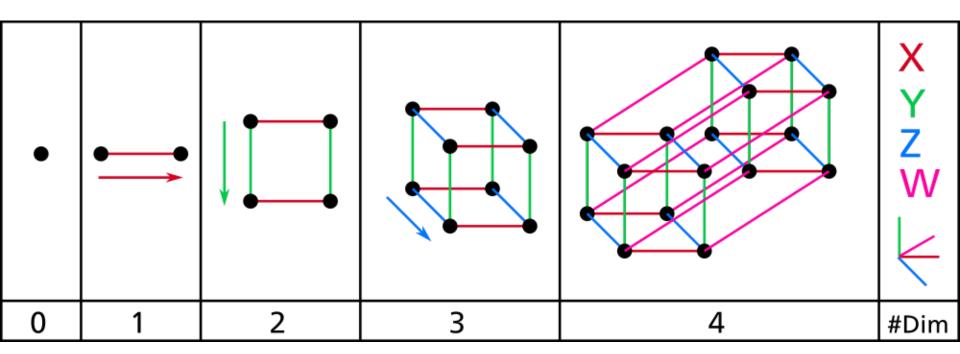
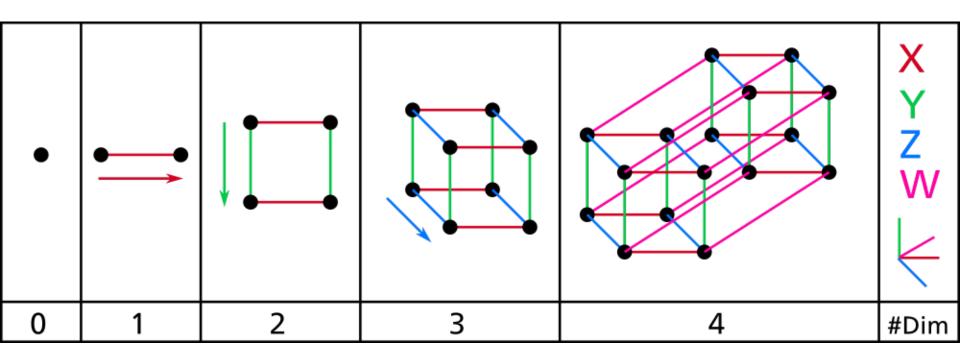
# Dimensionality Reduction



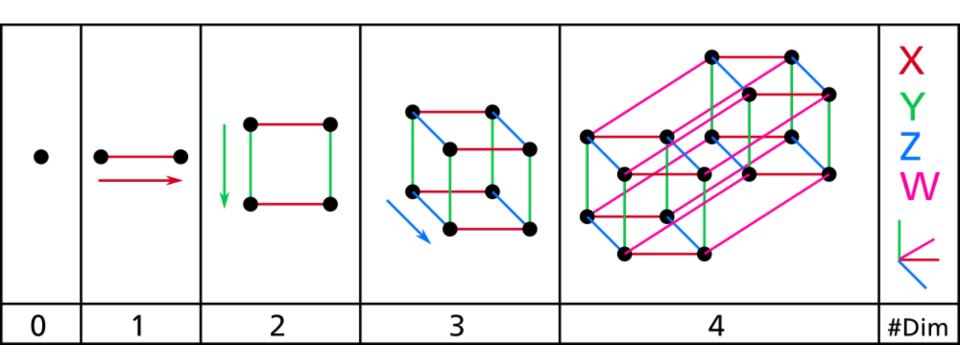




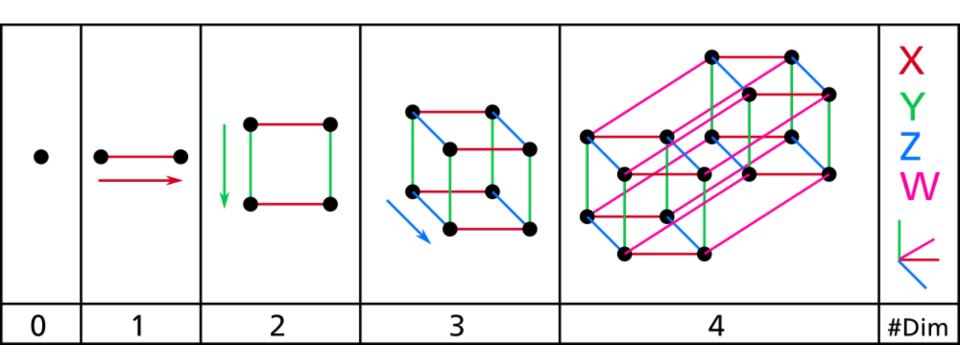
#### One dimension:

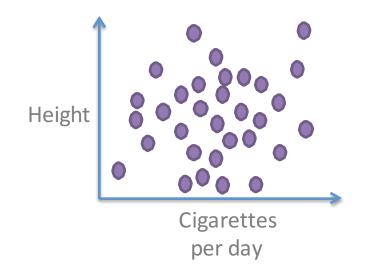
Small space Being close quite probable





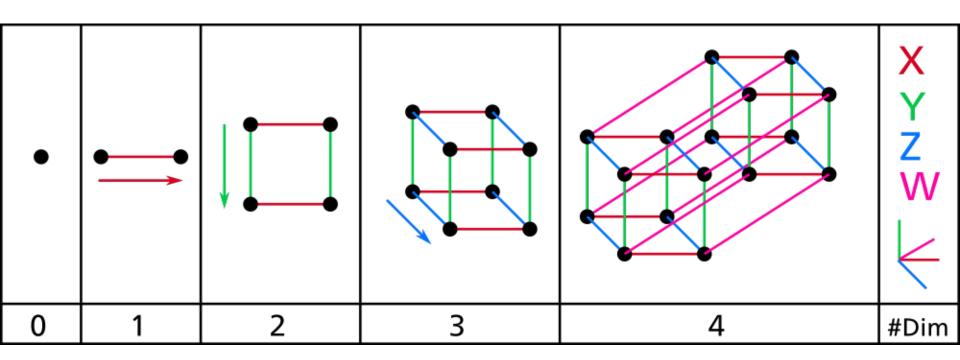


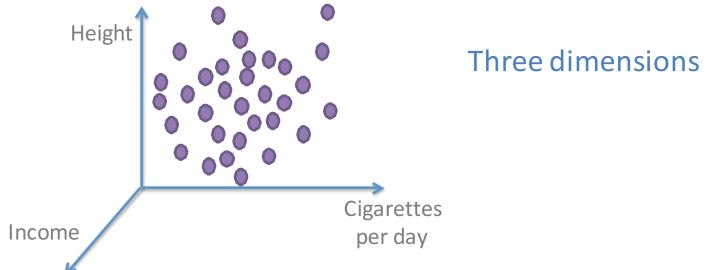


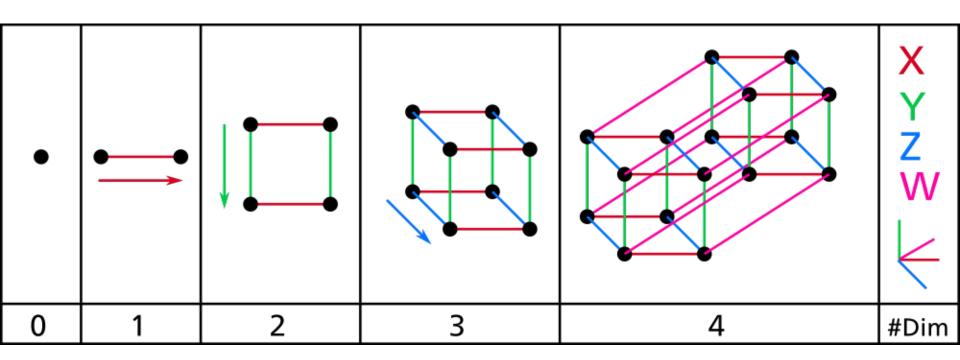


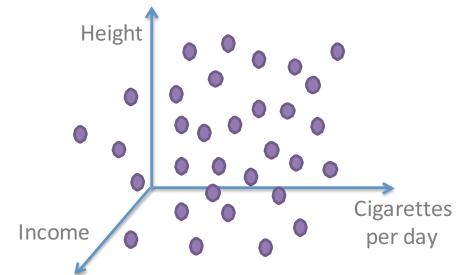
#### Two dimensions:

More space but still not so much Being close not improbable



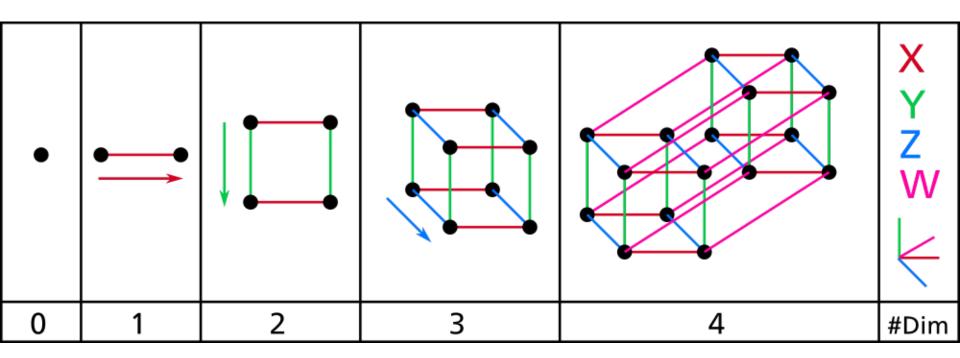


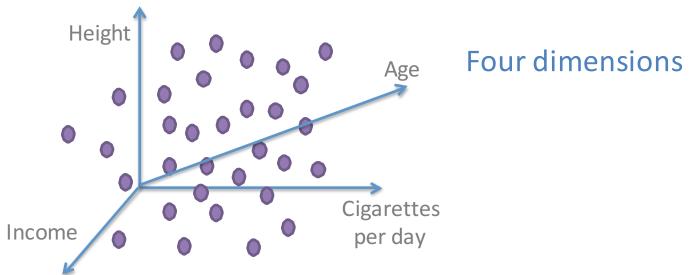


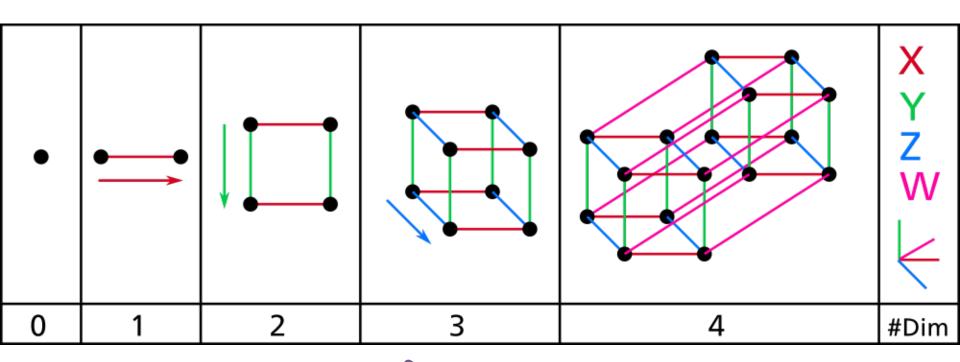


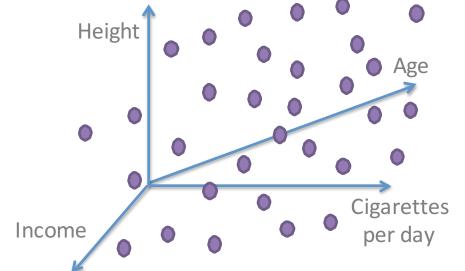
#### Three dimensions:

Much larger space Being close less probable



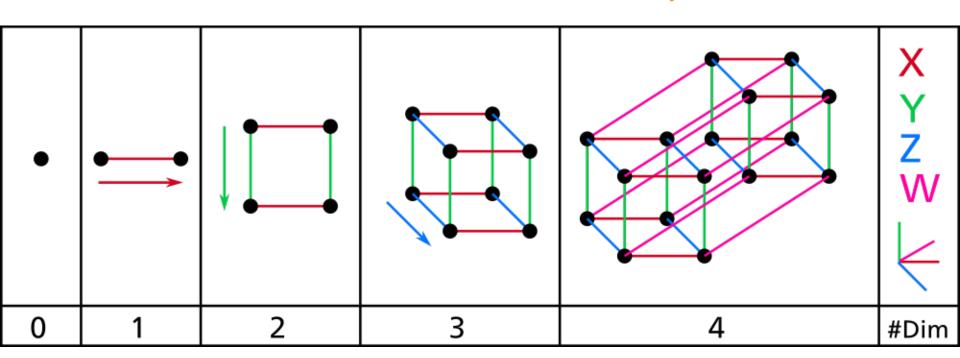


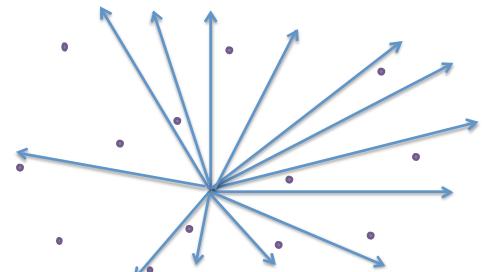




#### Four dimensions:

omg so much space Being close quite improbable





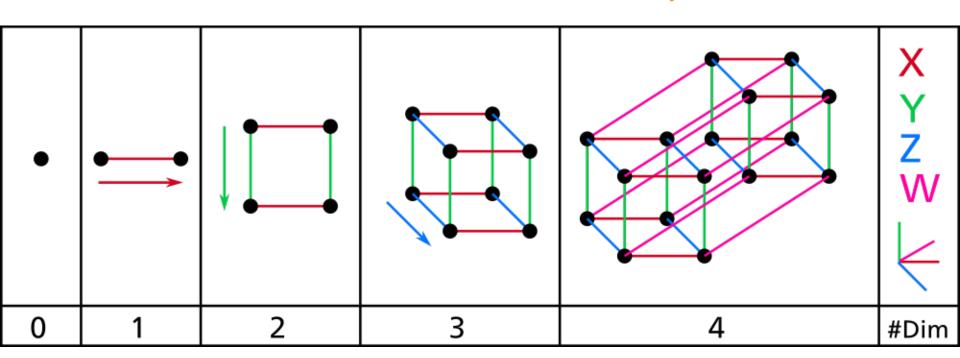
#### Thousand dimensions:

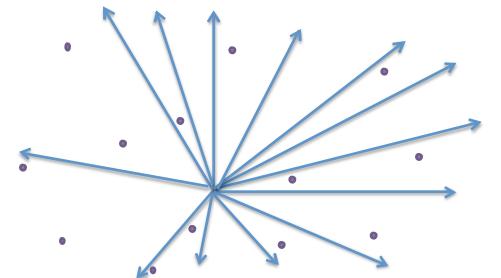
Helloooo... hellooo.. helloo...

Can anybody hear meee.. mee..

mee.. mee..

So alone....



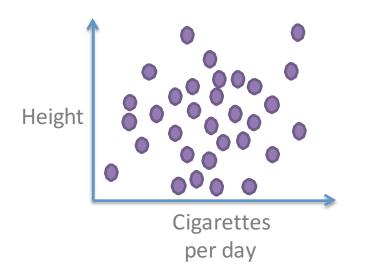


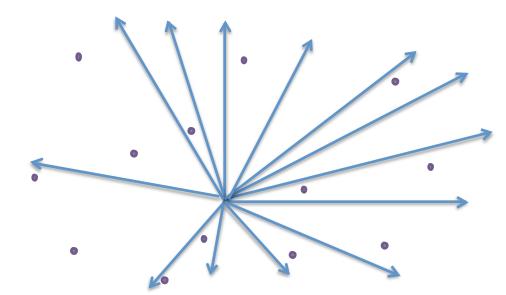
#### Thousand dimensions:

I specified you with such high resolution, with so much detail, that you don't look like anybody else anymore. You're unique.

# Demonstration of how space grows (ipython notebook)

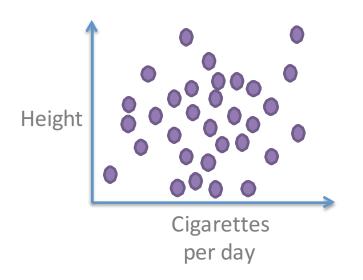
Classification, clustering and other analysis methods become exponentially difficult with increasing dimensions.

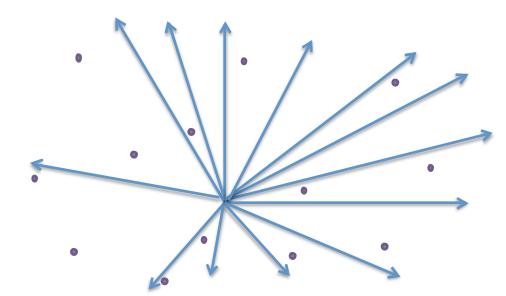




Classification, clustering and other analysis methods become exponentially difficult with increasing dimensions.

To understand how to divide that huge space, we need a whole lot more data (usually much more than we do or can have).



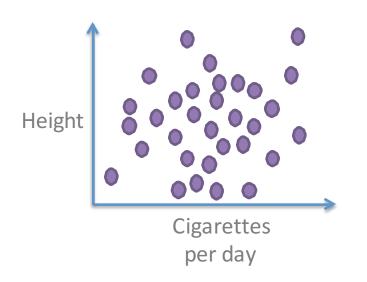


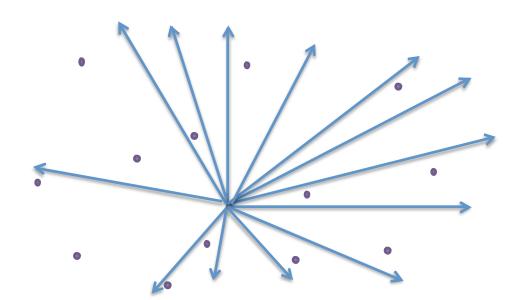
# **Dimensionality Reduction**

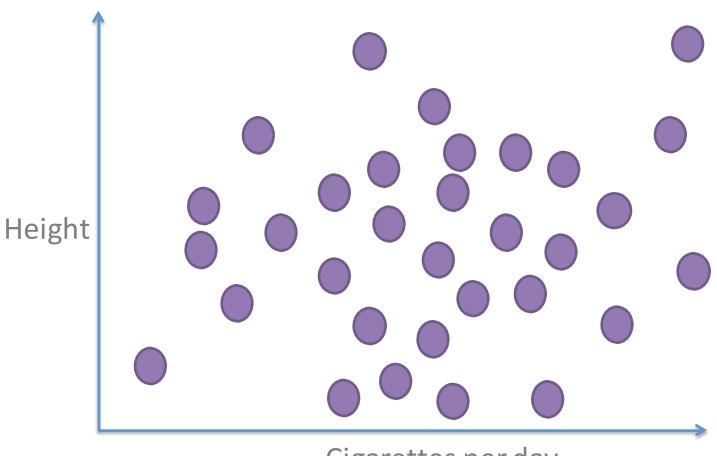
Lots of features, lots of data is best. But what if you don't have the luxury of ginormous amounts of data?

Not all features provide the same amount of information.

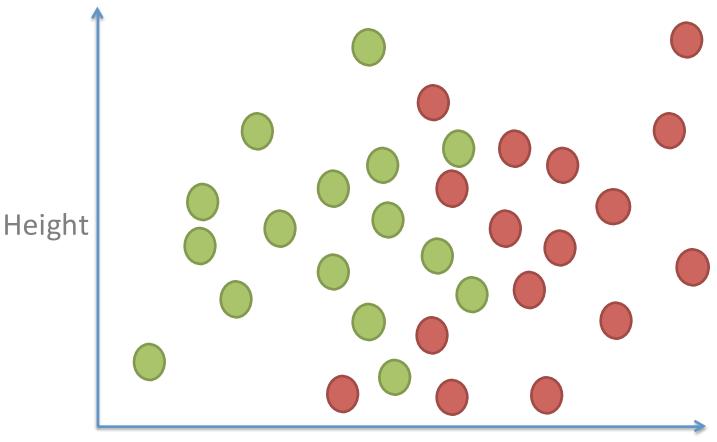
We can reduce the dimensions (compress the data) without necessarily losing too much information.



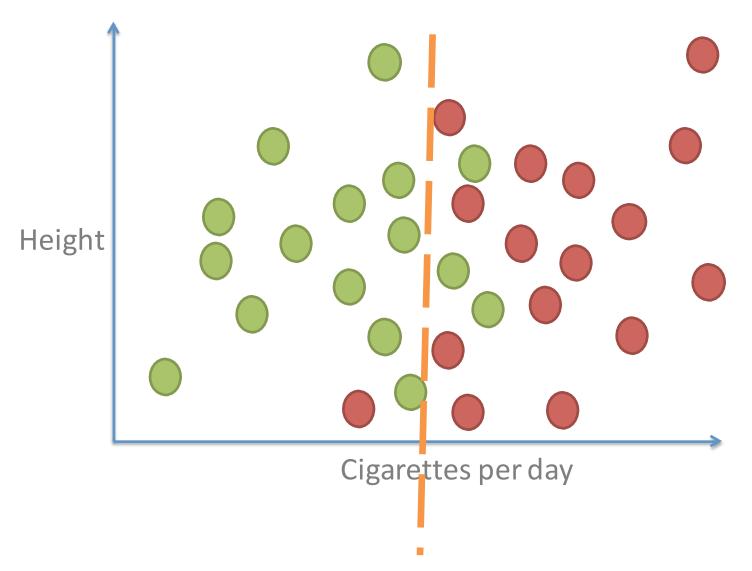


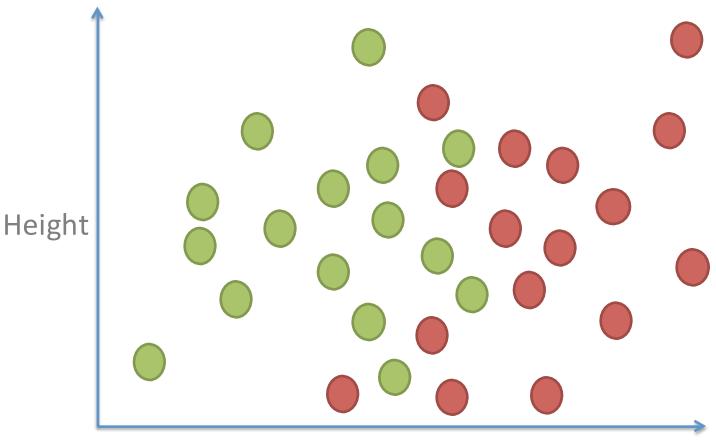


Cigarettes per day



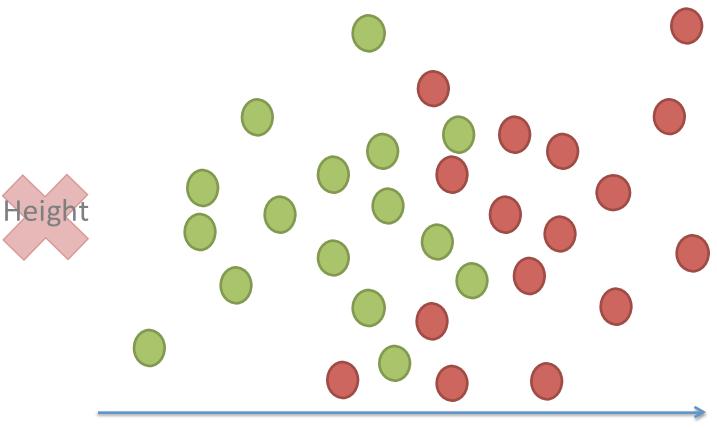
Cigarettes per day



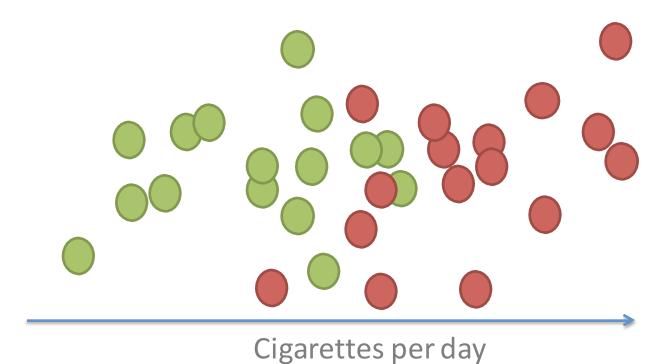


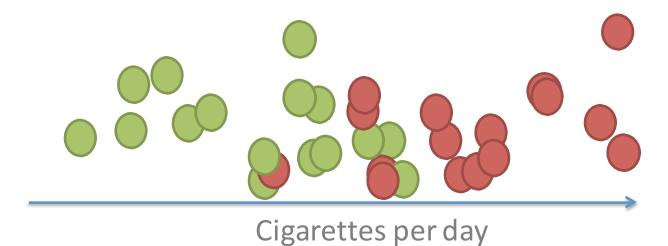
Cigarettes per day

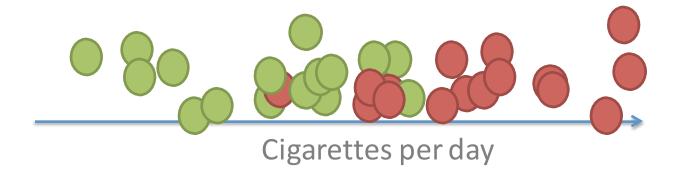
Healthy / Heart Disease



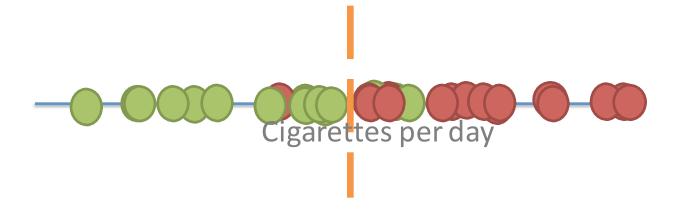
Cigarettes per day

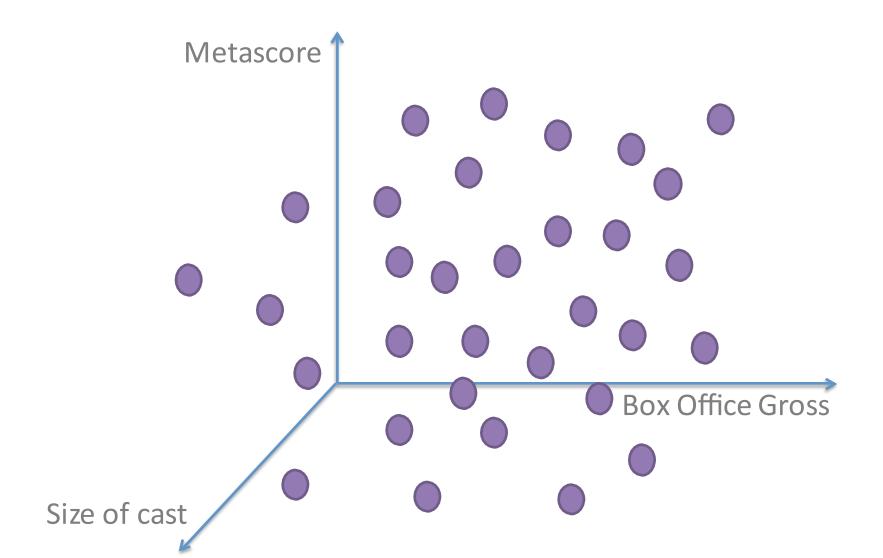


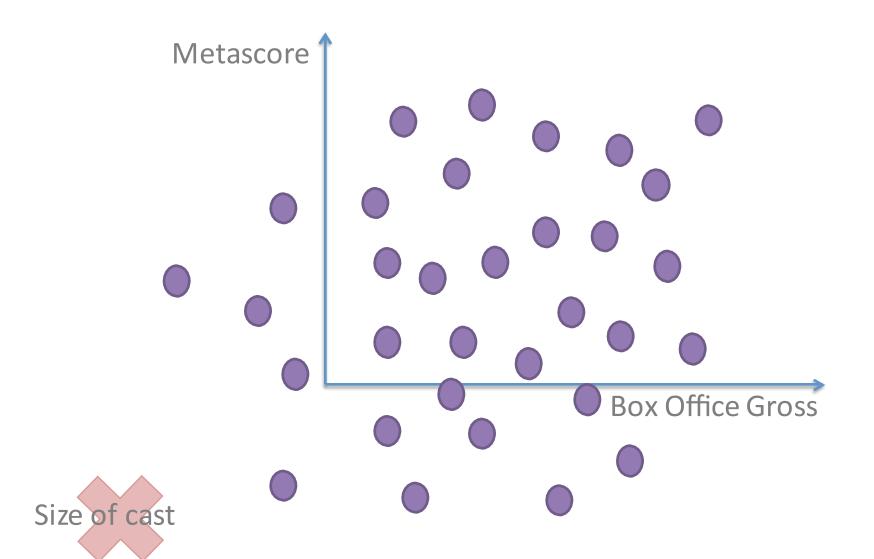


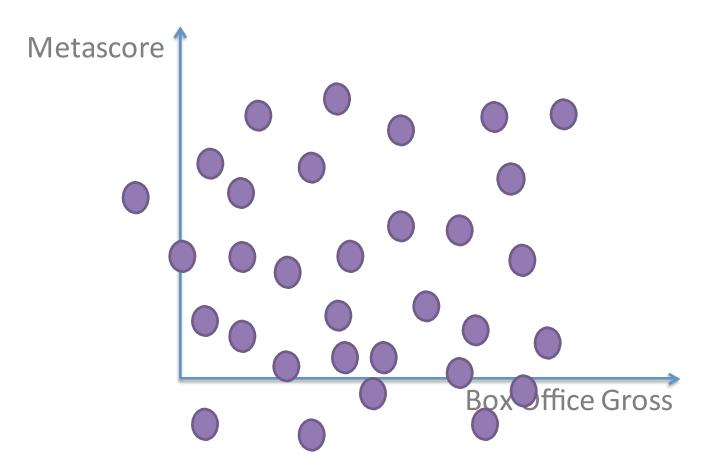




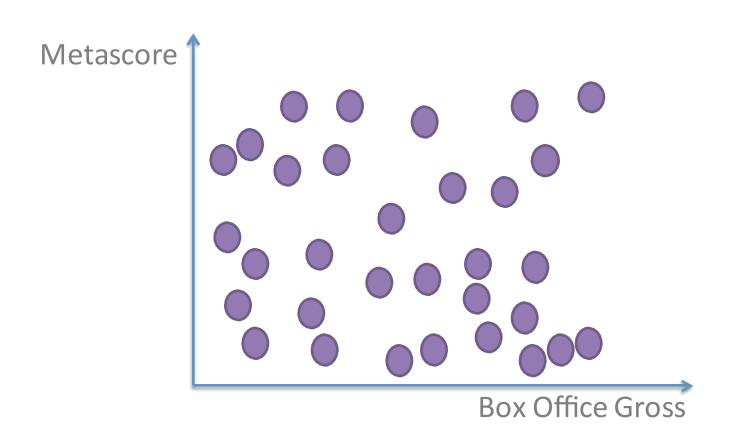












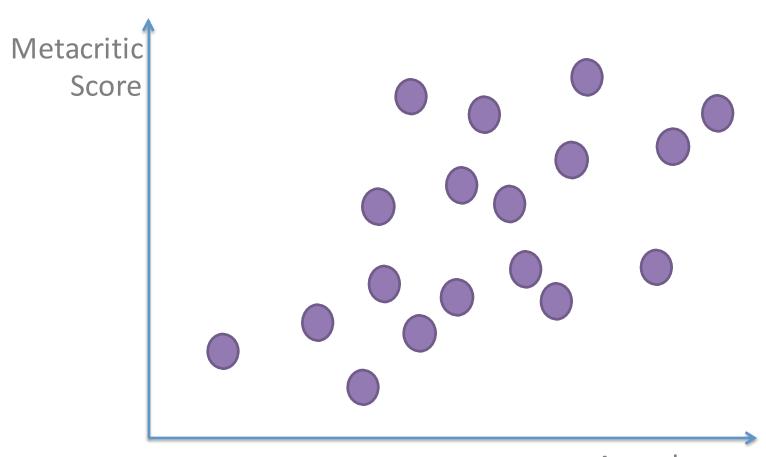
#### Common Sense

Experiments (remove a feature, fit again, evaluate results)

Regularization (in regression)

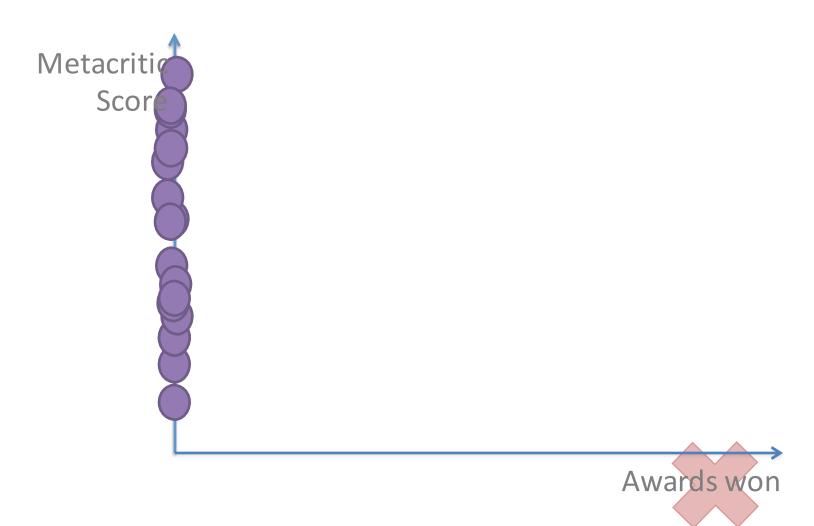
Feature scores (chi<sup>2</sup>, F-test, etc. : SelectKBest())

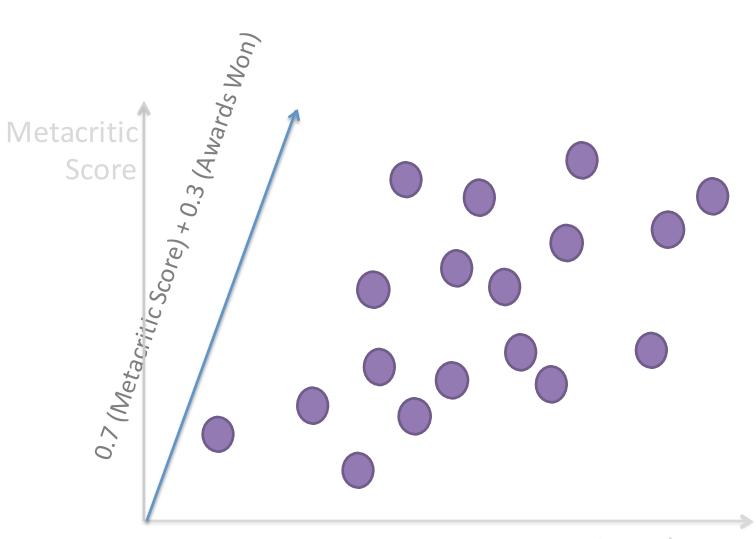
Do I have to choose the dimensions among existing features?

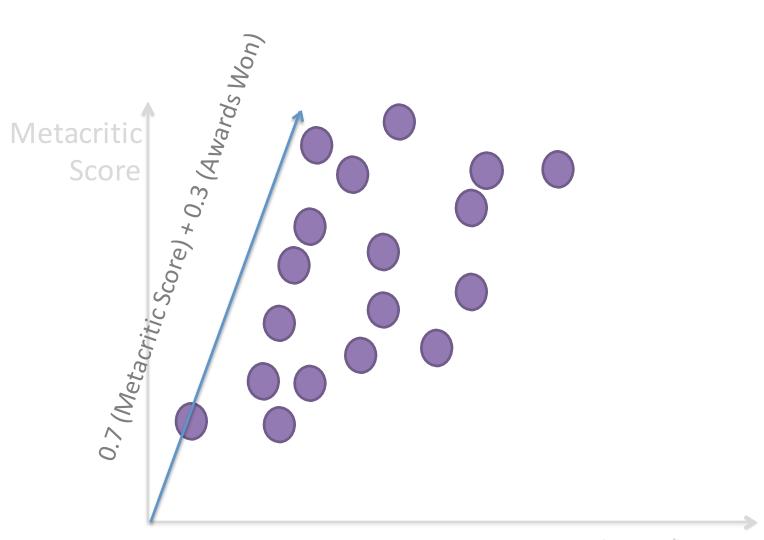


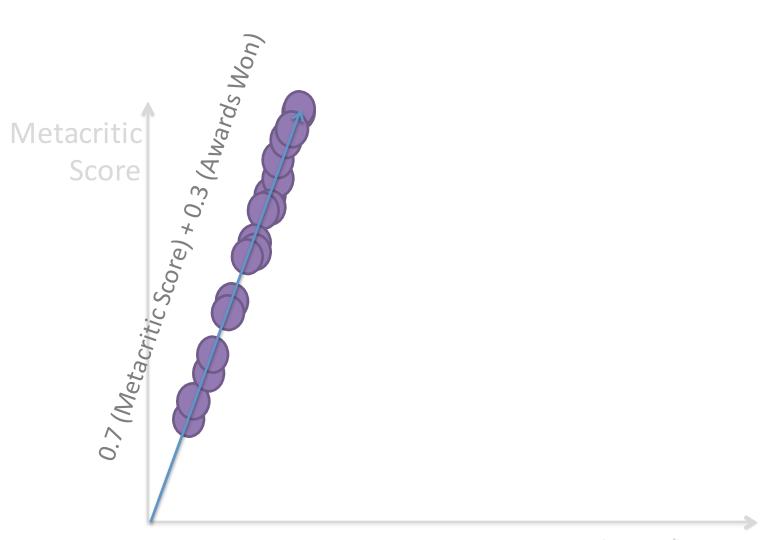
Awards won

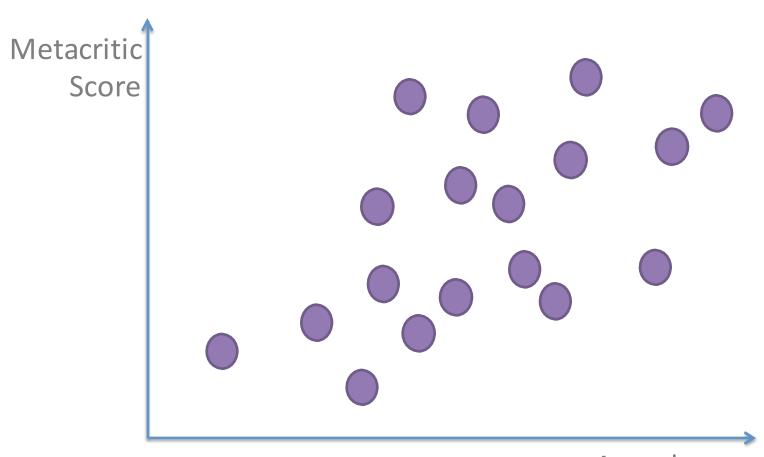
Do I have to choose the dimensions among existing features?



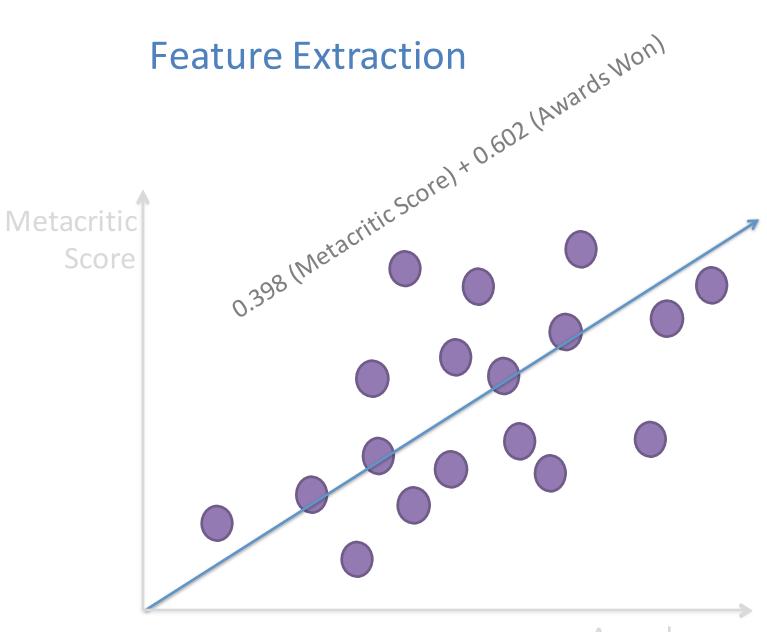


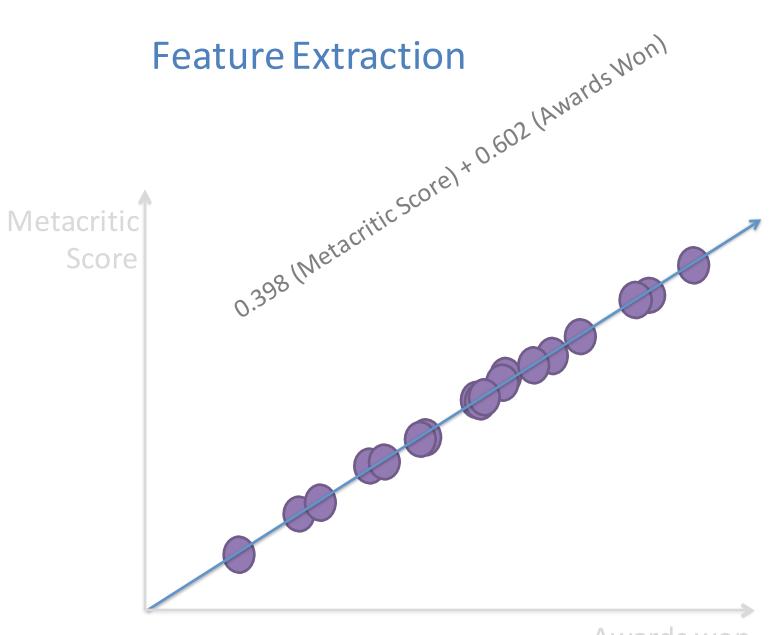


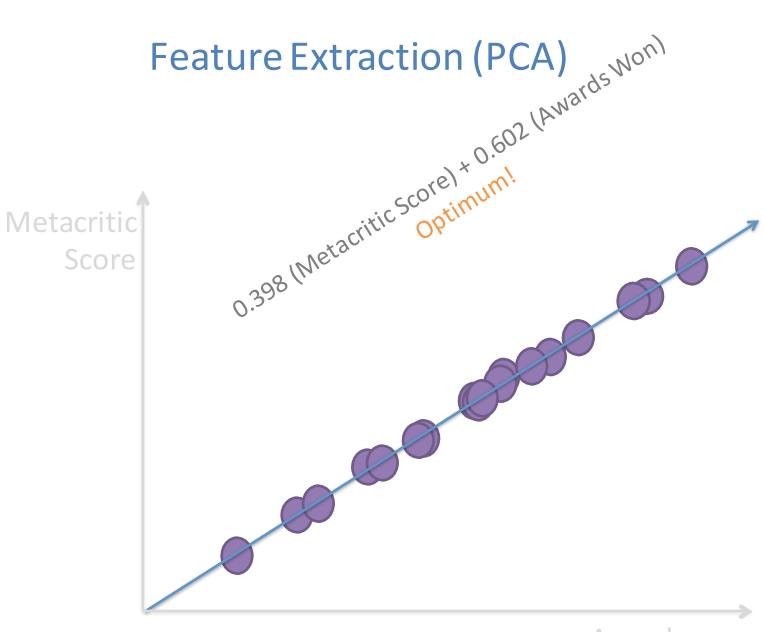




Awards won







Advantage: You retain more information

Disadvantage: You lose interpretability

Advantage: You retain more information

Disadvantage: You lose interpretability

2D

Oscar\_or\_not = logit( $\beta_1$ (Metascore) +  $\beta_2$ (Awards))

Advantage: You retain more information

Disadvantage: You lose interpretability

#### 2D

Oscar\_or\_not = logit( $\beta_1$ (Metascore) +  $\beta_2$ (Awards))

#### Feature selection 1D

Oscar\_or\_not = logit( $\beta_1$ (Metascore))

Advantage: You retain more information

Disadvantage: You lose interpretability

#### 2D

Oscar\_or\_not = logit( $\beta_1$ (Metascore) +  $\beta_2$ (Awards))

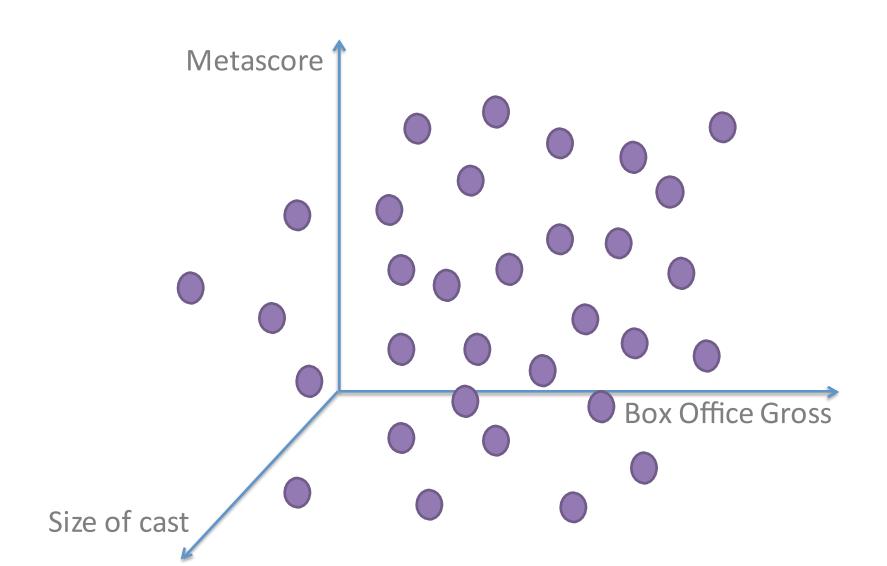
#### Feature selection 1D

Oscar\_or\_not = logit( $\beta_1$ (Metascore))

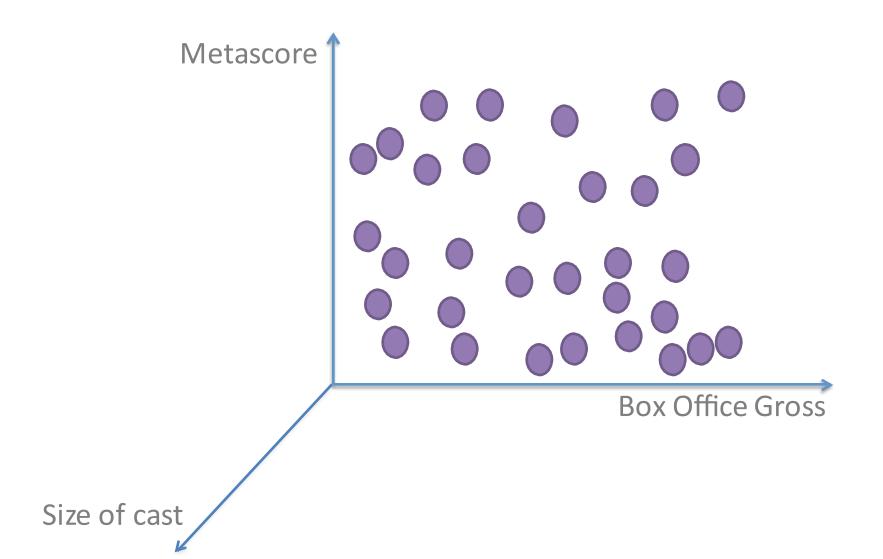
#### Feature extraction 1D

Oscar\_or\_not = logit( $\beta_1(0.4*Metascore + 0.6*Awards)$ )

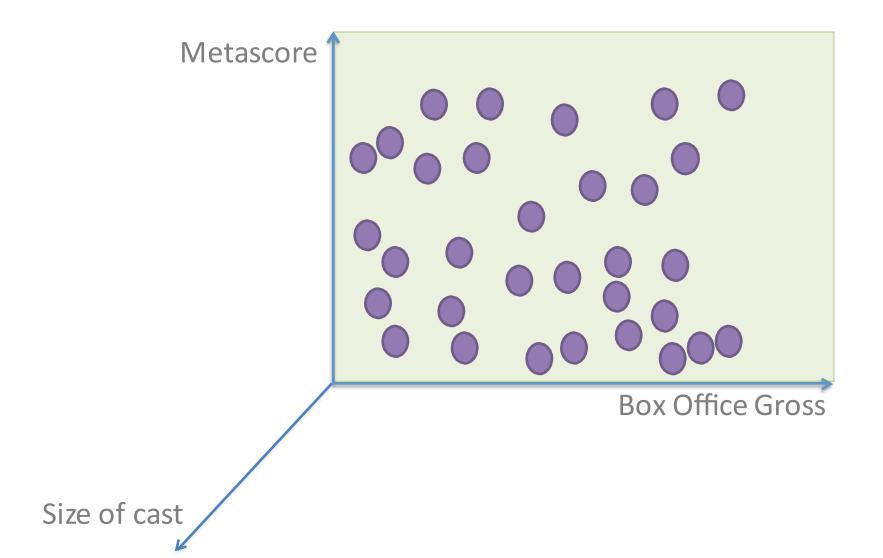
# 3D → 2D Feature Selection

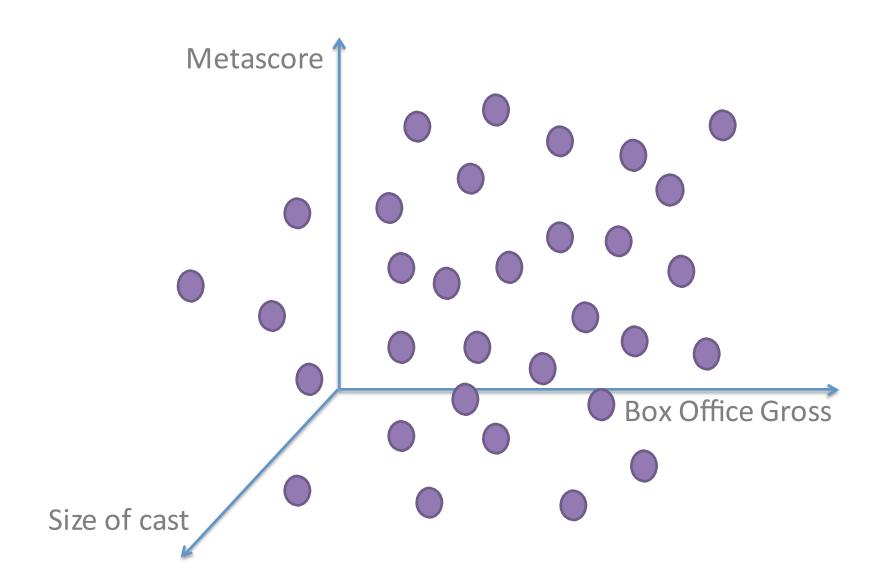


## 3D → 2D Feature Selection

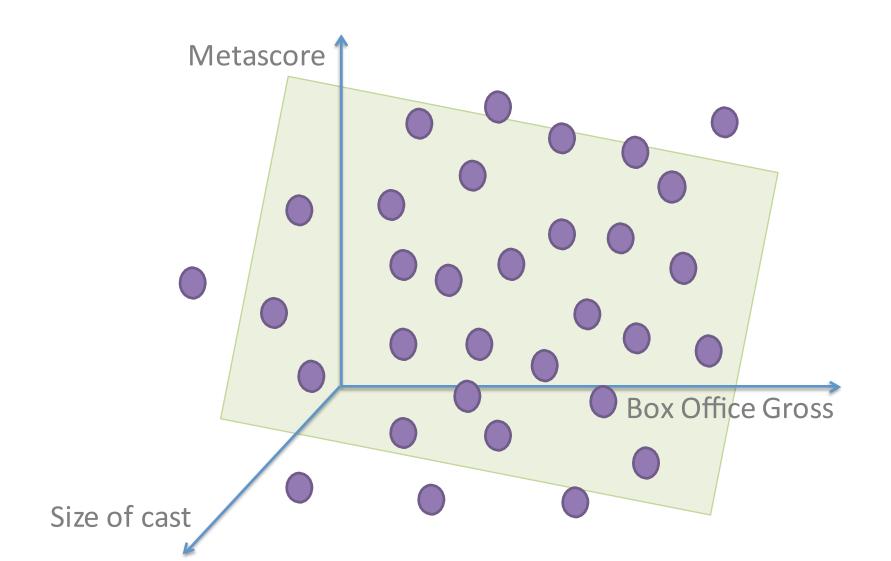


## 3D → 2D Feature Selection

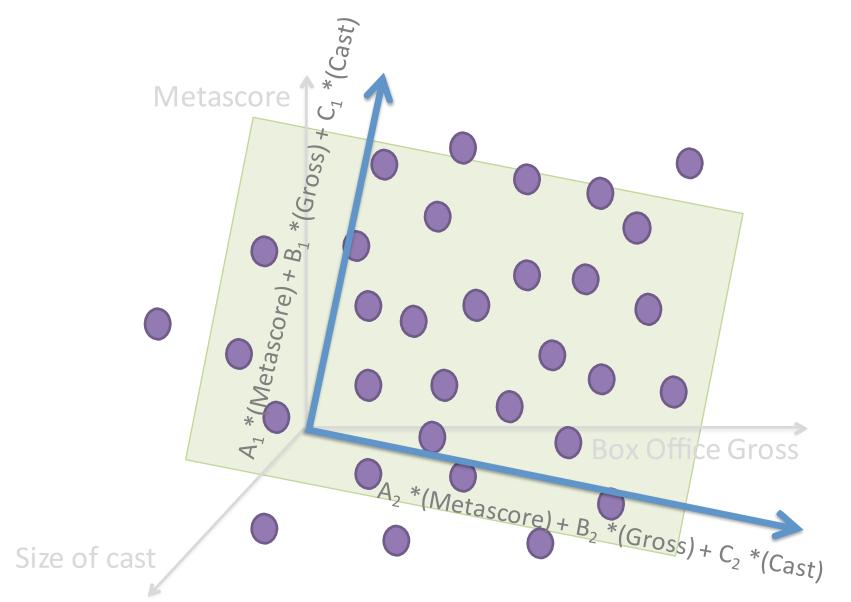




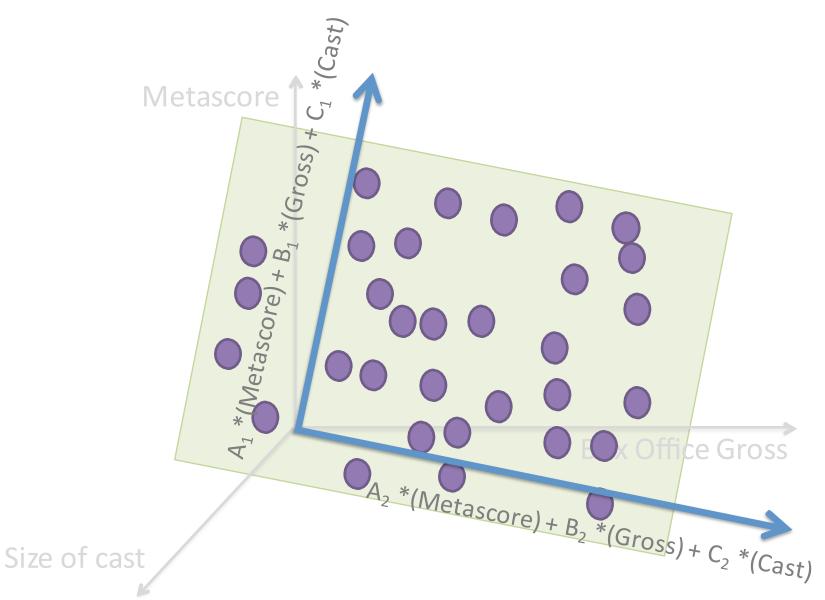
Optimum plane



Optimum plane



Optimum plane



# from sklearn.decomposition import PCA

```
reducer = PCA( n_components = 20 )
reduced_X = reducer.fit_transform(X)
```

# How and why to use PCA

Improving your clustering

Improving your classification (alternative to feature selection)

Visualizing high dimensional data in 2D or 3D

Data compression with little loss

### **PCA Math**

Vectors defining the reduced hyperplane are eigenvectors of the covariance matrix of the features.

Singular Value Decomposition (SVD) is a related decomposition that can be used to solve the PCA problem as well, and with better numeric properties.

(See notebook.)