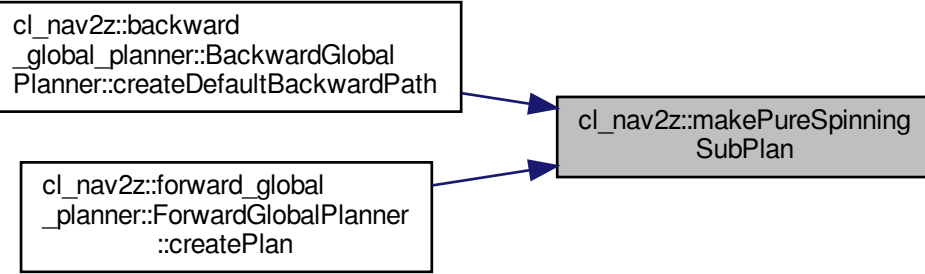


cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::createDefaultBackwardPath

cl_nav2z::forward_global
_planner::ForwardGlobalPlanner
::createPlan

cl_nav2z::makePureSpinning
SubPlan



```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createDefaultBackwardPath"] --> C["cl_nav2z::makePureSpinning  
SubPlan"]; B["cl_nav2z::forward_global  
_planner::ForwardGlobalPlanner  
::createPlan"] --> C;
```

The diagram illustrates a dependency or call relationship. Two source boxes on the left point via blue arrows to a single target box on the right. The top source box contains the text 'cl_nav2z::backward' followed by '_global_planner::BackwardGlobalPlanner::createDefaultBackwardPath' on two lines. The bottom source box contains 'cl_nav2z::forward_global' followed by '_planner::ForwardGlobalPlanner::createPlan' on two lines. The target box on the right contains 'cl_nav2z::makePureSpinning' followed by 'SubPlan' on two lines. The target box has a light gray background, while the source boxes are white.