

OVERVIEW

- **Planned:**
 - 12 Cards
 - 28.7h
- **Current status:**
 - 11 Cards done, 1 blocked
 - 29.2h

TIME ESTIMATES

- 4 cards matched exactly
- 5 cards +0.5h
- 1 card +1.5h (Pico setup)
- 1 card -0.3h

BEST CARDS

- *choose CAD software & get familiar*
 - 2h limit avoided paralysis by analysis
- *model first version of robot*
 - again, timelimit doing too much detail
 - got valuable insights for space in robot
 - still got time to do other things

WORST CARDS

- *make Pico control one motor*
 - blocked until sprint end (no battery)
 - reason: bad communication?
- *print robot frame v1*
 - v1 was not ready for physical print
 - had to print something else (wheels)
 - required out-of sprint modelling time

BIGGEST FAILURE

