

Forecast reconciliation

3. Probabilistic forecast reconciliation

Rob J Hyndman



MONASH University

Photo by Edvard Alexander Rølvaag on Unsplash

robjhyndman.com/fr2023

Outline

- 1 Definition of probabilistic coherence
- 2 Evaluating probabilistic forecasts
- 3 Emergency Services Demand
- 4 Evaluating multivariate probabilistic forecasts
- 5 Example: Australian electricity generation

Outline

- 1 Definition of probabilistic coherence
- 2 Evaluating probabilistic forecasts
- 3 Emergency Services Demand
- 4 Evaluating multivariate probabilistic forecasts
- 5 Example: Australian electricity generation

The coherent subspace

Coherent subspace

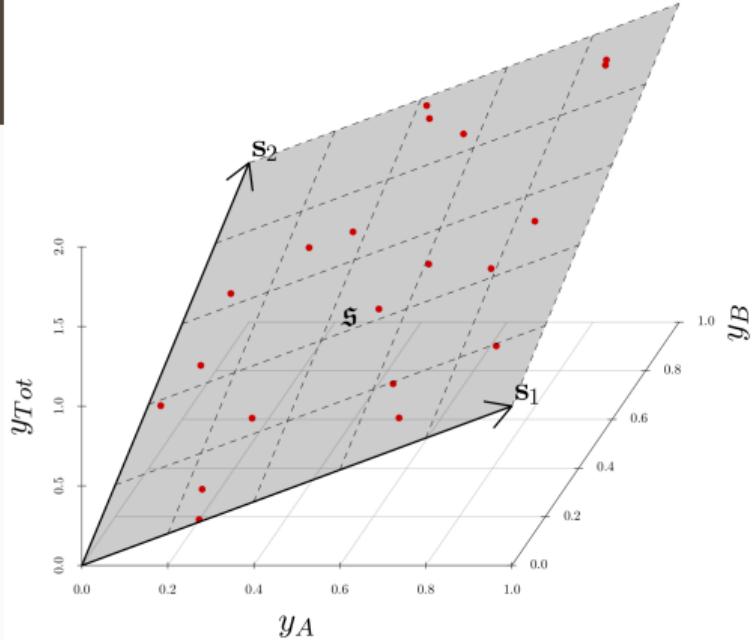
m -dimensional linear subspace $\mathfrak{s} \subset \mathbb{R}^n$ for which linear constraints hold for all $\mathbf{y} \in \mathfrak{s}$.

Hierarchical time series

An n -dimensional multivariate time series such that $\mathbf{y}_t \in \mathfrak{s} \quad \forall t$.

Coherent point forecasts

$\tilde{\mathbf{y}}_{t+h|t}$ is *coherent* if $\tilde{\mathbf{y}}_{t+h|t} \in \mathfrak{s}$.



$$y_{Tot} = y_A + y_B$$

The coherent subspace

Coherent subspace

m -dimensional linear subspace $\mathfrak{s} \subset \mathbb{R}^n$ for which linear constraints hold for all $\mathbf{y} \in \mathfrak{s}$.

Hierarchical time series

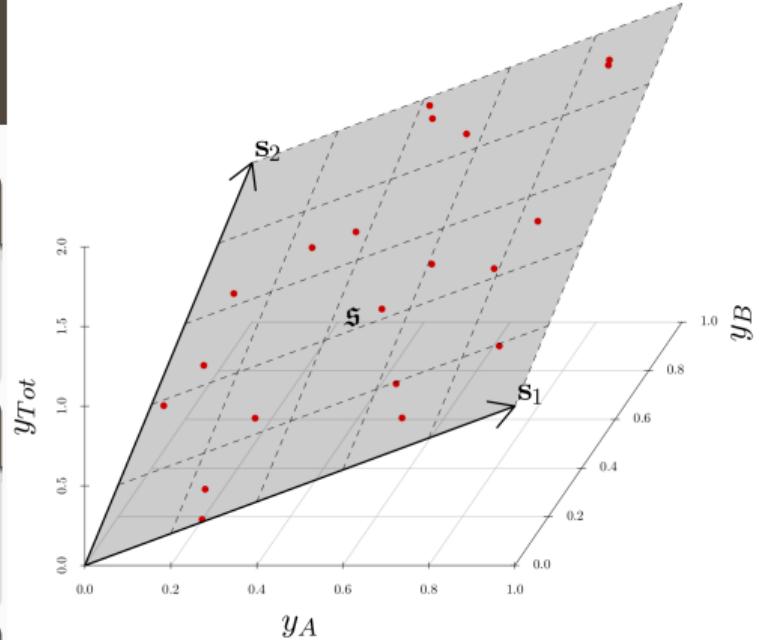
An n -dimensional multivariate time series such that $\mathbf{y}_t \in \mathfrak{s} \quad \forall t$.

Coherent point forecasts

$\tilde{\mathbf{y}}_{t+h|t}$ is *coherent* if $\tilde{\mathbf{y}}_{t+h|t} \in \mathfrak{s}$.

Base forecasts

Let $\hat{\mathbf{y}}_{t+h|t}$ be vector of *incoherent* initial h -step forecasts.



$$y_{Tot} = y_A + y_B$$

The coherent subspace

Coherent subspace

m -dimensional linear subspace $\mathfrak{s} \subset \mathbb{R}^n$ for which linear constraints hold for all $\mathbf{y} \in \mathfrak{s}$.

Hierarchical time series

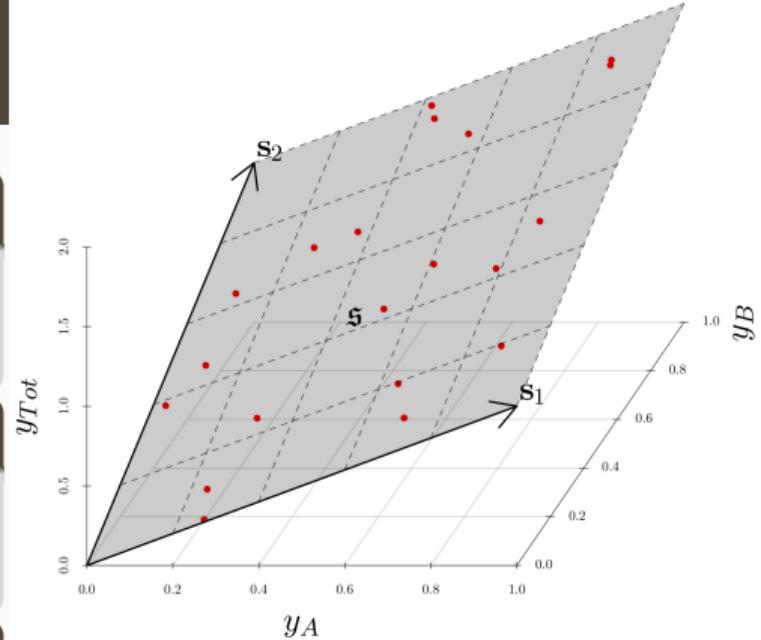
An n -dimensional multivariate time series such that $\mathbf{y}_t \in \mathfrak{s} \quad \forall t$.

Coherent point forecasts

$\tilde{\mathbf{y}}_{t+h|t}$ is *coherent* if $\tilde{\mathbf{y}}_{t+h|t} \in \mathfrak{s}$.

Base forecasts

Let $\hat{\mathbf{y}}_{t+h|t}$ be vector of *incoherent* initial h -step forecasts.



$$y_{Tot} = y_A + y_B$$

Reconciled forecasts

Let ψ be a mapping, $\psi : \mathbb{R}^n \rightarrow \mathfrak{s}$.
 $\tilde{\mathbf{y}}_{t+h|t} = \psi(\hat{\mathbf{y}}_{t+h|t})$ “reconciles” $\hat{\mathbf{y}}_{t+h|t}$.

Coherent probabilistic forecasts

Coherent probabilistic forecasts

Given the triple $(\mathbb{R}^m, \mathcal{F}_{\mathbb{R}^m}, \nu)$, a coherent probability triple $(\mathfrak{s}, \mathcal{F}_{\mathfrak{s}}, \check{\nu})$ is such that

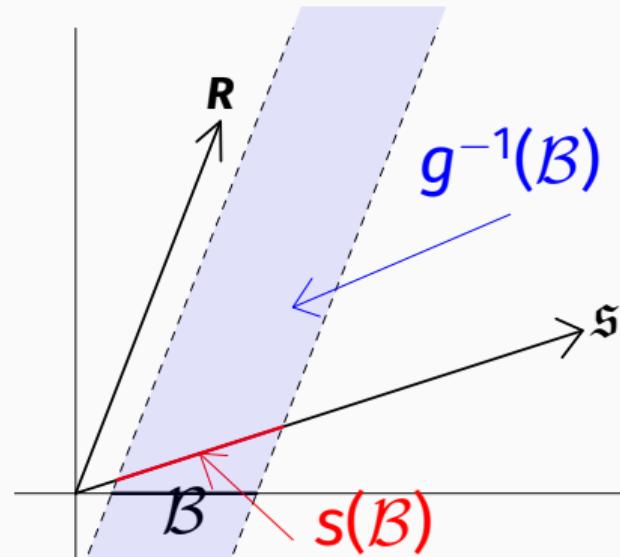
$$\check{\nu}(s(\mathcal{B})) = \nu(\mathcal{B}) \quad \forall \mathcal{B} \in \mathcal{F}_{\mathbb{R}^m}$$

Probabilistic forecast reconciliation

The reconciled probability measure of $\hat{\nu}$ wrt $\psi(\cdot)$ is such that

$$\tilde{\nu}(\mathcal{B}) = \hat{\nu}(\psi^{-1}(\mathcal{B})) \quad \forall \mathcal{B} \in \mathcal{F}_{\mathfrak{s}}$$

where $\psi^{-1}(\mathcal{B}) := \{\mathbf{y} \in \mathbb{R}^n : \psi(\mathbf{y}) \in \mathcal{B}\}$ is the pre-image of \mathcal{B} , that is the set of all points in \mathbb{R}^n that $\psi(\cdot)$ maps to a point in \mathcal{B} .



$$\psi = s \circ g$$

Construction of reconciled distributions

Reconciled density of bottom-level

Density of bottom-level series under reconciled distribution is

$$\tilde{f}_b(\mathbf{b}) = |\mathbf{G}^*| \int \hat{f}(\mathbf{G}^- \mathbf{b} + \mathbf{G}_\perp \mathbf{a}) d\mathbf{a}$$

- \hat{f} is density of incoherent base probabilistic forecasts
- \mathbf{G}^- is $n \times m$ generalised inverse of \mathbf{G} st $\mathbf{G}\mathbf{G}^- = \mathbf{I}$
- \mathbf{G}_\perp is $n \times (n - m)$ orthogonal complement to \mathbf{G} st $\mathbf{G}\mathbf{G}_\perp = \mathbf{0}$
- $\mathbf{G}^* = (\mathbf{G}^- : \mathbf{G}_\perp)$, and \mathbf{b} and \mathbf{a} are obtained via

the change of variables $\mathbf{y} = \mathbf{G}^* \begin{pmatrix} \mathbf{b} \\ \mathbf{a} \end{pmatrix}$

Construction of reconciled distributions

Reconciled density of full hierarchy

Density of full hierarchy under reconciled distribution is

$$\tilde{f}_y(\mathbf{y}) = |\mathbf{S}^*| \tilde{f}_b(\mathbf{S}^- \mathbf{y}) \mathbb{1}\{\mathbf{y} \in \mathfrak{s}\}$$

- $\mathbf{S}^* = (\mathbf{S}^{-'} \quad \mathbf{S}_{\perp})'$
- \mathbf{S}^- is $m \times n$ generalised inverse of \mathbf{S} such that $\mathbf{S}^- \mathbf{S} = \mathbf{I}$
- \mathbf{S}_{\perp} is $n \times (n - m)$ orthogonal complement to \mathbf{S} : $\mathbf{S}'_{\perp} \mathbf{S} = \mathbf{0}$

Construction of reconciled distributions

Reconciled density of full hierarchy

Density of full hierarchy under reconciled distribution is

$$\tilde{f}_y(\mathbf{y}) = |\mathbf{S}^*| \tilde{f}_b(\mathbf{S}^- \mathbf{y}) \mathbb{1}\{\mathbf{y} \in \mathfrak{s}\}$$

- $\mathbf{S}^* = (\mathbf{S}^{-'} \quad \mathbf{S}_{\perp})'$
- \mathbf{S}^- is $m \times n$ generalised inverse of \mathbf{S} such that $\mathbf{S}^- \mathbf{S} = \mathbf{I}$
- \mathbf{S}_{\perp} is $n \times (n - m)$ orthogonal complement to \mathbf{S} : $\mathbf{S}'_{\perp} \mathbf{S} = \mathbf{0}$

Gaussian reconciliation

If the incoherent base forecasts are $N(\hat{\mu}, \hat{\Sigma})$, then the reconciled density is $N(\mathbf{S}\mathbf{G}\hat{\mu}, \mathbf{S}\mathbf{G}\hat{\Sigma}\mathbf{G}'\mathbf{S}')$

Construction of reconciled distributions

Reconciled density of full hierarchy

Density of full hierarchy under reconciled distribution is

$$\tilde{f}_y(\mathbf{y}) = |\mathbf{S}^*| \tilde{f}_b(\mathbf{S}^- \mathbf{y}) \mathbb{1}\{\mathbf{y} \in \mathfrak{s}\}$$

- $\mathbf{S}^* = (\mathbf{S}^{-'} \quad \mathbf{S}_{\perp})'$
- \mathbf{S}^- is $m \times n$ generalised inverse of \mathbf{S} such that $\mathbf{S}^- \mathbf{S} = \mathbf{I}$
- \mathbf{S}_{\perp} is $n \times (n - m)$ orthogonal complement to \mathbf{S} : $\mathbf{S}'_{\perp} \mathbf{S} = \mathbf{0}$

Gaussian reconciliation

If the incoherent base forecasts are $N(\hat{\mu}, \hat{\Sigma})$, then the reconciled density is $N(\mathbf{S}\mathbf{G}\hat{\mu}, \mathbf{S}\mathbf{G}\hat{\Sigma}\mathbf{G}'\mathbf{S}')$

Elliptical reconciliation

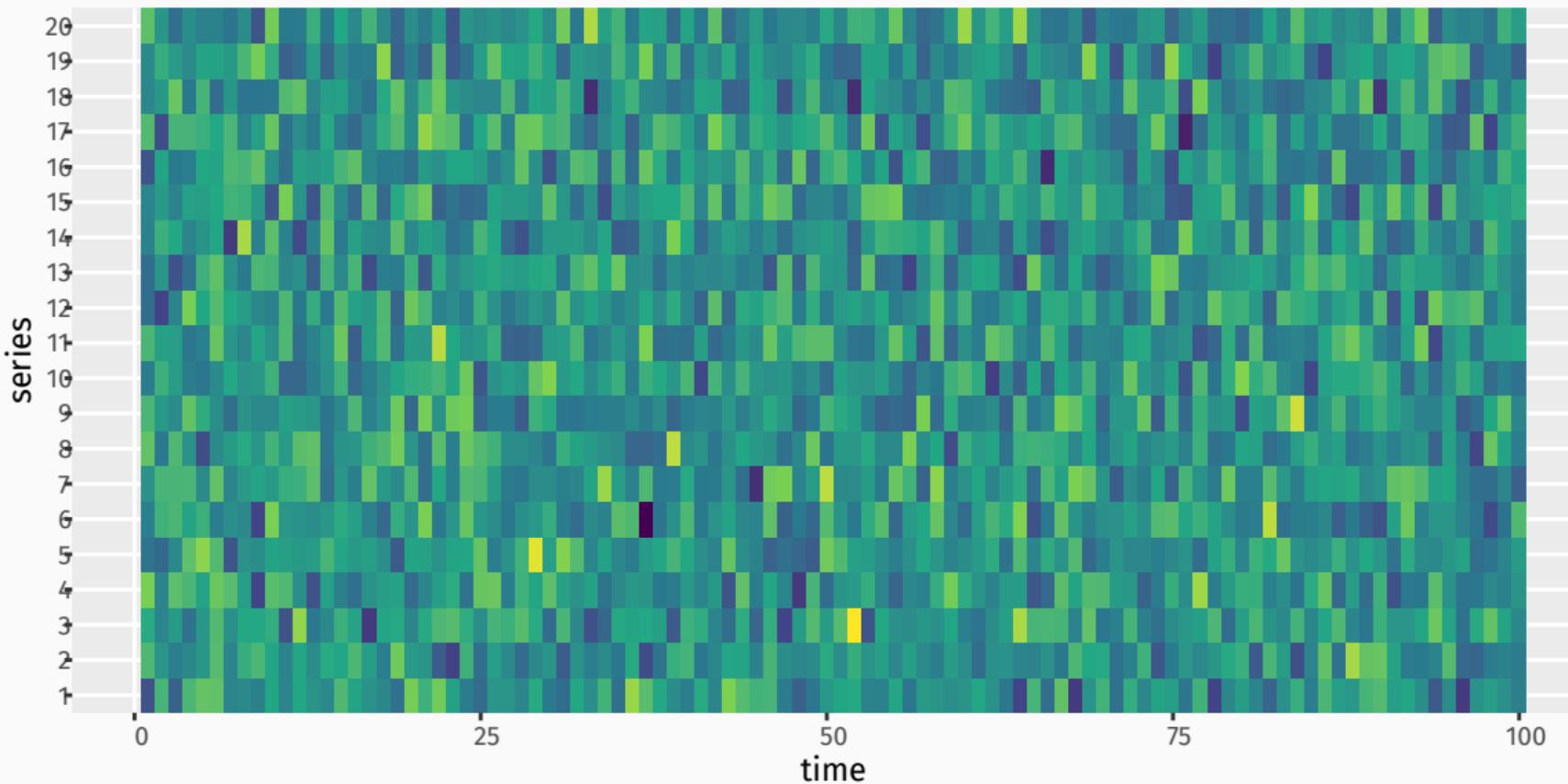
An elliptical distribution is obtained if the base forecasts are elliptical, unbiased, and $\text{rank}(\hat{\Sigma} - \Sigma) \leq n_a$

Simulation from a reconciled distribution

Suppose that $(\hat{\mathbf{y}}^{[1]}, \dots, \hat{\mathbf{y}}^{[L]})$ is a sample drawn from an incoherent probability measure $\hat{\nu}$. Then $(\tilde{\mathbf{y}}^{[1]}, \dots, \tilde{\mathbf{y}}^{[L]})$ where $\tilde{\mathbf{y}}^{[\ell]} := \psi(\hat{\mathbf{y}}^{[\ell]})$ for $\ell = 1, \dots, L$, is a sample drawn from the reconciled probability measure $\tilde{\nu}$.

- Simulate future sample paths for each series, by simulating from each model using a multivariate bootstrap of the residuals.
- Reconcile the sample paths.
- The reconciled sample paths are a sample from the reconciled distribution.

Simulation from a reconciled distribution



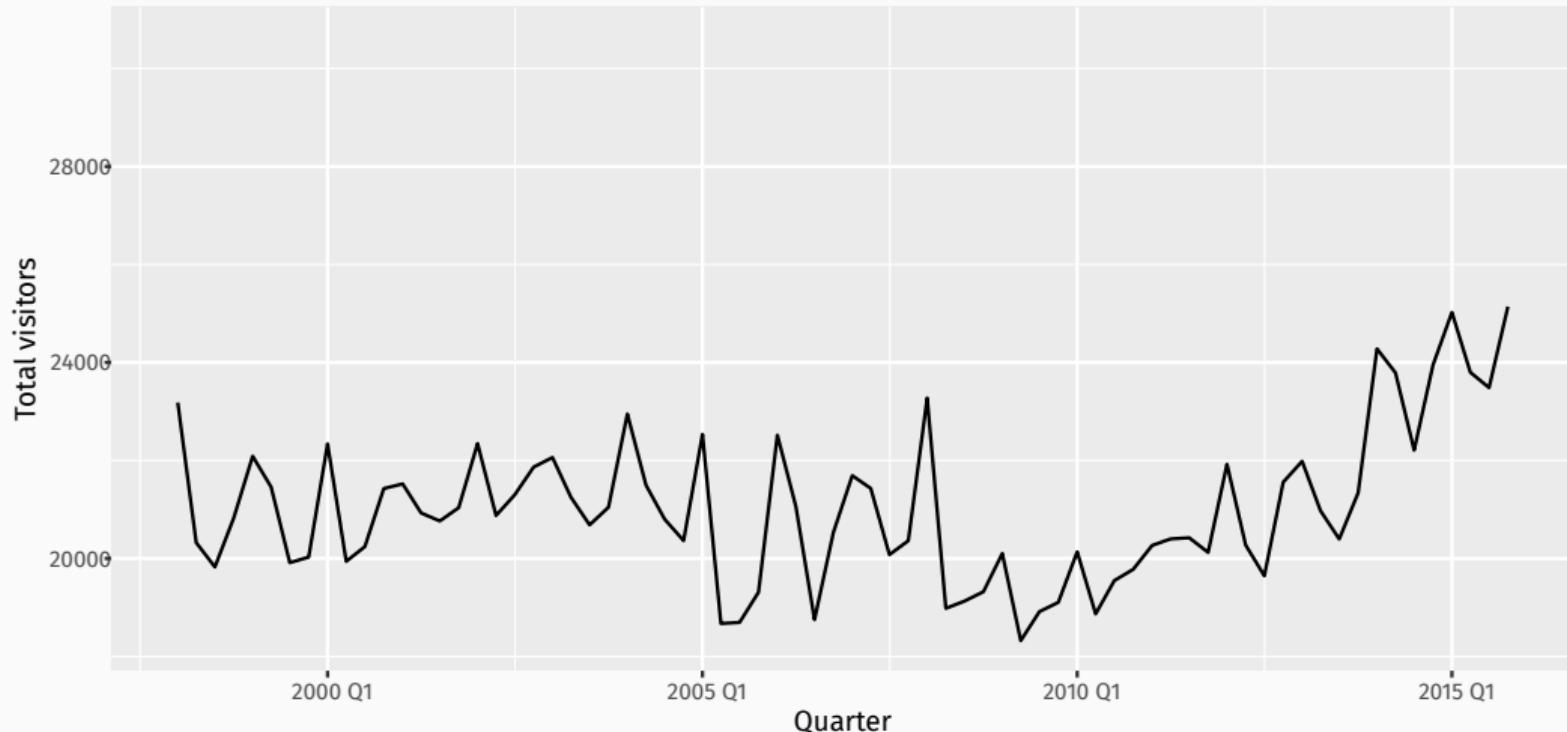
Simulation from a reconciled distribution

Outline

- 1 Definition of probabilistic coherence
- 2 Evaluating probabilistic forecasts
- 3 Emergency Services Demand
- 4 Evaluating multivariate probabilistic forecasts
- 5 Example: Australian electricity generation

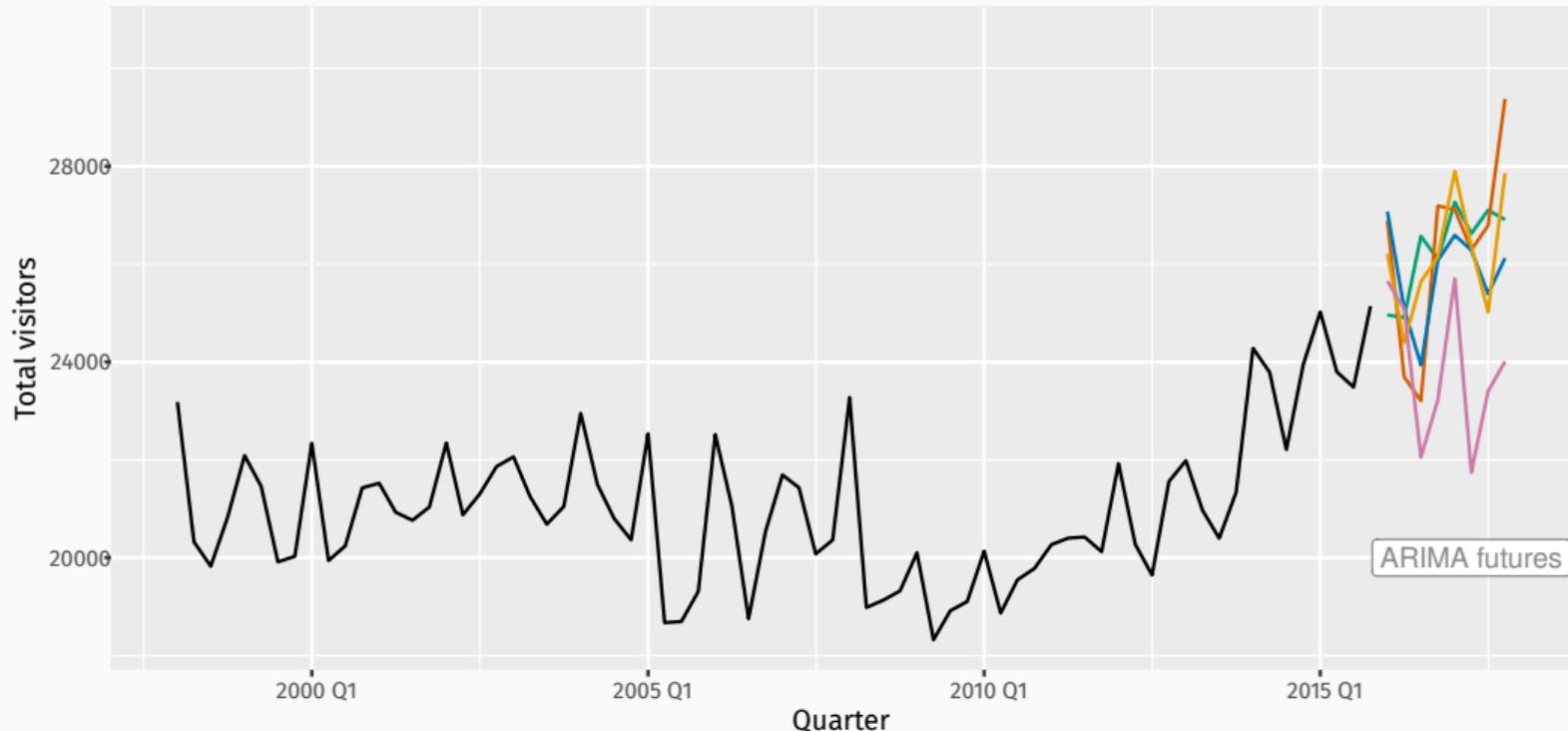
Evaluating probabilistic forecasts

Australian domestic tourism



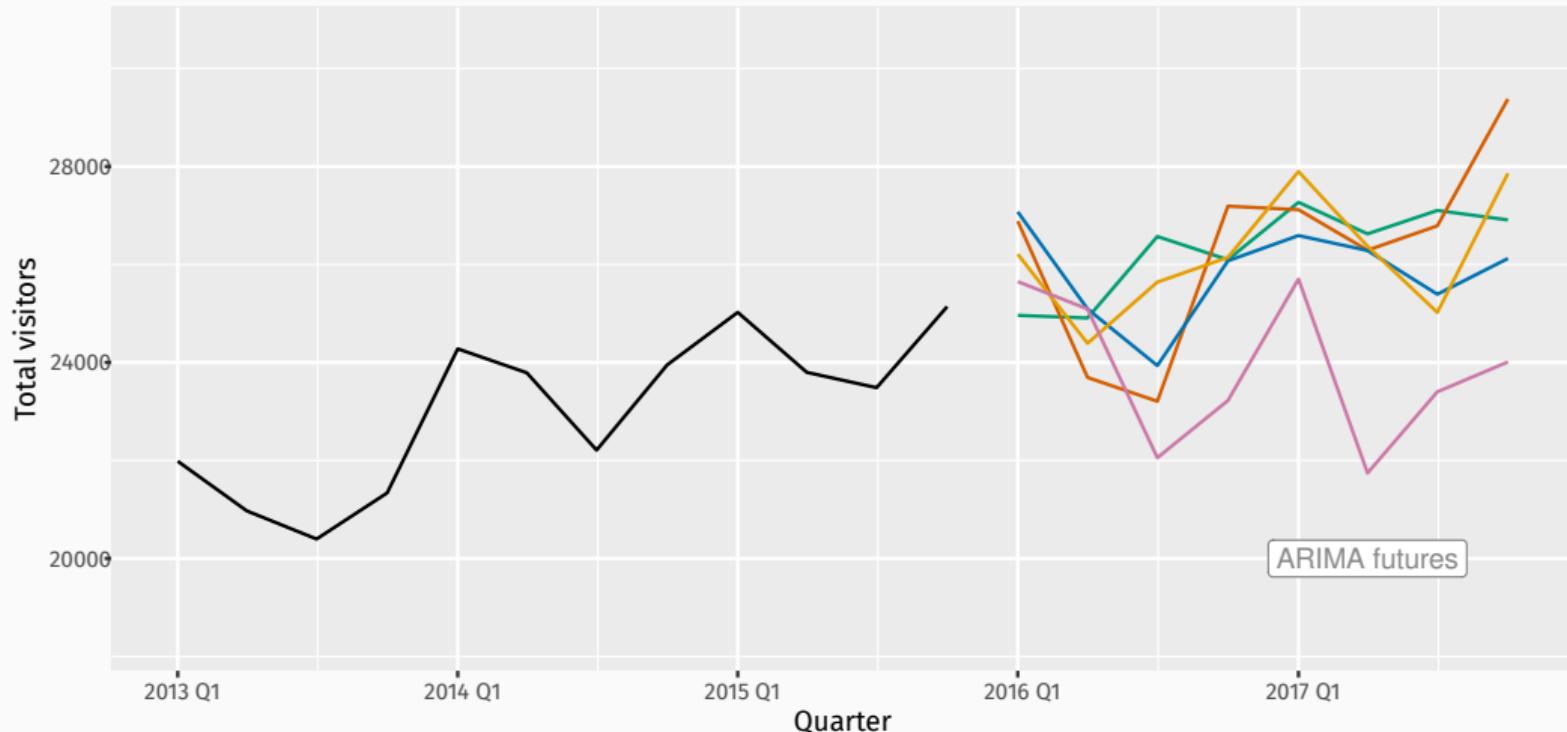
Evaluating probabilistic forecasts

Australian domestic tourism



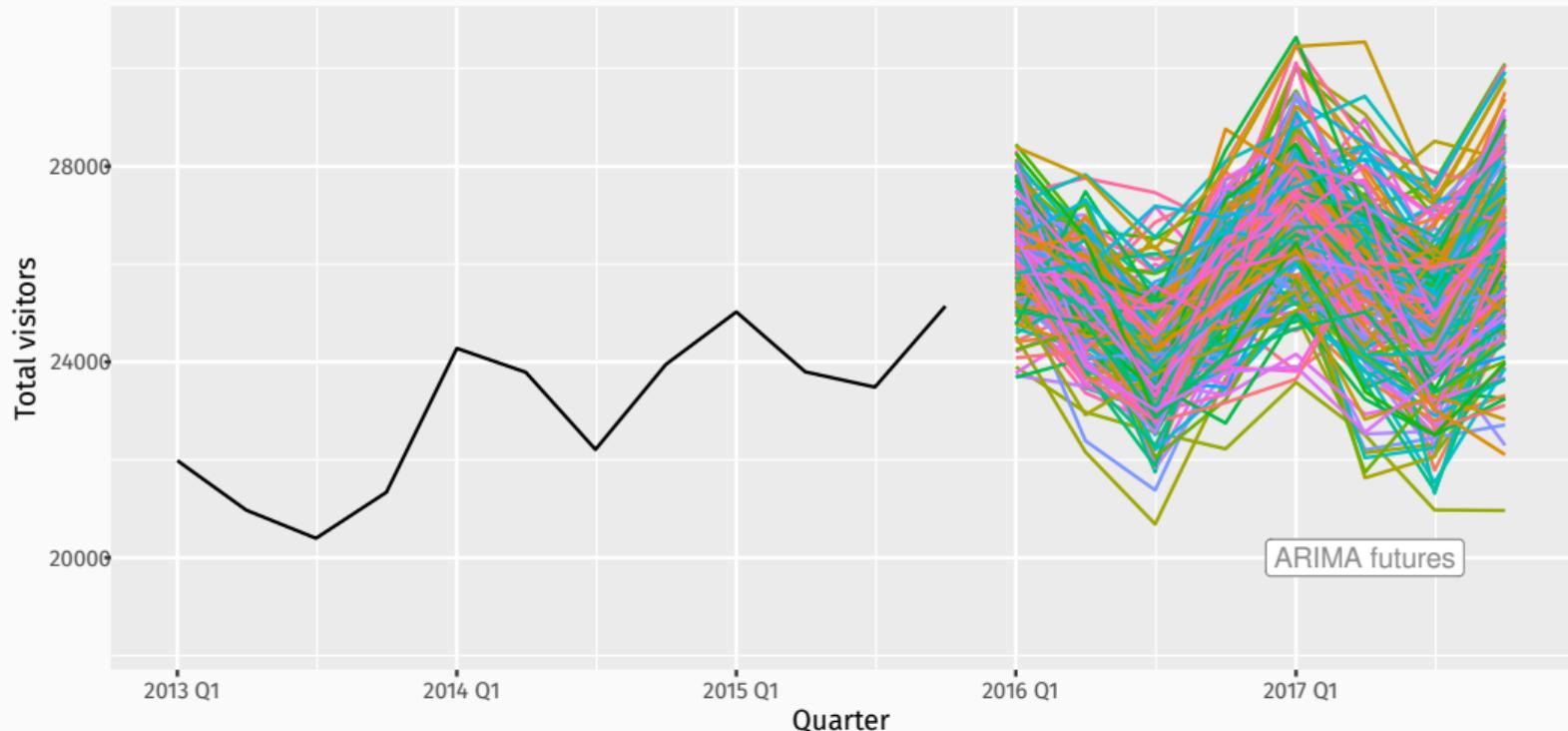
Evaluating probabilistic forecasts

Australian domestic tourism



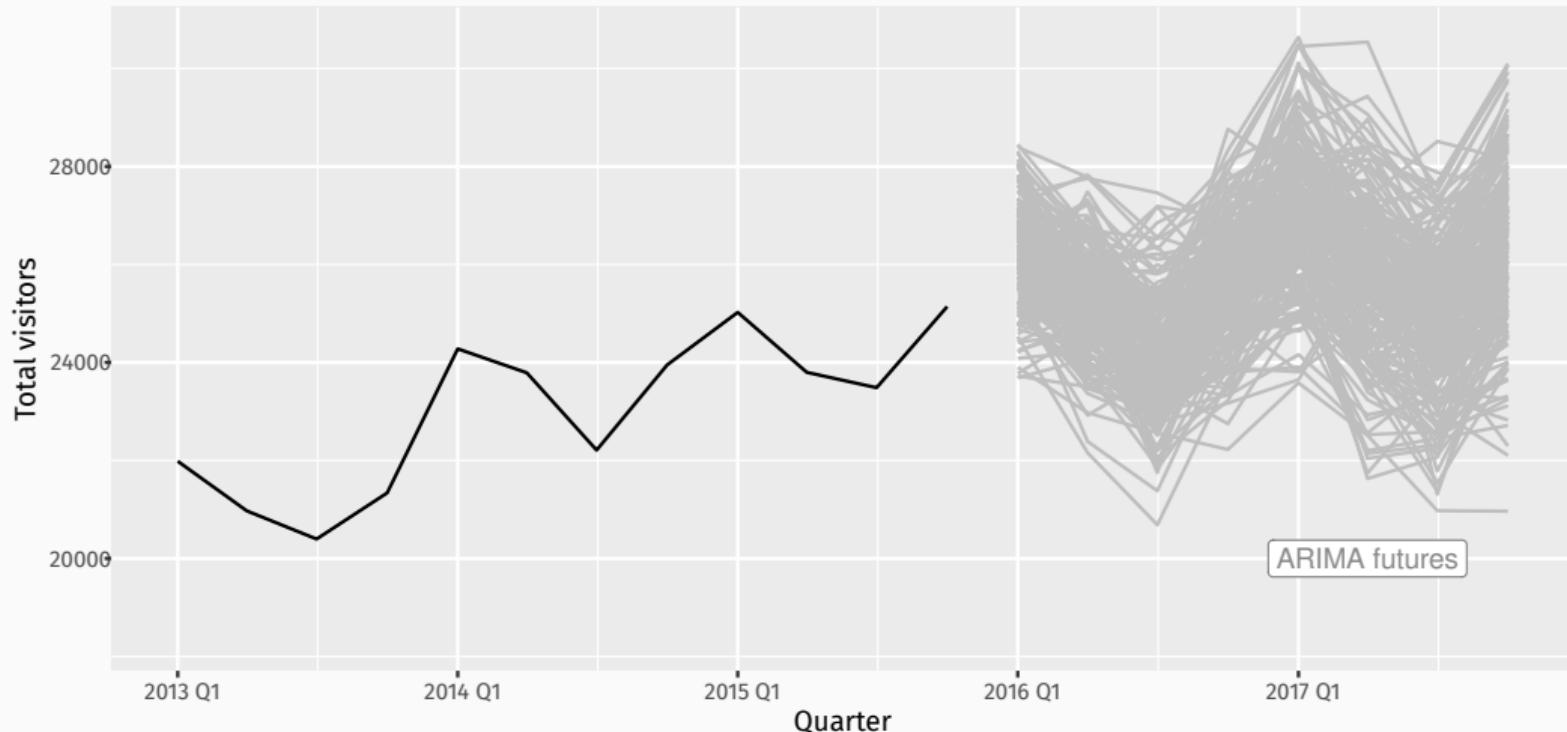
Evaluating probabilistic forecasts

Australian domestic tourism



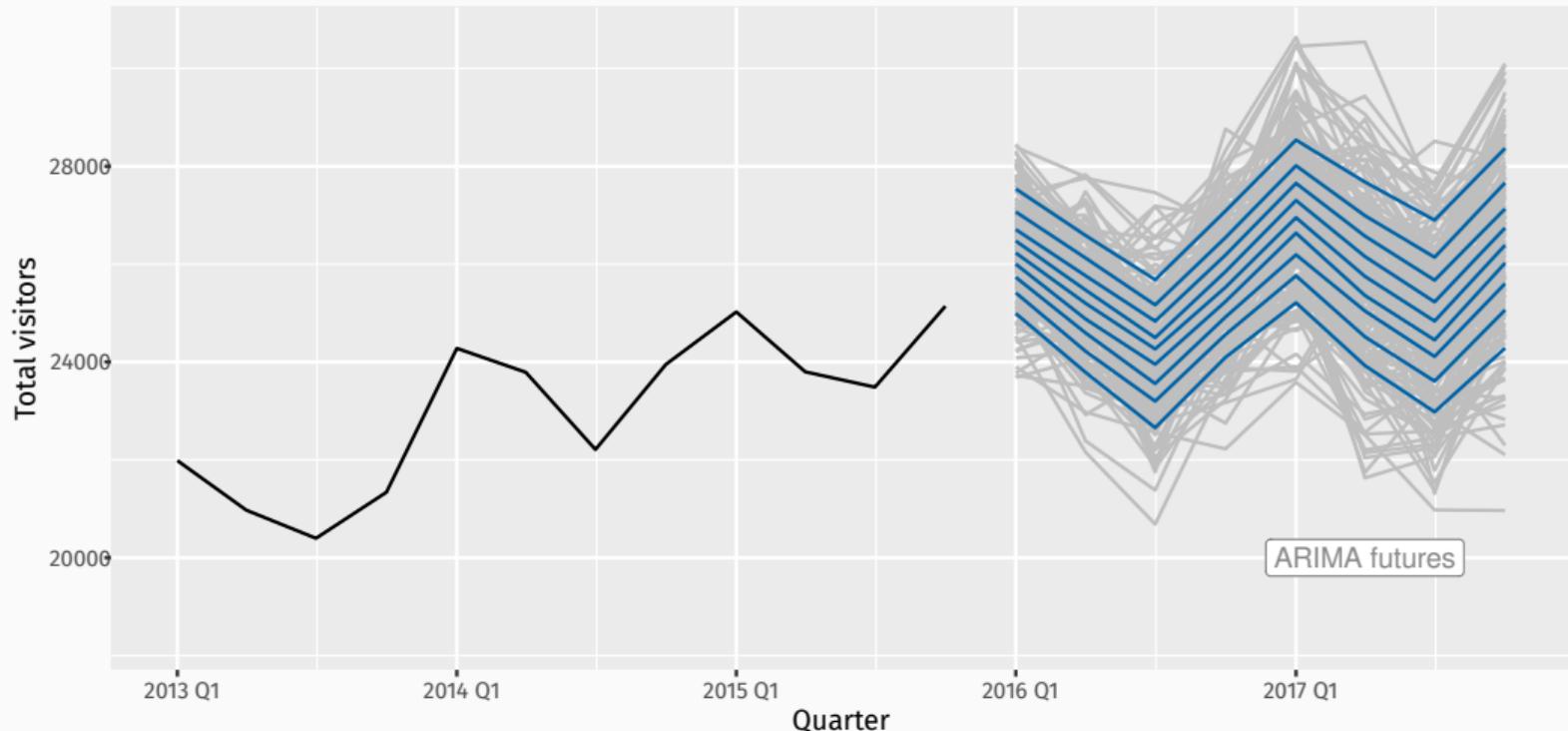
Evaluating probabilistic forecasts

Australian domestic tourism



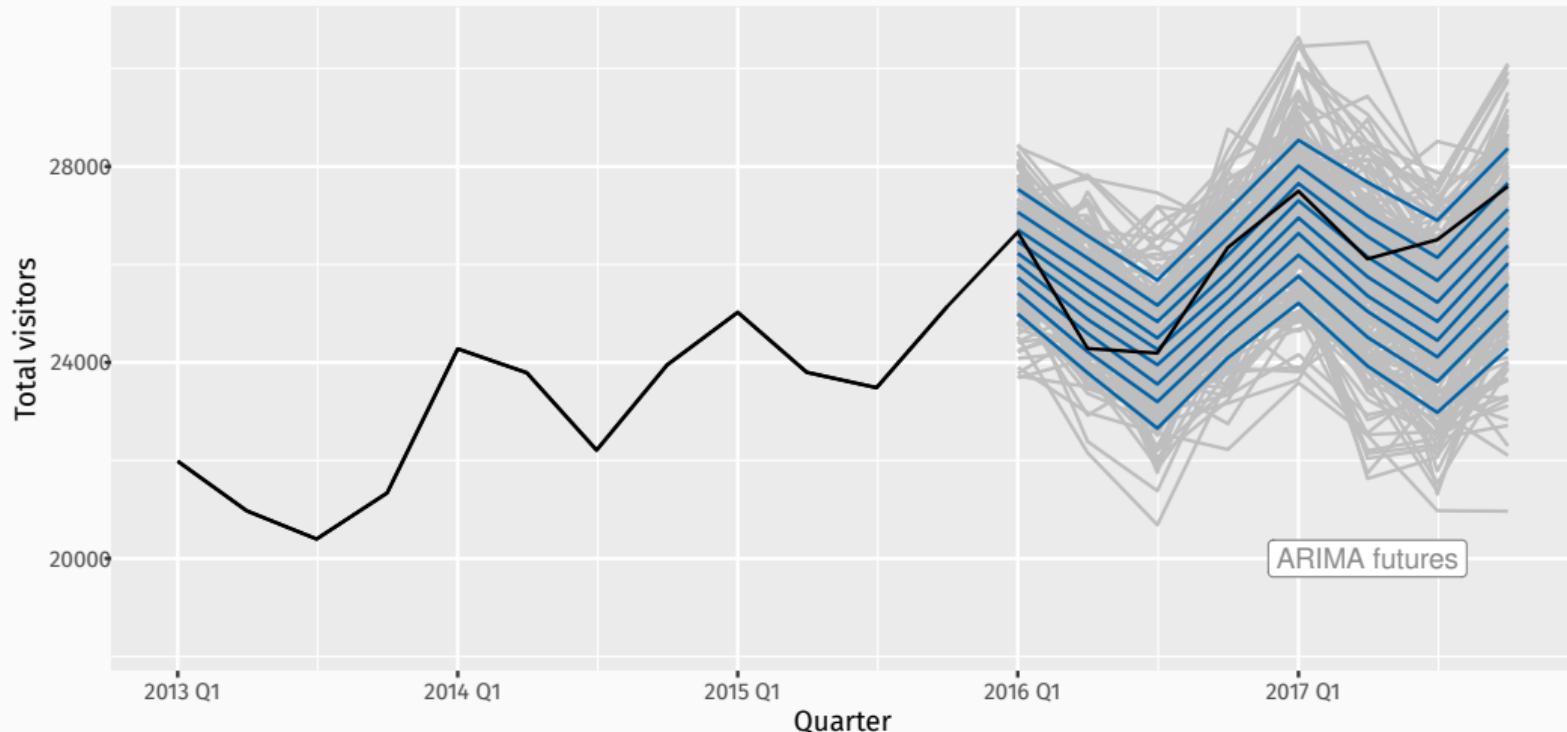
Evaluating probabilistic forecasts

Australian domestic tourism



Evaluating probabilistic forecasts

Australian domestic tourism



ARIMA futures

Evaluating probabilistic forecasts

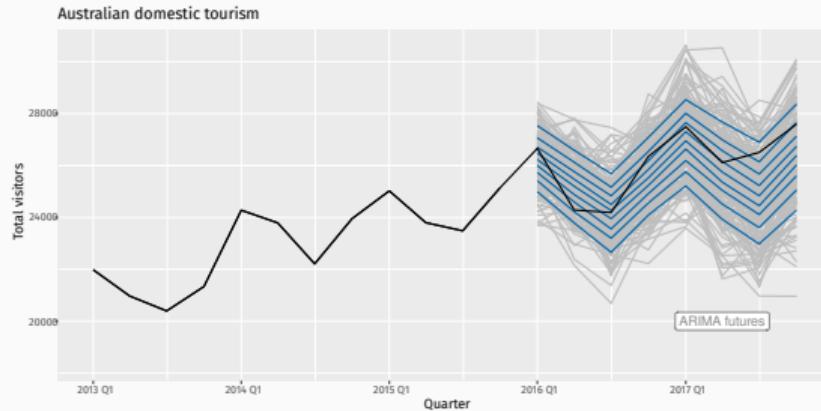
y_t = observation at time t

$q_{p,t}$ = quantile forecast: prob. p , time t

Quantile score

$$S_t(p, y) = \begin{cases} 2(1 - p)|y_t - q_{p,t}|, & \text{if } y_t < q_{p,t} \\ 2p|y_t - q_{p,t}|, & \text{if } y_t \geq q_{p,t} \end{cases}$$

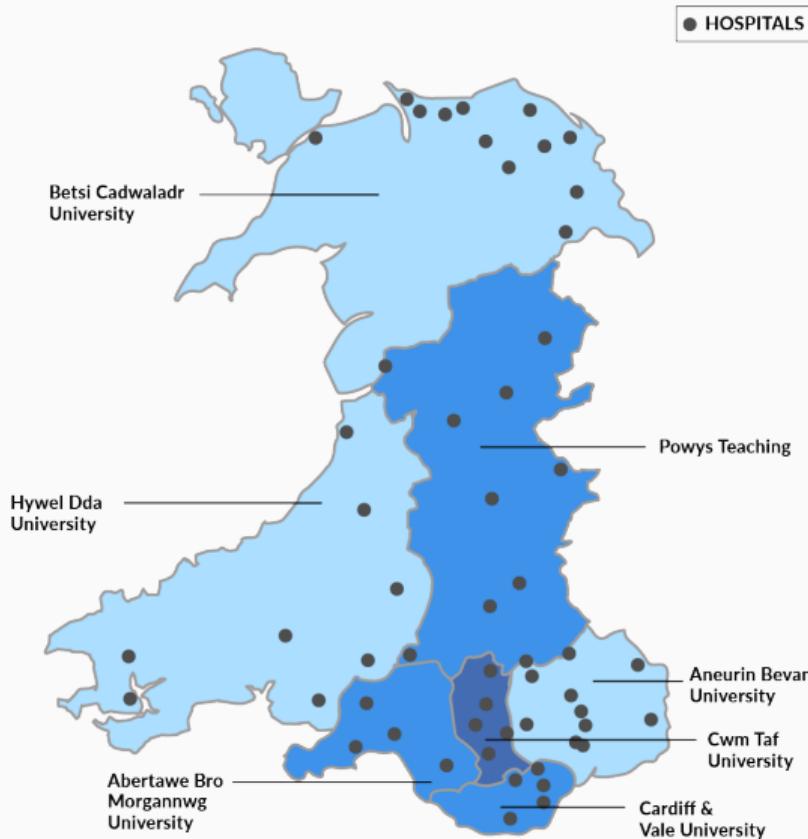
- Low S_t is good
- Multiplier of 2 often omitted, but useful for interpretation
- S_t like absolute error, weighted to account for likely exceedance
- Average $S_t(p, y)$ over p = CRPS (Continuous Rank Probability Score)



Outline

- 1 Definition of probabilistic coherence
- 2 Evaluating probabilistic forecasts
- 3 Emergency Services Demand
- 4 Evaluating multivariate probabilistic forecasts
- 5 Example: Australian electricity generation

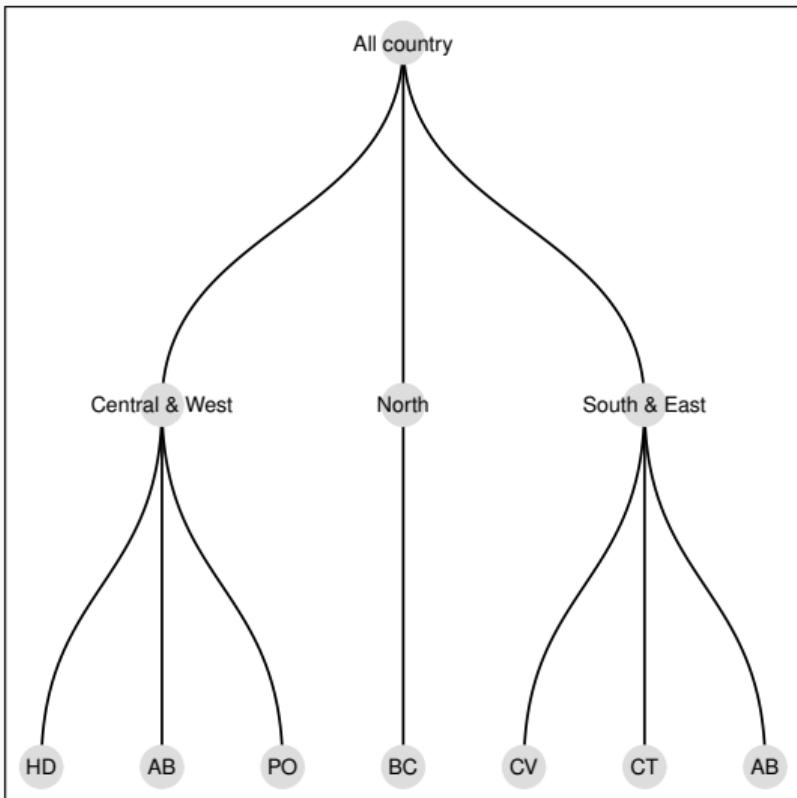
Wales Health Board Areas



Data

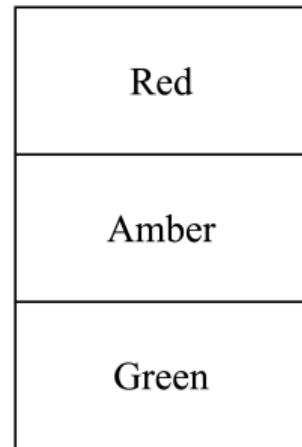
- Daily number of attended incidents:
1 October 2015 – 31 July 2019
- Disaggregated by:
 - ▶ control area
 - ▶ health board
 - ▶ priority
 - ▶ nature of incidents
- 2,142,000 rows observations from 1,530 time series.

Data structure



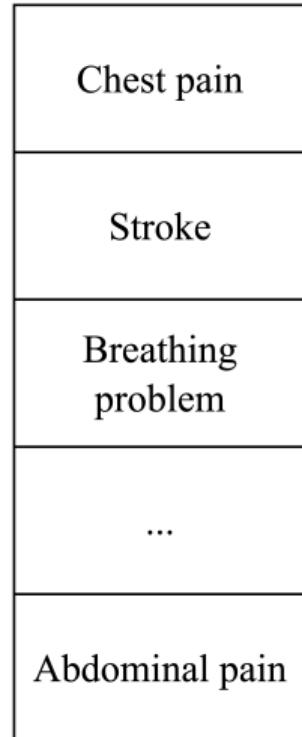
*

Priority



*

Nature of incident



Data structure

Level	Number of series
All country	1
Control	3
Health board	7
Priority	3
Priority * Control	9
Priority * Health board	21
Nature of incident	35
Nature of incident * Control	105
Nature of incident * Health board	245
Priority * Nature of incident	104
Control * Priority * Nature of incident	306
Control * Health board * Priority * Nature of incident (Bottom level)	691
Total	1530

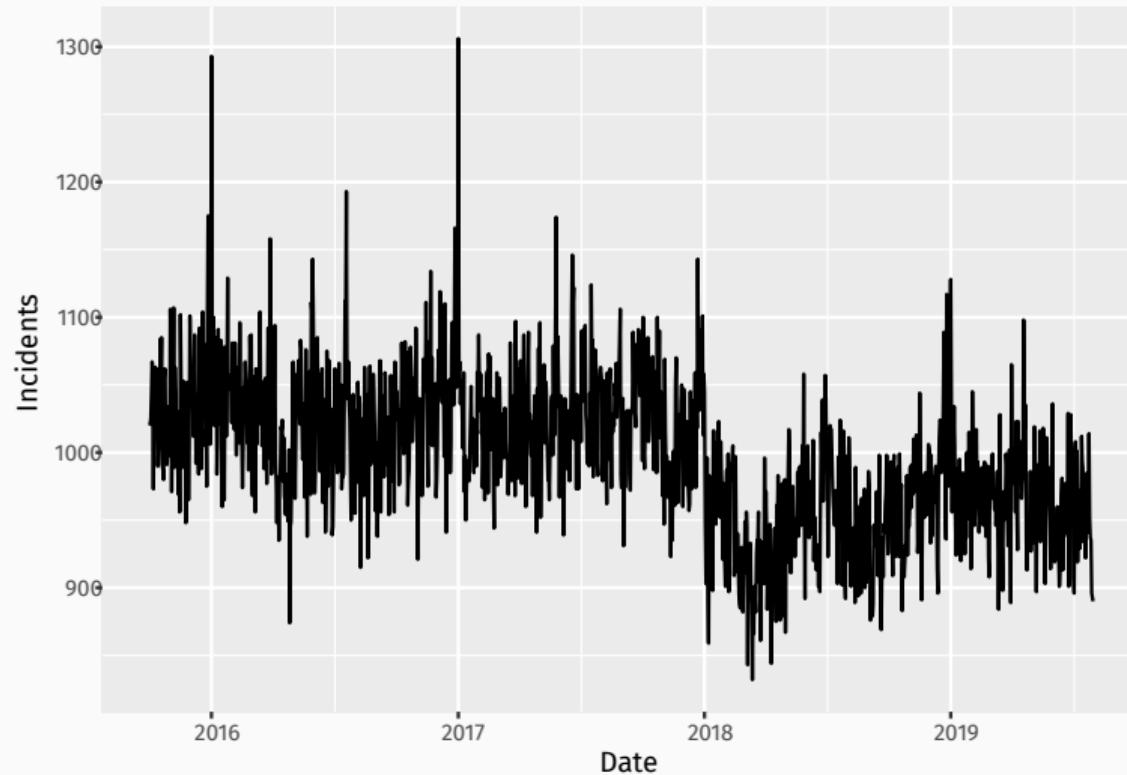
Data

```
# A tsibble: 2,142,000 x 6 [1D]
# Key:      region, category, nature, lhb [1,530]
  date      region     category     nature      lhb      incident
  <date>    <chr*>     <chr*>     <chr*>     <chr*>     <dbl>
1 2015-10-01 <aggregated> <aggregated> <aggregated> <aggregated> 1020
2 2015-10-02 <aggregated> <aggregated> <aggregated> <aggregated> 1021
3 2015-10-03 <aggregated> <aggregated> <aggregated> <aggregated> 1025
4 2015-10-04 <aggregated> <aggregated> <aggregated> <aggregated> 1043
5 2015-10-05 <aggregated> <aggregated> <aggregated> <aggregated> 1067
6 2015-10-06 <aggregated> <aggregated> <aggregated> <aggregated> 1063
7 2015-10-07 <aggregated> <aggregated> <aggregated> <aggregated> 973
8 2015-10-08 <aggregated> <aggregated> <aggregated> <aggregated> 1057
9 2015-10-09 <aggregated> <aggregated> <aggregated> <aggregated> 1026
10 2015-10-10 <aggregated> <aggregated> <aggregated> <aggregated> 1063
# i 2,141,990 more rows
```

Data

```
# A tsibble: 2,142,000 x 6 [1D]
# Key:      region, category, nature, lhb [1,530]
  date      region category nature    lhb      incident
  <date>    <chr*>  <chr*>   <chr*>  <chr*>    <dbl>
1 2015-10-01 C       Amber   ABDOMINAL HD        0
2 2015-10-01 C       Amber   ABDOMINAL PO        0
3 2015-10-01 C       Amber   ABDOMINAL SB        0
4 2015-10-01 C       Amber   ABDOMINAL <aggregated> 0
5 2015-10-01 C       Amber   ALLERGIES HD        0
6 2015-10-01 C       Amber   ALLERGIES PO        1
7 2015-10-01 C       Amber   ALLERGIES SB        0
8 2015-10-01 C       Amber   ALLERGIES <aggregated> 1
9 2015-10-01 C       Amber   ANIMALBIT HD        0
10 2015-10-01 C      Amber   ANIMALBIT PO       0
# i 2,141,990 more rows
```

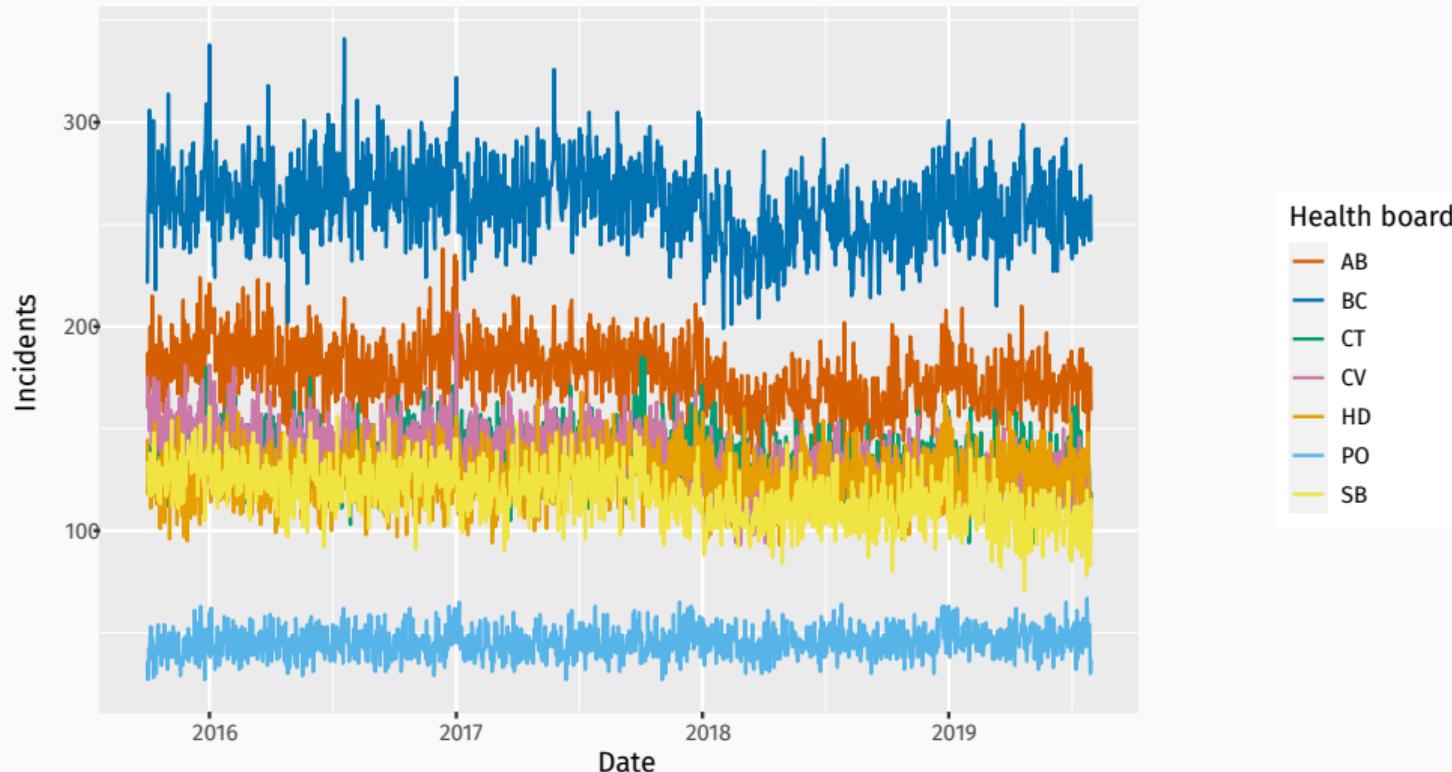
Aggregated daily incidents



Daily incidents by control area



Data incidents by health board



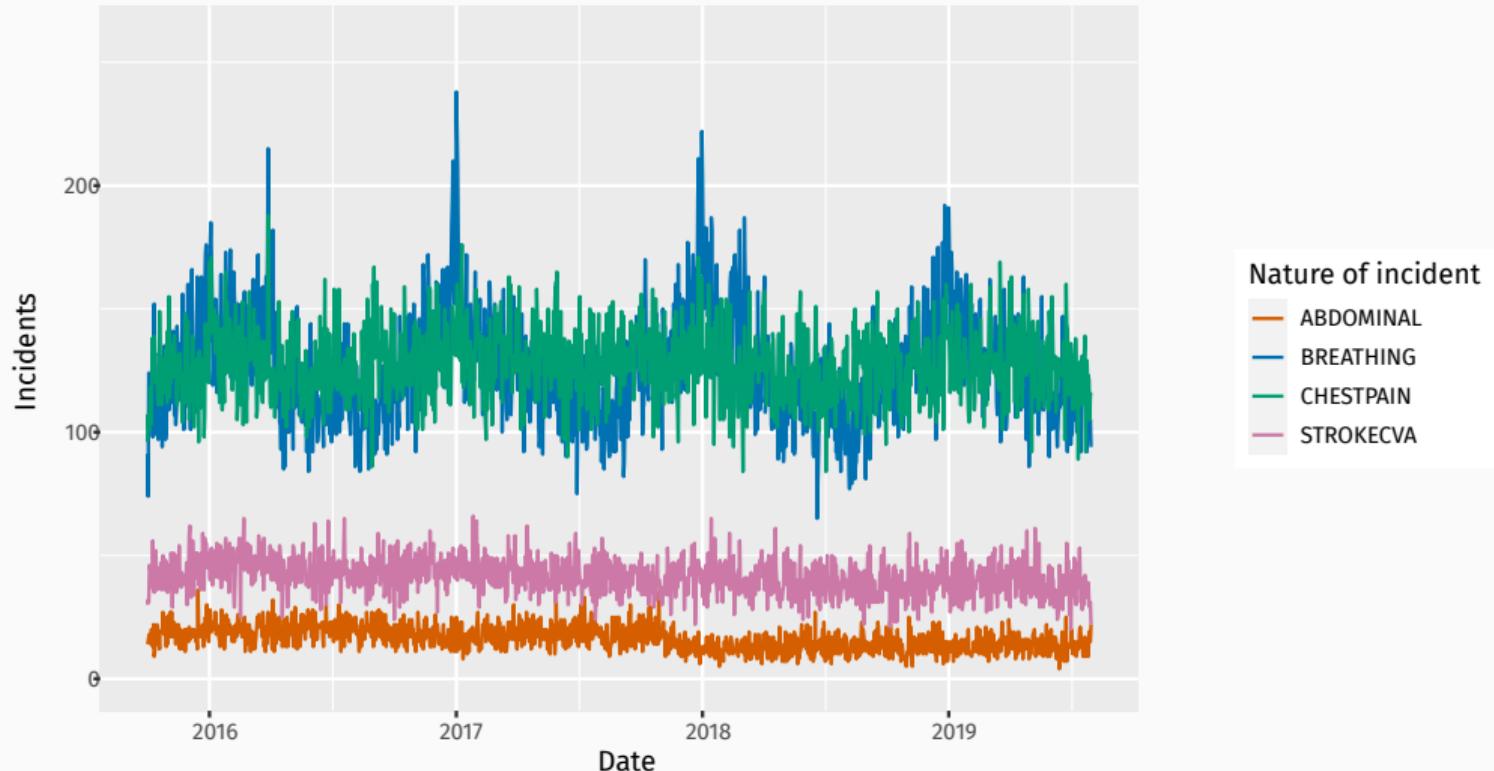
Data incidents by priority



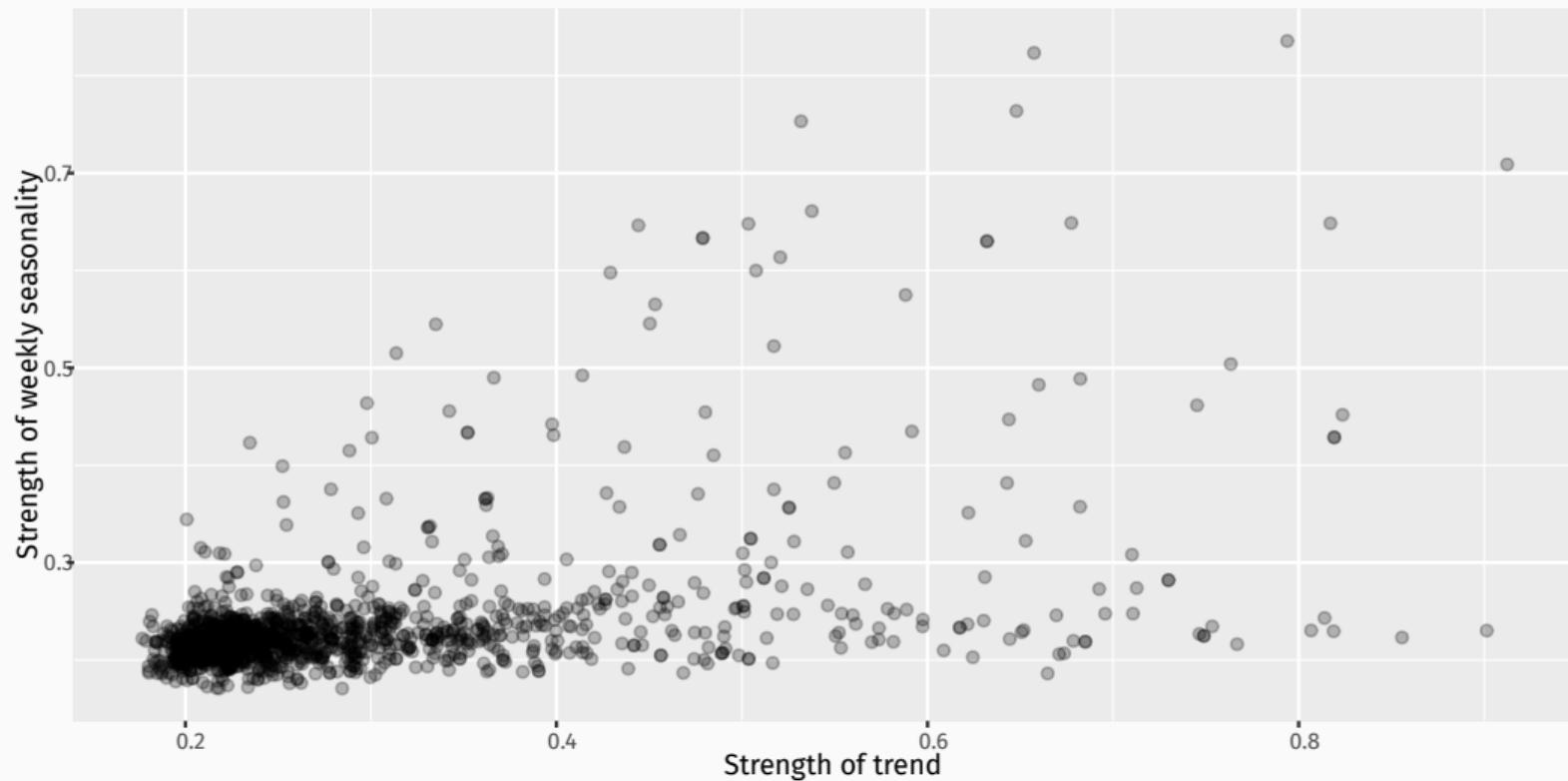
Data incidents by nature of incident



Data incidents by nature of incident



Data features



Forecasting methods

- 1 **Naïve:** Empirical distribution of past daily attended incidents.
- 2 **ETS:** Exponential Smoothing State Space models.
- 3 **GLM:** Poission Regression with spline trend, day of the week, annual Fourier seasonality, public holidays, school holidays, Christmas Day, New Year's Day.
- 4 **TSGLM:** Poisson Regression with same covariates plus three autoregressive terms.
- 5 **Ensemble:** Mixture distribution of 1–4.

Forecasting methods

- 1 **Naïve:** Empirical distribution of past daily attended incidents.

$$y_{T+h|T} \sim \text{Empirical}(y_1, \dots, y_T)$$

Forecasting methods

- 1 **Naïve:** Empirical distribution of past daily attended incidents.

$$y_{T+h|T} \sim \text{Empirical}(y_1, \dots, y_T)$$

- 2 **ETS:** Exponential Smoothing State Space models.

$$y_{T+h|T} \sim \text{Normal}(\hat{y}_{T+h|T}, \hat{\sigma}_{T+h|T}^2)$$

Forecasting methods

3

GLM: Poisson Regression

$$y_{T+h|T} \sim \text{Poisson}(\hat{y}_{T+h|T}) \quad \text{where} \quad \hat{y}_{T+h|T} = \exp(\mathbf{x}'_{T+h}\boldsymbol{\beta})$$

and \mathbf{x}_{T+h} is a vector of covariates including

- spline trend
- day of the week
- annual Fourier seasonality
- public holidays
- school holidays
- Christmas Day
- New Year's Day

Forecasting methods

	Estimate	Std. Error	z value	Pr(> z)	Significance
(Intercept)	6.998511	0.017412	401.93	< 2e-16	***
Spline_1	0.027859	0.004740	5.88	4.2e-09	***
Spline_2	-0.088244	0.006394	-13.80	< 2e-16	***
Spline_3	-0.075036	0.004784	-15.68	< 2e-16	***
Spline_4	-0.111854	0.010202	-10.96	< 2e-16	***
Spline_5	-0.043009	0.004462	-9.64	< 2e-16	***
Monday	0.019147	0.003174	6.03	1.6e-09	***
Tuesday	-0.016414	0.003180	-5.16	2.4e-07	***
Wednesday	-0.015479	0.003184	-4.86	1.2e-06	***
Thursday	-0.006804	0.003178	-2.14	0.03230	*
Friday	0.012235	0.003156	3.88	0.00011	***
Saturday	0.005293	0.003165	1.67	0.09438	.
Fourier_S1_365	0.005365	0.001294	4.15	3.4e-05	***
Fourier_C1_365	0.008263	0.001263	6.54	6.1e-11	***
Fourier_S2_365	0.004235	0.001271	3.33	0.00086	***
Fourier_C2_365	-0.010510	0.001216	-8.64	< 2e-16	***
Fourier_S3_365	-0.000556	0.001275	-0.44	0.66303	
Fourier_C3_365	0.002650	0.001243	2.13	0.03294	*
Public_holiday	0.033278	0.005697	5.84	5.2e-09	***
School_holiday	0.004857	0.002346	2.07	0.03843	*
Xmas	-0.051902	0.016772	-3.09	0.00197	**
New_years_day	0.120385	0.015573	7.73	1.1e-14	***

Signif. codes:					
	---	•	••	•••	

Forecasting methods

4

TSGLM: Poisson Regression

$$y_{T+h|T} \sim \text{Poisson}(\hat{y}_{T+h|T})$$

where $\hat{y}_{T+h|T} = \exp \left(\mathbf{x}'_{T+h} \boldsymbol{\beta} + \sum_{k=1}^3 \alpha_k \log(y_{T+h-k} + 1) \right)$

and \mathbf{x}_{T+h} is a vector of covariates including

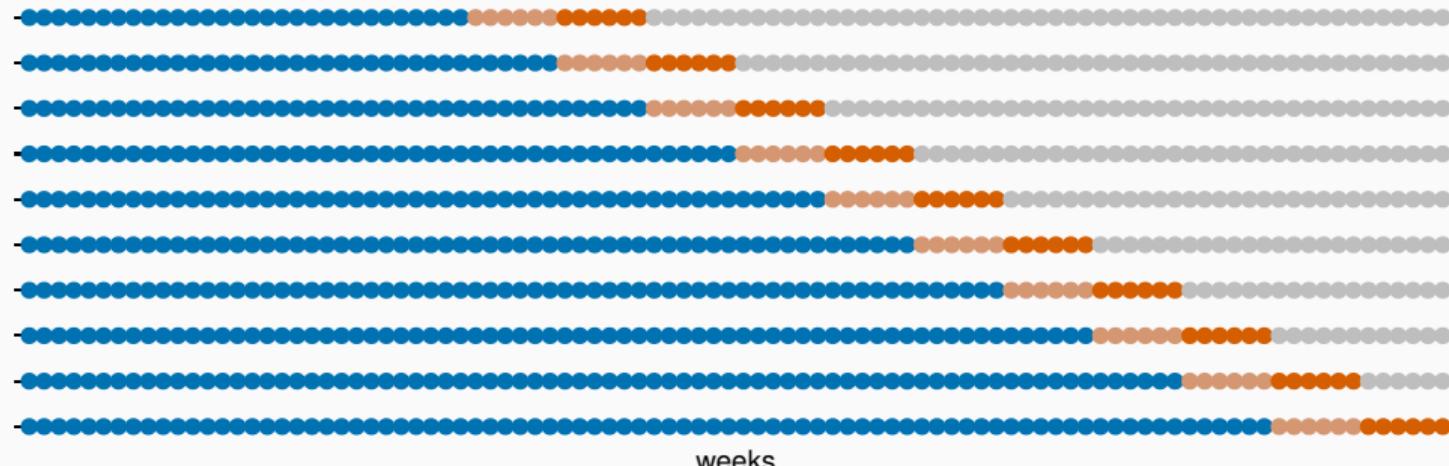
- spline trend
- day of the week
- annual Fourier seasonality
- public holidays
- school holidays
- Christmas Day
- New Year's Day

Nonparametric bootstrap reconciliation

- Fit model to all series and store the residuals as ξ_t .
- These should be serially uncorrelated but cross-sectionally correlated.
- Draw iid samples from ξ_1, \dots, ξ_T with replacement.
- Simulate future sample paths for model using the bootstrapped residuals.
- Reconcile each sample path using MinT.
- Combine the reconciled sample paths to form a mixture distribution at each forecast horizon.

Performance evaluation

- Ten-fold time series cross-validation
- Forecast horizon of 1–84 days
- Each training set contains an additional 42 days.
- Forecasts at 43–84 days correspond to planning horizon.



Performance evaluation

$$\text{MASE} = \text{mean}(|q_j|)$$

$$q_j = \frac{e_j}{\frac{1}{T-m} \sum_{t=m+1}^T |y_t - y_{t-m}|}$$

- y_t = observation for period t
- e_j = forecast error for forecast horizon j
- T = size of training set
- $m = 7$

Performance evaluation

$$\text{MSSE} = \text{mean}(q_j^2)$$

$$q_j^2 = \frac{e_j^2}{\frac{1}{T-m} \sum_{t=m+1}^T (y_t - y_{t-m})^2}$$

- y_t = observation for period t
- e_j = forecast error for forecast horizon j
- T = size of training set
- $m = 7$

Performance evaluation

$$\text{CRPS} = \text{mean}(p_j)$$

$$p_j = \int_{-\infty}^{\infty} (G_j(x) - F_j(x))^2 dx,$$

- $G_j(x)$ = forecast distribution for forecast horizon j
- $F_j(x)$ = true distribution for same period

Forecast accuracy



Forecast accuracy: 43–84 days ahead

		MSSE			
Method	Model	Total	Control areas	Health boards	Bottom
Base	Naïve	1.169	1.056	1.062	1.031
Base	ETS	0.979	0.875	0.816	0.975
Base	GLM	0.813	0.897	0.875	1.009
Base	TSGLM	0.822	0.901	0.875	1.050
Base	Ensemble	0.599	0.729	0.774	0.993
MinT	Naïve	1.168	1.057	1.062	2.095
MinT	ETS	0.785	0.852	0.845	0.994
MinT	GLM	0.720	0.827	0.837	1.803
MinT	TSGLM	0.722	0.833	0.839	1.851
MinT	Ensemble	0.560	0.706	0.765	1.557

Forecast accuracy: 43–84 days ahead

		MASE			
Method	Model	Total	Control areas	Health boards	Bottom
Base	Naïve	1.139	1.059	1.047	1.019
Base	ETS	0.963	0.930	0.899	1.038
Base	GLM	0.910	0.940	0.923	1.002
Base	TSGLM	0.911	0.939	0.924	1.005
Base	Ensemble	0.782	0.856	0.876	1.008
MinT	Naïve	1.138	1.059	1.047	2.651
MinT	ETS	0.877	0.916	0.915	1.289
MinT	GLM	0.848	0.901	0.902	2.493
MinT	TSGLM	0.852	0.903	0.903	2.513
MinT	Ensemble	0.753	0.844	0.872	2.260

Forecast accuracy: 43–84 days ahead

		CRPS			
Method	Model	Total	Control areas	Health boards	Bottom
Base	Naïve	30.387	10.882	5.500	0.302
Base	ETS	14.309	6.074	3.476	0.244
Base	GLM	15.396	6.253	3.576	0.244
Base	TSGLM	15.316	6.227	3.575	0.245
Base	Ensemble	12.978	5.727	3.430	0.243
MinT	Naïve	30.368	10.902	5.498	0.313
MinT	ETS	13.515	5.967	3.547	0.243
MinT	GLM	13.839	5.917	3.453	0.246
MinT	TSGLM	14.000	5.947	3.455	0.248
MinT	Ensemble	12.585	5.728	3.426	0.247

Conclusions

- Ensemble mixture distributions give better forecasts than any component methods.
- Forecast reconciliation improves forecast accuracy, even when some component methods are quite poor.
- The ensemble without the Naïve method was worse.
- Forecast reconciliation allows coordinated planning and resource allocation.

Outline

- 1 Definition of probabilistic coherence
- 2 Evaluating probabilistic forecasts
- 3 Emergency Services Demand
- 4 Evaluating multivariate probabilistic forecasts
- 5 Example: Australian electricity generation

Evaluating probabilistic forecasts

Continuous Rank Probability Score (univariate forecasts)

Forecast distribution F_t and observation y_t .

$$\text{CRPS}(F_t, y_t) = \int_0^1 S_{p,t}(p, y_t) dp = E_F|Y - y_t| - \frac{1}{2}E_F|Y - Y^*|$$

- Y and Y^* are iid draws from F_t .
- Optimal when F_t is truth (i.e., it is a proper score)

Evaluating probabilistic forecasts

Continuous Rank Probability Score (univariate forecasts)

Forecast distribution F_t and observation y_t .

$$\text{CRPS}(F_t, y_t) = \int_0^1 S_{p,t}(p, y_t) dp = E_F|Y - y_t| - \frac{1}{2}E_F|Y - Y^*|$$

- Y and Y^* are iid draws from F_t .
- Optimal when F_t is truth (i.e., it is a proper score)

Energy score (multivariate forecasts)

$$\text{ES}(F_t, \mathbf{y}_t) = E_F\|\mathbf{Y} - \mathbf{y}_t\| - \frac{1}{2}E_F\|\mathbf{Y} - \mathbf{Y}^*\|$$

Evaluating probabilistic forecasts

Continuous Rank Probability Score (univariate forecasts)

Forecast distribution F_t and observation y_t .

$$\text{CRPS}(F_t, y_t) = \int_0^1 S_{p,t}(p, y_t) dp = E_F|Y - y_t| - \frac{1}{2}E_F|Y - Y^*|$$

- Y and Y^* are iid draws from F_t .
- Optimal when F_t is truth (i.e., it is a proper score)

Energy score (multivariate forecasts)

$$\text{ES}(F_t, \mathbf{y}_t) = E_F||\mathbf{Y} - \mathbf{y}_t|| - \frac{1}{2}E_F||\mathbf{Y} - \mathbf{Y}^*||$$

Log score (multivariate forecasts)

$$\text{LS}(F_t, \mathbf{y}_t) = -\log f(\mathbf{y}_t)$$

Evaluating probabilistic forecasts

Proper scoring rule

optimized when true forecast distribution is used.

Evaluating probabilistic forecasts

Proper scoring rule

optimized when true forecast distribution is used.

Scoring Rule	Coherent v Incoherent	Coherent v Coherent
Log Score	Not proper	<ul style="list-style-type: none">• Ordering preserved if compared using bottom-level only
Energy Score	Proper	<ul style="list-style-type: none">• Full hierarchy should be used.• Rankings may change otherwise.

Score optimal reconciliation

Algorithm proposed by Panagiotelis et al (2020) for optimizing \mathbf{G} using stochastic gradient descent to optimize Energy Score.

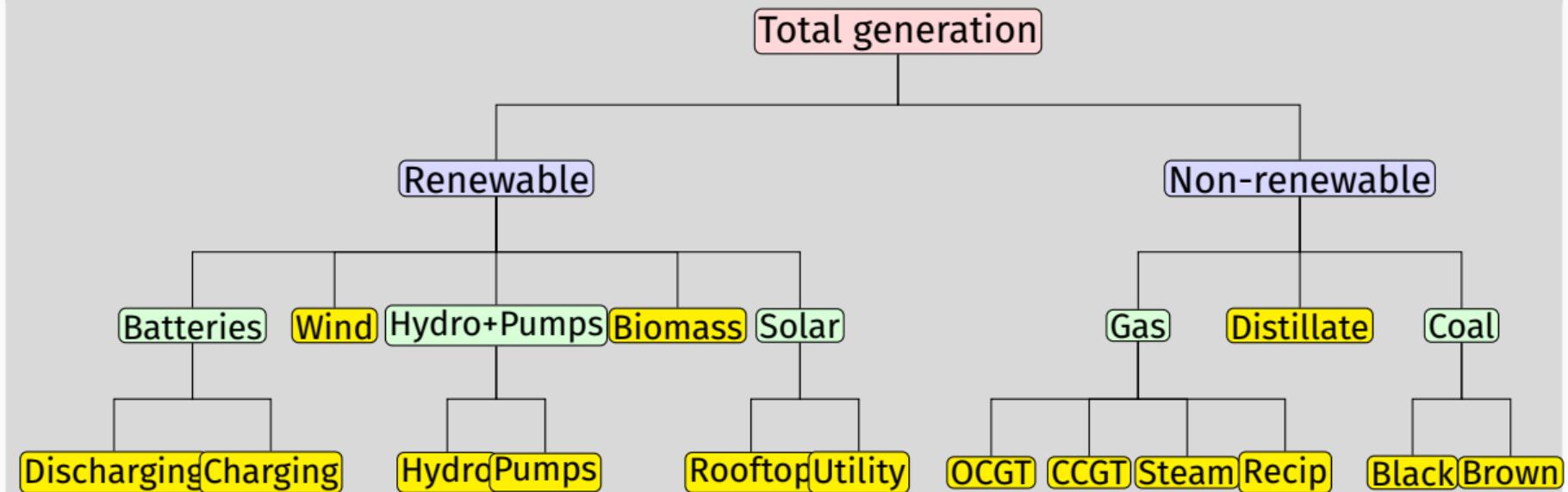
- 1 Compute base forecasts over a test set.
- 2 Compute OLS reconciliation: $\mathbf{G} = (\mathbf{S}'\mathbf{S})^{-1}\mathbf{S}'$
- 3 Iteratively update \mathbf{G} using SGD with Adam method and ES objective over a test set

Outline

- 1 Definition of probabilistic coherence
- 2 Evaluating probabilistic forecasts
- 3 Emergency Services Demand
- 4 Evaluating multivariate probabilistic forecasts
- 5 Example: Australian electricity generation

Example: Australian electricity generation

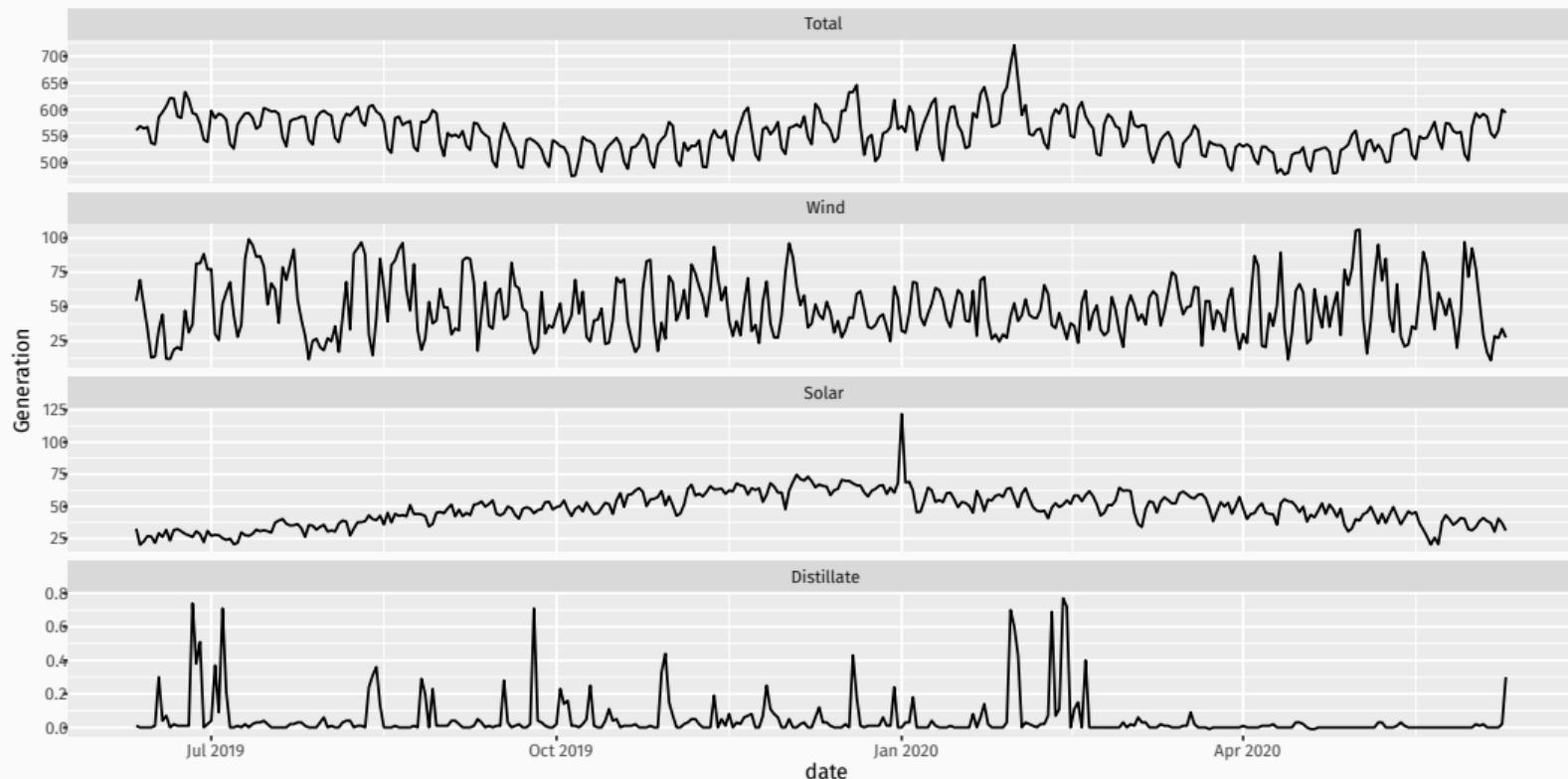
Daily time series from opennem.org.au



$n = 23$ series

$m = 15$ bottom-level series

Example: Australian electricity generation

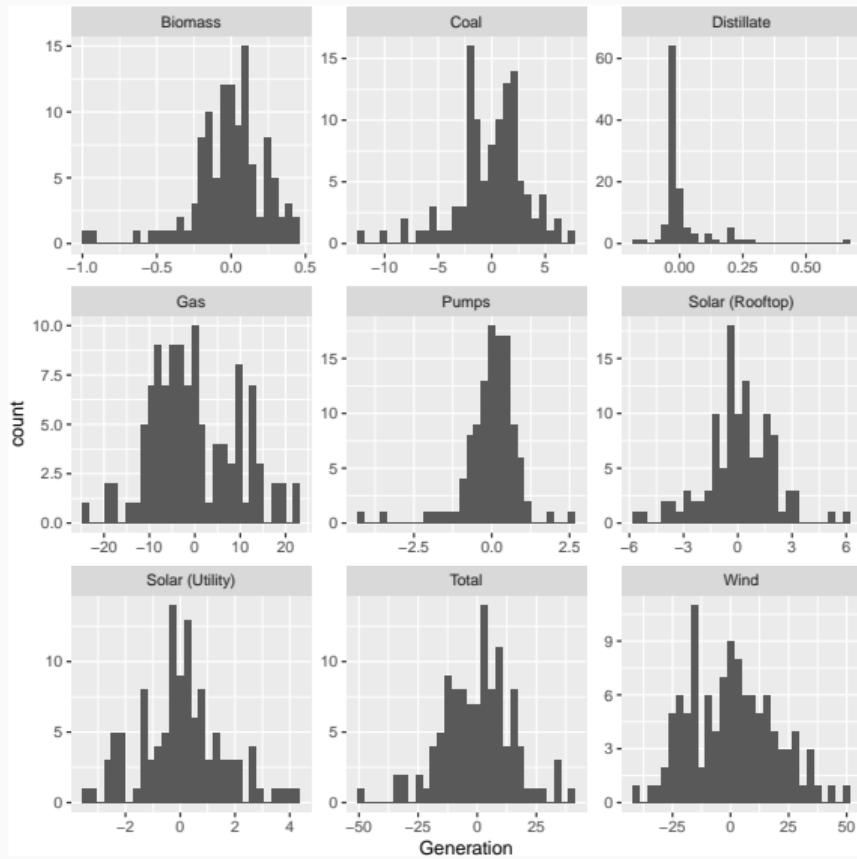


Example: Australian electricity generation

Forecast evaluation

- Rolling window of 140 days training data, and one-step-forecasts for 170 days test data.
- One-layer feed-forward neural network with up to 28 lags of target variable as inputs.
- Implemented using NNETAR() function in fable package.
- Model could be improved with temperature predictor.

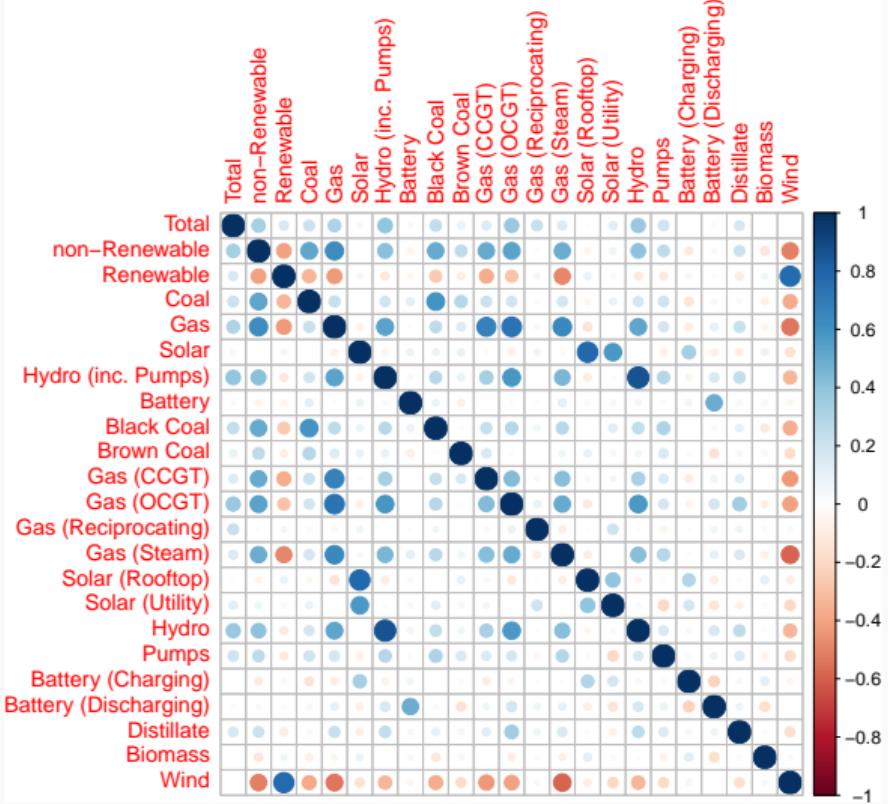
Example: Australian electricity generation



**Histogram of residuals:
2 Oct 2019 – 21 Jan 2020**

Clearly non-Gaussian

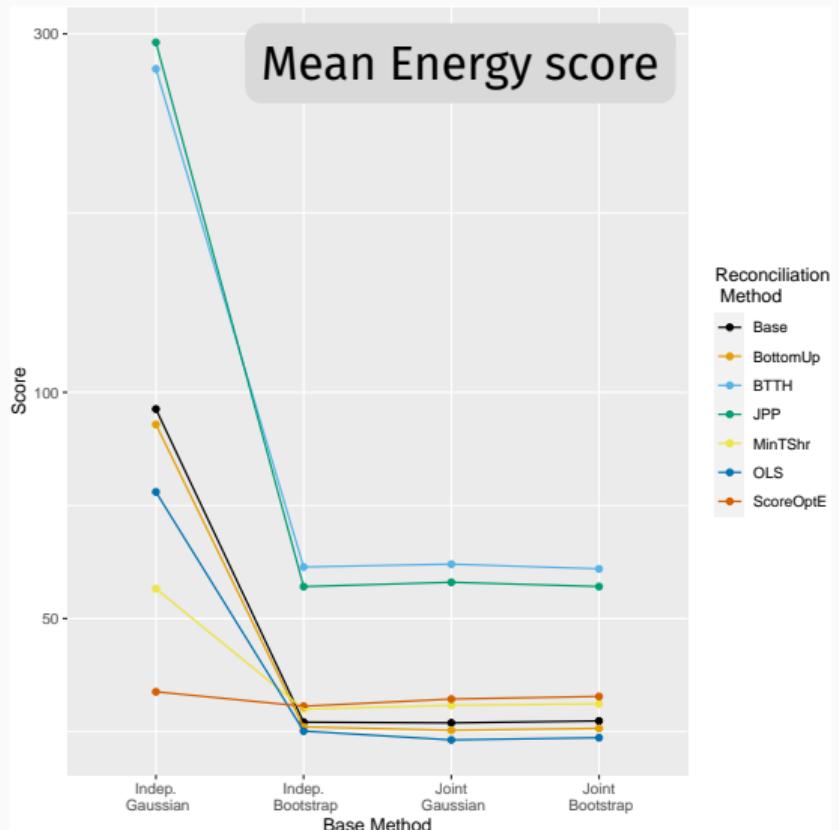
Example: Australian electricity generation



**Correlations of residuals:
2 Oct 2019 – 21 Jan 2020**

Blue = positive correlation.
Red = negative correlation.
Large = stronger correlations.

Example: Australian electricity generation



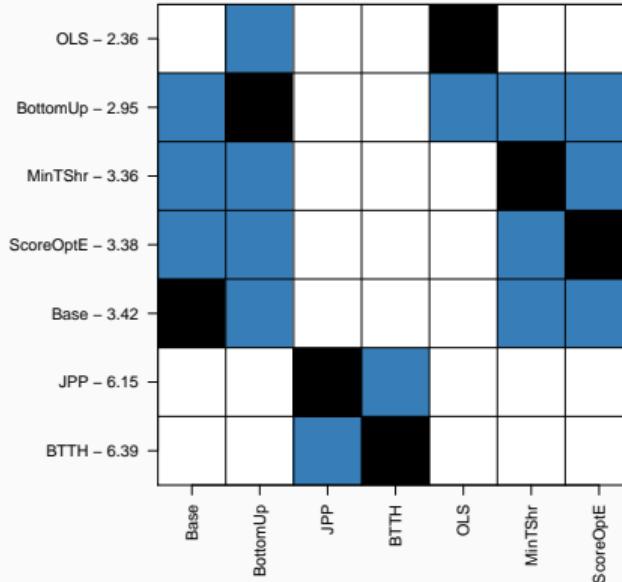
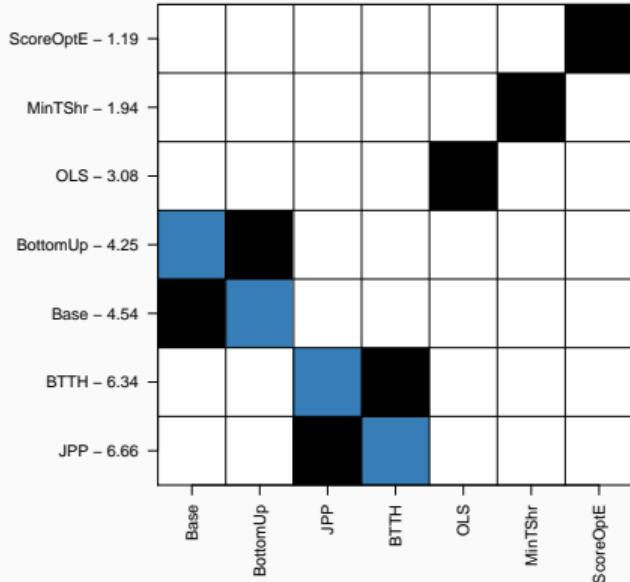
Base residual assumptions

- Gaussian independent
- Gaussian dependent
- Non-Gaussian independent
- Non-Gaussian dependent

Reconciliation methods

- Base
- BottomUp
- BTTH: Ben Taieb, Taylor, Hyndman
- JPP: Jeon, Panagiotelis, Petropoulos
- OLS
- MinT(Shrink)
- Score Optimal Reconciliation

Example: Australian electricity generation



Nemenyi test for different scores

Base forecasts are independent and Gaussian.

Nemenyi test for different scores

Base forecasts are obtained by jointly bootstrapping residuals.

References

-  Ben Taieb, S, JW Taylor, and RJ Hyndman (2021). Hierarchical Probabilistic Forecasting of Electricity Demand with Smart Meter Data. *J American Statistical Association* **116**(533), 27–43.
-  Panagiotelis, A, P Gamakumara, G Athanasopoulos, and RJ Hyndman (2023). Probabilistic forecast reconciliation: properties, evaluation and score optimisation. *European J Operational Research* **306**(2), 693–706.
-  Rostami-Tabar, B and RJ Hyndman (2023). “Hierarchical Time Series Forecasting in Emergency Medical Services”. robjhyndman.com/publications/fem.