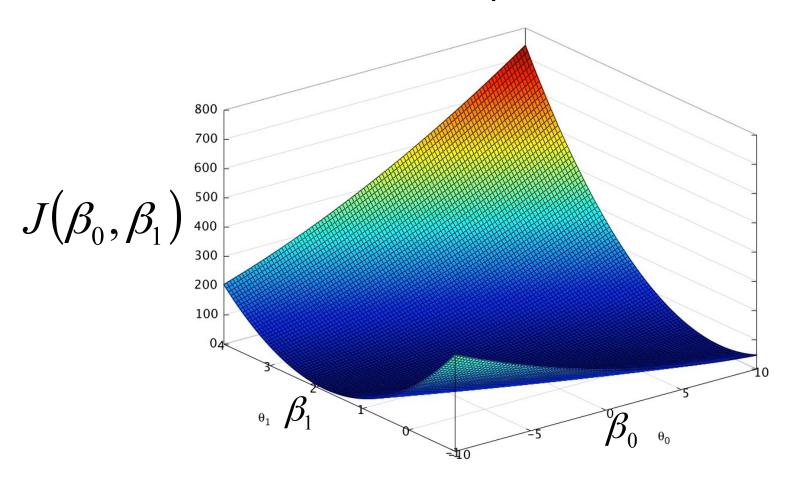
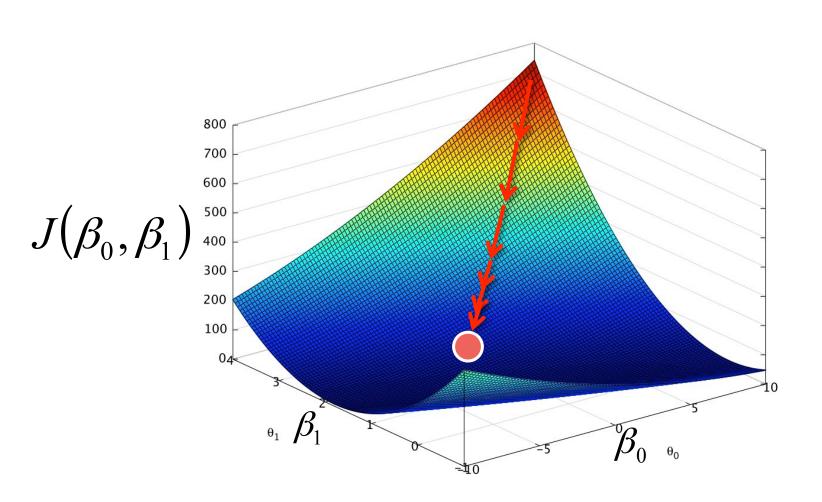
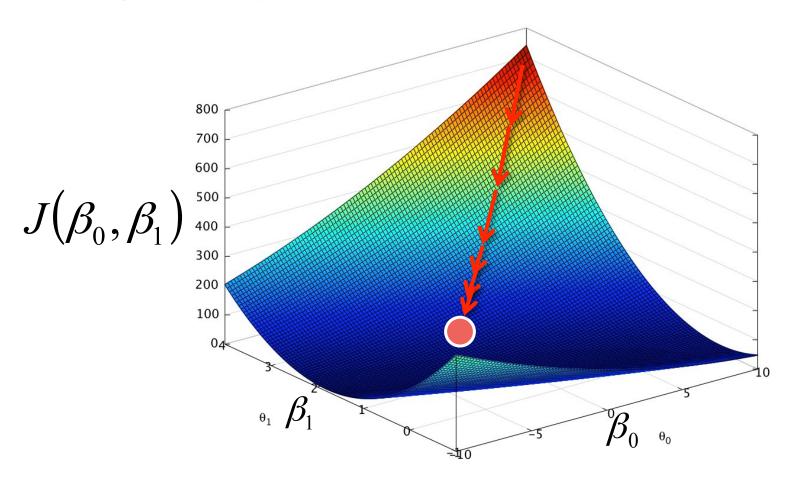


## Start with a cost function $J(\beta)$ :

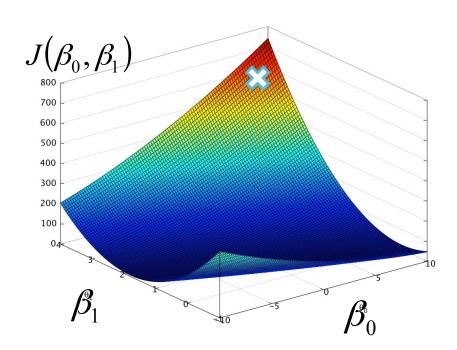




Then gradually move to the minimum.

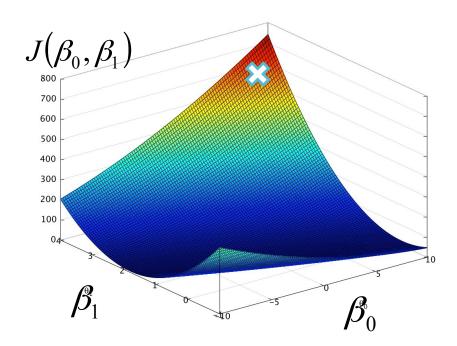


How can we do this?



How can we do this? (without seeing the graph of  $J(\beta)$ !)

Start with the function  $J(\beta)$ :

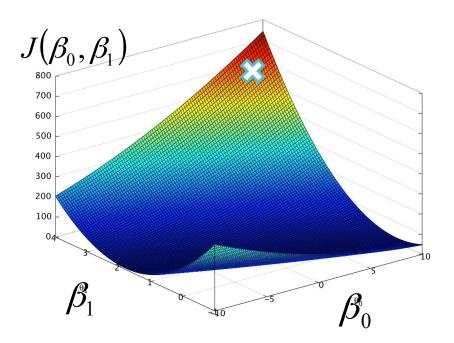


# How can we do this?

(without seeing the graph of  $J(\beta)$ !)

## Start with the function $J(\beta)$ :

$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

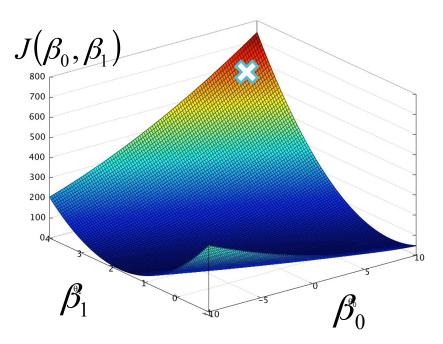


How can we do this? (without seeing the graph of  $J(\beta)$ !)

Start with the function  $J(\beta)$ :

$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

and compute its gradient vector  $\nabla J(\beta)$ .



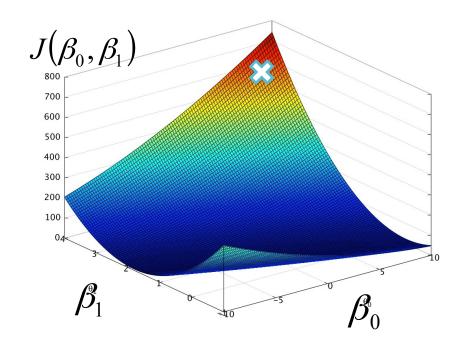
How can we do this? (without seeing the graph of  $J(\beta)$ !)

Start with the function  $J(\beta)$ :

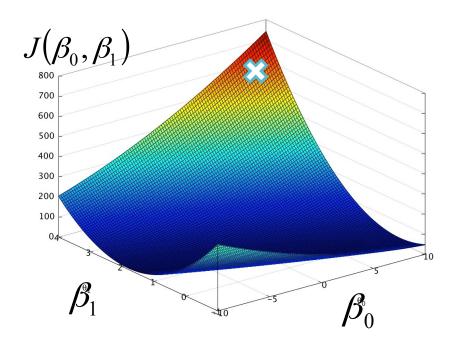
$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

and compute its gradient vector  $\nabla J(\beta)$ .

The gradient points in the "direction of maximum increase" of J.

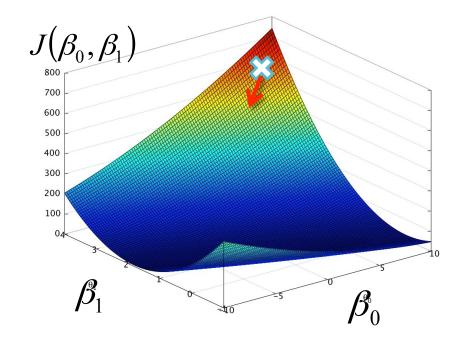


$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$



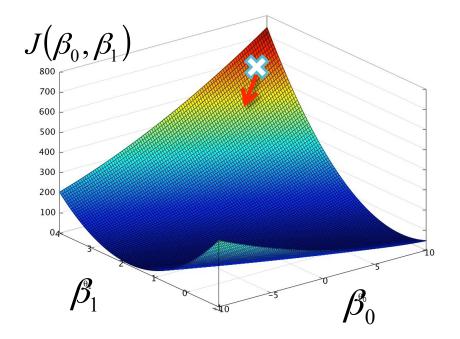
$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

$$w_1 = w_0 - \alpha \nabla \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$



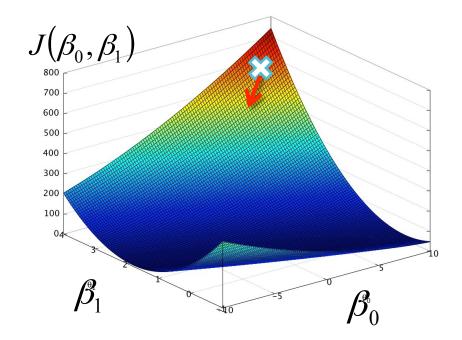
$$J(\beta_{0}, \beta_{1}) = \sum_{i=1}^{m} \left( (\beta_{0} + \beta_{1} x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^{2}$$

$$w_{1} = w_{0} - \alpha \left( \frac{\partial}{\partial \beta_{0}}, \dots, \frac{\partial}{\partial \beta_{n}} \right) \sum_{i=1}^{m} \left( (\beta_{0} + \beta_{1} x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^{2}$$



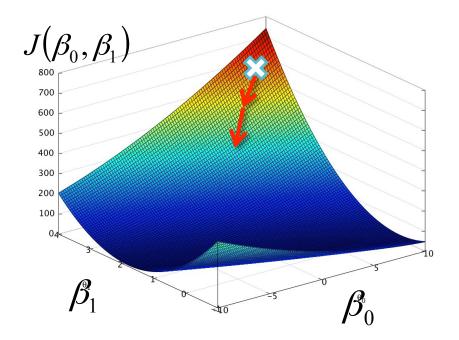
$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

$$w_1 = w_0 - \alpha \nabla \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$



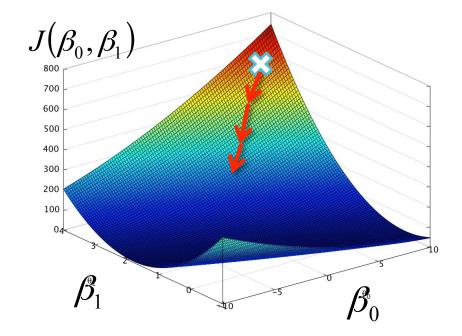
$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

$$w_2 = w_1 - \alpha \nabla \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$



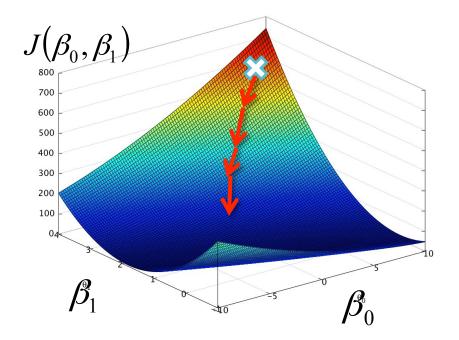
$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

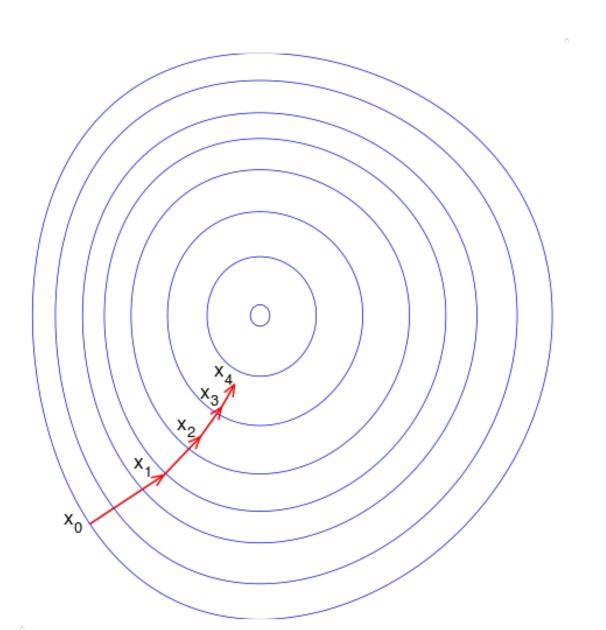
$$w_3 = w_2 - \alpha \nabla \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

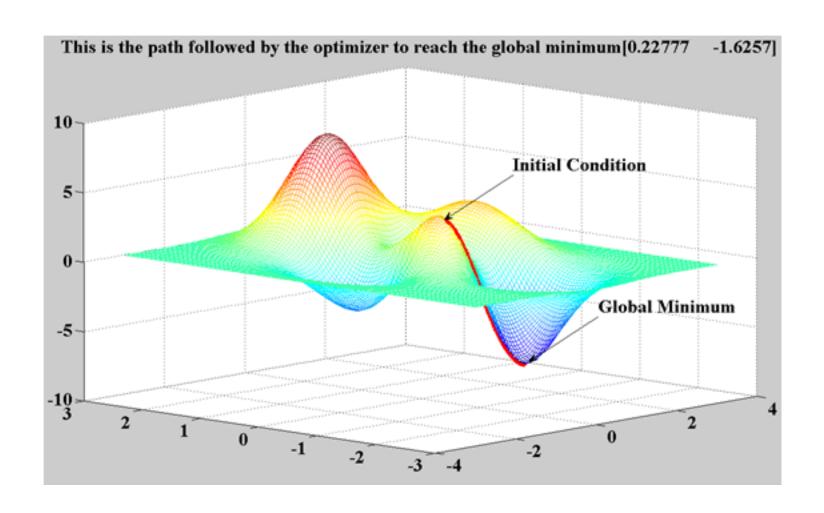


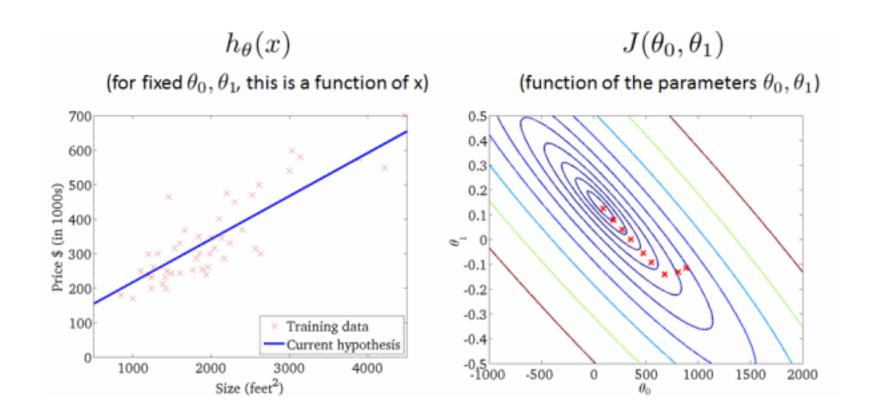
$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

$$w_4 = w_3 - \alpha \nabla \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

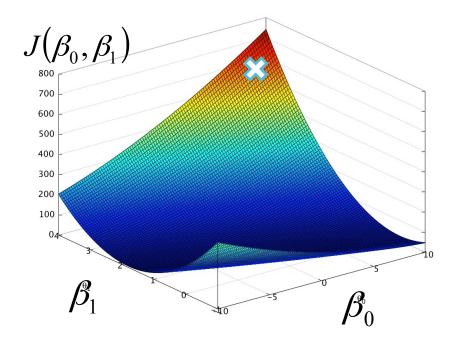




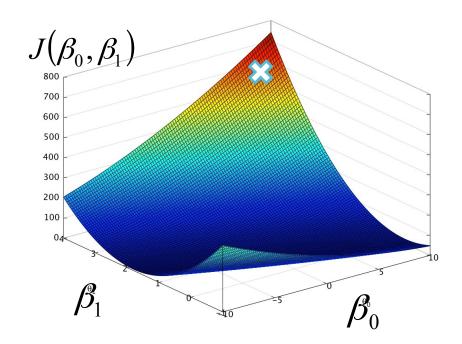




$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

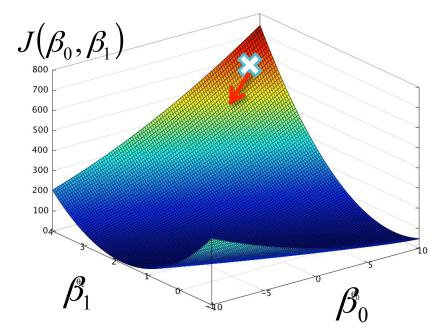


$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$



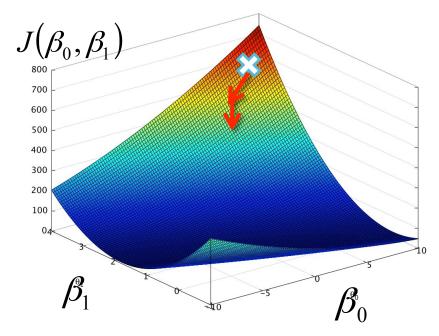
$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

$$w_1 = w_0 - \alpha \nabla \left( (\beta_0 + \beta_1 x_{obs}^{(0)}) - y_{obs}^{(0)} \right)^2$$



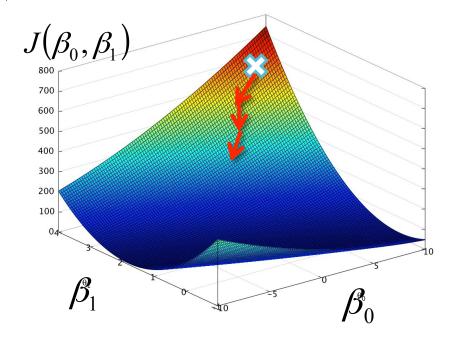
$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

$$w_2 = w_1 - \alpha \nabla \left( (\beta_0 + \beta_1 x_{obs}^{(1)}) - y_{obs}^{(1)} \right)^2$$



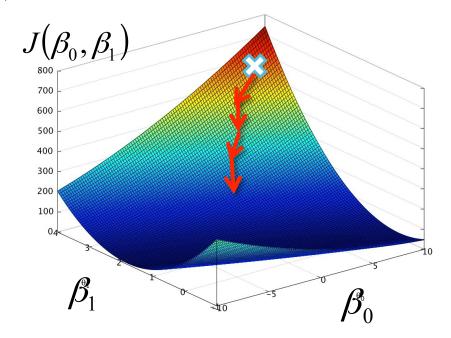
$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

$$w_3 = w_2 - \alpha \nabla \left( (\beta_0 + \beta_1 x_{obs}^{(2)}) - y_{obs}^{(2)} \right)^2$$



$$J(\beta_0, \beta_1) = \sum_{i=1}^{m} \left( (\beta_0 + \beta_1 x_{obs}^{(i)}) - y_{obs}^{(i)} \right)^2$$

$$w_4 = w_3 - \alpha \nabla \left( (\beta_0 + \beta_1 x_{obs}^{(3)}) - y_{obs}^{(3)} \right)^2$$



#### Faster

Derivative of single point at each step (instead of 100K)

## **Online Training**

Only need to keep single point in memory
No need to store 100K rows, large data no problem

## **Covers Many Algorithms**

Gradient Descent is the bottleneck for linear algorithms Can do Linear Regression, Logistic Regression, SVMs

## **Some Implementations**

## Some Implementations

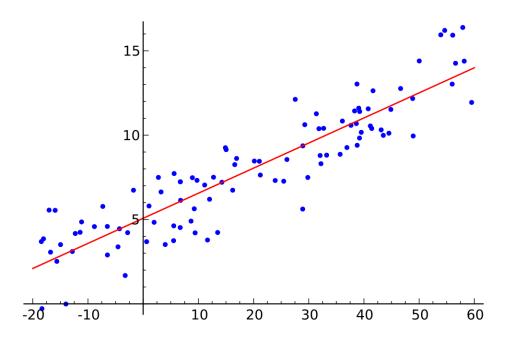
from sklearn.linear\_model import SGDRegressor

from sklearn.linear\_model import SGDClassifier

## from sklearn.linear\_model import SGDRegressor

#### from sklearn.linear\_model import SGDRegressor

SGDRegressor(loss='squared\_loss')

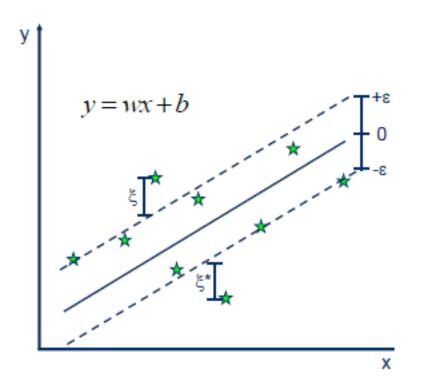


Sum of squared errors

squared loss == Linear Regression

#### from sklearn.linear\_model import SGDRegressor

SGDRegressor(loss='epsilon\_insensitive')

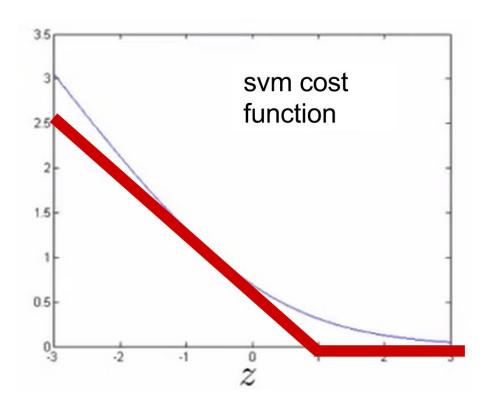


Best loss name ever

epsilon insensitive loss == SVM Regression

SGDClassifier(loss='hinge')

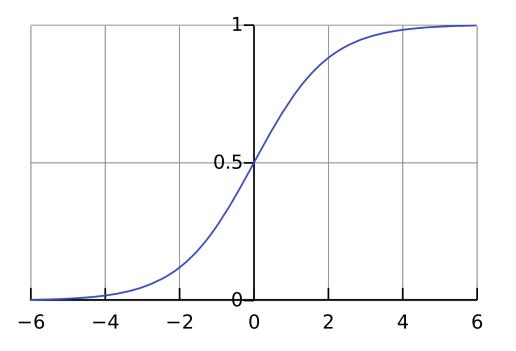
SGDClassifier(loss='hinge')



Looks like a hinge.

hinge loss == SVM

SGDClassifier(loss='log')



This one's kind of clear

log loss == Logistic Regression

```
SGDClassifier(alpha=0.0001, penalty='l2', l1_ratio=0.15)
```

Regularization parameters
Penalty values: '11', '12', 'elasticnet'