

Likelihood-based inference in temporal hierarchies

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Outline

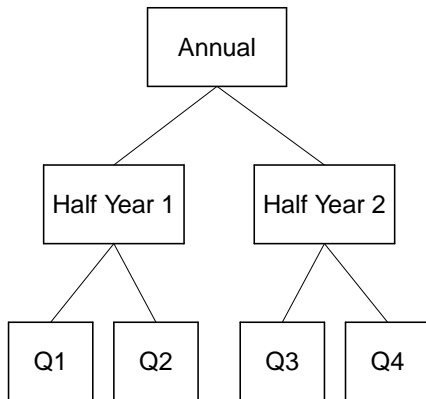
- 1 Introduction
- 2 Heat load forecasting
- 3 Likelihood inference
- 4 Conclusion and Future

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Motivation

- Models on different aggregation levels
- Models on each level may not agree
- Reconciliation ensure consistent forecasts
- Reconciliation often improve forecast accuracy on all levels



Reconciliation

The reconciled forecast is calculated by

$$\tilde{\mathbf{y}} = (\mathbf{S}^T \boldsymbol{\Sigma}^{-1} \mathbf{S})^{-1} \mathbf{S}^T \boldsymbol{\Sigma}^{-1} \hat{\mathbf{y}}$$

where:

- $\tilde{\mathbf{y}}$: reconciled forecast
- \mathbf{S} : the summation matrix
- $\boldsymbol{\Sigma}$: a variance-covariance matrix
- $\hat{\mathbf{y}}$: the base forecast

$$\mathbf{S} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Regression setting

$$\hat{\mathbf{y}} = \mathbf{S} \tilde{\mathbf{y}} + \boldsymbol{\epsilon}; \quad \boldsymbol{\epsilon} \sim N(\mathbf{0}, \boldsymbol{\Sigma})$$

Choosing the correct variance

Different options for Σ :

- $\Sigma = I$
- Variance scaling (proportional to volume of level)
- Use observed variance-covariance of base forecast error
- Ignore cross level correlation
- Use shrinkage on the observed variance-covariance (usually preferred).
I.e.

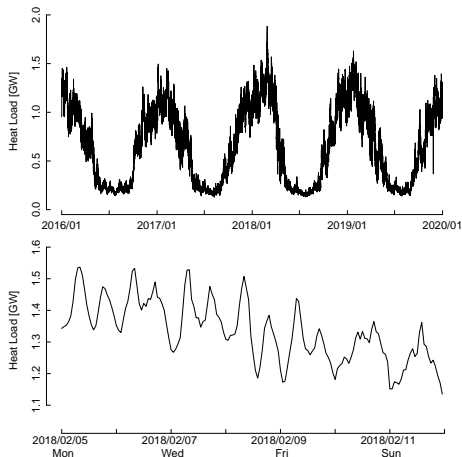
$$\hat{\Sigma}_s = \lambda \hat{\Sigma} + (1 - \lambda) \text{diag} \hat{\Sigma}$$

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Data

- District heating from an area of greater Copenhagen
- Clear annual and diurnal variation
- State of the art commercial hourly forecast (1-24 hours ahead)
- 2016 used for initialization



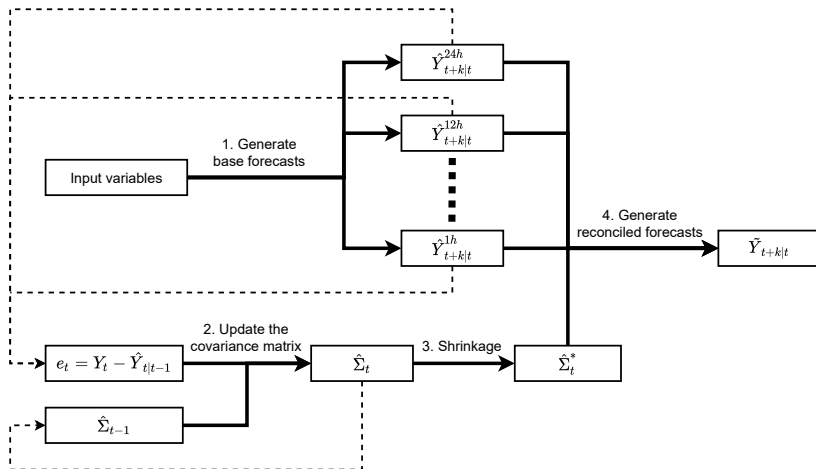
From Bergsteinsson et al. (2021).

A case study

- 1 hour level used as evaluation
- All other levels modeled in the study
- 2, 3, 4, 6, 8, 12, and 24 hours forecast:
 - Recursive Least Square
 - Forecast of ambient temperature
 - Diurnal variation
 - Auto-regressive parts
- Σ_t (60 by 60) estimated using the full variance covariance with shrinkage, and recursive updating.

Work flow of modeling

5. Compute forecast error when observations become available



From Bergsteinsson et al. (2021).

Some results (RRMSE)

	2017–2019			
	Base RMSE	Expanding Window	Rolling Window	Exponential Smoothing
Daily	0.5960	-23.75	-22.49	-23.93
Twelve-hourly	0.3516	-24.08	-22.83	-24.2
Eight-hourly	0.3538	-43.51	-42.72	-43.69
Six-hourly	0.2876	-44.64	-43.75	-44.76
Four-hourly	0.1765	-36.06	-35.19	-36.37
Three-hourly	0.1334	-33.03	-32.05	-33.26
Two-hourly	0.0884	-30.09	-29.07	-30.36
Hourly	0.0383	-14.75	-13.46	-15.07

Adapted from Bergsteinsson et al. (2021).

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Motivation / Aim

The starting point

$$\tilde{\mathbf{y}} = (\mathbf{S}^T \mathbf{\Sigma}^{-1} \mathbf{S})^{-1} \mathbf{S}^T \mathbf{\Sigma}^{-1} \hat{\mathbf{y}}$$

Comments and aim

- Observations appear only through the variance-covariance matrix $\mathbf{\Sigma}$
- The estimation of $\mathbf{\Sigma}$ includes a large number of parameters
- Formulate a parameterized model for obtaining $\mathbf{\Sigma}$
- Reduce dimension of the parameter space by well-known likelihood techniques

Example

Example: Assume that half year levels generated by

$$Y_t = \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \epsilon_t,$$

AR(1) models half-year levels and annual levels, i.e. the models

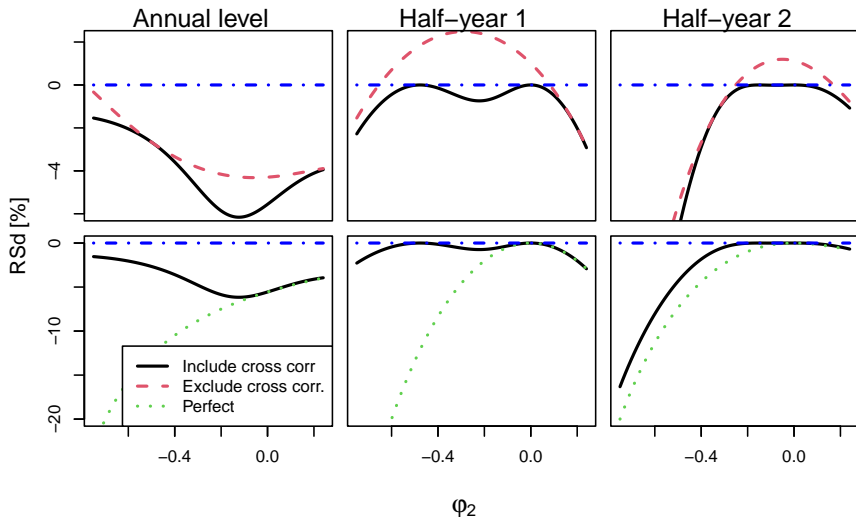
$$\begin{aligned} y_t^A &= \phi_1^A y_{t-1}^A + \epsilon_t^A \\ y_t^H &= \phi_1^H y_{t-1}^H + \epsilon_t^H. \end{aligned}$$

Full setup

$$\mathbf{y}_{2t+2|2t} = \begin{bmatrix} y_{2t+2|2t}^A \\ y_{2t+1|2t}^H \\ y_{2t+2|2t}^H \end{bmatrix}; \quad \hat{\mathbf{y}}_{2t+2|2t} = \begin{bmatrix} \hat{y}_{2t+2|2t}^A \\ \hat{y}_{2t+1|2t}^H \\ \hat{y}_{2t+2|2t}^H \end{bmatrix}; \quad \mathbf{S} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

and e.g. $\Sigma = \text{Var}[\mathbf{y}_{2t+2} - \hat{\mathbf{y}}_{2t+2}]$ can be calculated explicitly.

Choosing the correct variance-covariance



$$\phi_1 = 0.75$$

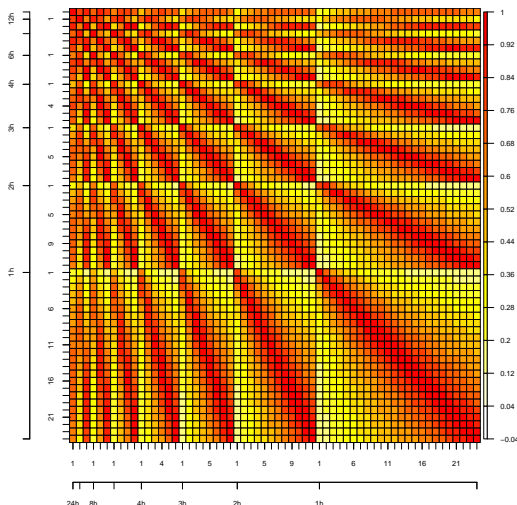
Modeling of variance-covariance matrix

Σ (some challenges):

- High-dimensional
- High correlations

Some suggestions

- Parametric models for the correlation
- Use statistical methods for reduction



Graphics: Møller et al. (2023)

A parametric model

Starting from the bottom level define (Møller et al., 2023)

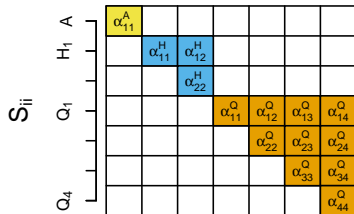
$$\begin{aligned}
 \boldsymbol{\epsilon}_1 &= \boldsymbol{u}_1 & ; \quad \boldsymbol{u}_1 &\sim N(\mathbf{0}, \boldsymbol{\Sigma}_1), \\
 \boldsymbol{\epsilon}_2 &= \boldsymbol{S}_{21}\boldsymbol{u}_1 + \boldsymbol{u}_2 & ; \quad \boldsymbol{u}_2 &\sim N(\mathbf{0}, \boldsymbol{\Sigma}_2), \\
 \boldsymbol{\epsilon}_3 &= \boldsymbol{S}_{31}\boldsymbol{u}_1 + \boldsymbol{S}_{32}\boldsymbol{u}_2 + \boldsymbol{u}_3 & ; \quad \boldsymbol{u}_3 &\sim N(\mathbf{0}, \boldsymbol{\Sigma}_3), \\
 &\vdots & \\
 \boldsymbol{\epsilon}_K &= \sum_{j=1}^{K-1} \boldsymbol{S}_{Kj}\boldsymbol{u}_j + \boldsymbol{u}_K & ; \quad \boldsymbol{u}_K &\sim N(\mathbf{0}, \boldsymbol{\Sigma}_K),
 \end{aligned}$$

where $Cov[\boldsymbol{u}_i, \boldsymbol{u}_j] = \mathbf{0}$, ($i \neq j$). And

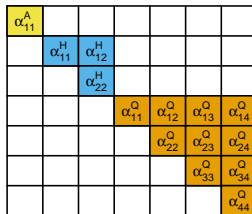
$$\boldsymbol{\Sigma}_i^{-1} = \boldsymbol{S}_{ii}\boldsymbol{S}_{ii}^T,$$

with \boldsymbol{S}_{ii} is an upper triangular matrix.

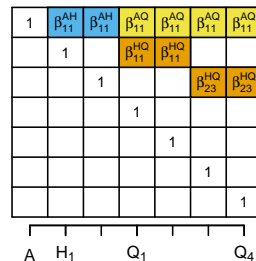
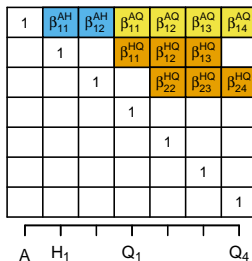
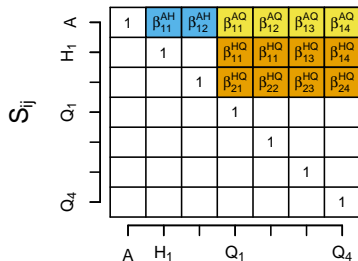
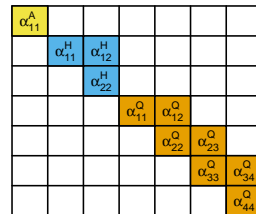
Full-Full



Full-1



Null



S_{QQ}, S_{HQ}

S_{HH}, S_{AH}

S_{AA}, S_{AQ}

Estimation

Likelihood

$$l(\boldsymbol{\beta}, \boldsymbol{\alpha}; \mathbf{V}) \propto -\frac{T-1}{2} \text{Tr} \boldsymbol{\Sigma}^{-1} \mathbf{V} + \frac{T-1}{2} \log |\boldsymbol{\Sigma}^{-1}|,$$

where \mathbf{V} is the observed variance-covariance matrix, $\boldsymbol{\Sigma}^{-1}$ is parameterized through the model and estimation is done

- Sequentially starting from the bottom level
- Using:
 - a robust EM-like algorithm (solving normal equations) and
 - the Newton method (using the Hessian of the likelihood)

diagonal elements of \mathbf{S}_{ii} is estimated in the log-domain.

Shrinkage

A simple modification of the likelihood by introducing weights in the following way:

$$l_s(\boldsymbol{\Sigma}; \mathbf{V}, \mathbf{w}) = l(\boldsymbol{\Sigma}; w_1 \mathbf{V} + w_2 \text{blockdiag} \mathbf{V} + w_3 \text{diag} \mathbf{V}),$$

where $\sum_i w_i = 1$.

Statistical tests

As the method is based on likelihood estimation we have access to

- Wald test for individual parameters or sets of parameters
- Likelihood ratio test for individual parameters or specific hypothesis

In the work we explore

- Wald test for testing if parameters should be zero or equal and confirm using LRT
- Effect of different initial structures

The algorithm, Bottom level

1 Estimation.

- 1 Initialise a variance–covariance structure for the bottom level
- 2 Iterate between α_{ij} and α_{ii} a fixed number of times
- 3 Use the result from 2 as initial value for the Newton method.
- 4 Report the parameter estimates, likelihood, and Hessian.

2 Model reduction.

- 1 Choose in which order to test parameters for removal
- 2 Calculate the test statistics for the increasing set of parameters until significant and confirm by LRT.
- 3 Calculate the test statistics for all relevant pairwise comparison and individual parameters that can be set to zero
- 4 Reduce model, and confirm by likelihood-ratio test.
- 5 Report parameters and structure of S_{ii} and S_{ij} .

The algorithm, Top levels

- 1 Iterate through higher aggregation levels with the lower levels fixed in the same way as the bottom level, now including estimation of β
- 2 Report the final result.

Case study

- Electricity load in Sweden 2016-2020
- 2016-2019 used for estimating mean value structure
- Linear model including annual and diurnal variation
- Double seasonal AR models of the residuals (daily and weekly)
- Temporal reconciliation of residuals



Some results

	SE		SE1		SE2		SE3		SE4	
	df	RRMSE	df	RRMSE	df	RRMSE	df	RRMSE	df	RRMSE
Obs-test	1830	-12.4	1830	-8.5	1830	-9.8	1830	-15.9	1830	-15.3
Obs-train	1830	0.1	1830	4.1	1830	2.1	1830	-2.3	1830	-5.2
Full-Full ₁	402	-4.8	306	-1.7	413	-4.1	413	-5.6	464	-5.5
Full-Full ₂	402	-5.3	306	0.8	413	-3.1	413	-5.8	464	-6.6
Full-2 ₁	219	-3.8	180	-3.2	237	-4.0	240	-3.9	264	-4.0
Full-2 ₂	219	-3.8	180	-2.2	237	-3.8	240	-4.9	264	-3.7
Null-Null ₁	83	-4.3	77	-2.7	81	-4.1	85	-4.8	85	-4.6
Null-Null ₂	83	-3.7	77	-0.7	81	-3.1	85	-4.0	85	-4.1
Shrink	0.015	-5.3	0.016	-1.3	0.035	-4.0	0.015	-7.4	0.016	-7.0
Auto-cov.	69	-2.2	49	-2.9	49	-3.5	71	-1.6	71	-2.2
Model-AR1	60	-2.4	60	-3.0	60	-3.2	60	-1.9	60	-2.2
Diag	60	-3.1	60	-2.4	60	-2.6	60	-2.9	60	-2.6

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Conclusion / Future

- Parameterized model for the variance-covariance matrix
- Statistical tests and huge reduction in number of parameters
- Similar performance as shrinkage
- Likelihood based inference including algorithms for estimation and testing
- Shrinkage needed

Open

- Error propagation from Σ to the weight matrix?
- Structured models for S_{ii} and S_{ij}

References

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- [2] Møller J.K., Nystrup P., and Madsen H. (2023). Likelihood-based inference in temporal hierarchies. *International Journal of Forecasting*, *in press*.
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Thank You!

Questions?