

60 Years of Portfolio Optimisation (2014)

- Markowitz (1952) was the first to quantify the risk/return tradeoff as an optimisation problem
- Classical framework must be modified for practical use

Standard MVO

- Universe of assets S_1, S_2, \dots, S_n with future returns $r = [r_1, \dots, r_n]^T$
- $\Omega \subset \mathbb{R}^n$ is the set of all possible portfolios
- A portfolio is repr. by weights $w = [w_1, \dots, w_n]^T, w \in \Omega$
- Risk is encapsulated in the cov matrix
 - ↳ $\sigma_{ij} = \sigma_{ji} = \rho_{ij} \sigma_i \sigma_j$ for $i \neq j$
 - ↳ all cov matrices are positive semidefinite
 - ↳ if assets are linearly independent, Σ will be positive definite so Σ is invertible
 - ↳ portfolio volatility is given by $\sigma(w) = \sqrt{w^T \Sigma w}$
- r may be estimated by its mean μ , where $\mu_i = E(r_i)$
- The MVO problem can then be formulated:
 - $\max_{w \in \Omega} \mu^T w - \lambda \cdot w^T \Sigma w$
 - $\max_{w \in \Omega} \mu^T w \quad \text{s.t.} \quad w^T \Sigma w \leq \sigma_{\max}^2$
 - $\max_{w \in \Omega} w^T \Sigma w \quad \text{s.t.} \quad \mu^T w \geq R_{\min}$
- If the constraint set only includes linear equalities/inequalities, MVO is a quadratic program (QP)

$$\Sigma = \begin{bmatrix} \sigma_{11} & \cdots & \sigma_{1n} \\ \vdots & \ddots & \vdots \\ \sigma_{n1} & \cdots & \sigma_{nn} \end{bmatrix}$$

variances

$$\sigma(w) = \sqrt{w^T \Sigma w}$$

Enhancing MVO

Transaction costs

- It is important to consider tx costs in allocation otherwise optimised portfolios may lose too much to slippage/commission.
- Slippage is the difference between the anticipated price at t_0 and the VWAP over $[t_0, t_0 + T]$, due to random fluctuations and market impact
- Slippage is most heavily influenced by trade size and asset liquidity
 ↳ one model is the Almgren model, which considers the permanent and temporary impacts for each order of x_i shares of stock i .

$$I^{\text{perm}}(x_i) = \gamma \cdot T \cdot \sigma_i \cdot \text{sign}(x_i) \cdot \left| \frac{x_i}{V_i \cdot T} \right|^{\alpha} \cdot \left(\frac{\theta_i}{V_i} \right)$$

$$I^{\text{temp}}(x_i) = \eta \cdot \sigma_i \cdot \text{sign}(x_i) \cdot \left| \frac{x_i}{V_i \cdot T} \right|^{\beta}$$

↑ float
↑ daily volume
↑ fraction of the day over which trade executes

↳ looking at a large dataset of trades gives $\alpha \approx 1$ $\beta \approx \frac{1}{2}$

- T_x cost = amount traded \times slippage:

$$TC_i(x_i) = |x_i| \cdot \left(\frac{1}{2} I^{\text{perm}}(x_i) + I^{\text{temp}}(x_i) \right)$$

$$= a_i x_i^2 + b_i \cdot |x_i|^{3/2}$$

Almgren actually uses $\beta \approx \frac{3}{5}$

- Let h_0 denote the dollar values of holdings, h denote new holdings, x be the vector of trades (# shares), p be price vector.

- The optimisation problem then becomes:

$$\begin{aligned} \max_{\omega \in \Omega} \quad & \mu^T h - \gamma \cdot h^T \Sigma h - \gamma \cdot TC(x) \leftarrow TC(x) = \sum_i TC_i(x_i) \\ \text{s.t.} \quad & h - x_0 p = h_0 \quad \leftarrow \text{new holdings come from trades} \\ & h^T 1 + TC(x) \leq h_0^T 1 \quad \leftarrow \text{self-financing, ie mkt impact funded by selling holdings.} \end{aligned}$$

- This is now a nonlinear program, either requiring special SOCP solvers or a QP relaxation.

Constraints in portfolio construction

- MVO allows users to incorporate many constraints, which may actually improved ex-post performance.
- Regulatory requirements must be respected even if they reduce performance - e.g short selling / leverage restrictions.
- Discretionary exposure constraints limit exposure to certain risk factors - these act as model insurance, reducing the effects of estimation errors.
- Trading constraints e.g "don't trade > 5% of daily volume" may reduce tx costs.

Quantifying the effects of constraints

- The transfer coefficient is defined as the correlation coeff. between the risk-adjusted active weights in an optimised portfolio and the forecasted alphas of portfolio securities.

- Can be used to evaluate the effects of constraints.
 - ↳ for unconstrained portfolios with uncorrelated alphas, weights \propto alphas.
 - ↳ but it does not decompose the effects of individual constraints.
- Shadow cost decomposition (using Lagrange multipliers) can ascribe an opportunity loss to each constraint
 - ↳ can be extended to attribute returns to objective terms.
 - ↳ evaluation is most useful on an ex-post basis.

Misalignment from constraints

- When the alpha model contains factors not present in the risk model, the optimiser may be unstable and underestimate true risk.
- Even when aligned, in the presence of weight bounds, risk may be greatly underestimated. An alpha alignment factor may be required to improve ex-post performance.

Improving Estimation Errors

- Classical MVO ignores estimation errors, and has 'error maximiser' properties.
- As a rule of thumb: expected return $>$ variance $>$ covariance ^{2x impt.} ^{2x impt.}
- A simple method is to use weight constraints, but this can impact stability.

- Alternatively, we can use diversification indicators as constraints
 ↳ related to information content: high information \Rightarrow concentrated.

Black-Litterman (BL)

- Expected rets are a weighted avg of market equilibrium and investor views, with weights depending on asset volatility/covariance and confidence.
 ↳ can also allow for relative views
- BL assumes that asset returns are multivariate normally-distributed, i.e. $r \sim N(\mu, \Sigma)$ but μ itself is distributed as $\mu \sim N(\pi, \Sigma_\pi)$ where π is a vector of eq. returns.

1. Investor views are expressed as $P_\mu \sim N(q, \Omega)$:

$P \in \mathbb{R}^{K \times n}$ 'picks out' assets you have a view on

$q \in \mathbb{R}^K$ expected return on views (alphas)

$\Omega \in \mathbb{R}^{n \times n}$ cov matrix of views (confidence)

2. Market equilibrium is based on the CAPM:

$$\pi_i = E(r_i) - r_f = \beta_i(E(r_m) - r_f)$$

$$\beta_i = \frac{\text{Cov}(r_i, r_m)}{\sigma_m^2}$$

- benchmark (mcap) weights: $w_b = [w_{b_1}, \dots, w_{b_n}]^\top$

- then the CAPM can be expressed as

$$\pi = \delta \sum w_b \quad \text{vector of risks, including covariances}$$

$$\delta = \frac{E(r_m) - r_f}{\sigma_m^2} \quad \left. \right\} \text{market price of risk}$$

- 3. BL expected returns

$$\hat{\mu}_{BL} = [(\tau \Sigma)^{-1} + P^T Q^{-1} P]^{-1} \underbrace{[(\tau \Sigma)^{-1} \pi + P^T Q^{-1} q]}_{\substack{\text{some tuning hyperparam} \\ \text{weighted avg of mkt with views}}}$$

↳ if no views ($q=0$) or zero conf ($Q=0$), $\hat{\mu}_{BL} = \pi$

↳ $(\tau \Sigma)^{-1}$ and $P^T Q^{-1} P$ are our conf in mkt and view.

- BL can be applied directly to any normally distributed prior (or zero for active managers)
- Extensions of BL can be used to incorporate views on volatility, nonlinear/non-normal views of returns etc.

Robust Optimisation

- Models optimisation problems with uncertainty sets on the parameters, then maximising the worst-case utility.
 - ↳ can work for other risk paradigms like VaR/CVaR.
 - ↳ should lead to satisfactory portfolios on most realisations of the parameters.
- Computationally tractable via second-order cone opt.
- It is unclear whether robust optimisation outperforms shrinkage.

Higher moments and tail risk

- Financial return distributions tend to have fat tails and asymmetries which cannot be described by mean-variances.
- It is possible to maximise utility under the empirical return dist., but generally MVO is a good approx (except for S-shaped utility functions).
- Skew and Kurtosis can be directly incorporated, as a better approx for general utility maximisation.
- CVaR optimisation can be formulated as a LP.

New directions in portfolio optimisation

Diversification

- 'Naive' $1/N$ diversification outperforms many policies out of sample - it is not subject to estimation error or data mining.
- Alternatively, we can optimise with only a risk model to find the global min variance (GMV) portfolio.

Measuring risk contributions

- One approach is to define the risk contrib. of position i as:
 $\hat{\sigma}_i(\omega) = \sigma(\omega) - \sigma(\omega_{-i})$ where ω_{-i} is the portfolio with the i th weight set to zero.

- However, this is unintuitive because $\sum \hat{\sigma}_i(\omega) \neq \sigma(\omega)$
 - Alternatively, we define the marginal risk contrib. (MRC) of asset i as: $MRC_i(\omega) = \frac{\partial \sigma(\omega)}{\partial w_i}$ ← rate of change of risk as weight of i increases
- $$(\sigma(\omega))^2 = \omega^T \Sigma \omega \Rightarrow 2\sigma(\omega) \nabla_{\omega} \sigma(\omega) = 2 \Sigma \omega$$
- $$\therefore MRC_i(\omega) = \frac{(\Sigma \omega)_i}{\sigma(\omega)} \leftarrow i^{\text{th}} \text{ component}$$
- ↳ the risk contrib. (RC) is then $RC_i(\omega) = w_i \cdot MRC_i(\omega)$
- ↳ note that $\sum RC_i(\omega) = \sigma(\omega)$
- ↳ the relative risk contrib (RRC) is $RRC_i(\omega) = \frac{RC_i(\omega)}{\sigma(\omega)}$

Risk Parity

- A portfolio is a risk parity portfolio with respect to Σ iff $RRC_i(\omega) = 1/n$, $i=1,\dots,n$.
- ↳ i.e. total risk is allocated evenly across assets.
- In general, existence / uniqueness / constructions may be difficult or impossible depending on constraints.
- As an opt. problem, we aim to minimise the deviation from risk parity (DRP). Multiple measures could be used, e.g.:
 - $DRP(\omega) = \sum_i \sum_j [w_i(\Sigma \omega)_i - w_j(\Sigma \omega)_j]^2$ ← all pairwise diff.
 - $DRP(\omega) = \sum_i \left(\frac{w_i(\Sigma \omega)_i}{(\sigma(\omega))^2} - \frac{1}{n} \right)^2$ ← sum of square deviations
- ↳ but these metrics are nonconvex in ω , so may get stuck in local minima and are generally harder to optimise.

- In the long-only case, we can solve:

$$\min_{w \geq 0} w^T \Sigma w - \sum_i \ln w_i \quad \rightarrow \text{logarithmic barrier}$$

- ↳ the optimality condition is $2\Sigma w - w^{-1} = 0$ (set grad = 0)
- or equivalently $w_i (\Sigma w)_i = \frac{1}{2}$ $\downarrow w^{-1} \equiv [\frac{1}{w_1}, \frac{1}{w_2}, \dots \frac{1}{w_n}]^T$
- ↳ then $RRC_i(w) = \frac{1/2}{n/2} = \frac{1}{n}$
- ↳ since the optimality condition for this objective and risk parity are the same, we can just use this objective, which is convex in w .
- ↳ results may need to be scaled such that $\sum_i w_i = 1$.

Mixing different sources of alpha

- Rather than combining multiple alpha views into a single value, it may be desirable to let model mixing occur at the optimiser level.
- ↳ may want to constrain risk contrbs due to each alpha source
- ↳ alphas may have different 'periods'.
- Consider two sets of alphas, e.g strategic (μ^x) and tactical (μ^y), with respective active weights w_A^x and w_A^y . Optimise:

$$\max_{w \in \Omega} (\mu^x)^T w_A^x + (\mu^y)^T w_A^y - \gamma \cdot (w_A^x + w_A^y)^T \Sigma (w_A^x + w_A^y) - \delta T(w)$$

s.t. $w - w_A^x - w_A^y = w_B$ weight = active + benchmark

$$(w_A^x)^T \Sigma w_A^x \leq u^x \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{budget risk between the two.}$$

$$(w_A^y)^T \Sigma w_A^y \leq u^y \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{↳ budgets can change based on performance}$$

Views on groups of securities

- How should you allocate if you are bullish on AAPL but bearish on tech stocks?
- Similar to model mixing except we must map between groups and securities. This can be done with a $m \times n$ incidence matrix G , where $G_{gi} = 1$ if asset i is in group g , and zero otherwise.
 - ↳ benchmark security weights \rightarrow group weights via $w_g^B = G w_B^I$
- Suppose we have group weights w^G . We then scale the security weights in the group by $w_g^G / (w_B^G)_g$, i.e our group weight vs benchmark group weight:
 - ↳ this produces a security-level benchmark
 - ↳ we can then define the group/security active weights
- We can then optimise as before.

Multi-period Optimisation (MPO)

- MPO jointly models risk, alpha and its decay, and impact costs.
 - ↳ i.e when you should trade, not just what
- Let returns be modelled by $r_{t+1} = \mu_t + \alpha_t + \varepsilon'_{t+1}$
returns to comp. for risk \rightarrow predictable excess alpha

- Alphas are forecasted with a factor model with K mean-reverting factors:

$$\alpha_t = B f_t + \varepsilon_t^\alpha \quad \begin{matrix} \leftarrow B \in \mathbb{R}^{n \times K} \text{ factor loadings} \\ \leftarrow f \in \mathbb{R}^K \text{ factors} \end{matrix}$$

$$\Delta f_{t+1} = -D f_t + \varepsilon_{t+1}^f \quad \begin{matrix} \leftarrow D \in \mathbb{R}^{K \times K} \text{ mean reversion coefficients} \\ \leftarrow \varepsilon \text{ idiosyncratic components.} \end{matrix}$$
- We can incorporate permanent and temporary tx costs by adding additional costs to the investor's α .
- The MPO problem is then given by:

$$\max_{\Delta w_1, \Delta w_2, \dots, \Delta w_{T-1}} E \left[\sum_{t=1}^{T-1} (1-p)^t \left(w_t^\top \alpha_t - \frac{\lambda}{2} w_t^\top \Sigma w_t - \frac{1}{2} \Delta w_t^\top \Lambda \Delta w_t \right) + (1-p)^T \left(w_T^\top \alpha_T - \frac{\lambda}{2} w_T^\top \Sigma w_T \right) \right]$$

discount factor diagonal tx cost matrix

↳ i.e. maximise PV of period returns less tx costs over every possible rebalance

- This is a stochastic linear-quadratic regulator problem, and can be solved with standard theory.