

# *The RoboSense Challenge*

*In conjunction with the 38th IEEE/RSJ Int. Conf. Intell. Robots Syst. (IROS), Hangzhou, China*

*The 2<sup>nd</sup> place in the category*

## *Track 3: Sensor Placement*

*is presented to*

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*for the submission*

*Point Loom*

*Sponsored by*



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*Date*

*RoboSense 2025 Organizing Team*

*Organizers*