

sm\_dance\_bot\_warehouse  
\_3::radial\_motion\_states  
::StiRadialLoopStart::loopWhile  
Condition



```
graph LR; A["sm_dance_bot_warehouse_3::radial_motion_states::StiRadialLoopStart::loopWhileCondition"] --> B["smacc2::ISmaccState::getLogger"]
```

smacc2::ISmaccState  
::getLogger