

Rob J Hyndman

Functional time series

with applications in demography

1. Tools for functional time series analysis

Mortality rates

Fertility rates

Outline

1 Functional time series

2 Functional principal components

3 Data visualization

4 References

Functional time series

$$y_t(x_i) = g_\lambda(z_t(x_i)) = \begin{cases} \log[z_t(x_i)] & \text{if } \lambda = 0; \\ \lambda^{-1} [z_t^\lambda(x_i) - 1] & \text{otherwise.} \end{cases}$$
$$= s_t(x_i) + \sigma_t(x_i)\varepsilon_{t,i}$$

- $z_t(x_i)$ is observed data for age x_i in year t ,
 $i = 1, \dots, N, \quad t = 1, \dots, T.$
- λ chosen so that $\varepsilon_{t,i} \sim \text{NID}(0, 1)$.
- We assume $s_t(x)$ is a smooth function of x .
- We need to estimate $s_t(x)$ from the data for
 $x_1 < x < x_N$.
- We want to forecast whole curve $z_t(x)$ for
 $t = T + 1, \dots, T + h$.

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Smoothing functional time series

$$y_t(x_i) = g_\lambda(z_t(x_i)) = \begin{cases} \log(z_t(x_i)) & \text{if } \lambda = 0; \\ \lambda^{-1} (z_t^\lambda(x_i) - 1) & \text{otherwise.} \end{cases}$$
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- Estimate $s_t(x)$ using penalized regression spline with a large number of knots.
- For mortality data, use $\lambda = 0$ and constrain $s_t(x)$ to be monotonic for $x > 50$.
- For fertility data, use $\lambda = 0.4$ and constrain $s_t(x)$ to be concave.
- Fit is weighted with $w_t(x_i) = \sigma_t^{-2}(x_i)$.

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$D_t(x_i)$ = number of deaths at age x_i in year t .

$E_t(x_i)$ = total population aged x_i on June 30 in year t .

$m_t(x_i) = D_t(x_i)/E_t(x_i)$ = observed mortality rate.

$\mu_t(x_i)$ = “true” mortality rate.

$$D_t(x_i) \sim \text{Poisson}(E_t(x_i)\mu_t(x_i))$$

$$\mathbb{E}[m_t(x_i)] = \mu_t(x) \text{ and } \mathbb{V}[m_t(x_i)] = \mu_t(x_i)E_t^{-1}(x_i).$$

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Taylor series approx

$$\mathbb{V}[g_\lambda(X)] = \sigma_X^2[g'_\lambda(\mu_X)]^2$$

$$\mathbb{V}[\log(X)] = \sigma_X^2/\mu_X^2$$

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$$\sigma^2(x_i) = \mathbb{V}(\log[m_t(x_i)])$$

$$\approx [\mu_t(x_i)E_t^{-1}(x_i)]\mu_t(x)^{-2}$$

$$= \mu_t(x_i)^{-1}E_t(x_i)^{-1}$$

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$$\sigma^2(x_i) = \mathbb{V}(g_\lambda[f_t(x_i)])$$

$$= [\mu_t(x_i)E_t^{-1}(x_i)] \mu_t(x)^{2\lambda-2}$$

$$= \mu_t(x_i)^{2\lambda-1} E_t(x_i)^{-1}$$

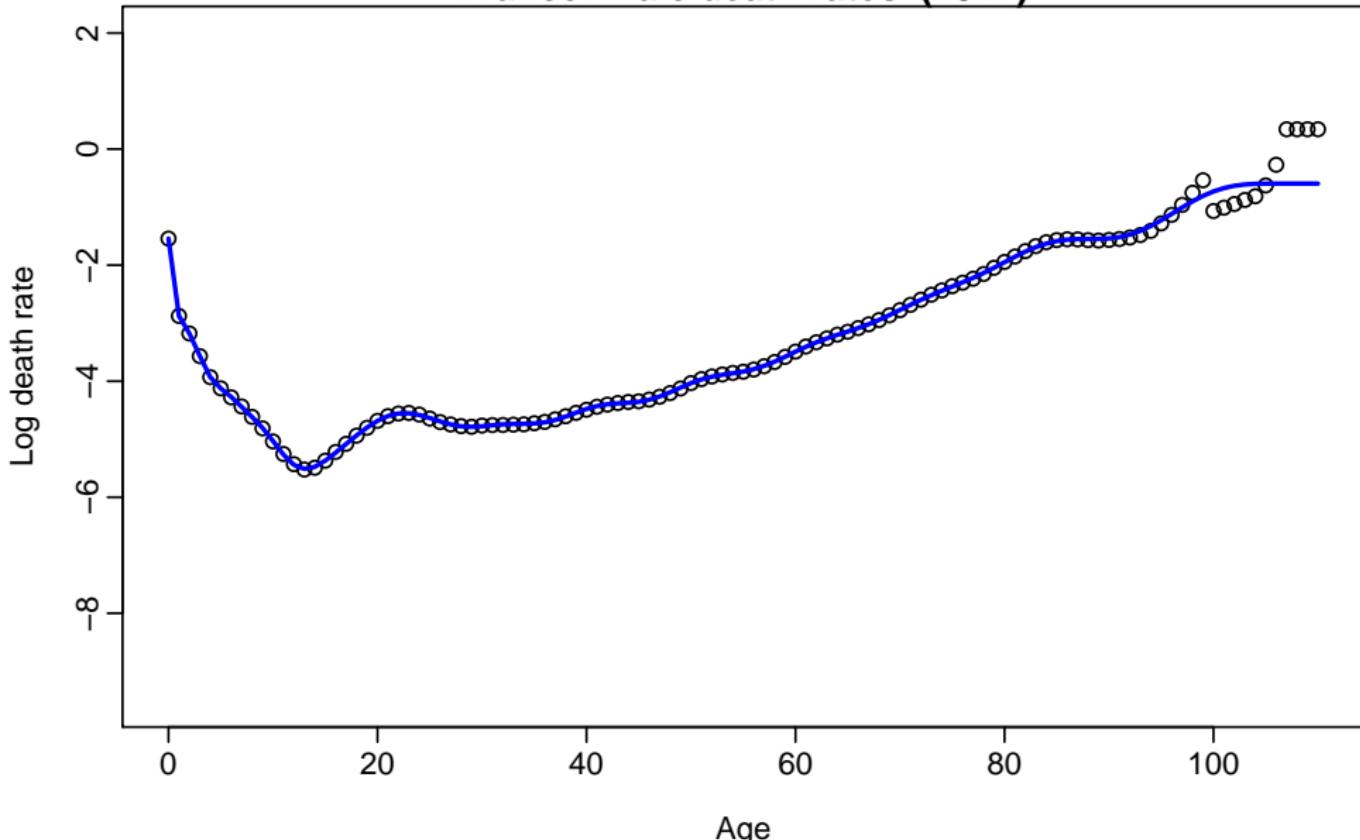
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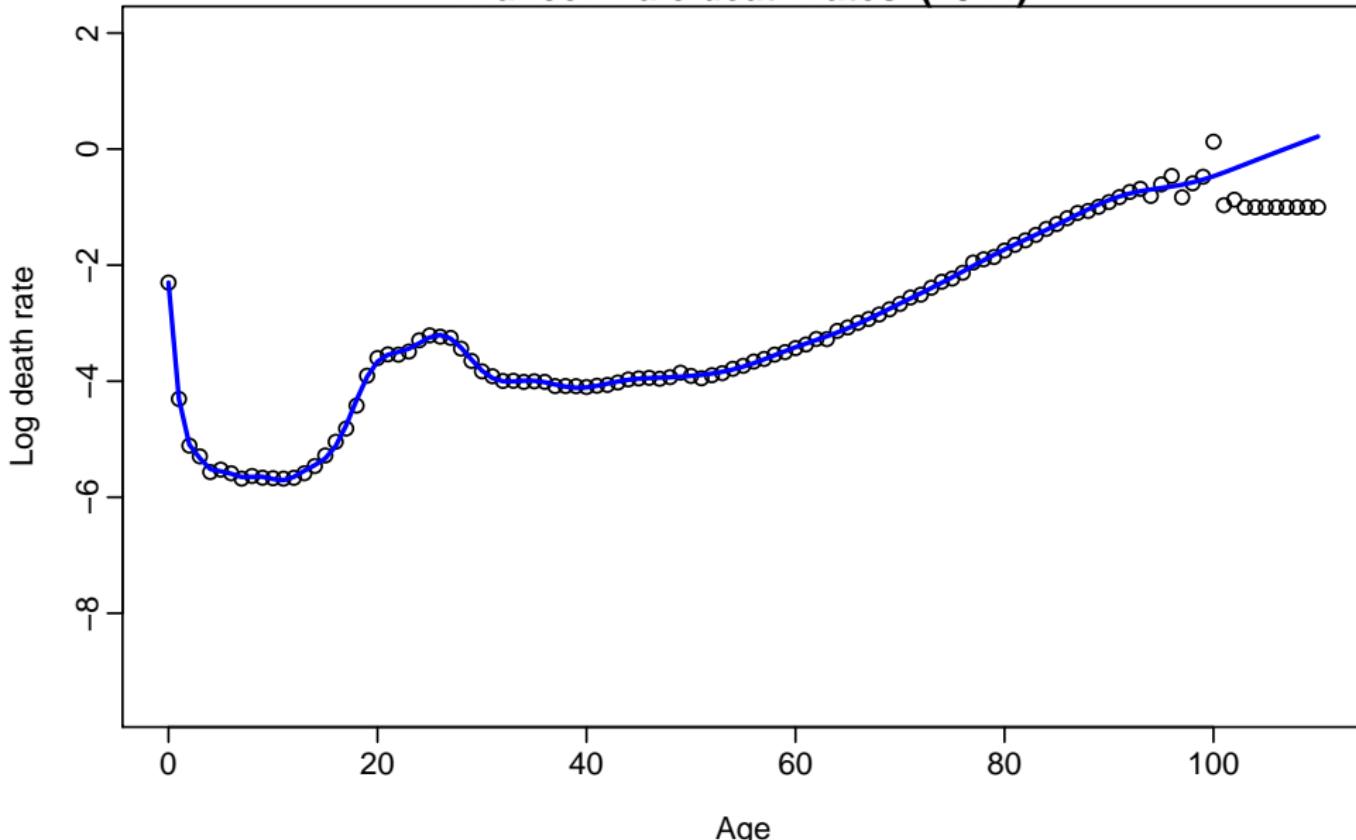
Smoothing functional time series

France: male death rates (1821)



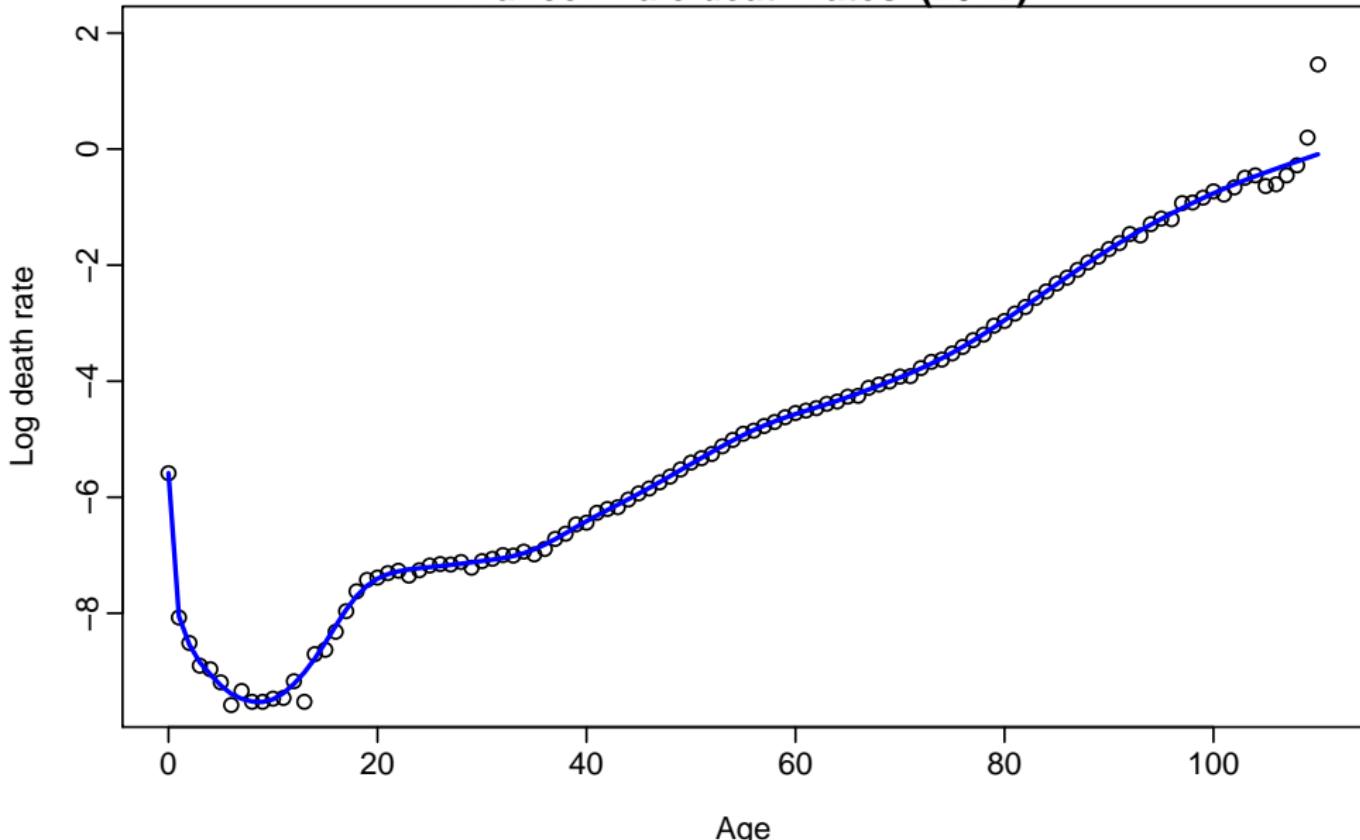
Smoothing functional time series

France: male death rates (1944)



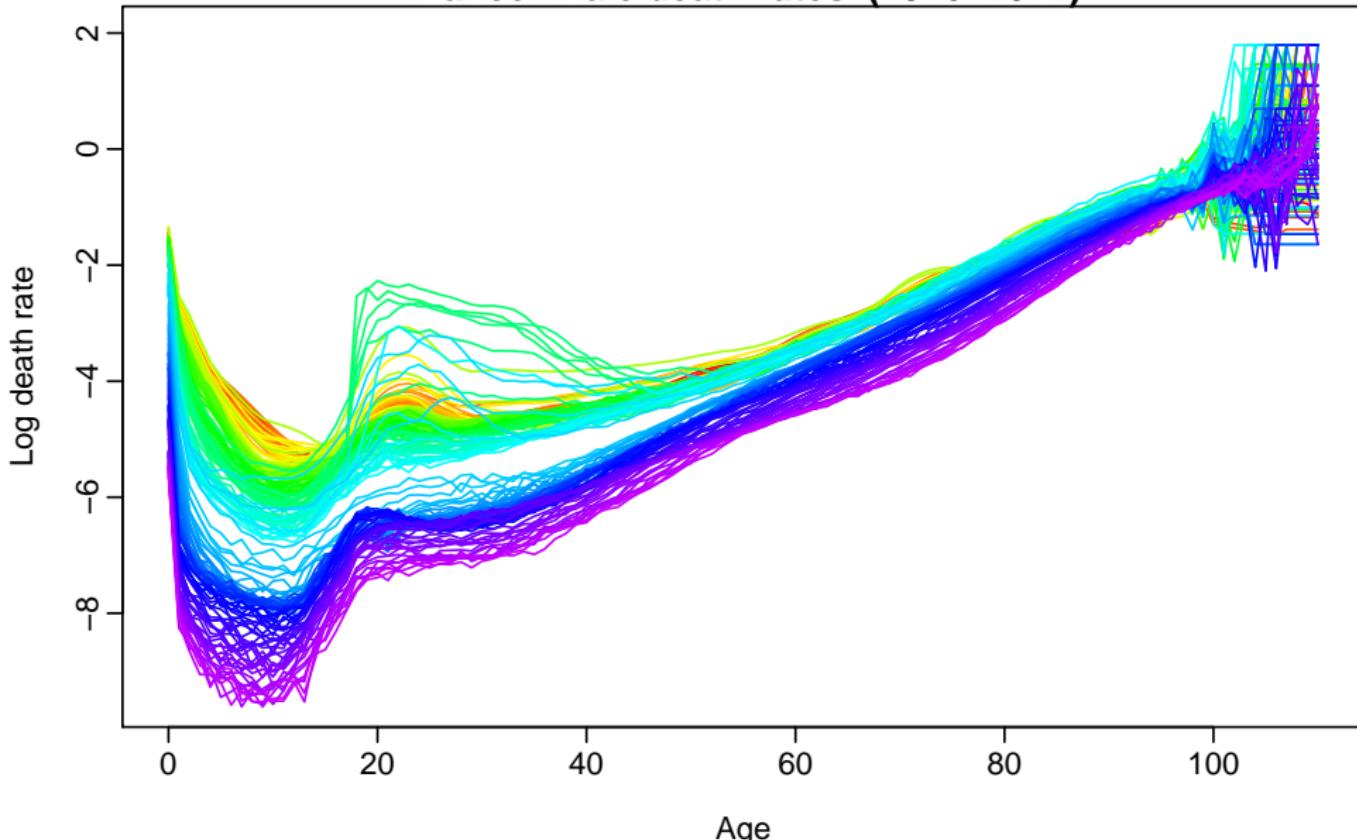
Smoothing functional time series

France: male death rates (2012)



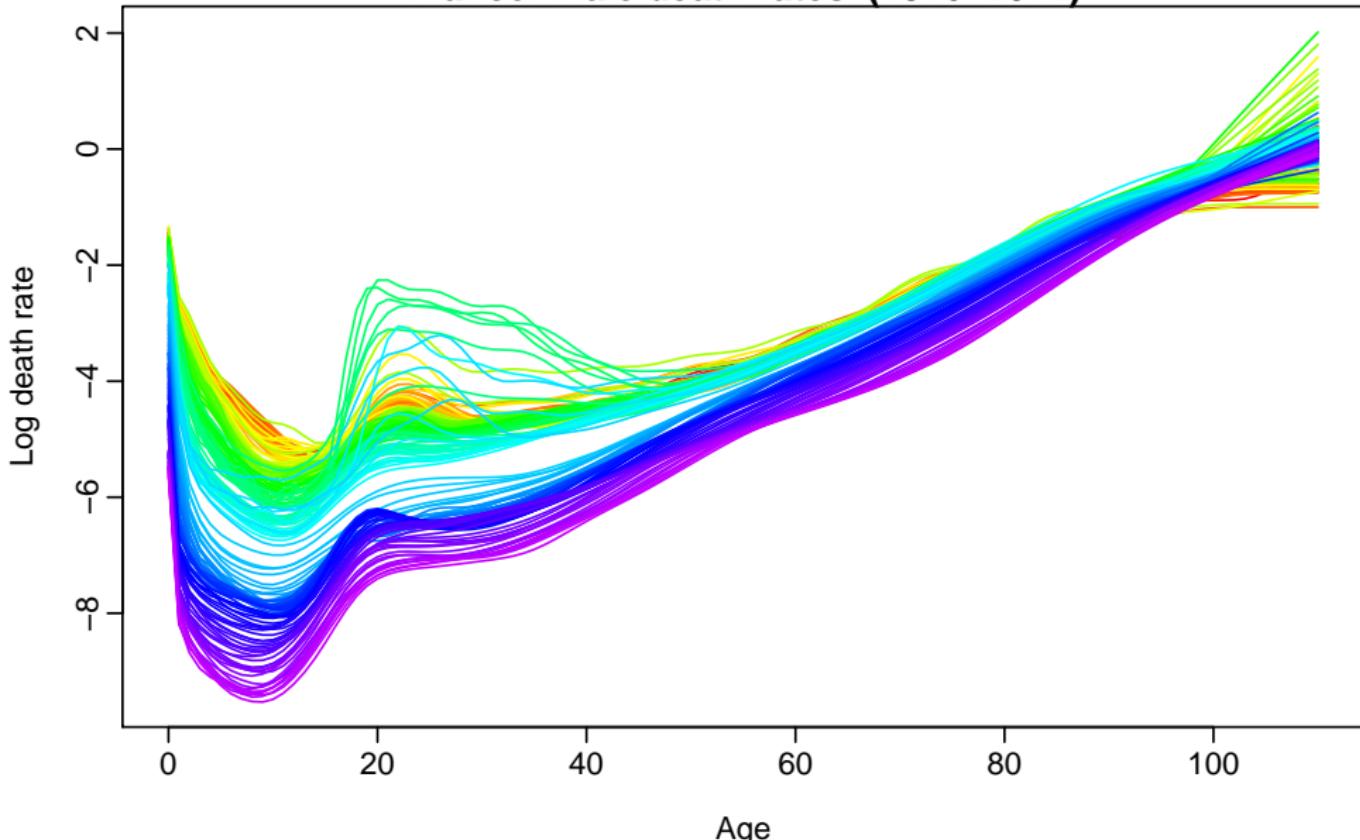
Smoothing functional time series

France: male death rates (1816–2012)



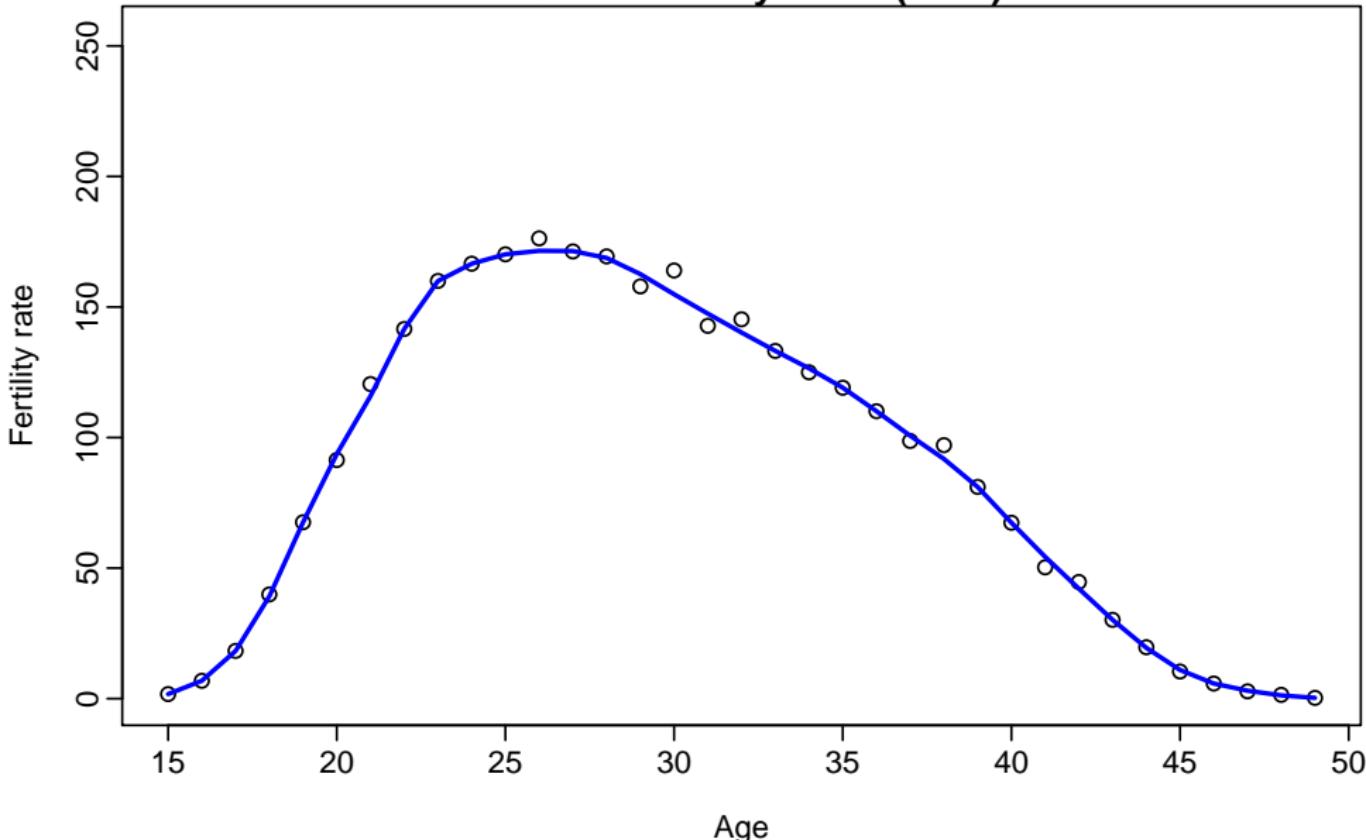
Smoothing functional time series

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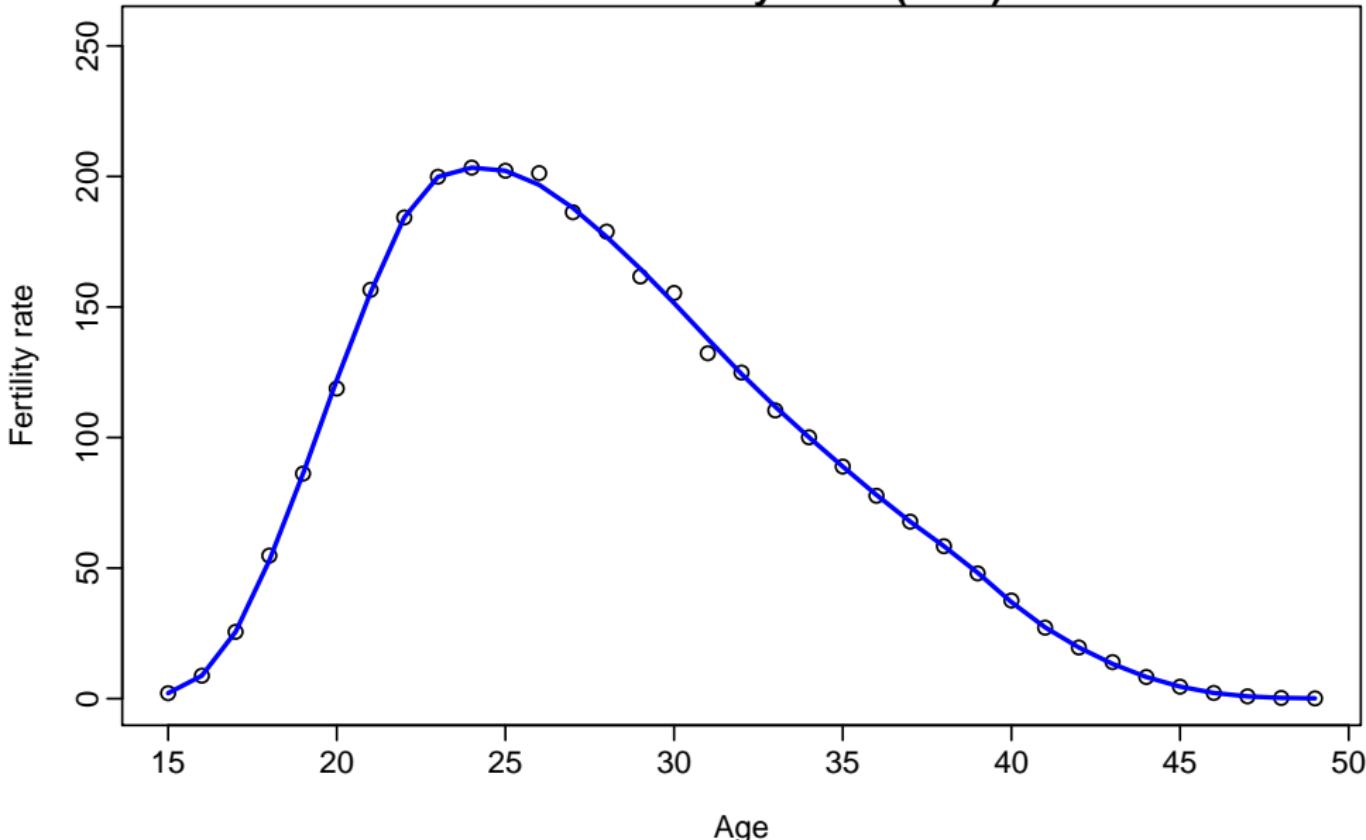
Smoothing functional time series

Australia fertility rates (1921)



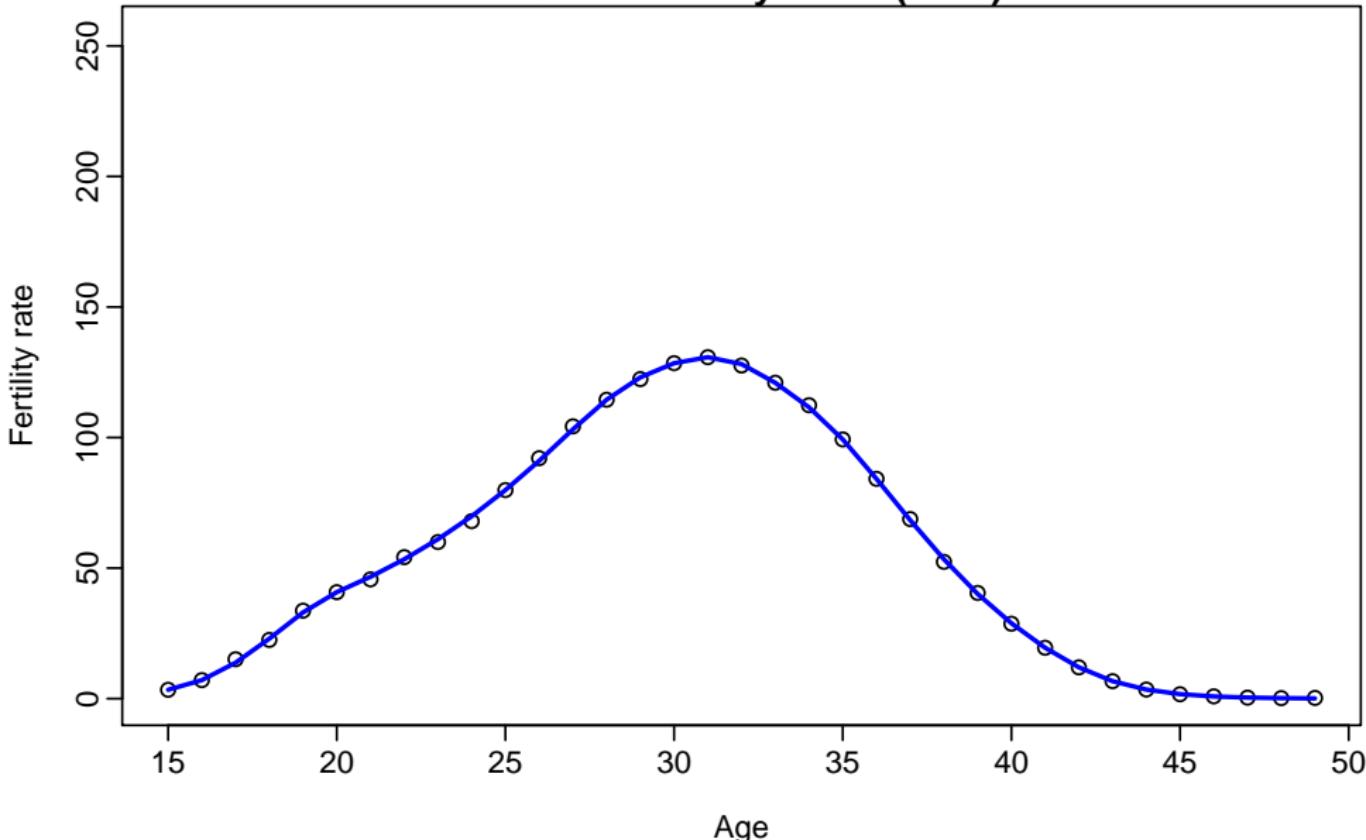
Smoothing functional time series

Australia fertility rates (1950)



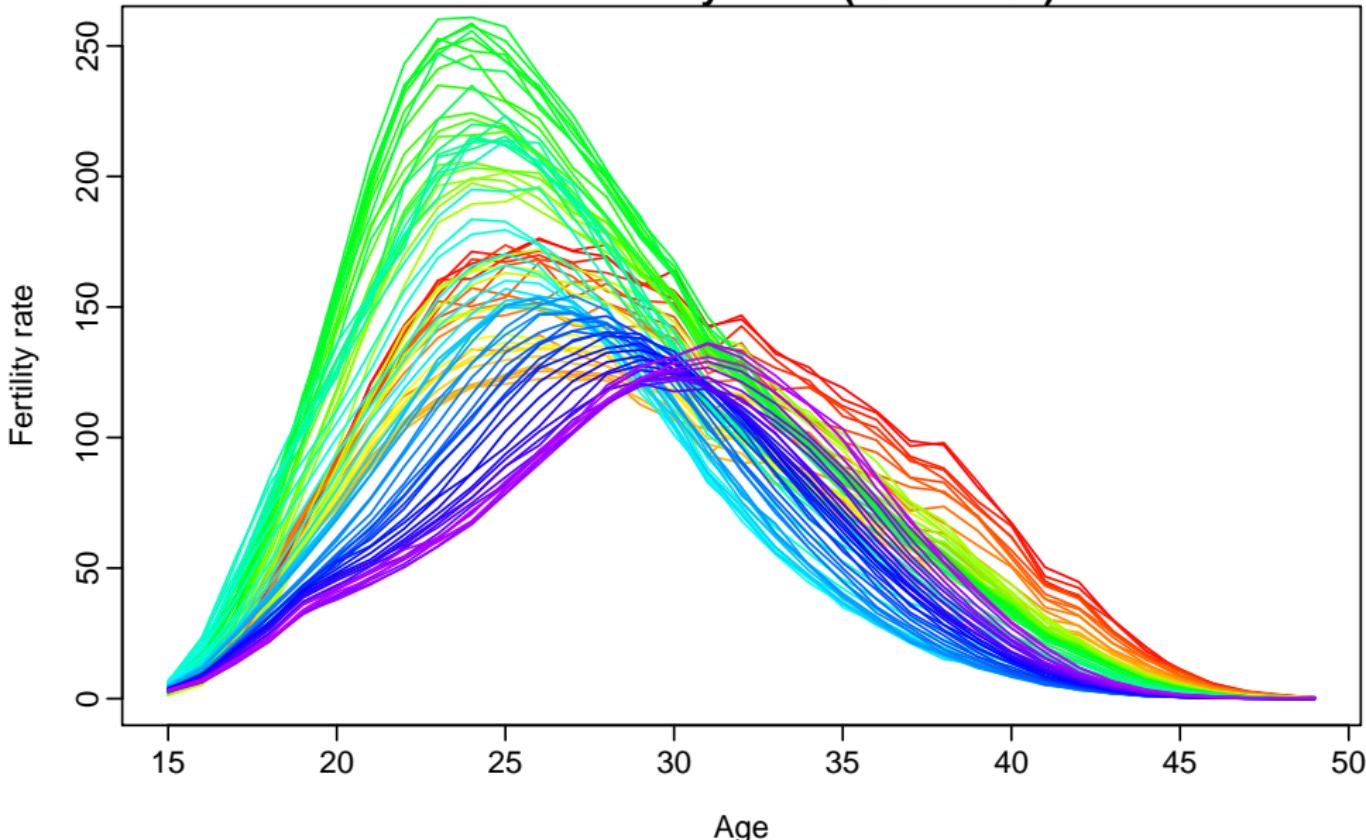
Smoothing functional time series

Australia fertility rates (2009)



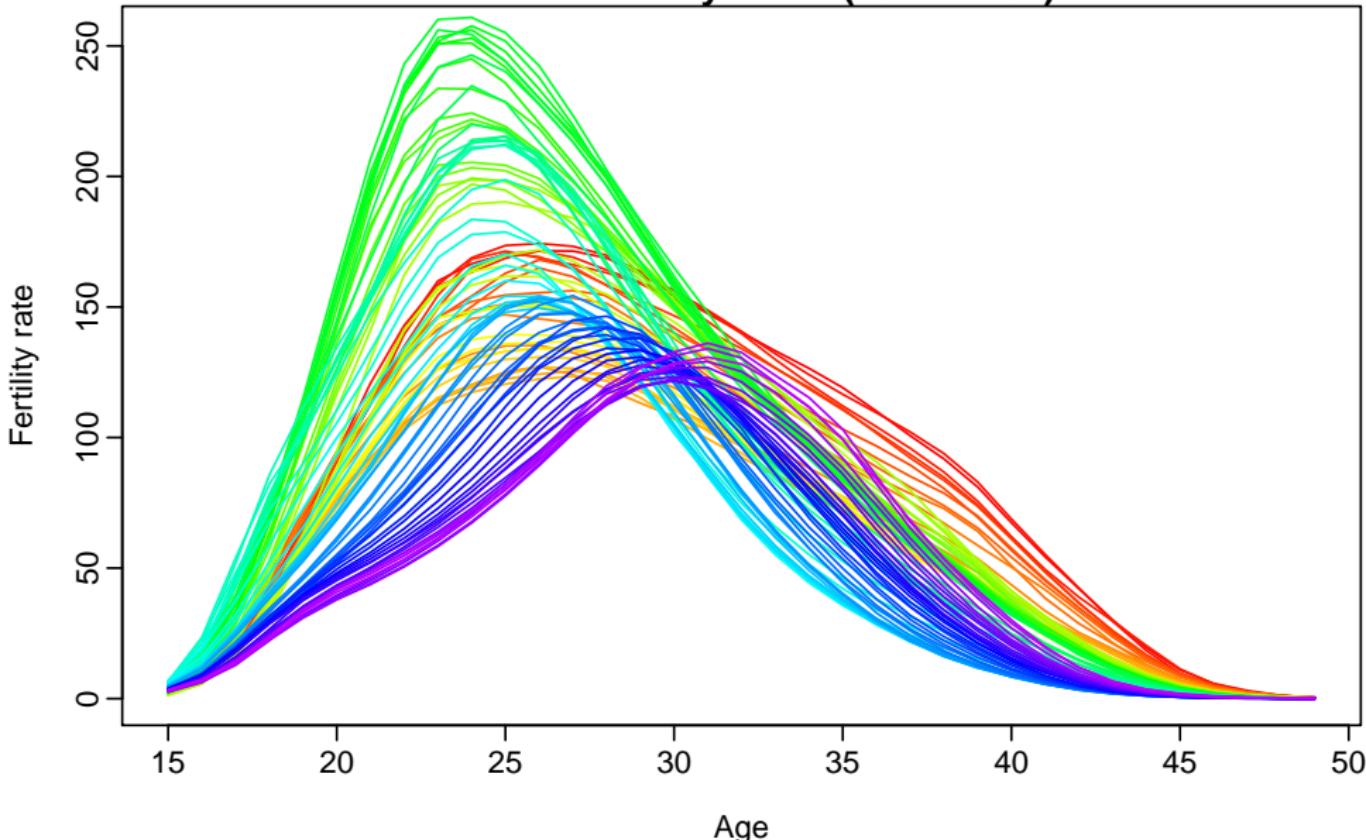
Smoothing functional time series

Australia fertility rates (1921–2009)



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2 Functional principal components

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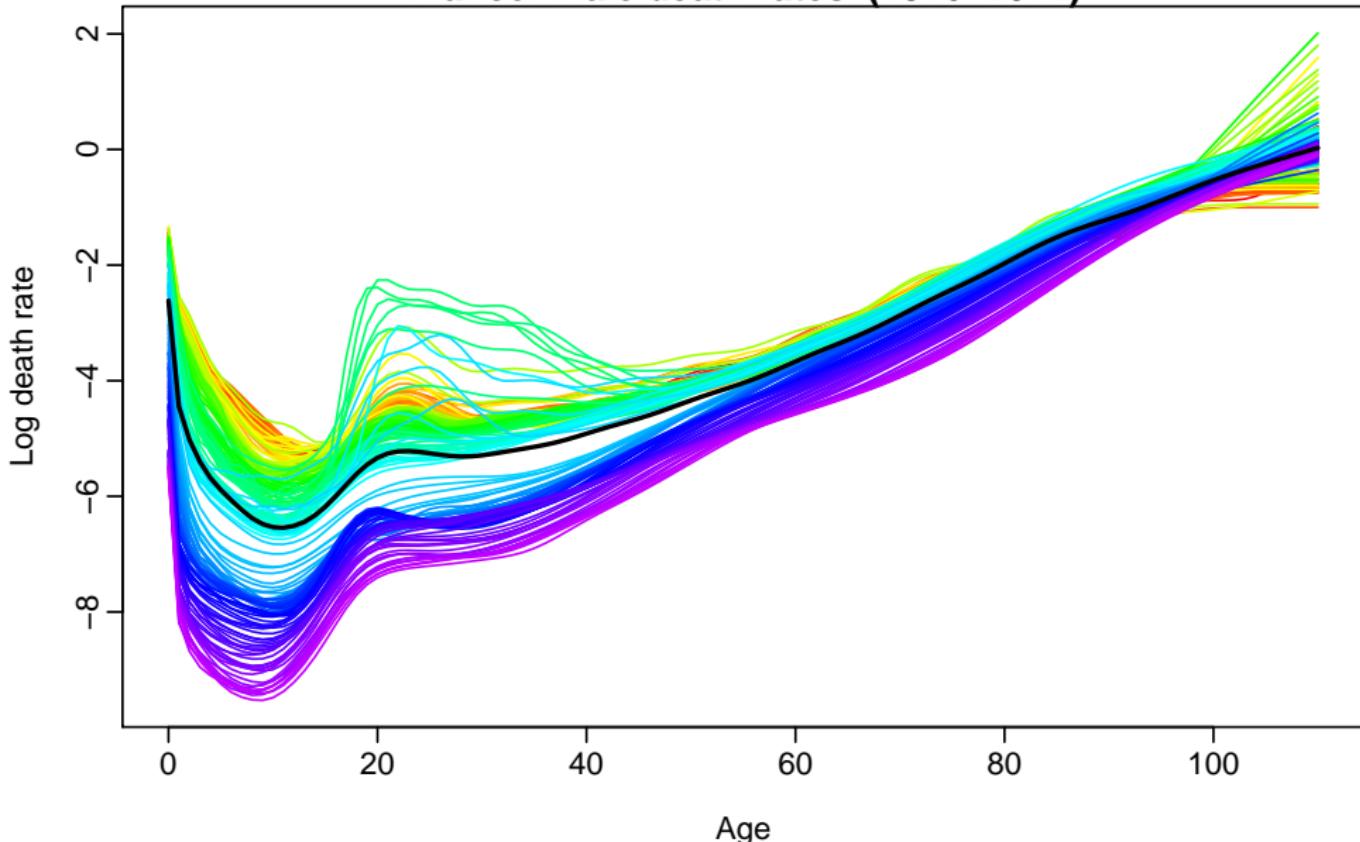
Functional principal components

$$y_t(x_i) = s_t(x_i) + \sigma_t(x_i)\varepsilon_{t,i},$$

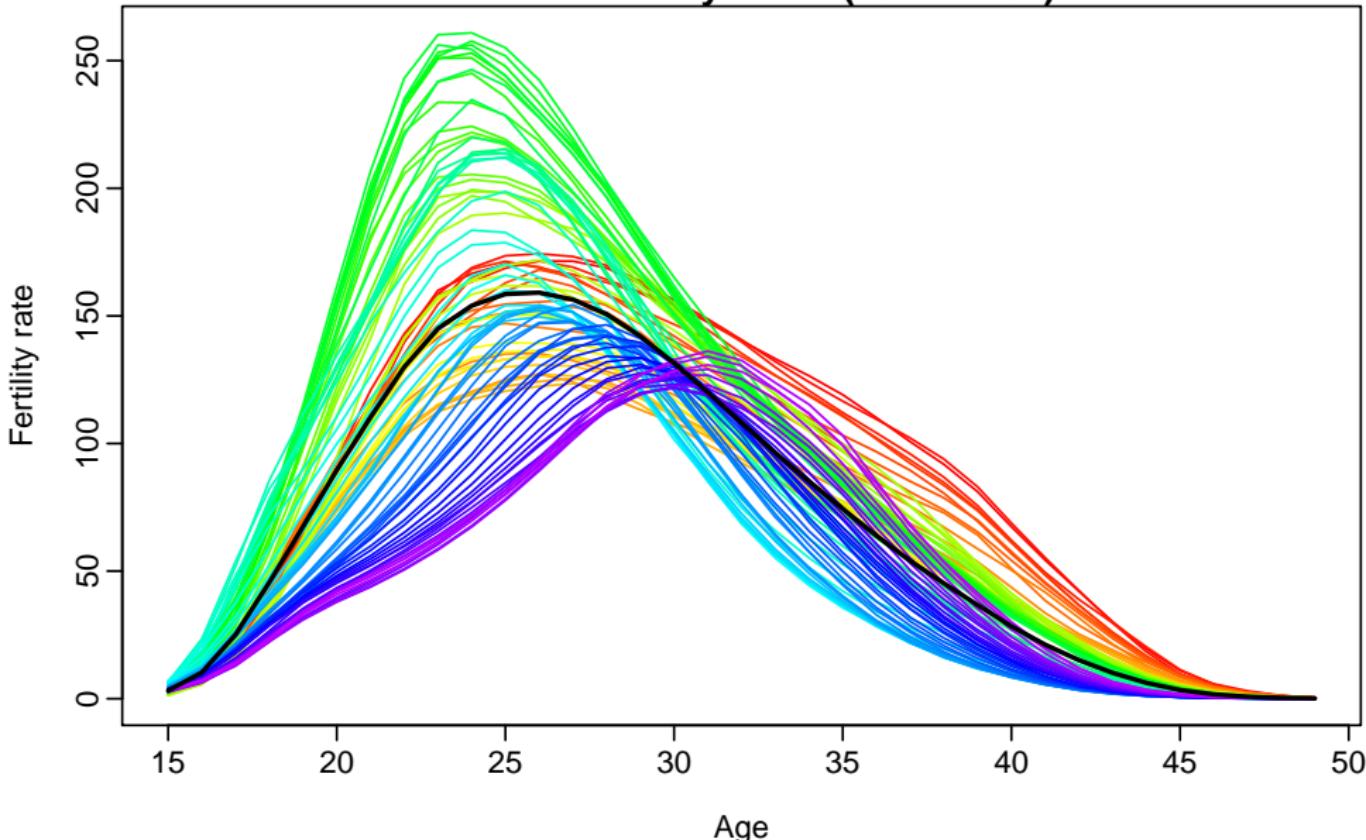
$$s_t(x) = \mu(x) + \sum_{k=1}^{T-1} \beta_{t,k} \phi_k(x)$$

- 1 Estimate smooth functions $s_t(x)$ using weighted penalized regression splines.
- 2 Compute $\mu(x)$ as $\bar{s}(x)$ across years.
- 3 Compute $\beta_{t,k}$ and $\phi_k(x)$ using functional principal components.

France: male death rates (1816–2012)



Australia fertility rates (1921–2009)



Functional principal components

(Ramsay and Silverman, 1997,2002).

- In FDA, each principal component is specified by a weight function $\phi_k(x)$.
- The PC scores for each year are given by

$$\beta_{k,t} = \int \phi_k(x) [\hat{s}_t(x) - \bar{s}(x)] dx$$

- The aim is to:

Find a set of orthogonal functions $\phi_1(x), \phi_2(x), \dots, \phi_m(x)$ such that the variance explained by the first principal component is maximized.

Then the second principal component is obtained by removing the variance explained by the first principal component from the data.

And so on for the third principal component, etc.

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Functional principal components

The optimal basis functions

Approximate $s_t(x)$ using

$$s_t(x) = \bar{s}(x) + \sum_{k=0}^K \beta_{t,k} \phi_k(x) + r_t(x)$$

The basis function $\phi_k(x)$ which minimizes

$\text{MISE} = \frac{1}{T} \sum_{t=1}^T \int r_t^2 dx$ is the k th principal component
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Computationally equivalent approach

- Let $s_t^*(x) = s_t(x) - \bar{s}(x)$.
- Discretize $s_t^*(x)$ on a dense grid of q equally spaced points.
- Denote discretized $s_t^*(x)$ as $T \times q$ matrix \mathbf{G} .
- SVD of $\mathbf{G} = \Phi \Lambda \Psi'$ where $\phi_k(x)$ is k th column of Φ .
- $\beta_{t,k}$ is (t, k) th element of $\mathbf{G}\Phi$.
- The basis functions are orthogonal.
- This means the coefficients series are also uncorrelated with each other, i.e., $\text{Corr}(\hat{\beta}_{t,i}, \hat{\beta}_{t,j}) = 0$ for $i \neq j$. However, $\text{Corr}(\hat{\beta}_{t,i}, \hat{\beta}_{s,j}) \neq 0$ in general for $t \neq s$ and $i \neq j$.

Functional principal components

Computationally equivalent approach

- Let $s_t^*(x) = s_t(x) - \bar{s}(x)$.
- Discretize $s_t^*(x)$ on a dense grid of q equally spaced points.
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- SVD of $\mathbf{G} = \Phi \Lambda \Psi'$ where $\phi_k(x)$ is k th column of Φ .
- $\beta_{t,k}$ is (t, k) th element of $\mathbf{G}\Phi$.
- The basis functions are orthogonal.
- This means the coefficients series are also uncorrelated with each other, i.e., $\text{Corr}(\hat{\beta}_{t,i}, \hat{\beta}_{t,j}) = 0$ for $i \neq j$. However, $\text{Corr}(\hat{\beta}_{t,i}, \hat{\beta}_{s,j}) \neq 0$ in general for $t \neq s$ and $i \neq j$.

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Functional principal components

Eigenvector approach

- Let $\mathbf{V} = (T - 1)^{-1} \mathbf{G}' \mathbf{G}$ be $m \times m$ sample covariance matrix of \mathbf{G} .
- Let $\Phi_K = [\phi_1, \dots, \phi_K]$ consist of the first K eigenvectors of \mathbf{V} where $K \leq T - 1$. The (i, j) th element of Φ_K is $\phi_i(x_j^*)$.
- Robust versions possible using robust “covariance” estimation.

Functional principal components

Eigenvector approach

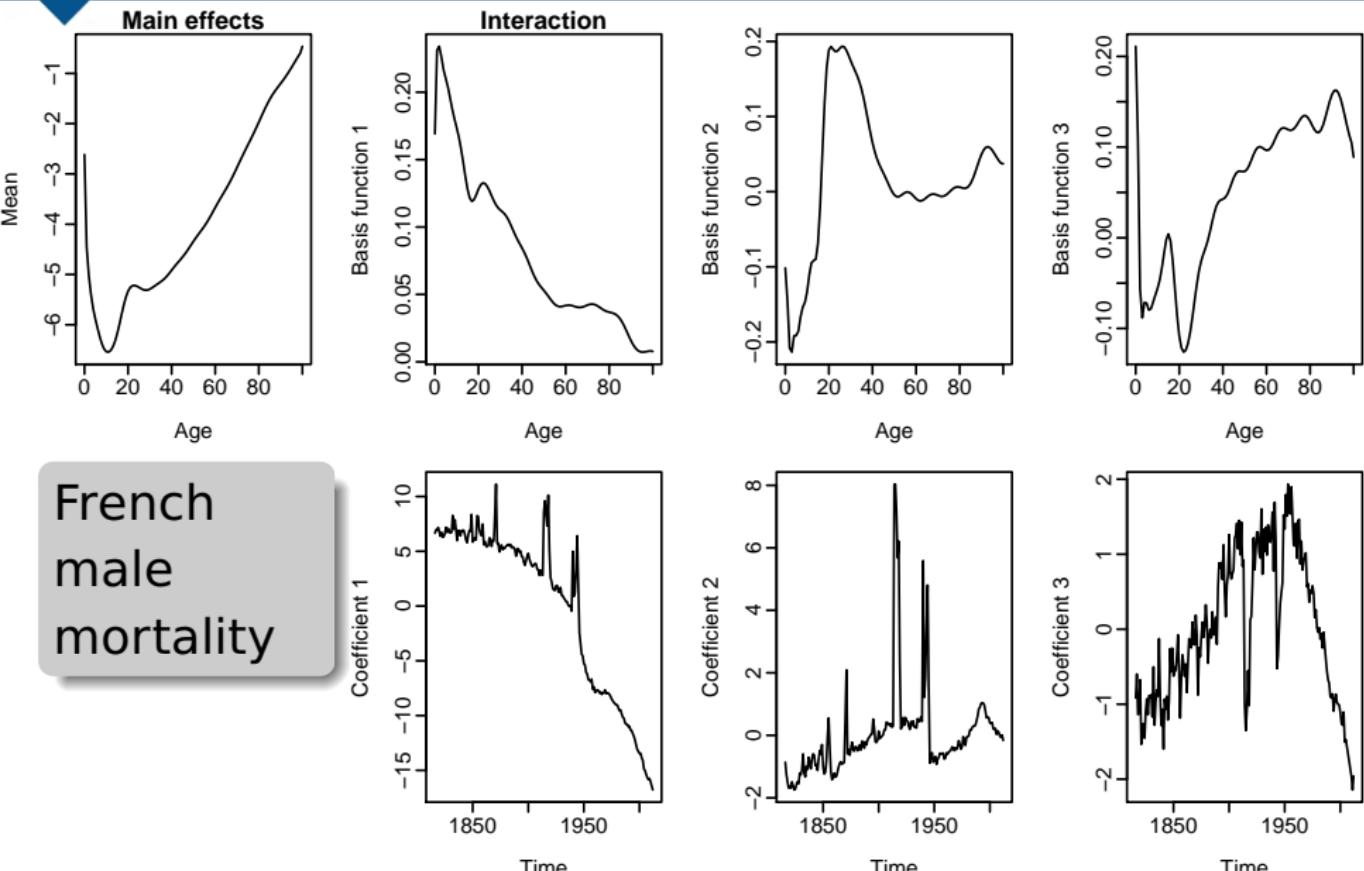
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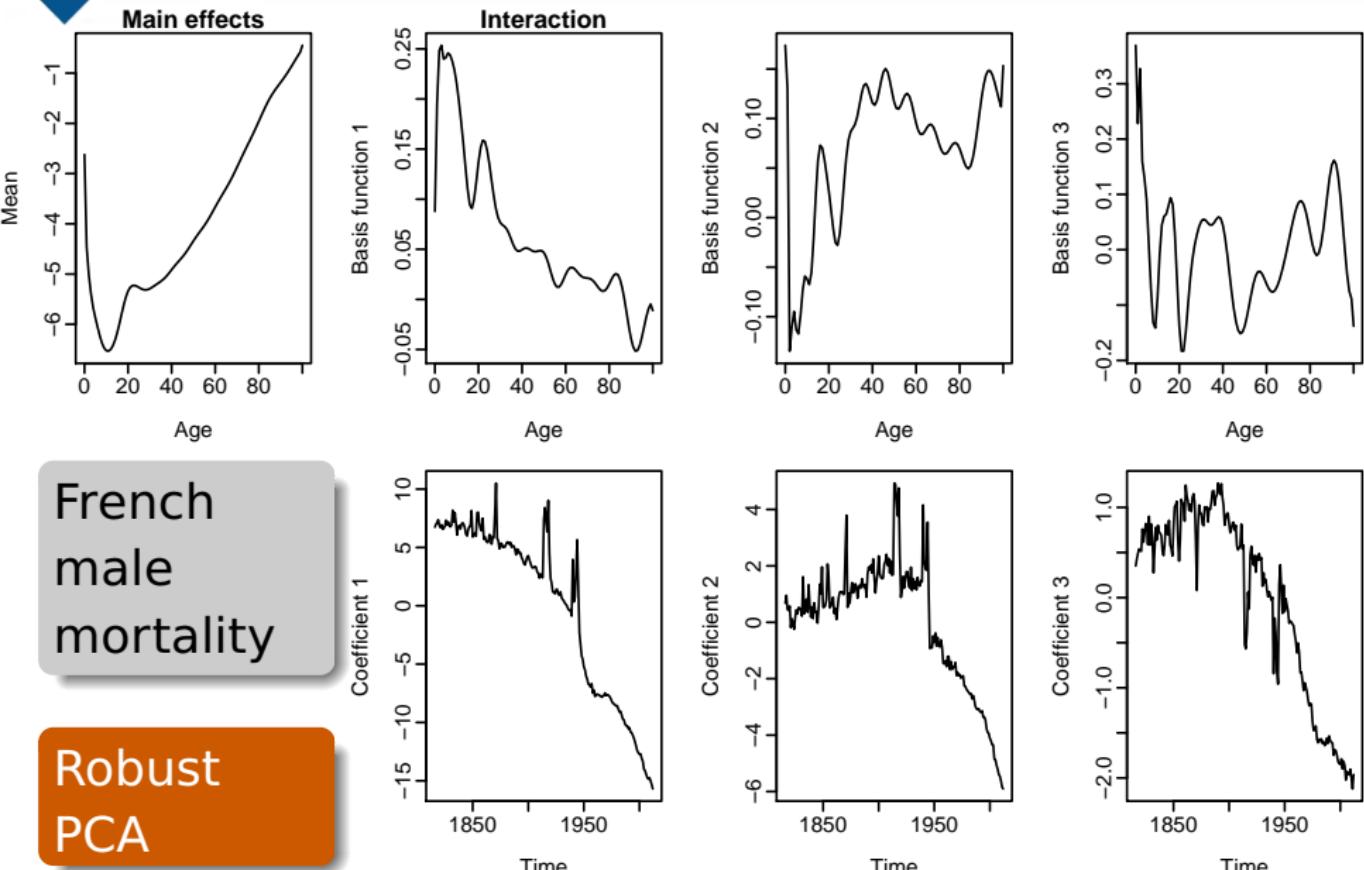
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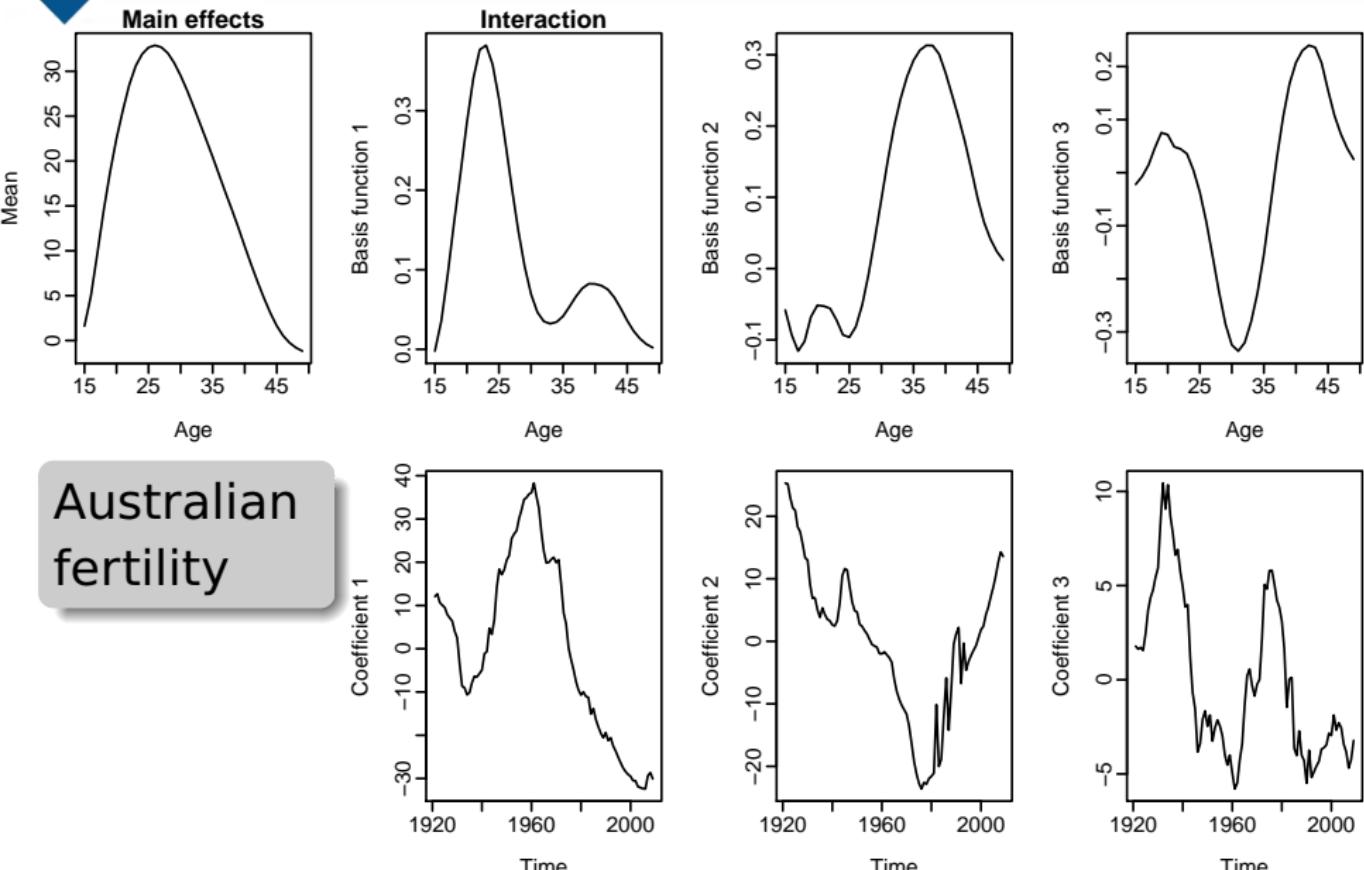
Functional principal components



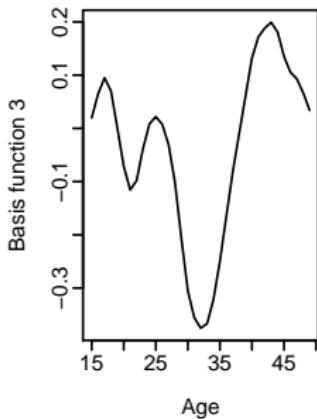
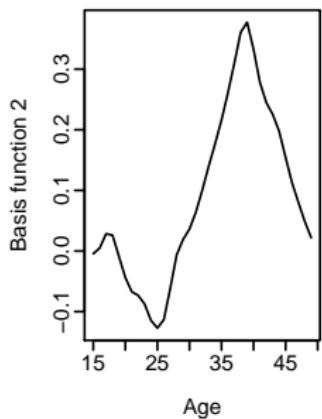
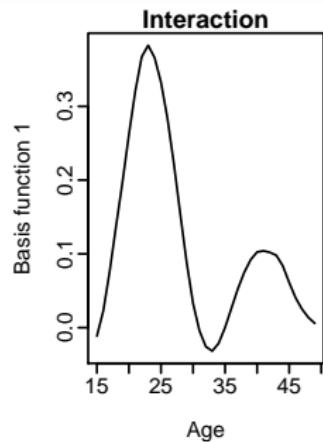
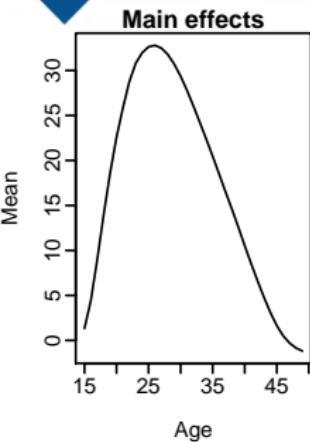
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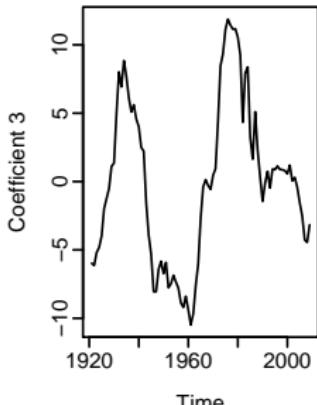
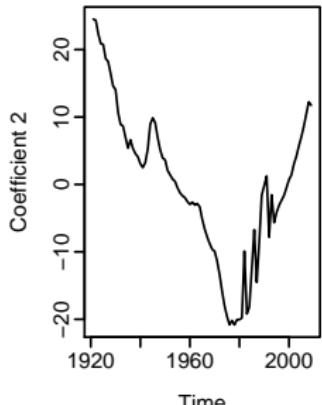
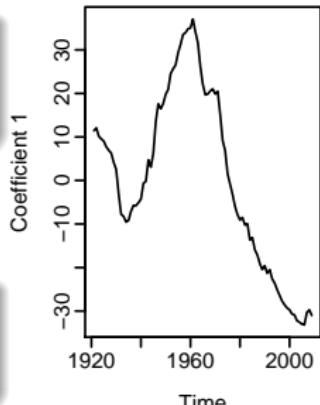
Functional principal components



Functional principal components



Australian
fertility



Robust
PCA

Outline

1 Functional time series

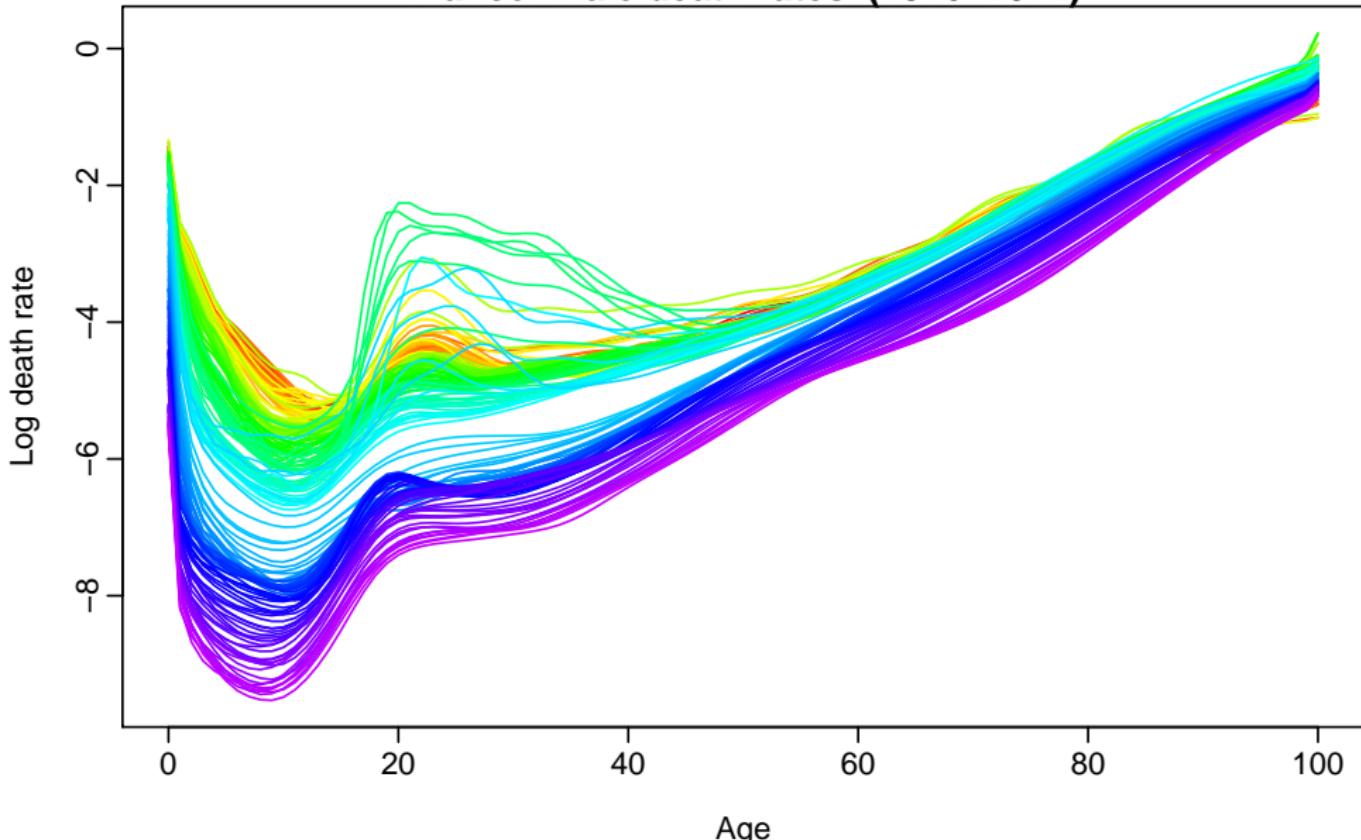
2 Functional principal components

3 Data visualization

4 References

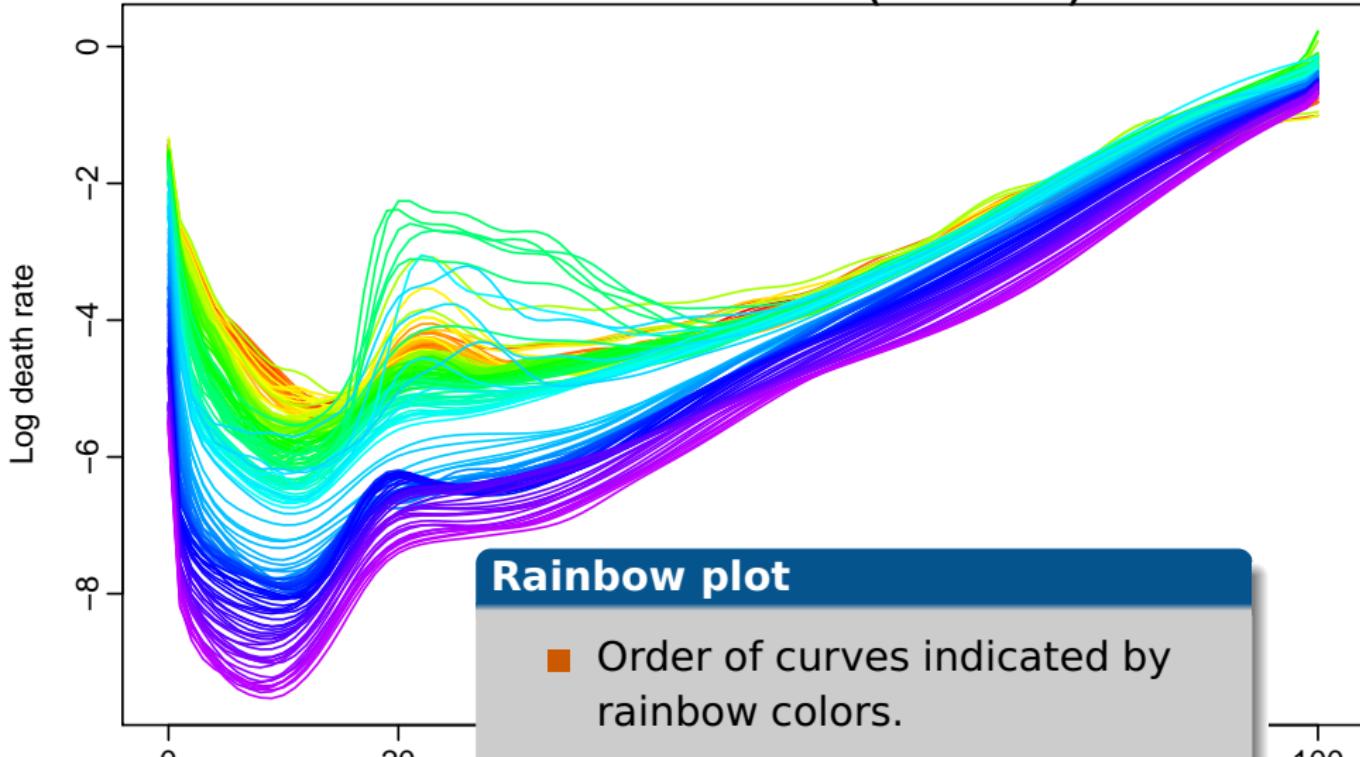
French male mortality rates

France: male death rates (1816–2012)



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Order by functional depth

Febrero, Galeano and Gonzalez-Manteiga (2007) proposed:

$$o_t = \int D(y_t(x)) dx$$

where $D(y_t(x))$ is a univariate depth measure for each x .

- o_t provides an ordering of curves by “functional depth”.
- Problem: may not detect shape outliers.

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Bivariate functional depth

Alternative: Apply bivariate depth measures to first two PC scores.

Plot $\beta_{t,2}$ vs $\beta_{t,1}$

- ▶ Each point in scatterplot represents one curve.
- ▶ Outliers show up in bivariate score space.
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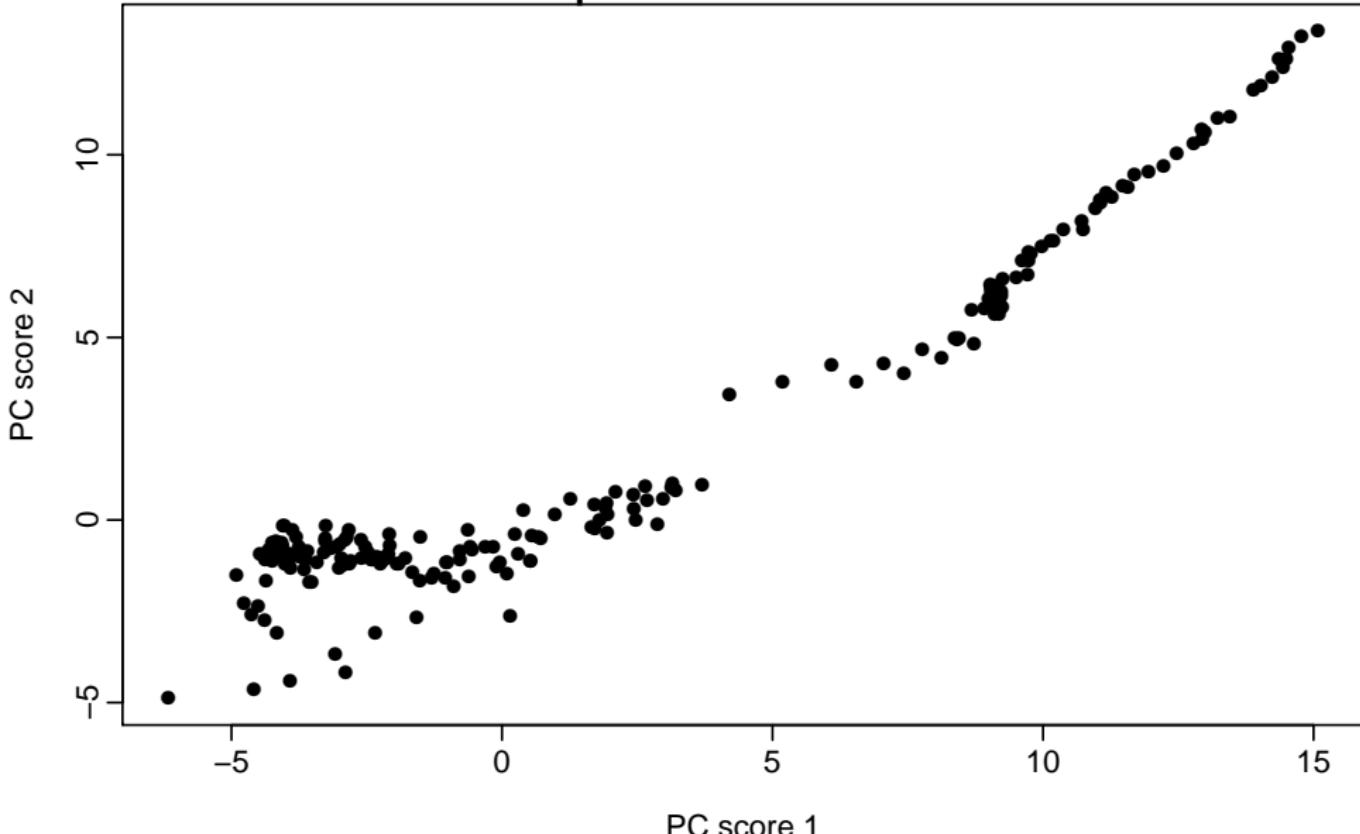
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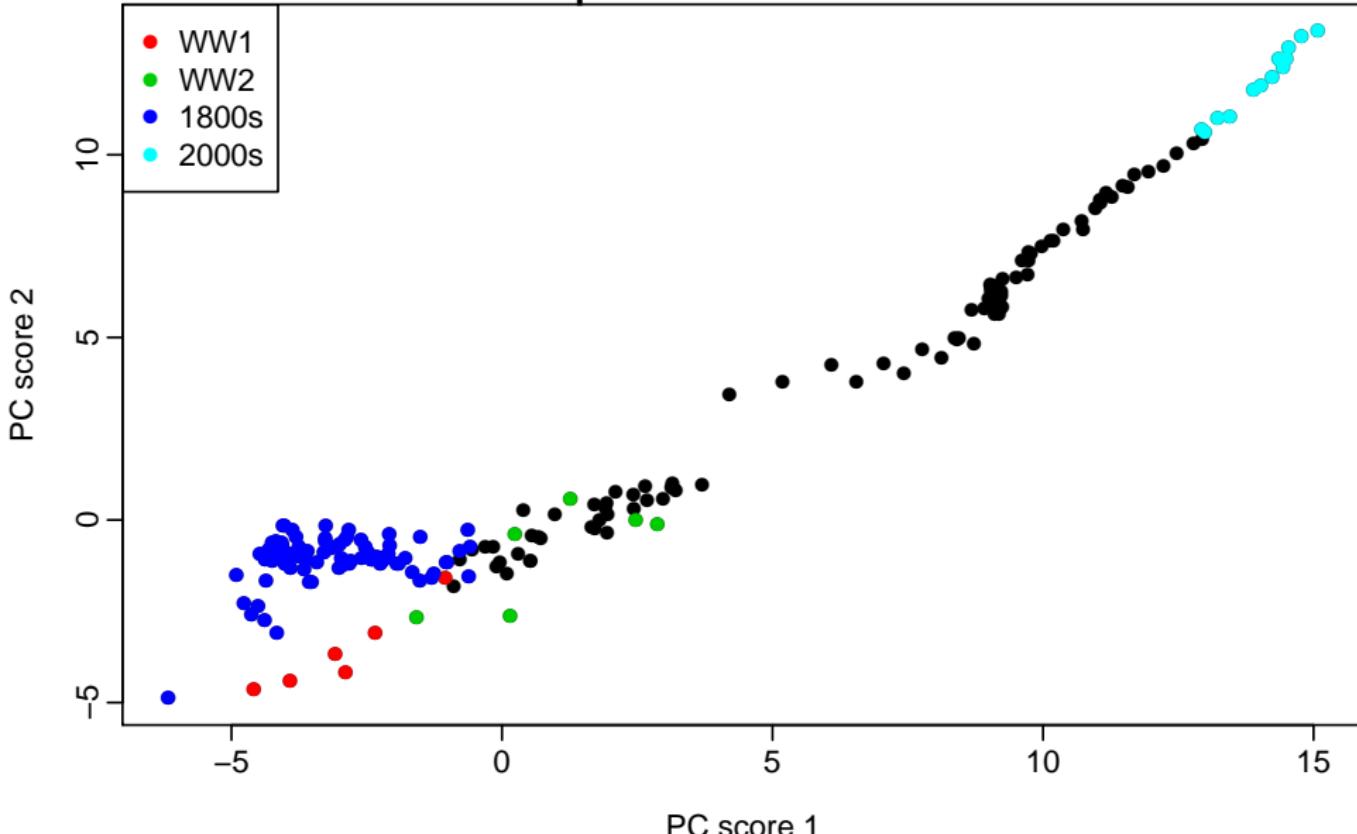
Robust PC scores

Scatterplot of first two PC scores



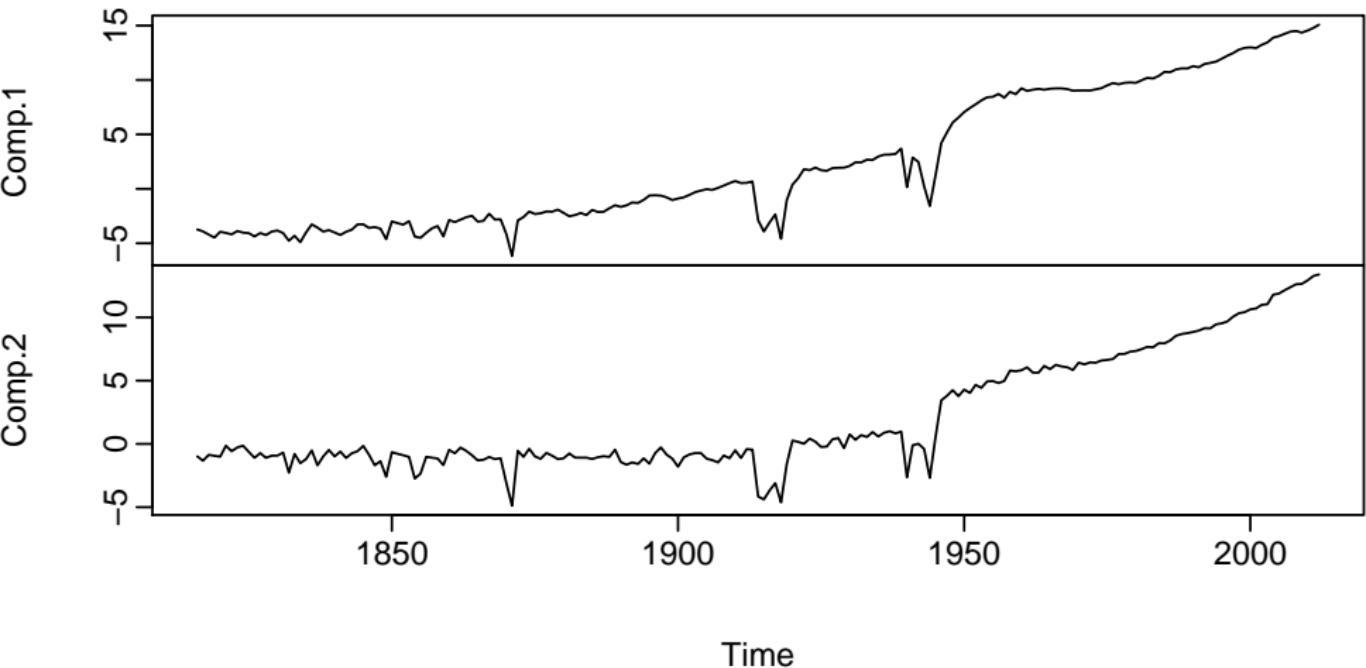
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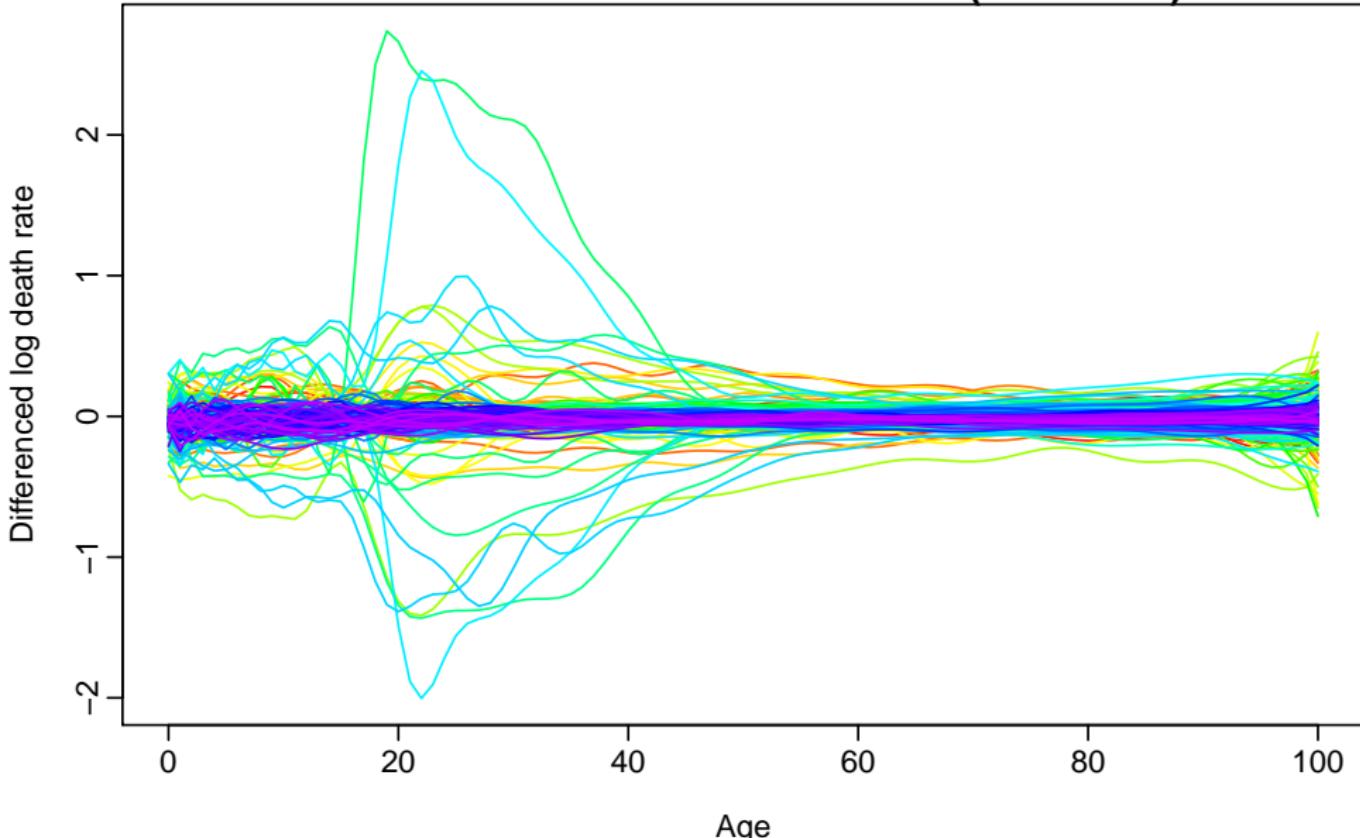
Robust PC scores

PC scores



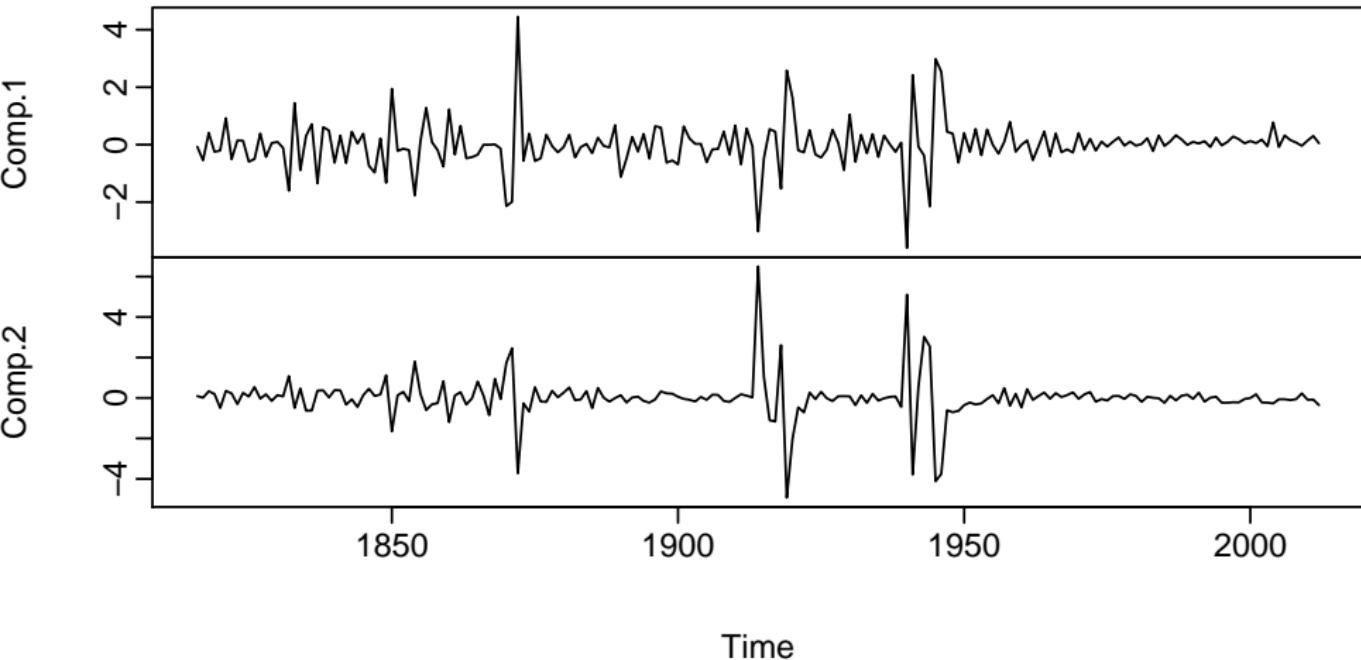
French male mortality rates

France: differenced male death rates (1816–2012)



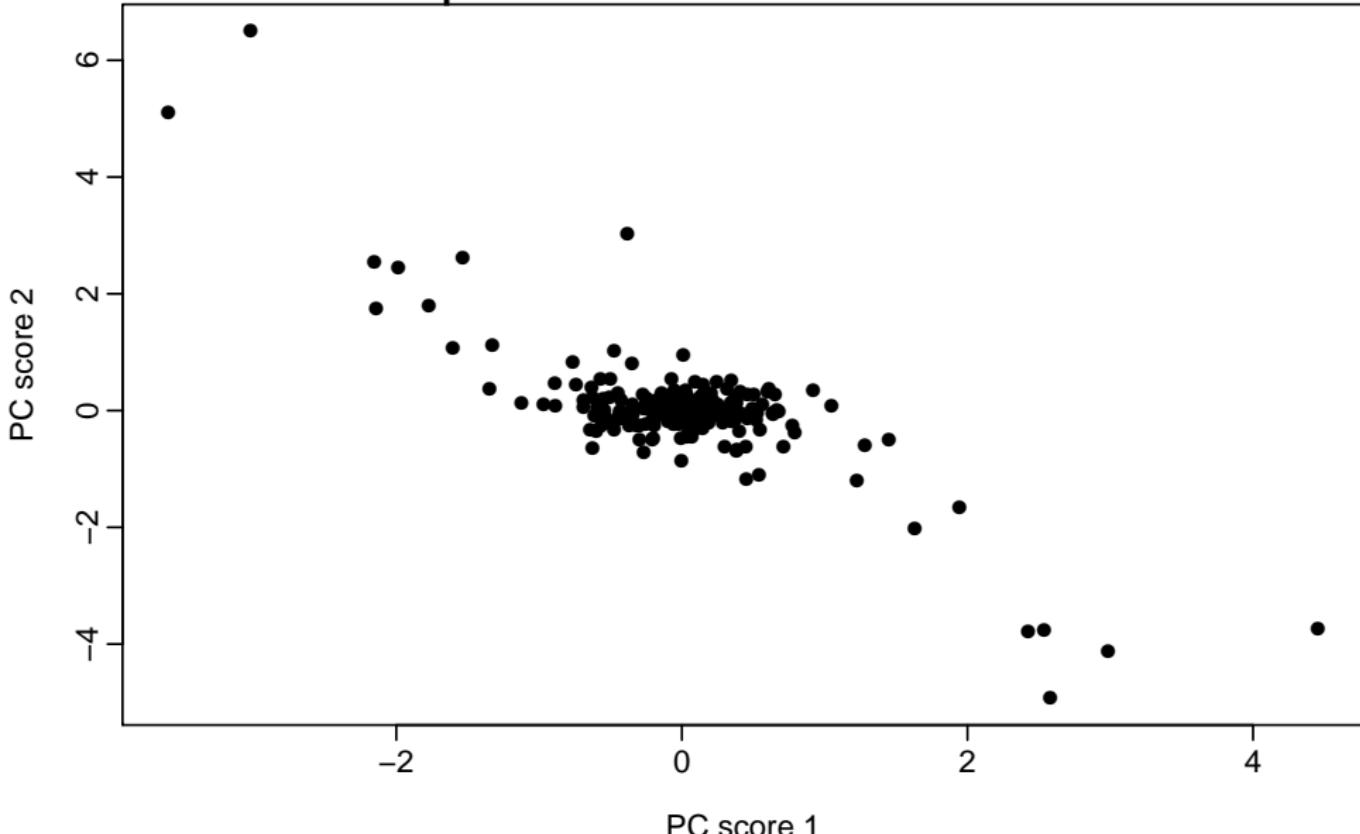
Robust PC scores

PC scores on differences



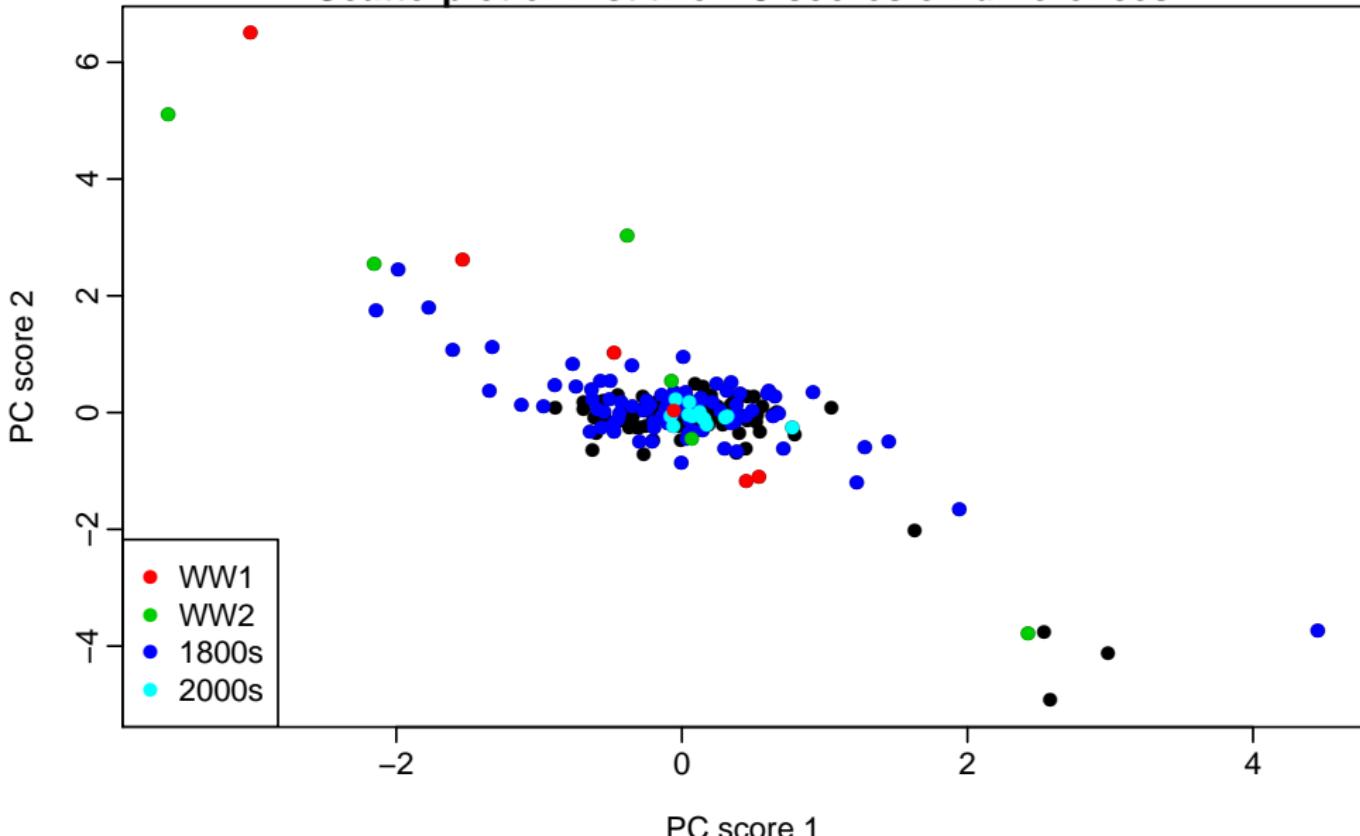
Robust PC scores

Scatterplot of first two PC scores on differences



Robust PC scores

Scatterplot of first two PC scores on differences



Halfspace location depth

The halfspace depth of a point q :

(Due to Hotelling, 1929; Tukey, 1975)

- For each closed halfspace that contains q , count number of observations not in halfspace. The minimum over all halfspaces is the depth of that point.
- The median is the point with maximum depth (not generally unique).
- Any point outside convex hull of the data has depth zero.

Halfspace location depth

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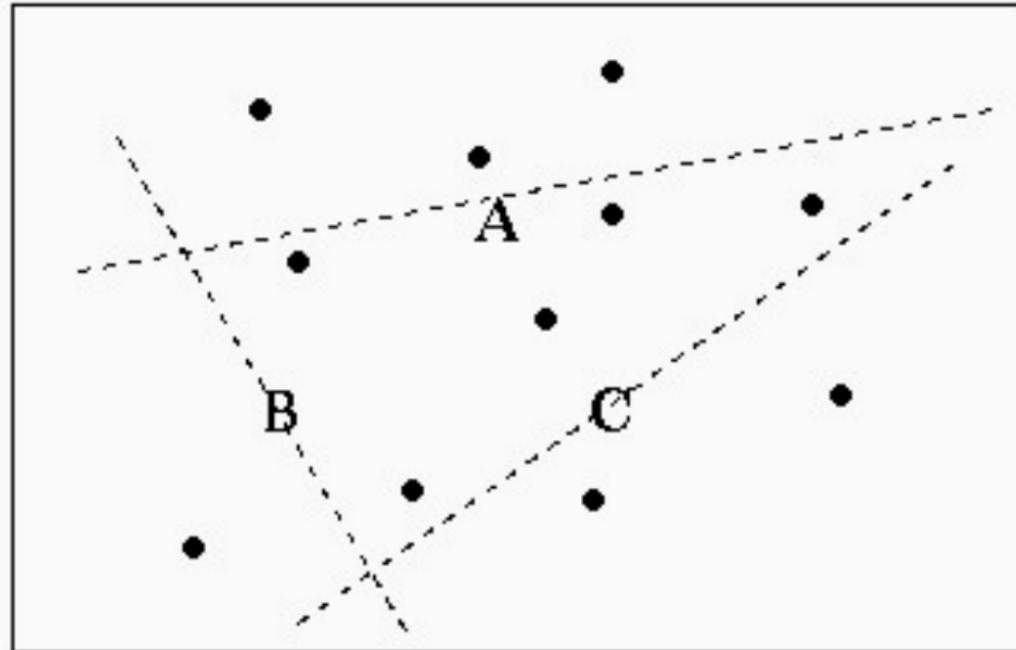


Fig.5 : Depth of certain points with respect to a data set.
 $\text{depth}(A) = 3$, $\text{depth}(B) = 1$, $\text{depth}(C) = 2$.

Halfspace location depth

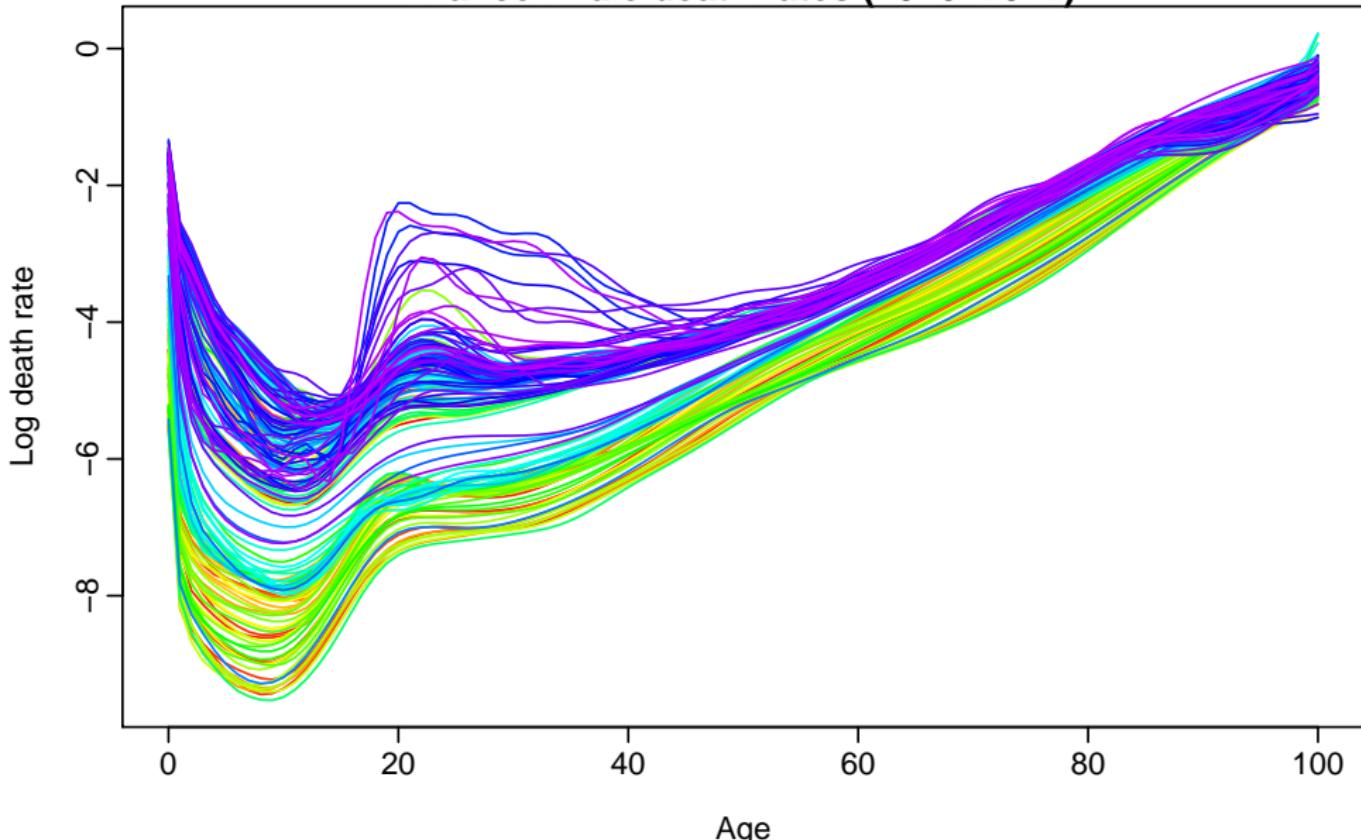
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Ordering by halfspace depth

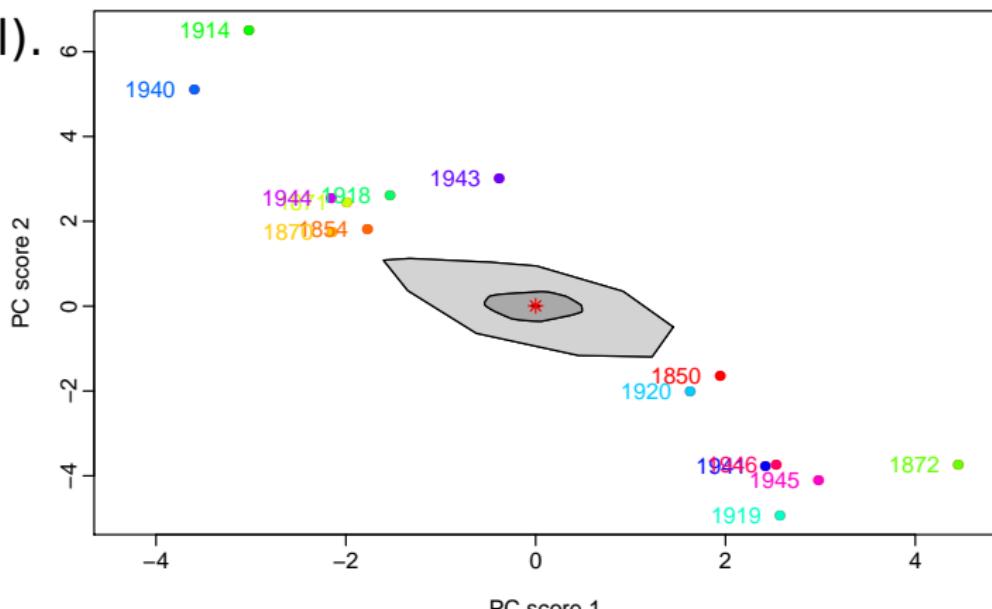
France: male death rates (1816–2012)



Bivariate bagplot

Due to Rousseeuw, Ruts & Tukey (Am.Stat. 1999).

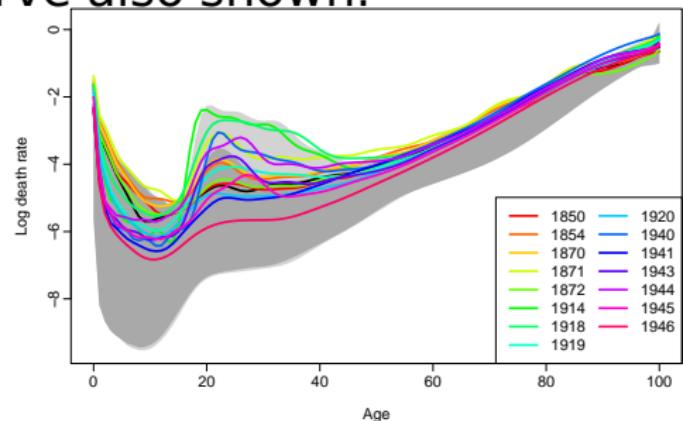
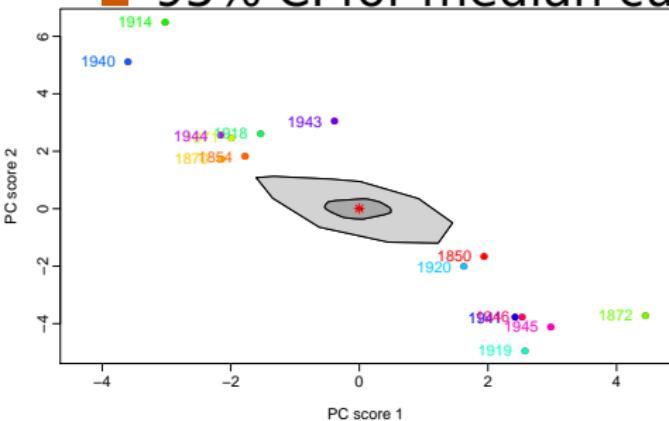
- Rank points by halfspace location depth.
- Display median, 50% convex hull and outer convex hull (with 99% coverage if bivariate normal).



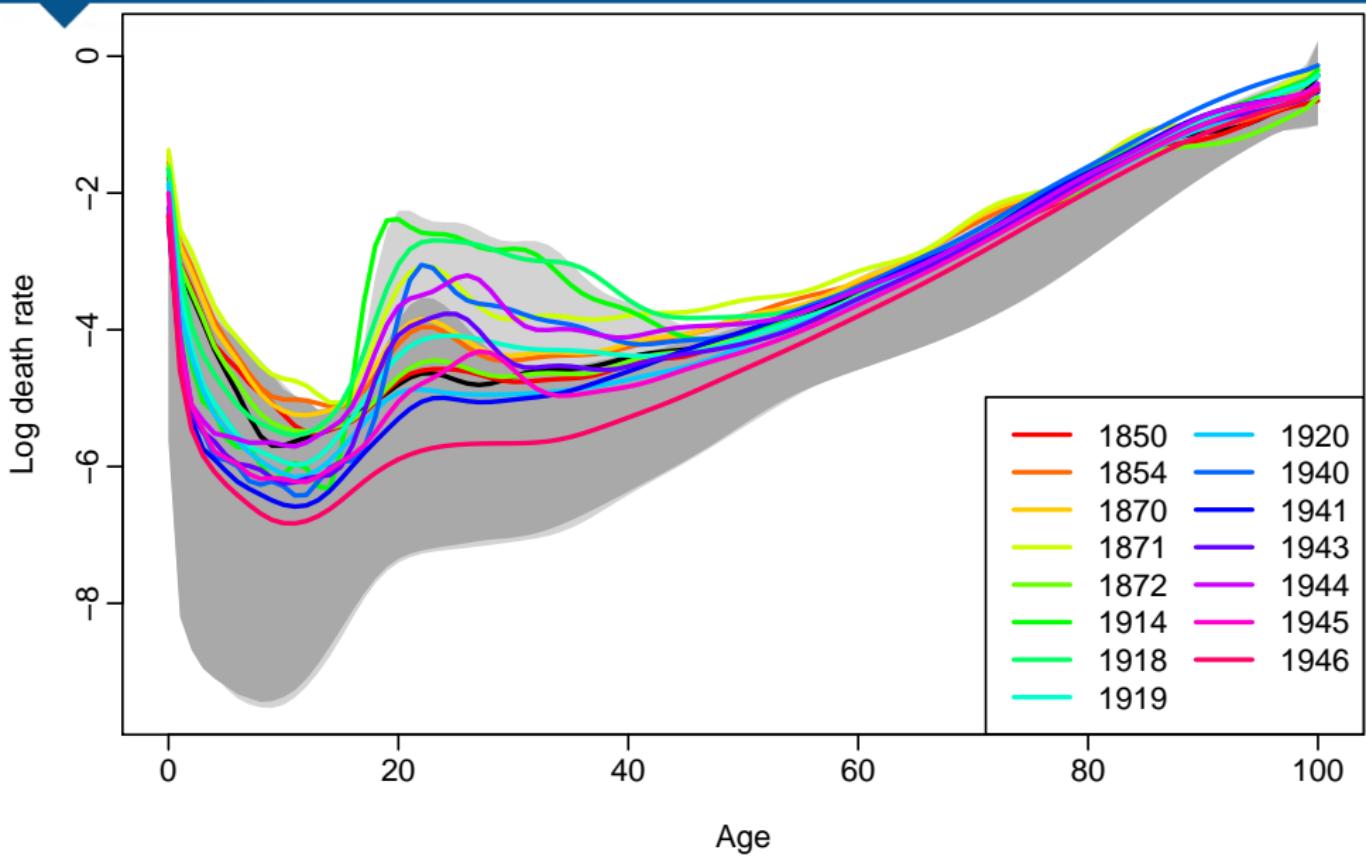
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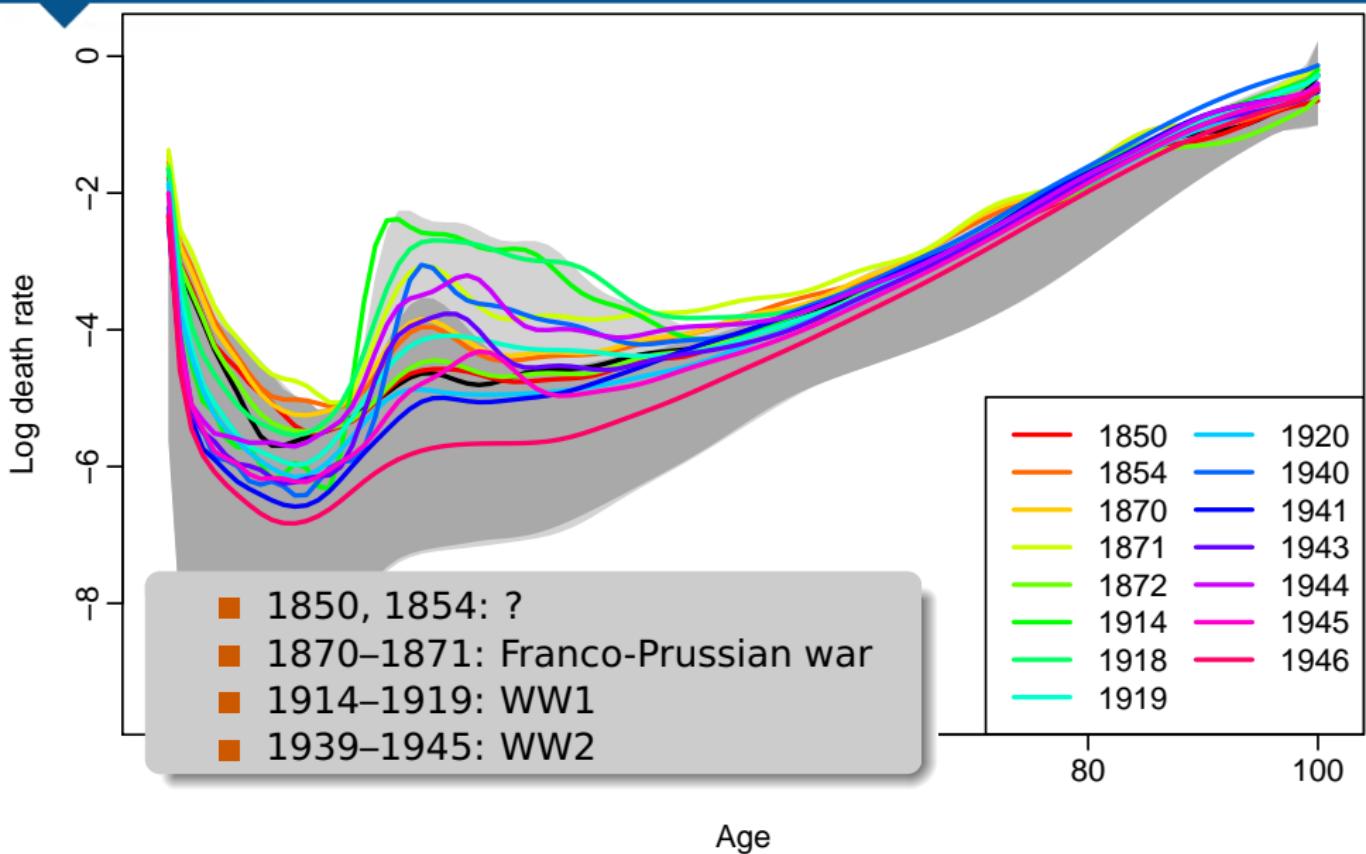
- Rank points by halfspace location depth.
- Display median, 50% convex hull and outer convex hull (with 99% coverage if bivariate normal).
- Boundaries contain all curves inside bags.
- 95% CI for median curve also shown.



Functional bagplot

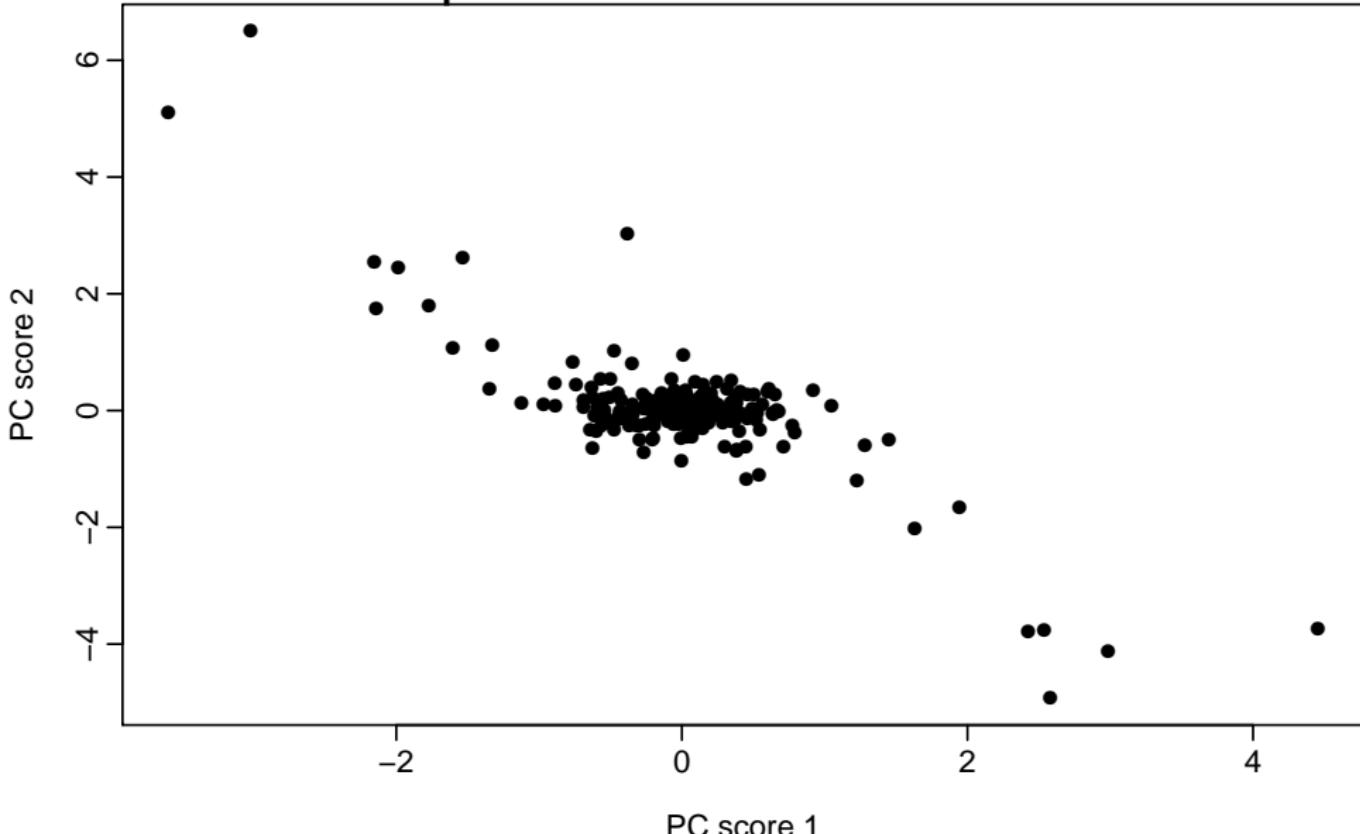


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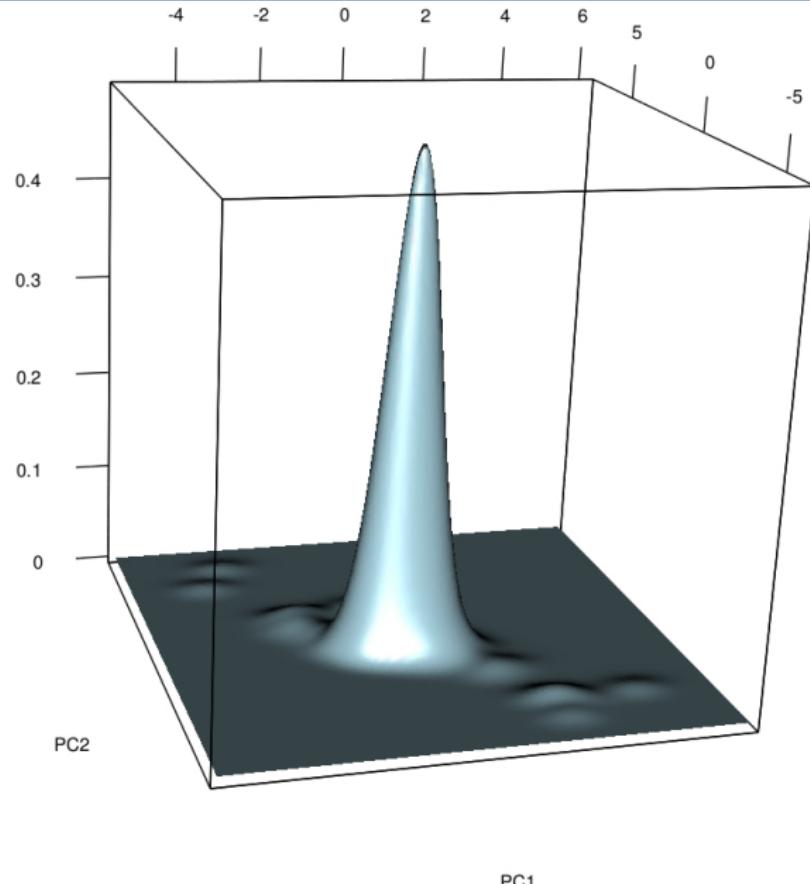


Kernel density estimate

Scatterplot of first two PC scores on differences

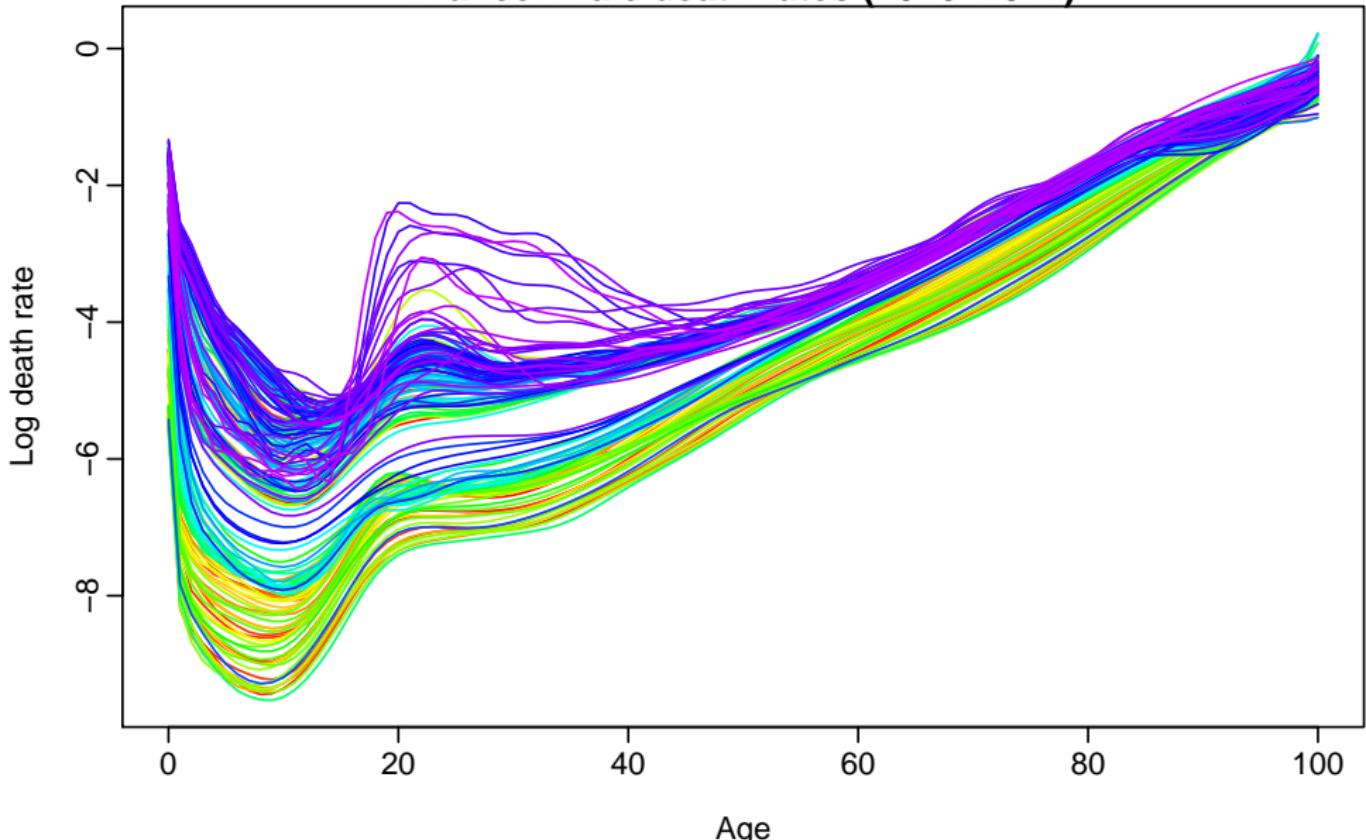


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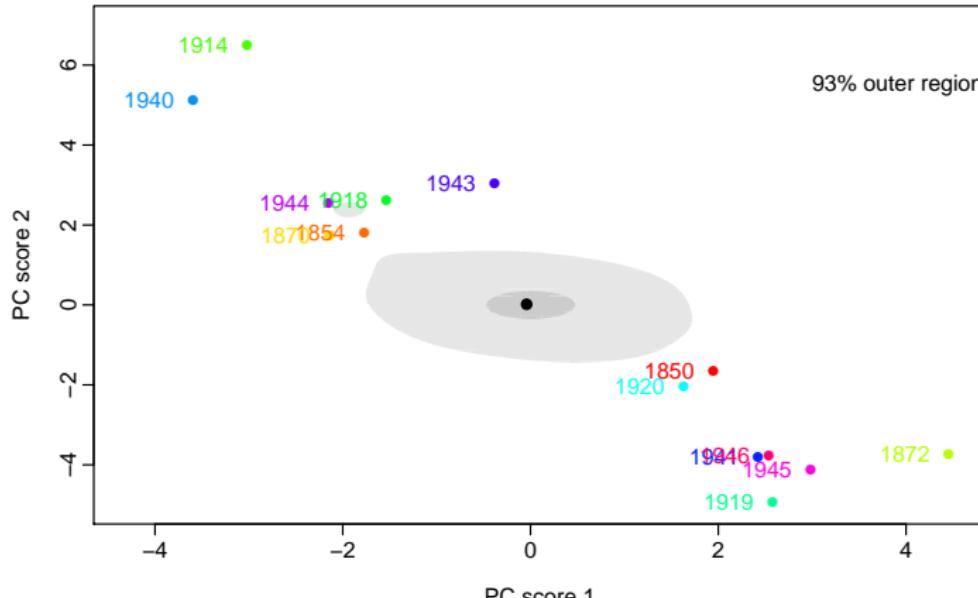
Ordering by bivariate density

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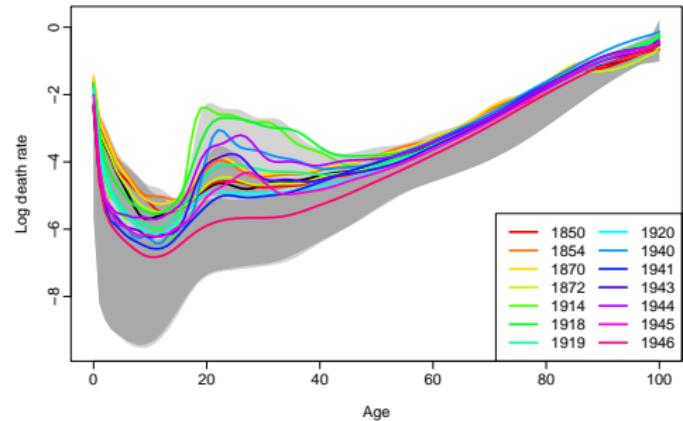
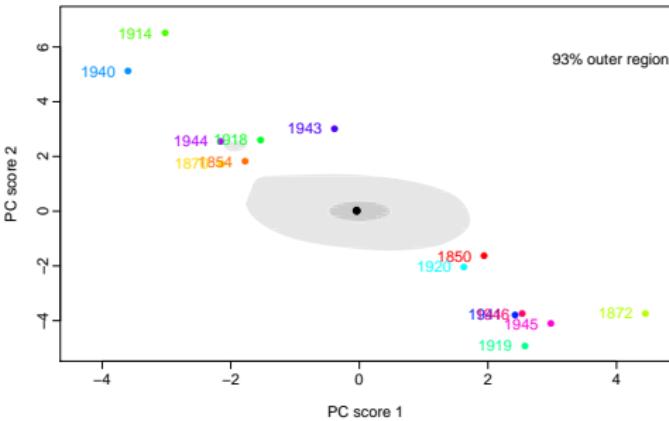
Functional HDR boxplot

- Bivariate HDR boxplot due to Hyndman (1996).
- Rank points by value of kernel density estimate.
- Display mode, 50% and (usually) 99% highest density regions (HDRs) and mode.

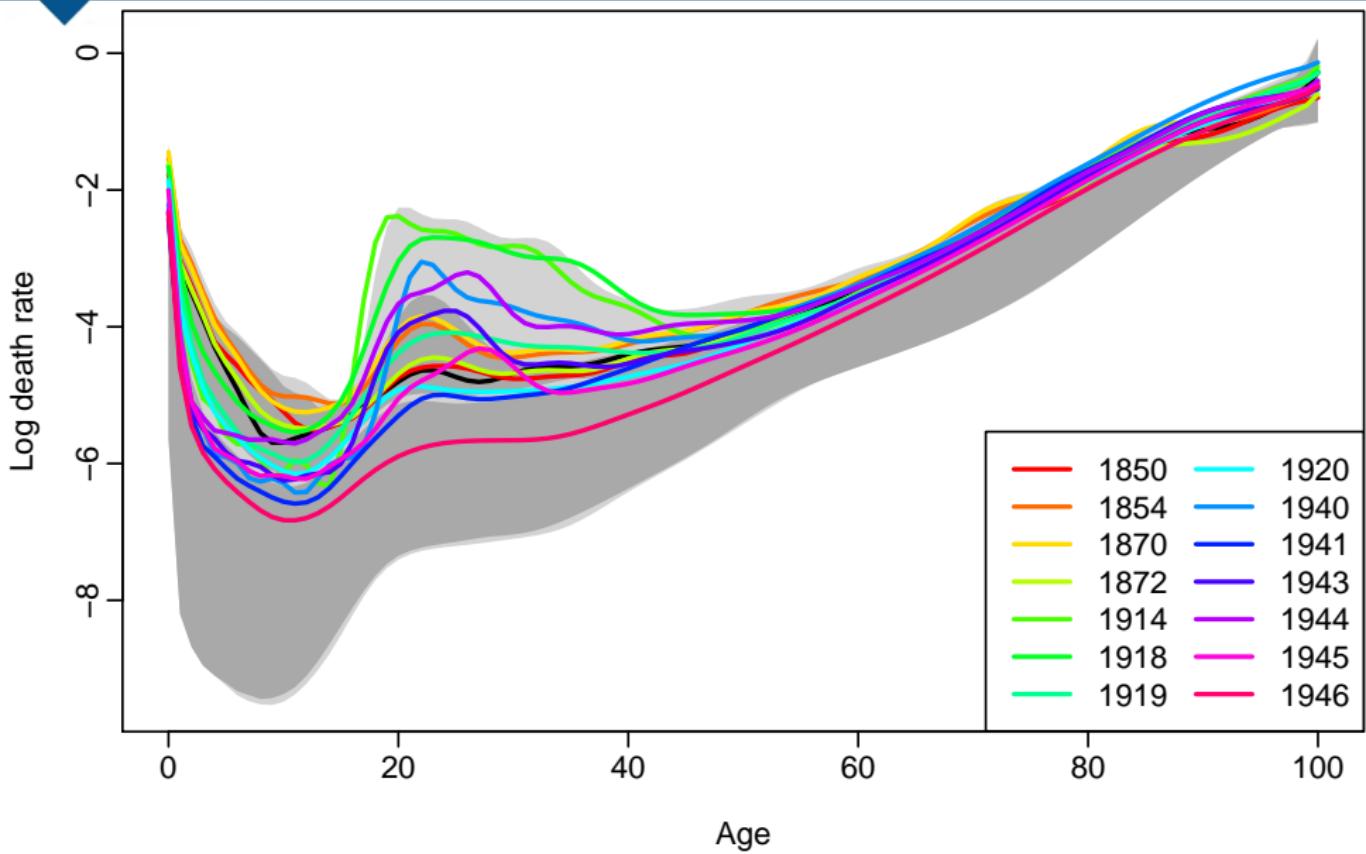


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Functional HDR boxplot



Outline

1 Functional time series

2 Functional principal components

3 Data visualization

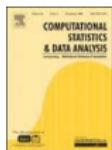
4 References

Selected references



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cran.r-project.org/package=demography