# Cerberus: A MOOSE-based application for solving the SP<sub>3</sub> equations

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#### Roberto Fairhurst Agosta, Kathryn D. Huff

Advanced Reactors and Fuel Cycles University of Illinois at Urbana-Champaign

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#### Outline

- 1 Introduction
  Objectives
  Motivation
- 2 Methodology Equations Implementation Kernels
- Results

2-G. 2-D

2-G, 3-D

4 Final Remarks

Conclusions Acknowledgement Questions

#### Objectives

- Describe the implementation of the SP<sub>3</sub> equations in a MOOSE-based application.
- Verify the implementation by conducting the following exercises:
  - One-group, two-dimensional eigenvalue problem.
  - C5 MOX Benchmark (2D)
  - C5 MOX Benchmark (3D mini-core variation)

#### Motivation

#### Why a neutronics solver?

- Neutronics provide information on the power distribution.
- Crucial role in the thermal-fluids behavior of a reactor.
- Multi-physics simulations for safety assessment.

#### Why the $SP_3$ equations?

- Fewer equations than P<sub>3</sub>.
- Reduces the computational expense.
- · Conserves a reasonable accuracy.
- More accurate solution than diffusion approximation.

#### Why MOOSE?

- Partial differential equations describe the reactor physics.
- Computational framework for solving coupled equation systems.
- Open-source, enabling wider collaboration.
- API that facilitates coupling between various applications targeting different phenomena.

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#### $P_3$ equations

- $P_N$  expands the angular dependence in spherical harmonics.
- For N=3, steady-state, and one-dimension [5]:

$$\frac{d}{dx}\phi_{1,g} + \Sigma_{t,g}\phi_{0,g} = \sum_{g'=1}^{G} \Sigma_{s0,g'\to g}\phi_{0,g'} + \frac{\chi_g}{k_{eff}} \sum_{g'=1}^{G} \nu \Sigma_{f,g'}\phi_{0,g'} + Q_{0,g}$$
(1)

$$\frac{1}{3}\frac{d}{dx}\phi_{0,g} + \frac{2}{3}\frac{d}{dx}\phi_{2,g} + \Sigma_{t,g}\phi_{1,g} = \sum_{g'=1}^{G} \Sigma_{s1,g'\to g}\phi_{1,g'} + Q_{1,g}$$
 (2)

$$\frac{2}{5}\frac{d}{dx}\phi_{1,g} + \frac{3}{5}\frac{d}{dx}\phi_{3,g} + \Sigma_{t,g}\phi_{2,g} = \sum_{g'=1}^{G} \Sigma_{s2,g'\to g}\phi_{2,g'} + Q_{2,g}$$
(3)

$$\frac{3}{7}\frac{d}{dx}\phi_{2,g} + \Sigma_{t,g}\phi_{3,g} = \sum_{g'=1}^{G} \Sigma_{s3,g'\to g}\phi_{3,g'} + Q_{3,g}. \tag{4}$$

# $P_3$ equations (2)

#### Assumptions [2]:

- isotropic external source
- negligible anisotropic group-to-group scattering

$$\frac{d}{dx}\phi_{1,g} + \Sigma_{0,g}\phi_{0,g} = \sum_{g'\neq g}^{G} \Sigma_{s0,g'\to g}\phi_{0,g'} + \frac{\chi_{g}}{k_{eff}} \sum_{g'=1}^{G} \nu \Sigma_{f,g'}\phi_{0,g'} + Q_{0,g}$$
 (5)

$$\frac{1}{3}\frac{d}{dx}\phi_{0,g} + \frac{2}{3}\frac{d}{dx}\phi_{2,g} + \Sigma_{1,g}\phi_{1,g} = 0$$
 (6)

$$\frac{2}{5}\frac{d}{dx}\phi_{1,g} + \frac{3}{5}\frac{d}{dx}\phi_{3,g} + \Sigma_{2,g}\phi_{2,g} = 0$$
 (7)

$$\frac{3}{7}\frac{d}{dx}\phi_{2,g} + \Sigma_{3,g}\phi_{3,g} = 0. \tag{8}$$

# $P_3$ equations (3)

With the following definitions:

$$D_{0,g} = \frac{1}{3\Sigma_{1,g}}, \quad D_{2,g} = \frac{9}{35\Sigma_{3,g}}$$
 $\Phi_{0,g} = \phi_{0,g} + 2\phi_{2,g}, \quad \Phi_{2,g} = \phi_{2,g}$ 

the equations become:

$$-D_{0,g}\frac{d^2}{dx^2}\Phi_{0,g} + \Sigma_{0,g}\Phi_{0,g} - 2\Sigma_{0,g}\Phi_{2,g} = S_{0,g}$$
(9)

$$-D_{2,g}\frac{d^2}{dx^2}\Phi_{2,g} + \left(\Sigma_{2,g} + \frac{4}{5}\Sigma_{0,g}\right)\Phi_{2,g} - \frac{2}{5}\Sigma_{0,g}\Phi_{0,g} = -\frac{2}{5}S_{0,g}$$
(10)

where

$$S_{0,g} = \sum_{g' \neq g}^{G} \Sigma_{s0,g' \to g} \left( \Phi_{0,g'} - 2 \Phi_{2,g'} \right) + \frac{\chi_g}{k_{eff}} \sum_{g'=1}^{G} \nu \Sigma_{f,g'} \left( \Phi_{0,g'} - 2 \Phi_{2,g'} \right) + \mathcal{Q}_{0,g}.$$

# $SP_3$ approximation

- $P_N$ : yields the exact transport solution as  $N \to \infty$ .
- 3D:  $(N+1)^2$  equations. If N=3, 16 equations.
- 1D: (N+1) equations yield (N+1)/2. If N =3, 2 equations.
- $SP_N$  approximation replaces  $\frac{d^2}{dx^2}$  by  $\Delta$ .

#### $SP_3$ equations

$$-D_{0,g}\Delta\Phi_{0,g} + \Sigma_{0,g}\Phi_{0,g} - 2\Sigma_{0,g}\Phi_{2,g} = S_{0,g}$$
(11)

$$-D_{2,g}\Delta\Phi_{2,g} + \left(\Sigma_{2,g} + \frac{4}{5}\Sigma_{0,g}\right)\Phi_{2,g} - \frac{2}{5}\Sigma_{0,g}\Phi_{0,g} = -\frac{2}{5}S_{0,g}.$$
 (12)

With the Marshak vacuum BCs [1]

$$\frac{1}{4}\Phi_{0,g} \pm \frac{1}{2}\hat{n} \cdot J_{0,g} - \frac{3}{16}\Phi_{2,g} = 0 \tag{13}$$

$$-\frac{3}{80}\Phi_{0,g} \pm \frac{1}{2}\hat{n} \cdot J_{2,g} + \frac{21}{80}\Phi_{2,g} = 0$$
 (14)

where

$$J_{n,g} = -D_{n,g} \nabla \Phi_{n,g}.$$

- Computational framework for solving coupled equation systems.
- Input are the weak form of the equations.
- MOOSE and LibMesh translate them into residual and Jacobian functions.
- PetSc solution routines solve the equations.

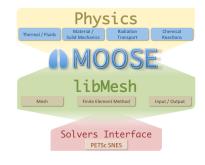


Figure: MOOSE framework. Image reproduced from [6].

# Example Code

# Strong Form $\rho C p \frac{\partial T}{\partial t} - \nabla \cdot k(T, B) \nabla T = f$

$$\int\limits_{\Omega} \rho C p \frac{\partial T}{\partial t} \psi_i + \int\limits_{\Omega} k \nabla T \cdot \nabla \psi_i - \int\limits_{\partial \Omega} k \nabla T \cdot \mathbf{n} \psi_i - \int\limits_{\Omega} f \psi_i = \mathbf{0}$$
 Kernel BoundaryCondition Kernel

```
Actual Code return _k[_qp]*_grad_u[_qp]*_grad_test[_i][_qp];
```

Figure: Translation into MOOSE kernels procedure [6].

#### Weak form: Equation 1

$$\langle D_{0,g} \nabla \Phi_{0,g}, \nabla \Psi \rangle - \langle D_{0,g} \nabla \Phi_{0,g}, \Psi \rangle_{BC} + \langle \Sigma_{0,g} \Phi_{0,g}, \Psi \rangle + \langle -2\Sigma_{0,g} \Phi_{2,g}, \Psi \rangle$$

$$+ \left\langle -\sum_{g' \neq g}^{G} \Sigma_{s0,g' \to g} \left( \Phi_{0,g'} - 2\Phi_{2,g'} \right), \Psi \right\rangle$$

$$+ \left\langle -\frac{\chi_g}{k_{eff}} \sum_{g'=1}^{G} \nu \Sigma_{f,g'} \left( \Phi_{0,g'} - 2\Phi_{2,g'} \right), \Psi \right\rangle + \langle -Q_{0,g}, \Psi \rangle = 0$$
(15)

with the boundary condition

$$\langle D_{0,g} \nabla \Phi_{0,g}, \Psi \rangle_{BC} = \left\langle \frac{1}{2} \Phi_{0,g} - \frac{3}{4} \Phi_{2,g}, \Psi \right\rangle_{BC}. \tag{16}$$

#### Weak form: Equation 2

$$\langle D_{2,g} \nabla \Phi_{2,g}, \nabla \Psi \rangle - \langle D_{2,g} \nabla \Phi_{2,g}, \Psi \rangle_{BC} + \left\langle \left( \Sigma_{2,g} + \frac{4}{5} \Sigma_{0,g} \right) \Phi_{2,g}, \Psi \right\rangle$$

$$+ \left\langle -\frac{2}{5} \Sigma_{0,g} \Phi_{0,g}, \Psi \right\rangle + \left\langle \frac{2}{5} \sum_{g' \neq g}^{G} \Sigma_{s0,g' \to g} \left( \Phi_{0,g'} - 2 \Phi_{2,g'} \right), \Psi \right\rangle$$

$$+ \left\langle \frac{2}{5} \frac{\chi_g}{k_{eff}} \sum_{g'=1}^{G} \nu \Sigma_{f,g'} \left( \Phi_{0,g'} - 2 \Phi_{2,g'} \right), \Psi \right\rangle + \left\langle \frac{2}{5} Q_{0,g}, \Psi \right\rangle = 0.$$

$$(17)$$

with the boundary condition

$$\left\langle D_{2,g} \nabla \Phi_{2,g}, \Psi \right\rangle_{BC} = \left\langle -\frac{3}{40} \Phi_{0,g} + \frac{21}{40} \Phi_{2,g}, \Psi \right\rangle_{BC}. \tag{18}$$

#### Cerberus Kernels: Equation 1

Table:  $SP_3$  kernels.

Kernel name	Equation 1		
SP3Diffusion	$\langle D_{0,g}  abla \Phi_{0,g},  abla \Psi  angle$		
SP3SigmaR	$\langle \Sigma_{0,g} \Phi_{0,g}, \Psi  angle$		
SP3SigmaCoupled	$\langle -2 \Sigma_{0,g} \Phi_{2,g}, \Psi \rangle$		
SP3InScatter	$ \left\langle -\sum_{g'\neq g}^{G} \sum_{s0,g'\rightarrow g} \left( \Phi_{0,g'} - 2\Phi_{2,g'} \right), \Psi \right\rangle $ $\left\langle -\frac{\chi_{g}}{k_{eff}} \sum_{g'=1}^{G} \nu \Sigma_{f,g'} \left( \Phi_{0,g'} - 2\Phi_{2,g'} \right), \Psi \right\rangle $		
SP3FissionEigenKernel	$\left\langle -\frac{\chi_{g}}{k_{\text{eff}}} \sum_{g'=1}^{G} \nu \Sigma_{f,g'} \left( \Phi_{0,g'} - 2 \Phi_{2,g'} \right), \Psi \right\rangle$		
BodyForce (MOOSE)	$\langle -Q_{0,g},\Psi angle$		
BC Kernel name			
SP3Vacuum	$\left\langle rac{1}{2}\Phi_{0, extit{g}} - rac{3}{4}\Phi_{2, extit{g}}, \Psi  ight angle_{ extit{BC}}$		

#### Cerberus Kernels: Equation 2

Table:  $SP_3$  kernels.

Kernel name	Equation 2		
SP3Diffusion	$\langle D_{2,g}  abla \Phi_{2,g},  abla \Psi  angle$		
SP3SigmaR	$\langle (\Sigma_{2,g} + \frac{4}{5}\Sigma_{0,g}) \Phi_{2,g}, \Psi \rangle$		
SP3SigmaCoupled	$ \begin{array}{c} \left\langle \left( \Sigma_{2,g} + \frac{4}{5} \Sigma_{0,g} \right) \Phi_{2,g}, \Psi \right\rangle \\ \left\langle -\frac{2}{5} \Sigma_{0,g} \Phi_{0,g}, \Psi \right\rangle \end{array} $		
SP3InScatter	$\left\langle \frac{2}{5} \sum_{g'\neq g}^{G} \sum_{s0,g'\to g} \left( \Phi_{0,g'} - 2\Phi_{2,g'} \right), \Psi \right\rangle$ $\left\langle \frac{2}{5} \frac{\chi_g}{k_{eff}} \sum_{g'=1}^{G} \nu \Sigma_{f,g'} \left( \Phi_{0,g'} - 2\Phi_{2,g'} \right), \Psi \right\rangle$		
SP3FissionEigenKernel	$\left\langle \frac{2}{5} \frac{\chi_g}{k_{sff}} \sum_{g'=1}^{G} \nu \Sigma_{f,g'} \left( \Phi_{0,g'} - 2 \Phi_{2,g'} \right), \Psi \right\rangle$		
BodyForce (MOOSE)	$\left\langle rac{2}{5}Q_{0,g},\Psi ight angle$		
BC Kernel name			
SP3Vacuum	$\left\langle -rac{3}{40}\Phi_{0,g}+rac{21}{40}\Phi_{2,g},\Psi ight angle_{BC}$		

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#### One-group, two-dimensional eigenvalue problem

- Problem presented in Brantley and Larsen, 2000 [2].
- One-energy group.
- Two-dimensional problem.
- Two materials: fuel and moderator.

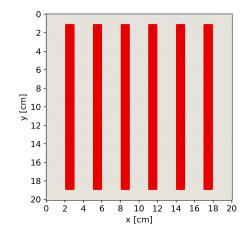


Figure: Problem's geometry.

# One-group, two-dimensional eigenvalue problem (2)



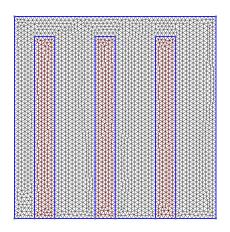


Figure: Gmsh 2D mesh.

# One-group, two-dimensional eigenvalue problem (3)

Table: Eigenvalue comparison.

k <sub>Ref</sub>	k <sub>SP3</sub>	$\Delta_{ ho}$
0.79862	0.79854	12

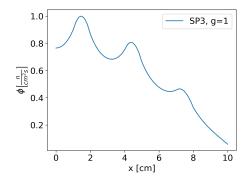


Figure: Scalar flux over line at y=4.5 cm.

#### C5 MOX Benchmark

- Exercise defined in 1994 by OECD/NEA [4].
- Two-energy groups.
- Two-dimensional problem.
- Two types of fuel: UO<sub>2</sub>, MOX.

# C5 MOX Benchmark (2)

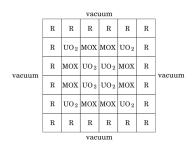


Figure: 2-D C5 MOX benchmark configuration. *R* represents the reflectors. Image reproduced from [3].

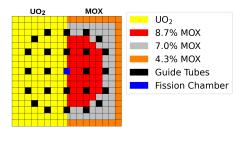


Figure: Structure of the UO2 and MOX assemblies.

# C5 MOX Benchmark (3)



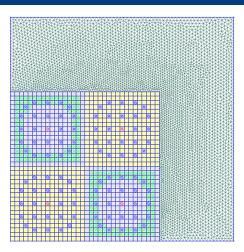


Figure: Gmsh 2D mesh.

# C5 MOX Benchmark (4)

If the higher order information of the scattering cross-section is not available (no correction):

$$D_{0,g} = \frac{1}{3\Sigma_{1,g}} = \frac{1}{3\Sigma_{t,g}} \tag{19}$$

The definition of the benchmark [4] recommends applying the diagonal transport correction:

$$D_{0,g} = \frac{1}{3\Sigma_{tr,g}}$$

$$\Sigma_{tr,g} = \Sigma_{t,g} - \bar{\mu}_g \Sigma_{s0,g}$$
(20)

where

 $\Sigma_{tr,g}=$  group g transport cross-section  $ar{\mu}_g=$  group g average cosine deviation angle.

# C5 MOX Benchmark (5)

	C5G2 Benchmark	Cer	berus
Case	$k_{Ref}$	$k_{SP_3}$	$\Delta_ ho$ [pcm]
No correction Transport correction	0.96969 0.93755	0.97106 0.93792	145 43

# C5 MOX Benchmark (6)

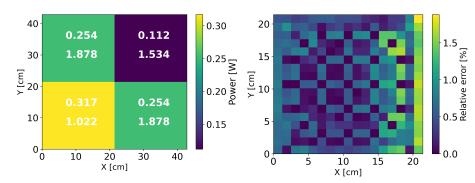


Figure: Assembly power distribution. Top: Assembly power. Bottom: Pin power relative difference expressed in %.

Figure: MOX assembly pin power relative difference expressed in %.

### C5 MOX Benchmark (7)

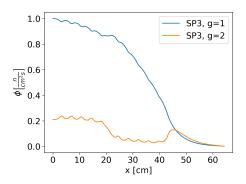


Figure: Scalar flux at y=10.71cm.

- 3D mini-core variation of the C5 MOX benchmark introduced by Ryu et al., 2013 [7].
- Two-energy group.
- Three-dimensional problem.
- Three materials: UO<sub>2</sub>, MOX, and reflector.

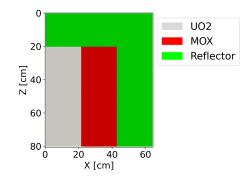


Figure: Axial layout of the C5G2 3D Benchmark.

# C5 MOX 3D (2)

Table: Eigenvalue comparison.

k <sub>Ref</sub>	k <sub>SP3</sub>	$\Delta_{ ho}$
0.91974	0.91979	6

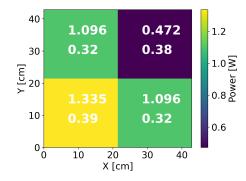


Figure: Power distribution in the C5G2 3D Benchmark. Top: power distribution. Bottom: relative difference expressed in %.

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- Implemented the kernels to solve the steady-state SP<sub>3</sub> equations in the MOOSE-based application Cerberus.
- Conducted three exercises whose reference results were known:
  - First exercise: Eigenvalue difference of 12 pcm.
  - Second exercise:
    - Eigenvalue difference of 145 pcm.
    - Pin power distribution within 2% difference.
    - Third exercise:
      - Eigenvalue difference of 6 pcm.
      - Assembly power distribution within 1% difference.
- Transport correction is necessary when the scattering higher moments are unknown.
- Future work may develop new applications or integrate this application to other physics solvers.

### Acknowledgement

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# Thank you. Questions?

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