

Identification of DC Pixels using Boosted Decision Trees

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Abstract

A new method of Direct Cherenkov (DC) pixel identification, relying on machine learning, was developed. A set of Cosmic Ray telescope images for training were each simulated twice, both with and without the Extended Air Shower (EAS) background, enabling the DC pixel in every realistic telescope images to be reliably identified using the corresponding background-free image. Using all pixels from these realistic training images, a Boosted Decision Tree (BDT) was trained to identify DC pixels. The BDT performance was tested on a second set of test realistic telescope images, and compared to existing methods of DC pixel identification.

1 Introduction

In Cosmic Ray air showers, the primary particle will often emit DC light in the upper atmosphere, before generating an EAS in interaction with the lower atmosphere. In telescope images, this DC light is usually concentrated in a single ‘DC pixel’. Identifying this pixel is challenging, because the DC light is much fainter than that from the EAS, which will be recorded in the DC pixel and many of surrounding pixels. As a result, most telescope images will have many bright pixels adjacent to one another, among which one will be the DC pixel. However, if found, the DC pixel can indicate the primary particle energy and charge.

Currently, the DC pixel is identified after applying a number of cuts first, used a method developed by the HESS collaboration [1]. From the subset of events passing these cuts, the variable

$$Q_{DC} = \frac{Intensity}{Intensity_{N.N.max}}$$

is defined as the ratio of the intensity of a pixel to the largest neighbouring pixel intensity. The DC pixel candidate is simply that with the largest Q_{DC} among those passing the cuts. However, this method is neither reliable nor efficient. An improved method would aim to increase the number of correctly identified events, and enable cuts which better discriminate between correctly and incorrectly identified events.

Using the CORSIKA package, Cosmic Ray events were simulated both with and without an EAS component. The `sim_telarray` package was used to simulate the resultant telescope image, assuming the events were observed by the HESS telescope array. Using the EAS-free image to reliably identify the DC pixel, a Boosted Decision Tree (BDT) was trained on each pixel from a training set of telescope images. The pixel information was provided in the form of individual pixel entries, rather than as discrete sets for images or events.

Once trained, the BDT was applied to every pixel entry in a separate ‘testing’ set of simulated telescope images. For each pixel, the BDT assigned a ‘Signal Probability’, P_{signal} , indicating the likelihood of the pixel being the DC pixel. From an entire image, the pixel with the largest P_{signal} was identified as the DC pixel candidate. Repeating the double simulation technique for the test data, the true DC pixels in the test telescope images were reliably identified from EAS-free images. Thus, the accuracy of BDT identification for test telescope images was calculated.

2 Image Simulation

A full simulation of Cosmic Ray air showers was performed using the CORSIKA package [3], assuming a standard atmospheric profile derived from measurements conducted at the HESS site in Namibia. The simulated particles were Fe^{56} , within the Energy Range of 35 – 135 TeV and a spectrum $\phi \propto E^{-2.7}$. For each set of simulated event, 4 unique random number seeds were used to generate the shower. An altitude of 1800m was assumed, again corresponding to the HESS site. The simulated zenith angle ranged from $0^\circ < \theta < 2^\circ$, while the simulated azimuth angle ranges from $-2^\circ < \phi < 2^\circ$. The four smaller HESS-phase-1 telescopes were arranged in a cross along the x/y axis with the larger HESS-phase-2 ‘CT5’ telescope placed at the center. The length of each cross arm was 85m. The simulated target region of the cores was chosen to be a square centered on CT5, with each 300m-long side bisecting the x/y axis.

In order to identify the DC pixel, a simulation was initially run with an energy cut of 10 PeV on all muons and electrons. As the primary particle energy did not exceed this value, neither daughter muons and electrons, nor the photons they would have emitted, were simulated. Thus the hadronic Cherenkov Light from the primary particle and daughter fragments, but not the EAS light, was present in the camera image. A second identical ‘EAS Simulation’ was run including the same random seeds, but without the energy cut on muons and electrons. This gave a complete EAS image including the DC light.

Using the `sim_telarray` package [2], the expected HESS hardware response to each air shower was simulated. Among other things, the program accounts for atmospheric transmission and density, mirror positions, sizes and reflectivities, camera shadowing and triggering, quantum efficiency and pulse responses. Due to the comprehensive and detailed nature of these hardware simulations, the resultant images can be considered ‘realistic camera images’. For the EAS Simulation, the night sky background was also included by `sim_telarray`, further obscuring the DC pixel.

The HESS telescope has both a high gain Channel 0 and a low gain Channel 1. The `Sim_telarray` simulated value of SOMETHING? for each channel were recorded. The pedestal and gain for each channel were also recorded, and from this, Intensity in the pixel channel was found.

$$Intensity = (Count - Pedestal) \times Gain$$

In the case of many iron core events, Channel 0 will reach its maximum value and become saturated. Thus Channel 0 ceases to be useful for discriminating between high energy DC and non-DC pixels. Consequently, Channel 0 Intensities neglected while Channel 1 Intensities were used in all later analysis. This variable will henceforth be referred to simply as *Intensity*.

In addition to the *Intensity* of each pixel, the `Sim_telarray` package derives various Hillas whole-image parameters. These include the image width and length measured in degrees, from which the aspect ratio $A.R = \frac{width}{length}$ was calculated. Further, the reconstructed shower direction and the

shower center of gravity were calculated as positions in azimuth and zenith. Additionally the calculated energy and distance to core r_{core} were recorded.

For every pixel, the location within the image was determined from a standard HESS layout. The variables $\Delta_{C.o.G}$, $\Delta_{Direction}$ and Δ_{Line} were defined as the distance from the pixel to the shower center of gravity, shower direction, and the line joining those two points. Furthermore, the nearest neighbouring pixel IDs were calculated for every pixel position, enabling the count in each neighbouring pixel to be found. From this, two further pixel variables were defined. The largest neighbouring intensity $Intensity_{N.N.max}$ was found, and the ratio $Q_{DC} = \frac{Intensity}{Intensity_{N.N.max}}$ was derived. In addition the Nearest Neighbour Mean Count was recorded. These variables were recorded in every pixel entry, and together the pixel entries formed a complete dataset for each camera image.

3 DC Pixel Identification

The original method used by the HESS collaboration [1] was initially replicated, for which a number of cuts were applied to each image dataset.

Table 1: Cuts applied to image pixel sets

Variable	Cut
Q_{DC}	>1.3
$\Delta_{C.o.G}$	>0.17
$\Delta_{C.o.G}$	<0.91
$\Delta_{Direction}$	<0.45
Δ_{Line}	<0.23
Aspect Ratio	<0.75

From the subset of pixels satisfying these conditions, the remaining pixel with the largest Q_{DC} was selected as the DC pixel. In the original analysis, an additional cut $r_{core} > 0.4$ was applied. However, the uncertainty in determining the core position through Hillas Analysis is typically of the order of $\pm 30m$. Consequently, this particular cut was omitted, along with the Impact Parameter cuts. For every image, the total image amplitude I_{tot} was found. A cut was also placed requiring $Q_{DC} < 0.14 \times \log(I_{tot}(161 \times \cos \theta))$ where θ was the zenith angle. The result was compared with the true DC pixel, identified from the hadron-only image, to test the accuracy of this cut. Out of 400 events, it was found that only 55% of these events contained a clear DC signal, as defined by requiring the DC pixel to have $Intensity_{DC} > 150$ in the hadron-only image. SOMETHING! Of this subset of 'DC events', 17% events passed all of the required cuts. The Q_{DC} was found to be 100% accurate in identifying the DC pixel in those passing events, as shown in 1.

As an alternative to use of Q_{DC} , a new method of DC pixel identification was developed as part of this analysis by using a BDT trained with the Scikit Learn Python package. A set of 2000 simulated events was selected, and randomly split through use of the python random.random() function into two subsets for training and testing. The variable $DC_{Count} = Count - Mean_{N.N}$ was defined as an approximate 'DC signal', if the pixel were to be selected as the DC candidate. For every pixel in the 2000 simulated events HESS 1 images, an entry was formed of Q_{DC} , $\Delta_{C.o.G}$, $\Delta_{Direction}$, Δ_{Line} , Channel1, Channel0, DC_{Count} and $Mean_{N.N}$. A score of 0 was assigned to

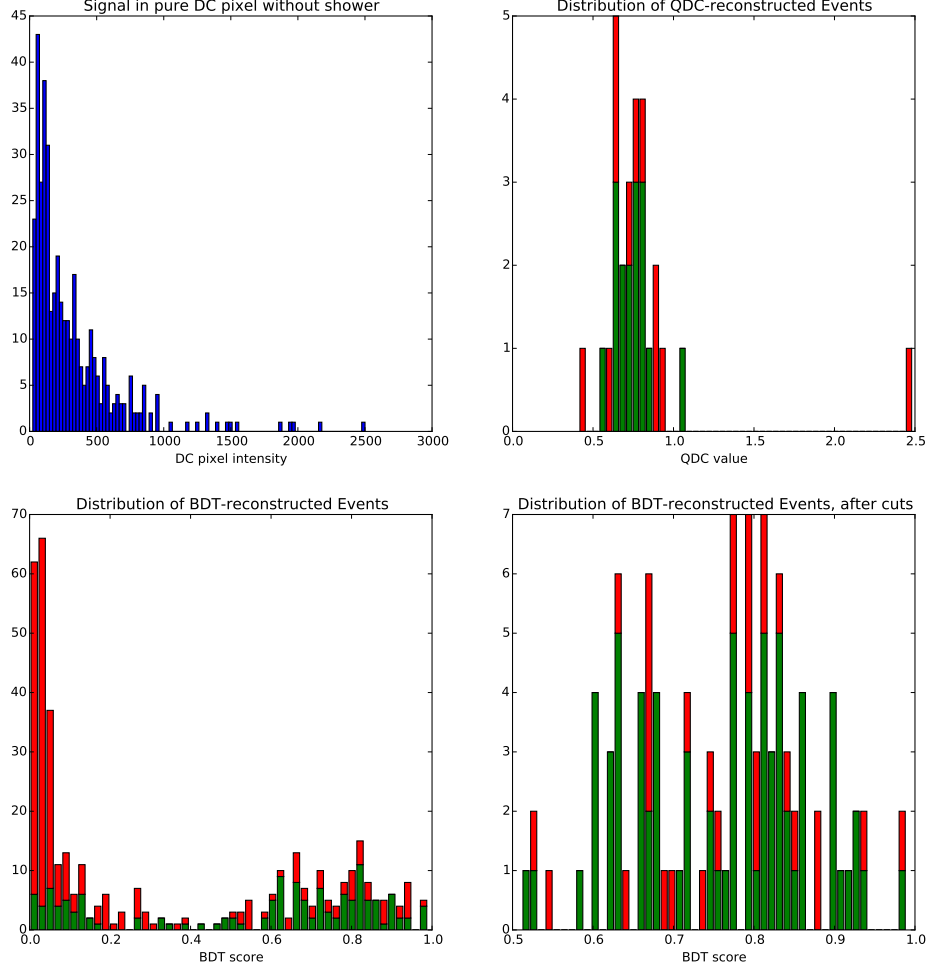


Figure 1: The DC signal in the shower-free pixel is shown in the top left, with a broad gaussian distribution with the tail of the night-sky background extending up to approximately 5000. Events below this are unlikely to be identified correctly because the DEC light is too faint. In the top right- the distribution of the dataset is shown, once all the non- Q_{DC} cuts have been applied. In the bottom left, the BDT score distribution is shown before any cuts. On the bottom right, we see the same distribution after both signal and BDT score cuts are applied. All green events are ones in which the DC pixel has been correctly identified, while red events are ones that have been incorrectly identified.

every pixel to indicate background, with the exception of those that were identified as the DC pixel through the Shower-Free simulation. If the DC count in the shower-free simulation was larger than 300, the pixel was included with a score of 1, identifying it as a signal pixel. Pure DC pixels below the threshold cut of 300 were deemed to be too faint to reconstruct, so these entries were omitted from the training set.

Having created a dataset, the BDT was then trained with a maximum depth of 5, and 100 trees generated. It was found that the BDT was 100 % accurate for the entire training dataset, with a breakdown of 100 % for the training background and 99 % accurate with the training signal. When the trained BDT was applied to the testing pixels, it was found to be 99.99 % accurate for the entire training dataset, with a breakdown of 100 % for the testing background and 99 % accurate with the testing signal. This indicates that the BDT was not significantly overtrained, which would otherwise be manifested by a large divergence in accuracy between testing and training data.

Having trained the BDT successfully, it was then applied to the same dataset as for the classic QDC identification. In each camera image, the event with the largest BDT score was deemed to be ‘most signal-like’, and thus selected as the DC pixel candidate. A cut was applied, requiring $Probability_{signal} > 0.5$ for the DC candidate to be accepted.

With this cut applied, out of 1200 events, 46% events passed all of the required cuts. The BDT was found to be 85 % accurate in identifying the DC pixel in those passing events.

In 1, a plot of true vs. reconstructed DC count is shown, obtained by comparing the BDT selected pixel to the hadron-only DC pixel. The black line indicates the optimal 1:1 ratio that we are aiming for. It is seen that there the vast majority of misidentified events have a small $candidate_{DCcount}$, forming a red line in the region $candidate_{DCcount} \approx 0$. To remove these misidentified events, we can apply a second cut requiring $candidate_{DCcount} > 300$.

Application of this combined cut greatly increases the successful identification rate. Of the 2000 events, 84% of events passed all of the required cuts. The BDT was found to be 90 % accurate in identifying the DC pixel in those passing events. This represents a very significant improvement in DC pixel identification over the previous QDC method, and corresponds to a fivefold increase in the number of HESS data events that can be studied using the LPD method. Use of this BDT method is thus assumed throughout the rest of this analysis.

4 Conclusion

Basically it just worked really well.

References

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