



Overview

Denavit-Hartenberg Parameters

LINK	d (mm)	θ (°)	a (mm)	α (°)		
LINK 1	180	θ1	150	0		
LINK 2	0	θ2	100	0		
LINK 3	d3	θ3	0	180		



DO NOT SCALE DRAWING

BREAK ALL SHARP EDGES AND REMOVE BURRS FIRST ANGLE PROJECTION

Example

Position

ROS2 Workshop

DTU Roboclub

TITLE

Simple SCARA robot model

	Å4	DTURC-SP-24-SCARA			
SCALE 1.3		3	WEIGHT	SHEET 1 of 1	