

cl\_moveit2z::CpTrajectory  
History::getLastTrajectory

cl\_moveit2z::CbExecuteLast  
Trajectory::onEntry

cl\_moveit2z::CbMoveLastTrajectory  
InitialState::onEntry

cl\_moveit2z::CbUndoLastTrajectory  
::onEntry

cl\_moveit2z::CpTrajectory  
History::getLastTrajectory

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graph LR; A[cl_moveit2z::CpTrajectory History::getLastTrajectory] --> D[cl_moveit2z::CpTrajectory History::getLastTrajectory]; B[cl_moveit2z::CbExecuteLast Trajectory::onEntry] --> D; C[cl_moveit2z::CbMoveLastTrajectory InitialState::onEntry] --> D; E[cl_moveit2z::CbUndoLastTrajectory ::onEntry] --> D;
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The diagram illustrates a call graph where four different functions or methods are calling a common target function. The target function, 'cl\_moveit2z::CpTrajectory History::getLastTrajectory', is highlighted in a grey box on the right. Four source functions, each in a white box with a black border, have blue arrows pointing towards the target. The source functions are: 'cl\_moveit2z::CpTrajectory History::getLastTrajectory' (top left), 'cl\_moveit2z::CbExecuteLast Trajectory::onEntry' (second from top left), 'cl\_moveit2z::CbMoveLastTrajectory InitialState::onEntry' (third from top left), and 'cl\_moveit2z::CbUndoLastTrajectory ::onEntry' (bottom left).