

FFORMA: Feature-based FORecast-model Averaging

Abstract

To produce good forecasts of time series, we must first solve the problem of which model to use. Moreover, forecasting accuracy can even be improved by combining different models. We present an automated method for combining forecasting models that outperforms any individual method in a set of the most popular ones in the time series forecasting literature, achieving second position in the M4 Competition. Our approach works in two phases. In the first, we use a dataset of time series to train a meta-model to assign probabilities to the forecasting methods with the goal of minimizing the average forecasting error. In the second phase, we forecast new series by assigning probabilities to methods using our previously trained meta-model, and then combine their individual forecasts using a weighted average with these probabilities. The inputs to the meta-model are features extracted from the series.

Keywords: FFORMA (Feature-based FORecast-model Averaging), FFORMS (Feature-based FORecast-model Selection), Time series features, Forecast combination, XGBoost, M4 Competition

1 Introduction

There are essentially two general approaches to forecast a time series: i) use of single model and ii) combination forecast or forecast model averaging. There is a growing consensus that the combination forecast is a way of improving forecast accuracy. Empirical work often provides evidence that the combination of forecasts resulting from several candidate forecasting models are often superior to their individual forecasts. Combining forecasts across different models is considered as a way of reducing the risk of selecting an inappropriate model. However, the main challenge in forecast combination is the selection of appropriate set of weights.

Bates & Granger (1969), was the first to forward the idea of “the combination of forecasts”. Since then, it has been extended in various ways and many approaches have been proposed to derive weights for forecast combination (Timmermann (2006)).

Recently, a few researchers have explored the use of time series features in selecting the most appropriate forecasting method. However, the use of time series features to derive weights for forecast combination has been rarely addressed in the literature. In this paper we propose a general framework to obtain weights for forecast combination based on features computed from the time series. We call this framework FFORMA (Feature-based FOfRecast Model Averaging). The proposed FFORMA framework has been used over the course of M4 competition and placed in second in forecast accuracy in both point forecasts and prediction intervals. This approach has been influenced by the work of Talagala, Hyndman & Athanasopoulos (2018) and is related to the previous work by Prudêncio & Ludermir (2004) in which they use machine learning techniques to define weights for the linear combination of forecasts based on five features extracted from the time series.

The rest of the paper is organized as follows: In [Section 2](#) we describe the FFORMA framework in a general sense, without specifying the set of features, forecasting methods and learning model implementation. This section contains the main contribution: posing the learning problem in a way that includes the information about the errors produced by each forecasting method and combines it with the features extracted from the series. [Section 3](#) gives the details of our implementation of FFORMA which achieved second place in the M4 Competition. This includes the required preprocessing steps, the sets of features and forecast methods, as well as the specific implementation of the meta-learning model. *The method to produce the prediction intervals for the M4 competition is also explained in this section.* We show empirical evidence on the good performance of the approach in [Section 4](#) by quantifying the difference between our proposed learning model and a traditional classifier approach. [Section 5](#) provides some final remarks and conclusions.

2 Methodology

2.1 Overview / Intuition

The objective of our meta-learning approach is to derive weights to combine a set of individual forecasting methods (e.g. ARIMA, exponential smoothing) to produce more accurate forecasts. Our framework requires a dataset of time series, called the *reference set*, from which we learn to produce the weights for any given time series.

We start from the reference set and a fixed set of forecasting methods, called the *pool of methods*. Each time series in the reference set is divided into training period and test period. Each

forecasting method in the pool is applied to the training period of each time series and forecast error measures are calculated over the test period. The inputs for training the meta-learning model are: i) features (e.g. length, autocorrelation coefficients, etc.) extracted from the training period of the series and ii) The forecast errors produced by the forecasting methods.

The model will learn to produce weights for each method in the pool as a function of the features of the series. Once the meta-learning model is trained, the inductive step consists of assuming that a new series we want to forecast comes from a *generating process* similar to the one that generated the reference set.

One common meta-learning approach is to learn to select the best method in the pool for each series, the one that produces the least forecasting error. This approach transforms the problem into a traditional classification problem by setting the individual forecasting methods as the classes and the best method as the target class for each time series, enabling the use of existing classification algorithms. However, this simplification removes relevant information which may be useful in the metalearning process, such as which methods produce similar errors to the best one for a series, or which series are more *difficult* than others. We do not apply this simplification and take into account the exact error that each method produces in each series, instead of just considering which one produces the minimum error. This information is introduced into the model by posing the problem as finding a function that assigns *probabilities* to each forecasting method for each series, with the objective of minimizing the expected error that is produced if the methods were picked at random following these probabilities.

Our approach can be easily transformed into a classification exercise by selecting the method corresponds to the largest probability produced by our model. If we allow a sufficiently rich hypothesis space to fit freely, we also end up assigning probability one to the methods with the least amount of error. Our approach can also be seen as a classification exercise but with *per class weights* (the forecasting errors) that vary per instance, combined with *per instance weights* that assign more importance to some series.

2.2 Algorithmic description

Algorithm 1 presents the Pseudo code of the proposed framework. The operation of FFORMA framework can be divided into two phases: (i) offline phase, in which we train a meta-learner, ii) online phase, in which we use the pre-trained meta-learner to identify weights for forecast combination and subsequently generate relevant forecasts. The offline phase of the FFORMA

framework has four main components: i) reference set, ii) the set of features to be extracted from the time series, iii) The set of forecasting methods and forecast error measure and iv) Meta-learning model. In Section 3, we describe these components in more detail with application to M4 competition.

Algorithm 1 The FFORMA framework - Forecast combination based on meta-learning.

Offline phase - train the learning model

Given:

$O = \{X_1, X_2, \dots, X_n\}$: the collection of N observed time series, the reference set.

P : Set of K forecasting algorithms such as ARIMA, ETS, SNAIVE, etc.

F : the set of functions to calculate time series features.

E : A forecasting error measure such as Mean Squared Error.

Output:

FFORMA meta-learner: A function from the extracted features to a set of K probabilities, one for each method in P .

Prepare the meta-data

For $j = 1$ to N :

- 1: Split X_j into a training period and test period.
- 2: Calculate the set of features for the training period by applying F .
- 3: Fit the models in P to the training period.
- 4: Calculate forecasts for the test period from each model.
- 5: Calculate forecast error measure E over the test period for all models in P .
- 6: Meta-data: input features x_j (step 2), output errors: e_j (step 5).

Train the meta-learner

- 7: Train a learning model based on the meta-data and errors, by minimizing:

$$\operatorname{argmin}_f \sum_{j=1}^N \sum_{k=1}^K f(x_j)_k e_{jk}$$

- 8: meta-learner.

Online phase - forecast a new time series

Given:

FFORMA classifier from step 8 .

Output:

Forecast for the new time series X_{new} .

- 9: For X_{new} calculate features x_{new} by applying F .
 - 10: From the features, use the meta-learner to produce w the vector of probabilities.
 - 11: Compute the individual forecasts of the methods in P for X_{new}
 - 12: Compute the final forecast by weighted average using w and the individual forecasts.
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Find a better name for the *underlying implementation of the learning model*, to distinguish it from the meta-learning model, which i think is the whole

3 Implementation and Application to M4 Competition

3.1 Reference set

For the M4 competition, we used the whole M4 data set as the reference set. The M4 competition database consists of 100,000 real-world time series of yearly, quarterly, monthly, weekly, daily and hourly data. To divide the series into training and testing period, we used the forecast horizon specified in the database as the size of the temporal holdout. When the training period resulted too short (less than 2 periods), the size of the temporal holdout was reduced. Some series were removed because they were constant after removing the holdout part.

3.2 Time series features

We use a set of 42 features. [Table 1](#) provides a brief description of features used in this experiment. The functions to calculate these features are implemented in `tsfeatures` R package by Hyndman et al. ([2018b](#)). Most of the features have been previously used by Hyndman, Wang & Laptev ([2015](#)) and Talagala, Hyndman & Athanasopoulos ([2018](#)). The last five heterogeneity features are calculated as below. First, the time series is pre-whitened using an AR model and obtain a new series z . Then, a GARCH(1, 1) model is fitted to the pre-whitened series and obtain the residual(r) series. Subsequently, the features 39-42 are computed. A detailed description of other features are provided in Talagala, Hyndman & Athanasopoulos ([2018](#)). The features corresponds to seasonal time series only are set to zero for the case of non-seasonal time series. Note that, we have not used any of the domain-specific features such as macro, micro, finance, etc., even though these information are available in the M4 data set.

3.3 Forecasting methods

We considered nine forecasting algorithms implemented in the `forecast` (Hyndman et al. [2018a](#)) package R package. They are (the specific R calls for fitting the models are given): i) automated ARIMA algorithm (`auto.arima`), ii) automated ETS algorithm (`ets`), iii) feed-forward neural network with a single hidden layer is fitted to the lags. The number of lags is automatically selected (`nnetar`), iv) random walk with drift (`rwf` with `drift=TRUE`), v) TBATS model (`tbats`), vi) Theta method forecast (`thetaf`), vii) naive forecasts (`naive`), viii) STL-AR Seasonal and Trend decomposition using Loess with AR modeling of the seasonally adjusted series (`stlm` with model function `ar`) and ix) seasonal naive forecasts (`snaive`). In all cases, the default setting is used. Further, in the case of an error when fitting the series (e.g. a series is constant), the

Table 1: Features used in FFORMA framework.

	Feature	Description	Non-seasonal	Seasonal
1	T	length of time series	✓	✓
2	trend	strength of trend	✓	✓
3	seasonality	strength of seasonality	-	✓
4	linearity	linearity	✓	✓
5	curvature	curvature	✓	✓
6	spikiness	spikiness	✓	✓
7	e_acf1	first ACF value of remainder series	✓	✓
8	e_acf10	sum of squares of first 10 ACF values of remainder series	✓	✓
9	stability	stability	✓	✓
10	lumpiness	lumpiness	✓	✓
11	entropy	spectral entropy	✓	✓
12	hurst	Hurst exponent	✓	✓
13	nonlinearity	nonlinearity	✓	✓
13	alpha	ETS(A,A,N) $\hat{\alpha}$	✓	✓
14	beta	ETS(A,A,N) $\hat{\beta}$	✓	✓
15	hwalpha	ETS(A,A,A) $\hat{\alpha}$	-	✓
16	hwbeta	ETS(A,A,A) $\hat{\beta}$	-	✓
17	hwgamma	ETS(A,A,A) $\hat{\gamma}$	-	✓
18	ur_pp	test statistic based on Phillips-Perron test	✓	✓
19	ur_kpss	test statistic based on KPSS test	✓	✓
20	y_acf1	first ACF value of the original series	✓	✓
21	diff1y_acf1	first ACF value of the differenced series	✓	✓
22	diff2y_acf1	first ACF value of the twice-differenced series	✓	✓
23	y_acf10	sum of squares of first 10 ACF values of original series	✓	✓
24	diff1y_acf10	sum of squares of first 10 ACF values of differenced series	✓	✓
25	diff2y_acf10	sum of squares of first 10 ACF values of twice-differenced series	✓	✓
26	seas_acf1	autocorrelation coefficient at first seasonal lag	-	✓
27	sediff_acf1	first ACF value of seasonally-differenced series	-	✓
28	y_pacf5	sum of squares of first 5 PACF values of original series	✓	✓
29	diff1y_pacf5	sum of squares of first 5 PACF values of differenced series	✓	✓
30	diff2y_pacf5	sum of squares of first 5 PACF values of twice-differenced series	✓	✓
31	seas_pacf	partial autocorrelation coefficient at first seasonal lag	✓	✓
32	crossing_point	number of times the time series crosses the median	✓	✓
33	flat_spots	number of flat spots, calculated by discretizing the series into 10 equal sized intervals and counting the maximum run length within any single interval	✓	✓
34	nperiods	number of seasonal periods in the series	-	✓
35	seasonal_period	length of seasonal period	-	✓
36	peak	strength of peak	✓	✓
37	trough	strength of trough	✓	✓
38	ARCH.LM	ARCH LM statistic	✓	✓
39	arch_acf	sum of squares of the first 12 autocorrelations of z^2	✓	✓
40	garch_acf	sum of squares of the first 12 autocorrelations of r^2	✓	✓
41	arch_r2	R^2 value of an AR model applied to Z^2	✓	✓
42	garch_r2	R^2 value of an AR model applied to e^2	✓	✓

SNAIVE forecast method is used instead.

3.4 Metal-learning model implementation

We choose the gradient tree boosting model of **xgboost** (Chen & Guestrin (2016)) as the underlying implementation of the learning model due to following reasons:

1. Ability to customize the model to fit our objective function
2. Computational efficiency: The size of the M4 data set requires a efficient model
3. Good performance in structure based problems

3.4.1 The xgboost objective function

The basic xgboost algorithm produces numeric values from the features, one for each forecasting method in our pool. We apply the softmax transform to these values prior to computing the the objective function shown in Algorithm 1 step 7, implemented as a custom objective function.

xgboost fits the model by gradient boosting, for which requires a gradient and hessian of the objective function. In our case, the gradient is the direct gradient of the objective, but the *correct* hessian is prone to numerical problems that need to be fixed for xgboost to converge. This is a relative common problem and one simple fix is to use an upper bound of the hessian by clamping small values to a larger one. In our case, we compute an alternate upper bound of the hessian by removing some terms from the *correct* hessian. Although both alternatives converge, our approach works faster, requiring less boosting steps to converge. This not only increases the computational efficiency, it also generalizes better due to a less complex set of trees produced in the final solution.

The functions involved in computing the objective are the following:

- $y(x)$ is the output of the xgboost algorithm
- $p_j = \frac{e^{y(x)_j}}{\sum_k e^{y(x)_k}}$ is the transformation to probabilities by applying the softmax transform.
- $L = \sum p_j e_j$ is the loss of the function p .
- $G_j = \frac{\partial L}{\partial p_j} = p_j(e_j - \sum_k e_k p_k)$

$$H_j = \frac{\partial G_j}{\partial p_j} \approx \hat{H}_j = p_j(e_j(1 - p_j) - G_j)$$

3.4.2 Hyperparameters

The results of xgboost are particularly dependent on its hyper-parameters such as learning rate, number of boosting steps, maximum complexity allowed for the trees or subsampling sizes. In our case we limit the hyper-parameter search space based on some initial

results and rules of thumb and explore it using Bayesian optimization, (implemented in the `rBayesianOptimization` R package (Yan 2016)) measuring performance on a 10% holdout version of the reference set. We picked the most regularized hyper-parameter set from the top solutions of the exploration.

3.5 Prediction Intervals

The M4 Competition also featured a sub competition over the accuracy of prediction intervals. For this part, we used a different approach. In order to compute the intervals we used the point forecast produced by our meta-learner as the center of the interval and computed the 95% bounds of the interval by a linear combination of the bounds of three forecasting methods: Thetaf, SNAIVE and NAIVE methods. The coefficients for the linear combination were calculated in a data driven way also over the M4 database. The procedure is as follows:

1. For the training period of each series in the data set:
 1. Compute the point forecast of the meta-learning.
 2. Compute the 95% *predicion radius* for the thetaf, snaive and naive, this is the difference between the 95% upper bound and the point forecast for each horizon.
2. For each forecasting horizon required in the data set:
 1. Find the coefficients that minimize the MSIS error of the interval with the meta-learning point forecast as center and a linear combination of the radiuses of thetaf, snaive and naive as radius. The minimization is done by gradient descent over the test period of the series.

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This procedure produces at set of three coefficients for each prediction horizon in the M4 dataset and these coefficients will be the same independently of the series we want to forecast. *Unlike the point forecast, these coefficients are not restricted to be probabilities, the optimization is unrestricted.* In order to prevent overfitting for the center of the intervals, the training part of the M4 dataset was divided in two halves, and our metalearning approach was trained in one half and applied to the other.

4 Results

We measure the impact of our main contribution by comparing the average forecasting error produced by our proposed combination model to a reference implementation of a traditional classification approach, in which a model is trained to pick the best method, which will then

be used for the final forecast. We use the same set of features, the same pool of forecasting methods, the same underlying implementation (xgboost), and in both approaches we perform hyperparameter search prior to fitting the model using bayesian optimization. This way, we isolate the model differences. In the M4 competition dataset for point forecast, our approach produces a **relative improvement of 10%** over the reference, measured as $\frac{\text{classifier error}}{\text{proposed method error}}$.

5 Discussion and Conclusions

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