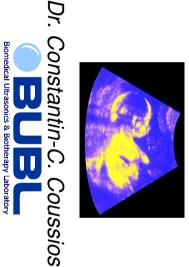
## BME2 - Biomedical Ultrasonics

# Lecture 5: Medical Ultrasound Imaging



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Acknowledgments: Prof. Ronald A. Roy, George Eastman Visiting Professor 2006-07



Department o f Engineering Scienc

#### Contents

- 5.1.A brief history of ultrasound imaging
- 5.2. Basic element of a B-Mode scanner and scanning methods
- 5.3. Transmit electronics and beam forming
- 5.4. Ultrasound propagation: diffraction, absorption and scattering
- 5.5. Receive beam forming and time-gain compensation
- 5.6. Filtering, detection and display

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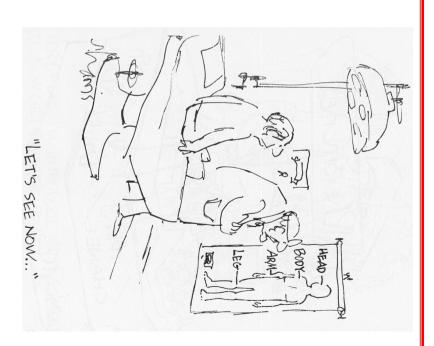
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Wells P.N.T., Physical principles of ultrasonic diagnosis, Academic Press, London, 1969a

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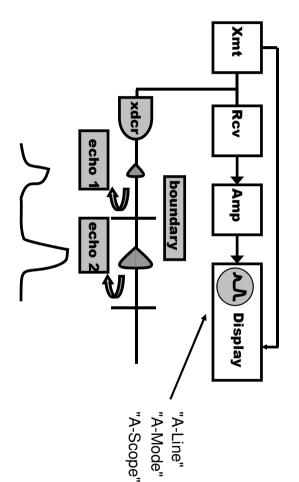
### First... a Little History About Imaging Ultrasound

Doc knows about as much anatomy as I do!



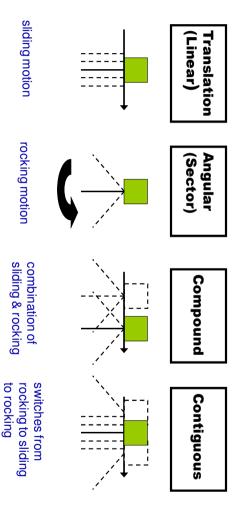
## **Early Developments**

- SONAR "Echo Ranging" at Ultrasound Frequencies
- Firestone (1945) developed the "reflectoscope" and applied pulse ranging techniques to flaw detection



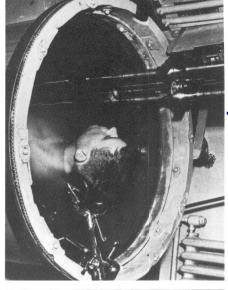
## **Early Developments**

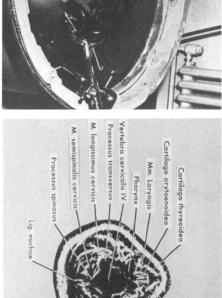
- It didn't take long before someone thought to move the transducer the 2-D "B-Mode" scan was born
- Howey fitted a pulse echo transducer to a B-29 gun turret (Holmes, 1980); scanned a patient's neck along a circular arc
- Early systems employed water baths
- Wild and Reid developed first hand-held contact scanners (Wells, 1969)



## **Early Developments**

## Howery's B-29 Ultrasonic Tomographic System



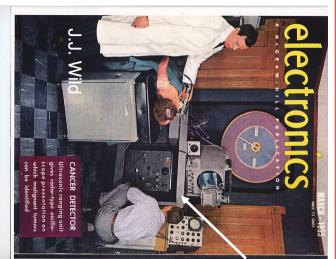


Lucky Patient

Annotated "Image" of the Neck

## Milestone Imaging Systems

Adapted from Szabo (2004)



Radar Equipment!

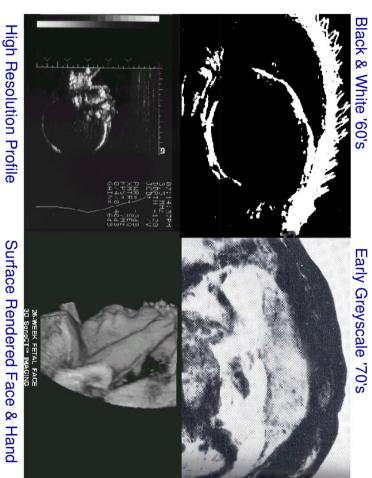
J. Reid



Early Phased Array System
"HP 70020A"

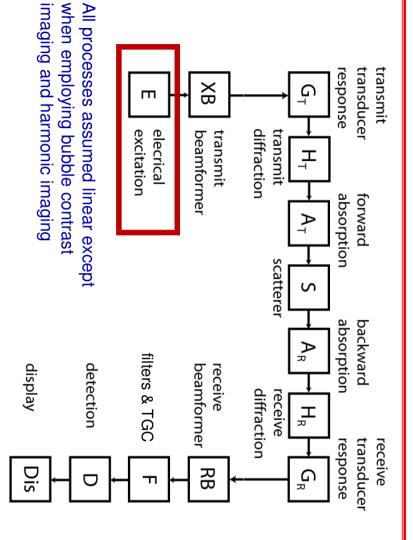
Early Mechanically Scanned System

#### Milestone Images Four Views of a Fetus



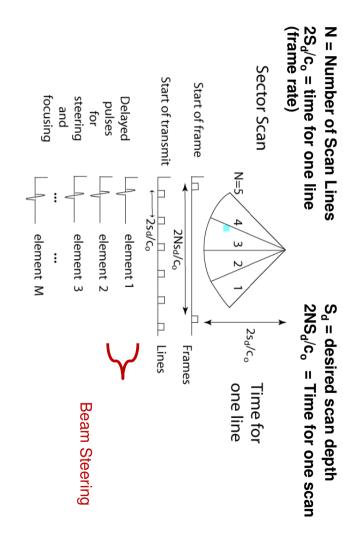
Surface Rendered Face & Hand

Adapted from Szabo (2004)

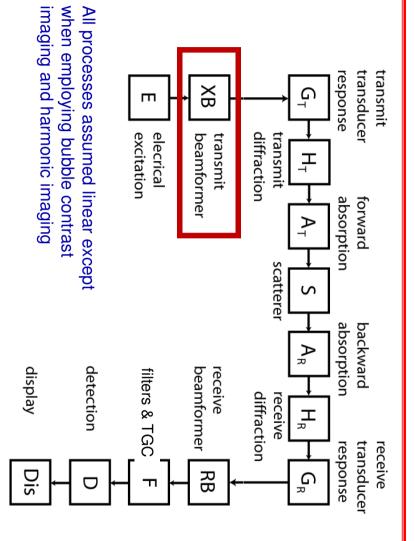


## Step 1: Electrical Excitation

Primitive Excitation Pulses Consist of Precisely Timed Single-Cycle Pulses or Multiple-Cycle Pulses



Adapted from Szabo (2004)

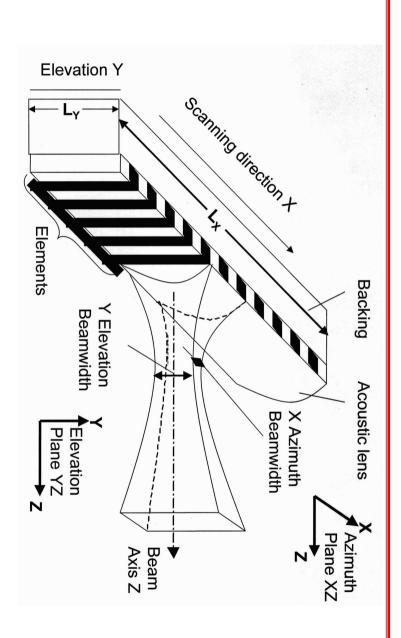


#### Step 2: **Transmit Beamformer**

- continuous apertures Arrays consist of many small elements as opposed to large
- plane Each element is excited by signals delayed (phased) to steer and focus the beam electronically in the "scan" or "azimuth"
- A fixed focus lens provides focusing in the elevational plane
- By varying the delays to individual elements you can both focus the beam and direct its' axis.
- Beams can be radially scanned or linearly scanned
- Beamforming on receive proceeds in the same way as on
- You delay the received signals
- You linearly sum the delayed signals

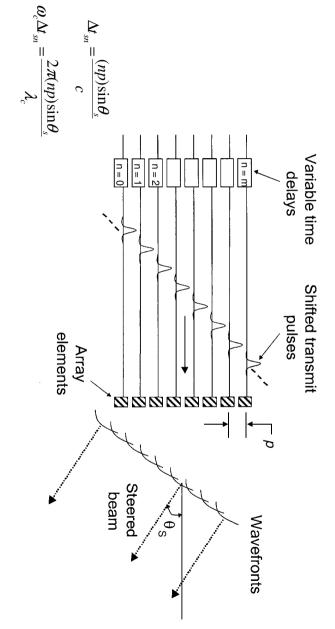
Adapted from Panda (1988) via Szabo (2004)

## **Linear Array Geometry**



## Phase Delay Beamsteering

corresponding to a wavefront at angle  $\theta_s$  from the Z axis. Introduce a linear time (phase) delay across the array elements



From Szabo (2004)

## **Phase Delay Focusing**

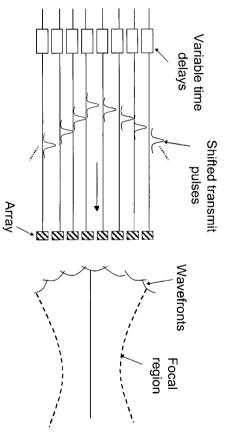
- that simulate the curved wavefront Arrays can be focused by adding time delays
- c = distance from origin to focal point

 $\mathcal{T}_{n}$ 

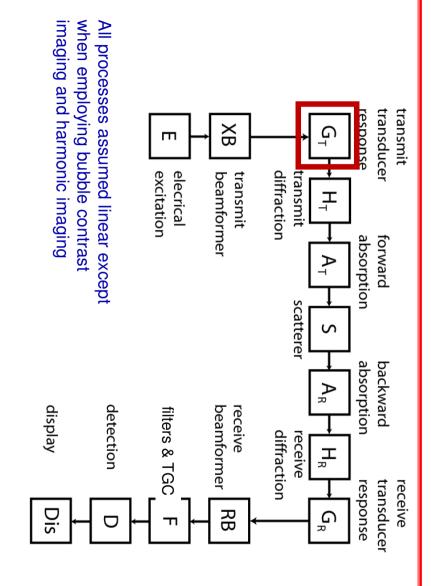
 $\mathcal{C}$ 

 $\sqrt{\left(x_r - x_n\right)^2 + z_r^2}$ 

- $x_n = \text{distance from origin to center of nth}$  element (np)
- $t_o = {
  m constant\ delay\ added\ to\ avoid\ negative\ delays}$



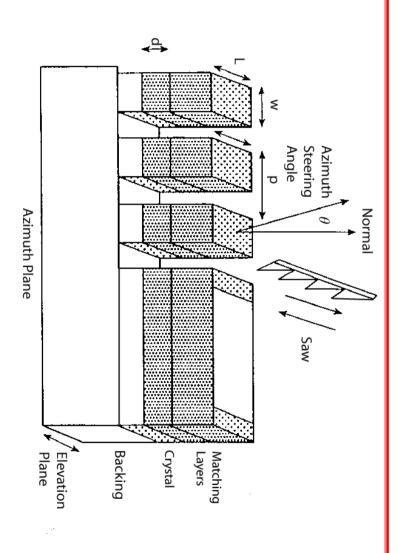
elements



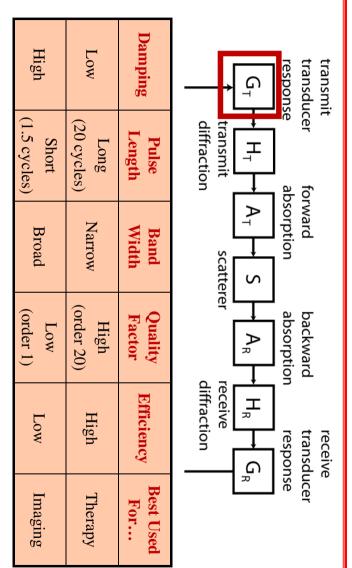
# Step 3: Transducer Considerations

- and construction. Most arrays employ piezoelectric elements characterized by a resonance frequency and Q determined by material properties
- Geometry and shape of piezoelectric material
- Crystallographic orientation of PZT
- Electrode placement
- onto a backing pedestal Most arrays are stacked layers with large surface area bonded
- The sandwich is cut into rows using a saw
- Space between elements is the "kerf"
- Width of the elements is given by "w"
- Distance between element centers is the "pitch", p (typically 1/2 a wavelength)
- elevational focusing The cut elements are then covered by a cylindrical lens for

# Step 3: Transducer Considerations

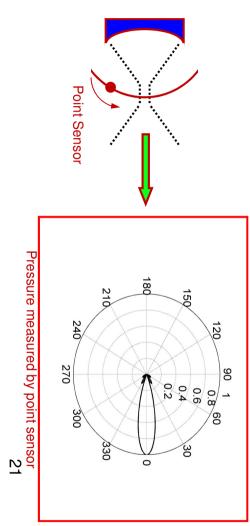


Adapted from Szabo (2004)



## An Important Principle: Reciprocity

- receiver are interchanged that an acoustic response remains the same when the source and In its most elementary form the acoustic reciprocity principle states
- the same on receive as it is on transmit A useful corollary: The acoustic response of a linear transducer is

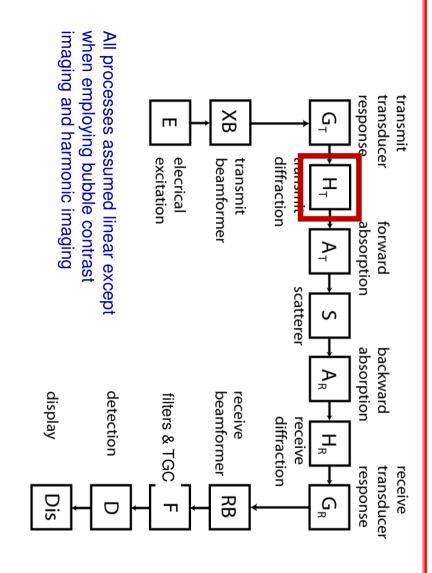


## lmaging vs Therapy Competing Transducer Characteristics

- Axial resolution is given by the spatial pulse length
- B-mode imaging: 1-2 cycle pulse length
- Doppler-mode imaging: 5-10 cycle pulse
- Imaging transducers therefore possess a low quality factor
- Lots of damping (inefficient)
- Operate at low duty cycles to minimize heating and adverse bioeffects
- Therapy arrays must generate high peak acoustic intensities
- Axial resolution given by focusing
- CW or very long pulses
- Tight focusing requires a large aperture
- High efficiency requires low damping (high quality factor)

#### A tradeoff exists

- Good imaging transducers are poor therapy transducers, and vice versa
- Image-guided therapy scan-heads usually employ separate transducers for imaging and therapy



## Step 4: Transmit Diffraction

- along the source surface. described by the mutual interference of "wavelets" generated Radiating sources on the scale of a wavelength create a field
- Subdivide the continuous source into an array of point sources
- Each point source is acoustically compact and generates spherical wave
- Sum these individual fields together to yield the radiated pressure field
- Rayleigh-Sommerfeld integral (Goodman, 1968)

$$\phi(r, \omega, t) = \frac{-1}{2\pi} \int_{S} \frac{e^{i\left[\omega - \vec{k} \cdot (\vec{r} - \vec{r}_{o})\right]}}{\left|\vec{r} - \vec{r}_{o}\right|} V_{n}(r_{o}) dS$$

is the radiating surface Where  $V_n(r_o)$ is the surface-normal component of the particle velocity and S

## Step 4: Transmit Diffraction

then Let  $A_n(r_o)$  be the distribution of normal particle velocity across S,

$$V_n(r_o) = VA_n(r_o)$$

Rayleigh-Sommerfeld integral becomes

$$p(r,\omega,t) = \frac{i\rho ckV}{2\pi} \int_{S} \frac{e^{i\left[\alpha - \vec{k} \cdot (\vec{r} - \vec{r}_{o})\right]}}{\left|\vec{r} - \vec{r}_{o}\right|} A_{n}(r_{o}) dS$$

dimensions are small compared with axial distances, thus The Fresnel (or paraxial) approximation assumes that lateral

$$\left| \vec{r} - \vec{r}_o \right| \approx Z$$

## Step 4: Transmit Diffraction

Therefore:

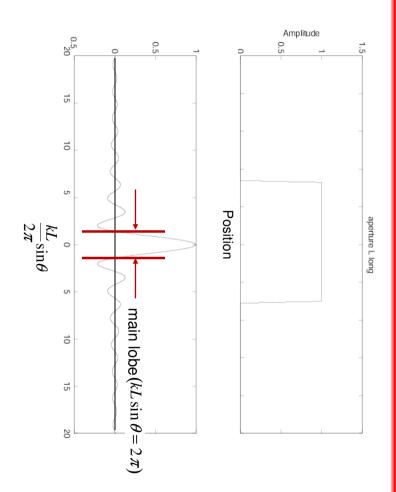
$$p(r,\omega,t) = \frac{i\rho ckV}{2\pi c} e^{i\alpha} \int_{S} e^{i\left[-\bar{k}\cdot\bar{r}\right]} A_{n}(r_{o}) dS$$

- The far field radiation pattern for a transducer looks something like the spatial Fourier transform of  $A_n(r_o)$  the "apodization" function.
- For a uniform line source of length L, the apodization function is the rectangular function. The transform is a sinc function. Can show that

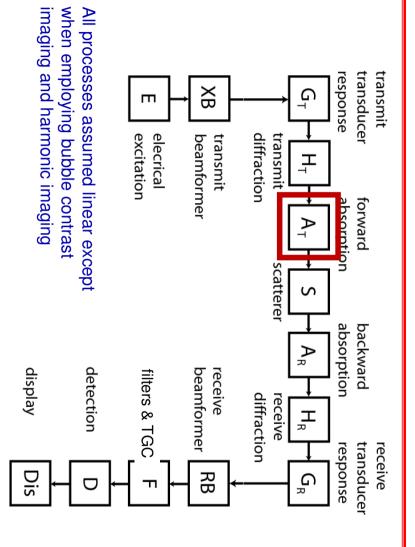
$$p(\theta) \propto \sin\left(\frac{kL}{2\pi}\sin\theta\right) = \frac{\sin(\frac{1}{2}kL\sin\theta)}{\frac{1}{2}kL\sin\theta}$$

- Beam possesses a main lobe plus side lobe structure
- Acoustically small aperture -- small kL -- wide beam
- Acoustically large aperture -- large kL -- narrow beam

## Step 4: Transmit Diffraction



Adapted from Szabo (2004)



# Step 5: Propagation Losses in Tissue

- Waves propagating in real media experience losses
- Thermal conductivity
- Viscous losses
- Molecular relaxation
- propagating wave, a process known as attenuation. These losses, along with scattering, remove energy from the
- A time harmonic propagating plane wave is written as

$$P(z,t) = P_o e^{-\alpha z} e^{i(\alpha t - kz)}$$

where alpha is the attenuation coefficient in nepers/cm. This is essentially a plane wave with a loss factor that increases exponentially with distance.

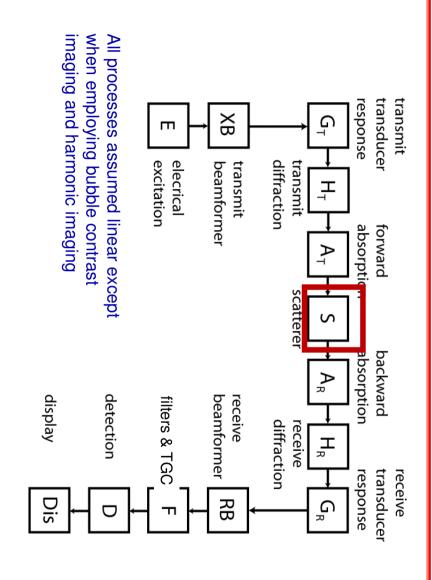
- as intensities consider the effect of attenuation on pulse waveforms as well Because imaging is done with pulse echoes, it is useful to
- Understanding frequency-dependent attenuation is key

## Step 5: Propagation Losses in Tissue

- Visco-thermal absorption has quadratic frequency dependence
- Not the case for propagation through tissues
- Power law attenuation model:  $\alpha(f) = \alpha_c + \alpha_f f$
- Dispersion

$$c(f) = c_o + \Delta c(f)$$

- General rule of thumb for power law attenuation:  $y \approx 1.1$
- Duck (1990) has compiled data for a number of different tissues
- Scattering contributes to measured attenuation
- About 10-15% of total attenuation at low MHz frequencies
- Deviation from viscothermal behavior is not fully understood
- Viscoelastic rheology, multiple relaxation times, etc
- Beyond scope of lecture: See Szabo (2004) for a detailed discussion



### Step 6: The Scattering Medium

- What information is contained in an ultrasound image?
- the propagation medium Spatially dependent backscatter and transmission "properties" of
- Interfaces
- Volume scattering
- Transmission and forward scatter impacts returns from objects "downstream"
- This information is further "colored" by systemic characteristics
- Transducer spatial and temporal response
- Signal processing algorithms
- Image processing algorithms
- Frequency-dependent propagation losses
- Nonlinearity
- you see on the screen and the diagnosis of illness Radiologists are needed to bridge the gap between what

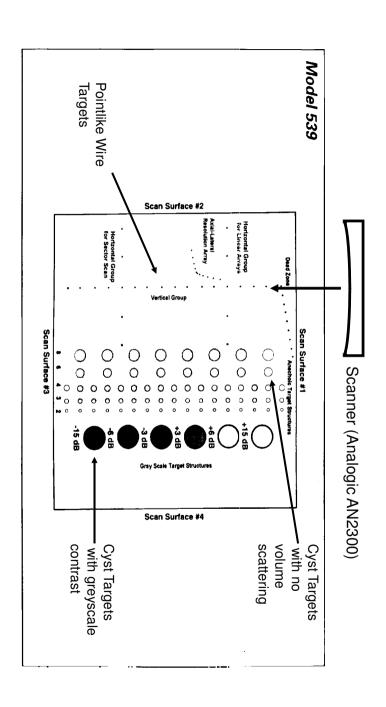
#### scales Tissues present scatterers possessing several length Step 6: The Scattering Medium

- Class 1: Objects much smaller than  $\lambda$  diffusive scattering
- Rayleigh scattering from individual particles (Morse & Ingard, 1968)
- Pronounced frequency dependence ( $I_s$  proportional to  $f_s$
- Discrete returns are not resolved you get volume scattering
- density of scattering particles -- not changes in bulk acoustic impedance Contrast based on compressibility and density of the particles and the number

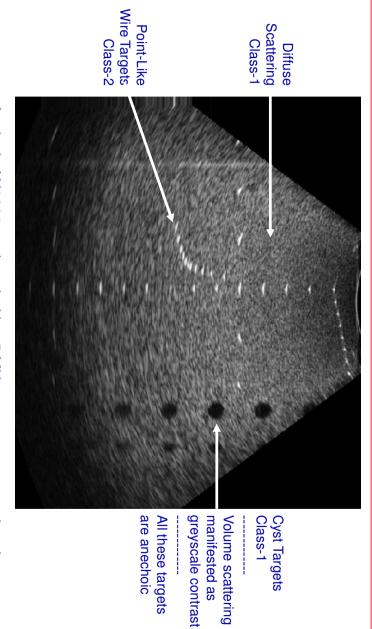
$$p_s = \frac{1}{3} \frac{p_i}{kr} (ka)^3 \left[ \left( \frac{\kappa - \kappa_s}{\kappa} \right) + \left( \frac{3(\rho - \rho_s)}{2(\rho + \rho_s)} \right) \cos \theta_s \right] \qquad ka << 1$$

- Class 2: Objects on the order of  $\lambda$  diffractive scattering
- Discrete returns with complicated angle and frequency dependence
- Governed by matching boundary conditions -- continuity of normal stress and normal velocity -- at the surface of the scatterer (Morse & Ingard, 1968)
- Invoke the Born approximation
- Class 3: Objects and interfaces much larger than  $\lambda$  specular reflection
- Manifested as discrete returns that obey Snell's law
- Contrast based primarily on the impedance mismatch at the boundary
- Interfacial transmission loss matters too!

#### Step Geometry <u>ნ</u> of A.T The Scattering Medium <u>.</u> **Labs Calibration Phantom**

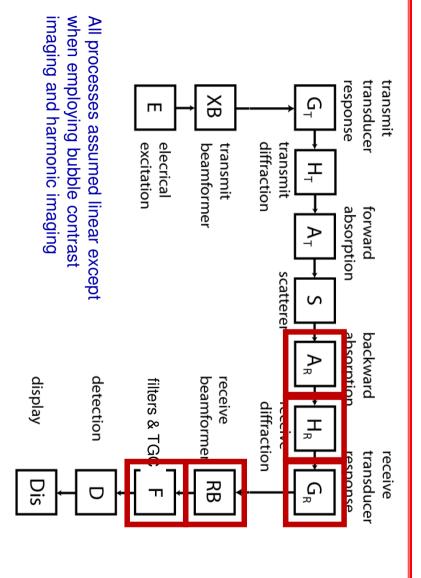


#### B-Mode Image of A.T.S. Labs Calibration Phantom Step 6: The Scattering Medium



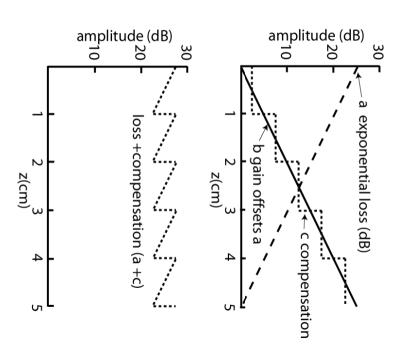
Analogic AN2300 equipped with a 5 MHz convex array scanhead

Adapted from Szabo (2004)



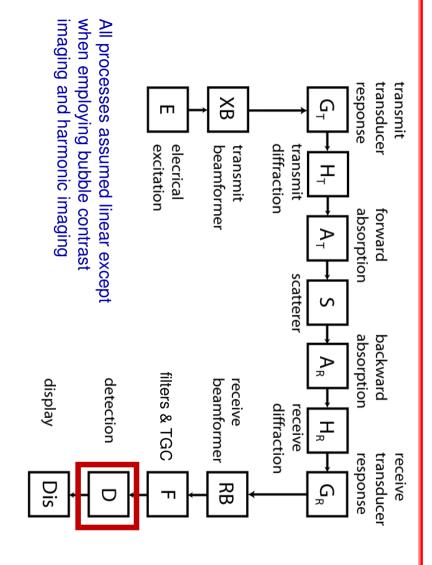
## Time Gain Compensation Step 11: Correcting for Attenuation Loss

- Divide the image into a stack of separate strips
- Horizontal strips (linear scan format
- Concentric arcs (sector scanned format)
- Data arriving in time windows corresponding to each strip is fed to a different receive preamplifier stage
- Set the TGC gains to offset average loss in each zone



Step 11: Filtering

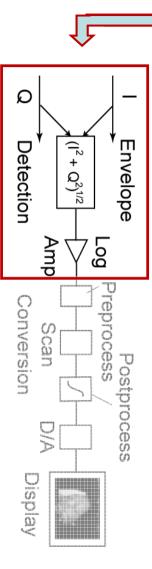
- Low-pass anti-aliasing filter
- Bandpass filter centered at  $\omega_o$  for conventional B-Mode imaging
- imaging Bandpass filter filter centered at  $2\omega_o$  for harmonic

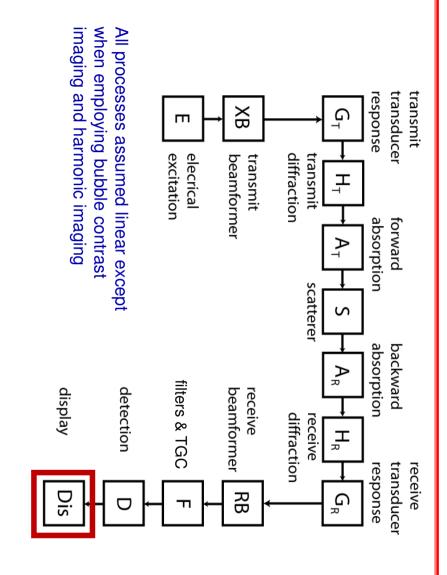


Adapted from Szabo (2004)

## Step 12: Detection

- Filtered beamformed signal is envelope detected
- Done in analog using diode bridges (lose phase information)
- information -- good for Doppler) Done in analog using a quadrature demodulator (preserves phase
- Done digitally using a variety of techniques
- Result is logarithmically compressed
- End up with an "A-line" in a known scan vector direction

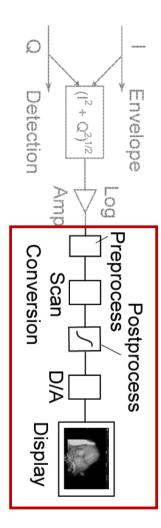




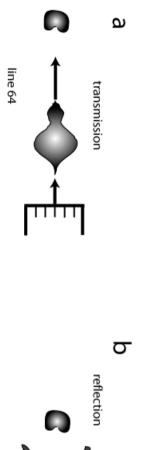
Step 13: Display

Adapted from Szabo (2004)

- Subsequent scan vectors are obtained and stored in memory
- proper geometrical orientation pulse-echo image where the lines are arranged in their All the lines are interpolated or "scan converted", forming a
- compressed echo amplitude information) and displayed The image is converted to grey scale (represented



### Recapitulation



Ф focusing (rf alignment)

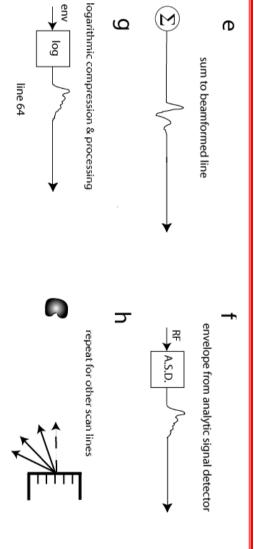
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 $\cap$ 

reception

## Recapitulation

Adapted from Szabo (2004)



(M)

Φ

9

log



geometric arrangement of scan lines

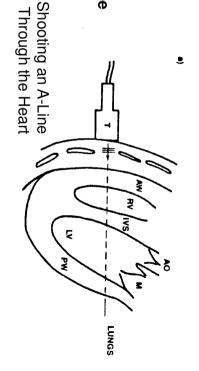
image from interpolated scan lines



## **Popular Imaging Modalities**

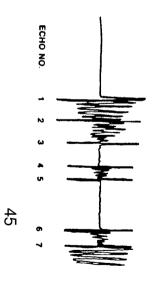
#### A-Mode

- Shoot a single line and view the depth (time) dependent returns.
- Similar to what you might see on an oscilloscope display, where time is converted to distance: ∆z = c∆t



Resulting A-Mode Display

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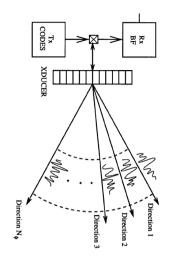


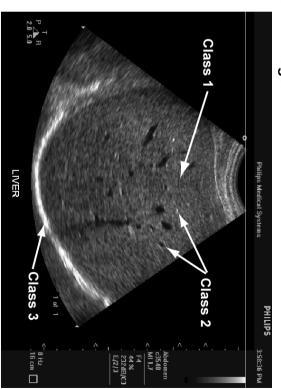
Phillips Medical Systems

## **Popular Imaging Modalities**

#### **B-Mode**

- Generate a series of scan lines in a plane (the imaging plane)
- (sector scan). The lines can be scanned linearly (linear scan) or angularly
- Propagation time is converted to distance:  $\Delta z = c\Delta t$
- Combine the scans to form a 2-D image.





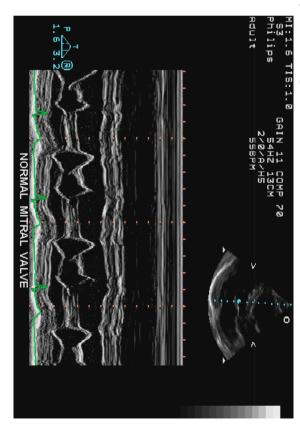
## Popular Imaging Modalities

#### M-Mode

- x-y display where depth is y and x is a running display of the same imaging line shot over and over, and return amplitudes are encoded as brightness
- Displays a time history of activity (interface motion) for a given line
- Duplex M-Mode: displayed in conjunction with B scan

Duplex B-mode image and M-mode display of a mitral valve in the heart

The cardiac cycle is clearly evident in the M-mode display



Phillips Medical Systems

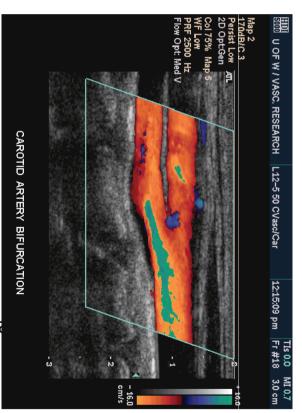
## **Popular Imaging Modalities**

#### Color Flow Doppler

- A spatial map that depicts blood flow mean velocity with direction given by color
- The map is overlayed on a B-Mode image

Linear B-mode image with color Dopper overlayed

Contiguous imaging format (sector steering plus translation)



## **Popular Imaging Modalities**

- Color M-Mode
- Standard M mode plus a color flow depiction of flow
- Displays a time history of a single color flow line

Color Flow Doppler Image (top)

Color M-Mode display (bottom)

