Improving forecasts via subspace projections

Rob J Hyndman



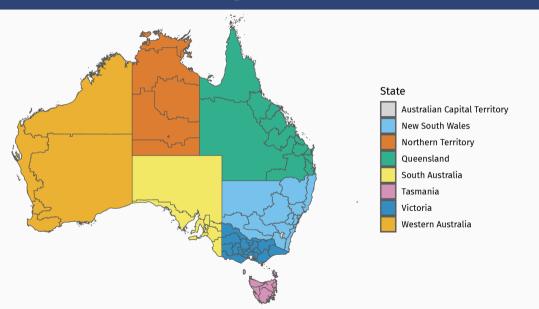
Outline

- 1 Improving hierarchical forecasts
- 2 Improving univariate forecasts
- 3 Improving multivariate forecasts
- 4 Final comments

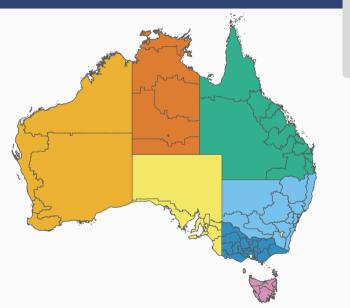
Outline

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Australian tourism regions



Australian tourism regions



- Monthly data on visitor nights: 1998 – 2016
- 7 states
- 27 zones
- 76 regions





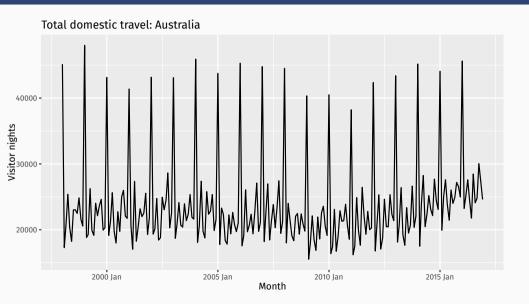
New South Wales Northern Territory

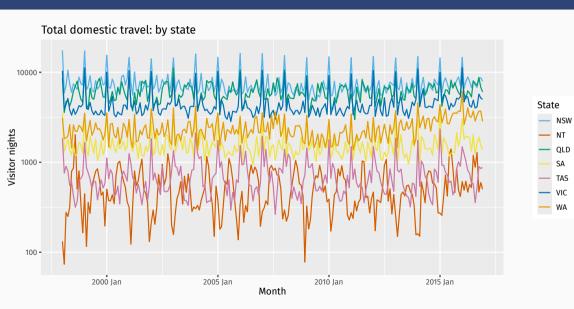
Queensland

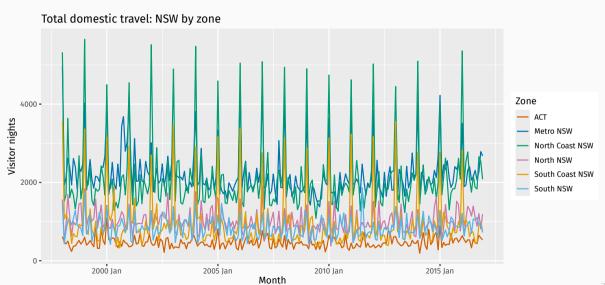
South Australia

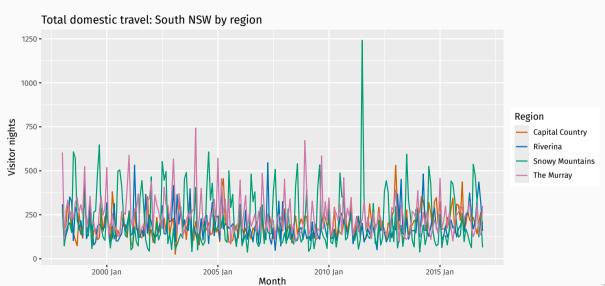
Tasmania Victoria

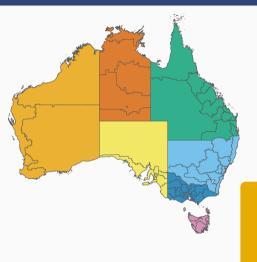
Western Australia











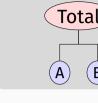
Aggregation level	# series
National	1
State	7
Zone	27
Region	76
Total	111

- Need forecasts at all levels of aggregation.
- Compute base forecasts using univariate models. These will not add up.
- Adjust base forecasts to ensure they are "coherent" giving reconciled forecasts.

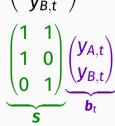
Notation

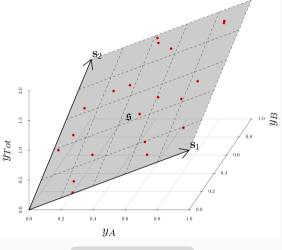
Almost all collections of time series with linear constraints can be written as $\mathbf{y}_t = \mathbf{S}\mathbf{b}_t$

- \mathbf{v}_t = vector of all series at time t
- $y_{Total,t}$ = aggregate of all series at time t.
- $y_{X,t}$ = value of series X at time t.
- \mathbf{b}_t = vector of most disaggregated series at time t
- **S** = "summing matrix" containing the linear constraints.

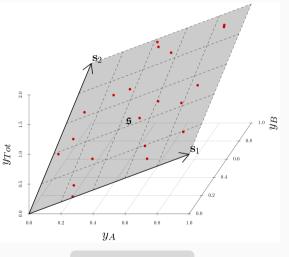








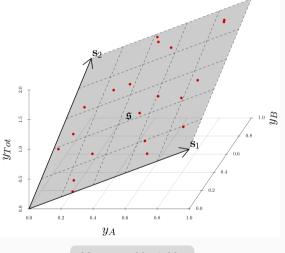
 $y_{\text{Total}} = y_A + y_B$



Base forecasts

Let $\hat{\mathbf{y}}_{t+h|t}$ be vector of *incoherent* initial *h*-step forecasts.

 $y_{\text{Total}} = y_A + y_B$

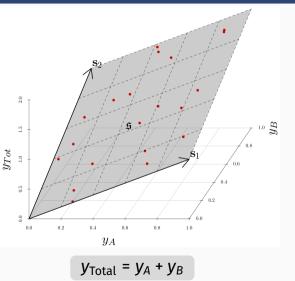


Base forecasts

Let $\hat{\mathbf{y}}_{t+h|t}$ be vector of incoherent initial h-step forecasts.

Reconciled forecasts

Let **M** be a projection matrix. $\tilde{\mathbf{y}}_{t+h|t} = \mathbf{M}\hat{\mathbf{y}}_{t+h|t}$ "reconciles" $\hat{\mathbf{y}}_{t+h|t}$.



Base forecasts

Let $\hat{\mathbf{y}}_{t+h|t}$ be vector of incoherent initial h-step forecasts.

Reconciled forecasts

Let \mathbf{M} be a projection matrix. $\tilde{\mathbf{y}}_{t+h|t} = \mathbf{M}\hat{\mathbf{y}}_{t+h|t}$ "reconciles" $\hat{\mathbf{y}}_{t+h|t}$.

- **S** forms a basis set for \$
- All projections are of the form $\mathbf{M} = \mathbf{S}(\mathbf{S}'\Psi\mathbf{S})^{-1}\mathbf{S}'\Psi$ where Ψ is a positive definite matrix.
- How to choose the best Ψ ?

Minimum trace reconciliation

Wickramasuriya et al (2019)

$$\tilde{\mathbf{y}}_{t+h|t} = \mathbf{M}\hat{\mathbf{y}}_{t+h|t}$$

Reconciled forecasts

Base forecasts

Minimum trace reconciliation

Wickramasuriya et al (2019)

$$\tilde{\mathbf{y}}_{t+h|t} = \mathbf{M}\hat{\mathbf{y}}_{t+h|t}$$

Reconciled forecasts

Base forecasts

Base forecast covariance:

$$\mathbf{W}_h = \text{Var}[\mathbf{y}_{T+h} - \hat{\mathbf{y}}_{t+h|t} \mid \mathbf{y}_1, \dots, \mathbf{y}_T]$$

■ Reconciled forecast covariance:

$$\mathbf{V}_h = \text{Var}[\mathbf{y}_{T+h} - \tilde{\mathbf{y}}_{t+h|t} \mid \mathbf{y}_1, \dots, \mathbf{y}_T]) = \mathbf{MW}_h \mathbf{M}'$$

Minimum trace reconciliation

Wickramasuriya et al (2019)

$$\tilde{\mathbf{y}}_{t+h|t} = \mathbf{M}\hat{\mathbf{y}}_{t+h|t}$$

Reconciled forecasts

Base forecasts

Base forecast covariance:

$$\mathbf{W}_h = \text{Var}[\mathbf{y}_{T+h} - \hat{\mathbf{y}}_{t+h|t} \mid \mathbf{y}_1, \dots, \mathbf{y}_T]$$

Reconciled forecast covariance:

$$\mathbf{V}_h = \text{Var}[\mathbf{y}_{T+h} - \tilde{\mathbf{y}}_{t+h|t} \mid \mathbf{y}_1, \dots, \mathbf{y}_T]) = \mathbf{M} \mathbf{W}_h \mathbf{M}'$$

Minimum trace (MinT) reconciliation

If **M** is a projection, then trace of V_h is minimized when $\Psi = W_h$ $\mathbf{M} = \mathbf{S}(\mathbf{S}'W_h^{-1}\mathbf{S})^{-1}\mathbf{S}'W_h^{-1}$

Linear projections

$$\tilde{\boldsymbol{y}}_{t+h|t} = \boldsymbol{S}(\boldsymbol{S}'\boldsymbol{W}_h^{-1}\boldsymbol{S})^{-1}\boldsymbol{S}'\boldsymbol{W}_h^{-1}\hat{\boldsymbol{y}}_{t+h|t}$$

Reconciliation method	W _h
OLS	1
WLS(var)	diag(W 1)
WLS(struct)	diag(S1)
MinT(sample)	Ŵ sam
MinT(shrink)	$\hat{m{W}}_{\sf shr}$

- All approximate MinT by assuming $\mathbf{W}_h = k_h \mathbf{W}_1$.
- $\hat{\mathbf{W}}_{sam}$ is sample estimate of the residual covariance matrix
- $\hat{\mathbf{W}}_{shr}$ is shrinkage estimator τ diag($\hat{\mathbf{W}}_{sam}$) + $(1 \tau)\hat{\mathbf{W}}_{sam}$ where τ selected optimally.

tourism

```
# A tsibble: 17,328 x 5 [1M]
# Kev:
            state, zone, region [76]
  state zone region month visitors
  <chr> <chr> <chr> <chr> <mth>
                                  <fdb>>
1 NSW
        ACT Canberra 1998 Jan 612.
2 NSW
        ACT Canberra 1998 Feb
                                   471.
3 NSW
        ACT
            Canberra 1998 Mar
                                   430.
4 NSW
        ACT
            Canberra 1998 Apr
                                   499.
5 NSW
        ACT
             Canberra 1998 Mav
                                   338.
6 NSW
        ACT
             Canberra 1998 Jun
                                   236.
7 NSW
        ACT
             Canberra 1998 Jul
                                   371.
8 NSW
        ACT
            Canberra 1998 Aug
                                   375.
9 NSW
        ACT
            Canberra 1998 Sep
                                   449.
10 NSW
        ACT
             Canberra 1998 Oct
                                   517.
# i 17.318 more rows
```

```
tourism_agg <- tourism |>
 aggregate_key(state / zone / region, visitors = sum(visitors))
# A tsibble: 25,308 x 5 [1M]
# Key: state, zone, region [111]
     month state zone
                                   region
                                              visitors
     <dbl>
1 1998 Jan <aggregated> <aggregated> <aggregated>
                                                 45151.
2 1998 Feb <aggregated> <aggregated> <aggregated>
                                                 17295.
3 1998 Mar <aggregated> <aggregated> <aggregated>
                                                 20725.
4 1998 Apr <aggregated> <aggregated> <aggregated>
                                                 25389.
5 1998 May <aggregated> <aggregated> <aggregated>
                                                 20330.
6 1998 Jun <aggregated> <aggregated> <aggregated>
                                                 18238.
7 1998 Jul <aggregated> <aggregated> <aggregated>
                                                 23005.
8 1998 Aug <aggregated> <aggregated> <aggregated>
                                                 23033.
9 1998 Sep <aggregated> <aggregated> <aggregated>
                                                 22483.
10 1998 Oct <aggregated> <aggregated> <aggregated>
                                                 24845.
# i 25,298 more rows
```

fit <- tourism_agg |>

```
filter(vear(month) <= 2015) |>
 model(ets = ETS(visitors))
# A mable: 111 x 4
# Key: state, zone, region [111]
  state
          zone
                          region
                                                   ets
  <chr*> <chr*>
                          <chr*>
                                               <model>
 1 NSW
          ACT
                          Canberra
                                          <ETS(M,N,A)>
2 NSW
          ACT
                          <aggregated>
                                          <ETS(M,N,A)>
 3 NSW
         Metro NSW
                          Central Coast
                                          <ETS(M,N,A)>
 4 NSW
                                          <ETS(M,N,A)>
         Metro NSW
                          Sydney
 5 NSW
                          <aggregated>
                                          <ETS(M,N,A)>
         Metro NSW
 6 NSW
          North Coast NSW Hunter
                                          <ETS(M,N,M)>
 7 NSW
          North Coast NSW North Coast NSW <ETS(M,N,M)>
8 NSW
          North Coast NSW <aggregated>
                                          <ETS(M,N,M)>
 9 NSW
          North NSW
                          Blue Mountains
                                          <ETS(M,N,M)>
10 NSW
          North NSW
                          Central NSW
                                          <ETS(A.N.A)>
# i 101 more rows
```

```
fc <- fit |>
 reconcile(
   ols = min trace(ets, method = "ols"),
   mint_s = min_trace(ets, method = "mint shrink").
 ) |>
 forecast(h = "2 years")
# A fable: 7,992 x 7 [1M]
# Kev: state, zone, region, .model [333]
  state zone region .model
                                 month
  <chr*> <chr*> <chr*> <chr> <mth>
1 NSW
         ACT Canberra ets 2016 Jan
2 NSW
        ACT Canberra ets 2016 Feb
3 NSW
         ACT Canberra ets
                              2016 Mar
4 NSW
         ACT Canberra ets
                              2016 Apr
5 NSW
         ACT
              Canberra ets
                              2016 May
         ACT
              Canberra ets
                              2016 Jun
6 NSW
7 NSW
         ACT
               Canberra ets
                              2016 Jul
8 NSW
         ACT
               Canberra ets
                              2016 Aug
```

2014 lan

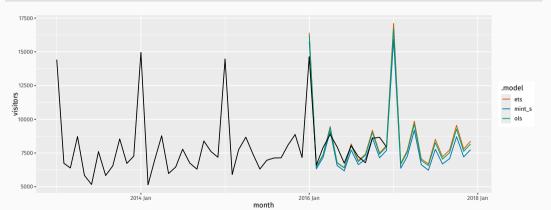
```
fc |>
                                                                   filter(is_aggregated(state)) |>
                                                                   autoplot(filter(tourism_agg, year(month) > 2012), level = NULL)
                                                     40000 -
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              .model
sions is in the second 
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            mint s
                                                     20000 -
```

month

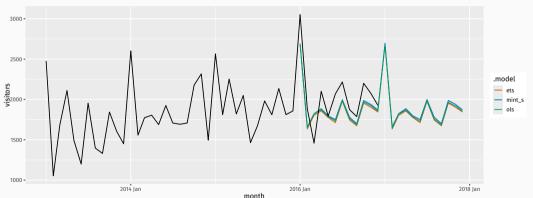
2016 lan

2018 Jan

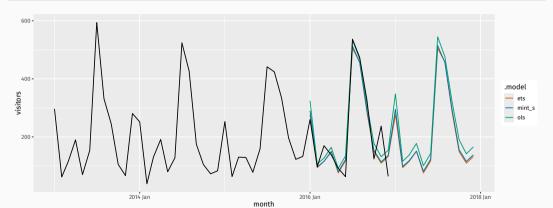
```
fc |>
  filter(state == "NSW" & is_aggregated(zone)) |>
  autoplot(filter(tourism_agg, year(month) > 2012), level = NULL)
```



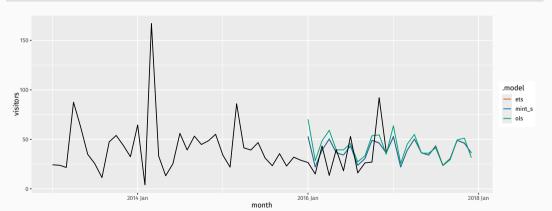
```
fc |>
  filter(region == "Melbourne") |>
  autoplot(filter(tourism_agg, year(month) > 2012), level = NULL)
```



```
fc |>
  filter(region == "Snowy Mountains") |>
  autoplot(filter(tourism_agg, year(month) > 2012), level = NULL)
```



```
fc |>
  filter(region == "Barossa") |>
  autoplot(filter(tourism_agg, year(month) > 2012), level = NULL)
```



Performance evaluation

RMSSE =
$$\sqrt{\text{mean}(q_j^2)}$$

$$q_j^2 = \frac{e_j^2}{\frac{1}{T-m} \sum_{t=m+1}^{T} (y_t - y_{t-m})^2}$$

- y_t = observation for period t
- e_j = forecast error for forecast horizon j
- T = size of training set
- = m = 12

```
accuracy(fc, tourism_agg, measures = list(rmsse = RMSSE))
```

```
# A tibble: 333 x 7
  .model state
                              region
                                          .type rmsse level
                   zone
                                         <chr> <dbl> <fct>
  <chr> <chr*>
                   <chr*>
                              <chr*>
2 mint_s <aggregated> <aggregated> Test 0.896 National
3 ols <aggregated> <aggregated> <aggregated> Test 0.768 National
4 ets
        NSW
                   <aggregated> <aggregated> Test 0.921 State
5 mint_s NSW
                   <aggregated> <aggregated> Test 0.893 State
6 ols
        NSW
                   <aggregated> <aggregated> Test 0.881 State
7 ets
        NT
                   <aggregated> <aggregated> Test 1.24 State
8 mint_s NT
                   <aggregated> <aggregated> Test 1.22 State
9 ols
                   <aggregated> <aggregated> Test 1.18 State
        NT
10 ets
        OLD
                   <aggregated> <aggregated> Test 0.860 State
# i 323 more rows
```

```
accuracy(fc, tourism_agg, measures = list(rmsse = RMSSE)) |>
summarise(rmsse = sqrt(mean(rmsse^2)), .by = .model)
```

 Overall, both reconciliation methods are more accurate than the base ETS forecasts.

9 ets

11 ols

10 mint_s Region

12 ets Region

Zone

Region

0.935

0.839

0.843

0.858

```
accuracy(fc, tourism_agg, measures = list(rmsse = RMSSE)) |>
 summarise(rmsse = sqrt(mean(rmsse^2)), .by = c(.model, level)) |>
# A tibble: 12 x 3
  .model level rmsse
  <chr> <fct> <dbl>
1 ets National 0.755
2 ols National 0.768
3 mint s National 0.896
4 ols State 0.905
5 ets State 0.919
6 mint_s State 0.953
7 ols
        7one
                 0.912
8 mint s Zone
                 0.914
```

```
accuracy(fc, tourism_agg, measures = list(rmsse = RMSSE)) |>
summarise(rmsse = sqrt(mean(rmsse^2)), .by = c(.model, level)) |>
```

```
# A tibble: 12 x 3
  .model level
                rmsse
  <chr> <fct> <dbl>
1 ets National 0.755
2 ols National 0.768
3 mint s National 0.896
4 ols State 0.905
5 ets State 0.919
6 mint_s State 0.953
7 ols
        7one
                0.912
8 mint_s Zone
                0.914
9 ets
        Zone
                0.935
10 mint_s Region
                0.839
11 ols
       Region
                0.843
12 ets Region
                0.858
```

- Reconciliation is best for all levels except national.
- Improvements due to reconciliation are greater at lower levels.

Mean square error bounds

Panagiotelis, Gamakumara, Athanasopoulos, and Hyndman (2021)

Distance reducing property

Let $\|\mathbf{u}\|_{\Psi}$ = $\mathbf{u}'\Psi\mathbf{u}$. Then $\|\mathbf{y}_{t+h} - \tilde{\mathbf{y}}_{t+h|t}\|_{\Psi} \leq \|\mathbf{y}_{t+h} - \hat{\mathbf{y}}_{t+h|t}\|_{\Psi}$

- Ψ -projection is guaranteed to improve forecast accuracy over base forecasts using this distance measure.
- Distance reduction holds for any realisation and any forecast.
- OLS reconciliation minimizes Euclidean distance.

Wickramasuriya (2021)

$$||\mathbf{y}_{t+h} - \tilde{\mathbf{y}}_{t+h|t}||_{2}^{2} = ||\mathbf{M}(\mathbf{y}_{t+h} - \hat{\mathbf{y}}_{t+h|t})||_{2}^{2}$$

$$\leq ||\mathbf{M}||_{2}^{2} ||\mathbf{y}_{t+h} - \hat{\mathbf{y}}_{t+h|t}||_{2}^{2}$$

$$= \sigma_{\max}^{2} ||\mathbf{y}_{t+h} - \hat{\mathbf{y}}_{t+h|t}||_{2}^{2}$$

- lacksquare σ_{\max} is the largest eigenvalue of $m{M}$
- $\sigma_{\max} \geq 1$ as **M** is a projection matrix.
- Every projection reconciliation is better than base forecasts using Euclidean distance.

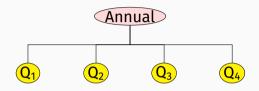
$$\begin{split} &\text{tr} \Big(\mathsf{E}[\boldsymbol{y}_{t+h} - \tilde{\boldsymbol{y}}_{t+h|t}^{\mathsf{MinT}}]'[\boldsymbol{y}_{t+h} - \tilde{\boldsymbol{y}}_{t+h|t}^{\mathsf{MinT}}] \Big) \\ &\leq \text{tr} \Big(\mathsf{E}[\boldsymbol{y}_{t+h} - \tilde{\boldsymbol{y}}_{t+h|t}^{\mathsf{OLS}}]'[\boldsymbol{y}_{t+h} - \tilde{\boldsymbol{y}}_{t+h|t}^{\mathsf{OLS}}] \Big) \\ &\leq \text{tr} \Big(\mathsf{E}[\boldsymbol{y}_{t+h} - \hat{\boldsymbol{y}}_{t+h|t}]'[\boldsymbol{y}_{t+h} - \hat{\boldsymbol{y}}_{t+h|t}] \Big) \end{split}$$

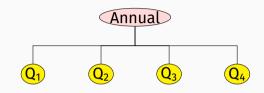
Using sums of variances:

- MinT reconciliation is better than OLS reconciliation
- OLS reconciliation is better than base forecasts

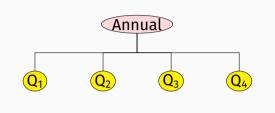
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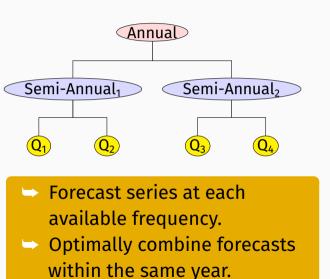
- Forecast series at each available frequency.
- Optimally combine forecasts within the same year.



$$\mathbf{y}_{\tau} = \begin{bmatrix} \mathbf{x}_{\tau} \\ \mathbf{x}_{\tau,1}^{[1]} \\ \mathbf{x}_{\tau,2}^{[1]} \\ \mathbf{x}_{\tau,3}^{[1]} \end{bmatrix}$$

- Forecast series at each available frequency.
- Optimally combine forecasts within the same year.

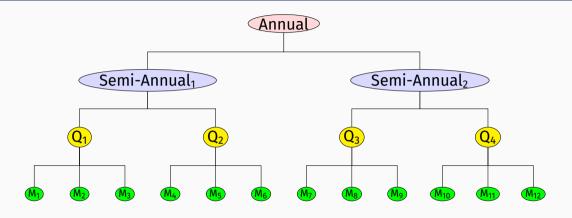
au = index of largest temporal aggregation level.



$$\begin{vmatrix} X_{\tau}^{[4]} \\ X_{\tau,1}^{[2]} \\ X_{\tau,2}^{[2]} \\ = X_{\tau,1}^{[1]} \\ X_{\tau,2}^{[1]} \\ \end{vmatrix}$$

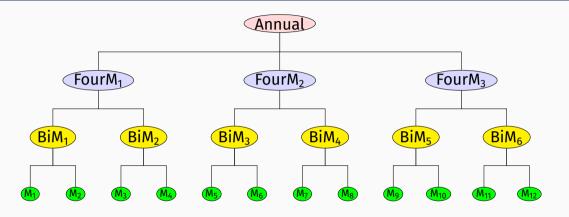
$$\tau$$
 = index of largest temporal aggregation level.

Temporal reconciliation: monthly data



- Forecast series at each available frequency.
- Optimally combine forecasts within the same year.

Temporal reconciliation: monthly data



- Forecast series at each available frequency.
- Optimally combine forecasts within the same year.

Temporal reconciliation: monthly data

Temporal reconciliation

For a time series y_1, \ldots, y_T , observed at frequency m:

$$x_j^{[k]} = \sum_{t=(j-1)k+1}^{jk} y_t$$
 for $j = 1, \dots, \lfloor T/k \rfloor$

- $k \in \mathcal{K} = \{k_1, \dots, k_p\}$ denote the p factors of m in ascending order, where $k_1 = 1$ and $k_p = m$
- $\mathbf{x}_{i}^{[1]} = y_{t}$
- A single unique hierarchy is only possible when there are no coprime pairs in \mathcal{K} .
- \blacksquare $M_k = m/k$ is seasonal period of aggregated series.

Temporal reconciliation

$$\mathbf{x}_{\tau} = \mathbf{S}\mathbf{x}_{\tau}^{[1]}, \qquad \mathbf{S} = \begin{bmatrix} \mathbf{A} \\ \mathbf{I} \end{bmatrix}$$

where

$$\mathbf{X}_{\tau} = \begin{bmatrix} \mathbf{X}_{\tau}^{[k_{p}]} \\ \mathbf{X}_{\tau}^{[k_{p-1}]} \\ \vdots \\ \mathbf{X}_{\tau}^{[k_{1}]} \end{bmatrix} \qquad \mathbf{X}_{\tau}^{[k]} = \begin{bmatrix} \mathbf{X}_{M_{k}(\tau-1)+1}^{[k]} \\ \mathbf{X}_{M_{k}(\tau-1)+2}^{[k]} \\ \vdots \\ \mathbf{X}_{M_{k}\tau}^{[k]} \end{bmatrix} \qquad \mathbf{A} = \begin{bmatrix} \mathbf{1}'_{m} \\ \mathbf{1}'_{m/k_{p-1}} \otimes \mathbf{1}'_{k_{p-1}} \\ \vdots \\ \mathbf{1}_{m/k_{2}} \otimes \mathbf{1}'_{k_{2}} \end{bmatrix}$$

au is time index for most aggregated series,

$$k \in \mathcal{K} = \{k_1, \dots, k_p\}, \quad k_1 = 1, \quad k_p = m, \quad \tau = 1, \dots, T/m.$$

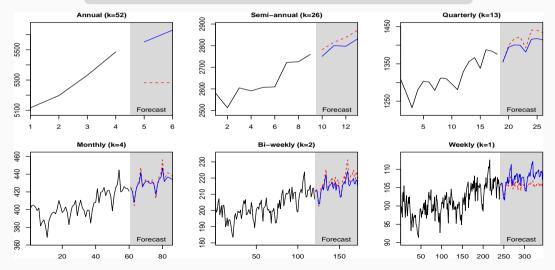
Example: Accident & emergency services demand

Weekly A&E demand data: 7 November 2010 to 7 June 2015.

```
Type 1 Departments — Major A&E
Type 2 Departments — Single Specialty
Type 3 Departments — Other A&E/Minor Injury Unit
Total Attendances
Type 1 Departments — Major A&E > 2 hours
Type 2 Departments — Single Specialty > 2 hours
Type 3 Departments — Other A&E/Minor Injury Unit > 2 hours
Total Attendances > 2 hours
Emergency Admissions via Type 1 A&E
Total Emergency Admissions via A&E
Other Emergency Admissions (i.e not via A&E)
Total Emergency Admissions
Number of patients spending > 2 hours from decision to admit to admission
```

Example: Accident & emergency services demand

Total emergency admissions via A&E



Example: Accident & emergency services demand

Test set: last 52 weeks

MASE comparison (ARIMA models)

Aggregation Level	h	Base	Reconciled	Change
Annual	1	3.4	1.9	-42.9%
Weekly	152	2.0	1.9	-5.0%
Weekly	13	2.3	1.9	-16.2%
Weekly	4	1.9	1.5	-18.6%
Weekly	1	1.6	1.3	-17.2%

Temporal reconciliation: M3 monthly series

- Apply temporal reconciliation to all 1428 monthly series from M3 competition
- Forecast horizon *h* = 18 months
- ETS and ARIMA models
- Measure percentage difference to base forecasts
- Reconciliation methods:
 - WLS_H (diagonal)
 - WLS_V (diagonal with common variances for same frequency)
 - WLS_s (diagonal/structural)

Temporal reconciliation: M3 monthly series

Improvement in MASE relative to base forecasts

			ETS				ARIMA			
Aggregation level	h	BU	WLS_H	WLS _V	WLS _S	BU	WLS_H	WLS_V	WLSs	
Annual	1	-12.1	-17.9	-17.8	-18.5	-25.4	-29.9	-29.9	-30.2	
Semi-annual	3	0.0	-6.3	-6.0	-6.9	-2.9	-8.1	-8.2	-9.4	
Four-monthly	4	3.1	-3.2	-3.0	-3.4	-1.8	-6.2	-6.5	-7.1	
Quarterly	6	3.2	-2.8	-2.7	-3.4	-2.6	-6.9	-7.4	-8.1	
Bi-monthly	9	2.7	-2.9	-3.0	-3.7	-1.3	-5.0	-5.5	-6.3	
Monthly	18	0.0	-3.7	-4.6	-5.0	0.0	-1.9	-3.2	-3.7	
Average	NA	-0.5	-6.1	-6.2	-6.8	-5.7	-9.7	-10.1	-10.8	

Outline

- 1 Improving hierarchical forecasts
- 2 Improving univariate forecasts
- 3 Improving multivariate forecasts
- 4 Final comments

Forecast Linear Augmented Projection (FLAP)

- We want to forecast multivariate series y_t .
- Linear combinations of \mathbf{y}_t may have better signal-noise ratio
- Construct many linear combinations $\mathbf{c}_t = \Phi \mathbf{y}_t$ (e.g., principal components or random combinations)
- Produce univariate forecasts of all series $\hat{\mathbf{y}}_{t+h|t}$ and all linear combinations $\hat{\mathbf{c}}_{t+h|t}$.
- Reconcile forecasts so they are coherent $(\tilde{c}_{t+h|t} = \Phi \tilde{y}_{t+h|t})$

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$$\mathbf{z}_t = \begin{vmatrix} \mathbf{y}_t \\ \mathbf{c}_t \end{vmatrix}$$
 $\tilde{\mathbf{z}}_{t+h} = \mathbf{M}\hat{\mathbf{z}}_{t+h|t}$

Forecast error variance reduction

If we know the covariance matrix $\mathbf{W}_h = \text{Var}(\mathbf{z}_{t+h} - \hat{\mathbf{z}}_{t+h|t})$, then

- The forecast error variance is reduced:
 - ▶ $Var(\mathbf{y}_{t+h} \hat{\mathbf{y}}_{t+h|t}) Var(\mathbf{y}_{t+h} \tilde{\mathbf{y}}_{t+h|t})$ is positive semi-definite.
- The forecast error variance of each series monotonically decreases with increasing number of components.

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In practice, we need to:

- **E**stimate \mathbf{W}_h (use the MinT shrinkage estimator).
- \blacksquare Construct the components, Φ .

Construction of Φ

Principal component analysis (PCA)

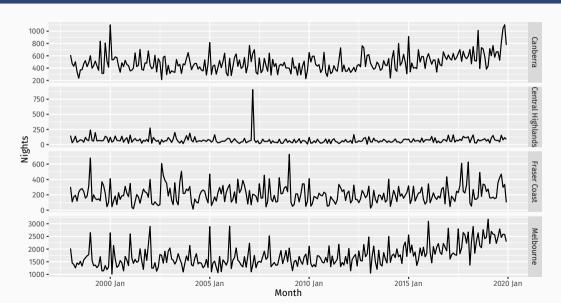
Finding the weights matrix Φ so that the resulting components maximise variance

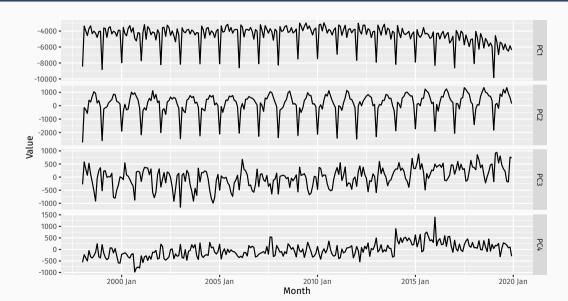
Simulation

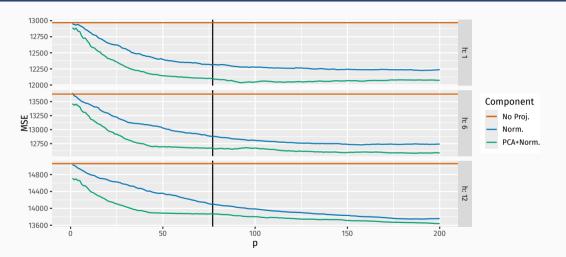
Generating values of Φ from a random distribution and normalising them to unit vectors

- Normal distribution
- Uniform distribution
- Orthonormal matrix

- Monthly Australian tourism data set aggregated by region giving 77 series, from Jan 1998 to Dec 2019.
- Use expanding window time series cross-validation with T = 84 observations in first training set, and forecast horizons h = 1, 2, ..., 12.



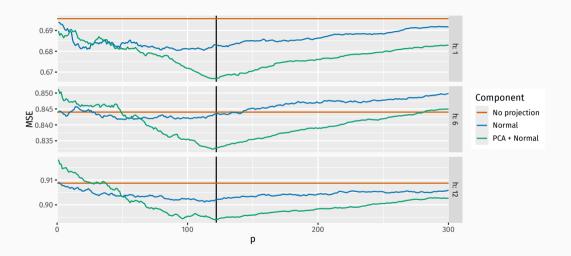




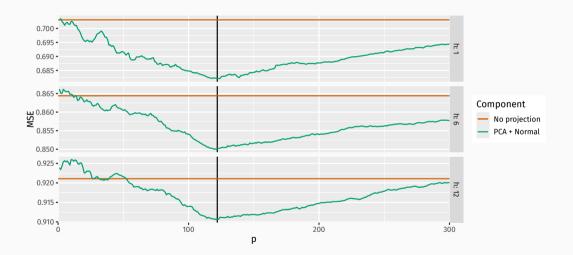
FRED-MD

- Monthly data of macroeconomic variables (McCracken and Ng, 2016).
- Data from Jan 1959 Sep 2023. 777 observations on 122 series.
- Same cleaning process as per McCracken and Ng (2016).
- All series scaled to have mean 0 and variance 1.
- Expanding time series cross-validation with initial size of 25 years and forecast horizon 12 months.

FRED-MD (ARIMA)



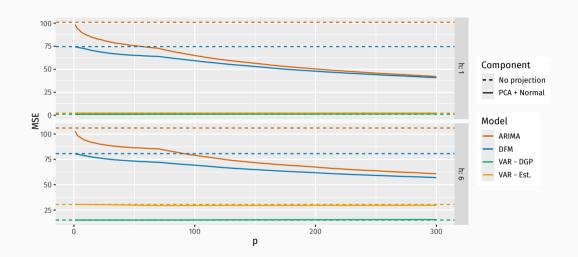
FRED-MD (DFM)



Simulation

- Data generating process: VAR(3) with 70 variables
- Sample size: *T* = 400
- Number of repeated samples: 220
- Base models:
 - automatic ARIMA (based on AICc)
 - DFM (structure chosen using BIC, different model for each horizon)

Simulation



Future research directions

- Investigate why PCA performs better than random weights
- Find other components that are better than PCA
- \blacksquare Find optimal components by minimising forecast error variance with respect to Φ
- Use forecast projection and forecast reconciliation together

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Software

Package	Language	Cross- sectional	Temporal	Cross- temporal	Probabilistic	Multivariate
hts	R	✓				
thief	R		\checkmark			
fable	R	\checkmark			✓	
FoReco	R	\checkmark	\checkmark	\checkmark	✓	
flap	R					✓
pyhts	Python	\checkmark	\checkmark			
hierarchicalforecast	Python	✓			\checkmark	

- hts, thief, and FoReco use ts objects
- fable uses tsibble objects
- flap uses matrices of base forecasts
- fable has plans to implement temporal and cross-temporal reconciliation



Thanks!



More information

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