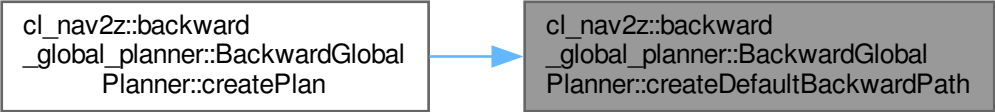


cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::createPlan



```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createPlan"] --> B["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createDefaultBackwardPath"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl_nav2z::backward', '_global_planner::BackwardGlobal', and 'Planner::createPlan' on three lines. The right box is gray with a black border and contains the text 'cl_nav2z::backward', '_global_planner::BackwardGlobal', and 'Planner::createDefaultBackwardPath' on three lines.

cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::createDefaultBackwardPath