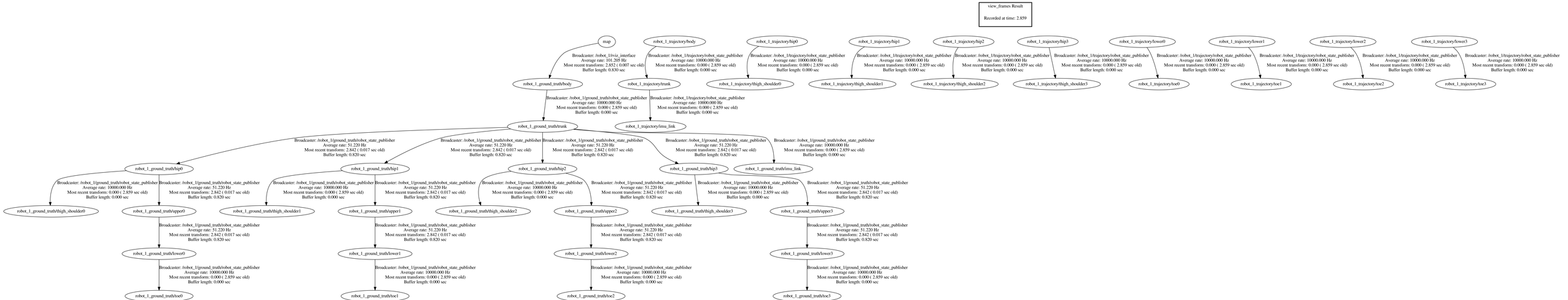
view_frames Result
Recorded at time: 2.859
map
robot_1_trajectory/body
robot_1_trajectory/hip0
robot_1_trajectory/hip1
robot_1_trajectory/hip2
robot_1_trajectory/hip3
robot_1_trajectory/lower0
robot_1_trajectory/lower1
robot_1_trajectory/lower2
robot_1_trajectory/lower3
Broadcaster: /robot_1/viz_interface
Average rate: 101.205 Hz
Most recent transform: 2.852 ( 0.007 sec old)
Buffer length: 0.820 sec
Broadcaster: /robot_1/trajectory/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 2.859 sec old)
Buffer length: 0.000 sec
robot_1_ground_truth/body
robot_1_trajectory/trunk
robot_1_trajectory/thigh_shoulder0
robot_1_trajectory/thigh_shoulder1
robot_1_trajectory/thigh_shoulder2
robot_1_trajectory/thigh_shoulder3
robot_1_trajectory/toe0
robot_1_trajectory/toe1
robot_1_trajectory/toe2
robot_1_trajectory/toe3
Broadcaster: /robot_1/ground_truth/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 2.859 sec old)
Buffer length: 0.000 sec
robot_1_ground_truth/trunk
robot_1_trajectory/imu_link
Broadcaster: /robot_1/ground_truth/robot_state_publisher
Average rate: 51.220 Hz
Most recent transform: 2.842 ( 0.017 sec old)
Buffer length: 0.820 sec
robot_1_ground_truth/hip0
robot_1_ground_truth/hip1
robot_1_ground_truth/hip2
robot_1_ground_truth/hip3
robot_1_ground_truth/imu_link
Broadcaster: /robot_1/ground_truth/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 2.859 sec old)
Buffer length: 0.000 sec
robot_1_ground_truth/thigh_shoulder0
robot_1_ground_truth/upper0
robot_1_ground_truth/thigh_shoulder1
robot_1_ground_truth/upper1
robot_1_ground_truth/thigh_shoulder2
robot_1_ground_truth/upper2
robot_1_ground_truth/thigh_shoulder3
robot_1_ground_truth/upper3
Broadcaster: /robot_1/ground_truth/robot_state_publisher
Average rate: 51.220 Hz
Most recent transform: 2.842 ( 0.017 sec old)
Buffer length: 0.820 sec
robot_1_ground_truth/lower0
robot_1_ground_truth/lower1
robot_1_ground_truth/lower2
robot_1_ground_truth/lower3
Broadcaster: /robot_1/ground_truth/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 2.859 sec old)
Buffer length: 0.000 sec
robot_1_ground_truth/toe0
robot_1_ground_truth/toe1
robot_1_ground_truth/toe2
robot_1_ground_truth/toe3