

```
image_tools::ROSCvMatContainer  
::get_sensor_msgs_msg_image  
_pointer_copy
```



A diagram illustrating a pointer relationship. A blue arrow points from the left box to the right box. The left box is white with a black border, and the right box is gray with a black border. Both boxes contain the same text, which is a C++ function call to get\_sensor\_msgs\_msg\_image\_copy.

```
image_tools::ROSCvMatContainer  
::get_sensor_msgs_msg_image_copy
```