CSC 770 Parallel Computing

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Parallel Sum by Divide and Conquer

What is divide and conquer

• Divide and conquer usually applies partitioning in a recursive manner by continually dividing the problem into smaller and smaller parts (MPI-scatter) and combining the results (MPI-gather).

Divide And Conquer

Divide and conquer algorithms generally have 3 steps:

- Divide: Split the sequence into subproblems.
- Conquer: Recursively solve the subproblems
- Combine: The solutions of subproblems to create the solution to the original problem.
 - There are 3 possibilities: (1) the maximum sum lies completely in the left subproblem, (2) the maximum sum lies completely in the right subproblem, and (3) the maximum sum spans across the split point. The first two cases are easy. The more interesting case is when the largest sum goes between the two subproblems. The maximum subsequence that spans the middle is equal to the largest sum of a suffix on the left and the largest sum of a prefix on the right.

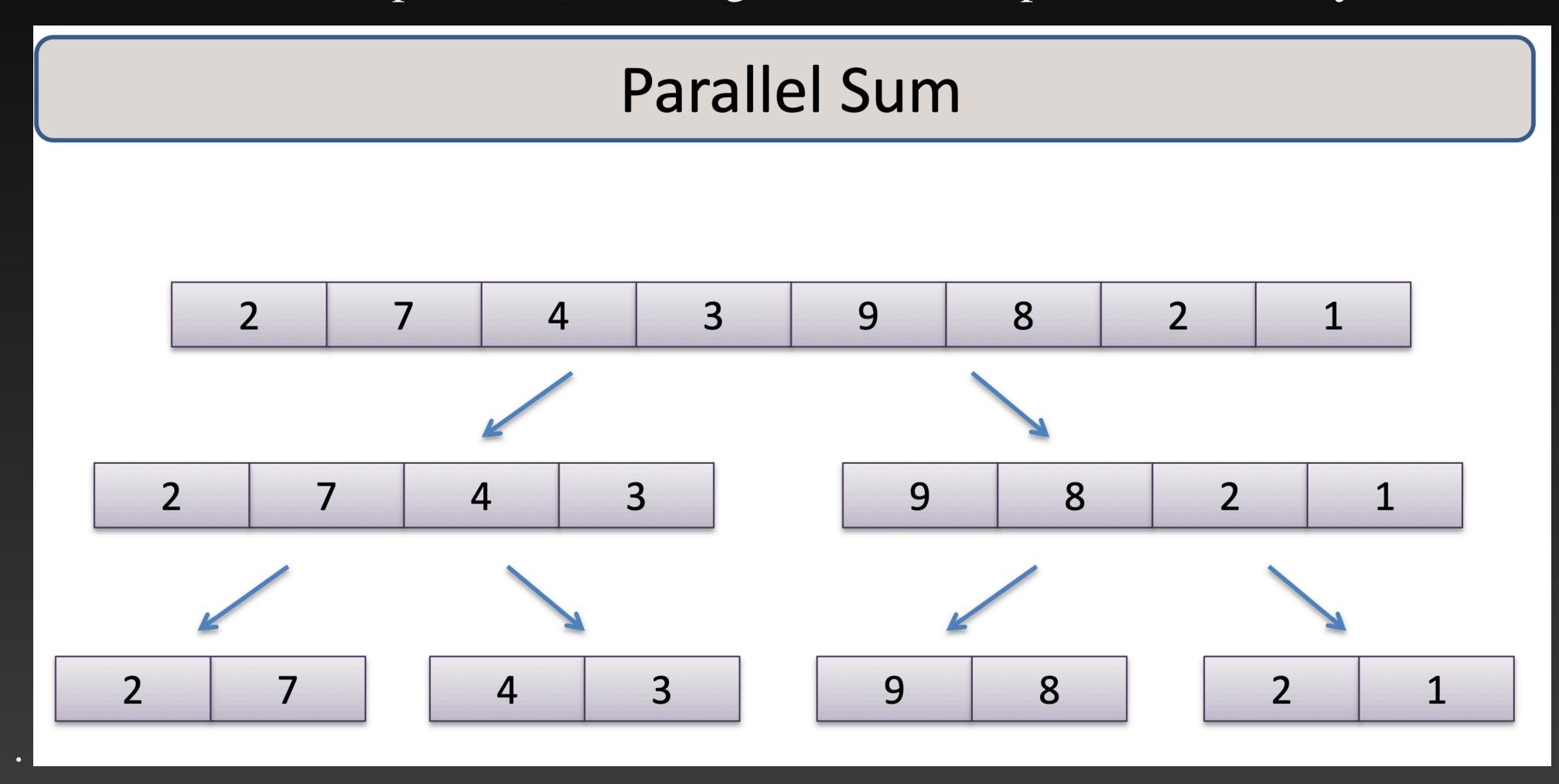
MPI Scatter and Gather

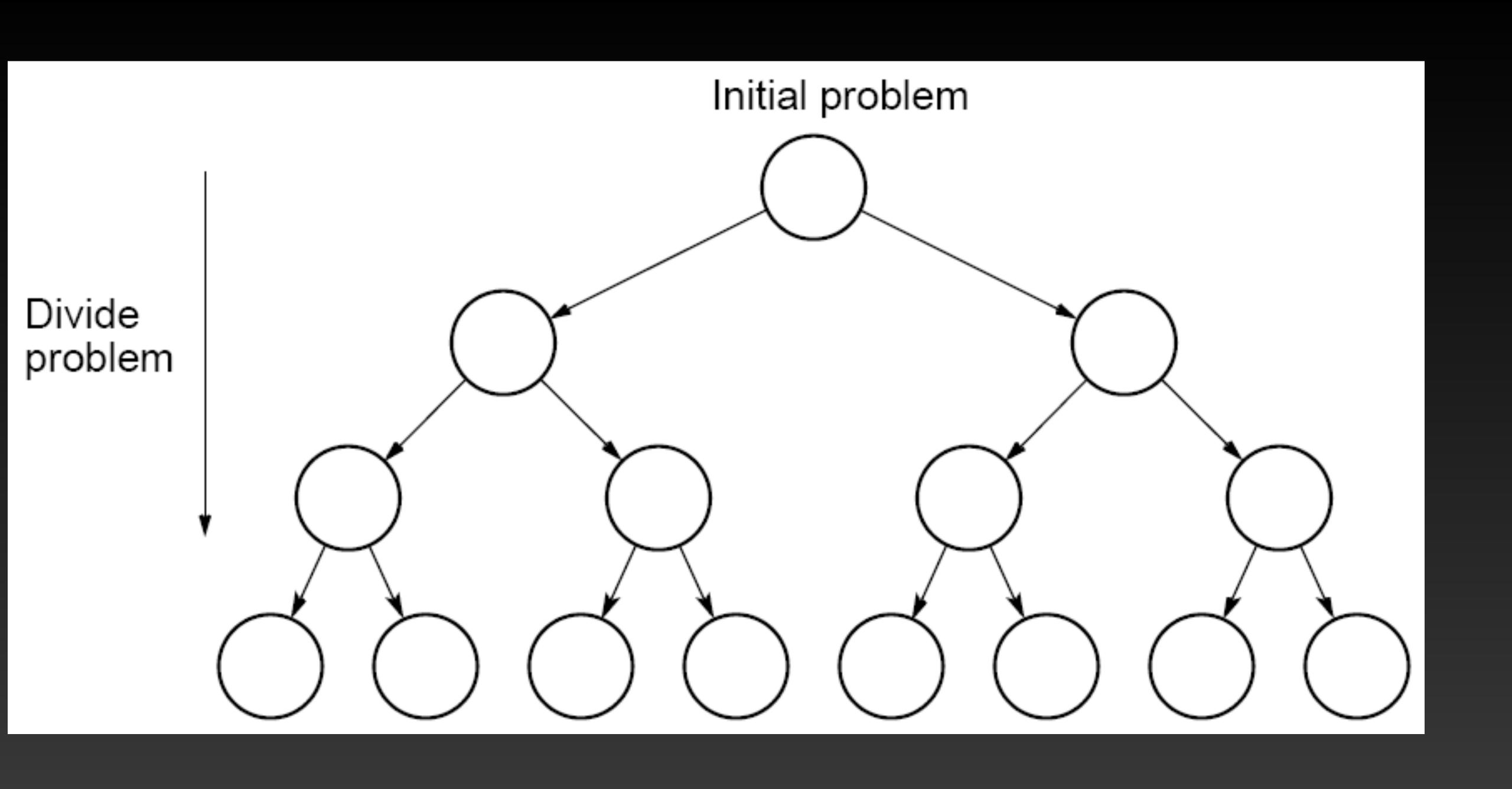
Two very important routines:

- Group functions that can manage the data distribution and collecting more easily.
- Scatter: involves a designated root process sending data to all processes in a communicator. Divides a big array into a number of smaller parts equal to the number of processes and sends each process (including the source) a piece of the array in rank order. MPI Scatter sends chunks of an array to different processes.
- Gather: MPI Gather is the inverse of MPI Scatter. Instead of spreading elements
 from one process to many processes, MPI Gather takes data stored from many
 processes (including the source or root) and gathers the elements to one single
 process and concatenates it in the receive array in rank order. This routine is
 highly useful to many parallel algorithms, such as parallel sorting and searching.

Divide into small portions

scatter: divides a big array into a number of smaller parts equal to the number of processes and sends each process (including the source) a piece of the array in rank order.





Code Snippet to scatter

```
for(int i = 1; i <= log2(size); i++){
   int dis = (int)pow(2, i-1);
   if (rank % dis == 0){

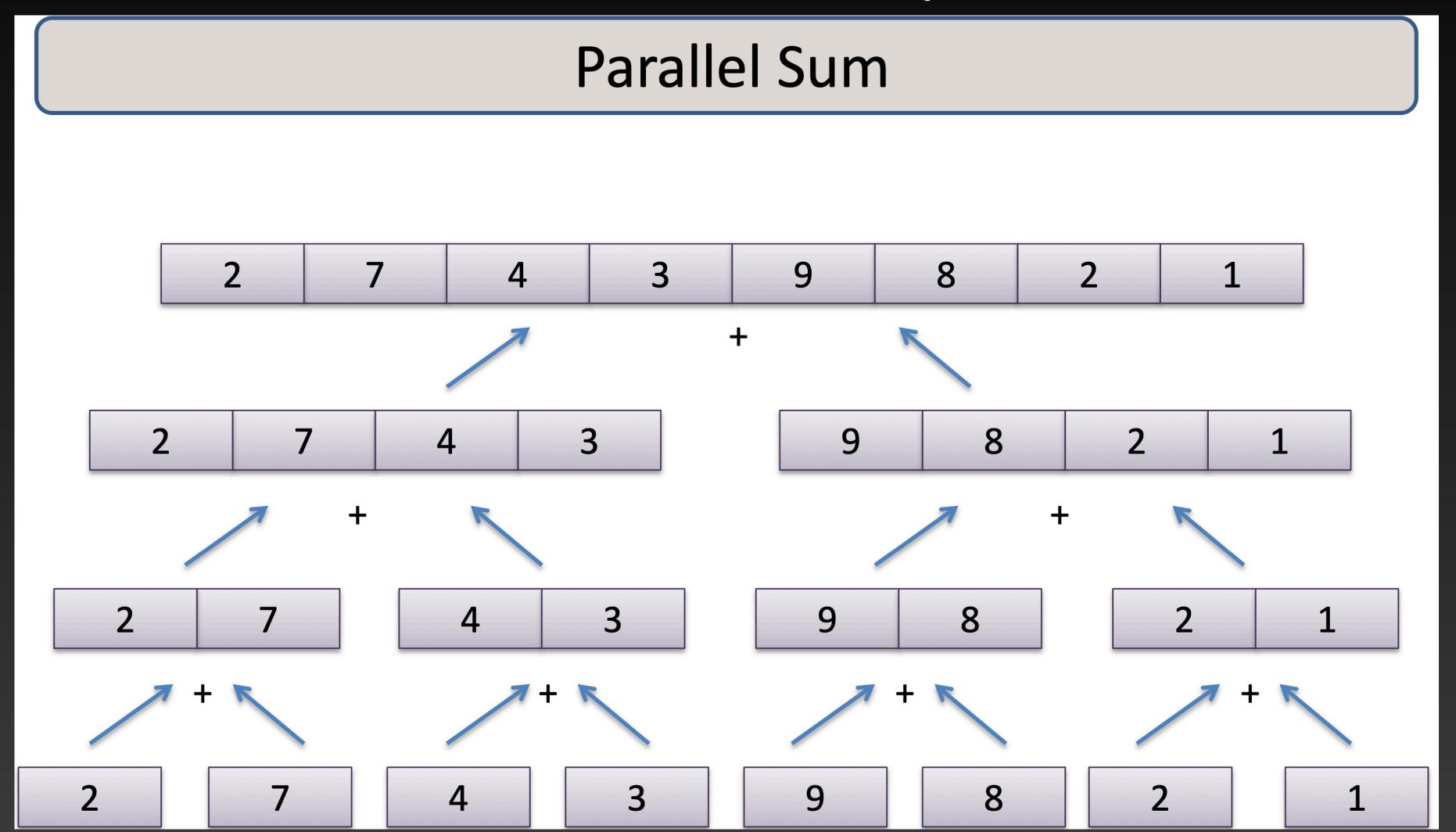
       if(rank % (2*dis) != 0){

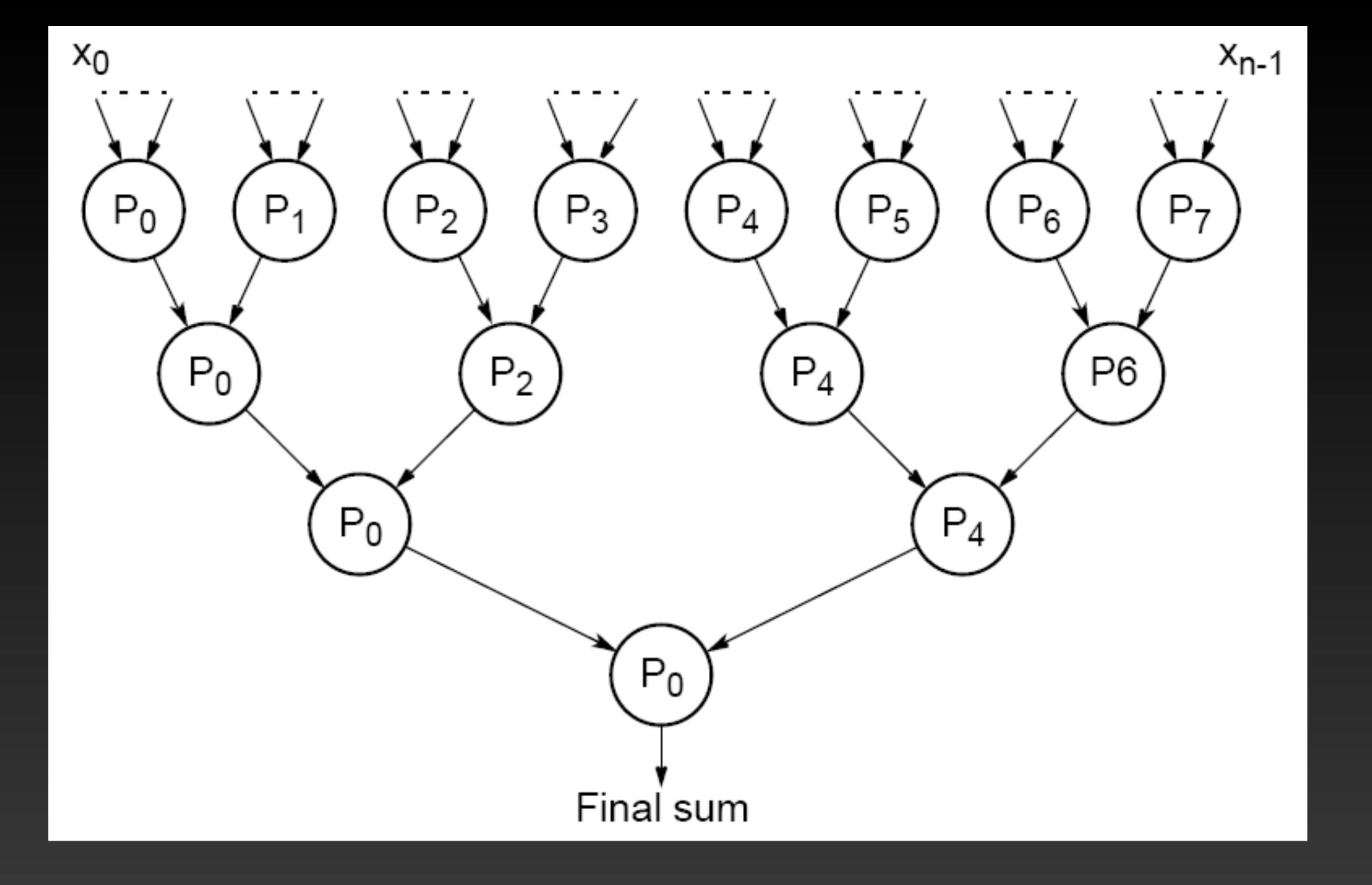
       int recvpid = rank - dis;
       if (recvpid >= 0 && recvpid <= (size - 1)){

            MPI_Send(&parallelSum, 1, MPI_INT, recvpid, i, MPI_COMM_WORLD);
            printf("Rank %d sends %d to rank %d\n", rank, parallelSum, recvpid);
       }
    }
}</pre>
```

MPI Gather

Gather: the opposite, receives data stored in small arrays from all the processes (including the source or root) and concatenates it in the receive array in rank order.

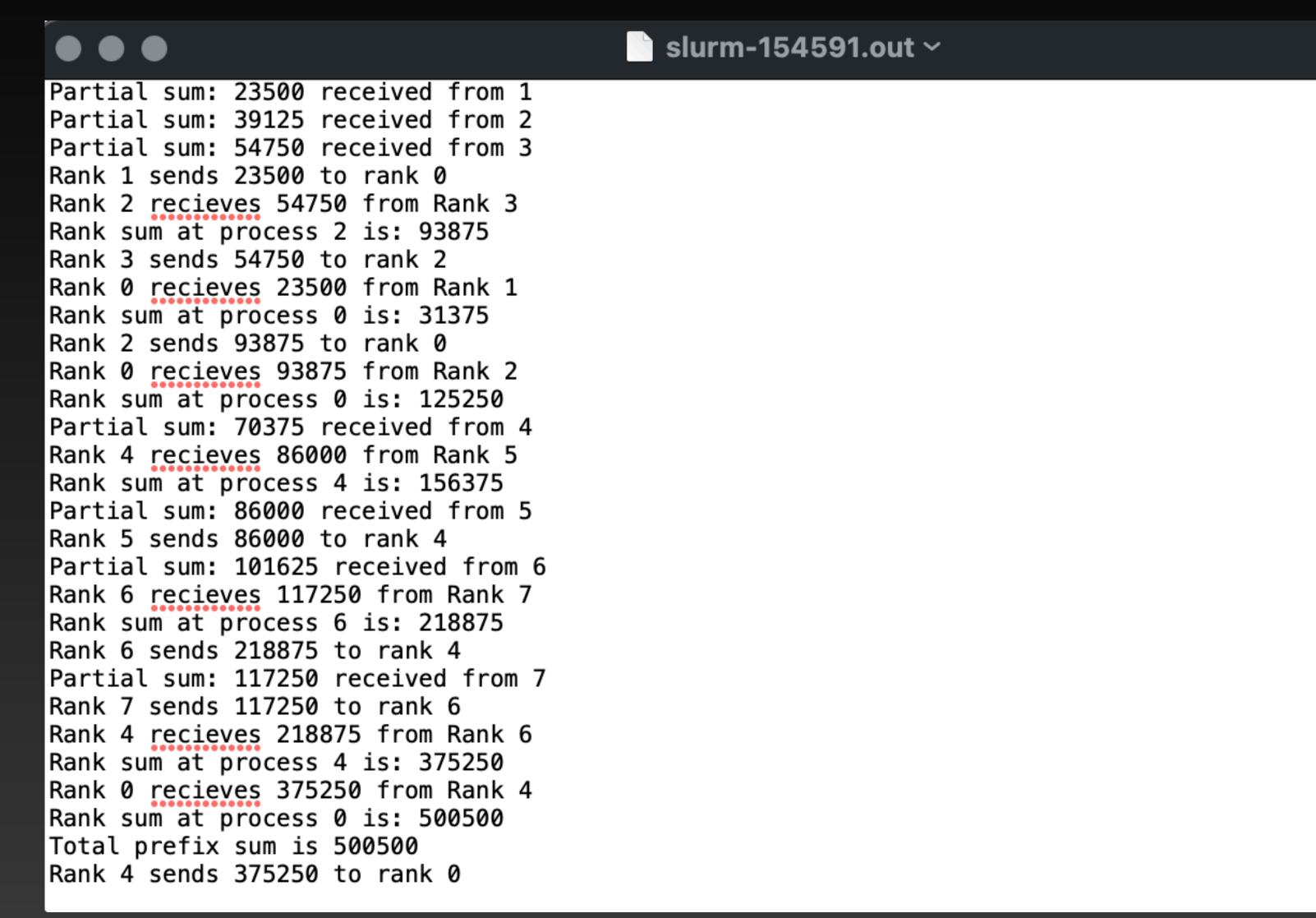




Code snippet to gather

```
if (rank % (2*dis) == 0){
        int sendpid = rank + dis;
        if (sendpid >= 0 && sendpid <= (size-1 )){</pre>
            MPI_Recv(&total, 1, MPI_INT, sendpid, i, MPI_COMM_WORLD, &status);
            printf("Rank %d recieves %d from Rank %d\n", rank, total, sendpid);
            parallelSum = parallelSum + total;
            printf("Rank sum at process %d is: %d\n", rank, parallelSum);
if (rank == 0){
    printf("Total prefix sum is %d\n", parallelSum);
```

Sample Output



Perfomance considerations

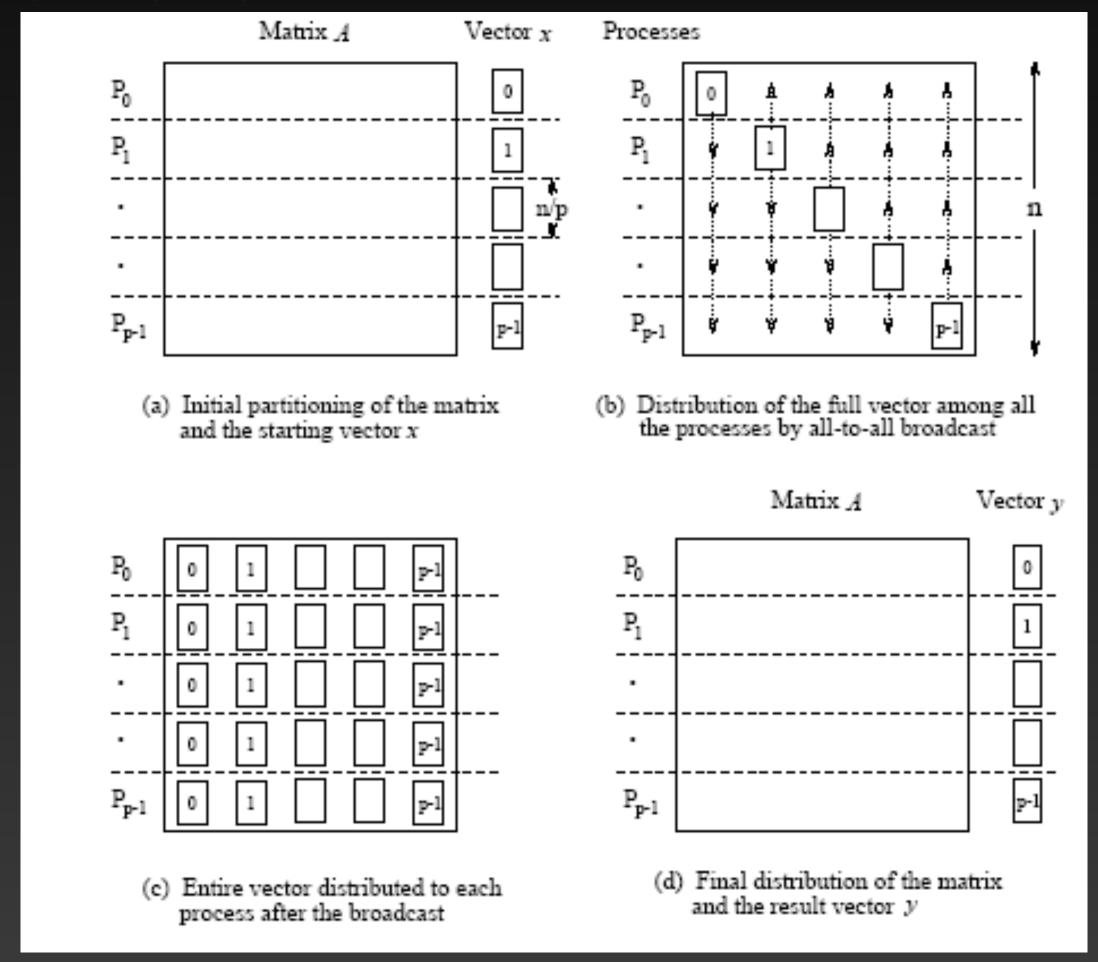
How an MPI_Scatter/Gather will work varies between implementations. Some MPI implementations may choose to use a series of MPI_Send as an underlying mechanism.

The parameters that may affect how MPI_Scatter works are:

- 1. Number of processes
- 2. Size of data
- 3. Interconnect For example, an implementation may avoid using a broadcast for very small number of ranks sending/receiving very large data.

1D Row-wise matrix multiplication

- The *n* x *n* matrix is partitioned among *n* processors, with each processor storing complete row of the matrix.
- The *n* x 1 vector *x* is distributed such that each process owns one of its elements.



1D Row-wise matrix multiplication

- Since each process starts with only one element of $\,x$, an all-to-all broadcast is required to distribute all the elements to all the processes.
- Process P_i now computes
- The all-to-all broadcast and the computation of y[i] both take time $\Theta(n)$. Therefore, the parallel time is $\Theta(n)$.

1D Row-wise matrix multiplication

- Consider now the case when p < n and we use block 1D partitioning.
- Each process initially stores n=p complete rows of the matrix and a portion of the vector of size n=p.
- The all-to-all broadcast takes place among p processes and involves messages of size n=p.
- This is followed by n=p local dot products.
- Thus, the parallel run time of this procedure is

$$T_P = rac{n^2}{p} + t_s \log p + t_w n.$$

This is cost-optimal.

Code snippet to scatter

```
//MPI_Bcast(data,row*column,MPI_INT,0,MPI_COMM_WORLD);
MPI_Scatterv(data,sendcount,displace,MPI_FLOAT,rec_data,sendcount[rank],MPI_FLOAT,0,MPI_COMM_WORLD);
count=sendcount[rank]/column;
sum=(float*)calloc(sizeof(float),count);
multi(count,sum,vec,rec_data,column);
float *result=(float *)calloc(sizeof(float),row);
int disp[size];
disp[0]=0;
reccount[0]=sendcount[0]/column;
for(i=1;i<size;i++)
{
    disp[i] = disp[i-1] + sendcount[i-1]/column;
    reccount[i]=sendcount[i]/column;
}</pre>
```

Code snippet to gather

```
MPI_Gatherv(sum,count,MPI_FLOAT,result,reccount,disp,MPI_FLOAT,0,MPI_COMM_WORLD);
if(rank==0)
{
```

2D/checkerboard matrix multiplication

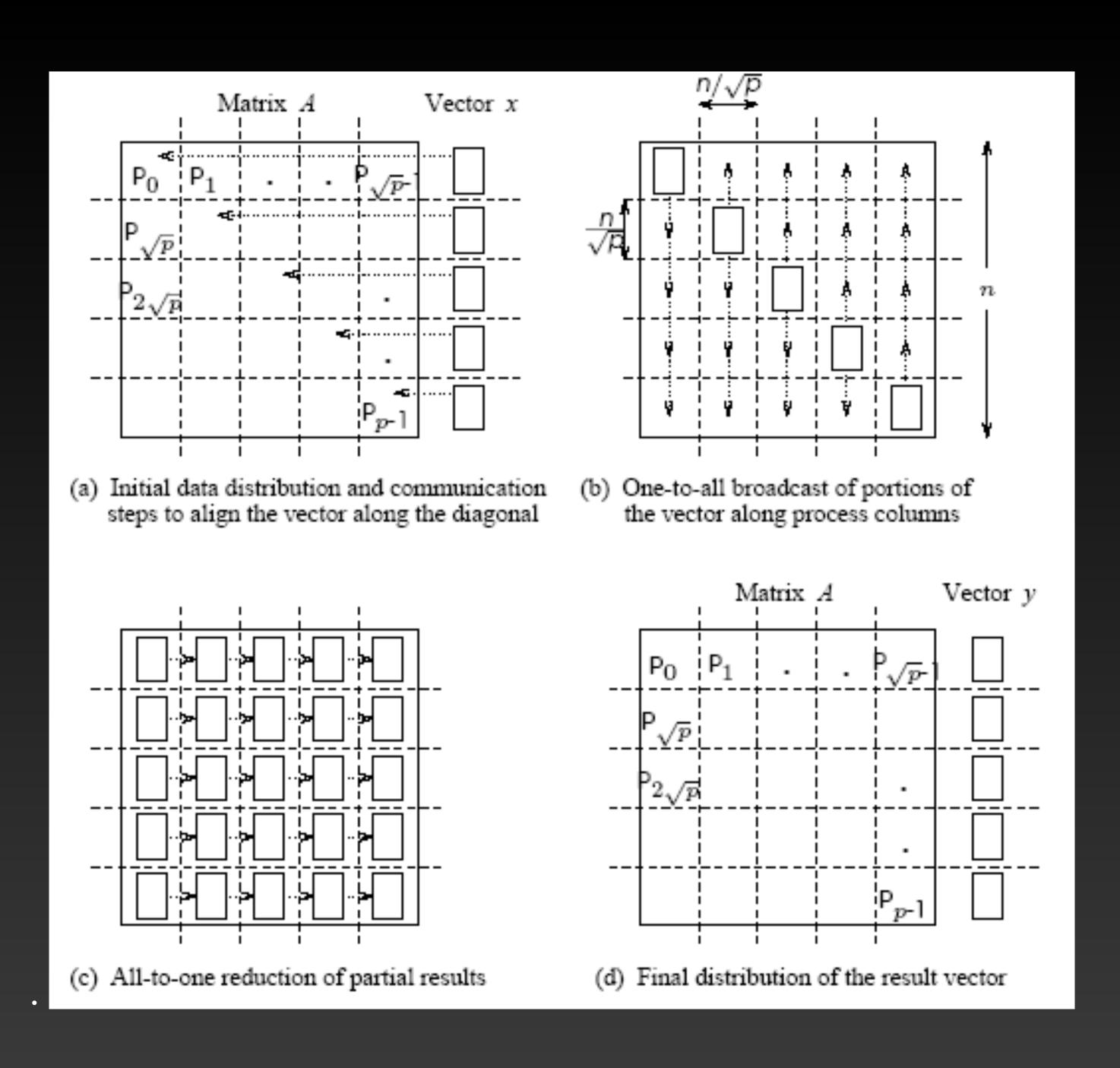
- •The $n \times n$ matrix is partitioned among n^2 processors such that each processor owns a single element.
- •The $n \times 1$ vector x is distributed only in the last column of n processors.

Checkerboard Partitioning

Checkerboard partitioning: a matrix is divided into small square or rectangular blocks and each of them is mapped to a processor. Maximum n^2 processors

More concurrency may be exploited

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Operations

- One to one: the processors holding the vector row value [i] send it to the [i][i] element in the matrix
- One to all: the diagonal matrix formed from the step above broadcasts all the values in the matrix[I][I] to all the other processors to allow multiplication
- The processors all reduce the values back to the master processor to hold the final multiplication vector

Code snippet of one to one and all to all

```
MPI_Bcast (Vector, SIZE, MPI_INT, 0, MPI_COMM_WORLD);
MPI_Scatter (MatrixA, 1, MPI_INT, MatrixA[start], 1, MPI_INT, 0, MPI_COMM_WORLD);
outPut[start] = 0;
outPut[start] += MatrixA[start][0]* Vector[(int)pid%SIZE];
```

Code snippet to reduce

```
MPI_Reduce(&outPut,&final,SIZE,MPI_INT, MPI_SUM,0,MPI_COMM_WORLD);
if (pid == 0) {
    printf("\nInput Matrix ");
for (int i = 0; i < SIZE; i++) {</pre>
    printf("\n\t|");
    for (int j = 0; j < SIZE; j++)</pre>
        printf("%2d ", MatrixA[i][j]);
    printf("|");
printf("\n\nVector\n");
for (int i = 0; i < SIZE; i++) {</pre>
    printf("\n\t|%2d ", Vector[i]);
    printf("|");
printf("\n\nMultiplication\n");
for (int i = 0; i < SIZE; i++) {</pre>
    printf("\n\t|%2d ", final[i]);
    printf("|");
MPI_Finalize();
return 0;
```

Sample results

```
\bullet \bullet \bullet
                                      slurm-154596.out
Java module loaded - the system's JAVA is replaced by JDK 1.8.0_211
Input Matrix
          1 2 3 4 5 6 7 8
         9 10 11 12 13 14 15 16
        17 18 19 20 21 22 23 24
        25 26 27 28 29 30 31 32
        33 34 35 36 37 38 39 40
        41 42 43 44 45 46 47 48
        49 50 51 52 53 54 55 56
        57 58 59 60 61 62 63 64
Vector
          2
          3
          4
          5
          6
          7
          8
         9
Multiplication
         2
          6
         |12
         20
```