ROS 2
Sensor sampling and image processing

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Recap

ROS 2 offers a common framework for the development of **robotics software**, providing services for:

- **organizing** and **building** a **distributed** software architecture;

- establishing mostly self-configured **inter-process communication** among modules;

- modules **configuration** and **management**.

The last two lectures will show **real applications** of these tools.

New code examples are available.

This lecture is [here](#).

Roadmap

1 Sensor sampling

2 Image processing

3 Software tools of the trade

4 Composition

Roadmap

1. **Sensor sampling**

2. Image processing

3. Software tools of the trade

4. Composition

Roadmap

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