

Optimization

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Problems with inequality constraints

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{subject to} & h_i(x) = 0, \quad i = 1, \dots, m, \\ & g_j(x) \leq 0, \quad j = 1, \dots, p\end{array}$$

where $h_i : \mathbb{R}^n \rightarrow \mathbb{R}$ for $i = 1, \dots, m$, $m \leq n$ and $g_j : \mathbb{R}^n \rightarrow \mathbb{R}$ for $j = 1, \dots, p$ are given functions.

Definition

Assume x^* is a feasible point. An inequality constraint $g_j(x) \leq 0$ is said to be active at x^* if $g_j(x^*) = 0$. It is inactive at x^* if $g_j(x^*) < 0$.

Definition

Let x^* be a feasible point, i.e. $h_i(x^*) = 0$, $i = 1, \dots, m$ and $g_j(x^*) \leq 0$, $j = 1, \dots, p$ and let $J(x^*)$ be the index set of active inequality constraints

$$J(x^*) = \{j : g_j(x^*) = 0\}.$$

We will say that x^* is a regular point if the vectors

$$\nabla h_i(x^*), i = 1, \dots, m, \nabla g_j(x^*), j \in J(x^*)$$

are linearly independent.

Example

Consider the following constraints on \mathbb{R}^2

$$h(x_1, x_2) = x_1 - 2 = 0 \quad \text{and} \quad g(x_1, x_2) = (x_2 + 1)^3 \leq 0.$$

Find the set of feasible points. Are the feasible points regular?

Let's introduce the Lagrangian function $\mathcal{L} : \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^p \rightarrow \mathbb{R}$, given by

$$\mathcal{L}(x, \lambda, \mu) = f(x) + \sum_{i=1}^m \lambda_i h_i(x) + \sum_{j=1}^p \mu_j g_j(x).$$

Theorem (Karush-Kuhn-Tucker (KKT) Theorem)

Let x^ be a local minimizer of $f : \mathbb{R}^n \rightarrow \mathbb{R}$ subject to $h(x) = 0$, $h : \mathbb{R}^n \rightarrow \mathbb{R}^m$, $m \leq n$, $g(x) \leq 0$, $g : \mathbb{R}^n \rightarrow \mathbb{R}^p$. Assume f , h_i , $i = 1, \dots, m$ and g_j , $j = 1, \dots, p$ are continuously differentiable functions and x^* is a regular point. Then, there exists $\lambda^* \in \mathbb{R}^m$ and $\mu^* \in \mathbb{R}^p$ such that*

- $\mu_j^* \geq 0$, for $j = 1, \dots, p$,
- $\frac{\partial \mathcal{L}}{\partial x_i}(x^*, \lambda^*, \mu^*) = 0$, for $i = 1, \dots, n$,
- $\mu_j^* g_j(x^*) = 0$, for $j = 1, \dots, p$.

Theorem (Karush-Kuhn-Tucker (KKT) Theorem)

Let x^* be a local maximizer of $f : \mathbb{R}^n \rightarrow \mathbb{R}$ subject to $h(x) = 0$, $h : \mathbb{R}^n \rightarrow \mathbb{R}^m$, $m \leq n$, $g(x) \leq 0$, $g : \mathbb{R}^n \rightarrow \mathbb{R}^p$. Assume f , h_i , $i = 1, \dots, m$ and g_j , $j = 1, \dots, p$ are continuously differentiable functions and x^* is a regular point. Then, there exists $\lambda^* \in \mathbb{R}^m$ and $\mu^* \in \mathbb{R}^p$ such that

- $\mu_j^* \leq 0$, for $j = 1, \dots, p$,
- $\frac{\partial \mathcal{L}}{\partial x_i}(x^*, \lambda^*, \mu^*) = 0$, for $i = 1, \dots, n$,
- $\mu_j^* g_j(x^*) = 0$, for $j = 1, \dots, p$.

Example

Consider the following optimization problem:

$$\begin{array}{ll}\text{minimize} & x_1^2 + x_2^2 \\ \text{subject to} & x_1 + x_2 \geq 5, \\ & x_1^3 \geq 1, \\ & x_2^2 \geq 4.\end{array}$$

- a. Solve the problem geometrically.
- b. Is it possible that the point $x^* = [2, 3]^T$ is a local minimizer of the formulated problem?

Theorem (Second Order Necessary Condition SONC)

Let x^* be a local minimizer of $f : \mathbb{R}^n \rightarrow \mathbb{R}$ subject to $h(x) = 0$, $h : \mathbb{R}^n \rightarrow \mathbb{R}^m$, $m \leq n$, $g(x) \leq 0$, $g : \mathbb{R}^n \rightarrow \mathbb{R}^p$. Assume f , h_i , $i = 1, \dots, m$ and g_j , $j = 1, \dots, p$ are twice continuously differentiable functions and x^* is a regular point. Then, there exist $\lambda^* \in \mathbb{R}^m$ and $\mu^* \in \mathbb{R}^p$ such that

- $\mu_j^* \geq 0$, for $j = 1, \dots, p$,
- $\frac{\partial \mathcal{L}}{\partial x_i}(x^*, \lambda^*, \mu^*) = 0$, for $i = 1, \dots, n$,
- $\mu_j^* g_j(x^*) = 0$, for $j = 1, \dots, p$,
- $\nabla^2 \mathcal{L}(x^*, \lambda^*, \mu^*)$ is positive semidefinite on $TS(x^*)$

$$TS(x^*) = \{y \in \mathbb{R}^n : y^T \nabla h_i(x^*) = 0, i = \overline{1, m}, y^T \nabla g_j(x^*) = 0, j \in J(x^*)\},$$

i.e. for all $y \in TS(x^*)$, $y^T \nabla^2 \mathcal{L}(x^*, \lambda^*, \mu^*) y \geq 0$.

Example

Use SONC to find all possible local minimizers of the following optimization problem:

$$\begin{array}{ll}\text{minimize} & x_1^2 + x_2^2 \\ \text{subject to} & x_1 + x_2 \geq 5, \\ & x_1 \geq 0, \\ & x_2 \geq 0.\end{array}$$

$$J(x^*, \mu^*) = \{j : g_j(x^*) = 0, \mu_j^* > 0\}$$

$$TS(x^*, \mu^*) = \{y \in \mathbb{R}^n : y^T \nabla h_i(x^*) = 0, i = \overline{1, m}, y^T \nabla g_j(x^*) = 0, j \in J(x^*, \mu_j^*)\}$$

Theorem (Second Order Sufficient Condition SOSC)

Suppose $f, h_i, i = \overline{1, m}, g_j(x), j = \overline{1, p}$ are twice continuously differentiable functions on \mathbb{R}^n and there exist a point $x^* \in \mathbb{R}^n$ satisfying $h_i(x^*) = 0, i = \overline{1, m}, g_j(x^*) \leq 0, j = \overline{1, p}, \lambda^* \in \mathbb{R}^m$ and $\mu^* \in \mathbb{R}^p$ such that:

- $\mu_j^* \geq 0$ for $j = 1, \dots, p,$
- $\frac{\partial \mathcal{L}}{\partial x_i}(x^*, \lambda^*, \mu^*) = 0$ for $i = 1, \dots, n,$
- $\mu_j^* g_j(x^*) = 0$ for $j = 1, \dots, p,$
- $\nabla^2 \mathcal{L}(x^*, \lambda^*, \mu^*)$ is positive definite on $TS(x^*, \mu^*),$ i.e. for all $y \in TS(x^*, \mu^*), y \neq 0, y^T \nabla^2 \mathcal{L}(x^*, \lambda^*, \mu^*) y > 0.$

then x^* is a strict local minimizer of f subject to $h_i(x) = 0, i = 1, \dots, m$ and $g_j(x) \leq 0, j = \overline{1, p}.$

Example

Consider the following optimization problem:

$$\begin{array}{ll}\text{maximize} & -(x_1 - 1)^2 - x_2 - e^{x_3^2} \\ \text{subject to} & x_2 - x_1 = 1, \\ & x_1 + x_2 \leq 2, \\ & x_3 \geq 0.\end{array}$$