

# *The RoboSense Challenge*

*In conjunction with the 38th IEEE/RSJ Int. Conf. Intell. Robots Syst. (IROS), Hangzhou, China*

*The 4<sup>th</sup> place in the category*

## *Track 3: Sensor Placement*

*is presented to*

*Zihang Wang, Yiming Peng, Guanyu Zong, Xu Li, Binghao Wang,  
Hao Wei, Yongxin Ma, Yunke Shi, Shuaipeng Liu, Dong Kong*

*for the submission*

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