smacc2::ISmaccClientBehavior stateMachine currentState - currentOrthogonal + ISmaccClientBehavior() + ~ISmaccClientBehavior() + getStateMachine() + getName() + requiresClient() + requiresComponent() + onEntry() + onExit() + executeOnEntry() + executeOnExit() # runtimeConfigure() # postEvent() # postEvent() # getCurrentState() # dispose() # getNode() # getLogger() onOrthogonalAllocation() smacc2::ISmaccUpdatable periodDuration smacc2::SmaccClientBehavior lastUpdate + ISmaccUpdatable() + ISmaccUpdatable() onEntry() + onExit() + executeUpdate() + setUpdatePeriod() + # update() cl ros publisher::CbDefault PublishLoop - deferedPublishFn - client + CbDefaultPublishLoop() + CbDefaultPublishLoop() + setMessage() + onEntry() + update() + onExit()