

# *The RoboSense Challenge*

*In conjunction with the 38th IEEE/RSJ Int. Conf. Intell. Robots Syst. (IROS), Hangzhou, China*

*The 5<sup>th</sup> place in the category*

*Track 5: Cross-Platform 3D Object Detection*

*is presented to*

*Shurui Qing, Wei Cong, Yao He*

*for the submission*

*TeamArcN*

*Sponsored by*



**HUAWEI**

*Oct 2025*

*Date*

*RoboSense 2025 Organizing Team*

*Organizers*