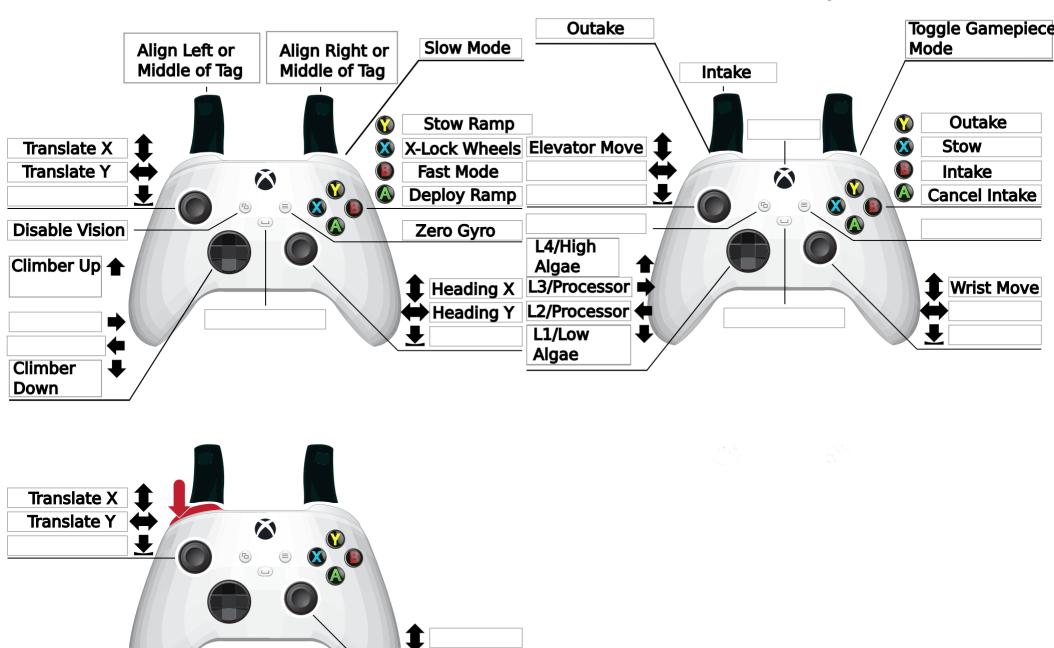
## **Driver Controls**

## **Operator Controls**



Angular Velocity