

The RoboSense Challenge

In conjunction with the 38th IEEE/RSJ Int. Conf. Intell. Robots Syst. (IROS), Hangzhou, China

The 2nd place in the category

Track 5: Cross-Platform 3D Object Detection

is presented to

Shuangzhi Li, Junlong Shen, Xingyu Li

for the submission

Point Loom

Sponsored by



Oct 2025

Date

RoboSense 2025 Organizing Team

Organizers