

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::findInitialCarrotGoal



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::findInitialCarrotGoal"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeCurrentEuclidean  
AndAngularErrorsToCarrotGoal"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and contains the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', and 'Planner::findInitialCarrotGoal'. The right box has a white background and contains the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', 'Planner::computeCurrentEuclidean', and 'AndAngularErrorsToCarrotGoal'. The arrow is a solid blue line.

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::computeCurrentEuclidean
AndAngularErrorsToCarrotGoal