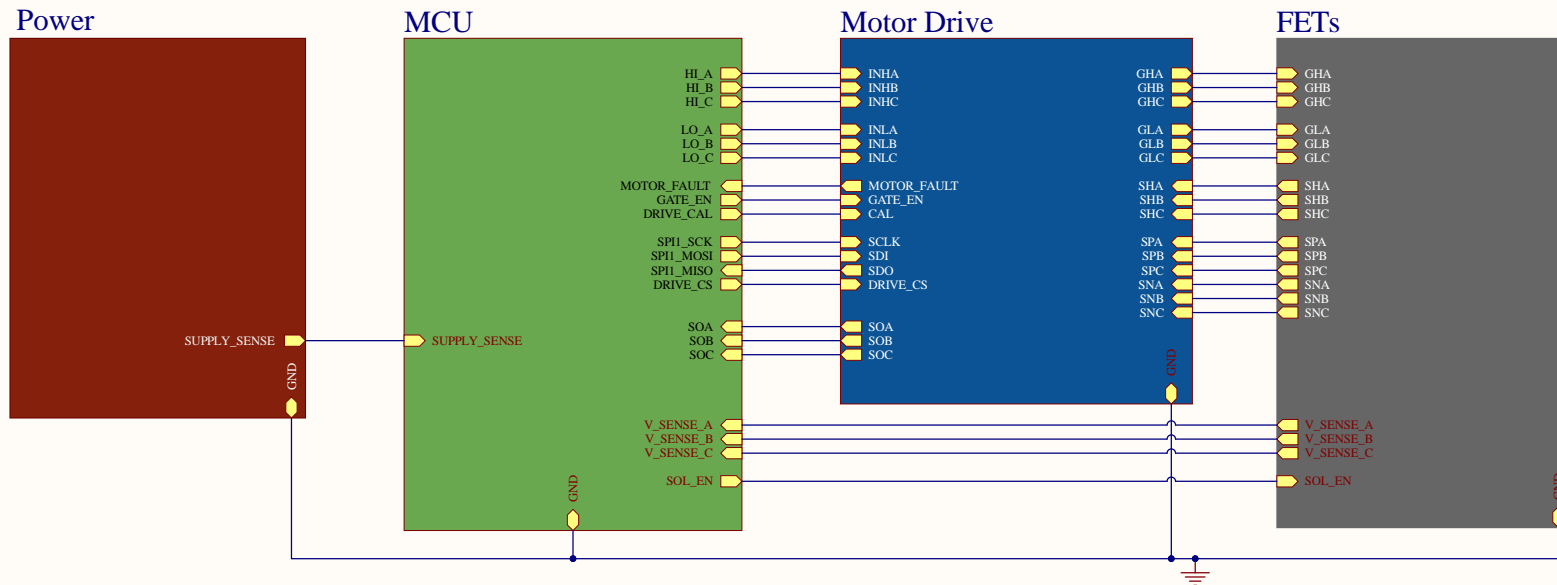


MAXWELL

An Open Source, three-phase motor controller for robot actuators



Specifications:

- Up to 60V input
- 70A Continuous current, 150A Peak
- PWM, CAN, and USB control
- Built in 5V BEC for radio receivers
- Sensorless, Sensored and FOC control
- Encoder support:
 - Hall sensors, Rotational encoders, Magnetic encoders (1 built in)

| | | |
|-----------------------|--------------------|----------------|
| Title: Overview | | |
| Size: A2 | Document Number: 1 | Revision: 1 |
| Date: 06/09/2023 | Sheet 1 of 6 | |
| File: Overview.SchDoc | | |
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A

B



D



A

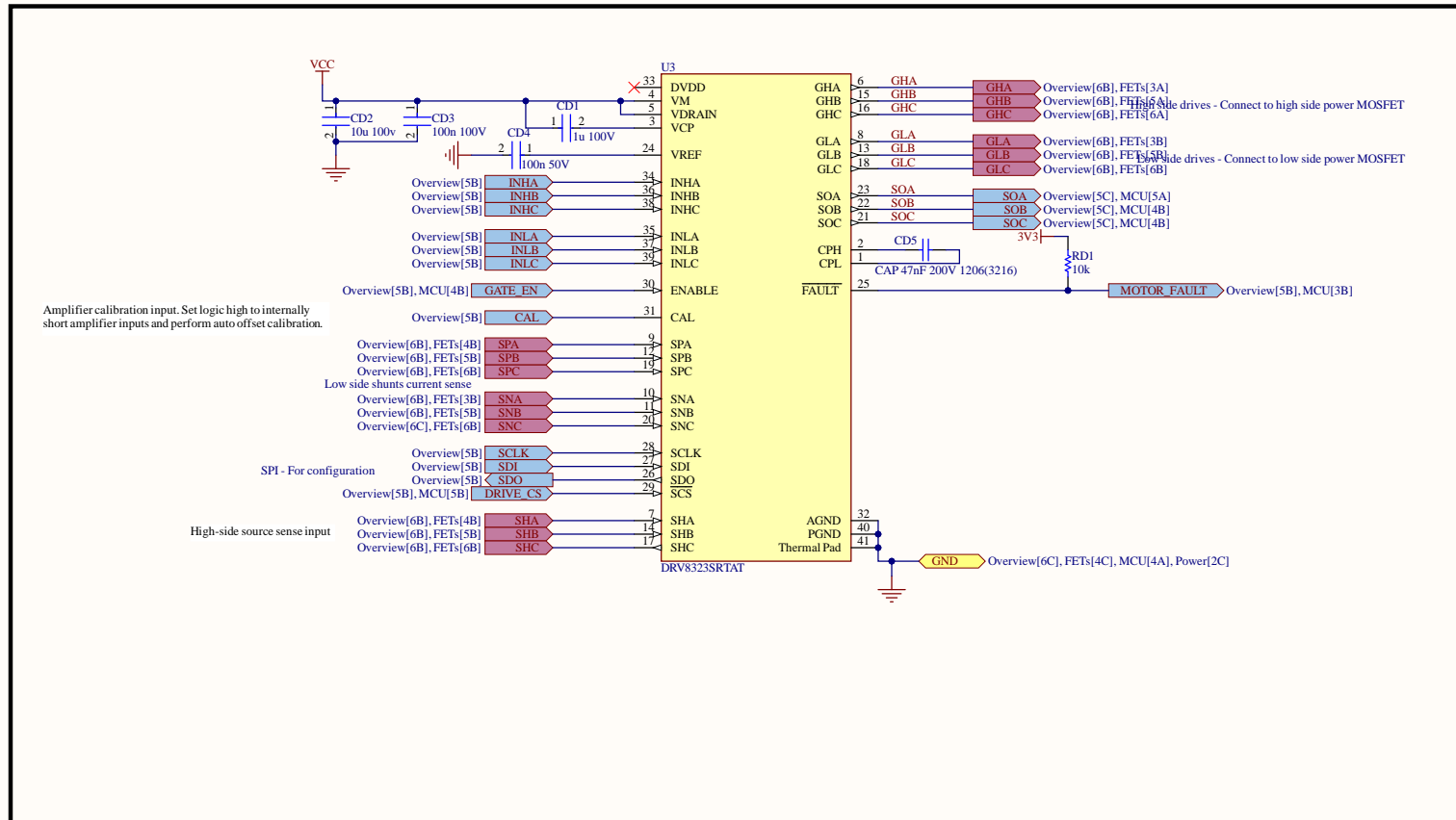


C

**ROBOSAM**

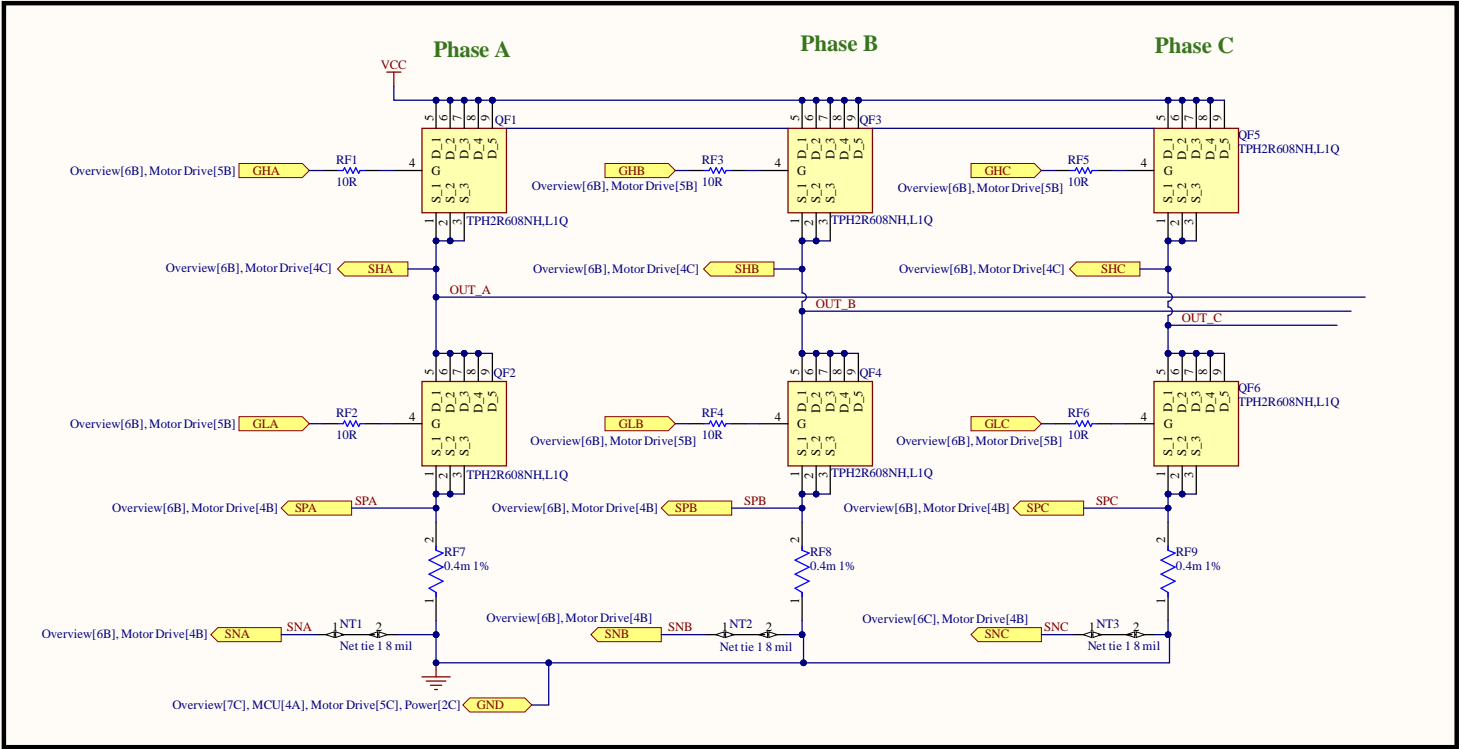
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| Size: A2 | Document Number: 3 | Revision: 1 |
| Date: 06/09/2023 | Sheet * of * | |
| File: MCU.SchDoc | | |
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[4] Motor Drive - D

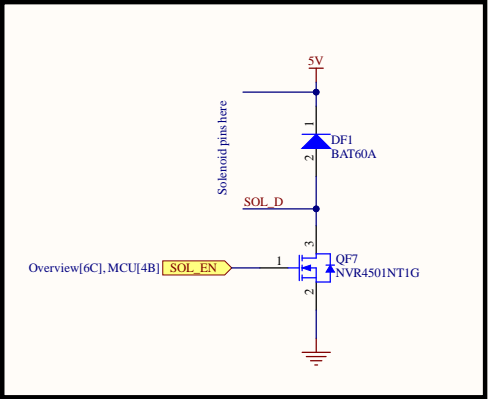


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| Title: Motor Drive | | |
| Size: A2 | Document Number: 4 | Revision: 1 |
| Date: 06/09/2023 | Sheet * of * | |
| File: Motor Drive.SchDoc | | |
| Drawn By: Sam Scott | | ROBOSAM |

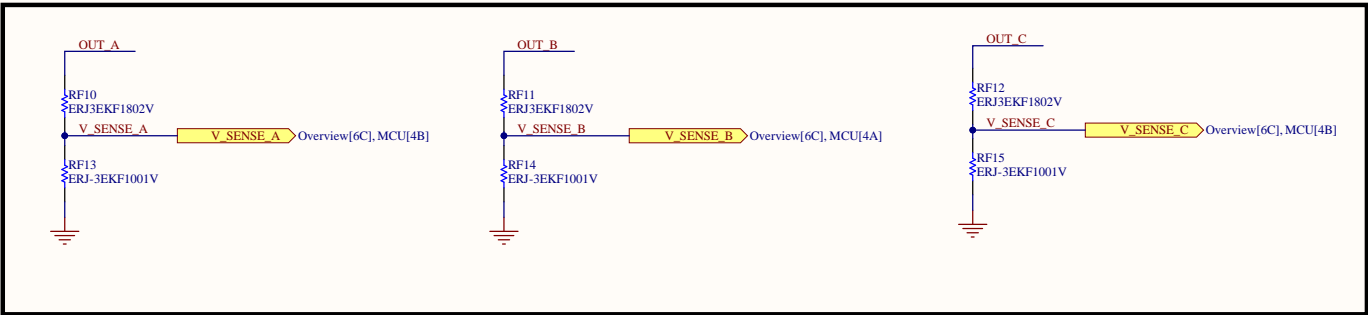
[5] FETs - F



FET for a solenoid brake



Resistor dividers to detect shunt voltage



| | | | |
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| Title: FETs | | | |
| Size: A2 | Document Number: 5 | | Revision: 1 |
| Date: 06/09/2023 | | Sheet * of * | |
| File: FETs.SchDoc | | | |
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