

Fluid Equations

- A fluid element must be:

↳ small enough so that macroscopic properties $\sim \text{const}$

↳ large enough to have a large number of particles.

- Collisional fluids have a small mean-free-path λ :

↳ particles maximise entropy

↳ well-defined pressure $p = p(\rho, T)$ ← equation of state

- Collisionless fluids have non-local effects and depend on I.C.s.

- Two frameworks for describing fluids:

↳ Eulerian → consider fluid properties as time-varying fields,
e.g. $\rho(r, t)$, $p(r, t)$, $T(r, t)$, $\underline{u}(r, t)$

↳ Lagrangian → perspective of a particular fluid element as time progresses (co-moving frame)

- Consider how quantity $Q(r, t)$ changes in the Lagrangian picture

$$\frac{DQ}{Dt} = \lim_{\delta t \rightarrow 0} \left[\frac{Q(r + \delta r, t + \delta t) - Q(r, t)}{\delta t} \right]$$

$$\Rightarrow \frac{DQ}{Dt} = \frac{\partial Q}{\partial t} + \underline{u} \cdot \nabla Q \quad \leftarrow \text{Lagrangian} \leftrightarrow \text{Eulerian}$$

convective derivative: gradient projected onto flow

- 3 ways to describe particle trajectories:

↳ streamlines show the velocity field at a given time, i.e. shows instantaneous tangents

↳ pathlines show the paths taken by individual fluid elements

↳ streaklines connect all points that passed through a particular reference point (e.g. after releasing a drop of dye).

↳ all 3 coincide if $\frac{\partial \underline{u}}{\partial t} = 0 \Rightarrow$ steady flow

Conserved quantities

- Conservation of mass:

↳ $\frac{dm}{dt} = -\text{rate of outflow}$

$$\frac{\partial}{\partial t} \int_V \rho dV = - \int_S \rho \underline{u} \cdot d\underline{s}$$

) div. theorem

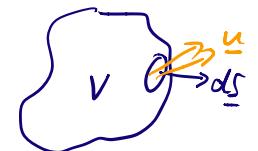
$$\Rightarrow \int_V \left(\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) \right) dV = 0$$

$$\Rightarrow \boxed{\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) = 0} \rightarrow \text{continuity equation (Eulerian)}$$

↳ easy to derive Lagrangian form: $\frac{D\rho}{Dt} = \frac{\partial \rho}{\partial t} + \underline{u} \cdot \nabla \rho$

$$\Rightarrow \boxed{\frac{D\rho}{Dt} + \rho \nabla \cdot \underline{u} = 0}$$

For an incompressible flow, $\frac{D\rho}{Dt} = 0 \Rightarrow \nabla \cdot \underline{u} = 0$, i.e. the fluid is divergence-free.



- The forces in a fluid are described with the stress tensor σ_{ij}

$$\hookrightarrow dF_i = \sigma_{ij} dS_j$$

$$\hookrightarrow \text{for an isotropic fluid, } \sigma_{ij} = p\delta_{ij} \Rightarrow dF = pdS$$

- Derive cons momentum by considering a fluid element subject to gravity and internal pressure

\hookrightarrow consider all quantities projected onto \hat{n}

$$\hookrightarrow \text{pressure force} = - \int_V p \hat{n} \cdot dS = - \int_V \hat{n} \cdot \nabla p dV$$

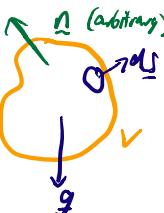
$$\hookrightarrow \text{NII: } \left(\frac{\partial}{\partial t} \int_V \rho \underline{u} dV \right) \cdot \hat{n} = - \int_V \hat{n} \cdot \nabla p dV + \int_V \rho g \cdot \hat{n} dV$$

\hookrightarrow fluid element so $\int dV \rightarrow \delta V$

$$\begin{aligned} p \frac{Du}{Dt} &= -\nabla p + \rho g \\ p \frac{\partial u}{\partial t} + \rho(\underline{u} \cdot \nabla) \underline{u} &= -\nabla p + \rho g \end{aligned}$$

→ momentum equations

→ easier to derive with box



- Consider the Eulerian rate of chg of momentum density

$$\partial_t(\rho u_i) = \rho \partial_t u_i + u_i \partial_t \rho \quad \substack{\text{sub cont} & \text{mom. eqns}}$$

$$= -\rho u_j \partial_j u_i - \partial_j \rho u_j + \rho g_i - u_i \partial_j (\rho u_j)$$

$$= -\partial_j (\underbrace{\rho u_i u_j}_{\equiv \sigma_{ij}} + \rho F_{ij}) + \rho g_i$$

$$\hookrightarrow \text{rewrite as } \partial_t(\rho \underline{u}) = -\nabla \cdot (\underbrace{\rho \underline{u} \otimes \underline{u} + \rho \underline{I}}_{\text{Flux of momentum density}}) + \rho \underline{g}$$

$\hookrightarrow \rho u_i u_j$ is a 'ram' pressure due to momentum flux of the bulk flow

Gravitation

$$\cdot g(r) = -G \int_V \rho(r') \frac{r-r'}{|r-r'|^3} dV$$

$$\cdot \text{Gives Poisson's equation: } \left\{ \begin{array}{l} \nabla \cdot g = -\nabla^2 \Psi = -4\pi G\rho \\ \int_S g \cdot dS = -4\pi G M_{\text{enc}} \end{array} \right.$$

- Potential of a spherically-symmetric system:

$$g(r) = \frac{GM_{\text{enc}}}{r^2} = \frac{d\Psi}{dr}$$

$$\Rightarrow \Psi = \int_{\infty}^r \frac{G}{r^2} \left(\int_0^r 4\pi \rho(r') r'^2 dr' \right) dr$$

$$\Psi(r) = -\frac{GM(r_0)}{r_0} + \int_{\infty}^r 4\pi G \rho(r) dr$$

- The GPE of a system is $\mathcal{L} = \frac{1}{2} \int \rho(r) \Psi(r) dV$

- Consider the moment of inertia of a composite system \leftarrow arbitrary origin

$$I = \sum_i m_i r_i^2 \Rightarrow \frac{1}{2} \frac{d^2 I}{dt^2} = \sum_i (r_i \cdot F_i + m_i \dot{r}_i^2)$$

$\hookrightarrow \sum_i r_i \cdot F_i$ is the GPE \leftarrow assume isolated system and forces are either local or gravitational

$\hookrightarrow \sum_i m_i \dot{r}_i^2$ is twice the KE

\hookrightarrow for a system in the steady state, $\frac{d^2 I}{dt^2} = 0$

\hookrightarrow combine to give the Virial theorem: $2T + \mathcal{L} = 0$

- The Virial thm relates mass, velocity, size:

$$T = \frac{1}{2} M \langle v^2 \rangle, \quad \mathcal{L} = -\frac{GM^2}{r} \Rightarrow \langle v^2 \rangle = \frac{GM}{r} \leftarrow \text{mass-weighted avg size.}$$

$\hookrightarrow E_{\text{tot}} = T + \mathcal{L} = -\frac{1}{2} M \langle v^2 \rangle$, so as 'temp' T (higher $\langle v^2 \rangle$), energy decreases \Rightarrow negative heat capacity

\hookrightarrow this is why structures form from smooth ICs.

Equations of State

- We have 3 scalar + 1 vector unknowns: $\rho, \mathbf{u}, p, \Psi$, but only 3 eqs (continuity, momentum, Poisn).
- The equation of state provides the additional constraint.
- For a barotropic fluid, pressure is only a function of density: $p = p(\rho)$
 - ↳ e.g. electron degeneracy pressure: $p \propto \rho^{5/3}$
 - ↳ e.g. isothermal ideal gas: $p \propto \rho$. This occurs when strong heating and strong cooling balance at a well-defined temp.
 - ↳ e.g. adiabatic ideal gas $p = k\rho^\gamma$.
- Fluid elements may each be adiabatic ($p = k\rho^\gamma$ with k const), but k may vary between elements \rightarrow isentropic if all have same k (because $\ln k \propto S_m$).

The Energy Equation

- From the 1st law of thermo, $\frac{DE}{Dt} = \frac{d\mathbf{Q}}{dt} + \frac{DW}{Dt}$
- ↳ $dW = -pdV \Rightarrow \frac{DW}{Dt} = -p \frac{D}{Dt} \left(\frac{1}{\rho} \right) = \frac{f}{\rho^2} \frac{D\rho}{Dt} \quad \leftarrow \text{for unit mass, } V = \frac{1}{\rho}$
- ↳ $\frac{d\mathbf{Q}}{dt} = -\dot{Q}_{cool} \Rightarrow \frac{DE}{Dt} = \frac{k}{\rho^2} \frac{D\rho}{Dt} - \dot{Q}_{cool}$

- The total energy of a fluid is $E = \rho \left(\frac{1}{2} \mathbf{u}^2 + \Psi + \epsilon \right)$
- ↳ $\frac{DE}{Dt} = \frac{D\rho}{Dt} \frac{E}{\rho} + \rho \left(\mathbf{u} \cdot \nabla \mathbf{u} + \frac{D\Psi}{Dt} + \frac{k}{\rho^2} \frac{D\rho}{Dt} - \dot{Q}_{cool} \right)$

↳ write everything in Eulerian, we know equations

$$\frac{\partial E}{\partial t} + \nabla \cdot [(E+p) \mathbf{u}] = \rho \frac{\partial \Psi}{\partial t} - \rho \dot{Q}_{cool}$$

← Energy equation

↳ LHS describes change in total energy due to the divergence of the enthalpy flux ($E+p$).

↳ RHS contains sources of energy. If no external sources, $\frac{\partial E}{\partial t} = \text{div}(\text{enthalpy flux})$.

Heating and cooling ← Astrophysical examples

- Most cooling processes involve radiation.

1. Collisionally excited atomic line radiation: ← electron-ion collision

↳ collision excites atom, which later emits a photon with energy χ

↳ luminosity per unit volume: $L_c \propto n_e n_{ion} e^{-X/K_B T} \chi / f_T$

↳ divide by ρ to get \dot{Q} (which is per unit mass)

2. Recombination emission:

↳ free electron captured in high energy state

↳ cascades down, releasing photons in the process.

↳ as above, $\dot{Q} \propto \rho f(T)$

3. Free-free emission (bremsstrahlung): electrons accelerated by nuclei so radiate. $\dot{Q} = \Lambda_0 \rho \sqrt{T}$

- Heating can occur internally, e.g. shocks or viscous flows.

- Cosmic rays are an external source of heat, with $\dot{Q} \propto \text{ray flux}$

- Combine heating and cooling to get $\dot{Q}_{cool} = A \rho T^\alpha - H$ ← CR cooling

Energy transport

- Thermal conduction: transfer of thermal energy down temp. gradients
 - ↳ energy flux: $F_{\text{cond}} = -K \nabla T$
 - ↳ so the rate of change of energy density is $-\nabla \cdot F_{\text{cond}} = \chi \nabla^2 T$
 - ↳ important in white dwarfs, supernova shocks
- Radiation transport:
 - ↳ in optically thick systems, radiation transports energy rather than cooling
 - ↳ radiative diffusion: $F_{\text{rad}} \propto -\nabla E_{\text{rad}}$
- Convection → circulating fluid motions (important in stars)

diffusion process

Stellar fluids

- In static equilibrium, $\mathbf{g} = 0$, $\frac{\partial}{\partial t} = 0$
 - ↳ momentum equation $\Rightarrow \nabla p = -\rho \nabla \Psi \leftarrow \text{HSE}$
 - ↳ ie pressure forces must balance gravity
- For a self-gravitating system, HSE must be solved together with Poisson's equation.
- Example: isothermal atmosphere with constant external \mathbf{g}
 - ↳ $\mathbf{g} = -g \hat{z}$, $p = \frac{RT}{m} \rho = A \rho$
 - $\Rightarrow A \nabla p = -\rho g \hat{z} \Rightarrow \frac{A \rho}{\rho} = -g$
 - ↳ $\ln \rho = -\frac{g z}{A} + \text{const} \Rightarrow \rho = \rho_0 e^{-\frac{g}{A} z}$
 - ↳ good model for Earth atmosphere
- Example: isothermal self-gravitating slab
 - ↳ $A \nabla p = -\rho \nabla \Psi \Rightarrow A \frac{\partial \rho}{\partial z} = -\rho \frac{\partial \Psi}{\partial z} \Rightarrow \Psi = -A \ln(\rho/\rho_0) + \Psi_0$
 - $\Rightarrow \rho = \rho_0 e^{-(\Psi - \Psi_0)/A}$
 - ↳ to proceed, use Poisson: $\frac{d^2 \Psi}{dz^2} = 4\pi G \rho_0 e^{-(\Psi - \Psi_0)/A}$
 - ↳ can model galaxy
- Model a star as a spherically-symmetric self-gravitating system in HSE.
 - ↳ HSE in spherical polaris: $\frac{dp}{dr} = -\rho \frac{d\Psi}{dr}$
 - ↳ $\rho > 0$ so p is a monotonically decreasing function of Ψ
 - ↳ $\frac{dp}{dr} = \frac{dp}{d\Psi} \frac{d\Psi}{dr} = -\rho \frac{d\Psi}{dr} \Rightarrow p = -\frac{dp}{d\Psi} \leftarrow \text{also monotonic}$

- ↪ $\rho = \rho(\Psi)$, $p = p(\Psi)$ $\Rightarrow p = p(\rho) \Rightarrow$ stars are barotropic
- A useful family of barotropes is $p = K\rho^{1+1/n}$, where $n = n(p)$
↪ polytropes have $n = \text{const}$
- ↪ if the star is isentropic (e.g. fully convective), $1 + \frac{1}{n} = \gamma \equiv \frac{C_V}{C_P}$, so the polytrope equation is the adiabatic eq. of state.
- Solve HSE + Poisson to get structure of polytrope:
↪ $-\nabla\Psi = \frac{1}{\rho}\nabla(pK\rho^{1+1/n}) = (n+1)\nabla(K\rho^{1/n})$
 $\Rightarrow \rho = \left(\frac{\Psi_T - \Psi}{(n+1)K}\right)^n$, where $\Psi_T = \Psi$ when $\rho=0$ (tidal potential)
- ↪ the central density: $\rho_c = \left(\frac{\Psi_T - \Psi_c}{(n+1)K}\right)^n \Rightarrow \rho = \rho_c \left(\frac{\Psi_T - \Psi}{\Psi_T - \Psi_c}\right)^n$
- ↪ let $\theta \equiv \frac{\Psi_T - \Psi}{\Psi_T - \Psi_c}$ and use a dimensionless radial coordinate ξ
↪ gives the Lane-Emden equation: $\frac{1}{\xi^2} \frac{d}{d\xi} \left(\xi^2 \frac{d\theta}{d\xi} \right) = -\theta^n$
- ↪ at $\xi=0$ (centre), $\theta=1$ and $\frac{d\theta}{d\xi}=0$
- Lane-Emden can be solved for $n=0, n=1, n=\infty$.
- The limit $n \rightarrow \infty$ gives the isothermal sphere: $\frac{1}{\xi^2} \frac{d}{d\xi} \left(\xi^2 \frac{d\theta}{d\xi} \right) = e^{-\Psi}$
↪ $\rho \propto r^{-2}$ as $r \rightarrow \infty$, so mass does not converge.
- ↪ in practice, we truncate at a finite radius \Rightarrow Bonnor-Ebert spheres

Scaling relations \rightarrow C.F. Stellar Homology

- Consider families of stars with the same polytrope index. The shape of the density curve in each star will be the same
- Using the rescaled coordinates:

$$\rho = \left(\frac{\Psi_T - \Psi_c}{(n+1)K} \right)^n \Rightarrow \Psi_T - \Psi_c = K(n+1) \rho_c^{1/n}$$

$$\therefore \xi = r \sqrt{\frac{4\pi G \rho_c}{\Psi_T - \Psi_c}} = r \sqrt{\frac{4\pi G \rho_c^{1-1/n}}{K(n+1)}}, \quad \rho = \rho_c \theta^n$$

↪ at the surface, $\xi = \xi_{\max}$, $\theta(\xi_{\max}) = 0$

- The mass of a polytrope is:

$$M = \int_0^{r_{\max}} 4\pi r^2 \rho dr = 4\pi \rho_c \left[\frac{4\pi G \rho_c^{1-1/n}}{K(1+n)} \right]^{-3/2} \int_0^{\xi_{\max}} \theta^n \xi^2 d\xi$$

same for a given n

$$\Rightarrow M \propto \rho_c^{\frac{1}{n}(2 - \frac{1}{n})}$$

↪ radius relation comes from def. of ξ : $r_{\max} \propto \rho_c^{1/2(1 - 1/n)}$

↪ eliminate ρ_c to get the mass-radius relation: $M \propto R^{\frac{3-n}{1-n}}$

- For white dwarfs, $\gamma = 5/3 \Rightarrow n = 3/2$, so $R \propto M^{-1/3}$. More massive WDs are smaller.

- However, $R \propto M^{-1/3}$ is wrong for most stars, because it assumes K is constant: $\left. \begin{aligned} p &= K\rho^{1+1/n} \\ p &= \frac{R^*}{M} \rho T \end{aligned} \right\} \Rightarrow T_c = \frac{MK}{R^*} \rho_c^{1/n}$

↪ T_c is similar in all stars (nuclear reactions) $\Rightarrow K \propto \rho_c^{-1/n}$

$$\Rightarrow M \propto \rho_c^{-1/2}, R \propto \rho_c^{-1/2} \Rightarrow M \propto R$$
 as observed

- ↪ we can use $K = \text{const}$ on an individual star when mass is changing on a fast timescale (before thermal eq. is established).

Sound Waves

Equilibrium fluid

$$\begin{cases} p = \rho_0 \\ p = \rho_0 \end{cases} \begin{matrix} \text{uniform} \\ \text{constant} \end{matrix}$$

$$\underline{u} = 0$$

- Eulerian perturbation: $\delta Q = \Delta Q - (\underline{\nabla} \cdot \underline{D}) Q$ element of displacement
 ↳ same as Lagrangian for uniform medium

- Apply perturbation to continuity/momentum eq. (to 1st order)

$$\hookrightarrow \text{continuity} \Rightarrow \frac{\partial}{\partial t} \Delta \rho + \rho_0 \nabla \cdot (\Delta \underline{u}) = 0$$

$$\hookrightarrow \text{momentum} \Rightarrow \frac{\partial}{\partial t} (\Delta \underline{u}) = -\frac{1}{\rho_0} \nabla (\Delta p) \\ = -\left. \frac{\partial p}{\partial \rho} \right|_{\rho_0} \frac{\nabla (\Delta p)}{\rho_0} \quad \text{Barotropic Eq of state}$$

$$\hookrightarrow \text{combine linearised eqs: } \boxed{\frac{\partial^2 (\Delta p)}{\partial t^2} = \left. \frac{\partial p}{\partial \rho} \right|_{\rho_0} \cdot \nabla^2 (\Delta \underline{u})} \quad \text{wave eq.}$$

- Guess plane wave solution $\Delta p = \Delta p_0 e^{i(\underline{k} \cdot \underline{x} - \omega t)}$

$$\hookrightarrow \omega^2 = \left. \frac{\partial p}{\partial \rho} \right|_{\rho_0} k^2 \Rightarrow \text{dispersionless waves}$$

$$\hookrightarrow \text{speed of sound: } c_s = \sqrt{\left. \frac{\partial p}{\partial \rho} \right|_{\rho_0}}$$

- Can relate density ↔ velocity perturbations:

$$\hookrightarrow \text{sub. } \Delta \underline{u}, \Delta p \text{ into continuity eq} \Rightarrow -i\omega \Delta p + \rho_0 i k \Delta \underline{u} = 0 \\ \Rightarrow \Delta \underline{u} = \frac{i\omega}{k} \frac{\Delta p}{\rho_0} = c_s \frac{\Delta p}{\rho_0}$$

↪ velocity and density perturb. in phase

↪ $\Delta \underline{u} \ll c_s$, i.e. sound wave much faster than fluid.

Small perturbation (Lagrangian)

$$p = \rho_0 + \Delta p$$

$$p = \rho_0 + \Delta p$$

$$\underline{u} = \Delta \underline{u}$$

Sound waves in a stratified atmosphere

- E.g. propagation through an isothermal atmosphere inNSE:

$$\hookrightarrow u_0 = 0, \quad \rho_0(z) = \tilde{\rho} e^{-z/H}, \quad p_0(z) = \tilde{p} e^{-z/H}, \quad H = \frac{R^* T}{g M}$$

↪ sound waves in the z direction are different

- With $g = -g \hat{z}$, momentum eq. becomes $\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial z} - g$

↪ substitute Eulerian perturbations then convert to Lagrangian

$$\hookrightarrow \text{continuity} \Rightarrow \frac{\partial \Delta p}{\partial t} + \rho_0 \frac{\partial \Delta u_z}{\partial z} = 0 \quad (\text{same as before})$$

$$\hookrightarrow \text{momentum} \Rightarrow \frac{\partial \Delta u_z}{\partial t} = -\frac{c_s^2}{\rho_0} \frac{\partial \Delta p}{\partial z}, \quad c_s = \sqrt{\frac{\partial p}{\partial \rho}} |_{\rho_0}$$

$$\hookrightarrow \text{combine to give: } \underbrace{\frac{\partial^2 \Delta p}{\partial t^2} - c_s^2 \frac{\partial^2 \Delta p}{\partial z^2}}_{\text{wave eq.}} + \underbrace{\frac{c_s^2}{\rho_0} \frac{\partial \Delta p}{\partial z} \frac{\partial \Delta p}{\partial z}}_{=-\frac{\rho_0}{M}} = 0$$

- Guessing plane wave solution: $\omega^2 = c_s^2 (k^2 - \frac{i k}{M})$ ← dispersion relation

$$k = \frac{i}{2M} \pm \sqrt{\frac{\omega^2}{c_s^2} - \frac{1}{4M^2}}$$

Case 1: $\omega > c_s / 2M$

$$\hookrightarrow \Delta p \propto e^{-z/2M} e^{i(\text{Re}(k) - \omega t)}$$

↪ $\frac{\Delta p}{\rho_0} \propto e^{z/2M}$, so perturbation theory fails eventually

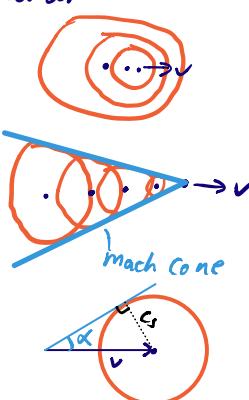
Case 2: $\omega < c_s / 2M$

$$\hookrightarrow \Delta p \propto e^{-kz} e^{i \omega t} \quad \text{← evanescent wave}$$



Shocks

- In an isotropic medium, sound wavefronts are circular
 - ↳ for a moving source, the centres of subsequent wavefronts are displaced
 - ↳ if $v > c_s$, a Mach cone forms:
 - ↳ the cone separates disturbed & undisturbed with a shockwave
 - ↳ the Mach number is $M \equiv \frac{v}{c_s}$; it determines the shape of the cone: $\sin \alpha = \frac{c_s}{v} = 1/M$



- For supersonic flows, the fluid may travel faster than signals can be transmitted → leads to discontinuities when the bulk 'realises' it has collided with something → **shocks**.
- Work in the reference frame of the shock.
- Integrate fluid equations over a small volume $d\sigma$ to get the **Rankine-Hugoniot relations**
- Continuity: $\frac{\partial}{\partial t} \left(\int_0^t p d\sigma \right) = \rho u |_{\text{post}} - \rho u |_{\text{pre}}$
 - ↳ in steady state, mass does not accumulate at $x=0 \Rightarrow \frac{\partial}{\partial t} [\cdot] = 0$
 - $\Rightarrow \rho_1 u_1 = \rho_2 u_2$ ← 1st R-H relation
- Momentum: $\rho_1 u_1^2 + p_1 = \rho_2 u_2^2 + p_2$ ← 2nd R-H
- Energy equation for an adiabatic shock:

$$\frac{\partial E}{\partial t} + \nabla \cdot [(E+p)u] = 0 \Rightarrow (E_1 + p_1)u_1 = (E_2 + p_2)u_2$$
 - ↳ $E = \rho \left(\frac{1}{2} u^2 + \epsilon + \Psi \right) \Rightarrow \frac{1}{2} u_1^2 + E_1 + \frac{p_1}{\rho_1} = \frac{1}{2} u_2^2 + E_2 + \frac{p_2}{\rho_2}$ ← 3rd R-H

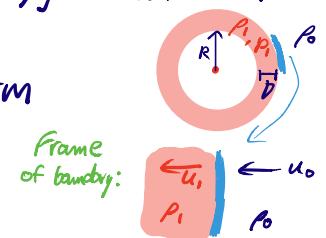
↳ can rewrite R-H III in terms of sound speed

$$\epsilon = \frac{1}{\gamma-1} \frac{p}{\rho}, \quad c_s^2 = \frac{\gamma p}{\rho} \Rightarrow \frac{1}{2} u_1^2 + \frac{c_{s,1}^2}{\gamma-1} = \frac{1}{2} u_2^2 + \frac{c_{s,2}^2}{\gamma-1}$$

- Jumps in ρ, p, T can all be written in terms of γ and M
 - ↳ for strong shocks ($M \gg 1$), $\frac{p_2}{\rho_1} \rightarrow \frac{\gamma+1}{\gamma-1} = \text{const}$
 - ↳ i.e. there is a maximum density jump for adiabatic shocks.
- 2nd law of thermo. dictates the direction of the jump
 - ↳ flow decelerates from super → sub-sonic, KE dissipated.
 - ↳ shocks are irreversible due to viscous processes

Supernova explosions

- Model supernova as point explosion of energy E within an ISM of density ρ_0 , and $p_0=0, T_0=0$.



- Creates an expanding layer of shocked ISM

$$\text{Strong shock} \Rightarrow \rho_1 = \rho_0 \frac{\gamma+1}{\gamma-1}$$

- ↳ shell consists of swept-up mass

$$\frac{4}{3} \pi R^3 \rho_0 = 4 \pi R^2 D \rho_1 \Rightarrow D = \frac{1}{3} \frac{\gamma-1}{\gamma+1} R \approx 0.08R$$

$$\text{relative velocity in shell: } U = u_0 - u_1 = u_0 - \frac{\rho_0}{\rho_1} u_0 = \frac{2u_0}{\gamma+1}$$

- The momentum of the shell is changing as it consumes ISM.

$$\text{rate of chg of momentum: } \frac{d}{dt} \left[\frac{4}{3} \pi R^3 \rho_0 \cdot \frac{2u_0}{\gamma+1} \right]$$

- ↳ caused by pressure inside the cavity. Assume $p_{\text{in}} = \alpha p_1$

$$\text{R-H II gives } p_1 = \frac{2}{\gamma+1} \rho_0 u_0^2 \leftarrow \text{Ram pressure into ISM}$$

$$\Rightarrow \frac{d}{dt} \left[\frac{4}{3} \pi R^3 p_0 \cdot \frac{2u_0}{\gamma+1} \right] = 4\pi R^2 p_m = 4\pi R^2 \alpha \cdot \frac{2}{\gamma+1} R u_0^2$$

$$\Rightarrow \frac{d}{dt} [R^3 u_0] = 3\alpha R^2 u_0^2 \Rightarrow \frac{d}{dt} [R^3 \dot{R}] = 3\alpha R^2 \dot{R}^2 \Leftarrow u_0 = \dot{R}$$

↳ seek power law solution $R \propto t^b \Rightarrow b = \frac{1}{4-3\alpha}$

$$\Rightarrow R \propto t^{1/(4-3\alpha)} \Rightarrow u_0 = \dot{R} \propto R^{3\alpha-3}$$

- Determine α by cons energy.

↳ ignore KE of cavity (little mass) and internal energy of shell (thin)

↳ KE of shell: $\frac{1}{2} \frac{4}{3} \pi R^3 p_0 u^2$

↳ internal energy of cavity: $\frac{4}{3} \pi R^3 \rho E = \frac{4}{3} \pi R^3 \alpha \frac{p_1}{\gamma-1}$

↳ sum to get $E \propto R^3 u_0^2 \propto t^{(6\alpha-3)/(4-3\alpha)}$

↳ E must be time dependent $\Rightarrow 6\alpha-3=0 \Rightarrow \alpha=1/2$

• Resulting dynamics: $R \propto t^{2/5}$, $u_0 \propto t^{-3/5}$, $p_1 \propto t^{-6/5}$

Similarity solutions to supernova explosions

• Previous derivation assumed: uniform shell, $p_{in} \ll p_1$, cold ISM.

• Similarity solutions use dimensional analysis.

• We only specify E and p_0

↳ unique combination to get a length scale: $\lambda = \left(\frac{Et^2}{p_0} \right)^{1/5}$

↳ define dimensionless distance param $\xi = \frac{r}{\lambda}$

↳ the evolution of any variable in space and time can be

separated into time behaviour \times scale: $x(t, r) = x_1(t) \tilde{x}(\xi)$

• Can rewrite derivatives:

$$\frac{\partial x}{\partial r} = x_1 \frac{dx}{d\xi} \frac{\partial \xi}{\partial r} \Big|_t, \quad \frac{\partial x}{\partial t} = \tilde{x}(\xi) \frac{dx_1}{dt} + x_1 \frac{dx}{d\xi} \frac{\partial \xi}{\partial t} \Big|_r$$

↳ use $\rho(r, t) = x_1(t) \tilde{\rho}(\xi)$ etc and sub. into fluid equations

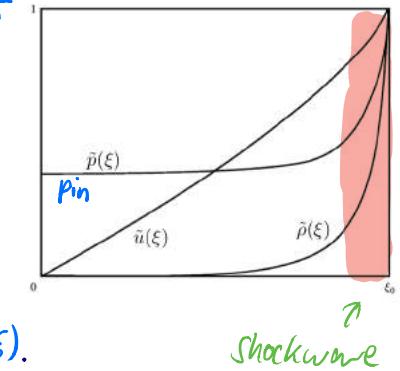
↳ fluid equations become ODEs

• Result is $R_{shock} \propto \left(\frac{E}{p_0} \right)^{1/5} t^{2/5}$

↳ most of the mass is indeed swept into a shell

↳ shell pressure is indeed a multiple of p_{in}

↳ can take weighted avg of different shell velocities using the form of $\tilde{u}(\xi)$.



• The SN explosion stalls when $p_1 \sim p_0$:

$$p_1 = \frac{2}{\gamma+1} p_0 u_0^2, \quad c_s^2 = \frac{\gamma p_0}{p_0} \Rightarrow \frac{2}{\gamma+1} p_0 u_0^2 \sim \frac{p_0 c_s^2}{t} \\ \Rightarrow u_0 \approx c_s$$

↳ shell no longer supersonic \rightarrow becomes a sound wave

↳ equivalently, when the energy of the explosion = internal energy swept up by the shockwave

Bernoulli's Equation

- Momentum equation: $\frac{\partial \underline{u}}{\partial t} + (\underline{u} \cdot \nabla) \underline{u} = -\frac{1}{\rho} \nabla p - \nabla \Psi$
 - ↳ define the vorticity $\underline{\omega} = \nabla \times \underline{u} \Rightarrow (\underline{u} \cdot \nabla) \underline{u} = \nabla \left(\frac{1}{2} u^2 \right) - \underline{u} \times \underline{\omega}$
 - ↳ for a barotropic fluid, $p = p(\rho)$

$$\frac{\partial}{\partial x} \int \frac{dp}{\rho} = \frac{\partial p}{\partial x} \frac{dp}{\partial \rho} = \frac{1}{\rho} \frac{\partial p}{\partial x} \Rightarrow -\frac{1}{\rho} \nabla p = \nabla \left(\int \frac{dp}{\rho} \right)$$

$$\Rightarrow \frac{\partial \underline{u}}{\partial t} + \nabla \left(\frac{1}{2} u^2 \right) - \underline{u} \times \underline{\omega} = -\nabla \left(\int \frac{dp}{\rho} + \Psi \right)$$
 - ↳ for a steady flow, we then have

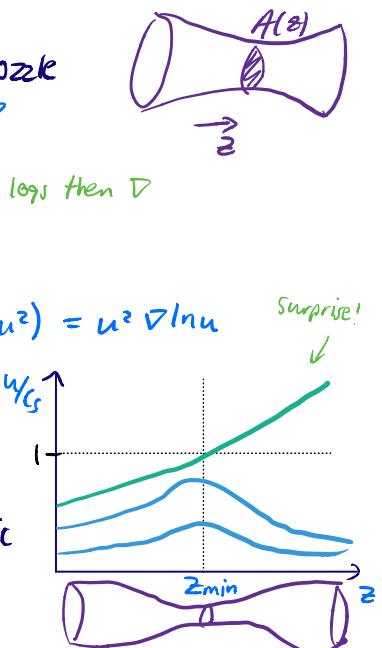
$$\underline{u} \cdot \nabla \left(\frac{1}{2} u^2 + \int \frac{dp}{\rho} + \Psi \right) = 0$$
 - Bernoulli's principle: $H = \frac{1}{2} u^2 + \int \frac{dp}{\rho} + \Psi$ is constant along a streamline (barotropic, steady flow).
 - For a general barotropic (unsteady) flow: \leftarrow without viscosity

$$\frac{\partial \underline{u}}{\partial t} = -\nabla H + \underline{u} \times \underline{\omega} \quad \xrightarrow{\nabla \times} \frac{\partial \underline{\omega}}{\partial t} = \nabla \times (\underline{u} \times \underline{\omega}) \quad \text{Helmholtz Equation}$$
 - ↳ the flux of vorticity through a surface S that moves with the fluid is constant: $\frac{D}{Dt} \int_S \underline{\omega} \cdot d\underline{S} = 0$
Kelvin's vorticity theorem
 - ↳ close analogy to magnetic field lines
 - If $\underline{\omega} = 0$, the fluid is irrotational
 - ↳ if irrotational, H is constant everywhere (not just on streamline)
 - ↳ if $\underline{\omega} = 0$ it remains so $\Rightarrow \underline{u} = -\nabla \Phi$
 - ↳ if flow is also incompressible, $\nabla \cdot \underline{u} = 0 \Rightarrow \nabla^2 \Phi = 0$

De Laval Nozzle

- Steady state barotropic flow through a nozzle
- Momentum: $\underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla p = -\frac{1}{\rho} c_s^2 \nabla p$
- Continuity: $\rho u A = \text{const} \equiv \dot{m}$ \downarrow take log, then ∇
 - ↳ $\frac{1}{\rho} \nabla p = -\nabla \ln \rho - \nabla \ln A$
 - ↳ $\underline{u} \cdot \nabla \underline{u} = [\nabla \ln u + \nabla \ln A] c_s^2$
- For irrotational flow, $\underline{u} \cdot \nabla \underline{u} = \nabla \left(\frac{1}{2} u^2 \right) = u^2 \nabla \ln u$ \downarrow surprise!

$$\Rightarrow (u^2 - c_s^2) \nabla \ln u = c_s^2 \nabla \ln A$$
 - An extremum in A implies either
 - ↳ extremum in u
 - ↳ $u = c_s$, i.e. subsonic \rightarrow supersonic
 - ↳ fluid continues to accelerate



- For Isothermal EoS, $p = \frac{R^* T}{\rho^n} \Rightarrow H = \frac{1}{2} u^2 + c_s^2 \ln \rho$
 - ↳ use Bernoulli equation ($H = \text{const}$) in terms of the min area A_m

$$u^2 = c_s^2 \left[1 + 2 \ln \left(\frac{u A}{c_s A_m} \right) \right], \text{ using } \rho u A = \text{const}$$
- For a Polytropic EoS, c_s varies with density
 - ↳ $p = k \rho^{1+\frac{1}{n}} \Rightarrow c_s^2 = \frac{n+1}{n} k \rho^{\frac{1}{n}}$
 - ↳ $H = \frac{1}{2} \left(\frac{\dot{m}}{A_p} \right)^2 + n c_s^2$

Spherical accretion

- Consider the spherically symmetric flow of matter onto a point mass. Assume steady state and barotropic EoS.
- Continuity: $4\pi r^2 \rho u = \dot{m}$, where u points inwards
 - in a steady flow, $\frac{d}{dr}(\ln \dot{m}) = 0 \Rightarrow \frac{d}{dr} \ln \rho = -\frac{d}{dr} \ln u = -\frac{2}{r}$
- Momentum: $u \frac{du}{dr} = -\frac{1}{\rho} \frac{dp}{dr} - \frac{GM}{r^2} \Rightarrow u^2 \frac{du}{dr} = -c_s^2 \frac{dp}{dr} - \frac{GM}{r^2}$
 - combine with continuity to get $(u^2 - c_s^2) \frac{d}{dr} \ln u = \frac{2c_s^2}{r} (1 - \frac{GM}{2c_s^2 r})$ (*)
- There is a critical radius $r = r_s = \frac{GM}{2c_s^2}$ ← sonic point
 - at $r = r_s$, either $u = c_s$ or u is extremised.
- For Isothermal EoS, $c_s = \sqrt{\frac{R_g T}{\rho}} = \text{const}$
 - $H = \frac{1}{2}u^2 + c_s^2 \ln \rho + \Psi = \text{const}$ (Bernoulli)
 - compare flow at general point to flow at sonic point
 $\Rightarrow u^2 = 2c_s^2 \left[\ln \left(\frac{r_s}{r} \right) - \frac{3}{2} \right] + \frac{2GM}{r}$
 - as $r \rightarrow 0$, $u^2 \rightarrow 2GM/r$ (free fall)
 - as $r \rightarrow \infty$ and $u \rightarrow 0$, $\rho \rightarrow \rho_\infty e^{-3/2}$ $\Rightarrow \rho_s = \rho_\infty e^{3/2}$
 - mass accretion rate: $\dot{m} = 4\pi r_s^2 \rho_s c_s = \frac{\pi G^2 M^2 \rho_\infty e^{3/2}}{c_s^3}$
- For Polytropic EoS we repeat the same procedure except substitute $u = \frac{\dot{m}}{4\pi r^2 \rho}$ earlier to simplify
 - $\Rightarrow \dot{m} = \frac{\pi (6M)^3 \rho_\infty}{C_{\infty}^3} \left(\frac{n}{n - \frac{3}{2}} \right)^{n-3/2}$ Bondi accretion
 - in $n \rightarrow \infty$ limit, becomes isothermal
 - for $n \rightarrow \frac{3}{2}$ ($\gamma = 5/3$), \dot{m} still finite even though c_s, ρ singular.

$$\cdot \dot{m} = AM^2 \Rightarrow M = \frac{M_0}{1 - A\dot{m}/M_0}$$

↳ $M \rightarrow \infty$ at finite time

↳ in reality, accretion will be limited by fuel supply or the Eddington limit ($\dot{m} \propto M$)

• Dependence on reservoir properties:

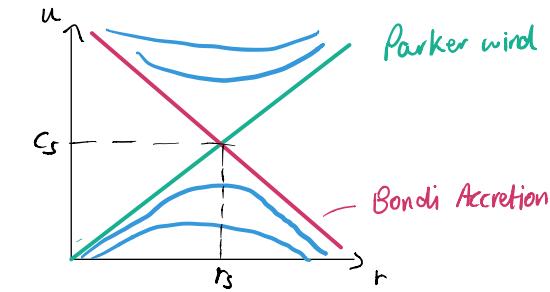
$$\hookrightarrow \dot{m} \propto \frac{\rho_\infty}{C_{\infty}^3} \propto \frac{\rho_\infty}{C_{\infty}^5} \rightarrow \text{higher accretion rates from colder material}$$

↳ for a moving accretion point with velocity v_∞ rel. to medium:

$$\dot{m} \sim \frac{(GM)^2 \rho_\infty}{(C_\infty^2 + v_\infty^2)^{3/2}} \quad \text{← Bondi-Hoyle-Lyttleton}$$

• Another solution to (*) is the Parker wind

↳ physically, the very hot central gas causes an outward wind



• These solutions are very sensitive to assumptions, e.g. nonzero angular momentum / B-fields break symmetry.

Fluid Instabilities

- A fluid is unstable if a perturbation to the steady state flow grows with time.

↳ linearly unstable if an arbitrarily small perturbation grows
 ↳ overstable if perturbations oscillate with growing amplitude

- Stable if perturbation decays/oscillates

Convective instability

- Perturb a fluid element upwards (originally in NSE)
- Pressure will quickly equilibrate (acoustic waves), but there may not be time for heat exchange
 ↳ density evolves adiabatically.

↳ if $\rho^* < \rho'$, the perturbed element is buoyant and continues to rise → unstable.

Adiabatic density change: $p = k p^\delta \Rightarrow \rho^* = \rho \left(\frac{p_1}{p}\right)^{1/\delta}$
 $p' = k p^{*\delta} \quad \text{with } \delta = \gamma - 1$

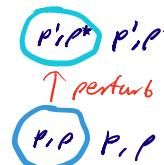
↳ $\rho^* = \rho + \frac{dp}{dz} \delta z \Rightarrow \rho^* = \rho \left(1 + \frac{1}{\rho} \frac{dp}{dz} \delta z\right)^{1/\delta} \approx \rho + \frac{\rho}{\rho^\delta} \frac{dp}{dz} \delta z$

↳ density of background atmosphere: $\rho' = \rho + \frac{dp}{dz} \delta z$

↳ unstable if $\rho^* < \rho' \Rightarrow \frac{d}{dz} (\ln \rho \rho^*) < 0 \Rightarrow \boxed{\frac{dk}{dz} < 0}$

↳ Schwarzschild criterion: convective unstable if entropy decreases upwards

↳ temperature: $K \propto \rho^{1-\delta} T^\gamma \Rightarrow \frac{dT}{dz} < (1-\delta) \frac{T}{\rho} \frac{dp}{dz}$



- A convectively stable fluid undergoes SHM:

$$\rho^* \frac{\partial^2}{\partial t^2} \delta z = -g(\rho^* - \rho')$$

$$\Rightarrow \frac{d^2}{dt^2} \delta z = -\frac{g}{T} \left[\frac{\partial T}{\partial z} - (1-\delta) \frac{T}{\rho} \frac{dp}{dz} \right] \delta z$$

↳ internal gravity waves oscillating at the Brunt-Väisälä frequency

Gravitational instability

- Equilibrium: $p = p_0 = \text{const}$, $\rho = \rho_0 = \text{const}$, $\Psi = \Psi_0 = \text{const}$, $y = 0$
 ↳ Jeans swindle: technically can't have $p = \text{const}$ AND $\Psi = \text{const}$
- Governing equations: continuity, momentum, Poisson, barotropic EoS
- Perturb, e.g. $p = p_0 + \Delta p$, $\Psi = \Psi_0 + \Delta \Psi$
- Linearise and assume plane waves: $\Rightarrow \omega^2 = c_s^2 \left(k^2 - \frac{4\pi G \rho_0}{c_s^2} \right)$
 ↳ define Jeans wavenumber $k_J^{-2} = \frac{4\pi G \rho_0}{c_s^2} \Rightarrow \boxed{\omega^2 = c_s^2 (k^2 - k_J^{-2})}$
- $k \gg k_J \Rightarrow$ normal soundwaves
- $k \gtrsim k_J \Rightarrow$ modified sound waves (slower group velocity)
- $k \ll k_J \Rightarrow \omega$ imaginary so perturbations grow exponentially
 ⇒ gravitational instability

Maximum stable wavelength is the Jeans length $\lambda_J = \sqrt{\frac{4\pi G \rho_0}{6}} \quad \text{with}$
 an associated Jeans mass $M_J \sim \rho_0 \lambda_J^3$

↳ systems undergo gravitational collapse when $M > M_J$

↳ for isothermal collapse, $M_J \propto G^3 \rho_0^{-1/2} \propto (T^3 / \rho_0)^{1/2}$ so $M_J \downarrow$
 as system collapses ⇒ gravitational fragmentation.

Interface instabilities

- Interfaces have discontinuous

changes in density / tangential velocity

↪ assume incompressible and irrotational

$$\nabla \cdot u = 0, \quad \nabla \times u = 0 \Rightarrow u = -\nabla \Phi$$

↪ Φ is a velocity potential satisfying $\nabla^2 \Phi = 0$

↪ split potentials into perturbed and unperturbed

$$\begin{aligned} \Phi_{\text{low}} &= -Ux + \phi \quad \checkmark \\ \Phi_{\text{up}} &= -U'x + \phi' \end{aligned} \Rightarrow \nabla^2 \phi = \nabla^2 \phi' = 0$$

↪ seek plane wave solutions

$$\xi = A \exp(i(kx - \omega t))$$

$$\phi = C \exp(i(kx - \omega t) + k_z z)$$

$$\phi' = C' \exp(i(kx - \omega t) + k'_z z)$$

↪ $\nabla^2 \phi = 0$ and $\phi \rightarrow 0$ as $z \rightarrow -\infty \Rightarrow k_z = k$

↪ similarly, $\nabla^2 \phi' = 0 \Rightarrow k'_z = -k$

$$\begin{aligned} \text{At the interface, } u_z &= \frac{D\xi}{Dt} \Rightarrow -\frac{\partial \Phi}{\partial z} = \frac{\partial \xi}{\partial t} + U \frac{\partial \xi}{\partial x} \\ &\quad -\frac{\partial \Phi'}{\partial z} = \frac{\partial \xi}{\partial t} + U' \frac{\partial \xi}{\partial x} \end{aligned}$$

↪ sub in plane wave solution $\therefore -kC = i(KU - \omega)A$

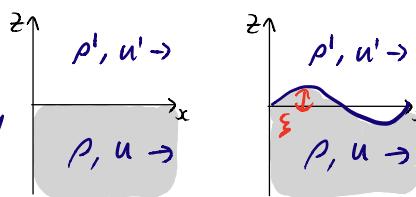
$$kC' = i(KU' - \omega)A$$

$$\begin{aligned} \text{• Momentum equation} \Rightarrow \nabla \left[-\frac{\partial \Phi}{\partial t} + \frac{1}{2} u^2 + \frac{p}{\rho} + g\xi \right] &= 0 \\ &\quad \checkmark \text{ must be FC(t)} \end{aligned}$$

↪ pressure is continuous at the interface

$$\therefore p \left(-\frac{\partial \Phi}{\partial t} + \frac{1}{2} u^2 + g\xi \right) = p' \left(-\frac{\partial \Phi'}{\partial t} + \frac{1}{2} u'^2 + g\xi \right) + pF(t) - p'F'(t)$$

$$\therefore pF(t) - p'F'(t) = K = \text{const} \quad \leftarrow \text{consider values at } \infty$$



- Combine equations to get the dispersion relation:

$$\rho(KU - \omega)^2 + \rho'(KU' - \omega)^2 = kg(\rho - \rho')$$

- For surface gravity waves, the denser fluid is below
↪ $\rho' < \rho$ and let $U = U' = 0$ (fluids at rest)

$$\text{↪ dispersion relation: } \omega^2 = k \frac{g(\rho - \rho')}{\rho + \rho'} \Rightarrow \frac{\omega}{k} = f(k)$$

$$\hookrightarrow \text{if } \rho' < \rho \text{ (e.g. ocean), } \frac{\omega}{k} = \pm \sqrt{g/k}$$

- If the denser fluid is on top (static):

$$\omega^2 = k \frac{g(\rho - \rho')}{\rho + \rho'} \Rightarrow \frac{\omega}{k} = \pm i \sqrt{\frac{g(\rho - \rho')}{\rho + \rho'}}$$

↪ for $K \in \mathbb{R}$, ω is imaginary so there are exponentially growing/decaying solutions

↪ Rayleigh-Taylor instability

- If the denser fluid is below but fluids are moving:

↪ solve dispersion relation for $\frac{\omega}{k}$ ← quadratic

$$\Rightarrow \frac{\omega}{k} = \frac{\rho U + \rho' U'}{\rho + \rho'} \pm \sqrt{\frac{g(\rho - \rho')}{k(\rho + \rho')}} - \frac{\rho \rho' (U - U')^2}{(\rho + \rho')^2}$$

↪ stability depends on sign inside square root

↪ if $g > 0$, always unstable → Kelvin-Helmholtz instability

↪ for $g < 0$, longer wavelengths are stabilised.

Thermal instability

- Consider perturbations of the energy equation

↳ first rewrite in terms of K

$$\begin{aligned} p = k\rho^\gamma &= \frac{R_g}{m} \rho T \\ \Rightarrow dK &= \rho^{1-\gamma}(1-\alpha) \left[\underbrace{\frac{p}{\rho^2} dp + \frac{R_g}{m(1-\alpha)} dT}_{= -dQ} \right] \\ \Rightarrow \frac{DK}{Dt} &= -(\gamma-1)\rho^{1-\gamma} \dot{Q} \end{aligned}$$

↳ gives the entropy form of the energy equation

$$\frac{1}{K} \frac{DK}{Dt} = -(\gamma-1) \frac{\rho \dot{Q}}{P}$$

- Assume the fluid is a static ideal gas (no gravity) in thermal equilibrium: $\underline{u}_0 = 0$, $\dot{Q}_0 = 0$, $DK_0 = 0$

- Perturb and linearise:

$$\frac{\partial \Delta p}{\partial t} + p_0 \nabla \cdot (\Delta \underline{u}) = 0$$

$$p_0 \frac{\partial \Delta u}{\partial t} = -\nabla(\Delta p)$$

$$\frac{\partial \Delta K}{\partial t} = -\frac{\gamma-1}{p_0 \gamma-1} \Delta \dot{Q} \quad \text{sub } \Delta \dot{Q} = \frac{\partial \dot{Q}}{\partial p} |_p \Delta p + \frac{\partial \dot{Q}}{\partial \rho} |_p \Delta \rho$$

↳ seek plane wave solutions e.g. $\Delta p = p_1 e^{ik \cdot \underline{x} + qt}$, such that $R(q) > 0 \Rightarrow$ instability

↳ result is a cubic dispersion relation $E(q) = 0$

↳ unstable if the real root of $E(q)$ is > 0

↳ Field criterion: unstable if

$$\frac{\partial \dot{Q}}{\partial T} |_p < 0$$

* ↳ ie unstable if cooling ↓ as temp ↑

↳ e.g. power-law cooling of the form $\dot{Q} \propto T^\alpha$ is unstable for $\alpha < 1$ (Bremsstrahlung has $\alpha = 0.5$)

- If a system is field-unstable, all modes are unstable
- Even for field-stable systems, there may be unstable modes

↳ for large wavelengths (small K), $E(q) \approx q^2(q + A^* p_0^\alpha)$

↳ isochoric thermal instability: $\frac{\partial \dot{Q}}{\partial T} |_p < 0$ ↳ density, not pressure

↳ for short wavelengths, sound waves bring pressure equilibrium so behaviour at const p matters

↳ for long wavelengths, there is insufficient time for pressure to equalise → const p matters

- If gravity is included, buoyancy can stabilise thermal instabilities.

Viscous Flows

- We have assumed that changes in momentum are entirely due to pressure and gravity (valid for $\lambda \rightarrow 0$ limit) \leftarrow mean free path
- For finite λ , momentum can diffuse through the fluid
- Consider a linear shear flow
 - in addition to bulk flow, there are random thermal velocities
 - flux of i momentum in j direction
$$\langle p v_i v_j \rangle = \alpha \rho u_i \sqrt{\frac{k_B T}{m}}$$

$\underbrace{u_i}_{\text{bulk momentum}} + \underbrace{u_j}_{\text{thermal velocity in } j \text{ direction}}$
- α is a constant of order 1. For hard spheres, $\alpha = \frac{5\sqrt{\pi}}{64}$
- the net momentum flux through a plane of thickness δL is: $-\rho(\partial_j u_i)\delta L \alpha \sqrt{\frac{kT}{m}}$
- $\delta L \approx \lambda = \frac{1}{n\sigma} = \frac{1}{n\rho} = \frac{m}{\rho r} = \frac{m}{\rho \pi a^2}$
- momentum flux = $-(\partial_j u_i) \frac{m}{\sigma} \alpha \sqrt{\frac{kT}{m}}$
- This momentum flux modifies the momentum equation:

$$\frac{\partial}{\partial t}(\rho u_i) = -\partial_j(\rho u_i u_j + p \delta_{ij}) + \partial_j \left[\frac{\alpha}{\sigma} \sqrt{m k T} \partial_j u_i \right] + \rho g_i$$
- $\eta \equiv \frac{\alpha}{\sigma} \sqrt{m k T}$ is the shear viscosity
- η is independent of density \rightarrow more particles, but shorter λ
- $\eta \propto T$. Isothermal systems have $\eta = \text{const}$
- for Coulomb interactions, $\lambda \propto T^2 \Rightarrow \eta \propto T^{5/2}$

Navier-Stokes

- We can generalise to allow for viscous stresses in different directions
- Define the viscous stress tensor σ_{ij}' . It must be:
 - Invariant to Galilean transformations
 - Linear in velocity gradients
 - Isootropic
- the most general tensor that satisfies this is

$$\sigma_{ij}' = \eta (\partial_j u_i + \partial_i u_j - \frac{2}{3} \delta_{ij} \partial_k u_k) + \begin{matrix} \text{shear flow} \\ \text{viscosity} \end{matrix} \rightarrow \begin{matrix} 3 \delta_{ij} \partial_k u_k \\ \text{bulk compression} \end{matrix}$$
- momentum equation: $\frac{\partial}{\partial t}(\rho u_i) = -\partial_j(\rho u_i u_j + p \delta_{ij} + \sigma_{ij}') + \rho g_i$
- combining this with continuity gives the Navier-Stokes equation
- For an isothermal unshocked fluid, $\eta = \text{const}$ and 3×0
- $\Rightarrow \frac{\partial u}{\partial t} + u \cdot \nabla u = -\frac{1}{\rho} \nabla p - \nabla \Psi + \frac{\eta}{\rho} [\nabla^2 u + \frac{1}{3} \nabla(\nabla \cdot u)]$
- $\frac{\eta}{\rho} \equiv \nu$ is the coefficient of kinematic viscosity
- The importance of viscosity is characterised by the Reynolds number

$$Re = \frac{|u \cdot \nabla u|}{|\nu \nabla^2 u|} \sim \frac{UL}{\nu}$$

U is a velocity scale,
 L is a lengthscale
- viscosity important for small Re
- Viscosity allows for momentum transmission by shearing:
 - stabilises fluid instabilities (i.e. damping)
 - irreversibly dissipates KE or heat

- Vorticity: take the curl of the Navier-Stokes equation

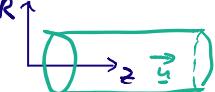
$$\Rightarrow \frac{\partial \underline{w}}{\partial t} = \nabla \times (\underline{u} \times \underline{w}) + \frac{\eta}{\rho} \nabla^2 \underline{w}$$

- ↳ viscosity allows for vorticity to diffuse through the fluid
- ↳ relative importance of advection/diffusion is given by Re
- ↳ vorticity can be introduced into an irrotational flow due to boundary interactions → then diffuses into the bulk

I. 4

Flow in a pipe

- Consider a steady-state, laminar, incompressible flow through a circular pipe (neglecting gravity)



- Neglect edge effects → $u = u(R)$

- Navier-Stokes: $\frac{\partial u}{\partial t} + \underline{u} \cdot \nabla u = -\frac{1}{\rho} \nabla p - \nabla \Phi + \nu (\nabla^2 u + \frac{1}{R} \nabla (\nabla \cdot u))$

$$\Rightarrow \nu \nabla^2 u = \frac{1}{\rho} \nabla p$$

$$\hookrightarrow \text{laminar} \Rightarrow u_R = u_\phi = 0 \Rightarrow \frac{\partial p}{\partial R} = \frac{\partial p}{\partial \phi} = 0$$

$$\hookrightarrow z\text{-component: } \nu \underbrace{\frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial u_z}{\partial R} \right)}_{R \text{ only}} = \underbrace{\frac{1}{\rho} \frac{\partial p}{\partial z}}_{z \text{ only}} = \text{const} = -\frac{1}{\rho} \frac{\Delta p}{L}$$

$$\cdot \text{Integrate equation to get } u = -\frac{\Delta p}{4\rho v L} R^2 + a \ln R + b$$

$$\hookrightarrow \text{finite at } R=0 \Rightarrow a=0 \Rightarrow u = \frac{\Delta p}{4\rho v L} (R^2 - R_0^2)$$

$$\hookrightarrow u(R_0) = 0 \text{ (no slip)}$$

$$\cdot \text{Mass flux: } Q = \int_0^{R_0} 2\pi R \rho u dR$$

- Beyond a certain Re (flow rate), there will be turbulence.

Accretion

- If infalling gas has net angular momentum (almost always true), Bondi accretion is not applicable. Gas tends to form **accretion disks** \rightarrow near-Keplerian orbits
- Accretion requires fluid elements to lose angular momentum
- Model a thin accretion disk in cylindrical coordinates:
 - \hookrightarrow axisymmetry $\Rightarrow \frac{\partial u_\phi}{\partial t} = 0$
 - \hookrightarrow HSE vertically $\Rightarrow u_z = 0$
- Angular velocity: $\Omega = \sqrt{\frac{GM}{R^3}}$ \rightarrow varies with R so there will be shear between layers.
- Continuity: $\frac{\partial \rho}{\partial t} + \frac{1}{R} \frac{\partial}{\partial R} (R \rho u_R) + \frac{1}{R} \frac{\partial}{\partial \phi} (R \rho u_\phi) + \frac{\partial}{\partial z} (\rho u_z) = 0$
 - $\Rightarrow \frac{\partial \rho}{\partial t} + \frac{1}{R} \frac{\partial}{\partial R} (R \rho u_R) = 0$ axisymmetry HSE
 - \hookrightarrow For accretion disks, the surface density is more relevant
 $\Sigma \equiv \int_{-\infty}^{\infty} \rho dz \Rightarrow \frac{\partial \Sigma}{\partial t} + \frac{1}{R} \frac{\partial}{\partial R} (R \Sigma u_R) = 0$
 - \hookrightarrow can also derive directly by considering flow of mass in/out of annulus
- Likewise for the momentum equation, we can use Navier-Stokes or consider annuli:
 - $\frac{\partial}{\partial t} (\text{angular momentum}) = \text{ang mtn in} - \text{ang mtn out} + \text{net torque}$
 - $\Rightarrow \frac{\partial}{\partial t} (2\pi R \Omega \Sigma R^2) = f(R) - f(R+\Delta R) + 6(R+\Delta R) - 6(R)$
 - $\hookrightarrow f(R) \equiv 2\pi R \Sigma u_R \Omega R^2$ describes the advection of ang mtn

\hookrightarrow viscous torque: $G(R) = 2\pi R v \Sigma R \frac{\partial \Omega}{\partial R} R = 2\pi R^3 v \Sigma \frac{d\Omega}{dR}$

$$\Rightarrow \frac{\partial}{\partial t} (R \Sigma u_\phi) = -\frac{1}{R} \frac{\partial}{\partial R} (\Sigma R^3 u_\phi u_R) + \frac{1}{R} \frac{\partial}{\partial R} (v \Sigma R^3 \frac{d\Omega}{dR})$$

\cdot For an axisymmetric orbit, $\frac{\partial u_\phi}{\partial t} = 0$

$$\Rightarrow u_R = \frac{\frac{2}{3} R (\nu \Sigma R^3 \frac{d\Omega}{dR})}{R \Sigma \frac{2}{3} R (R^2 - R)}$$

\hookrightarrow sub u_R into continuity eq and use Newtonian point source with $\Omega = \sqrt{GM/R^3} \Rightarrow \frac{\partial \Sigma}{\partial t} = \frac{3}{R} \frac{\partial}{\partial R} \left[R^{1/2} \frac{2}{3} R (\nu \Sigma R^{1/2}) \right]$

\hookrightarrow surface density obeys a diffusion-like equation

\hookrightarrow if $v = v(R)$ only, it becomes a linear diffusion equation
 \hookrightarrow hence narrow rings start to spread out, becoming disks.

Estimate accretion time:

$$\frac{\Sigma}{t_{\text{acc}}} \sim \frac{1}{R} \cdot \frac{1}{R} \left[R^{1/2} \frac{1}{R} \nu \Sigma R^{1/2} \right] \sim \frac{\nu \Sigma}{R^2}$$

$$\Rightarrow t_{\text{acc}} \sim \frac{R^2}{\nu} = \frac{R}{u_\phi} \frac{R u_\phi}{\nu} = \Omega^{-1} \cdot R e$$

\hookrightarrow kinetic theory gives very small $\nu \rightarrow$ accretion timescale greater than the age of the universe

\hookrightarrow i.e. the 'viscosity' driving accretion cannot be microphysical viscosity \rightarrow believed to be due to turbulence.

$\hookrightarrow [\nu] = [L]^2 [T]^{-1} = [u][L]$. Using the characteristic quantities in a disk, $\nu = \alpha c_s H$, where $\alpha < 1 = \text{const}$

Steady-state accretion disks

- Energy dissipation per unit area of disk

$$\begin{aligned} \text{flux} \rightarrow F_{\text{diss}} &= - \int \sigma \eta \partial_j u_i \partial_i u_j \frac{dv}{2\pi R dr d\phi} \\ &= \frac{1}{2} \int \eta (\partial_j u_i + \partial_i u_j)^2 dz \\ &= \int \eta R^2 \left(\frac{du}{dr} \right)^2 dz = \nu \Sigma R^2 \left(\frac{du}{dr} \right)^2 \end{aligned}$$

Continuity: $\frac{\partial \Sigma}{\partial t} + \frac{1}{R} \frac{\partial}{\partial R} (R \Sigma u_r) = 0$

↳ steady state $\Rightarrow R \Sigma u_r = C_1 = - \frac{\dot{m}}{2\pi} \leftarrow$ in positive for in flux

$$\Rightarrow u_r = - \frac{\dot{m}}{2\pi R \Sigma}$$

Axially-symmetric orbit: $u_r = \frac{\frac{2}{3}\eta \left(\nu \Sigma R^3 \frac{du}{dr} \right)}{R \Sigma \frac{2}{3} \frac{\partial}{\partial R} (R^2 \Omega)}$

↳ steady state accretion around a point mass ($\Omega^2 = \frac{GM}{R^3}$)

$$\Rightarrow - \frac{\dot{m}}{2\pi R \Sigma} = - \frac{3}{\Sigma R^{1/2}} \frac{\partial}{\partial R} (\nu \Sigma R^{1/2})$$

↳ integrate with inner torque boundary condition \rightarrow no viscous torque at some inner radius i.e. $\nu \Sigma = 0$ at $R = R_*$

$$\Rightarrow \nu \Sigma = \frac{\dot{m}}{3\pi} \left(1 - \sqrt{\frac{R_*}{R}} \right)$$

- Sub into dissipation formula: $F_{\text{diss}} = \frac{36M\dot{m}}{4\pi R^3} \left(1 - \sqrt{\frac{R_*}{R}} \right)$

↳ total energy emitted: $L = \int_{R_*}^{\infty} F_{\text{diss}} \cdot 2\pi R dR = \frac{GM\dot{m}}{2R_*}$

↳ i.e. disk radiates half of the accreting matter's binding energy

↳ other half is KE of infalling matter

- Far from the inner disk, $F_{\text{diss}} \approx \frac{36M\dot{m}}{4\pi R^3}$

↳ the local rate of loss of binding energy is:

$$F_{\text{diss,est}} = \underbrace{\frac{1}{2\pi R dr}}_{\text{area of annulus}} \cdot \underbrace{\frac{2}{\partial R} \left(\frac{6M\dot{m}}{R} \right)}_{\Delta GPE} \cdot \underbrace{\frac{1}{2}}_{1/2 \text{ radiated}}$$

↳ i.e. $2/3$ of dissipated energy is not from ΔGPE

↳ source is viscous transport of energy from inner \rightarrow outer disk

- Can estimate disk temp assuming BB radiation:

$$\stackrel{\text{top}}{\int} \stackrel{\text{bottom}}{\int} 2 \cdot \sigma T_{\text{eff}}^4 = \frac{36M\dot{m}}{4\pi R^3} \left(1 - \sqrt{\frac{R_*}{R}} \right)$$

↳ at large distances, $T_{\text{eff}} \propto R^{-3/4}$

- All observables are independent of viscosity \rightarrow need to observe non-steady disks to learn about ν .

Plasmas

Magneto hydrodynamics (MHD)

- Model fully ionised hydrogen as two cohabiting fluids:
 - Proton fluid $m^+, n^+, \underline{u}^+$
 - Electron fluid $m^-, n^-, \underline{u}^-$
- Aggregate properties of fluid:
 - density $\rho = m^+n^+ + m^-n^-$
 - com velocity is the density-weighted avg: $\underline{u} = \frac{m^+n^+\underline{u}^+ + m^-n^-\underline{u}^-}{\rho}$
 - charge density $q = n^+e^+ + n^-e^-$
 - current density $\underline{j} = e^+\underline{n}^+\underline{u}^+ + e^-\underline{n}^-\underline{u}^-$
- Conserve particle number: $\frac{\partial n^\pm}{\partial t} + \nabla \cdot (n^\pm \underline{u}^\pm) = 0$
 - multiply eqns by m^\pm to get $\frac{\partial p}{\partial t} + \nabla \cdot (\rho \underline{u}) = 0$ ← continuity
 - multiply by e^\pm to get charge conservation: $\frac{\partial q}{\partial t} + \nabla \cdot \underline{j} = 0$
- Momentum equation:
 - Lorentz force on each particle: $F = q(\underline{E} + \underline{u} \times \underline{B})$
 - for each fluid: fraction of pressure gradient attributed to each fluid

$$m^\pm n^\pm \left(\frac{\partial \underline{u}^\pm}{\partial t} + \underline{u}^\pm \cdot \nabla \underline{u}^\pm \right) = e^\pm n^\pm (\underline{E} + \underline{u}^\pm \times \underline{B}) - f^\pm \nabla p$$
 - sum: $\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla p + q\underline{E} + \underline{j} \times \underline{B}$ new terms
- Ohm's law connects \underline{j} with the electromagnetic fields:

$$\underline{j} = \sigma(\underline{E} + \underline{u} \times \underline{B})$$
 where σ is the conductivity.

Equations of MHD:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) = 0$$

Mass continuity

$$\frac{\partial q}{\partial t} + \nabla \cdot \underline{j} = 0$$

Charge continuity

$$\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla p + q\underline{E} + \underline{j} \times \underline{B}$$

Momentum

$$\underline{j} = \sigma(\underline{E} + \underline{u} \times \underline{B})$$

Ohm's law

+ Maxwell's equations

Ideal MHD

- Consider a non-relativistic and highly conducting plasma
- Approx fields as varying over lengthscale l and timescale τ .
- $\nabla \times \underline{E} = -\frac{\partial \underline{B}}{\partial t} \Rightarrow \frac{\underline{E}}{l} \sim \frac{\underline{B}}{\tau} \Rightarrow \frac{\underline{E}}{\underline{B}} \sim u$
- $\left| \frac{\frac{1}{c^2} \frac{\partial \underline{E}}{\partial t}}{|\nabla \times \underline{B}|} \right| \sim \frac{1}{c^2} \left(\frac{l}{\tau} \right)^2 \sim \frac{u^2}{c^2} \ll 1$ (non-relativistic)
 - can ignore displacement current $\Rightarrow \nabla \times \underline{B} = \mu_0 \underline{j}$
- $\left| \frac{q\underline{E}}{|\nabla \times \underline{B}|} \right| \sim \frac{q\underline{E}}{jB} \sim \frac{\epsilon_0 (l \cdot \underline{E}) E}{\mu_0 |\nabla \times \underline{B}| B} \sim \frac{\epsilon_0 E / l E}{\frac{1}{\mu_0} B / l B} \sim \frac{u^2}{c^2} \ll 1$
 - $q\underline{E}$ is negligible in the momentum eq.
 - i.e. charge neutrality is preserved
- Combine Ampere/Ohm: $\nabla \times \underline{B} = \mu_0 \underline{j} = \mu_0 \sigma (\underline{E} + \underline{u} \times \underline{B})$
 - take curl $\Rightarrow \frac{\partial \underline{B}}{\partial t} = \nabla \times (\underline{u} \times \underline{B}) + \frac{1}{\mu_0 \sigma} \nabla^2 \underline{B}$ ← same form as vorticity
 - good conductor $\Rightarrow \sigma$ large $\Rightarrow \frac{\partial \underline{B}}{\partial t} = \nabla \times (\underline{u} \times \underline{B})$

↪ magnetic flux is 'frozen' into the plasma

• For a good conductor, $E + \underline{u} \times \underline{B} = \frac{1}{\sigma} \underline{j} \rightarrow 0 \Rightarrow E \perp \underline{B}$

• Ideal momentum equation: $\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla p + \frac{1}{\mu_0} (\nabla \times \underline{B}) \times \underline{B}$

①
↪ electromagnetic force per unit volume is $\underline{f}_{mag} = \frac{1}{\mu_0} (\nabla \times \underline{B}) \times \underline{B}$

↪ using vector identity: $\underline{f}_{mag} = \frac{1}{\mu_0} \left[-\nabla \left(\frac{B^2}{2} \right) + (\underline{B} \cdot \nabla) \underline{B} \right]$
magnetic pressure magnetic tension

↪ can absorb magnetic pressure into ∇p to get:

$$\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = \frac{1}{\mu_0} (\underline{B} \cdot \nabla) \underline{B} - \nabla p_{tot} \quad \leftarrow p_{tot} = p + \frac{B^2}{2\mu_0}$$

MHD waves

• New terms in the momentum eq → different waves.

• Perturb density, pressure, fluid velocity, \underline{B} -field ← barotropic EoS

• Seek plane wave solutions, e.g. $\Delta \underline{B} = \underline{B}_0 e^{i(\underline{k} \cdot \underline{r} - \omega t)}$

$$\hookrightarrow \frac{\partial}{\partial t} \rightarrow -i\omega, \quad \nabla \rightarrow i\underline{k}$$

$$\hookrightarrow \text{continuity} \rightarrow \omega \Delta p = p_0 \underline{k} \cdot \Delta \underline{u}$$

$$\hookrightarrow \text{momentum} \rightarrow \omega p_0 \Delta \underline{u} = \frac{1}{\mu_0} [(\underline{B}_0 \cdot \Delta \underline{B}) \underline{k} - (\underline{B}_0 \cdot \underline{k}) \Delta \underline{B}] + c_s^2 \Delta \underline{u} / k$$

$$\hookrightarrow \text{flux-freezing} \rightarrow \omega \Delta \underline{B} = \underline{B}_0 (\underline{k} \cdot \Delta \underline{u}) - (\underline{B}_0 \cdot \underline{k}) \Delta \underline{u}$$

① Perturbation perpendicular to field, $\underline{k} \perp \underline{B}_0$

↪ simplify eqns then eliminate $\Delta p, \Delta \underline{B}$

↪ $\Delta \underline{u} \propto \underline{k}$ so this is a longitudinal mode

$$\hookrightarrow \text{result is } \omega^2 = (c_s^2 + \frac{B^2}{\mu_0 p_0}) k^2$$

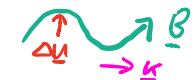
↪ define the Alfvén speed $V_A = \sqrt{\frac{B^2}{\rho \mu_0}} \Rightarrow \omega^2 = (c_s^2 + V_A^2) k^2$

↪ it is a fast magnetosonic wave, travelling faster than the sound speed due to magnetic pressure.

② Perturbation parallel to field, $\underline{k} \parallel \underline{B}_0$

$$\hookrightarrow \omega^2 = \frac{B_0^2}{\mu_0 p_0} k^2 \Rightarrow \omega^2 = V_A^2 k^2 \quad \leftarrow \text{Alfvén waves}$$

↪ transverse incompressible waves due to magnetic tension



↪ another permitted solution is the standard sound wave

- For a general perturbation ($\underline{B}, \underline{k}$ at angle θ) there are 3 modes: Alfvén wave, fast magnetosonic, slow magnetosonic

Magneto-rotational instability

- Consider the local frame of a patch in an accretion disk



- Momentum eq:

$$\frac{D \underline{u}}{Dt} = \underbrace{-\frac{1}{\rho} \nabla p}_{\text{pressure gradient}} + \underbrace{\frac{1}{\mu_0 p} (\nabla \times \underline{B}) \times \underline{B}}_{\text{magnetic force}} + \underbrace{2 \underline{u} \times \underline{\Omega}}_{\text{Coriolis}} + \underbrace{\underline{\Omega} \times (\underline{\Omega} \times \underline{r})}_{\text{Centrifugal}} - \underbrace{R \Omega_k(R)^2 \underline{R}}_{\text{gravity}}$$

- Assume:

↪ uniform field $\underline{B}_0 = B_0 \hat{z}$ ← aligned with $\underline{\Omega}$

↪ cold gas → ignore pressure

↪ only consider $\underline{k} \parallel \underline{B}_0$ perturbations

Perturbed eqn: $\frac{D\Delta u}{Dt} - 2\Delta u \times \underline{\Omega} = \frac{1}{\mu_0 \rho} (\underline{B}_0 \cdot \nabla) \Delta \Phi - \alpha R \underbrace{\frac{d\Omega^2}{dR}}_{mismatch\ of\ centri/gravity} \hat{R}$

↳ seek plane wave solutions and use MHD eqs to get expression for ΔB

$$\text{result: } \omega^4 - \omega^2 \left[4\Omega^2 - \frac{d\Omega^2}{d\ln R} + 2(KV_A)^2 \right] + (KV_A)^2 \left[(KV_A)^2 + \frac{d\Omega^2}{d\ln R} \right] = 0$$

Ignoring magnetic physics: $\omega^2 = 4\Omega^2 + \frac{d\Omega^2}{d\ln R} = \frac{1}{R^3} \frac{d}{dR} (R^4 \Omega^2) \equiv \lambda_R^2$

↳ if $\lambda_R^2 > 0$ we get radial epicyclic approximations

↳ if $\lambda_R^2 < 0$ (i.e. h decreases with radius), the flow is unstable.

Including magnetism, unstable if $\omega^2 < 0 \Rightarrow (KV_A)^2 + \frac{d\Omega^2}{d\ln R} < 0$

↳ if the field is weak, KV_A is negligible

⇒ unstable if $\frac{d\Omega^2}{dR} < 0$

↳ hence even Keplerian flow is unstable → magnetorotational instability.

↳ MRI is stabilized if $K > K_{\text{crit}}$:

$$(K_{\text{crit}} V_A)^2 = -\frac{d\Omega^2}{d\ln R} = 3\Omega^2 \text{ in Keplerian case}$$