

C3A - Display Technology

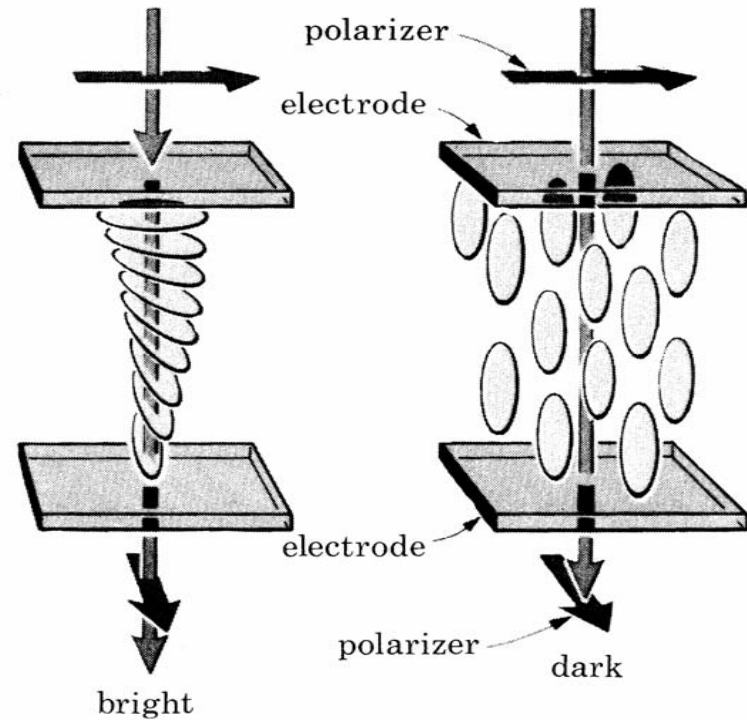
Peter Raynes

Lecture 3

- Twisted nematic (TN) LCD
 - Device structure
 - Defects
 - Properties
- Passive addressing
 - RMS addressing
 - Alt & Pleshko analysis
- Continuum Theory
 - Energy due to distortions
 - Energy due to electric fields
 - Total energy

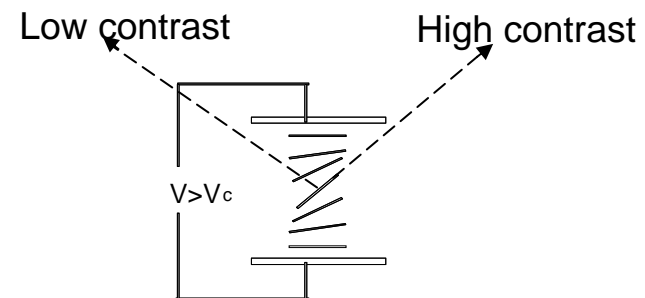
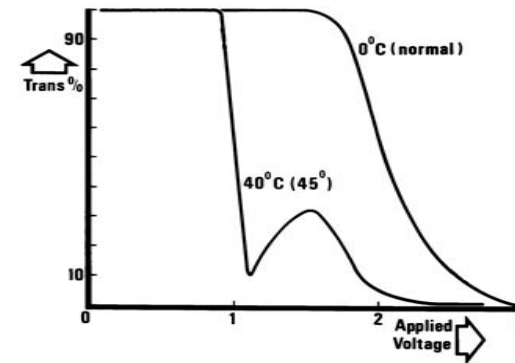
TN Device Structure

- Schadt & Helfrich 1971
- Planar alignment
- 90° twist angle
 - Rotates polarised light by 90°
- Voltage switches device
 - $\Delta\epsilon > 0$
 - $V \geq 1$ Volt
- Operation
 - Reflection: 'Normally white' mode
 - Transmission: 'Normally black' mode



TN Mode - Switching

- Switches between
 - 1~3 Volts
- Depends on
 - Temperature
 - Viewing angle
 - Polar angle
 - Depends on n
- Produces multiplexing problems



TN Optics

- TN transmission (parallel polars)
(Gooch-Tarry equation 1975)

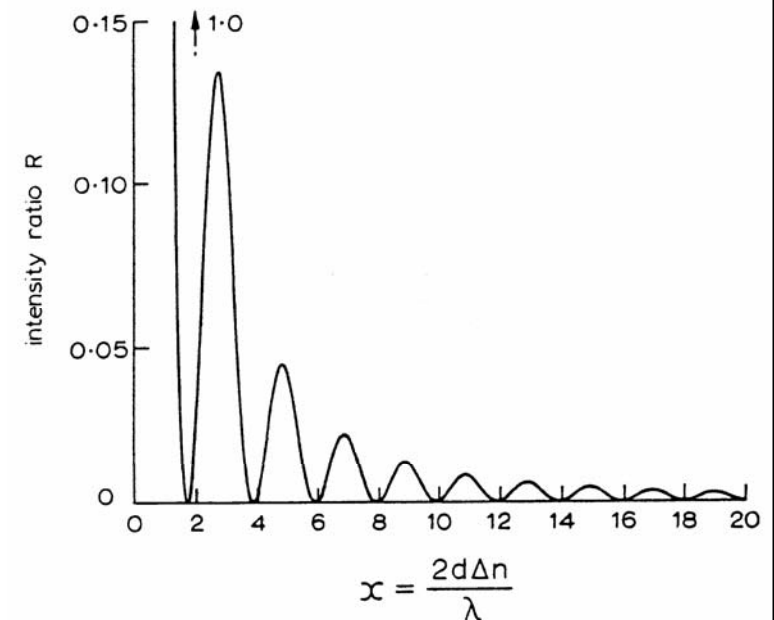
$$T_{TN} = \frac{\sin^2(\pi/2) \left[1 + (2\Delta n \cdot d / \lambda)^2 \right]^{\frac{1}{2}}}{1 + (2\Delta n \cdot d / \lambda)^2}$$

- $T_{TN} = 0$ when either:

$$\Delta n \cdot d > \lambda \quad (\text{Mauguin 1911})$$

$$\text{or: } (\Delta n \cdot d / \lambda)^2 = (m^2 - 1/4) \quad (\text{G-T})$$

$$\Rightarrow \Delta n \cdot d > 0.87\lambda, 1.94\lambda, \dots$$



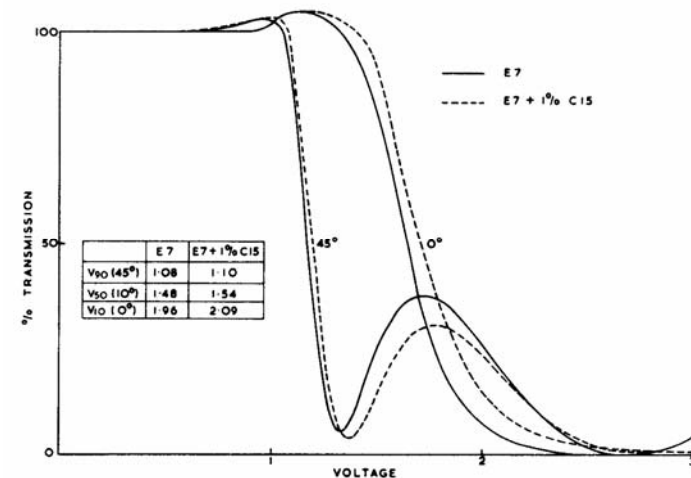
Reverse Twist and Tilt Defects

- Thin lines (all voltages)
 - $\pm \frac{\pi}{2}$ twist
- Thick lines ($V > V_c$)
 - $\pm \theta$ reorientation
 - Only present in one twist
 - Twist \Leftrightarrow alignment pre-tilt
- Degrade appearance
 - \Rightarrow Must eliminate the defects



Elimination of Defects

- Want twist with no defects
- Use chiral nematic
- Pitch of chiral nematic
 - Sign must match surface pre-tilt (Raynes 1975)
- Magnitude
 - Matching ($P = 4d$)
 - $\Rightarrow P \approx 20 \mu\text{m}$
 - Degrades contrast severely

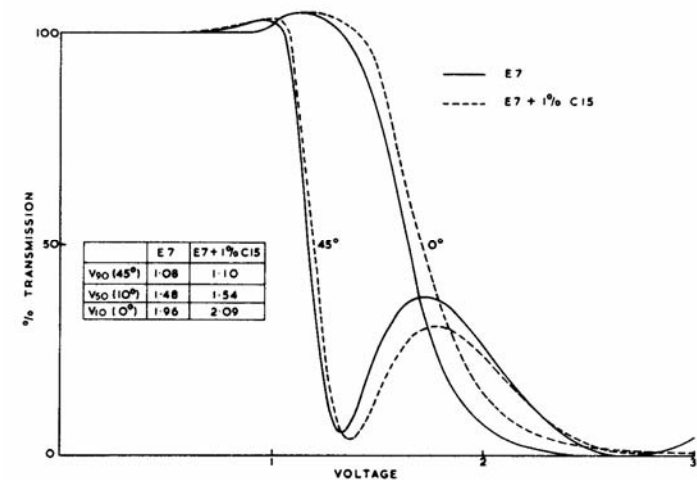


Effect of Pitch on Transmission

- Difference in twist across layer for matching pitch ($P = 4d$)
- Influences transmission
- Transmission at $V > V_c$ given by:

$$T \approx \left(\frac{2\pi d V_c}{PV} \right)^2$$

- Use $P \approx 200 \mu\text{m}$

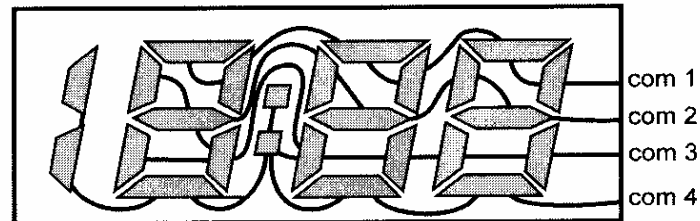


Surface Pre-tilt

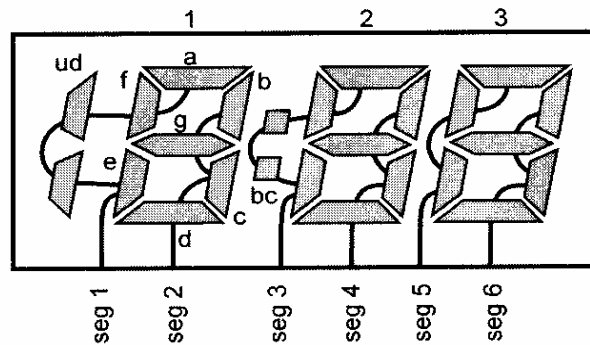
- Needed to eliminate defects
- What magnitude?
 - Too large ($>3^\circ$)
 - Rounds the threshold
 - Bad for multiplexing
 - Too small ($<1^\circ$)
 - Allows defects
 - Grow new defects at pixel corners
 - Electrode edge effects
 - Usually use $1\sim2^\circ$

Passive Multiplexed Displays

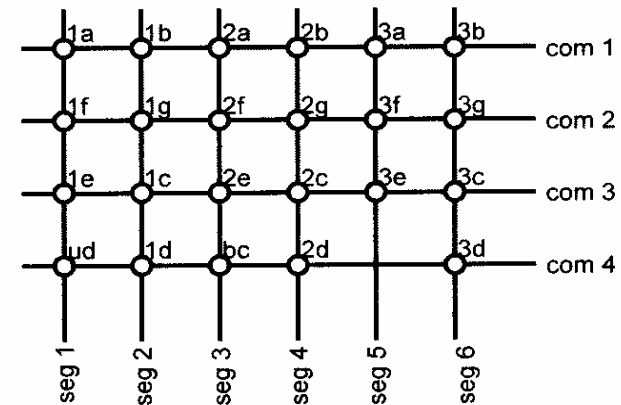
Common substrate



Segment substrate



Matrix equivalent



Passive Multiplex Addressing

Driving signals

V_S scanned down rows
 $\pm V_D$ on columns

Speeds

$\tau_{\text{liquid crystal}} \gg \tau_{\text{addressing}}$

\Rightarrow Square of RMS voltage

$$\Rightarrow V_{RMS}^2 = \frac{1}{T} \int_0^T V^2(t) dt$$

		$-V_D$	$+V_D$	$-V_D$
\downarrow	0	$+V_D$	$-V_D$	$+V_D$
	V_S	$V_S + V_D$	$V_S - V_D$	$V_S + V_D$
	0	$+V_D$	$-V_D$	$+V_D$

Optimum Conditions

$$V_{RMS}^2 = \frac{1}{T} \int_0^T V^2(t) dt$$

For N rows $V_{ON}^2 = \frac{1}{N} (V_S^2 + 2V_S V_D + N V_D^2)$

$$V_{OFF}^2 = \frac{1}{N} (V_S^2 - 2V_S V_D + N V_D^2)$$

Addressing maximised (ie $\frac{V_{ON}}{V_{OFF}}$ max.) when $\frac{V_S}{V_D} = \sqrt{N}$

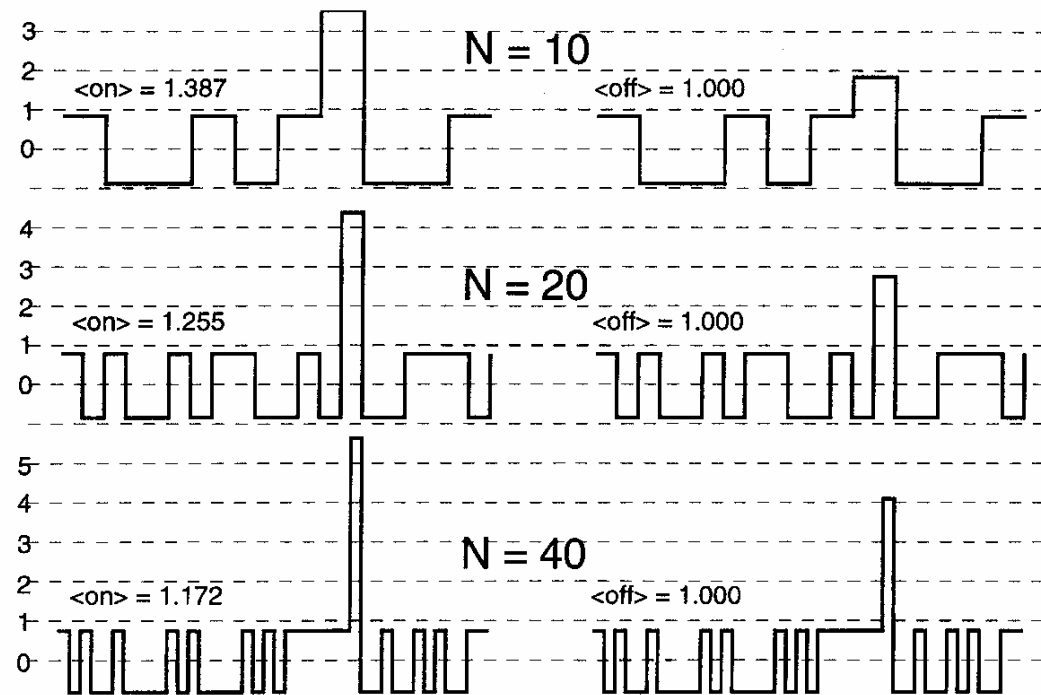
Giving $\left(\frac{V_{ON}}{V_{OFF}} \right)_{\max} = \sqrt{\frac{\sqrt{N} + 1}{\sqrt{N} - 1}}$ (Alt & Pleshko 1975)

Resulting Waveforms

$$\frac{V_S}{V_D} = \sqrt{N}$$

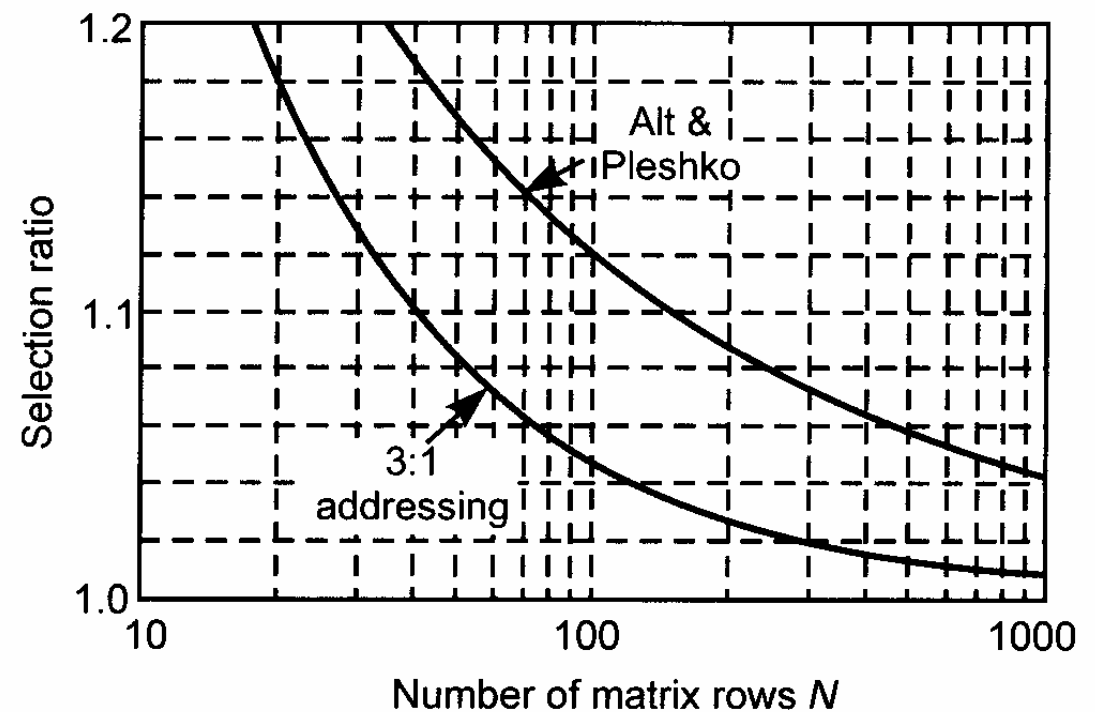
Invert voltages:

- So that DC = 0
- Every few lines



Resulting Performance

$$\frac{V_{ON}}{V_{OFF}} = \sqrt{\frac{\sqrt{N} + 1}{\sqrt{N} - 1}}$$



Driver Voltages

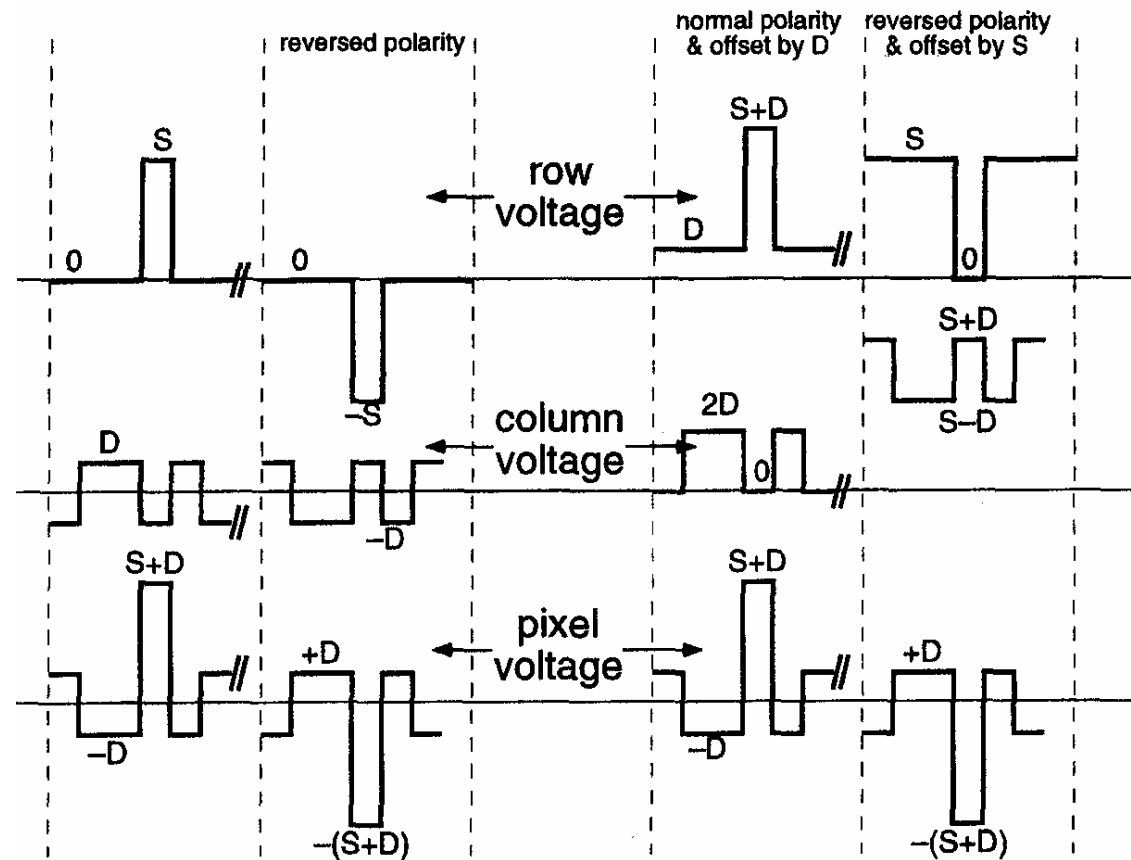
- $\frac{V_S}{V_D} = \sqrt{N}$
 - e.g. $\frac{V_S}{V_D} = 20$ ($N = 400$)
 - $V_D \approx 2V$
 - $V_S \approx 40V$
 - Voltage swings
 - $V_D \approx \pm 2V$
 - $V_S \approx \pm 40V$
 - Uneven between V_D and V_S
 - Large for V_S (80V)
 - Negative voltages

	$-V_D$	$+V_D$	$-V_D$
0	$+V_D$	$-V_D$	$+V_D$
V_S	$V_S + V_D$	$V_S - V_D$	$V_S + V_D$
0	$+V_D$	$-V_D$	$+V_D$

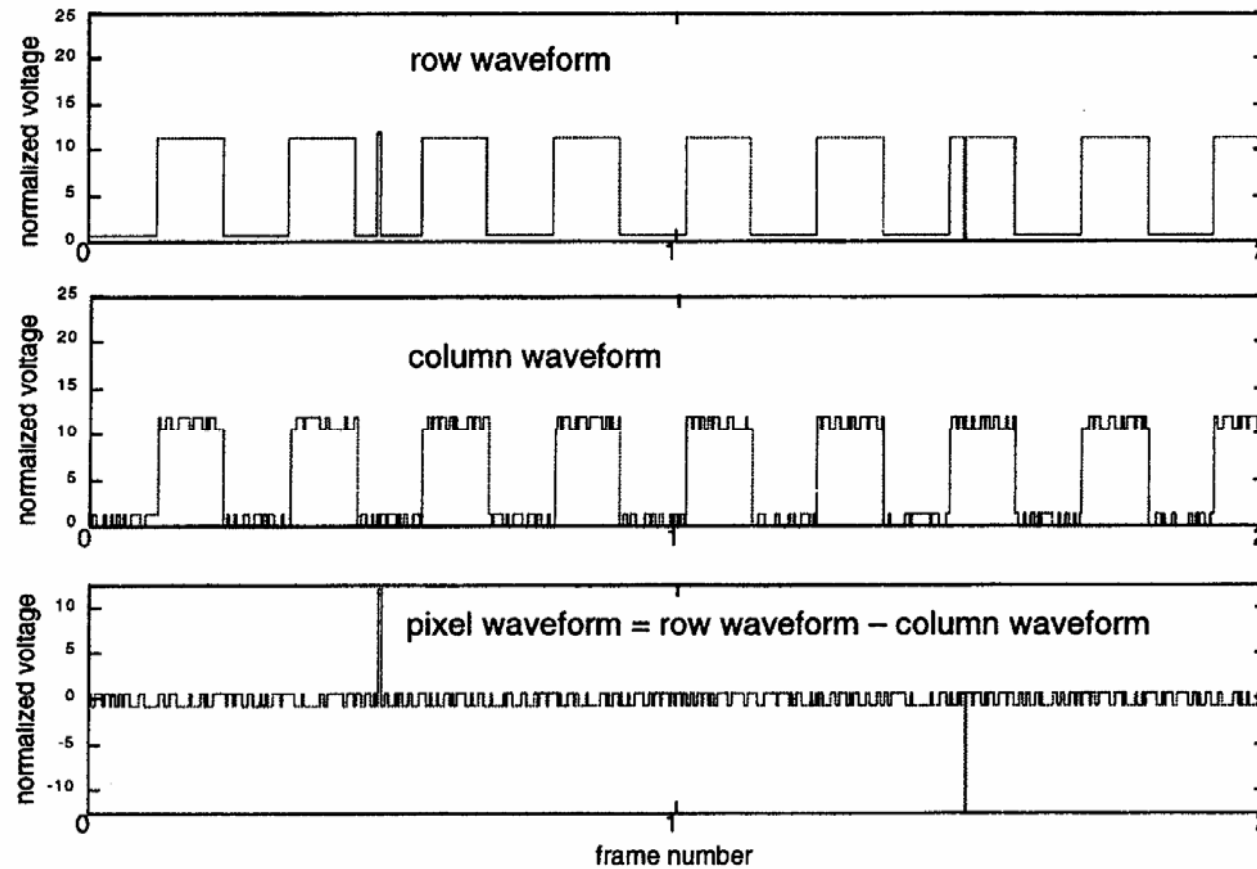
Driver Voltage Reduction - 1

- Adding same voltage to rows and columns does not change pixel voltage
- For example:
 - In positive cycle add V_D
 - In negative cycle add V_S
- Voltage $\approx 1/2$

Driver Voltage Reduction - 2



Resulting Waveforms



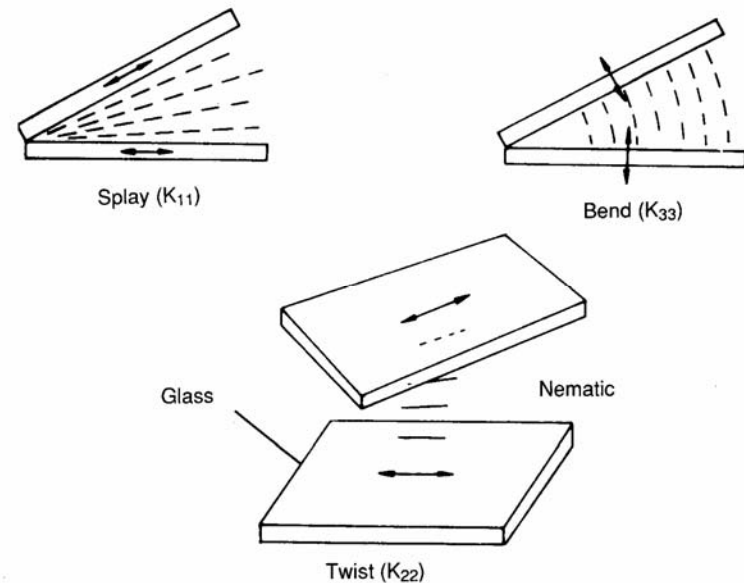
Continuum Theory - Energy Due to Distortions

- Distortion energy density of director \underline{n} (Frank 1958)

$$F_k = 1/2 \left\{ k_{11} (\text{div } \underline{n})^2 + k_{22} (\underline{n} \cdot \text{curl } \underline{n})^2 + k_{33} (\underline{n} \times \text{curl } \underline{n})^2 \right\}$$

- Elastic constants

- k_{11} splay, k_{22} twist and k_{33} bend
- Magnitude $\approx 10^{-11}$ N



Continuum Theory - Adding an Electric Field

- Dielectric energy density:

$$F_E = 1/2 \underline{D} \cdot \underline{E}$$

- Total energy density:

$$W = F_k + F_E$$

$$\Rightarrow W = 1/2 \left\{ k_{11} (\text{div } \underline{n})^2 + k_{22} (\underline{n} \cdot \text{curl } \underline{n})^2 \right. \\ \left. + k_{33} (\underline{n} \times \text{curl } \underline{n})^2 + \underline{D} \cdot \underline{E} \right\}$$

- Find solutions for $\underline{n}(x, y, z)$
 - which minimise total energy $\int W \, dx \, dy \, dz$
 - with relevant boundary conditions imposed

Next Lecture

- Minimising the total energy
 - 1-D solutions
 - Critical voltage for Freedericksz transition
 - Useful analytical solutions for TN devices
- Supertwisted nematic LCDs
 - Basic device performance
 - Director modeling
 - Material optimisation