

7 Markov Chains

For the Markov chain, the past and **the future are conditionally independent**. For the special case of random walk on an undirected network, the network structure is the key to determining the stationary distribution.

We can picture a Markov chain intuitively by imagining a system with *states* and someone randomly wandering around from state to state.

For many interesting Markov chains, the *stationary* distribution of the chain helps us understand how the chain will behave in the long run.

7.1 Markov property and transition matrix

A sequence of RVs X_0, X_1, X_2, \dots evolving over time. This is called a *stochastic process*.

Markov chains have a form of one-step dependence, allowing to do beyond IIDs but still have very convenient structure.

Markov chains widely used for simulations of complex distributions, via algorithms known as *Markov chain Monte Carlo (MCMC)*.

Markov chains live in both space and time: the set of possible states X_n is called *state space*, and index n represents evolution of the process over *time*. The state space can be discrete or continuous, and time can also be discrete or continuous. We will focus on *discrete-state, discrete-time* Markov Chains with a *finite* state space.

Markov Chain

A sequence of RVs X_0, X_1, X_2, \dots taking values in *state space* $\{1, 2, \dots, M\}$ is called *Markov chain* $\forall n \geq 0$,

$$P(X_{n+1} = j | X_n = i, X_{n-1} = i-1, \dots, X_0 = i_0) = P(X_{n+1} = j | X_n = i)$$

$P(X_{n+1} = j | X_n = i)$ is called the *transition probability* from state i to state j . This Markov chain is *time-homogeneous*, which means that

$P(X_{n+1} = j | X_n = j)$ is the same $\forall n$.

We can describe the probabilities of moving from state to state using a matrix called *transition matrix* whose i, j entry is probability of going from i -th to j -th state in a single step.

Translation matrix

Let X_0, X_1, X_2, \dots be a Markov chain $\{1, 2, \dots, M\}$ and let $q_{ij} = P(X_{n+1} = j | X_n = i)$ be transition probability from state i to state j . The matrix $Q = (q_{ij})$ is the *transition matrix* of the chain. Q is nonnegative and each row sums to 1.

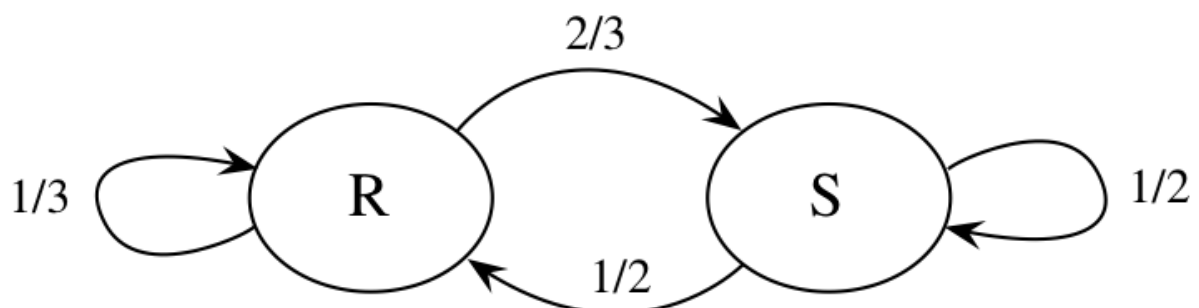
Example: Rainy-sunny Markov chain

If today is rainy, tomorrow it will be rainy with $P = 1/3$ and sunny with $P = 2/3$. If today is sunny, tomorrow it will be rainy with $P = 1/2$ and sunny with $P = 1/2$.

Let X_n be the weather on day n and X_0, X_1, X_2, \dots is a Markov chain on the state space $\{R, S\}$. Translation matrix of this chain is:

$$\begin{matrix} & R & S \\ \begin{matrix} R \\ S \end{matrix} & \begin{pmatrix} 1/3 & 2/3 \\ 1/2 & 1/2 \end{pmatrix} \end{matrix}$$

Also we can represent this chain as graph:

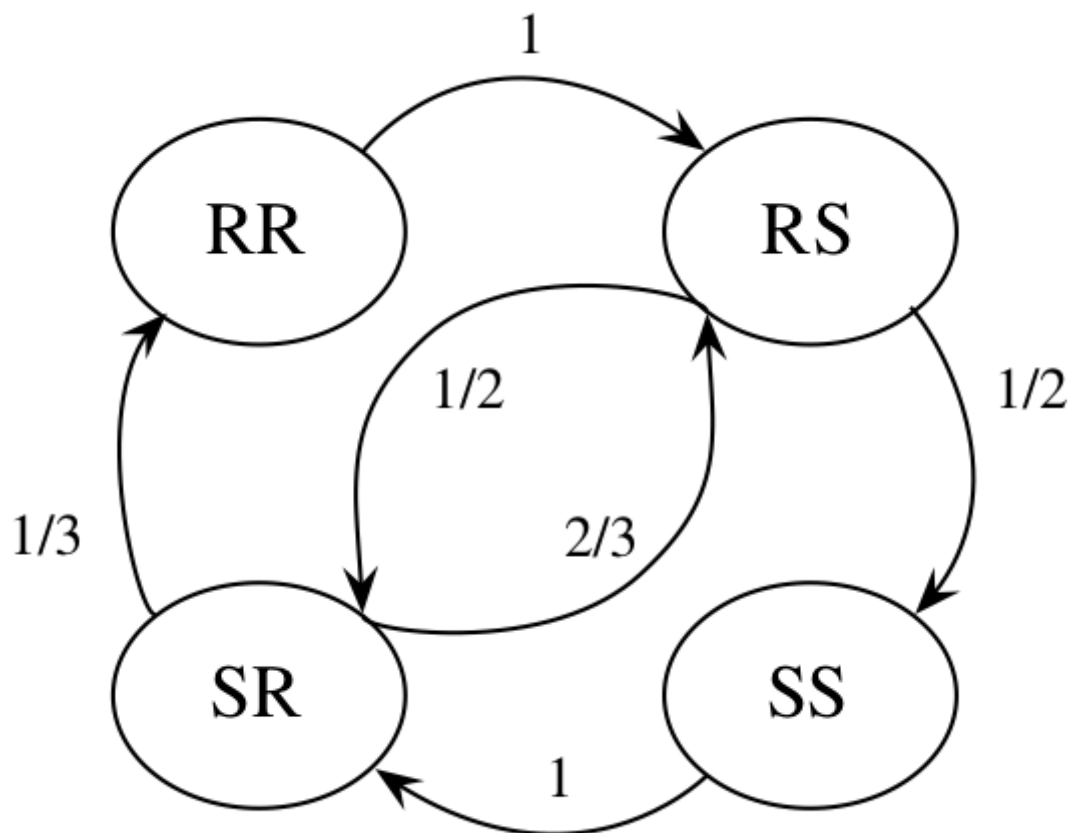


And what if tomorrow's weather depends on today's and yesterday's weather? To illustrate it, we can create a new Markov chain. Let $Y_n = (X_{n-1}, X_n) \forall n \geq 1$. Then Y_1, Y_2, \dots is a Markov chain on the state space $\{(R, R), (R, S), (S, R), (S, S)\}$.

Transition matrix of this chain is:

$$\begin{array}{c}
 \\
 (R, R) \\
 (R, S) \\
 (S, R) \\
 (S, S)
 \end{array}
 \begin{array}{c}
 (R, R) \quad (R, S) \quad (S, R) \quad (S, S) \\
 \left(\begin{array}{cccc}
 0 & 1 & 0 & 0 \\
 0 & 0 & 1/2 & 1/2 \\
 1/3 & 2/3 & 0 & 0 \\
 0 & 0 & 1 & 0
 \end{array} \right)
 \end{array}$$

This Markov chain may be represented as the following graph:



Similarly, we can build a chain on n-order dependencies.

N-step transition probability

The n -step transition probability $q_{ij}^{(n)}$ from i to j is the probability of being at j exactly n steps after being at i .

$$q_{ij}^{(n)} = P(X_n = j | X_0 = i).$$

Of course,

$$q_{ij}^{(n)} = \sum_k q_{ik} q_{kj}.$$

The n -th power of the transition matrix gives the n -step transition probabilities $q_{ij}^{(n)}$ is the (i, j) -th entry of Q^n .