



# RoboCup@Home Education Rules 2024

Version: 2024.03.17

RoboCup@Home Education Committee

## **ABOUT**

This is the set of official rules of the RoboCup@Home Education Competition 2024. It is produced and maintained by the RoboCup@Home Education Committee.. It is published at the RoboCup@Home Education website [https://www.robocupathomeedu.org/rules].

Any opinion or inquiry, please refer to oc@robocupathomeedu.org.

## **ACKNOWLEDGEMENTS**

We would like to thank the members of the committee for producing and maintaining this document. We would also like to express our gratitude to everyone whom we are not able to list down here, but has given us valuable opinions and suggestions to improve the content of this document.

- Amy Eguchi | University of California, San Diego, USA
- Jeffrey Too Chuan Tan | MyEdu AI Robotics Research Centre, Malaysia
- Kanjanapan Sukvichai | Kasetsart University, Thailand
- Yoshinobu Hagiwara | Ritsumeikan University, Japan
- Jean-François Laplume | RoboCupJunior France, France
- Kareem Youssri | Arab Academy for Science and Technology, Egypt
- Kosei Demura | Kanazawa Institute of Technology, Japan

Execs and Trustees Supporting @Home Education Competition

- Justin Hart | University of Texas at Austin, USA (Exec)
- Alexander Moriarty | Fetch Robotics, USA (Exec)
- Hiroyuki Okada | Tokyo Information Design Professional University, Japan (Trustee)
- Luca Iocchi | Sapienza University of Rome, Italy (Trustee)
- Raymond Sheh | Georgetown University, USA (Trustee)

# **CONTENTS**

ABOUT	2
ACKNOWLEDGEMENTS	2
CONTENTS	3
1. INTRODUCTION	4
1.1 RoboCup@Home Education	4
1.2 RoboCup@Home Education competition	4
1.2.1 Hands-on Workshops	4
1.2.2 Educational Competition	4
1.3 Robot Platforms	5
1.4 Participation Categories	5
1.5 Eligibility and Qualification	6
1.6 Awards	6
2. COMPETITION RULES	7
2.1 Fundamental Concept and General Rules	7
2.1.1 Task Selections	7
2.1.2 Manipulation Task Adjustment	7
2.2 Team Poster and Presentation	8
2.3 Educational Assessment Approach	8
2.3.1 Incremental Scoring	8
2.3.2 The "Skip Rule"	8
2.3.3 The "Simplify Rule"	8
2.4 Competition Tasks	9
2.4.1 Task 1: Carry My Luggage	9
Score sheet	9
2.4.2 Task 2: Find My Mates	10
Score sheet	10
2.4.3 Task 3: Receptionist	11
Score sheet	11
2.5 Finals: Presentation and Demonstration	12
2.5.1 Task	12
REFERENCES	13

## 1. INTRODUCTION

## 1.1 RoboCup@Home Education

**RoboCup@Home Education** is an educational initiative in RoboCup@Home that promotes educational efforts to boost RoboCup@Home participation and artificial intelligence (AI)-focused service robot development [1].

This initiative currently has four efforts to promote RoboCup@Home competition:

- 1. **Organizing RoboCup@Home Education Competitions** (local, national, SuperRegional, international)
- 2. Providing Open Source Educational Robot Platforms for RoboCup@Home (service robotics)
- 3. Providing OpenCourseWare for the learning of AI-focused service/partner robot development
- 4. Organize Outreach Workshops

## 1.2 RoboCup@Home Education Competition

The **RoboCup@Home Education Competition** is a competition focusing on education to cultivate beginner teams for RoboCup@Home competitions. The unique **Workshop+Competition** format for beginner teams effectively boosts novice participants for challenging service/partner robot development and AI learning within a short period of time. @Home Education is hosted internationally and locally, by the community, and for the community.

The purpose of the @Home Education Competition is to open participation in @Home competition for **everyone**, especially novice and non-expert participants. Our communities around the world are hosting @Home Education competitions at various levels, from **regional/local events** within regions, to **SuperRegional events** covering Asia-Pacific, Europe and the Americas, and the **international competition** hosted in the annual international RoboCup events.

## 1.2.1 Hands-on Workshops

@Home Education committee provides hands-on workshops to guide participants to develop a robot for a competition. **Prior experience in robot development is not required**. However, some basic programming skills are needed.

Our workshops are in two forms - online or in-person. The online workshop materials can be found on @Home Education website: <a href="https://www.robocupathomeedu.org/learn/online-classroom">https://www.robocupathomeedu.org/learn/online-classroom</a>

The in-person workshops are organized with the local organizer's request, usually. Before the international competition, @Home Education can provide an opportunity for local teams by organizing a workshop in collaboration with the LOC to promote @Home locally. In addition, to facilitate inexperienced participants to join the event, basic robot building materials or the SPL robots could be shared with qualified beginner teams to work for the robot development in preparation for a competition.

#### 1.2.2 Educational Competition

@Home Education adapts RoboCup@Home's official rulebook in order to maintain the standard of the development. However, @Home Education only uses selected tasks that are more relevant for novice teams, In addition, it adjusts the assessment scheme for the educational purposes of @Home Education Competition.

#### 1.3 Robot Platforms

There are 2 types of robot platforms in the Education competition: **Open Platform (OP)** and **Standard Platform (SP)**.

Teams in Open Platform use **custom built robots** for the competitions. The competition's development focus is on both **hardware** and **software** designs. Examples of the custom built robots in @Home Education competition can be seen in Fig. 1.

Teams in Standard Platform use **Pepper robots from Aldebaran** at the United Robotics Group. (Fig. 2) [2] in the competitions. The development focus is mainly on software design.





Fig. 1 Custom build robots in Education competition



Fig. 2 Standard robot platform - Pepper robot from SoftBank Robotics

## 1.4 Participation Categories and Registrations

@Home Education has two categories - Open Platform (OP) and Standard Platform (SP). The competition will be run in two categories.

The registration will be done in two registration categories - Major and Junior registrations. Teams with ALL team members who are 19 year-olds or younger can register as Junior teams. Teams with ALL team members who are older than 19 year-olds must register as Major teams. If the majority of the team members are 19 year-olds or younger, the team can decide to register the older members as mentors. However, the mentor-team member ratio must be 1-3 or more. The youngest team members who can register as Junior members are 14 year-olds.

## 1.5 Eligibility and Qualification

The purpose of the @Home Education competition is to open @Home competition participation to everyone, especially novice and inexperienced participants. Due to the vast differences in the background and preparations/robot developments among potential participants, @Home Education qualification procedure is different from regular RoboCup qualification processes.

In the qualification procedure, teams are required to submit qualification materials (Team Description Paper (TDP) and Team Video) to the committee for review. The Team Description Paper requirements can be found here. The Team Video should show what the team has developed so far using the hardware (if applicable) or simulation, or using diagrams to explain the solution that the team has developed within five minutes. If the video is longer than five minutes, the committee will not review the portion after the 5 minute mark.

Below are some eligibilities and qualifications that we look for in the team application:

- Teams with their own hardware (both Open and SPL):
  - Experience in local @Home Education events Teams are encouraged to participate in local events first, and advance toward international events.
  - Experienced teams in international events could participate in @Home Education competition as long as the majority of the team members are novice and new to RoboCup competition.
  - Robot hardware costs should be similar to those of the workshop's basic robot platform (<USD 5k).
- Teams without own hardware:
  - Experience in robot development and robot competitions with similar level i.e. teams from other RoboCup leagues or robotics competitions with some related technical competency.
  - Familiarity with the basic robot platform/SPL experience in working on related hardware and developing software systems, especially with the RoboCup@Home Education OpenCourseWare/SPL.

#### 1.6 Awards

For each platform there will be Ranking Awards based on the competition performance. There are also some certificate awards, including sponsored Technical Awards and People's Choice Awards.

## 2. COMPETITION RULES

## 2.1 Fundamental Concept and General Rules

Fundamentally, the Education competition rules are based on the finalized (previous year) RoboCup@Home's official rulebook. This is to maintain the standard and development along with RoboCup@Home. However, for the educational purpose, several adjustments are made to put more focus on the teams' growth.

#### 2.1.1 Task Selections

We are selecting skill-based tasks from the RoboCup@Home rulebook that are more relevant for novice teams development from the workshop learning. This year, the task selections are as follows:

- 1. Carry My Luggage Navigation task
- 2. Find My Mates Vision task
- 3. **Receptionist** Speech task

## 2.1.2 Manipulation Task Adjustment

For Open Platform robots, due the size and height of the robots, the object placement for manipulation tasks is adjusted to be located within the reach of the working envelope of the robot arm (Fig. 3).



Fig. 3 Object placement and the working envelope of the robot arm [3]

For Standard Platform robots, the manipulation task can be assisted (by human) using the *simplify rule*.

#### 2.2 Team Poster and Presentation

As part of the Finals, all teams are required to prepare a team poster introducing their own team technical development. The A1 size posters are supposed to be posted at the poster area at the beginning of the event.

There will be a team poster presentation session at the end of the workshop sessions, before the start of the competition. All teams will present their poster to introduce their team technical development.

## 2.3 Educational Assessment Approach

In the Education competition, we are formulating more suitable assessment approaches for the educational purpose.

## 2.3.1 Incremental Scoring

Compared to the objective based scoring approach in RoboCup@Home, the incremental scoring approach by dividing the task scoring goals into subgoals, can enable partial scoring to assist new teams, who may be challenging for them to produce complete solutions as beginners. The updates are made in red to the task scoresheets. Also, the human assistance mechanism, "Deus ex Machina" is replaced with the above subgoals to cover the task flows.

## 2.3.2 The "Skip Rule"

The skip rule is a mechanism for the teams to "skip" for difficult parts within a task to proceed to the next subgoal. The purpose is to encourage teams to attempt the tasks even only partially (e.g. only vision task or only speech task if the navigation system is not working).

It is important to note that the skip rule is not a retry mechanism, i.e. the teams cannot retry the same subgoal when applying the skip rule, but have to proceed to the next subgoal.

#### 2.3.3 The "Simplify Rule"

To further motivate teams to attempt difficult challenges instead of calling skip rule, the simplify rule allows teams to run a subgoal of the task under simpler conditions for a reduction of points (i.e. 50%).

For example, in an object recognition task, a team can use their own object, this would be an intermediate score comparing recognizing objects decided by the OC. For people perception or people following, teams may ask to use their own team member (possibly with a predefined colored shirt) instead of a person chosen by OC.

OC can limit the number and the type of such simplifications and teams are required to announce them before the test.

## 2.4 Competition Tasks

Based on the previous year RoboCup@Home rulebook of 2022, 3 tasks and Finals are selected as follows:

## 2.4.1 Task 1: Carry My Luggage

The description in section 5.1 Carry My Luggage [Party Host] (pg. 41-43) is referred to.

#### Score sheet

The maximum time for this test is 5 minutes.

Action	Score
Main Goal	
Picking up the correct bag	100
Detect the selected bag	(50)
Take the selected bag [For SPL team - Find a person and communicate	(50)
with the person to bring the bag for the guest]	300
Following the person to the car	
Follow the operator to the outside of the arena	(150)
Follow the operator to the car	(150)
Drop the bag at the car	50
Avoid the crowd of people obstructing the path	50
Avoid the small object on the ground	50
Avoid the hard-to-see object	50
Avoid the area blocked with retractable barriers	

	T
Bonus rewards	100
Reentering the arena	(50)
Re-enter into inside of the arena	(50)
Back to the starting point	300
Joining and staying in the queue on the way to the arena	(150)
Joining the queue	(150)
Staying in the queue	
Regular Penalties	-50
Dropping the bag	
Deus Ex Machina Penalties	-50
Rediscovering the operator by natural interaction	-100
Rediscovering the operator by unnatural interaction	-200
Rediscovering the operator by direct contact	
Special Penalties & Bonuses	-500
Not attending (see sec. 3.9.1)	-100
Using alternative start signal (see sec. 3.4.4)	
Total Score (excluding special penalties & standard bonuses)	600 (Max 1000)

## 2.4.2 Task 2: Find My Mates

The description in section 5.4 Find My Mates [Party Host] (pg. 48-49) is referred to.

#### Score sheet

The maximum time for this test is 5 minutes.

Action	Score
Main Goal	
Report a guest location	2 x 100
Detect a guest	$(2 \times 40)$
<ul> <li>Move to the front of a guest</li> </ul>	$(2 \times 10)$
<ul> <li>Back to the front of the operator</li> </ul>	$(2 \times 10)$
<ul> <li>Provide the guest location</li> </ul>	$(2 \times 40)$
Provide location unique feature	$2 \times 50$
Provide description of a guest	2 x 150
<ul> <li>Provide the correct guest's name</li> </ul>	$(2 \times 50)$
<ul> <li>Provide the correct guest's description 1</li> </ul>	$(2 \times 50)$
<ul> <li>Provide the correct guest's description 2</li> </ul>	$(2 \times 50)$
Bonus rewards	
Report the 3rd guest location	150
Detect the 3rd guest	(50)
<ul> <li>Move to the front of a guest</li> </ul>	(25)
Back to the front of the operator	(25)
<ul> <li>Provide the 3rd guest location</li> </ul>	(50)
Provide description of a 3rd guest	250

Provide the correct 3rd guest's name	(50)
• Provide the correct 3rd guest's description 1	(100)
<ul> <li>Provide the correct 3rd guest's description 2</li> </ul>	(100)
Deus Ex Machina Penalties	
Person has to wave the robot in order to be found	2 x -75
Person has to tell the robot where he/she is sitting/standing	2 x -75
Person has to approach to the robot (e.g. walk and stand in front of it)	2 x -150
Special Penalties & Bonuses	
Not attending (see sec. 3.9.1)	-500
Using alternative start button (see sec. 3.4.4)	-100
Total Score (excluding special penalties & standard bonuses)	600 (Max 1000)

## 2.4.3 Task 3: Receptionist

The description in section 5.6 Receptionist [Party Host] (pg. 52-53) is referred to.

#### Score sheet

The maximum time for this test is 5 minutes.

Action	Score
Main Goal	
Introduce a new guest to every other guest and offer a seat	2 x 250
Introduce the guest's name	$(2 \times 50)$
<ul> <li>Introduce the guest's favorite drink</li> </ul>	$(2 \times 50)$
Detect an empty seat	$(2 \times 100)$
<ul> <li>Pointing/Facing at the empty seat while offering it</li> </ul>	$(2 \times 50)$
Look at the person talking	50
Look at the person being described	50
Look in the direction of navigation	50
Continue with wrong name or drink	2 x -50
Persistent inappropriate gaze - away from conversational partner	2 x -50
Persistent gaze not in the direction of the navigation while moving	-50
Bonus rewards	
Open the entrance door for a guest [For SPL team - Find a person and	2 x 100
communicate with the person to open the door for the guest]	150
Describe the first guest to the second guest	
Deus Ex Machina Penalties	2x - 75
Alternative HRI	2 x -200
Not recognizing people	
Special Penalties & Bonuses	-500
Not attending (see sec. 3.9.1)	
Total Score (excluding special penalties & standard bonuses)	650 (Max 1000)

#### 2.5 Finals: Presentation and Demonstration

The description in Chapter 7 Finals (pg. 85-86) is referred to.

All teams compete in Finals.

#### 2.5.1 Task

The objectives of this year are:

- The robot helps a person that has had a small accident in their home.
- The robot monitors a person while they are going about their day and reacts appropriately if it notices any unusual events.

The procedure for the demonstration and the timing of slots is as follows:

- 1. **Setup and demonstration:** The team has a maximum of *10 minutes* for setup, presentation and demonstration.
- 2. **Interview and cleanup:** After the demonstration, there is another 5 minutes where the team answers questions by the jury members. During the interview time, the team has to undo its changes to the environment.

## **REFERENCES**

- [1] J. T. C. Tan, L. Iocchi, A. Eguchi, H. Okada, "Bridging Robotics Education between High School and University: RoboCup@Home Education," *Int. Conf. of IEEE AFRICON 2019*, Sep. 2019.
- [2] Aldebaran's Pepper robot, <a href="https://unitedrobotics.group/en/robots/pepper">https://unitedrobotics.group/en/robots/pepper</a>
- [3] ROS Wiki,

http://wiki.ros.org/turtlebot kinect arm calibration/Tutorials/CalibratingKinectToTurtleBotArm