smacc2::ISmaccComponent

stateMachine_
owner_

+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresClient()
# createSiblingComponent()
# createSiblingNamedComponent()
# getNode()
# getLogger()
# getStateMachine()
- initialize()
- setStateMachine()

smacc2::components ::CpTopicPublisher< MessageType >

+ queueSize
+ durability
+ reliability
- pub_
- initialized_
- topicName_

+ CpTopicPublisher()
+ ~CpTopicPublisher()
+ publish()
+ onInitialize()

< geometry_msgs::msg ::PoseWithCovarianceStamped >

< geometry_msgs::msg ::PoseStamped >

< std_msgs::msg::Int8 >

smacc2::components ::CpTopicPublisher< geometry_msgs::msg:: PoseWithCovarianceStamped >

+ queueSize
+ durability
+ reliability
- pub_
- initialized_
- topicName_

+ CpTopicPublisher()
+ ~CpTopicPublisher()
+ publish()
+ onInitialize()

smacc2::components ::CpTopicPublisher< geometry_msgs::msg:: PoseStamped >

+ queueSize
+ durability
+ reliability
- pub_
- initialized_
- topicName_

+ CpTopicPublisher()
+ ~CpTopicPublisher()
+ publish()
+ onInitialize()

smacc2::components ::CpTopicPublisher< std_msgs::msg::Int8 >

+ queueSize
+ durability
+ reliability
- pub_
- initialized_
- topicName_

+ CpTopicPublisher()
+ ~CpTopicPublisher()
+ publish()
+ onInitialize()