

Robot Operating System 2

Lecture 3: Node Configuration

Roberto Masocco

`roberto.masocco@uniroma2.it`

University of Rome "Tor Vergata"

Department of Civil Engineering and Computer Science Engineering

Intelligent Systems Lab

May 4, 2022



TOR VERGATA
UNIVERSITY OF ROME

School of Engineering

Roadmap

1 Node Parameters

2 Launch Files

Roadmap

1 Node Parameters

2 Launch Files

Roadmap

1 Node Parameters

2 Launch Files