

sm_aware_avp::clients
::aware_client::CbNavigateGlobal
Position::onEntry



```
graph LR; A["sm_aware_avp::clients  
::aware_client::CbNavigateGlobal  
Position::onEntry"] --> B["sm_aware_avp::clients  
::ClAware::publishGoalPose"]
```

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::ClAware::publishGoalPose