smacc2::ISmaccClient # components_ - stateMachine orthogonal + ISmaccClient() + ~ISmaccClient() + onInitialize() + getName() + getComponent() + getComponent() + getType() + getStateMachine() + connectSignal() + requiresClient() + getComponents() + postEvent() + postEvent() # onOrthogonalAllocation() # createComponent() # createNamedComponent() # getNode() # getLogger() - initialize() - setStateMachine() - setOrthogonal() smacc2::client bases ::SmaccPublisherClient + topicName + queueSize + durability + reliability + pub - initialized + SmaccPublisherClient() + ~SmaccPublisherClient() + configure() + publish() cl ros publisher::ClRosPublisher sm dance bot strikes sm dance bot::cl string back::cl string publisher publisher::CIStringPublisher ::CIStringPublisher + topicName + CIRosPublisher() + topicName + ~ClRosPublisher() + CIStringPublisher() + configure() + CIStringPublisher() + onInitialize()

+ publish()

+ onInitialize()