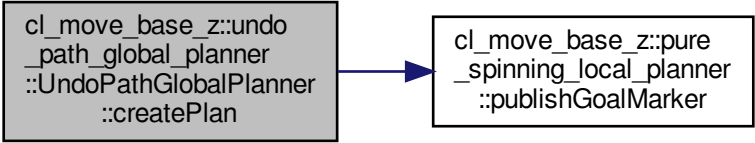


```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::createPlan
```



The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains the text 'cl\_move\_base\_z::undo', '\_path\_global\_planner', '::UndoPathGlobalPlanner', and '::createPlan' stacked vertically. The right box has a white background and contains the text 'cl\_move\_base\_z::pure', '\_spinning\_local\_planner', and '::publishGoalMarker' stacked vertically. The arrow is a solid blue line with a triangular arrowhead pointing towards the right box.

```
cl_move_base_z::pure  
_spinning_local_planner  
::publishGoalMarker
```