#### Moscow Russian Federation ⊠ robolamp@ya.ru robolamp

## Yulia Yakovleva

### Experience

October 2015 - Robotics researcher/developer, Institute for Information Trans-August 2017 mission Problems RAS (Kharkevich Institute), Moscow.

- Self-driving car positioning and control software development:
  - System launch tool to replace ROSLaunch (Python, ROS, Paramiko): Just a more flexible tool than ROSLaunch.
  - Local positioning system (C++, Eigen, Kalman filters): EKF and rollbacks/roll-ons to use measurements with various delays.
  - Trajectory control system (C++, ROS);
  - Developers' web-interface (Python, JS (Leaflet.JS, Bootstrap), ROS): Interactive tool allows to correct positioning and control route passing.
  - Road markup-relied localization system (C++, ROS): A system uses recognized road markup for more accurate positioning.
  - Field testing:
- Initiative works in deep learning for robotics control (just for fun).

June 2015 – Junior web-developer, WETA Group, Remote.

October 2015 Full-stack web-development

• Security system web-interface development: Two web-application were developed using Django non-rel backend and JS + Backbone. JS + Marionette.JS + Raphaël.JS frontend with MongoDB database;

July 2013 – Control systems developer, Modern Signal Processing and Contol June 2015 Technologies R&D Laboratory, Chelyabinsk.

Control systems development.

- Turboshaft control system development:
  - Turboshaft math modelling using MATLAB/Simulink;
  - Design, assembling and commissioning of turboshaft control system control cabinets;
- Autonomous car trajectory control system development:
  - Participated in car control system structure development;
  - Control algorithms development and math modelling using MAT-LAB/Simulink and VisSim;
  - Algorithms realization (C++, control unit with STM32 and NuttX RTOS);
  - Car control system test bench software development using Python 2.7 with NumPy and UDP;
  - Participated in commissioning, HIL and field tests;
- UAV test bench software development: Scilab, interaction with National Instruments data acquisition system
- January 2012 **Laboratory assistant**, South Ural State University, Chelyabinsk. June 2015 Participated in research works.

#### Education

#### 2010–2015 National Research South Ural State University;

Computer Technologies, Control and Radio Electronics Faculty; Automation and Control Department;

MEng, graduated with honours.

# 2015–2017 Moscow Institute of Physics and Technology (State University);

Department of Innovation and High Technologies;

Cognitive technologies sub-faculty;

MSc in Computer Science.

## Languages

Russian Native speaker

English Intermediate

German Beginner

Polish Beginner

Skills

Main:

C++ (Eigen, Boost), Python (Jupyter, NumPy, Sklearn, Paramiko), Matlab/Simulink, SciLab, VisSim, Git, ROS, Linux, LaTeX, Dynamic systems math modelling.

Experience with:

Bash, C, OpenCV, JS (Underscore.JS, Backbone.JS, Leaflet.JS), MongoDB, Django, Machine Learning, Computer Vision.

Miscellaneous

Interests

RC airplanes and quadrotors, skiing, bicycling.