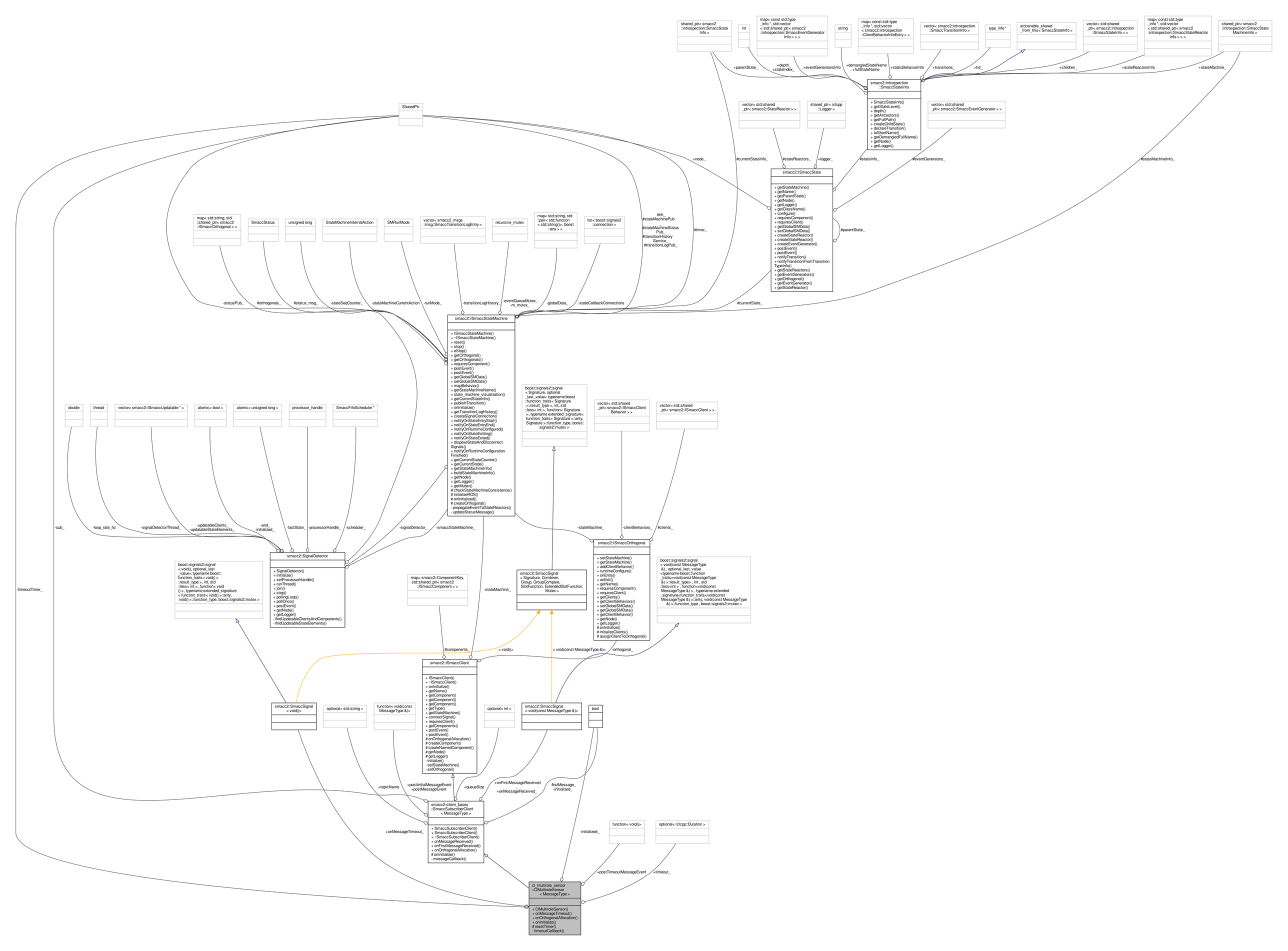
shared_ptr< smacc2 ::introspection::SmaccState Info >
int
map< const std::type _info *, std::vector < std::shared_ptr< smacc2 ::introspection::SmaccEventGenerator Info > > >
string
map< const std::type _info *, std::vector < smacc2::introspection ::ClientBehaviorInfoEntry > >
vector< smacc2::introspection ::SmaccTransitionInfo >
type_info *
std::enable_shared _from_this< SmaccStateInfo >
vector< std::shared _ptr< smacc2::introspection ::SmaccStateInfo > >
map< const std::type _info *, std::vector < std::shared_ptr< smacc2 ::introspection::SmaccStateReactor Info > > >
shared_ptr< smacc2 ::introspection::SmaccState MachineInfo >
+parentState_
+depth_
+stateIndex_
+eventGeneratorsInfo
+demangledStateName
+fullStateName
+staticBehaviorInfo
+transitions_
+tid_
+children_
+stateReactorsInfo
+stateMachine_
smacc2::introspection ::SmaccStateInfo
+ SmaccStateInfo()
+ getStateLevel()
+ depth()
+ getAncestors()
+ getFullPath()
+ createChildState()
+ declareTransition()
+ toShortName()
+ getDemangledFullName()
+ getNode()
+ getLogger()
SharedPtr
vector< std::shared _ptr< smacc2::StateReactor > >
shared_ptr< rclcpp ::Logger >
vector< std::shared _ptr< smacc2::SmaccEventGenerator > >
+node_
#currentStateInfo_
#stateReactors_
+logger_
#stateInfo_
#eventGenerators_
#stateMachineInfo_
smacc2::ISmaccState
+ getStateMachine()
+ getName()
+ getParentState()
+ getNode()
+ getLogger()
+ getClassName()
+ configure()
+ requiresComponent()
+ requiresClient()
+ getGlobalSMData()
+ setGlobalSMData()
+ createStateReactor()
+ createStateReactor()
+ createEventGenerator()
+ postEvent()
+ postEvent()
+ notifyTransition()
+ notifyTransitionFromTransition TypeInfo()
+ getStateReactors()
+ getEventGenerators()
+ getOrthogonal()
+ getEventGenerator()
+ getStateReactor()
#parentState_
#timer_
#hh_
#stateMachinePub
#stateMachineStatus Pub_
#transitionHistory Service_
#transitionLogPub_
map< std::string, std ::shared_ptr< smacc2 ::ISmaccOrthogonal > >
SmaccStatus
unsigned long
StateMachineInternalAction
SMRunMode
vector< smacc2_msgs ::msg::SmaccTransitionLogEntry >
recursive_mutex
map< std::string, std ::pair< std::function < std::string()>, boost ::any > >
list< boost::signals2 ::connection >
-statusPub_
#orthogonals_
#status_msg_
-stateSeqCounter_
-stateMachineCurrentAction
-runMode_
-transitionLogHistory_
-eventQueueMutex_
-m_mutex_
-globalData_
-stateCallbackConnections
#currentState_
smacc2::ISmaccStateMachine
+ ISmaccStateMachine()
+ ~ISmaccStateMachine()
+ reset()
+ stop()
+ eStop()
+ getOrthogonal()
+ getOrthogonals()
+ requiresComponent()
+ postEvent()
+ postEvent()
+ getGlobalSMData()
+ setGlobalSMData()
+ mapBehavior()
+ getStateMachineName()
+ state_machine_visualization()
+ getCurrentStateInfo()
+ publishTransition()
+ onInitialize()
+ getTransitionLogHistory()
+ createSignalConnection()
+ notifyOnStateEntryStart()
+ notifyOnStateEntryEnd()
+ notifyOnRuntimeConfigured()
+ notifyOnStateExitting()
+ notifyOnStateExited()
+ disposeStateAndDisconnect Signals()
+ notifyOnRuntimeConfiguration Finished()
+ getCurrentStateCounter()
+ getCurrentState()
+ getStateMachineInfo()
+ buildStateMachineInfo()
+ getNode()
+ getLLogger()
+ getMutex()
# checkStateMachineConsistence()
# initializeROS()
# onInitialized()
# createOrthogonal()
- propagateEventToStateReactors()
- updateStatusMessage()
double
thread
vector< smacc2::ISmaccUpdatable * >
atomic< bool >
atomic< unsigned long >
processor_handle
SmaccFifoScheduler *
-sub_
-loop_rate_hz
-signalDetectorThread_
-updatableClients_
-updatableStateElements_
-end_
-initialized_
-lastState_
-processorHandle_
-scheduler_
-timeoutTimer_
boost::signals2::signal < Signature, optional _last_value= typename boost ::function_traits< Signature >::result_type >, int_std ::less< int >, function< Signature >, typename extended_signature< function_traits< Signature >::arity, Signature >::function_type, boost:: signals2::mutex >
vector< std::shared _ptr< smacc2::ISmaccClient Behavior > >
vector< std::shared _ptr< smacc2::ISmaccClient > >
-signalDetector_
-smaccStateMachine_
-stateMachine_
-clientBehaviors_
#clients_
smacc2::SignalDetector
+ SignalDetector()
+ initialize()
+ setProcessorHandle()
+ runThread()
+ join()
+ stop()
+ pollingLoop()
+ pollOnce()
+ postEvent()
+ getNode()
+ getLogger()
- findUpdatableClientsAndComponents()
- findUpdatableStateElements()
smacc2::ISmaccOrthogonal
+ setStateMachine()
+ getStateMachine()
+ addClientBehavior()
+ runtimeConfigure()
+ onEntry()
+ onExit()
+ getName()
+ requiresComponent()
+ requiresClient()
+ getClients()
+ getClientBehaviors()
+ setGlobalSMData()
+ getGlobalSMData()
+ getClientBehavior()
+ getNode()
+ getLLogger()
# onInitialize()
# initializeClients()
# assignClientToOrthogonal()
boost::signals2::signal < void(), optional_last _value< typename boost:: function_traits< void() > ::result_type >, int_std ::less< int >, function< void () >, typename extended_signature < function_traits< void() >::arity, void() >::function_type, boost::signals2::mutex >
map< smacc2::ComponentKey, std::shared_ptr< smacc2 ::ISmaccComponent > >
smacc2::SmaccSignal < Signature, Combiner, Group, GroupCompare, SlotFunction, ExtendedSlotFunction, Mutex >
boost::signals2::signal < void(const MessageType &) , optional_last_value <typename boost::function _traits<void(const MessageType &) > ::result_type>, int_std ::less<int > , function<void(const MessageType &) >::function_type , boost::signals2::mutex >
-stateMachine_
#components_
< void()>
< void(const MessageType &)>
-orthogonal_
smacc2::ISmaccClient
+ ISmaccClient()
+ ~ISmaccClient()
+ onInitialize()
+ getName()
+ getComponent()
+ getComponent()
+ getComponent()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
+ getComponents()
+ postEvent()
+ postEvent()
# onOrthogonalAllocation()
# createComponent()
# createNamedComponent()
# getNode()
# getLogger()
- initialize()
- setStateMachine()
- setOrthogonal()
smacc2::SmaccSignal < void()>
optional< std::string >
function< void(const MessageType &)>
optional< int >
smacc2::SmaccSignal < void(const MessageType &)>
bool
+topicName
+postInitialMessageEvent
+postMessageEvent
+queueSize
+onFirstMessageReceived
+onMessageReceived_
-firstMessage_
-initialized_
smacc2::client_bases ::SmaccSubscriberClient < MessageType >
+ SmaccSubscriberClient()
+ SmaccSubscriberClient()
+ ~SmaccSubscriberClient()
+ onMessageReceived()
+ onFirstMessageReceived()
+ onOrthogonalAllocation()
# onInitialize()
- messageCallback()
+onMessageTimeout_
-initialized_
function< void()>
optional< rclcpp::Duration >
+postTimeoutMessageEvent
+timeout_
cl_multirole_sensor ::ClMultiroleSensor < MessageType >
+ ClMultiroleSensor()
+ onMessageTimeout()
+ onOrthogonalAllocation()
+ onInitialize()
# resetTimer()
- timeoutCallback()