Genetic sequence alignment acceleration using a FPGA based platform

What methods can be used to accelerate the Smith-Waterman algorithm for genetic sequence alignment with an FPGA equipped platform?

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Summary

De (korte) samenvatting, toegankelijk voor een breed publiek, wordt in het Nederlands geschreven en bevat **maximum 3500 tekens**. Deze samenvatting moet ook verplicht opgeladen worden in KU Loket.

Abstract

Het extended abstract of de wetenschappelijke samenvatting wordt in het Engels geschreven en bevat **500 tot 1.500 woorden**. Dit abstract moet **niet** in KU Loket opgeladen worden (vanwege de beperkte beschikbare ruimte daar).

Keywords: Voeg een vijftal keywords in (bv: Latex-template, thesis, ...)

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List of symbols

Maak een lijst van de gebruikte symbolen. Geef het symbool, naam en eenheid. Gebruik steeds SI-eenheden en gebruik de symbolen en namen zoals deze voorkomen in de hedendaagse literatuur en normen. De symbolen worden alfabetisch gerangschikt in opeenvolgende lijsten: kleine letters, hoofdletters, Griekse kleine letters, Griekse hoofdletters. Onderstaande tabel geeft het format dat kan ingevuld en uitgebreid worden. Wanneer het symbool een eerste maal in de tekst of in een formule wordt gebruikt, moet het symbool verklaard worden. Verwijder deze tekst wanneer je je thesis maakt.

b	Breedte	$[mm]$
A	Oppervlakte van de dwarsdoorsnede	$[mm^2]$
c	Lichtsnelheid	$[m/s]$

List of abbreviations

Chapter 1

Introduction

Chapter 2

Background information in molecular biology

2.1 Biology and DNA

2.1.1 History of genetics and DNA

Genetics For thousands of years, humans have observed the effects of heredity and implemented their knowledge to domesticate plants and animals. However, the science behind heredity was only started to be understood since 1859 with the publication of *on the origin of species* by Charles Darwin.

Around 1865, Austrian monk and botanist Gregor Mendel, who studied at the university in Brno in the current Czech Republic, published his results on the hybridization studies of pea plants. He is often credited as being the father of modern genetics. In his findings, he implemented the role of *factors* that influence the expression of traits. These factors later became known as *genes*.

Gregor Mendel

Molecular biology In 1869, Swiss physician Friedrich Miescher discovered a microscopic substance in the pus of discarded surgical bandages. Later, in 1909, Phoebus Levene named this substance Deoxyribonucleic Acid (DNA) since it is found in the nucleus of a cell and has acidic properties.

The full structure of DNA was discovered by Francis Crick and James Watson at the Cavendish Laboratory at the University of Cambridge.

2.1.2 Structure of DNA

DNA, or Deoxyribonucleic Acid, is what stores the genetic information of all living organisms. It is the information that programs all of the activities in a cell.

Structurally, DNA is a polymer, which means each molecule is built up out of small repeating molecular units. In DNA, these units are called *nucleotides*.

RED: deoxyribose carbon sugar
BLUE: phosphate group
YELLOW: nitrogen base
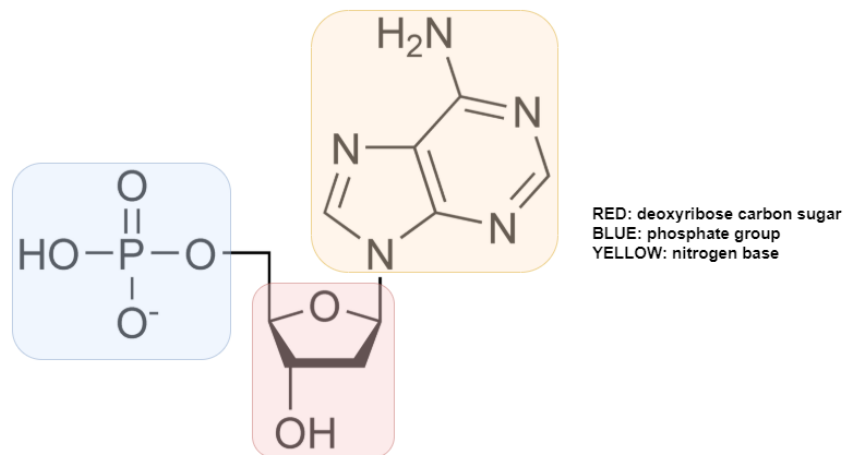
Figure 2.1: The structure of one nucleotide

Each nucleotide consists of 3 parts:

1. A carbon sugar molecule called *Deoxyribose*.

2. A phosphate group to connect the Deoxyribose molecules.

3. One of four possible nitrogen bases: Adenine (A), Thymine (T), Cytosine (C) or Guanine (G).

It is important to note that in most living organisms DNA does not exist as a single polymer, but rather a pair of molecules that are held tightly together. This is the famous *double helix*.
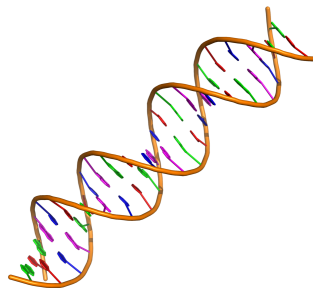
Figure 2.2: The famous double helix

Like in any good structure, there is a need for the main support. In DNA, the sugars and phosphates

bond together to form twin backbones. These sugar-phosphate bonds run down each side of the helix, but chemically in opposite directions.

The first phosphate group, at the start of the molecule, connects to the sugar group's 5th carbon. At the end of the structure, the 3rd carbon of the sugar group is unconnected. This makes a pattern typically noted as $[5' \rightarrow 3']$. Now, since the other molecule in the helix goes in the opposite direction, the pattern of the other backbone is typically noted as $[3' \rightarrow 5']$.
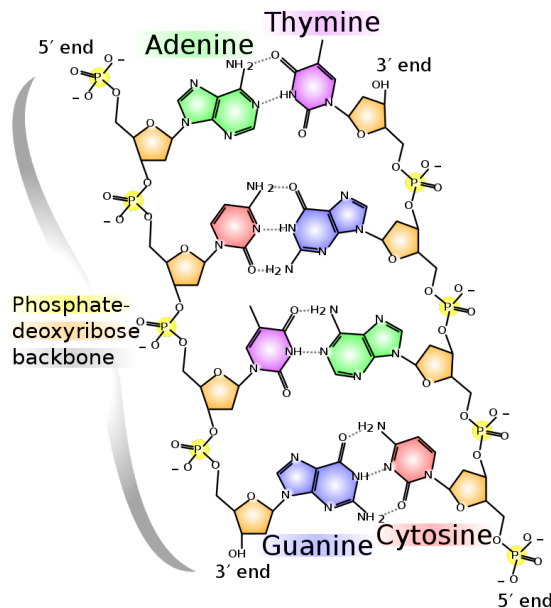
Figure 2.3: the DNA structure

These two long chains are linked together by the nitrogen bases via their relatively weak hydrogen bonds, but there can't just be any pair of nitrogen bases. Adenine can only make hydrogen bonds with Thymine. Likewise, Guanine can only bond with Cytosine. These bonded nitrogen bases are called *base paires*.

It is the order of these bases, which is also called the *sequence*, that allows this DNA to store useful information. In this way, e.g. $AGGTCCATG$ means something completely different as a base sequence than e.g. $TTCCAGATC$.

Since each of the bases in the sequence has only one possible counterpart, you can predict what its matching counterpart will be in the opposite string. For example:

If the following sequence is known

$$[5' - AGGTCCG - 3']$$

we can deduce the sequence in the other direction as

$$[3' - TCCAGGC - 5']$$

2.1.3   DNA in the human body

In human cells, DNA molecules can be found in the nucleus of all cells in the body. It consists of 46 very long molecules, which during cell division condense in what we call *chromosomes*. The only exception is in reproductive cells, which only have 23 chromosomes. These chromosomes are packed tightly together in the nucleus of the cell. If all of these chromosomes are put together, this makes about 3 billion base pairs. These 3 billion base pairs provide the assembly instructions for pretty much everything inside the cell.

These 46 chromosomes, which make up our whole DNA, are always present in pairs in the cells. Each time, the pair consists of one chromosome from each parent.

These 23 chromosome pairs are classified in:

- 22 pairs of autosomal chromosomes. These are marked 1 to 22 according to the length of the sequence. The longest chromosome (chromosome number-1) is 248,956,422 bases long. The shortest (chromosome number-22) is 50,818,468 bases long.

- In each cell, there is also an X chromosome plus an X or Y, dependent on the gender.
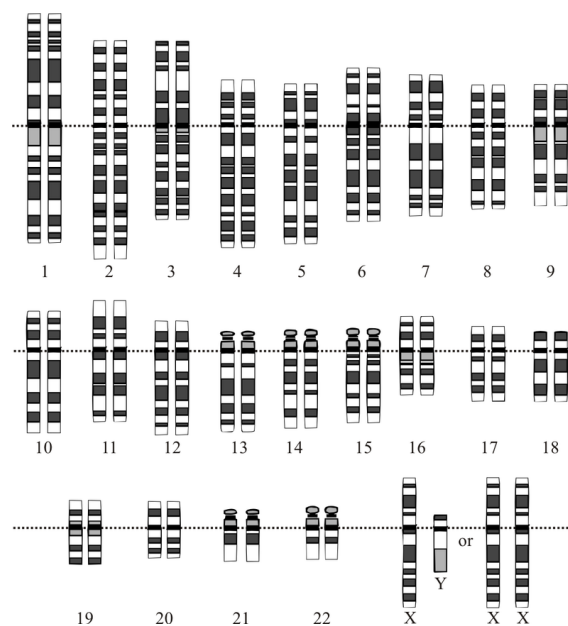
Figure 2.4: the human chromosomes

2.2   The Human Genome Project

In the field of Bioinformatics, an important dataset is the *Human Genome*. This is the full string of DNA found in the Nucleus, ordered from chromosome 1 to 22, followed by the X and Y chromosome.

In October 1990, biologists in the relatively new field of molecular biology started the Human Genome Project. The goal of this project was to determine the sequence of the 3 billion base pairs that make up human DNA. This project was completed in 2003, So nowadays we have a good idea of how the human genome is built up.

The Human Genome is easily found on the internet since it is publically available. One of the most often used is *HG19*, which was published in 2009. Since DNA has only 4 possible bases (A, T, C or G), this can be encoded in a 2-bit representation. If this encoding is used, the Human Genome is approximately 750 megabytes.

Figure 2.5: the order of the human genome

2.3 Sequencing

2.3.1 The sequencing technology

The term *Sequencing* is used for all techniques to read and decipher the DNA code from a given snippet of DNA. During the last years, the techniques that sequence human DNA has changed quite a lot. For about 15 years the *Next Generation Sequencing (NGS)* is the technique most often used. The biggest advantage of NGS, in comparison with other techniques, is the speed of the sequencing since it can sequence billions of short DNA molecules in parallel. In practice, this sequencing is most often done by the instruments of Illumina, which dominates the market (around 90% market share).

How NGS works

1. The DNA to sequence is isolated from the cells. Most often this is the whole genome.

2. The isolated DNA can now be copied enzymatically. This step is repeated until there are enough copies of the same DNA, usually this is in the millions or billions of copies.
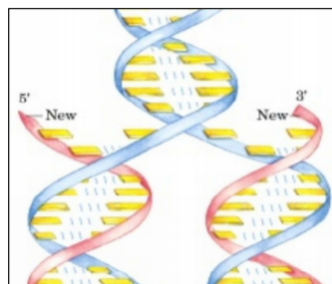
Figure 2.6: the enzymatic copying of a string of DNA. The original is unzipped, thus allowing new nucleotide bases to attach to the exposed bases.

3. The full DNA sequence is now broken apart into small DNA molecules (100 to 1000 bases long). This is done using enzymes or high-frequency sound waves.

4. Now the sequencing can start: a *flow cell* is used where these small DNA molecules can bind to a glass surface.

5. Different enzymatic and chemical reactions can now be done on this flow cell through an automatic flow of reagents. The following steps are iterated until the full read has been filled in:

   (a) The entire flowcell is filled with nucleotides, all with different nitrogen bases. Important is that at each of these nucleotides there is a fluorescent group attached to the phosphor group. This makes sure no other nucleotide can bind.

   (b) The fluorescent groups have a different color, dependent on the nitrogen base attached (A, G, T of C). At this time a camera picture of the flowcell is taken and stored.

   (c) after the flowcell is emptied of the loose nucleotides, another reagent flows in this flowcell. This reagent splits the fluorescent group from the phosphor group, so that in the next iteration a new nucleotide group can bind with the read.
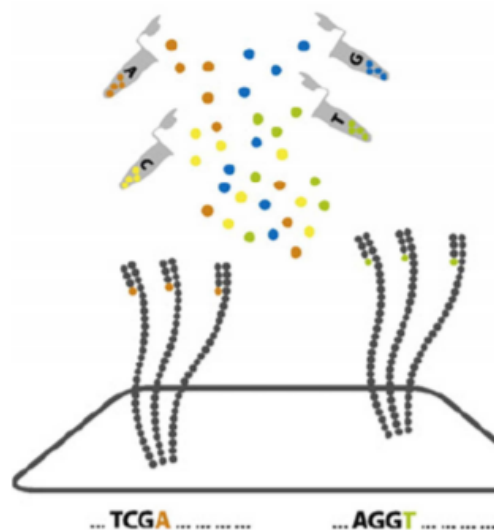
Figure 2.7: Sequencing technology used by Illumina attaches a nucleotide with a fluorescent tag to the next base in the read, captures a picture the read to determine the base, and removes the fluorescent tag so a new nucleotide group can bind in the next iteration.

6. After the whole DNA snippets have been filled in, the machine deduces the sequence in the DNA snippet. The pictures taken during the operation are in order the colors released in a specific spot, and by extent the attached nitrogen base. By the means of some image processing techniques, it is quite easy to get all the sequences in the flowcell. this is called the *Primary processing*.

Figure 2.8: From left to right is the pictures taken at each iteration in the flowcell. The color at that specific spot marks which nucleotide has been bound. With the use of some image processing techniques the exact sequence in that spot can be identified.

7. In the *secondary processing*, the sequence is trimmed by quality, etc. The operations that are done on the read in this step are outside the scope of this thesis.

As a result of the NGS, we get a file in the FASTQ format.

2.3.2   The FASTQ file format

Since the color in the camera pictures in the primary processing can have a light shift, there is a specific "uncertainty" what the base is in that spot. This is called the *quality* of the base.

The *FASTQ* file format has become the de-facto standard as output from sequencing instruments. It is a text-based format for storing both the bases in the sequence and their corresponding quality. FASTQ has become the de facto standard for storing the output of sequencing machines.

A FASTQ file uses four lines per sequence:

1. a '@' character followed by a sequence ID, plus an optional description.

2. The sequence of letters identified by the machine. This is either A, G, C, T or n when the base cannot be identified with a specific threshold certainty.

3. a '+' character, optionally followed by the sequence ID (again) and an optional description.

4. the quality values for each respective base in line 2. The length of this line must be the same as the number of bases in line 2

The quality score in memory is a value in the range $0x21$ (lowest quality) to $0x7e$ (highest quality). Since this value is represented in ASCII in the file format, this ranges from the '!' character to the '~' character. Hereunder is a complete list of the possible values of the quality score:

```
!"#$%&'()*+,-./0123456789:;<=>?@ABCDEFGHIJKLMNOPQRSTUVWXYZ
[\]^_`abcdefghijklmnopqrstuvwxyz{|}~
```

Important to note is that this quality score is logarithmic. Also, the '@' and '+' character is contained in the possible values for the score, so when implementing the interpreter for this file, this is something to look out for.

A FASTQ file containing a single sequence might look like this:

```
@SEQ_ID
GATTTGGGGTTCAAAGCAGTATCGATCAAATAGTAAATCCATTTGTTCAACTCACAGTTT
+
!''*((((***+))%%%++)(%%%%).1***-+*''))**55CCF>>>>>>CCCCCCC65
```

Keep in mind that most of the time a FASTQ file consists of multiple of these sequences, all stacked under each other.

Chapter 3

Methods for genetic sequence alignment

3.1 Genetic sequence aligning

The human genome (e.g. $HG19$) is used as a reference genome for all sequenced human DNA. However, The genetic code of all humans is slightly different. Genetic sequence alignment is the science where you try to align 2 sequences with each other so that the amount of differences is minimal. In this chapter, the most frequently used algorithms are examined.

3.1.1 Alignment in general

In genetic codes, there are 3 types of differences between the given sequence and the reference:

- Insertion: one or more bases have been added in the genetic code in a specific spot.

- Deletion: one or more bases have been removed from the genetic code in a specific spot.

- Substitution: one or more bases have been substituted by other bases.

Inserts and deletions are often described by a single term, *indel*. In literature, this is most often represented with a '$-$' character.

For example: if we want to align the following sequences:

```
Seq1: ATATCGGC
Seq2: ATCG
```

The alignment itself can now be done in different ways. Possible alignments are:

```
        Alignment 1
        Seq1: AtaTCgGc
        Seq2: A--TC-G-
        Alignment 2
        Seq1: atATCGgc
        Seq2: --ATCG--
```

Which alignment that is the actual output, depends on the algorithm and the given parameters.

Keep in mind, there is no one "correct" alignment. The core of the alignment algorithms is the same each time, but the parameters of these algorithms are changed depending on the application.

3.2 Local VS global alignment

To explain the difference between local and global alignment, we can take a look at the following example:

```
        The 2 DNA sequences:
        Seq1: TCCCAGTTTGTGTCAGGGGACACGAG
        Seq2: CGCCTCGTTTTCAGCAGTTATGTGCAGATC


        Alignment 1 :
        Seq1: -----------tccCAGTT-TGTGTCAGgggacacgag
        Seq2: cgcctcgttttcagCAGTTATGTG-CAGatc-------


        Alignment 2 :
        Seq1 : tcCCa-GTTTgt-GtCAGggg-acaC-GA-g
        Seq2 : cgCCtcGTTTtcaG-CAGttatgtgCaGAtc
```

Both alignments are valid but different. The first alignment is *locally aligned*. This means that the similarities are prioritized in the same region, with the similarity as high as possible. On the other hand, the second alignment is *globally aligned*. Here the similarities over the full length of the sequences are used for the alignment.

In practice, the local alignment is used most often, since it can give you information of 2 sequences that do not have (approximately) the same length.

3.3 Commonly used algorithms

In this section, we will take a look at some algorithms that are used most often for genetic sequence alignment.

The algorithms that are used most often are categorized in 2 ways:

- local alignment VS global alignments

- dynamic algorithms VS heuristic algorithms: dynamic algorithms are exact but slow and computationally demanding, whereas heuristic algorithms are faster but are approximations and the best alignment is not guaranteed.

Hereunder is a schematic view of some algorithms that are used in practice:

	Dynamic programming	Heuristic programming
Local alignment	Smith-waterman	FASTA, BLAST
Global alignment	Needleman-Wunsch	X

Table 3.1 Classification of genetic alignment algorithms

Keep in mind, a lot of other claimed "algorithms" (for example BFAST, ...), are accelerated versions of the Smith-Waterman algorithm.

3.3.1 Needleman-Wunsch

Needleman and Wunch proposed a new algorithm for genetic sequence alignment in 1970, now known as the *Needleman-Wunsch* (N-W) algorithm. Since this algorithm is meant for global alignment. Since global alignment is seldomly used in practice, further analysis of the algorithm will not be done. However, N-W has a lot of similarities with the Smith-Waterman algorithm, discussed in the next section.

3.3.2 Smith-Waterman

The *Smith-Waterman* (S-W) algorithm was first proposed by Temple F. Smith and Michael S. Waterman in 1981. It is a variation on (N-W), adapted for local alignment. It is a dynamic programming technique, so the optimal local alignment is guaranteed.

The core of the algorithm is a matrix fillup, with data dependencies on the previous cells. Hereunder an analysis of the algorithm:

1. Symbols used in the analysis:

   Let sequences $A = a_1 a_2 a_3 \dots a_n$ and $B = b_1 b_2 b_3 \dots b_m$ be the sequences that need to be locally aligned. Here n and m are the lengths of sequence A and B

2. Define the parameters:

   - Define $s(a,b)$ be the *similarity matrix* (sometimes also called the *substitution matrix*) for the two sequences. It is used for "rewarding" when $a_i = b_j$ and "punishing" when $a_i \neq b_j$.

In the most general way, we define the similarity score as a matrix of values, e.g.:

	A	C	G	T
A	3	-3	-3	-3
C	-3	3	-3	-3
G	-3	-3	3	-3
T	-3	-3	-3	3

Table 3.2 Similarity matrix example

Often, there are only 2 scores used (equal or not equal). In this case, the similarity matrix can be condensed as follows:

$$s(a_i, b_j) = \begin{cases} +3, & a_i = b_j \\ -3, & a_i \neq b_j \end{cases}$$

- Define d as the *gap penalty* which regulates the score for an insertion or a deletion. This parameter can be:

  - *Linear*: The penalty is constant. So, in this case, it doesn't matter e.g. the previous was also a gap.
  - *Affine*: An affine gap penalty considers gap opening and extension separately. For the sake of simplicity, this analysis will not cover it. The algorithm can be extended to include this affine gap penalty, but this would make the algorithm more complex and we would limit our ability to develop possible accelerations.

3. The initialization: We construct a scoring matrix H with dimensions $(n+1) \times (m+1)$. The first column and first row we initialize with 0.

   For example: if we want to align the sequences A = $TGTTACGG$ and B = $GGTTGACTA$:

		T	G	T	T	A	C	G	G
	0	0	0	0	0	0	0	0	0
G	0								
G	0								
T	0								
T	0								
G	0								
A	0								
C	0								
T	0								
A	0								

Table 3.3 Example of the initialization of the scoring matrix

4. Matrix fill in: We fill in the matrix using the following formula:

$$H_{ij} = max \begin{cases} H_{i-1,j-1} + s(a_i, b_j), \\ H_{i-1,j} - d, \\ H_{i,j-1} - d, \\ 0 \end{cases}$$

If we keep in mind that the value of a cell may never be lower than 0, we can represent the data dependencies in the following schematic:
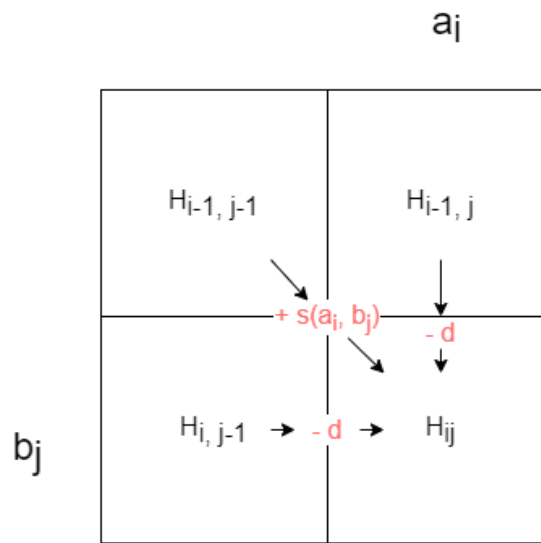

Figure 3.1: Data dependencies in the H matrix

Where $s(a,b)$ and d are the parameters of the algorithm. If we use the following values as an example:

$$s(a_i, b_j) = \begin{cases} +3, & a_i = b_j \\ -3, & a_i \neq b_j \end{cases} \qquad \text{and} \qquad d = 2$$

We can now fill up the scoring matrix H:

	T	G	T	T	A	C	G	G
0	0	0	0	0	0	0	0	0
G 0	0	3	1	0	0	0	3	3
G 0	0	3	1	0	0	0	3	6
T 0	3	1	6	4	2	0	1	4
T 0	3	1	4	9	7	5	3	2
G 0	1	6	4	7	6	4	8	6
A 0	0	4	3	5	10	8	6	5
C 0	0	2	1	3	8	13	11	9
T 0	3	1	5	4	6	11	10	8
A 0	1	0	3	2	7	9	8	7

Table 3.4 Example of a populated scoring matrix

5. Traceback: We start at the cell with the highest score in the matrix H. Starting here we only move left, up or diagonally (left-up) to the cell on which the value in the cell was based until we hit a cell with value 0.

	T	G	T	T	A	C	G	G
0	0	0	0	0	0	0	0	0
G 0	0	3	1	0	0	0	3	3
G 0	0	3	1	0	0	0	3	6
T 0	3	1	6	4	2	0	1	4
T 0	3	1	4	9	7	5	3	2
G 0	1	6	4	7	6	4	8	6
A 0	0	4	3	5	10	8	6	5
C 0	0	2	1	3	8	13	11	9
T 0	3	1	5	4	6	11	10	8
A 0	1	0	3	2	7	9	8	7

Table 3.5 Example of a traceback in S-W

From this traceback we can now deduce the following alignment:

```
GTT-AC
||||||
GTTGAC
```

This alignment is the output of our algorithm.

3.4 Problem definition

3.4.1 Mapping to a reference genome

From the sequencing machines, we get a big amount of reads in the FASTQ format. We should note that all these reads are worthless without a proper interpretation.

In most cases, the first step in the analysis of the reads is knowing from which part of the genome it is from. Typically, the read is compared with the whole genome in a local alignment, for example with the Smith-Waterman algorithm. As an output, we would get the position in the human genome and an alignment with its score (how well the sequence fits in that spot). This practice is commonly referred to as *Mapping to reference genome*.

Since the reads are 100 to 1000 bases long, and the whole human genome is approximately 3 billion bases, this comparison is computationally a very intensive task. If we analyze the S-W algorithm (as we have done in 3.3.2, we can see that the value of each cell in the matrix is only dependent on the left-upmost 3 cells. Therefore, It leads us to believe that this algorithm can be accelerated on other hardware solutions such as an FPGA (which will be discussed in chapter 4) since S-W is heavily parallelizable.

In most clinical applications where mapping to a reference genome is used, the number of reads to be compared with the genome is in the billions.
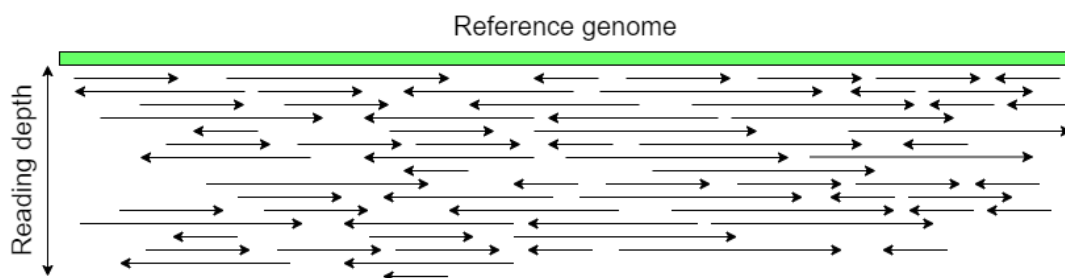

Figure 3.2: Mapping to a reference genome. The direction of the read is represented by arrows

Since the read can be from the complementary DNA molecule in the double helix, the sequences can be in forward $[5' \to 3']$ direction, or in complementary $[3' \to 5']$ direction. To transform that read to the used reference genome direction we need to perform the following changes to the read:

1. The bases should be changed to their corresponding base in the base pair;

2. The sequence should be reversed.

We have no way of knowing in which direction the read is taken, both the forward and the backward possibility should be compared with the reference and the best-aligned version of these two should be chosen.

Please note, in most normal cases we can assume the distribution of reads is practically uniform. Therefore, each base in the human genome will be covered by a statistically expected amount of reads. This amount is often referred to as the *reading depth*.

3.4.2 The sam and bam file format

As a convention, the output of mapping algorithms is in a *SAM* (Sequence Alignment Map) or *BAM* (Binary Alignment Map) file format. The BAM file format is just a compressed version of the SAM format, but the SAM format is more readable, which makes it easier for troubleshooting. There exists a lot of tools transform a SAM to BAM file already, so in this thesis we will focus on the SAM format.

//TODO

3.4.3 Clinical application

We will discuss two clinical applications of mapping to a reference genome.

1. ***NIPT* (non-invasive prenatal testing), a test for detecting genetic defects in a foetus.**
   During or After conception, DNA can be lost or gained in the fertilized egg cell. This can result in a severe syndrome of the child. For example, Down syndrome is caused by a trisomy of chromosome 21. Normally all chromosomes are present twice in each cell, one from the mother and the other from the father. In Down syndrome patients something went wrong during cell division at the very early stage of development, and the fetus has in its cells three times chromosome 21. Because chromosome 21 is quite small and does not contain that many genes, the child can survive, though with typical mental and clinical problems.

Figure 3.3: Trisomy 21 karyotype

Before high throughput DNA sequencing technologies were available like they are today, testing if a fetus has a trisomy-21 could only be done by taking a small amount of amniotic fluid (fluid around the fetus). However, to obtain this fluid there was a need for a risky invasive procedure (called *amniocentesis*) leading sometimes to termination of the pregnancy.

It is known that small amounts of DNA of the fetus are present in the blood of the mother, in the cell-free DNA (*cfDNA*) which we find in the blood plasma (the clear, aqueous part of the blood). The blood plasma is used by our body to transport 'waste', including DNA from cells that were broken down. When fetal cells die, which is a normal process, the building

blocks of these cells are transported in the plasma of the blood from the mother, included small DNA fragments from the fetus.

NIPT (non-invasive prenatal testing) is used to analyze DNA derived from the mother's blood. A large number of short cfDNA's are sequenced at random. Then, each sequence is mapped the whole human genome to find out where it comes from. Finally, the distribution of these reads is calculated. If we observed that a higher frequency of reads as compared to normal individuals coming from chromosome-21, it is almost certain that the fetus has Down's syndrome.
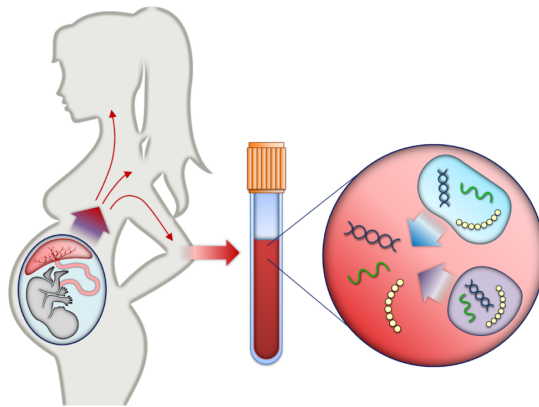

Figure 3.4: DNA of the fetus in the mothers blood

Using the same method, we can also find other defects in the number of chromosomes. For example trisomy 18 (Edwards syndrome), trisomy 13 (Patau syndrome) or even in the sex chromosomes, such as XXY (Klinefelter syndrome) or lack of a second X or a Y chromosome (Turner syndrome).

2. **Shallow whole-genome sequencing of tumor DNA.**
   It is a known fact that damaged DNA can lead to tumor development. This damage can be single bases changes but can also be loss or gain of larger DNA sequences where important genes are located. When someone is diagnosed with cancer, the knowledge of which DNA regions are lost or gained can be important to decide on treatment.

   A new technique to detect all gains and losses of DNA material in one single experiment is *sWGS* (shallow whole-genome sequencing). The technique is performed as follows: DNA from the tumor is fragmented (it is broken in small pieces, eg. by a fragmentize enzyme or by high-frequency sound). These pieces are sequenced randomly, and with a mapping algorithm to the reference genome, the over- or underrepresentation of reads (as compared with a normal sample) indicates if regions of the DNA have changed, and which regions these are.

Chapter 4

Platforms for accelerating Smith-Waterman

As we saw in the analysis of the Smith-Waterman algorithm in 3.3.2, we can see that the value of each cell in the matrix is only dependent on the left-upmost 3 cells. Therefore, It leads us to believe that this algorithm can be accelerated on other hardware solutions which are better equipped for parrallellism than a normal CPU.

4.1 Overview of possible hardware

4.1.1 CPU

4.1.2 GPU

4.1.3 FPGA

4.1.4 ASIC

4.2 Hardware selection

4.2.1 Recent advances in High Level Synthesis

4.3 Platform communication

4.3.1 USB

4.3.2 Ethernet

4.3.3 Alternatives and selection

bv. SATA, PCI, ...

Chapter 5

Initial Difficulties during the implementation

Disclaimer: This chapter is for amount of work :)

5.1 Using Vivado HLS and Xilinx SDK

5.1.1 learning HLS in examples

Ik moet nog starten met HLS, nog nooit gedaan.

learning HLS

lab1: BASIC WORKFLOW: How to make project, difference between sources and test bench, GUI and it's components, simulation, synthesis (=¿ estimate and Gantt chart), viewing resulting VHDL code, co-simulation, view simulation waveforms, IP Core export, creating multiple solutions and comparing, setting a directive (like unroll a loop).

lab2: DATA TYPES adhv FIR filter: floating point VS fixed point, saturation with fixed point, fixed point with larger internal bit-width (LSB laten vallen),

lab3: INTERFACES: - basic argument-level interfaces (ap_vld, ap_none, ap_hs) - block-level interface of pipelined component (pipeline on the top function)

lab4: ARRAYS: Sequential, pipelining internal loop, rewind parameter, top function pipelining, array map, array partition (cyclic and complete), array reshape technique

5.1.2 Learning how to program target board

hello world via Xilinx SDK =¿ baremetal -¿ zelf kiezen waar uitgevoerd + dataverplaatsingen zelf implementeren

5.2 SDSoC

Op een Linuxdistributie.

Snel functie verplaatsen van PS naar PL.

gebruikt ook delen van HLS

5.2.1 learning process on matrix multiplication example in SDSoC

Eerste test: matrixmultiplicatie

lab1: INTRODUCTION: basic workflow, working with hardware accelerators, running the project, ...

lab2: performance estimation: rescource utilization, comparing software and hardware implementations, overall speedup comparison (all using LINUX hosted)

lab3:

lab4:

lab5:

lab6:

lab7:

lab8:

Chapter 6

Initial approach with pure Smith-Waterman

6.1 The concept

6.2 System implementation

6.3 Possible initial speedups

6.4 Problems with this initial approach

computational complexity: O(mn)

Chapter 7

Acceleration idea: BFAST algorithm

7.1 BFAST algorithm

7.2 System implementation

7.3 Speedups

Chapter 8

Implementation results

…

Chapter 9

Conclusion and future research

Bibliography

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Appendix A

Uitleg over de appendices

Bijlagen worden bij voorkeur enkel elektronisch ter beschikking gesteld. Indien essentieel kunnen in overleg met de promotor bijlagen in de scriptie opgenomen worden of als apart boekdeel voorzien worden.

Er wordt wel steeds een lijst met vermelding van alle bijlagen opgenomen in de scriptie. Bijlagen worden genummerd het een drukletter A, B, C,...

Voorbeelden van bijlagen:

Bijlage A: Detailtekeningen van de proefopstelling

Bijlage B: Meetgegevens (op USB)

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