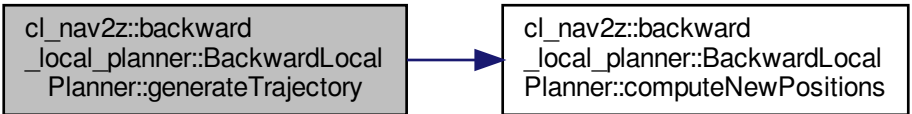
cl_nav2z::backward
_local_planner::BackwardLocal
Planner::generateTrajectory
cl_nav2z::backward
_local_planner::BackwardLocal
Planner::computeNewPositions