Your submission was sent successfully! Close

Thank you for contacting us. A member of our team will be in touch shortly. <u>Close</u>

You have successfully unsubscribed! Close

Thank you for signing up for our newsletter!

In these regular emails you will find the latest updates about Ubuntu and upcoming events where you can meet our team. Close

Your preferences have been successfully updated. <u>Close</u>

2/9/25, 05:34 1 of 7

Please note that this blog post has old information that may no longer be correct. We invite you to read the content as a starting point but please search for more updated information in the ROS documentation https://docs.ros.org/p



A well configured linter can catch common errors before code is even run or compiled. ROS 2 makes it easy to add linters of your choice and make them part of your package's testing pipeline.

We'll step through the process, from start to finish, of adding a linter to ament so it can be used to automatically test your projects. We'll try to keep it generic, but where we need to lean on an example we'll be referring to the linter we recently added https://ubuntu.com/bilog/ linting-ros-2-packages-with-mypyp for mypy, a static type analyzer for Python. You can view the finished source code for ment may chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_and ment_canke_mypy_chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_and ment_canke_mypy_chites://githbl.com/ment/ment_list/tree/mater/ment_mypy_and ment_canke_mypy_and ment_can

Design

We'll need to make sure our linter integrates into ament's testing pipeline. Namely, this means writing CMake scripts to integrate with ament_cmake_test and ament_lint_auto.

We need to be able to generate a JUNIX XML chttps://www.ibm.com/support/knowledgecenter/en/SSUFAU_1.0.0/com.ibm.rsaranalysis.codereview.cobol.doc/topics/cac_useresults_junit.html> report for the Jenkins build farm to parse, as well as handle automatically excluding directories with went Toxose files, so we'll need to write a wrapper script for our linter as well.

Overall, we'll need to write the following packages:

```
    ** assett_Lister!
    ** Collect files, ignore those in AMENT_LIGATION directories
    ** Configure and call lister
    ** Generate XML report
    ** asset_Lister!
    ** Set of CMANe scripts
    ** asset_Lister.
    ** asset_Lister.
    ** Lister.caske
    ** Function to invoke lister wrapper
    ** asset_Caske_Lister.
    ** Set of CMANE asset_Lister.
    ** Engistered at build as the CONFIG_EXTRA argument to asset _nackage.
    ** Set of Lister.caske.
    ** Set of Lister.caske.case.case_List_auto
    ** Registered at build as the CONFIG_EXTRA argument to asset_nackage.
```

Getting Started – Python

We'll start with making the ament_[linter] package.

We'll be using Python to write this package, so we'll add a setup. py file, and fill out some required fields. It's easiest to just take one from an existing linter and customize it. What it ends up containing will be specific to the linter you're adding, but for mypy it looks like this:

```
rion setupions amplit setup

sames'ament_mypy',

versions''0.7.3',

packages=find_packages(enclude=['test']),

package_stard(': a| enc.,

configuration/mark_mypy.ini',

linstall_require=['setuprols'],

rip_safe=false,

authon''end Kern',

author 'end Kern',

author 'end Kern',

author'end Kern',

author'end Kern',

surd-white;//github.com/ament/ament_lint',

domload_urther_theys//github.com/ament/ament_lint/releases',

keyonofs=['MoS'],

classifizes=[

'Intended Andisence:: Developers',

'License:: 505 Approved:: Apache Software License',

'License:: Software Development',

],

description='\text{\text{Normal}}

The ability to check code for user specified static typing with mypy.''',

ticense:: Apache License, Version 2.6',

ment_mypy = ament_mypy.main:main',

],

'ament_mypy = ament_mypy.main:main',

],
```

We'll of course need a package.mat file. We'll need to make sure it has an exec_depends on the linter's package name in ROSDistro https://github.com/ros/rosdistro/blob/master/CONTRIBUTING.md. This is required in order to actually install the linter itself as a dependency of our new ament linter package; without it any tests using it in CI would fail. Here's what it looks like for mypy:

The Code

Create a python file called ament_[linter]/main.py, which will house all the logic for this linter. Below is the sample skeleton of a linter, again attempting to be generic where possible but nonetheless based on ament_mypy.

```
# Import your linter here
import mypy.api # type: ignore
               parser.add_argument(
'paths',
                'paths',
nangga="*',
defaulte[os.curdir],
help='The files or directories to check. For directories files ending
'in '.py' will be considered.'
               )
parser.add_argument(
    '--exclude',
    metavar='filename',
    nargs='*',
    dest='excludes',
    help='The filenames to exclude.'
             )
parser.add_argument(
'--xunit-file',
help='Generate a xunit compliant XML file'
)
             # Example of a config file specification option
parser and argument(
'--config',
netavars'path',
dest'-config',
file', ostroide file',
default-os, path, jointo, path dirame(_file_), 'configuration', 'ament_mypy.ini'),
help-"the config file'
            # Example linter specific option
purser.add sympment(
--tached sympment)
--tached sympment
--tached sympment
default-uso.denvail.
default-uso.denvail.
dest-'cache (sympil).
help-'The location mypy will place its cache in. Defaults to system '
'mult dest-'cache (sympil).
             if args.xunit_file:
    start_time = time.time()
                       args.config_file and not os.path.exists(args.config_file):
print("Could not find config file "{}"."format(args.config_file), file=sys.stderr)
return 1
             filenames = _get_files(args.paths)
if args.excludes:
    filenames = [f for f in filenames
    if os.path.basename(f) not in args.excludes]
               if os.path.basename(f) not in
if not filenames:
    print('No files found', file=sys.stderr)
    return 1
                normal_report, error_messages, exit_code = _generate_linter_report(
filenames,
          if error messages:

print('myp' error encountered', file-sys.stderr)

print(error messages, file-sys.stderr)

print('nora' messages, file-sys.stderr)

print('noral_report, file-sys.stderr)

return exit_code
             errors_parsed = _get_errors(normal_report)
            print('\n{} files checked'.format(len(filenames)))
if not normal_report:
    print('No errors found')
else:
                        se:
print('{} errors'.format(len(errors_parsed)))
             print('\nChecked files:')
print(''.join(['\n* {}'.format(f) for f in filenames]))
          \label{eq:local_state} $$xal = get_{xunit_content(errors_parsed, testame, filenames, time,time() \cdot start_time)$$ path = os_path.dirrame(os_path.depath(args_xunit_file))$$ if not os_path.ois_tot(path); $$ with open (args_xunit_file, 'w') as f: f.write(on); $$ f.write(on)$$ if the path of the 
 > ***).format(
    test_name=testname,
    test_count-max(len(errors), 1),
    error_count-len(errors),
    time='(:.3f)'.format(round(elapsed, 3))
             reror in errors:

if error_group('lineno'):

pos == ': + str(error_group('lineno'))

pos == ': + str(error_group('clnen'))

pos == ': * str(error_group('clne'))

electricse

name=(quoted_name)

classname='(test_name)*

felium ensame=(duoted_name)
                                                else: there are no mypy problems report a single successful test and re-dedemt_to(""\
<tests of the successful test contains and re-dedemt_to(""\
<tests of the successful test and re-dedemt_to(""\
name="mypy"
```

```
# select files by extension
for filename in sorted(filenames):
    if filename in sorted(filenames):
    if filename.endowif(; ey):
    elif os.path.gin(dirpath, filename))
    files.append(path)
return [de, path.morpathif] for f in files]
 def_get_errors(report_string: str) -> List[Match]:
return list(re_finditer(r'^{Refilenames([a-za-Zi:])?[('?:]+):(('Relineno>\d+):)?(('Recolno>\d+):)?\ ('Retype=error|warming|note):\ ('Remsp=.*)$', report_string, re_MULTILINE) # noga: E501
 def _dedent_to(text: str, prefix: str) -> str:
    return textwrap.indent(textwrap.dedent(text), prefix)
 if __name__ == 'main':
    sys.exit(main(sys.argv[1:]))
We'll break this down into chunks
We write the file as an executable and use the argparse library to parse the invocation, so we begin the file with the shebang:
 and end it with the main logic:
if __name__ == 'main':
    sys.exit(main(sys.argv[1:]))
 to forward failure codes out of the script.
 The main() function will host the bulk of the program's logic. Define it, and make sure the entry_points argument in setup.py points to it.
 Notice the use of type hints <a href="https://www.python.org/dev/peps/pep-0484/">https://www.python.org/dev/peps/pep-0484/</a>, mypy will perform static type checking where possible and where these hints are designated
Parsing the Arguments
 We add the arguments to argparse that ament expects:
 parser.add_argument(
'paths'.
         'paths',
margs='*',
defaultelos.curdir],
help='The files or directories to check. For directories files ending
'in '.py' will be considered.'
)
parser.add_argument(
'--exclude',
metavar='filename',
nargs='*',
dest-'excludes',
help='The filenames to exclude.
 We also include any custom arguments, or args specific to the linter. For example, for mypy we also allow the user to pass in a custom config file to the linter, with a pre-configured default already set up:
# Example of a config file specification option
parser and argument(
'--config',
netsvar='path',
dest'-config', file',
default-os, path jointos, path.dirname(_file_), 'configuration', 'ament_mypy.ini'),
help-'the config file'
# Example linter specific option
parser.add argument(
...cache.dir.,
metworn-Cache.
dest'-cache.dir.,
dest'-cache.dir.,
help-"The location mpy will place its cache in. Defaults to system
"mull desize"
 Note: remember to include any packaged non-code files (like default configs) using a manifest or package_data= in setup.py.
Finally, parse and validate the args:
 args = parser.parse_args(argv)
if args.xunit_file:
    start_time = time.time()
 if args.config_file and not os.path.exists(args.config_file):

    print("Could not find config file "()'".format(args.config_file), file=sys.stderr)

    return 1
if os.path.basename(f) no
if not filenames:
    print('No files found', file=sys.stderr)
    return 1
 Aside: _get_files
 You'll notice the call to the helper function _set_files, shown below. We use as def _set_files(ashs. List[str]) > List[str]: file = fi
          # select files by extension
for filename in sorted(filenames);
if filename.embat(fi.pr):
files.ampend(oc.path.join(dirpath, filename))
files.ampend(path)
return [os.path.ampend(path)
return [os.path.ampend(file)]
 Note that in the near future this and _get_xunit_content will hopefully be de-duplicated into the ament_lint package.
 This function, when given a list of paths, expands out all files recursively and returns those .py files that don't belong in directories containing an AMENT_IGNORE file
 We exclude those files that are in the exclude argument list, and we return a failure from main if no files are left afterwards.
```

```
filenames = _get_files(args.paths)
  if args.excludes:
    filenames = [f for f in filenames
        if os.path.basename(f) not in args.excludes]
   if not filenames:
    print('No files found', file=sys.stderr)
    return 1
    Otherwise we pass those files, as well as relevant configuration arguments, to the linter.  \\
    Invoking the Linter
    We call the linter using whatever API it exposes:
   .g....ever AMTIC EXPOSES:
normal_report, error_messages, exit_code = _generate_linter_report(
filenames,
args.comfig.file,
args.cache_dir |
    abstracted here with the following method signature:
   Recording the Output
    Any failures the linter outputs are printed to stdout, while any internal linter errors go to stderr and return the (non-zero) exit code:
  if error_messages:
    print('linter error encountered', file-sys.
    print(error_messages, file-sys.stderr)
    print('\nRegular report continues:')
    print(normal_report, file-sys.stderr)
    return exit_code
    We collect each warning/error/note message emitted individually:
    We then report the errors to the user with something like:
  print('\n{} files checked'.format(len(filenames)))
if not normal_report:
    print('No errors found')
else:
    print('\{) errors'.format(len(errors_parsed)))
    print(normal_report)
    print('\nChecked files:')
print('\.join(['\n* {}'.format(f) for f in filenames]))
   Generating JUnit XML Output
    Here we generate an xml report write the file to disk in the requested location.
   Here we generate an xmn report write the mice to disk in the requested lot if args. xmsit_file or, path, basename(so, path, direase(args. xmnit_file)) file_name = os, path, basename(args. xmnit_file) suffix = ".mni' if file_name = ofise that suffix); file_name = file_name(:\lens\u00e4file); the file_name = file_name(:\lens\u00e4file); the file_name = file_name(:\lens\u00e4file); file_name = file_name(:\lens\u00e4file); testname = "(), ()".format(folder_name, file_name)
                     xxl = _get_wmit_content(errors_parsed, testame, filenames, time.time() - start_time)
path = ss_rath_dirmame(ss_path_abspath(ergs_wmit_file))
if not ss_path_sust(sighth);
with open(args_wmit_file, 'w') as f:
f_write(mi)
    An example of a valid output XML to the schema shttps://www.ibm.com/support/knowledgecenter/en/SSUFAU_1.0.0/com.ibm.rsaranalysis.codereview.cobol.dos/topics/cas_useresults_junit.html> is shown below
        <testcase
name="error (/tmp/pytest-of-ubuntu/pytest-164/use_me7/lc.py:8:0)*
classname="tst"</pre>
       </
      ...prust-of-ubuntu/pytest-16

* dailure message="warning message"/>

*/testuse>

* system out-Decked files:

* / tmap/pytest-of-ubuntu/pytest-164/use_me7/c.py

* / tmap/pytest-of-ubuntu/pytest-164/use_me7/c.py

* / tmap/pytest-of-ubuntu/pytest-164/use_me7/s.ps.py

* / tmap/pytest-of-ubuntu/pytest-164/use_me7/sen.ps.py

* / tmap/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pytest-of-ubuntu/pyt
    Aside: _get_xunit_content
```

We write a helper function_get_xunit_content, to format the XML output to the schema https://www.ibm.com/support/knowledgecenter/en/SSUFAU_1.0.0/com.ibm.rsar.analysis.codereview.cobol.dos/topics/kac_useresults_junit.html. This one is a bit specific to mypy, but hopefully it gives you a good idea of what's needed:

find_package(ament_cmake_test QUIET REQUIRED)
include('\${ament_cmake_mypy_DIR}/ament_mypy.cmake')
ament_register_extension('ament_lint_auto' 'ament_cmake_mypy'
'ament_cmake_mypy lint_book.cmake')

```
t(
  test_name=testname,
  test_count=max(len(errors), 1),
  error_count=len(errors),
  time="{:.3f}".format(round(elapsed, 3))
       if errors:

# report each mpyp error/warming as a failing testcase
for error in errors:

pos = "" strierror group('lineno');

pos == ":" strierror group('lineno');

if error group('calno');

xal == _dedent [strierror group('calno'))

xal == _dedent [strierror group('calno'))

**centracie

classame="(geoted_mame)"

- failure message=(goted_message)/>
                                      Return from main
 Finally, we return the exit code.
 The CMake Plugin
  Now that our linting tool is ready, we need to write an interface for it to attach to ament.
  Getting Started
  We create a new ros 2 package named ament chake [linter] in the ament lint folder, and fill out package.xml. As an example, the one for mypy looks like this:
We create a new Tos 2 package named ament cases [Linter] in the ment_lint rotoe, and rim out package, xmi. As an example challenge in the model here's http://www.wlb.org/2001/XMLSchema*>-qackage fromtal.sed*
- schematypens="http://www.wlb.org/2001/XMLSchema*>-qackage fromtal.sed*
- schematypens="http://www.wlb.org/anders-
- schematyp
      <buildtool_depend>ament_cmake_core</buildtool_depend>
<buildtool_depend>ament_cmake_test</buildtool_depend>
       <buildtool_export_depend>ament_cmake_test</buildtool_export_depend>ament_mypy</buildtool_export_depend>
       <test_depend>ament_cmake_copyright</test_depend>
<test_depend>ament_cmake_lint_cmake</test_depend>
  CMake Configuration
  We write the installation and testing instructions in (MakeLists.txt, as well as pass our extras file to ament_package. This is the one for mypy, yours should look pretty similar:
  cmake minimum required(VERSTON 3.5)
  project(ament_cmake_mypy NONE)
  find_package(ament_cmake_core REQUIRED)
find_package(ament_cmake_test REQUIRED)
   ament_package(
CONFIG_EXTRAS "ament_cmake_mypy-extras.cmake"
  find_package(ament_cmake_lint_cmake REQUIRED)
ament_lint_cmake()
endif()
 Then we register our extension with ament in ament_cmake_[linter]-extras.cmake. Again, this one is for mypy, but you should be able to easily repurpose it.
```

We then create a CMake function in cmake/ment_[Linter]. cnake to invoke our test when needed. This will be specific to your linter and the wrapper you wrote above, but here's how it looks for mypy:

```
#
# Add a test to statically check Python types using mypy.
 # sparam CONFIG_FILE: the name of the config file to use, if any # stype CONFIG_FILE: string # sparam ISTSIMME: the name of the test, default: "mypy" # stype TESTNAME: string # sparam AVGML: the files or directories to check # stype AVGML: that of stringps

* stype AVGML: that of stringps

* stype AVGML: that of stringps
          @public
     #

unution(ament_mypy)

cmake_parse_arguments(ARG "" "CONFIG_FILE:TESTNAME" "" ${ARGN})

if(MOT ARG_TESTNAME" "mypy")

endif()

endif()
        find_program(ament_mypy_BIN NAMES "ament_mypy")
if(NOT ament_mypy_BIN)
message(FATAL_ERROR "ament_mypy() could not find program 'ament_mypy'")
       set(result_file "$(AMENT_TEST_MESKITS_DIR)/$(PMDJECT_MAME)/$(ARG_TESTMAME).xunit.xml')
set(cod "$(ament_myp_zBip)" ~.vunit.file "$(result_file)")
List(APPBD cod ".config-file" $(AME_CMVBIG_FILE)")
endif()
set(file od $(ARG_UMPASSED_ARGUMENTS))
        file(MAME_DIRECTORY "$COMME_BINNAY_DIR//ament_mypy")
ament_add_test(
"$CAME_TESTANMED")
(COMMAD_SICHE)
(COMMAD_
 Finally, in ament_cmake_[linter]_lint_hook.cmake, we write the hook into the function we just defined. This one is for mypy but yours should look almost identical:
file(G.OD_SCONGS_python_files FOLLOW_SPMLDMC **.py*)
if(_python_files)
essage(TATUS **dede test 'mypy' to statically type check Python code.*)
esset(SYMLDMC **.py*)
 Final Steps
 With both packages ready, we build our new packages using colcon:
 -/ros2/src $ colcon build --packages-select ament_mypy ament_cmake_mypy --event-handlers console_direct+ --symlink-install
```

If all goes well, we can now use this linter just like any other to test our Python packages!

It's highly recommended you write a test suite to go along with your code. ament. mypy lints itself with flake8 and mypy, and has an extensive pytest https://docs.pytest.org/en/latest/contents.html based suite of functions to validate its behavior. You can see this suite here https://docs.pytest.org/en/latest/contents.html based suite of functions to validate its behavior. You can see this suite here https://docs.pytest.org/en/latest/contents.html based suite of functions to validate its behavior. You can see this suite here https://docs.pytest.org/en/latest/contents.html based suite of functions to validate its behavior. You can see this suite here https://docs.pytest.org/en/latest/contents.html based suite of functions to validate its behavior. You can see this suite here https://docs.pytest.org/en/latest/contents.html based suite of functions to validate its behavior. You can see this suite here https://docs.pytest.org/en/latest/contents.html based suite of functions to validate its behavior. You can see this suite here https://docs.pytest.org/en/latest/contents.html based suite of functions to validate its behavior. You can see this suite here https://docs.pytest.org/en/latest/contents.html based suite of functions to validate its behavior. You can see this suite here https://docs.pytest.org/en/latest/contents.html based suite based suite s

Check out our o<u>ther article chttps://ubuntu.com/blog/linting-ros-2-packages-with-mypy-o</u>n how to use the mypy linter if you'd like to learn more about how to invoke linters from your testing suite for other packages.

From home control to drones, robots and industrial systems, Ubuntu Core and Snaps provide robust security, app stores and reliable updates for all your IoT devices.

Get the latest Ubuntu news and updates in your inbox

Work email: ☐ ☐ *I agree to receive information about Canonical's products and services.

By submitting this form, I confirm that I have read and agree to Canonical's Privacy Policy https://www.ubuntu.com/legal/dataprivacy

Are you building a robot on top of Ubuntu and looking for a partner? Talk to us!

Related posts

Optimise your ROS snap - Part 2

Welcome to Part 2 of the "optimise your ROS snap" blog series. Make sure to check Part 1 before reading this blog post. This second part is going to present...

Optimise your ROS snap - Part 1

Do you want to optimise the performance of your ROS snap? We reduced the size of the installed Gazebo snap by 95%! This is how you can do it for your snap.

ROS orchestration with snaps

Application orchestration is the process of integrating applications together to automate and synchronise processes. In robotics, this is essential,...

2/9/25, 05:34 7 of 7