

Time Series Analysis & Forecasting Using R

bit.ly/fable2023

7. Exponential smoothing



Outline

- 1 Exponential smoothing
- 2 Trend methods
- 3 Lab Session 14
- 4 Seasonal methods
- 5 ETS taxonomy
- 6 Lab Session 15
- 7 Non-Gaussian forecast distributions

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Pharmaceutical Benefits Scheme



Pharmaceutical Benefits Scheme

The Pharmaceutical Benefits Scheme (PBS) is the Australian government drugs subsidy scheme.

- Many drugs bought from pharmacies are subsidised to allow more equitable access to modern drugs.
- The cost to government is determined by the number and types of drugs purchased. Currently nearly 1% of GDP.
- The total cost is budgeted based on forecasts of drug usage.

Pharmaceutical Benefits Scheme

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POLITICS

Opp demands drug price restriction after PBS budget blow-out

The Federal Opposition has called for tighter controls on drug prices after the Pharmaceutical Benefits Scheme (PBS) budget blew out by almost \$800 million.

The money was spent on two new drugs including the controversial anti-smoking aid Zyban, which dropped in price from \$220 to \$22 after it was listed on the PBS.

the Public Record
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FEATURES

the Public Record
Federal Election 2001

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Audio News Online

Pharmaceutical Benefits Scheme

- In 2001: \$4.5 billion budget, under-forecasted by \$800 million.
- Thousands of products. Seasonal demand.
- Subject to covert marketing, volatile products, uncontrollable expenditure.
- Although monthly data available for 10 years, data are aggregated to annual values, and only the first three years are used in estimating the forecasts.
- All forecasts being done with the FORECAST function in MS-Excel!

Historical perspective

- Developed in the 1950s and 1960s as methods (algorithms) to produce point forecasts.
- Combine a “level”, “trend” (slope) and “seasonal” component to describe a time series.
- The rate of change of the components are controlled by “smoothing parameters”: α , β and γ respectively.
- Need to choose best values for the smoothing parameters (and initial states).
- Equivalent ETS state space models developed in the 1990s and 2000s.

A model for levels, trends, and seasonalities

We want a model that captures the level (ℓ_t), trend (b_t) and seasonality (s_t).

How do we combine these elements?

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Multiplicatively?

$$y_t = \ell_{t-1} b_{t-1} s_{t-m} (1 + \varepsilon_t)$$

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Perhaps a mix of both?

$$y_t = (\ell_{t-1} + b_{t-1}) s_{t-m} + \varepsilon_t$$

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ETS models

General notation **E T S : ExponenTial Smoothing**

 ↗ ↑ ↖

Error Trend Season

Error: Additive ("A") or multiplicative ("M")

ETS models

General notation **E T S : ExponenTial Smoothing**



Error **Trend** **Season**

Error: Additive ("A") or multiplicative ("M")

Trend: None ("N"), additive ("A"), multiplicative ("M"), or damped ("Ad" or "Md").

ETS models

General notation **E T S : ExponenTial Smoothing**



Error Trend Season

Error: Additive ("A") or multiplicative ("M")

Trend: None ("N"), additive ("A"), multiplicative ("M"), or damped ("Ad" or "Md").

Seasonality: None ("N"), additive ("A") or multiplicative ("M")

ETS(A,N,N): SES with additive errors

Forecast equation

$$\hat{y}_{T+h|T} = l_T$$

Measurement equation

$$y_t = l_{t-1} + \varepsilon_t$$

State equation

$$l_t = l_{t-1} + \alpha \varepsilon_t$$

where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

ETS(A,N,N): SES with additive errors

Forecast equation	$\hat{y}_{T+h T} = l_T$
Measurement equation	$y_t = l_{t-1} + \varepsilon_t$
State equation	$l_t = l_{t-1} + \alpha \varepsilon_t$

where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

- “innovations” or “single source of error” because equations have the same error process, ε_t .
- Measurement equation: relationship between observations and states.
- Transition / state equation(s): evolution of state(s) over

ETS(M,N,N): SES with multiplicative errors

Forecast equation

$$\hat{y}_{T+h|T} = \ell_T$$

Measurement equation

$$y_t = \ell_{t-1}(1 + \varepsilon_t)$$

State equation

$$\ell_t = \ell_{t-1}(1 + \alpha\varepsilon_t)$$

where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

ETS(M,N,N): SES with multiplicative errors

Forecast equation	$\hat{y}_{T+h T} = \ell_T$
Measurement equation	$y_t = \ell_{t-1}(1 + \varepsilon_t)$
State equation	$\ell_t = \ell_{t-1}(1 + \alpha\varepsilon_t)$

where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

- Models with additive and multiplicative errors with the same parameters generate the same point forecasts but different prediction intervals.

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Holt's linear trend

Additive errors: ETS(A,A,N)

Forecast equation

$$\hat{y}_{T+h|T} = \ell_T + hb_T$$

Measurement equation

$$y_t = \ell_{t-1} + b_{t-1} + \varepsilon_t$$

State equations

$$\ell_t = \ell_{t-1} + b_{t-1} + \alpha\varepsilon_t$$

$$b_t = b_{t-1} + \beta\varepsilon_t$$

Holt's linear trend

Additive errors: ETS(A,A,N)

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Multiplicative errors: ETS(M,A,N)

Forecast equation

$$\hat{y}_{T+h|T} = \ell_T + hb_T$$

Measurement equation

$$y_t = (\ell_{t-1} + b_{t-1})(1 + \varepsilon_t)$$

State equations

$$\ell_t = (\ell_{t-1} + b_{t-1})(1 + \alpha\varepsilon_t)$$

Example: Australian population

```
aus_economy <- global_economy |>
  filter(Code == "AUS") |>
  mutate(Pop = Population / 1e6)
fit <- aus_economy |> model(AAN = ETS(Pop))
report(fit)
```

Series: Pop

Model: ETS(A,A,N)

Smoothing parameters:

alpha = 1

beta = 0.327

Initial states:

l[0] b[0]

10.1 0.222

sigma^2: 0.0041

AIC AICc BIC

-77.0 -75.8 -66.7

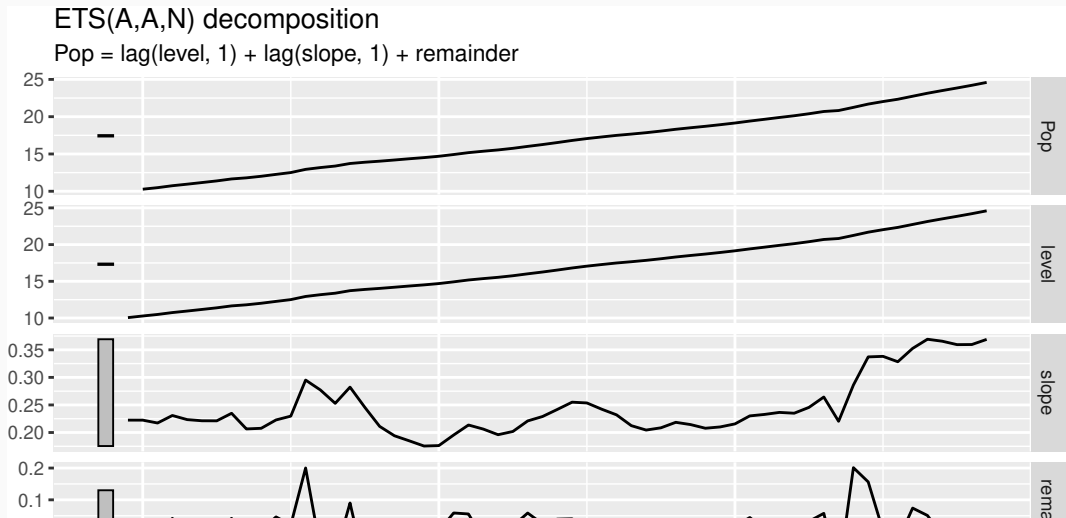
Example: Australian population

```
components(fit)
```

```
# A dable: 59 x 7 [1Y]
# Key:      Country, .model [1]
# :        Pop = lag(level, 1) + lag(slope, 1) + remainder
  Country   .model Year   Pop level slope remainder
  <fct>     <chr>  <dbl> <dbl> <dbl> <dbl>      <dbl>
1 Australia AAN    1959  NA    10.1 0.222  NA
2 Australia AAN    1960  10.3  10.3 0.222 -0.000145
3 Australia AAN    1961  10.5  10.5 0.217 -0.0159
4 Australia AAN    1962  10.7  10.7 0.231  0.0418
5 Australia AAN    1963  11.0  11.0 0.223 -0.0229
6 Australia AAN    1964  11.2  11.2 0.221 -0.00641
7 Australia AAN    1965  11.4  11.4 0.221 -0.000314
8 Australia AAN    1966  11.7  11.7 0.235  0.0418
9 Australia AAN    1967  11.8  11.8 0.206 -0.0869
10 Australia AAN   1968  12.0  12.0 0.208  0.00350
```

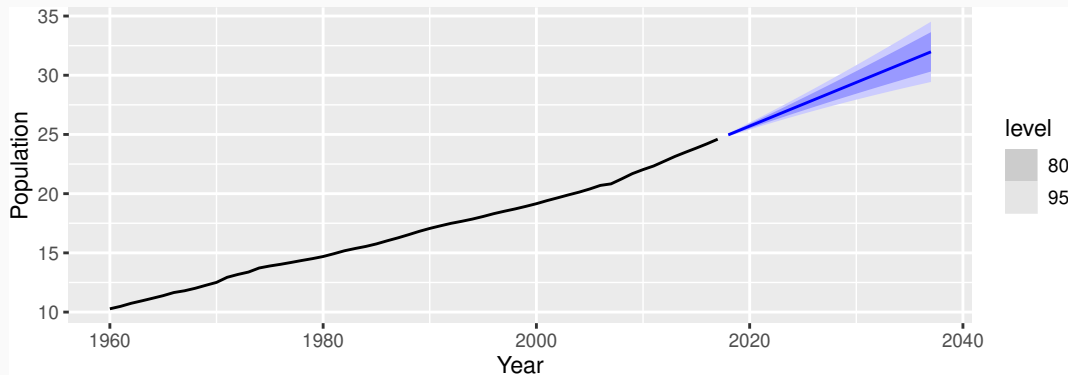
Example: Australian population

```
components(fit) |> autoplot()
```



Example: Australian population

```
fit |>  
  forecast(h = 20) |>  
  autoplot(aus_economy) +  
  labs(y = "Population", x = "Year")
```



ETS(A,Ad,N): Damped trend method

Additive errors

Forecast equation	$\hat{y}_{T+h T} = \ell_T + (\phi + \dots + \phi^{h-1})b_T$
Measurement equation	$y_t = (\ell_{t-1} + \phi b_{t-1}) + \varepsilon_t$
State equations	$\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$
	$b_t = \phi b_{t-1} + \beta \varepsilon_t$

ETS(A,Ad,N): Damped trend method

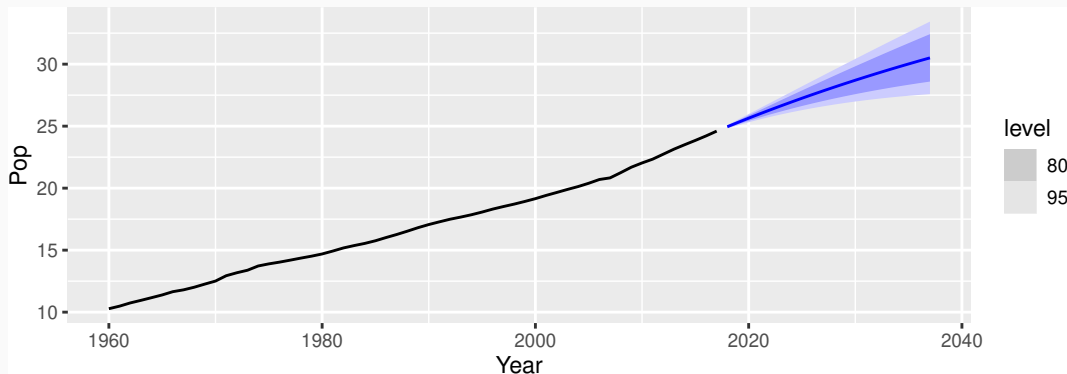
Additive errors

Forecast equation	$\hat{y}_{T+h T} = \ell_T + (\phi + \dots + \phi^{h-1})b_T$
Measurement equation	$y_t = (\ell_{t-1} + \phi b_{t-1}) + \varepsilon_t$
State equations	$\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$
	$b_t = \phi b_{t-1} + \beta \varepsilon_t$

- Damping parameter $0 < \phi < 1$.
- If $\phi = 1$, identical to Holt's linear trend.
- As $h \rightarrow \infty$, $\hat{y}_{T+h|T} \rightarrow \ell_T + \phi b_T / (1 - \phi)$.
- Short-run forecasts trended, long-run forecasts constant.

Example: Australian population

```
aus_economy |>  
  model(holt = ETS(Pop ~ trend("Ad"))) |>  
  forecast(h = 20) |>  
  autoplot(aus_economy)
```



Example: National populations

```
fit <- global_economy |>
  mutate(Pop = Population / 1e6) |>
  model(ets = ETS(Pop))
fit
```

```
# A mable: 263 x 2
```

```
# Key:      Country [263]
```

	Country	ets
	<fct>	<model>
1	Afghanistan	<ETS(A,A,N)>
2	Albania	<ETS(M,A,N)>
3	Algeria	<ETS(M,A,N)>
4	American Samoa	<ETS(M,A,N)>
5	Andorra	<ETS(M,A,N)>
6	Angola	<ETS(M,A,N)>
7	Antigua and Barbuda	<ETS(M,A,N)>
8	Arab World	<ETS(M,A,N)>
9	Argentina	<ETS(A,A,N)>
10	Armenia	<ETS(M,A,N)>
# i 253 more rows		

Example: National populations

```
fit |>  
  forecast(h = 5)
```

```
# A fable: 1,315 x 5 [1Y]
```

```
# Key:      Country, .model [263]
```

	Country	.model	Year	Pop	.mean
	<fct>	<chr>	<dbl>	<dist>	<dbl>
1	Afghanistan	ets	2018	N(36, 0.012)	36.4
2	Afghanistan	ets	2019	N(37, 0.059)	37.3
3	Afghanistan	ets	2020	N(38, 0.16)	38.2
4	Afghanistan	ets	2021	N(39, 0.35)	39.0
5	Afghanistan	ets	2022	N(40, 0.64)	39.9
6	Albania	ets	2018	N(2.9, 0.00012)	2.87
7	Albania	ets	2019	N(2.9, 6e-04)	2.87
8	Albania	ets	2020	N(2.9, 0.0017)	2.87
9	Albania	ets	2021	N(2.9, 0.0036)	2.86

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Lab Session 14

Try forecasting the Chinese GDP from the `global_economy` data set using an ETS model.

Experiment with the various options in the `ETS()` function to see how much the forecasts change with damped trend, or with a Box-Cox transformation. Try to develop an intuition of what each is doing to the forecasts.

[Hint: use `h=20` when forecasting, so you can clearly see the differences between the various options when plotting the forecasts.]

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ETS(A,A,A): Holt-Winters additive method

Forecast equation	$\hat{y}_{t+h t} = \ell_t + hb_t + s_{t+h-m(k+1)}$
Observation equation	$y_t = \ell_{t-1} + b_{t-1} + s_{t-m} + \varepsilon_t$
State equations	$\ell_t = \ell_{t-1} + b_{t-1} + \alpha\varepsilon_t$ $b_t = b_{t-1} + \beta\varepsilon_t$ $s_t = s_{t-m} + \gamma\varepsilon_t$

- $k = \text{integer part of } (h - 1)/m$.
- $\sum_i s_i \approx 0$.
- Parameters: $0 \leq \alpha \leq 1$, $0 \leq \beta \leq 1$, $0 \leq \gamma \leq 1 - \alpha$ and $m = \text{period of seasonality (e.g. } m = 4 \text{ for quarterly data)}$.

ETS(M,A,M): Holt-Winters multiplicative method

Forecast equation	$\hat{y}_{t+h t} = (\ell_t + hb_t)s_{t+h-m(k+1)}$
Observation equation	$y_t = (\ell_{t-1} + b_{t-1})s_{t-m}(1 + \varepsilon_t)$
State equations	$\ell_t = (\ell_{t-1} + b_{t-1})(1 + \alpha\varepsilon_t)$ $b_t = b_{t-1}(1 + \beta\varepsilon_t)$ $s_t = s_{t-m}(1 + \gamma\varepsilon_t)$

- k is integer part of $(h - 1)/m$.
- $\sum_i s_i \approx m$.
- Parameters: $0 \leq \alpha \leq 1$, $0 \leq \beta^* \leq 1$, $0 \leq \gamma \leq 1 - \alpha$ and $m = \text{period of seasonality (e.g. } m = 4 \text{ for quarterly data)}$.

Example: Australian holiday tourism

```
holidays <- tourism |>
  filter(Purpose == "Holiday")
fit <- holidays |> model(ets = ETS(Trips))
fit
```

A mable: 76 x 4

Key: Region, State, Purpose [76]

	Region	State	Purpose	ets
	<chr>	<chr>	<chr>	<model>
1	Adelaide	South Australia	Holiday	<ETS(A,N,A)>
2	Adelaide Hills	South Australia	Holiday	<ETS(A,A,N)>
3	Alice Springs	Northern Territory	Holiday	<ETS(M,N,A)>
4	Australia's Coral Coast	Western Australia	Holiday	<ETS(M,N,A)>
5	Australia's Golden Outback	Western Australia	Holiday	<ETS(M,N,M)>
6	Australia's North West	Western Australia	Holiday	<ETS(A,N,A)>
7	Australia's South West	Western Australia	Holiday	<ETS(M,N,M)>
8	Ballarat	Victoria	Holiday	<ETS(M,N,A)>
9	Barkly	Northern Territory	Holiday	<ETS(A,N,A)>
10	Barossa	South Australia	Holiday	<ETS(A,N,N)>

Example: Australian holiday tourism

```
fit |>  
  filter(Region == "Snowy Mountains") |>  
  report()
```

Series: Trips

Model: ETS(M,N,A)

Smoothing parameters:

alpha = 0.157

gamma = 1e-04

Initial states:

l[0] s[0] s[-1] s[-2] s[-3]

142 -61 131 -42.2 -27.7

sigma^2: 0.0388

AIC AICc BIC

852 854 869

Example: Australian holiday tourism

```
fit |>  
  filter(Region == "Snowy Mountains") |>  
  components(fit)
```

```
# A dable: 84 x 9 [1Q]
```

```
# Key:      Region, State, Purpose, .model [1]
```

```
# :      Trips = (lag(level, 1) + lag(season, 4)) * (1 + remainder)
```

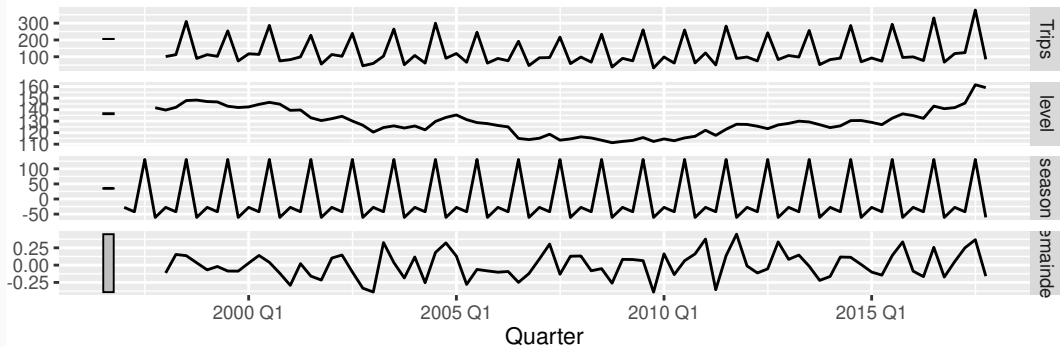
	Region <chr>	State <chr>	Purpose <chr>	.model <chr>	Quarter <qtr>	Trips <dbl>	level <dbl>	season <dbl>	remainder <dbl>
1	Snowy Mountai~	New	~ Holiday	ets	1997 Q1	NA	NA	-27.7	NA
2	Snowy Mountai~	New	~ Holiday	ets	1997 Q2	NA	NA	-42.2	NA
3	Snowy Mountai~	New	~ Holiday	ets	1997 Q3	NA	NA	131.	NA
4	Snowy Mountai~	New	~ Holiday	ets	1997 Q4	NA	142.	-61.0	NA
5	Snowy Mountai~	New	~ Holiday	ets	1998 Q1	101.	140.	-27.7	-0.113
6	Snowy Mountai~	New	~ Holiday	ets	1998 Q2	112.	142.	-42.2	0.154
7	Snowy Mountai~	New	~ Holiday	ets	1998 Q3	310.	148.	131.	0.137
8	Snowy Mountai~	New	~ Holiday	ets	1998 Q4	89.8	148.	-61.0	0.0335
9	Snowy Mountai~	New	~ Holiday	ets	1999 Q1	112.	147.	-27.7	-0.0687
10	Snowy Mountai~	New	~ Holiday	ets	1999 Q2	103.	147.	-42.2	-0.0199

Example: Australian holiday tourism

```
fit |>  
  filter(Region == "Snowy Mountains") |>  
  components(fit) |>  
  autoplot()
```

ETS(M,N,A) decomposition

$\text{Trips} = (\text{lag}(\text{level}, 1) + \text{lag}(\text{season}, 4)) * (1 + \text{remainder})$



Example: Australian holiday tourism

```
fit |> forecast()
```

```
# A fable: 608 x 7 [1Q]
```

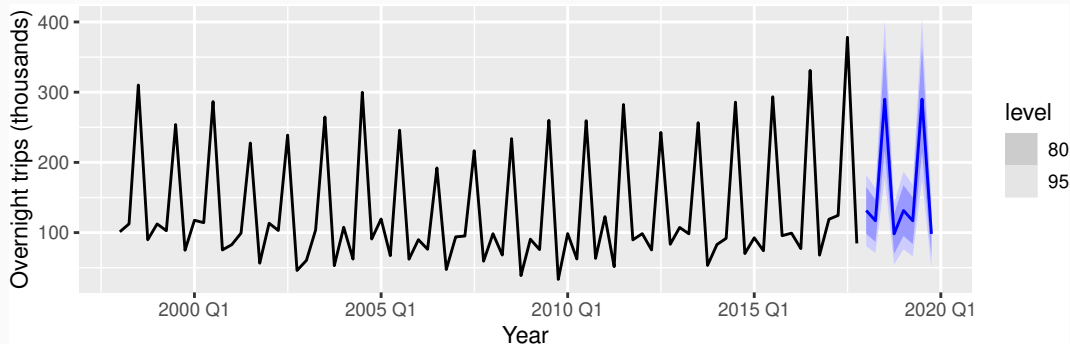
```
# Key:      Region, State, Purpose, .model [76]
```

	Region	State	Purpose	.model	Quarter	Trips	.mean
	<chr>	<chr>	<chr>	<chr>	<qtr>	<dist>	<dbl>
1	Adelaide	South Australia	Holiday	ets	2018 Q1	N(210, 457)	210.
2	Adelaide	South Australia	Holiday	ets	2018 Q2	N(173, 473)	173.
3	Adelaide	South Australia	Holiday	ets	2018 Q3	N(169, 489)	169.
4	Adelaide	South Australia	Holiday	ets	2018 Q4	N(186, 505)	186.
5	Adelaide	South Australia	Holiday	ets	2019 Q1	N(210, 521)	210.
6	Adelaide	South Australia	Holiday	ets	2019 Q2	N(173, 537)	173.
7	Adelaide	South Australia	Holiday	ets	2019 Q3	N(169, 553)	169.
8	Adelaide	South Australia	Holiday	ets	2019 Q4	N(186, 569)	186.
9	Adelaide Hills	South Australia	Holiday	ets	2018 Q1	N(19, 36)	19.4
10	Adelaide Hills	South Australia	Holiday	ets	2018 Q2	N(20, 36)	19.6

```
# i 598 more rows
```

Example: Australian holiday tourism

```
fit |>  
  forecast() |>  
  filter(Region == "Snowy Mountains") |>  
  autoplot(holidays) +  
  labs(x = "Year", y = "Overnight trips (thousands)")
```



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Exponential smoothing models

Additive Error

		Seasonal Component		
		N (None)	A (Additive)	M (Multiplicative)
Trend Component	N (None)	A,N,N	A,N,A	A,N,M
	A (Additive)	A,A,N	A,A,A	A,A,M
	A _d (Additive damped)	A,A _d ,N	A,A _d ,A	A,A_d,M

Multiplicative Error

		Seasonal Component		
		N (None)	A (Additive)	M (Multiplicative)
Trend Component	N (None)	M,N,N	M,N,A	M,N,M
	A (Additive)	M,A,N	M,A,A	M,A,M
	A _d (Additive damped)	M,A _d ,N	M,A _d ,A	M,A _d ,M

Estimating ETS models

- Smoothing parameters α, β, γ and ϕ , and the initial states $\ell_0, b_0, s_0, s_{-1}, \dots, s_{-m+1}$ are estimated by maximising the “likelihood” = the probability of the data arising from the specified model.
- For models with additive errors equivalent to minimising SSE.
- For models with multiplicative errors, **not** equivalent to minimising SSE.

Model selection

Akaike's Information Criterion

$$\text{AIC} = -2 \log(L) + 2k$$

where L is the likelihood and k is the number of parameters & initial states estimated in the model.

Model selection

Akaike's Information Criterion

$$AIC = -2 \log(L) + 2k$$

where L is the likelihood and k is the number of parameters & initial states estimated in the model.

Corrected AIC

$$AIC_c = AIC + \frac{2k(k+1)}{T - k - 1}$$

which is the AIC corrected (for small sample bias).

Model selection

Akaike's Information Criterion

$$\text{AIC} = -2 \log(L) + 2k$$

where L is the likelihood and k is the number of parameters & initial states estimated in the model.

Corrected AIC

$$\text{AIC}_c = \text{AIC} + \frac{2k(k+1)}{T - k - 1}$$

which is the AIC corrected (for small sample bias).

Bayesian Information Criterion

$$\text{BIC} = \text{AIC} + k(\log(T) - 2).$$

AIC and cross-validation

Minimizing the AIC assuming Gaussian residuals is asymptotically equivalent to minimizing one-step time series cross validation MSE.

Automatic forecasting

From Hyndman et al. (IJF, 2002):

- 1 Apply each model that is appropriate to the data.
Optimize parameters and initial values using MLE.
 - 2 Select best method using AICc.
 - 3 Produce forecasts using best method.
 - 4 Obtain forecast intervals using underlying state space model.
- Method performed very well in M3 competition.
 - Used as a benchmark in the M4 competition.

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Lab Session 15

Find an ETS model for the Gas data from `aus_production`.

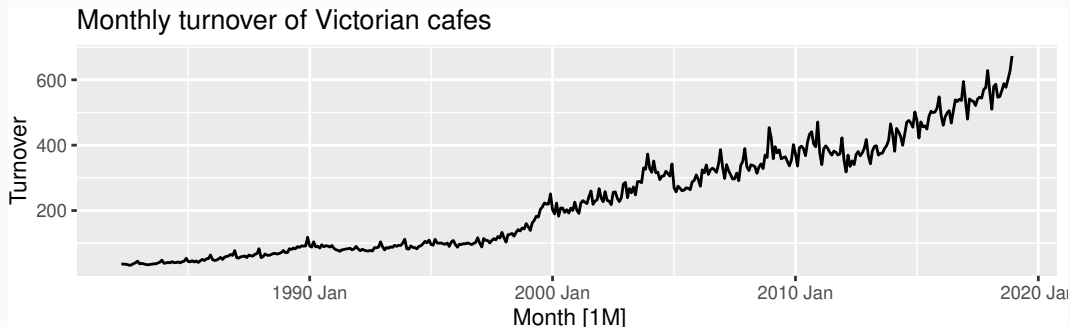
- Why is multiplicative seasonality necessary here?
- Experiment with making the trend damped. Does it improve the forecasts?

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- 6 Lab Session 15
- 7 Non-Gaussian forecast distributions**

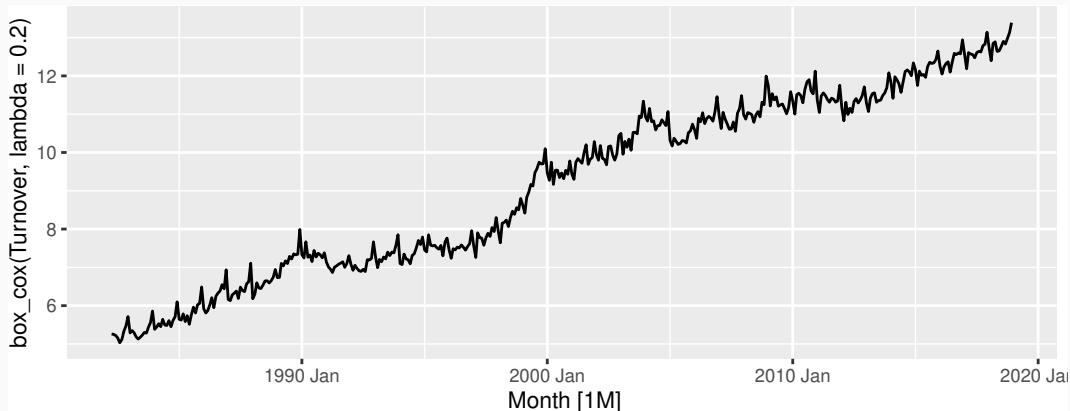
Non-Gaussian forecast distributions

```
vic_cafe <- tsibbledata::aus_retail |>
  filter(State == "Victoria",
         Industry == "Cafes, restaurants and catering services") |>
  select(Month, Turnover)
vic_cafe |>
  autoplot(Turnover) + labs(title = "Monthly turnover of Victorian cafes")
```



Forecasting with transformations

```
vic_cafe |> autoplot(box_cox(Turnover, lambda = 0.2))
```



Forecasting with transformations

```
fit <- vic_cafe |>  
  model(ets = ETS(box_cox(Turnover, 0.2)))  
fit
```

```
# A mable: 1 x 1  
  ets  
  <model>  
1 <ETS(A,A,A)>
```

```
(fc <- fit |> forecast(h = "3 years"))
```

```
# A fable: 36 x 4 [1M]  
# Key:      .model [1]  
  .model      Month      Turnover .mean  
  <chr>      <mth>      <dist> <dbl>  
1 ets      2019 Jan  t(N(13, 0.02)) 608.  
2 ets      2019 Feb  t(N(13, 0.028)) 563.  
3 ets      2019 Mar  t(N(13, 0.036)) 629.  
4 ets      2019 Apr  t(N(13, 0.044)) 615.  
5 ets      2019 May  t(N(13, 0.052)) 613.  
6 ets      2019 Jun  t(N(13, 0.061)) 593.
```

Forecasting with transformations

```
fit <- vic_cafe |>  
  model(ets = ETS(box_cox(Turnover, 0.2)))  
fit
```

```
# A mable: 1 x 1  
      ets  
  <model>  
1 <ETS(A,A,A)>
```

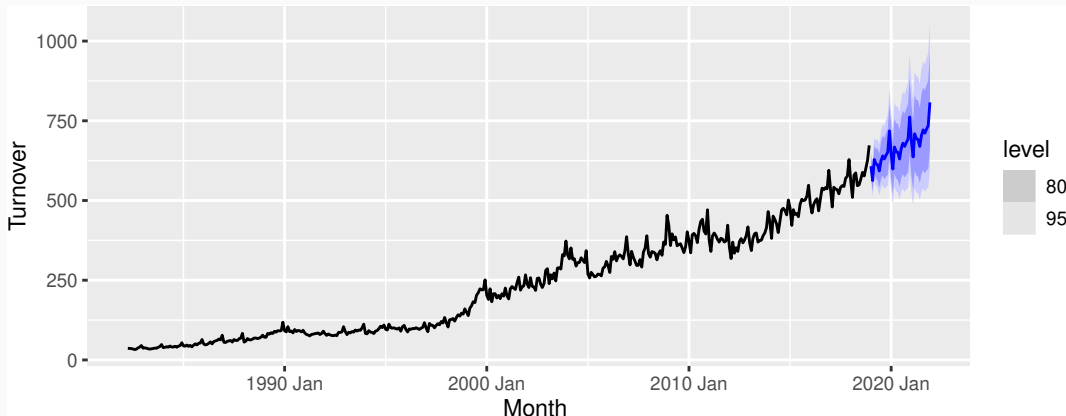
```
(fc <- fit |> forecast(h = "3 years"))
```

```
# A fable: 36 x 4 [1M]  
# Key:      .model [1]  
  .model    Month      Turnover .mean  
  <chr>     <mth>      <dist> <dbl>  
1 ets      2019 Jan    t(N(13, 0.02)) 608.  
2 ets      2019 Feb    t(N(13, 0.028)) 563.  
3 ets      2019 Mar    t(N(13, 0.036)) 629.  
4 ets      2019 Apr    t(N(13, 0.044)) 615.  
5 ets      2019 May    t(N(13, 0.052)) 613.  
6 ets      2019 Jun    t(N(13, 0.061)) 593.
```

- $t(N)$ denotes a transformed normal distribution.
- back-transformation and bias adjustment is done automatically.

Forecasting with transformations

```
fc |> autoplot(vic_cafe)
```



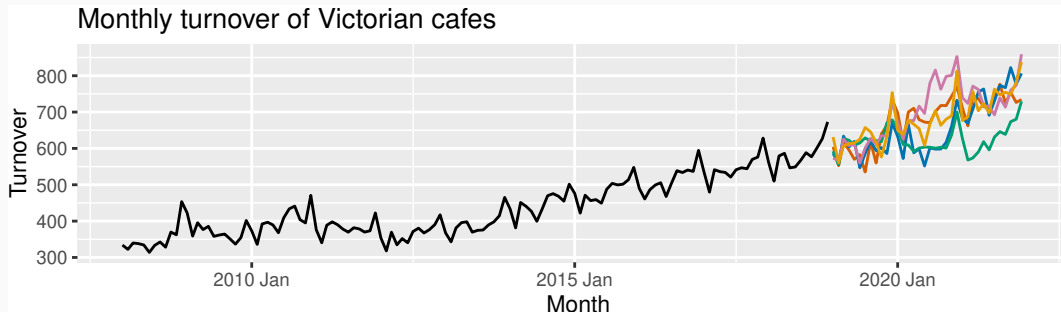
Bootstrapped forecast distributions

```
sim <- fit |> generate(h = "3 years", times = 5, bootstrap = TRUE)
sim
```

```
# A tsibble: 180 x 5 [1M]
# Key:       .model, .rep [5]
  .model .rep   Month .innov .sim
  <chr>  <chr>   <mth>  <dbl> <dbl>
1 ets    1      2019 Jan -0.0193 604.
2 ets    1      2019 Feb -0.0497 552.
3 ets    1      2019 Mar -0.0313 615.
4 ets    1      2019 Apr -0.0467 595.
5 ets    1      2019 May -0.160  570.
6 ets    1      2019 Jun  0.141  583.
7 ets    1      2019 Jul -0.434  535.
8 ets    1      2019 Aug  0.264  618.
9 ets    1      2019 Sep -0.203  560.
10 ets   1      2019 Oct  0.342  640.
# i 170 more rows
```

Bootstrapped forecast distributions

```
vic_cafe |>  
  filter(year(Month) >= 2008) |>  
  ggplot(aes(x = Month)) +  
  geom_line(aes(y = Turnover)) +  
  geom_line(aes(y = .sim, colour = as.factor(.rep)), data = sim) +  
  labs(title = "Monthly turnover of Victorian cafes") +  
  guides(col = FALSE)
```



Bootstrapped forecast distributions

```
fc <- fit |> forecast(h = "3 years", bootstrap = TRUE)  
fc
```

```
# A fable: 36 x 4 [1M]  
# Key:      .model [1]  
  .model      Month      Turnover .mean  
  <chr>      <mth>      <dist> <dbl>  
1 ets       2019 Jan sample[5000] 608.  
2 ets       2019 Feb sample[5000] 564.  
3 ets       2019 Mar sample[5000] 629.  
4 ets       2019 Apr sample[5000] 615.  
5 ets       2019 May sample[5000] 613.  
6 ets       2019 Jun sample[5000] 593.  
7 ets       2019 Jul sample[5000] 624.  
8 ets       2019 Aug sample[5000] 640.  
9 ets       2019 Sep sample[5000] 631.  
10 ets      2019 Oct sample[5000] 643.  
# i 26 more rows
```

Bootstrapped forecast distributions

```
fc |> autoplot(vic_cafe) +  
  labs(title = "Monthly turnover of Victorian cafes")
```

