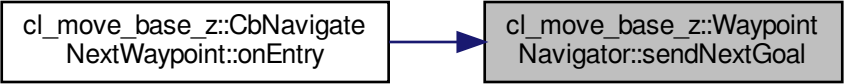


cl\_move\_base\_z::CbNavigate  
NextWaypoint::onEntry



```
graph LR; A["cl_move_base_z::CbNavigate  
NextWaypoint::onEntry"] --> B["cl_move_base_z::Waypoint  
Navigator::sendNextGoal"]
```

cl\_move\_base\_z::Waypoint  
Navigator::sendNextGoal