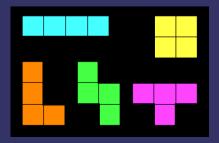
# Bin Packing Using Search Methods

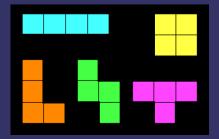
Robert Jackson

Applications
Current State of the Art
Shapes
Bins
Rotations
Search Methods
Heuristics



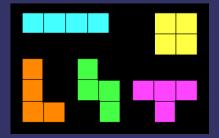
#### Overview

- Bin Packing optimization deals with the problem of fitting objects of various shapes and sizes into a bin of length *I* and width *w*.
- Search algorithms (DFS, A\*) can be used to traverse the possibility tree to find a configuration that leaves no holes.



### Long-term goal

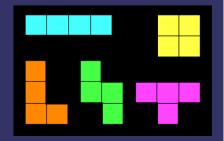
- Given a set of tetrominos T, and a bin of length I and width w, place each element of T at location x,y and rotation r.
- numTetrominos\*4 <= I\*w</p>
- numTetrominos\*4 + numHoles <= I\*w</p>



## The Problem



Shipping of Goods
Of various size/shapes



#### The Present Situation

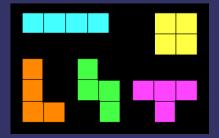
- Give a summary of the current situation
- Packing for:
  - Storage optimize space, time
  - Transport inertia, center of mass, space

#### Applications

- Memory Management (Paging)
- Shipping
- Storage
- Art

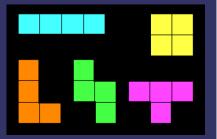
#### Commercial Application Suites

- optimal packing of various bins
- shipping containers
- pallets
- radioactive waste storage/transport



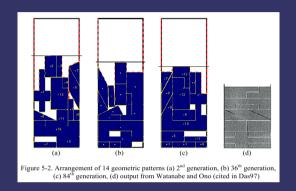
#### Development up to present

- Development made up to the current situation
- Important background information
- Original forecasts which turned out to be wrong
- Original forecasts which turned out to be true



#### Potential Alternatives

- State the alternative strategies
  - Genetic Algorithm (GA)
    - Pros: good for large tree,
    - Cons: slow, not optimal,
  - Constraint Satisfaction Problem (CSP)
    - Pros: fast
    - Cons: not easily modified
  - Packing homogeneous shapes/sizes
    - Pros: greatly reduces permutations
    - Cons: not possible in most instances
- List the pros and cons of each strategy
- Give a forecast of costs



# Genetic Algorithm by Arfath Pasha

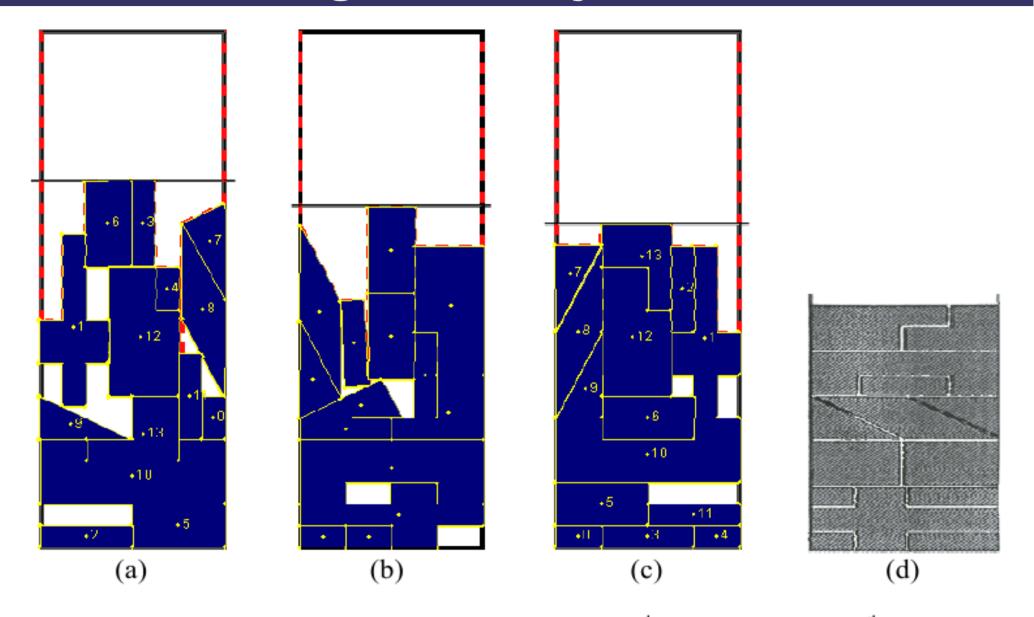
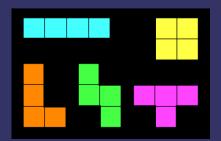


Figure 5-2. Arrangement of 14 geometric patterns (a) 2<sup>nd</sup> generation, (b) 36<sup>th</sup> generation, (c) 84<sup>th</sup> generation, (d) output from Watanabe and Ono (cited in Das97)

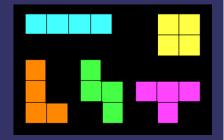
- Bin Packing Methods
- Overview
- Long-term goal
- The Present Situation
- Development up to present
- Potential Alternatives
- Recommendation



## My Project – Tetromino Bin Packer

#### Algorithms Implemented

- A\* (NumberOfTilesLeft and NumberOfHoles Heuristics)
- DSF
- Greedy Best First Search
- Hill Climbing
- Simulated Annealing



# Building the Tree – 1

```
class TetrisPieceActionsFunction {
public Set<Action> actions(Object state) {
for (int j = 0; j < board.getRows(); j++) {</pre>
    for (int i = 0; i < board.getColumns(); i++) {</pre>
         addActionsToSet(pool, i, j, board, actions);
```

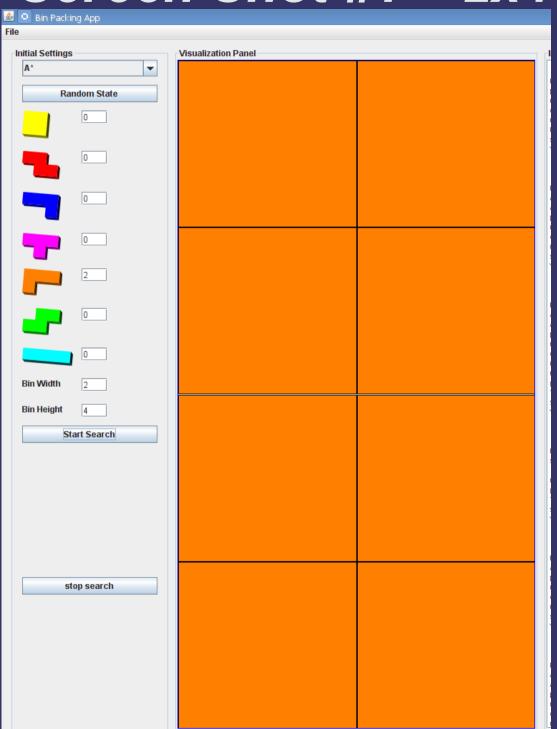
# Building the Tree – 2

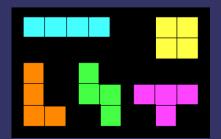
```
void addActionsToSet(...) {
    addSActionsToSet(board, location, actions);
    addIActionsToSet(board, location, actions);
```

# Building the Tree – 3

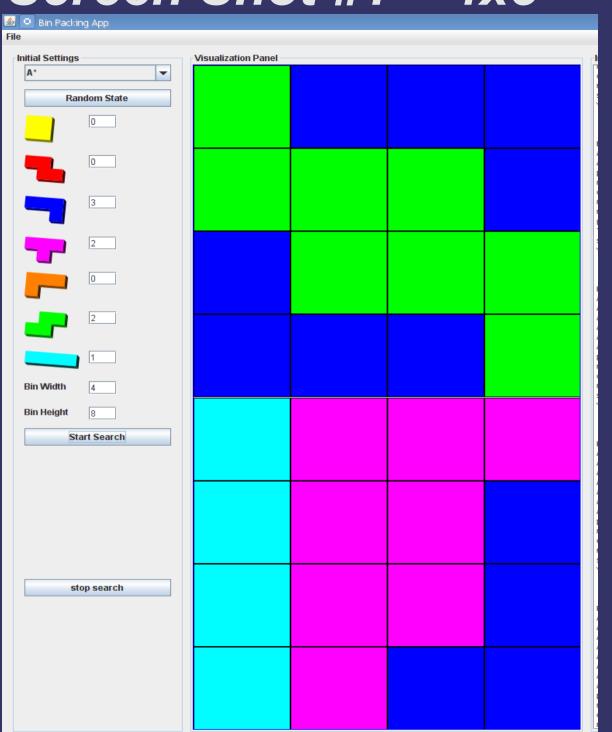
```
addSActionsToSet(TetrisBoard board, XYLocation loc, Set<Action> actions)
  TetrisPiece piece = TetrisPiece. S PIECE;
  if (board.willFit(piece, loc)
     && !BadMoveTest.isBadMove(board, piece, loc)) {
        actions.add(TetrisPieceAction.PLACE 5, loc);
  // try rotate and place S piece
  piece.rotateClockwise();
  if (board.willFit(piece, loc)
     && !BadMoveTest.isBadMove(board, piece, loc)) {
        actions.add(TetrisPieceAction.ROTATE_AND_PLACE_S, loc);
```

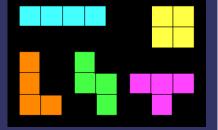
#### Screen Shot #1 - 2x4



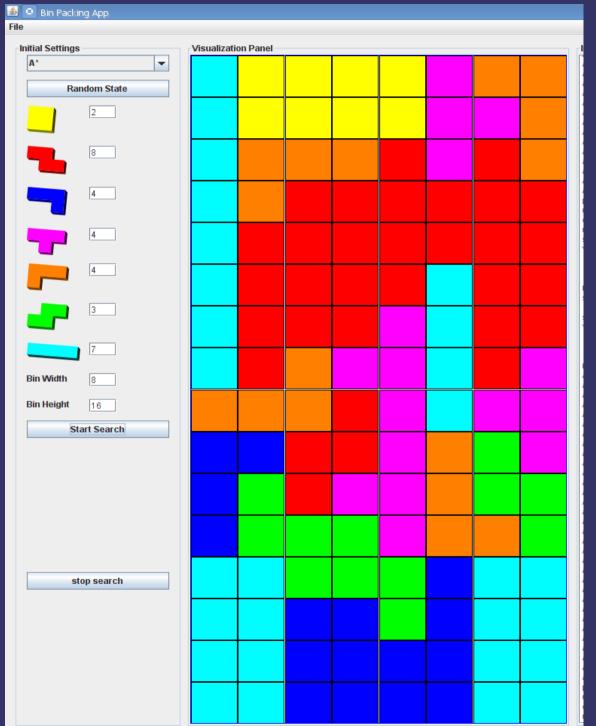


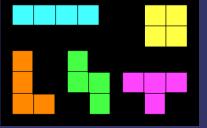
#### Screen Shot #1 - 4x8



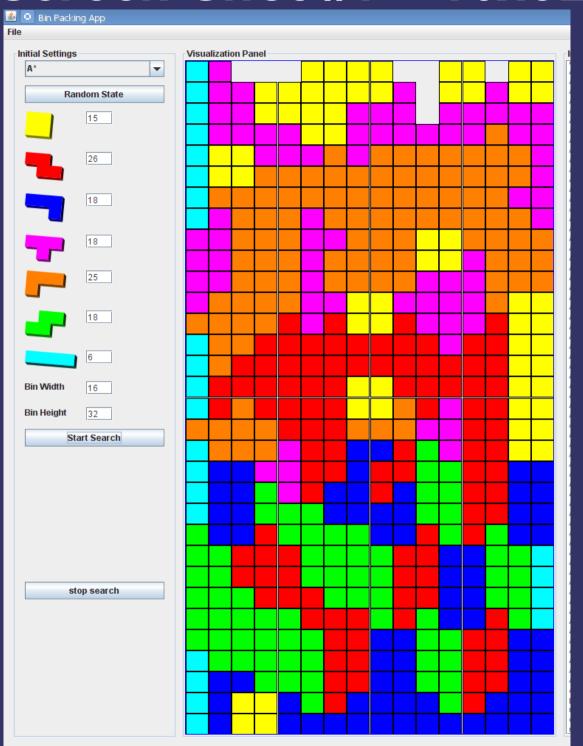


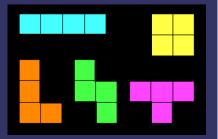
## Screen Shot #1 - 8x16



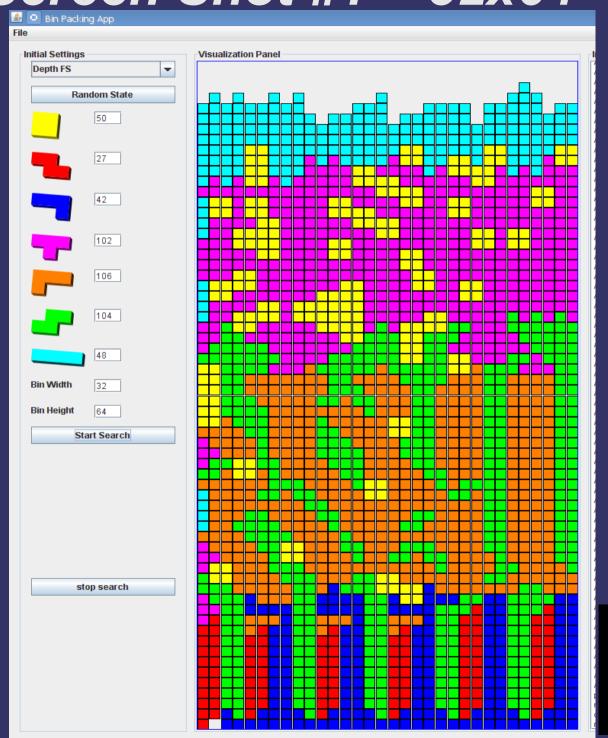


#### Screen Shot #1 - 16x32

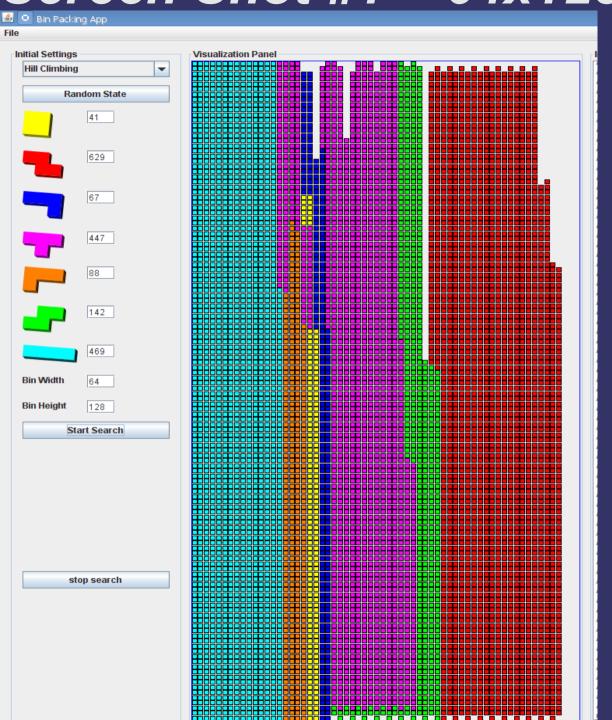


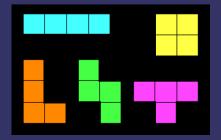


#### Screen Shot #1 - 32x64

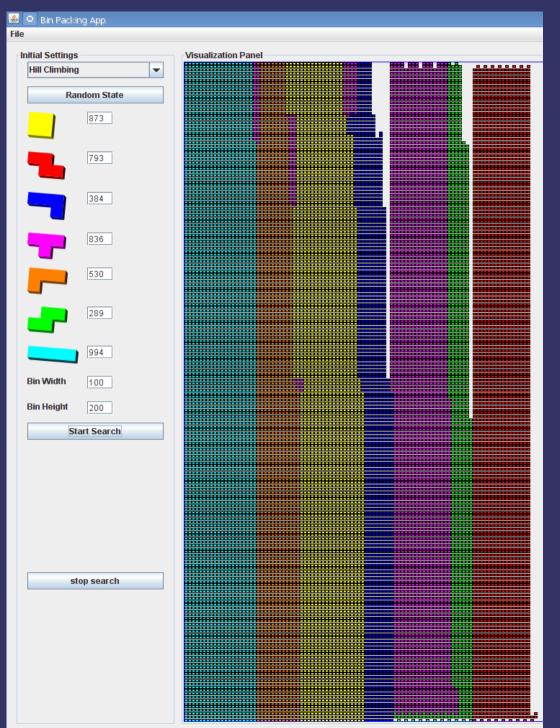


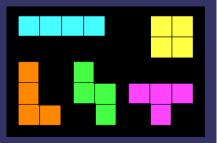
#### Screen Shot #1 - 64x128





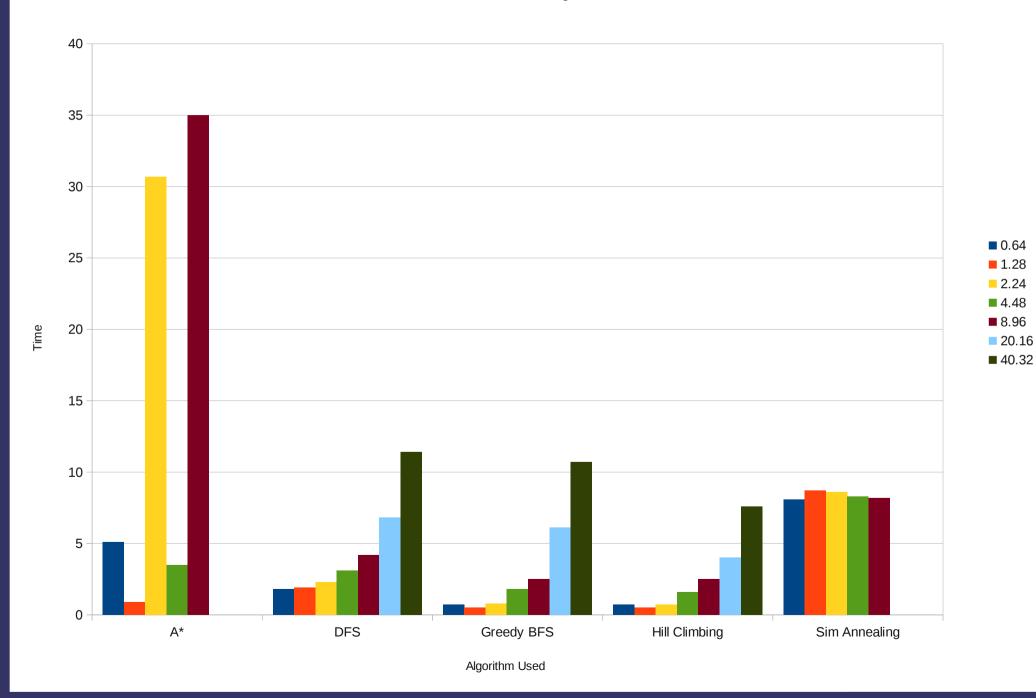
#### Screen Shot #1 - 100x200





#### Time Needed to Pack

#### For Varous Percentages of Bin



# **Question Time**

