

cl_nav2z::CbRotateLookAt
::onEntry

cl_nav2z::CbWaitPose
::onEntry

cl_nav2z::Pose::waitTransform
Update

```
graph LR; A[cl_nav2z::CbRotateLookAt::onEntry] --> C[cl_nav2z::Pose::waitTransform Update]; B[cl_nav2z::CbWaitPose::onEntry] --> C;
```

The diagram illustrates a dependency or call sequence. Two white rectangular boxes on the left represent callback functions: 'cl_nav2z::CbRotateLookAt::onEntry' (top) and 'cl_nav2z::CbWaitPose::onEntry' (bottom). Blue arrows point from each of these boxes to a single gray rectangular box on the right labeled 'cl_nav2z::Pose::waitTransform Update'. This indicates that both callbacks trigger or depend on the pose update function.