or conditions a patient might encounter

**Reward**: optimize patient care and improve health outcomes

#### States:

- 1. Admission: Initial state when a patient is admitted.
- 2. Patient Stable: Patient's condition is stable and recovering.
- 3. Patient Critical: Patient is in a critical condition.
- 4. Post-Treatment: Patient post-treatment but needs monitoring.
- 5. Discharge: Patient is ready for discharge.
- 6. Post-Discharge Care: Patient's status after leaving the hospital.
- 7. Readmission: Scenario where a patient is readmitted.
- 8. Patient Improving: Patient's health condition is improving.
- 9. Patient Deteriorating: Patient's health condition is deteriorating.
- 10. Critical Condition: Severe state of patient health.

This example of this reinforcement learning is to help analyze the patients that enter the hospital and help the Al figure out the severity of the patients health. Depending on the severity, this can help choose the most appropriate action for each state that can improve health or speed up a recovery.

Managing a restaurant

**Agent**: An AI system managing a restaurant kitchen **Action**: specific tasks being performed in the kitchen

**Environment**: A restaurant kitchen with various cooking stations.

State: different stages or phases of kitchen operations

**Reward**: delivering satisfying customer experiences. This tells the model that these kitchen operations are working to satisfy the customer in a quick and timely manner

#### States:

- 1. Order Received: Initial state upon receiving a customer's order.
- 2. Ingredient Preparation: State when ingredients are being readied for cooking.
- 3. Cooking in Progress: State where the dish is being prepared.
- 4. Dish Ready for Plating: The dish is ready to be plated for serving.
- 5. Plating and Garnishing: The final stage before serving the dish.
- 6. Serving Completed: Dish has been served to the customer.
- 7. Customer Satisfied: State indicating customer satisfaction.
- 8. Customer Unsatisfied: Reflecting an unsatisfactory customer experience.
- 9. Busy Period: High demand and activity in the kitchen.
- 10. Idle Period: Low activity and demand in the kitchen.

This reinforcement learning environment focuses on optimizing kitchen operations in a restaurant to deliver exceptional customer service. The AI agent adapts its actions in accordance with various states to maximize positive rewards, ensuring efficient operations and a superior dining experience for customers