

Cálculos

Roberto Álvarez

Table of contents

1 Ecuación Lotka-Volterra	1
1.1 Demostración de ambas ecuaciones	2
1.2 Para 1-D	3
1.3 Para 2D	5
1.4 Dinámicas Lotka-Volterra	6
1.4.1 Competencia que conduce a la extinción de especies	7
1.5 Estabilidad de comunidades grandes	10

1 Ecuación Lotka-Volterra

$$\frac{dx_i}{dt} = r_i x_i + \sum_{j=1}^n A_{ij} x_i x_j$$

$$\forall i = 1, 2, 3, \dots, n$$

$$\frac{dx_i}{dt} = x_i (r_i + \sum_{j=1}^n A_{ij} x_j)$$

Lotka-Volterra en forma vectorial

$$\frac{d\mathbf{x}}{dt} = D(\mathbf{x})(\mathbf{r} + \mathcal{A}\mathbf{x})$$

con el vector de abundancias de las poblaciones

$$\mathbf{x}(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \\ \vdots \\ x_n(t) \end{bmatrix}$$

$$D(\mathbf{x}) = \begin{pmatrix} x_1(t) & 0 & 0 & \dots & 0 \\ 0 & x_2(t) & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & x_n(t) \end{pmatrix}$$

El vector de tasas de crecimiento

$$\mathbf{r} = \begin{bmatrix} r_1 \\ r_2 \\ r_3 \\ \vdots \\ r_n \end{bmatrix}$$

La matriz de interacciones

$$\mathcal{A} = \begin{pmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \dots & a_{nn} \end{pmatrix}$$

1.1 Demostración de ambas ecuaciones

Entonces la parte $\mathbf{r} + \mathcal{A}\mathbf{x}$ es un vector columna

$$\mathbf{r} + \mathcal{A}\mathbf{x} = \begin{bmatrix} r_1 \\ r_2 \\ r_3 \\ \vdots \\ r_n \end{bmatrix} + \begin{pmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \dots & a_{nn} \end{pmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \\ \vdots \\ x_n(t) \end{bmatrix}$$

Si efectuamos la operación del producto de la matriz de interacciones \mathbf{A} con el vector columna de abundancias \mathbf{x}

$$\mathbf{r} + \mathcal{A}\mathbf{x} = \begin{bmatrix} r_1 \\ r_2 \\ r_3 \\ \vdots \\ r_n \end{bmatrix} + \begin{bmatrix} a_{11}x_1(t) + a_{12}x_2(t) + a_{13}x_3(t) + \dots + a_{1n}x_n(t) \\ a_{21}x_1(t) + a_{22}x_2(t) + a_{23}x_3(t) + \dots + a_{2n}x_n(t) \\ a_{31}x_1(t) + a_{32}x_2(t) + a_{33}x_3(t) + \dots + a_{3n}x_n(t) \\ \vdots \\ a_{n1}x_1(t) + a_{n2}x_2(t) + a_{n3}x_3(t) + \dots + a_{nn}x_n(t) \end{bmatrix}$$

Finalmente sumamos ambos vectores columnas \mathbf{r} y $\mathcal{A}\mathbf{x}$ tenemos:

$$\mathbf{r} + \mathcal{A}\mathbf{x} = \begin{bmatrix} r_1 + a_{11}x_1(t) + a_{12}x_2(t) + a_{13}x_3(t) + \dots + a_{1n}x_n(t) \\ r_2 + a_{21}x_1(t) + a_{22}x_2(t) + a_{23}x_3(t) + \dots + a_{2n}x_n(t) \\ r_3 + a_{31}x_1(t) + a_{32}x_2(t) + a_{33}x_3(t) + \dots + a_{3n}x_n(t) \\ \vdots \\ r_n + a_{n1}x_1(t) + a_{n2}x_2(t) + a_{n3}x_3(t) + \dots + a_{nn}x_n(t) \end{bmatrix}$$

Finalmente hacemos el producto de la matriz $\mathcal{D}(\mathbf{x})$ con el vector $\mathbf{r} + \mathcal{A}\mathbf{x}$

$$\mathcal{D}(\mathbf{x})(\mathbf{r} + \mathcal{A}\mathbf{x}) = \begin{pmatrix} x_1(t) & 0 & 0 & \dots & 0 \\ 0 & x_2(t) & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & x_n(t) \end{pmatrix} \begin{bmatrix} r_1 + a_{11}x_1(t) + a_{12}x_2(t) + a_{13}x_3(t) + \dots + a_{1n}x_n(t) \\ r_2 + a_{21}x_1(t) + a_{22}x_2(t) + a_{23}x_3(t) + \dots + a_{2n}x_n(t) \\ r_3 + a_{31}x_1(t) + a_{32}x_2(t) + a_{33}x_3(t) + \dots + a_{3n}x_n(t) \\ \vdots \\ r_n + a_{n1}x_1(t) + a_{n2}x_2(t) + a_{n3}x_3(t) + \dots + a_{nn}x_n(t) \end{bmatrix}$$

Finalmente:

$$\begin{bmatrix} r_1x_1(t) + a_{11}x_1^2(t) + a_{12}x_2(t)x_1(t) + a_{13}x_3(t)x_1(t) + \dots + a_{1n}x_n(t)x_1(t) \\ r_2x_2(t) + a_{21}x_1(t)x_2(t) + a_{22}x_2^2(t) + a_{23}x_3(t)x_2(t) + \dots + a_{2n}x_n(t)x_2(t) \\ r_3x_3(t) + a_{31}x_1(t)x_3(t) + a_{32}x_2(t)x_3(t) + a_{33}x_3^2(t) + \dots + a_{3n}x_n(t)x_3(t) \\ \vdots \\ r_nx_n(t) + a_{n1}x_1(t)x_n(t) + a_{n2}x_2(t)x_n(t) + a_{n3}x_3(t)x_n(t) + \dots + a_{nn}x_n^2(t) \end{bmatrix}$$

1.2 Para 1-D

$$\frac{dx}{dt} = x(t)(r + ax(t))$$

La solución no trivial es:

$$\frac{dx}{dt} = x^*(r + ax^*) = 0$$

$$r + ax^* = 0$$

$$x = -\frac{r}{a}$$

con $a < 0$ la solución es positiva

```
library(deSolve) # integrate ODEs
library(tidyverse) # plotting and wrangling
```

```

-- Attaching core tidyverse packages ----- tidyverse 2.0.0 --
v dplyr      1.1.4      v readr      2.1.5
v forcats    1.0.0      v stringr    1.5.1
v ggplot2    3.5.0      v tibble     3.2.1
v lubridate  1.9.3      v tidyr      1.3.1
v purrr      1.0.2

-- Conflicts ----- tidyverse_conflicts() --
x dplyr::filter() masks stats::filter()
x dplyr::lag()     masks stats::lag()
i Use the conflicted package (<http://conflicted.r-lib.org/>) to force all conflicts to become

```

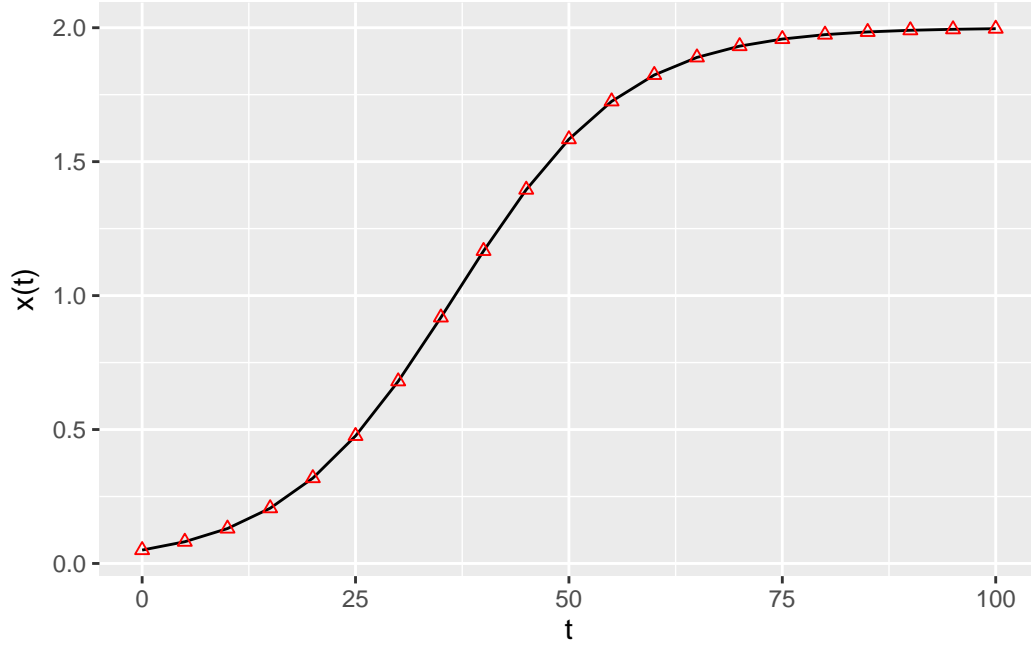
```

# define the differential equation
logistic_growth <- function(t, x, parameters){
  with(as.list(c(x, parameters)), {
    dxdt <- x * (r + a * x)
    list(dxdt)
  })
}

# define parameters, integration time, initial conditions
times <- seq(0, 100, by = 5)
x0 <- 0.05
r <- 0.1
a <- -0.05
parameters <- list(r = r, a = a)
# solve numerically
out <- ode(y = x0, times = times,
          func = logistic_growth, parms = parameters,
          method = "ode45")

# now compute analytically
solution <- r * x0 * exp(r * times) / (r - a * x0 * (exp(r * times) - 1))
# use ggplot to plot
res <- tibble(time = out[,1], x_t = out[,2], x_sol = solution)
ggplot(data = res) + aes(x = time, y = x_t) +
  geom_line() +
  geom_point(aes(x = time, y = x_sol), colour = "red", shape = 2) +
  ylab(expression("x(t)")) + xlab(expression("t"))

```



1.3 Para 2D

La solución de co-existencia para el modelo Lotka-Volterra generalizado es la siguiente:

$$\frac{dx_1}{dt} = x_1(r_1 + ax_1 + bx_2) = 0 \quad (1)$$

$$\frac{dx_2}{dt} = x_2(r_2 + cx_1 + dx_2) = 0 \quad (2)$$

Tendremos que encontrar las soluciones para $x_1 = 1$ y x_2 en términos de el vector de tasas de crecimiento \mathbf{r} y de la matriz de interacciones \mathcal{A}

Tarea

Es decir debemos demostrar que las soluciones de co-existencia:

$$1 + ax_1 + bx_2 = 0 \quad (3)$$

$$2 + cx_1 + dx_2 = 0 \quad (4)$$

son iguales a las soluciones vectoriales.

$$\mathbf{x}^* = \begin{bmatrix} x_1^* \\ x_2^* \end{bmatrix} = \mathcal{A}^{-1} \begin{bmatrix} -r_1 \\ -r_2 \end{bmatrix}$$

en dos dimensiones si una matriz \mathcal{A}

$$\mathcal{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

su inversa se calcula como:

$$\mathcal{A}^{-1} = \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} \frac{1}{\det(\mathcal{A})}$$

1.4 Dinámicas Lotka-Volterra

```
# Generalized Lotka-Volterra model
GLV <- function(t, x, parameters){
  with(as.list(c(x, parameters)), {
    x[x < 10^-8] <- 0 # prevent numerical problems
    dxdt <- x * (r + A %*% x)
    list(dxdt)
  })
}

# function to plot output
plot_ODE_output <- function(out){
  out <- as.data.frame(out)
  colnames(out) <- c("time", paste("sp", 1:(ncol(out) - 1), sep = "_"))
  out <- as_tibble(out) %>% gather(species, density, -time)
  pl <- ggplot(data = out) +
    aes(x = time, y = density, colour = species) +
    geom_line()
  show(pl)
  return(out)
}

# general function to integrate GLV
integrate_GLV <- function(r, A, x0, maxtime = 100, steptime = 0.5){
  times <- seq(0, maxtime, by = steptime)
  parameters <- list(r = r, A = A)
  # solve numerically
  out <- ode(y = x0, times = times,
    func = GLV, parms = parameters,
```

```

        method = "ode45")
# plot and make into tidy form
out <- plot_ODE_output(out)
return(out)
}

```

1.4.1 Competencia que conduce a la extinción de especies

```

set.seed(1) # for reproducibility
r_1 <- rep(1, 3)
A_1 <- -matrix(c(10, 9, 5,
                9, 10, 9,
                5, 9, 10), 3, 3, byrow = TRUE)
# check the existence of feasible equilibrium
print(solve(A_1, -r_1)) # not feasible

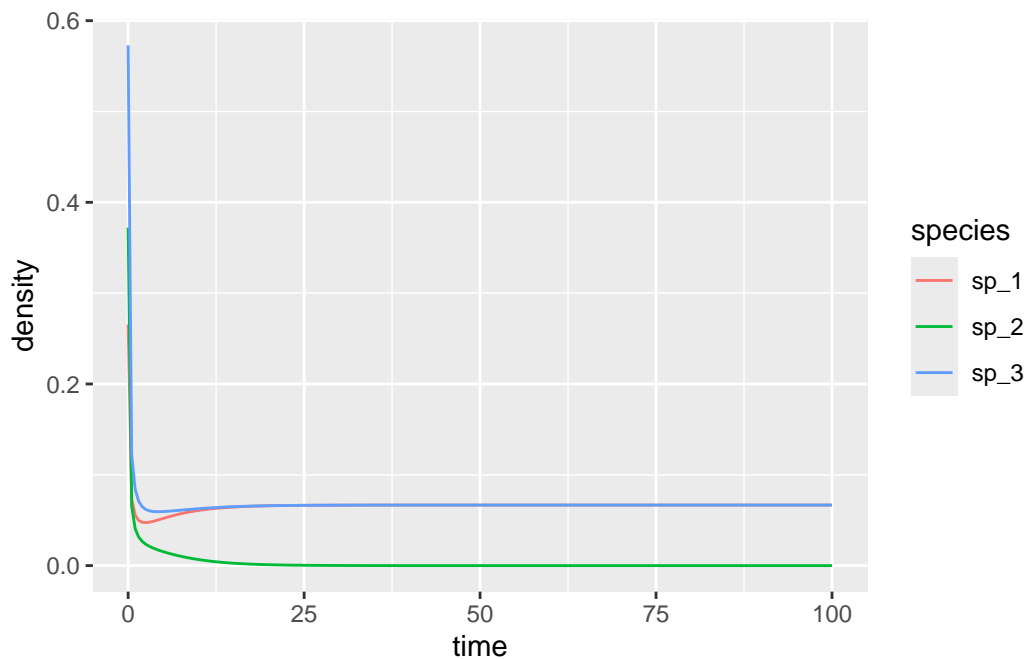
```

```
[1] -0.08333333  0.25000000 -0.08333333
```

```

x0_1 <- runif(3)
res_1 <- integrate_GLV(r_1, A_1, x0_1)

```



```

set.seed(2) # for reproducibility
r_2 <- rep(10, 3)
A_2 <- -matrix(c(10, 7, 12,
                 15, 10, 8,
                 7, 11, 10), 3, 3, byrow = TRUE)
# check the existence of feasible equilibrium
print(solve(A_2, -r_2)) # feasible

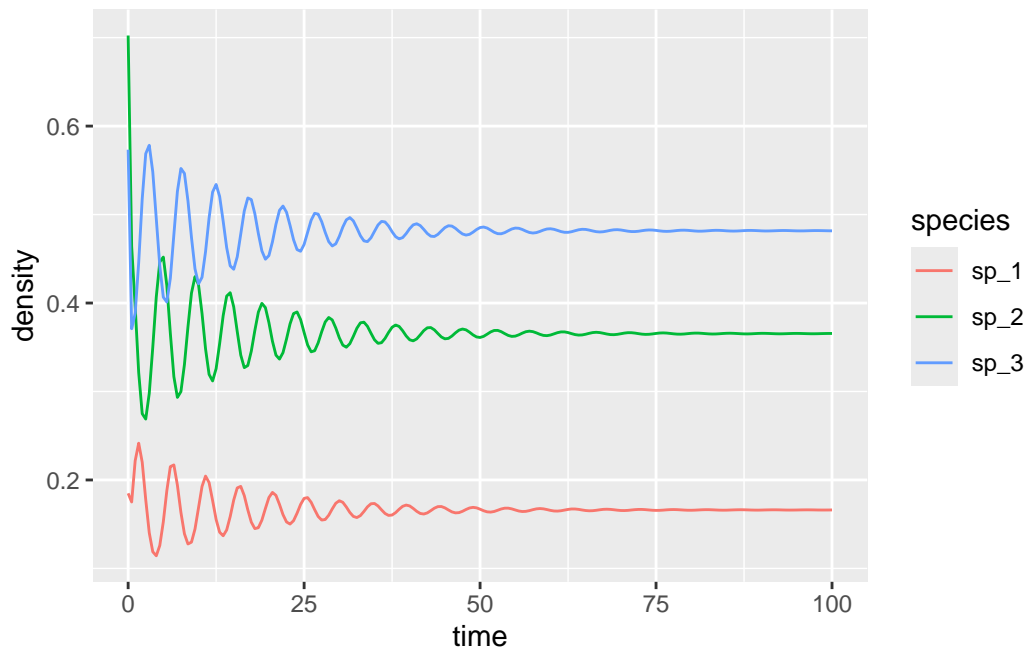
```

```
[1] 0.1661130 0.3654485 0.4817276
```

```

x0_2 <- runif(3)
res_2 <- integrate_GLV(r_2, A_2, x0_2)

```



```

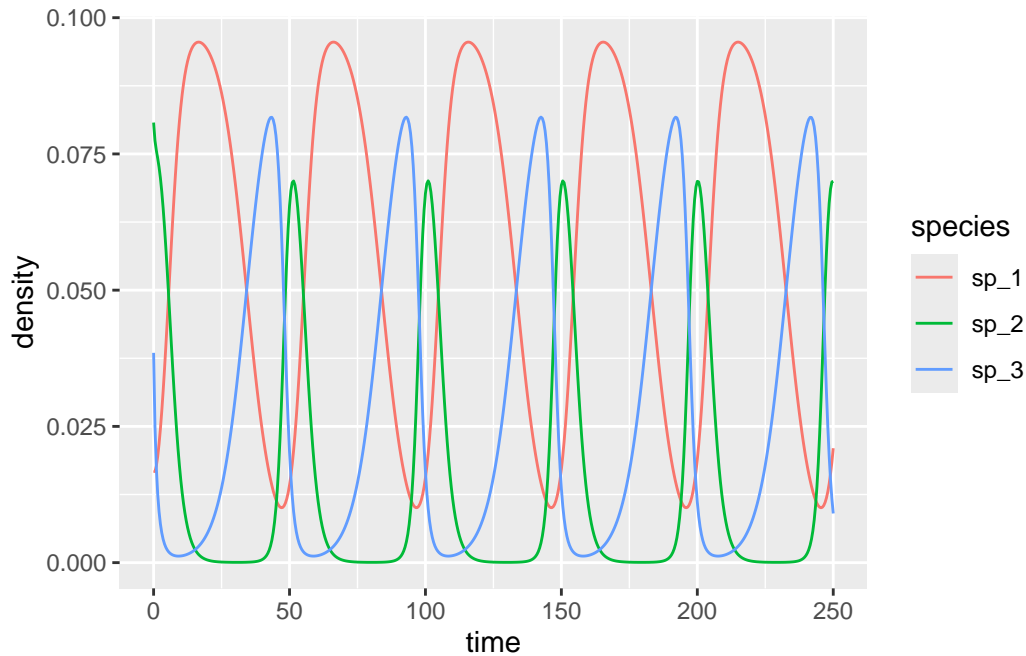
set.seed(3) # for reproducibility
r_3 <- rep(1, 3)
A_3 <- -matrix(c(10, 6, 12,
                 14, 10, 2,
                 8, 18, 10), 3, 3, byrow = TRUE)
# check the existence of feasible equilibrium
print(solve(A_3, -r_3)) # feasible

```



```
[1] 0.05714286 0.01428571 0.02857143
```

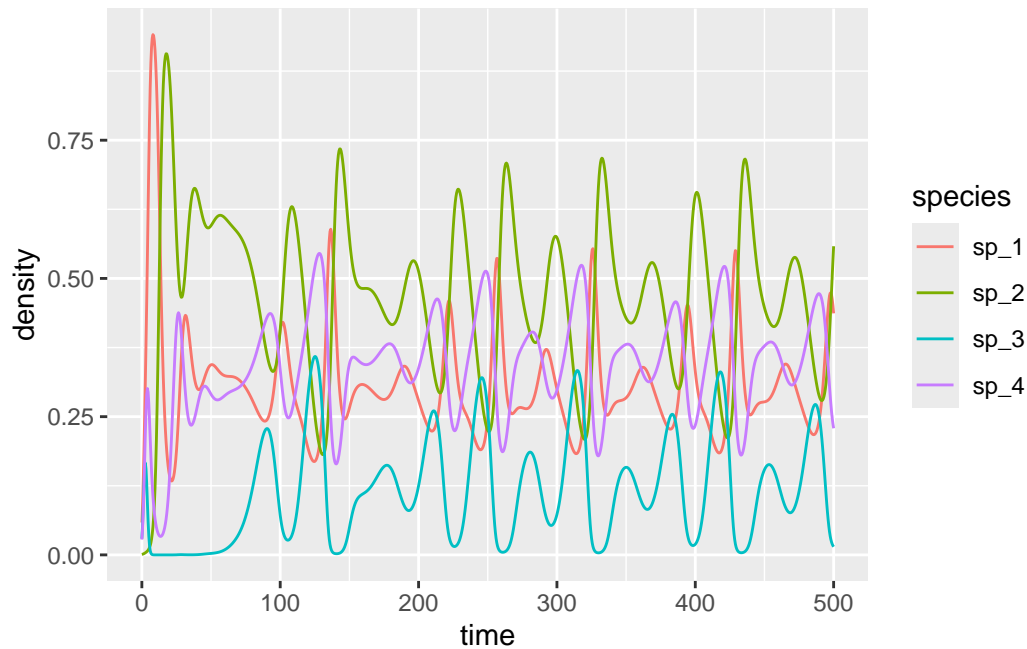
```
x0_3 <- 0.1 * runif(3)
res_3 <- integrate_GLV(r_3, A_3, x0_3, maxtime = 250)
```



```
set.seed(4) # for reproducibility
r_4 <- c(1, 0.72, 1.53, 1.27)
A_4 <- -matrix(c(1, 1.09, 1.52, 0,
                 0, 0.72, 0.3168, 0.9792,
                 3.5649, 0, 1.53, 0.7191,
                 1.5367, 0.6477, 0.4445, 1.27), 4, 4, byrow = TRUE)
# check the existence of feasible equilibrium
print(solve(A_4, -r_4)) # feasible
```

```
[1] 0.3013030 0.4586546 0.1307655 0.3557416
```

```
x0_4 <- 0.1 * runif(4)
res_4 <- integrate_GLV(r_4, A_4, x0_4, maxtime = 500)
```



1.5 Estabilidad de comunidades grandes

Robert May (1973) propuso una forma de generar una matriz aleatoria de interacciones

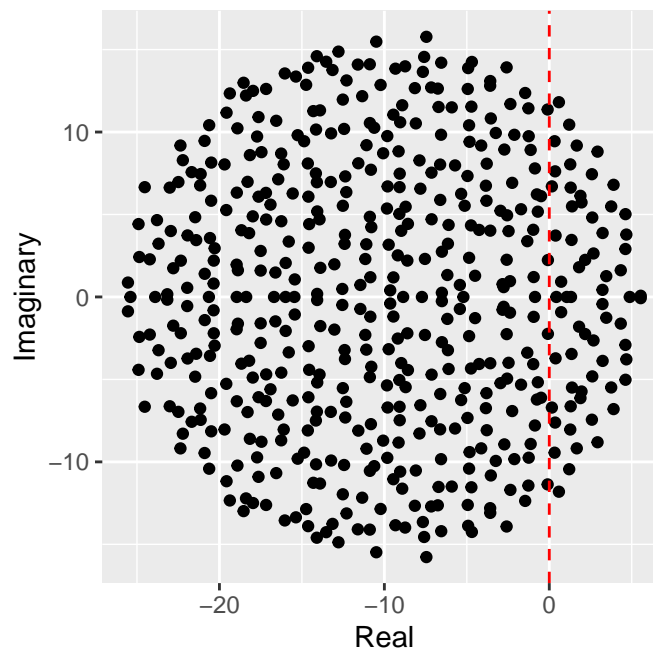
```
build_May_normal <- function(n, C, d, sigma){
  # fill the whole matrix
  M <- matrix(rnorm(n * n, mean = 0, sd = sigma), n, n)
  # remove connections
  M <- M * matrix(runif(n * n) <= C, n, n)
  # set diagonals
  diag(M) <- -d
  return(M)
}

plot_eigenvalues <- function(M, prediction = NULL){
  eig <- eigen(M, only.values = TRUE)$values
  dt <- tibble(Real = Re(eig), Imaginary = Im(eig))
  pl <- ggplot(dt) + aes(x = Real, y = Imaginary) +
    geom_point() +
    coord_equal() +
    geom_vline(xintercept = 0, colour = "red", linetype = 2)
```

```

    if (is.null(prediction) == FALSE) {
      pl <- pl + geom_vline(xintercept = prediction, colour = "black", linetype = 2)
    }
    show(pl)
  }
  set.seed(100) # for reproducibility
  # parameters
  n <- 500
  C <- 0.5
  d <- 10
  sigma <- 1
  M <- build_May_normal(n, C, d, sigma)
  #library(tidyr)
  plot_eigenvalues(M)

```



```

build_Allesina_Tang_normal <- function(n, C, d, sigma, rho){
  # sample coefficients in pairs
  pairs <- MASS::mvrnorm(n = n * (n-1) / 2,
    mu = c(0, 0),
    Sigma = sigma^2 * matrix(c(1, rho, rho, 1), 2, 2))
  # build a completely filled matrix

```

```

M <- matrix(0, n, n)
M[upper.tri(M)] <- pairs[,1]
M <- t(M)
M[upper.tri(M)] <- pairs[,2]
# determine which connections to retain
Connections <- (matrix(runif(n * n), n, n) <= C) * 1
Connections[lower.tri(Connections)] <- 0
diag(Connections) <- 0
Connections <- Connections + t(Connections)
M <- M * Connections
diag(M) <- -d
return(M)
}

# parameters
n <- 500
C <- 0.5
d <- 10
sigma <- 1
rho <- 0.4
M <- build_Allesina_Tang_normal(n, C, d, sigma, rho)
prediction <- sqrt(n * C * sigma^2) * (1 + rho) - d
plot_eigenvalues(M, prediction)

```

