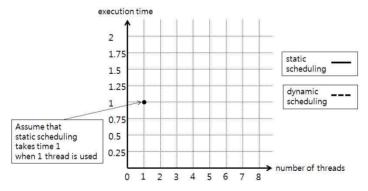
2014.1 Multicore Computing Final Exam (June 17th 11am-12pm)

supervisor	
signature	

StudentID#: (), Name: ()

- * You may answer in either Korean or English.
- 1. (18points) Fill out the blanks (a)~(n) with the most appropriate English words.
- In CUDA, threads within a block can cooperate through (a.
- In CUDA, (b.) is a group of threads where multiprocessor executes the same instruction at each clock cycle.
- (c.) is the ability of a system, network, or process to handle a growing amount of work in a capable manner or its ability to be enlarged to accommodate that growth.
- Main advantages of PSRS (Parallel Sorting by Regular Sampling) over parallel quicksort and hyper-quicksort algorithms, are
 - Better (d.)
 - Repeated communications of a same value are avoided
 - The number of processes does not have to be (e.), which is required by the other two algorithms.
- [In OpenMP] By default, all variables declared outside a parallel block are shared variables except (f.
- 2. (30points) Project 2 in our class was to write 'C with OpenMP' codes that compute the number of prime numbers between 1 and 200000 using static scheduling and dynamic scheduling just like the source code below.

```
#include <omp.h>
                                               int main () {
                                                  int i, NUM THREADS;
#include <stdio.h>
#include <stdlib.h>
                                                  int counter=0;
                                                  printf("number of threads: ");
#define NUM END 200000
                                                  scanf("%d", &NUM_THREADS);
int isPrime(int x){
                                                  omp set num threads (NUM THREADS);
   int i;
                                                  #pragma omp parallel
   if(x<=1) return 0;
   for(i=2; i<x; i++)
                                                      #pragma omp for (c)
                                                                                                 schedule ( static or dynamic )
      if((x%i == 0)&&(i!=x)) return 0;
                                                      for (i=0; i<=NUM END; i++) {
   return 1:
                                                         if(isPrime(i)) counter++:
Example of Execution Output Result:
                        <---- user input
number of threads: 2
                                                  printf("Answer: %d\n", counter);
                                                  return 0:
Answer: 17984
```



(b) Explain why you drew the graph like above for static scheduling curve and dynamic scheduling curve. Your answer should include explanation on the performance characteristics of the two methods with respect to different number of threads and explanation on why such performance characteristics are achieved.

```
static scheduling curve : (dynamic scheduling curve : (
```

(c) Fill out the blank (c) with the most appropriate codes in the above source code. Your answer:

```
3. (14points) Answer to following questions.
```

(a) What is GPGPU? Explain. (

(b) What does a CUDA synchronization(동기화) function __syncthreads() do? Explain with sufficient details. (Be specific!)

4. (8points) Fill out the blanks in the following pseudo-code for parallel merge algorithm that takes two sorted array $T[p_1..r_1]$ and $T[p_2..r_2]$ as input, and merge them into one sorted array $A[p_3..]$ as output, which is executed in parallel.

```
\operatorname{Par-Merge}(T, p_1, r_1, p_2, r_2, A, p_3)
1. n_1 \leftarrow r_1 - p_1 + 1, n_2 \leftarrow r_2 - p_2 + 1
2. if n_1 < n2 then
          p_1 \leftrightarrow p_2, r_1 \leftrightarrow r_2, n_1 \leftrightarrow n_2
4. if n_1 = 0 then return
5. else
           q_1 \leftarrow \lfloor (p_1 + r_1)/2 \rfloor
7.
           q_2 \leftarrow (a)
                                                                         (T[q_1], T, p_2, r_2)
           q_3 \leftarrow p_3 + (q_1 - p_1) + (q_2 - p_2)
           A[q_3] \leftarrow T[q_1]
           spawn (b)
                                                                             (\mathit{T}, p_1, q_1 - 1, p_2, q_2 - 1, A, p_3)
1.0
                                                                             (T,q_1+1,r_1,q_2+1,r_2,A,q_3+1)
11.
                        (c)
12.
           svnc
```

6.(30points) Consider following C and CUDA code that adds two vectors using many-core GPU. Write a CUDA kernel function add in the box (a) that can handle vectors with arbitrary size 'vec_size'. Insert appropriate code into the box (b) for CUDA kernel function call. Assume that kernel function call 'add' should generate 128 threads per block.

```
#include <stdio.h>
                                                                                       void vector_init(int* x, int size)
#include <stdlib.h>
#define THREAD NUM 128 // CUDA kernel 'add' should generate 128 threads per block
                                                                                              int i:
                                                                                              for (i=0;i<size;i++) {
  global__ void add(int *a, int *b, int *c, int vec_size) {
                                                                                                     x[i]=i;
  (a)
                                                                                       Example of Execution Output Result:
                                                                                                                <---- user input
                                                                                       vector size: 1234567
                                                                                       a[0]=0 , b[0]=0 , c[0]=0
int main(void) {
                                                                                       a[1]=1 , b[1]=1 , c[1]=2
      int N, *a, *b, *c, *d a, *d b, *d c;
                                                                                       a[2]=2 , b[2]=2, c[2]=4
      printf("vector size :");
                                                                                       a[3]=3 , b[3]=3, c[3]=6
      scanf("%d",&N); // get the size of vectors as a user input from keyboard
                                                                                       a[4]=4 , b[4]=4 , c[4]=8
                                                                                       a[5]=5 , b[5]=5, c[5]=10
       // Alloc space for device copies of a, b, c
                                                                                       a[6]=6 , b[6]=6, c[6]=12
       cudaMalloc((void **)&d a, N*sizeof(int));
      cudaMalloc((void **)&d_b, N*sizeof(int));
                                                                                       a[7]=7 , b[7]=7 , c[7]=14
                                                                                       a[8]=8 , b[8]=8, c[8]=16
       cudaMalloc((void **)&d c, N*sizeof(int));
                                                                                       a[9]=9 , b[9]=9, c[9]=18
                                                                                       a[10]=10 , b[10]=10, c[10]=20
      // Alloc space for host copies of a, b, c and setup input values
                                                                                       a[11]=11 , b[11]=11, c[11]=22
       a = (int *)malloc(N*sizeof(int)); vector_init(a, N);
                                                                                       a[12]=12, b[12]=12, c[12]=24
       b = (int *)malloc(N*sizeof(int)); vector_init(b, N);
       c = (int *)malloc(N*sizeof(int));
       // Copy inputs to device
                                                                                       a[1234564]=1234564 , b[1234564]=1234564,
       cudaMemcpy(d_a, a, N*sizeof(int), cudaMemcpyHostToDevice);
                                                                                       c[1234564]=2469128
       cudaMemcpy(d_b, b, N*sizeof(int), cudaMemcpyHostToDevice);
                                                                                       a[1234565]=1234565 , b[1234565]=1234565,
                                                                                       c[1234565]=2469130
       add
            (b)
                                                                                       a[1234566]=1234566 , b[1234566]=1234566,
                                                                                       c[1234566]=2469132
       // Copy result back to host
       cudaMemcpy(c, d c, N*sizeof(int), cudaMemcpyDeviceToHost);
       for (int i=0; i<N; i++)
             printf("a[\$d]=\$d \ , \ b[\$d]=\$d, \ c[\$d]=\$d\n", i, a[i], i, b[i], i, c[i]);
       free(a); free(b); free(c); cudaFree(d a); cudaFree(d b); cudaFree(d c);
       return 0:
```