

sm\_aws\_warehouse\_navigation  
::StAcquireSensors::sendInitial  
PoseEstimation



```
graph LR; A["sm_aws_warehouse_navigation::StAcquireSensors::sendInitialPoseEstimation"] --> B["cl_nav2z::Amcl::setInitialPose"]
```

cl\_nav2z::Amcl::setInitialPose