The heuristic I chose to implement calculates cost by determining the number of tiles out of their respective goal row and/or column. I rationalized this choice by analyzing the way the successor function was set up. We can use the information that successors are Cardinal-direction shifted in conjunction with the lumped (returned value) cost in order to infer relationships about tile position.

For example, if we know that the heuristic cost is a small multiple of 5 or 3, we can see that our matrix could only contain a specific number of incorrect row/column arrangements. This could allow for expansion on our A* algorithm to skip expanding nodes and instead jump to possible, more efficient solutions. In this way, it provides some interesting benefits.

This heuristic is admissible, and would most likely work best for small matricies/state sizes.