

cl_move_group_interface
::CbCircularPouringMotion
::createMarkers

cl_move_group_interface
::CbMoveCartesianRelative2
::generateTrajectory

cl_move_group_interface
::CbCircularPouringMotion
::generateTrajectory

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::getCurrentEndEffectorPose



```
graph LR; A["cl_move_group_interface  
::CbCircularPouringMotion  
::createMarkers"] --> D["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::getCurrentEndEffectorPose"]; B["cl_move_group_interface  
::CbMoveCartesianRelative2  
::generateTrajectory"] --> D; C["cl_move_group_interface  
::CbCircularPouringMotion  
::generateTrajectory"] --> D;
```

The diagram illustrates a mapping or inheritance relationship. Three source boxes on the left point via blue arrows to a single target box on the right. The target box is shaded gray, while the source boxes are white with black borders. The source boxes contain method names from the 'cl_move_group_interface' namespace, specifically related to circular pouring and Cartesian relative movement. The target box contains a method name related to end effector trajectory and pose retrieval.