```
smacc2::ISmaccClientBehavior
- stateMachine
- currentState
- currentOrthogonal
+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
+ onEntry()
+ onExit()
+ executeOnEntry()
+ executeOnExit()
# runtimeConfigure()
# postEvent()
# postEvent()
# getCurrentState()
# dispose()
# getNode()
# getLogger()
onOrthogonalAllocation()
               Δ
smacc2::SmaccClientBehavior
+ onEntry()
+ onExit()
                        _multirole_sensor
                      ::CbDefaultMultiRoleSensor
                        Behavior< ClientType >
                      + deferedEventPropagation

    CbDefaultMultiRoleSensor

                      Behavior()
                      + onOrthogonalAllocation()
                      + propagateEvent()
                      + propagateEvent2()
                      + onEntry()
                      + onExit()
                      + onMessageCallback()
                      + getEventLabel()
                           < CILidarSensor >
  cl_multirole_sensor
  ::CbDefaultMultiRoleSensor
   Behavior < CILidar Sensor >
  + sensor
  + deferedEventPropagation

    CbDefaultMultiRoleSensor

  Behavior()
  + onOrthogonalAllocation()
  + propagateEvent()
  + propagateEvent2()
  + onEntry()
  + onExit()
  + onMessageCallback()
  + getEventLabel()
                Д
   sm_dance_bot_warehouse
_2::cl_lidar::CbLidarSensor
   + CbLidarSensor()
   + onEntry()
   + onMessageCallback()
```