Matlab Code

```
% Hunter Phillips
% Homework 9
% MAE 488
% 04/17/19
clear
format compact
%% Header
d_bullets = repmat('*', 50, 1); % concise way to make a lot of chars
fprintf('%c',d bullets)
fprintf('\nMAE 488, Homework #9, Spring 2019, Hunter Phillips\n')
fprintf('%c',d_bullets)
fprintf('\n\n')
clear
%% Problem 11.2M
su_bullets = repmat('*', 25, 1); % setting up cmd line output
un_bullets = repmat('-', 25, 1);
un_bullets = repmat('-', 25,
fprintf('%c',su_bullets)
fprintf('\nProblem 11.2M\n')
fprintf('%c',su_bullets)
fprintf('\n\n')
f1 = figure(1);
hold on
% Root Locus Plot
num = [1 0];
den = [3 0 12];
h = tf(num,den)
rlocus(h)
title({'MAE 488, Homework 9, Problem 11.2M'}, 'interpreter', 'latex', 'FontSize', 16)
% print(f1,'..\results\problem_10_29_1.png','-dpng','-r1200');
%% Problem 11.6M
su_bullets = repmat('*', 25, 1); % setting up cmd line output un_bullets = repmat('-', 25, 1);
dn_bullets = repmat( - , 25,
fprintf('%c',su_bullets)
fprintf('\nProblem 11.6M\n')
fprintf('%c',su_bullets)
fprintf('\n\n')
% Multiply Gp_s and Gc_s as given to obtain:
Gc_Gp_s = tf([1 12 30 100],[1 3 2 0])
poles_a = pole(Gc_Gp_s)
zeros_a = zero(Gc_Gp_s)
fprintf('K = (TD)(KP) = 0.5KP\n\n')
% Finding closed-loop transfer function
% closed loop feedback
Ys_Rs = feedback(modifi_2,1)
poles c = pole(Ys Rs)
zeros c = zero(Ys Rs)
%% Problem 11.9M
su_bullets = repmat('*', 25, 1); % setting up cmd line output
un_bullets = repmat('-', 25, 1);
fprintf('%c',su_bullets)
fprintf('\nProblem 11.9M\n')
fprintf('%c',su_bullets)
```

```
fprintf('\n\n')
f2 = figure(2);
hold on
% Rearranging results in:
1 + (5p/4) \cdot ((s^2+6s+8)/(s(s^2+(25/4)s+4)))=0
t_fun = tf([1 6 8],[1 (25/4) 4 0])
poles_9_b = pole(t_fun)
zeros_9_b = zero(t_fun)
rlocus(t_fun)
ylim([-3 3])
title({'MAE 488, Homework 9, Problem 11.9M'}, 'interpreter', 'latex', 'FontSize', 16)
%% Problem 11.45M
su_bullets = repmat('*', 25, 1); % setting up cmd line output
un_bullets = repmat('-', 25, 1);
fprintf('%c',su_bullets)
fprintf('\nProblem 11.45M\n')
fprintf('%c',su_bullets)
fprintf('\n\n')
f3 = figure(3);
hold on
\ensuremath{\mathtt{\textit{\$}}} Solving mass spring damper system for equations of motion
% 2x' + 8x' + (k2+26)*x = (k2)*y

% CE = 2s^2 + 8s + 26 + k2 = 0

% Standard form = 1 + ((k2)/2)(1/(s^2+4s+13) = 0
tfunn = tf([1],[1 4 13])
rlocus(tfunn)
title({'MAE 488, Homework 9, Problem 11.45M'}, 'interpreter', 'latex', 'FontSize', 16)
largest_damp_ratio = cos(atan(3/2)) % info from pole on plot for 2 and 3
```

Matlab Output ************** MAE 488, Homework #9, Spring 2019, Hunter Phillips **************** ******** Problem 11.2M ******** h =S ----- $3 s^2 + 12$ Continuous-time transfer function. ******** Problem 11.6M ******** $Gc_Gp_s =$ $s^3 + 12 s^2 + 30 s + 100$ -----

Continuous-time transfer function.

 $s^3 + 3 s^2 + 2 s$

0

-2

-1

$$-10.0000 + 0.0000i$$

$$K = (TD)(KP) = 0.5KP$$

$$Y_{S}R_{S} =$$

$$5 \text{ s}^3 + 60 \text{ s}^2 + 150 \text{ s} + 500$$

Continuous-time transfer function.

$$-8.6881 + 0.0000i$$

$$-0.9059 + 2.9616i$$

zeros_c =

$$-1.0000 + 3.0000i$$

Problem 11.9M

t_fun =

$$s^2 + 6 s + 8$$

$$s^3 + 6.25 s^2 + 4 s$$

Continuous-time transfer function.

poles_9_b =

0

-0.7238

 $zeros_9_b =$

-4

-2

Problem 11.45M

tfunn =

 $s^2 + 4 s + 13$

Continuous-time transfer function.

largest_damp_ratio = 0.5547

Matlab Figures

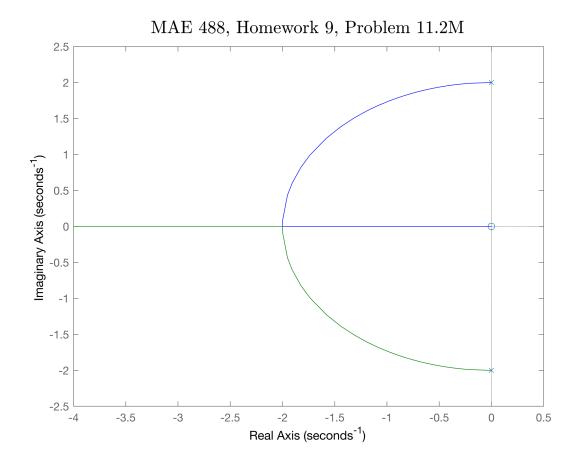


Figure 1: Problem 11.2

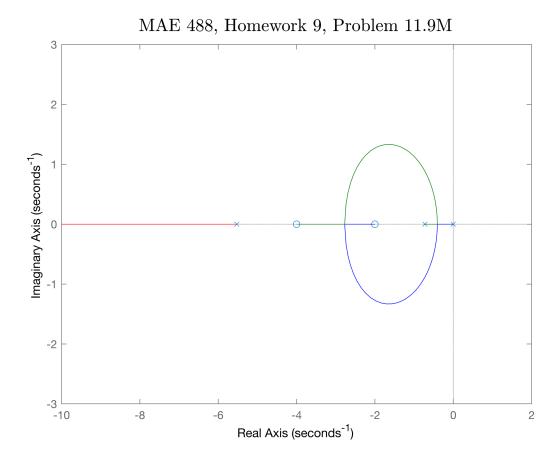


Figure 2: Problem 11.9

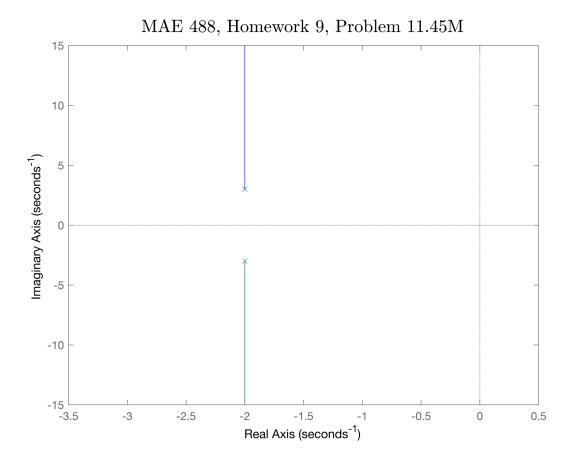


Figure 3: Problem 11.45