

# Matlab Code

```
% Hunter Phillips
% Homework 7
% MAE 488
% 03/12/19

clc
clear
format compact

%% Header
d_bullets = repmat('*', 50, 1); % concise way to make a lot of chars
fprintf('%c',d_bullets)
fprintf('\nMAE 488, Homework #7, Spring 2019, Hunter Phillips\n')
fprintf('%c',d_bullets)
fprintf('\n\n')

clear

%% Problem 50M

su_bullets = repmat('*', 25, 1); % setting up cmd line output
fprintf('\n')
fprintf('%c',su_bullets)
fprintf('\nProblem 50M\n')
fprintf('%c',su_bullets)
fprintf('\n\n')

% Part A
fprintf('Part A\n-----\n\n')
sys=tf(5000,[1,26,269,1524,4680]);
using_equation = stepinfo(sys,'RiseTimeLimits',[0,1])

% Part B
fprintf('\nPart B\n-----\n\n')
root1 = -3.0000 + 6.0000*j;
root2 = -3.0000 - 6.0000*j;
po = poly([root1 root2]);
sys=tf(5000,po); % 5000 comes from unit step
using_dom_root = stepinfo(sys,'RiseTimeLimits',[0,1])

% comparison
fprintf('\nIt can be seen that using the dominant roots provides a decently reasonable\nestimate of the
qualities derived: Percent Overshoot, Peak Time, and 100% Rise Time.\n')
fprintf('\nUsing the given equation, the overshoot of %.2f%% was smaller than the dominant root
estimation of %.2f%%.\n...
    , using_equation.Overshoot, using_dom_root.Overshoot)
fprintf('\nUsing the given equation, the peak time of %.2f seconds was larger than the dominant root
estimation of %.2f seconds.\n...
    , using_equation.PeakTime, using_dom_root.PeakTime)
fprintf('\nUsing the given equation, the 100% rise time of %.2f seconds which was larger than the
dominant root estimation of %.2f seconds.\n\n...
    , using_equation.SettlingTime, using_dom_root.SettlingTime)

%% Problem 52S

f1 = figure(1);

su_bullets = repmat('*', 25, 1); % setting up cmd line output
fprintf('\n')
fprintf('%c',su_bullets)
fprintf('\nProblem 52S\n')
fprintf('%c',su_bullets)
fprintf('\n\n')

poly_block_52M = [-27/800, 27/80, 0,0]
LTI_52M = tf(1,[0.125, 0.75, 1])

sim('Problem_52S.slx')

plot(simout.time, simout.data)
legend('x(t)', 'y(t)', 'location', 'northeast', 'FontSize',16,'interpreter','latex')
ylabel('Function')
xlabel('Time')
title({'MAE 488, Homework 7, Problem 8.52S'},'interpreter','latex','FontSize',16)
```

```

fprintf('Results Plotted in Figure 1\n')
% print(f1,'..\results\problem_8_52S.png','-dpng','-r1200');

%% Problem 54S

f2 = figure(2);

su_bullets = repmat('*', 25, 1); % setting up cmd line output
fprintf('\n')
fprintf('%c',su_bullets)
fprintf('\nProblem 54S k = 4\n')
fprintf('%c',su_bullets)
fprintf('\n\n')

% For k = 4
k=4;
LTI_54M = tf(1,[5,3,7,k])
sim('Problem_54S.slx')

plot(simout.time, simout.data)
legend('x(t)', 'location', 'northeast', 'FontSize',16, 'interpreter', 'latex')
ylabel('Function')
xlabel('Time')
title({'MAE 488, Homework 7, Problem 8.54S'}, 'interpreter', 'latex', 'FontSize',16)

fprintf('Results Plotted in Figure 2\n')
% print(f2,'..\results\problem_8_54S_1.png','-dpng','-r1200');

% Experimenting with k

su_bullets = repmat('*', 25, 1); % setting up cmd line output
fprintf('\n')
fprintf('%c',su_bullets)
fprintf('\nProblem 54S varying k\n')
fprintf('%c',su_bullets)
fprintf('\n\n')

f3 = figure(3);
n=5;
for k = 1:n
    subplot(n,1,k);
    LTI_54M = tf(1,[5,3,7,k]);
    sim('Problem_54S.slx')
    plot(simout.time, simout.data)
    if k == 1
        title({'MAE 488, Homework 7, Problem 8.54S'}, 'interpreter', 'latex', 'FontSize',16)
    end
    kpr = sprintf('%d',k);
    ylabel(strcat('k = ',kpr))
end
xlabel('Time')

fprintf('Results Plotted in Figure 3\n')
% print(f3,'..\results\problem_8_54S_2.png','-dpng','-r1200');

```

## Matlab Output

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MAE 488, Homework #7, Spring 2019, Hunter Phillips

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Problem 50M

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Part A

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using\_equation =

struct with fields:

RiseTime: 0.5736

SettlingTime: 1.3950

SettlingMin: 1.0402

SettlingMax: 1.2028

Overshoot: 12.5811

Undershoot: 0

Peak: 1.2028

PeakTime: 0.7552

## Part B

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using\_dom\_root =

struct with fields:

RiseTime: 0.3391

SettlingTime: 1.2451

SettlingMin: 106.3108

SettlingMax: 134.2074

Overshoot: 20.7866

Undershoot: 0

Peak: 134.2074

PeakTime: 0.5219

It can be seen that using the dominant roots provides a decently reasonable estimate of the qualities derived: Percent Overshoot, Peak Time, and 100% Rise Time.

Using the given equation, the overshoot of 12.58% was smaller than the dominant root estimation of 20.79%.

Using the given equation, the peak time of 0.76 seconds was larger than the dominant root estimation of 0.52 seconds.

Using the given equation, the 100% rise time of 1.39 seconds which was larger than the dominant root estimation of 1.25 seconds.

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## Problem 52S

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poly\_block\_52M =

-0.0338   0.3375   0   0

LTI\_52M =

1

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$0.125 s^2 + 0.75 s + 1$

Continuous-time transfer function.

Results Plotted in Figure 1

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Problem 54S k = 4

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LTI\_54M =

1

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5 s^3 + 3 s^2 + 7 s + 4

Continuous-time transfer function.

Results Plotted in Figure 2

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Problem 54S varying k

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Results Plotted in Figure 3

## Matlab Figures

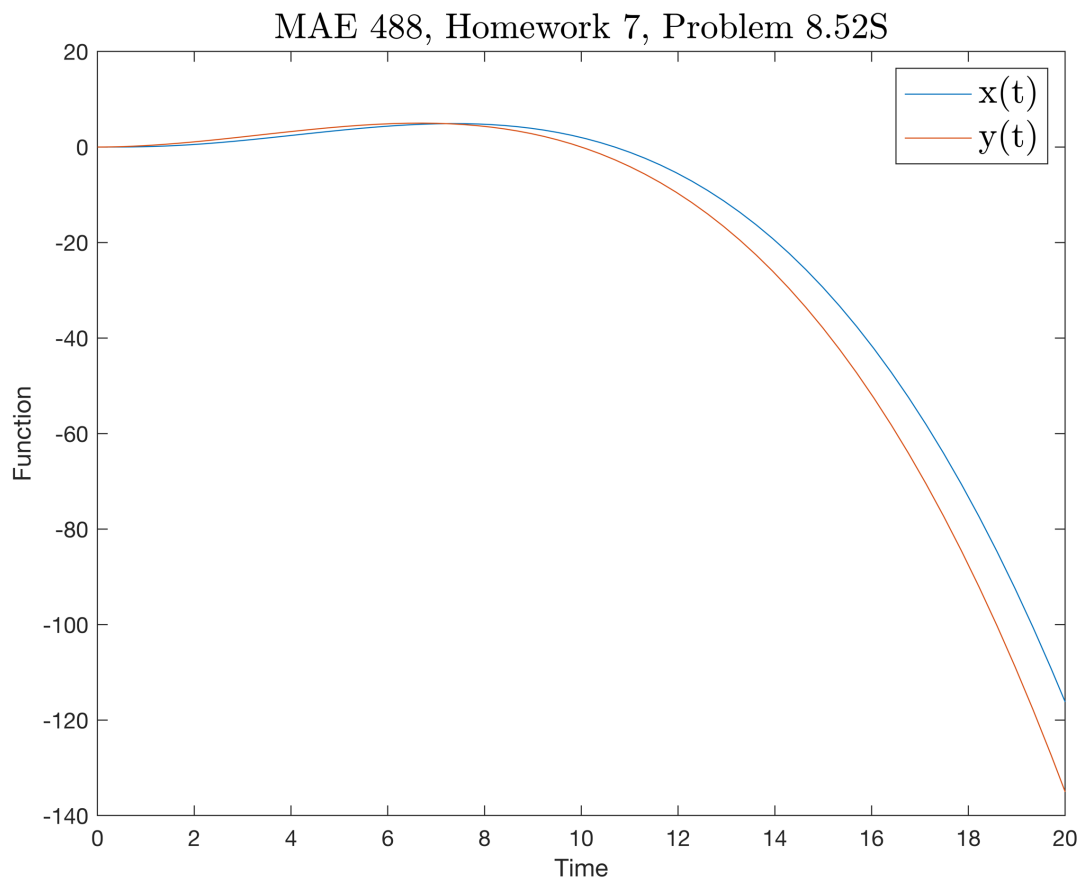


Figure 1: Problem 8.52S

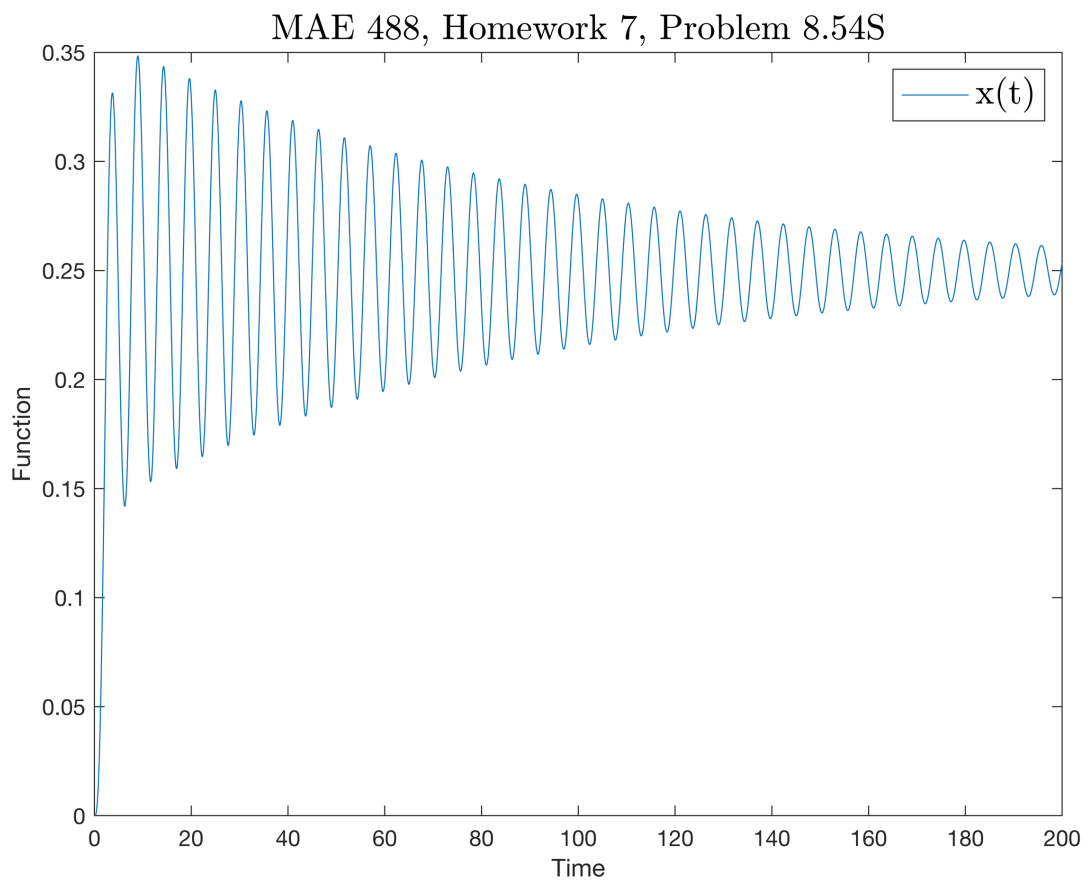


Figure 2: Problem 8.54S for  $k = 4$



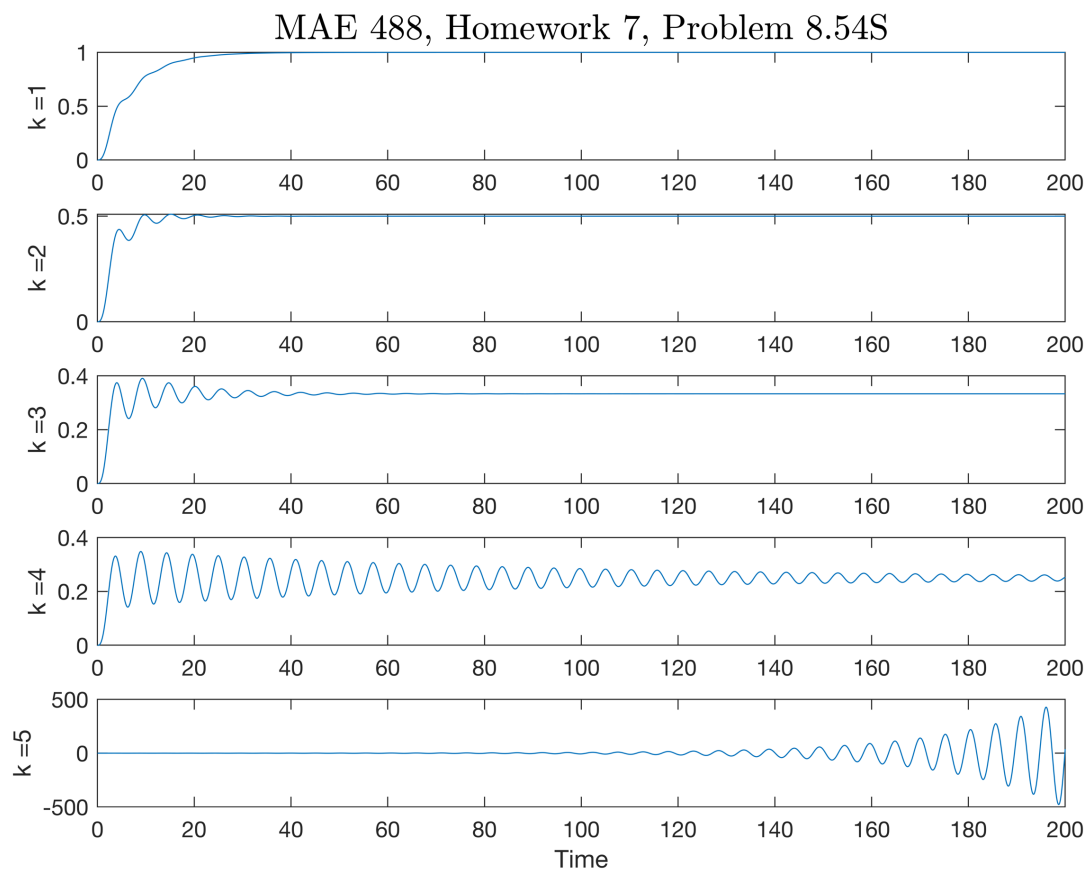
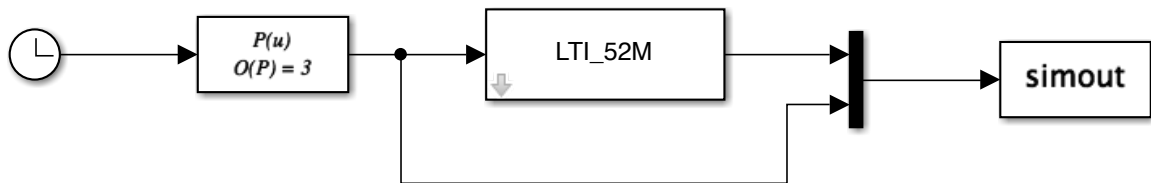
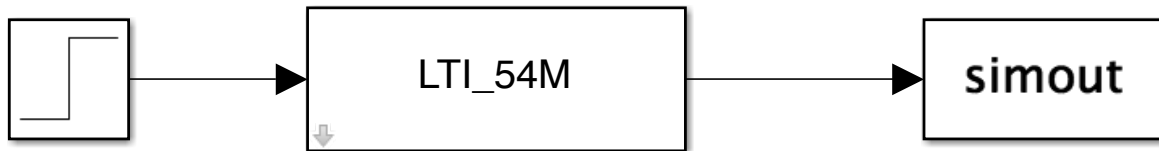


Figure 3: Problem 8.54S for varying  $k$

## Simulink Models



Problem 52.S



Problem 54.S