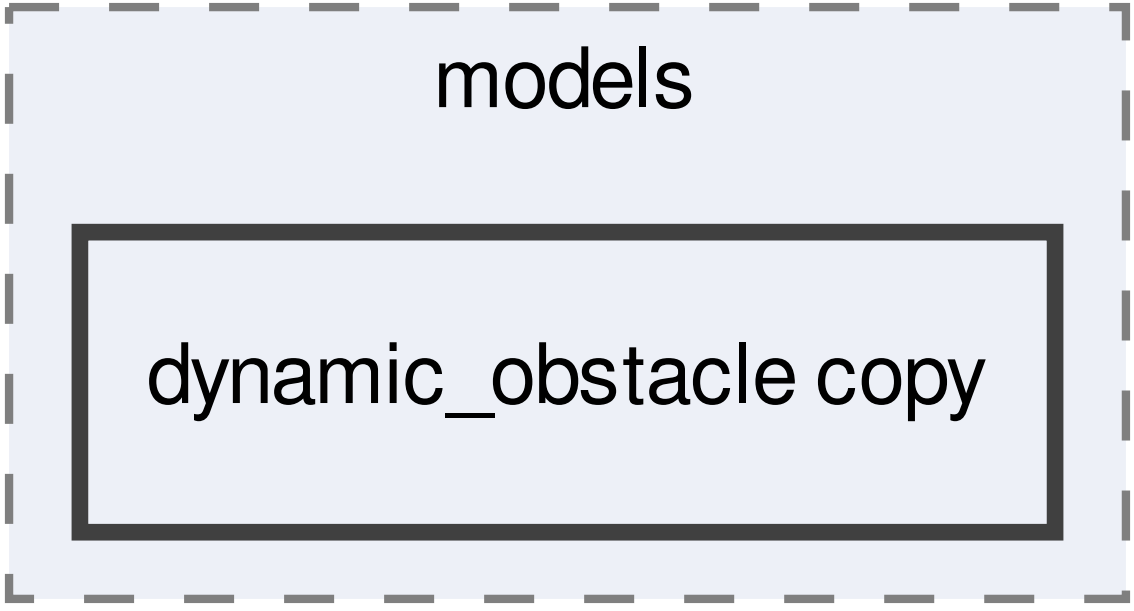
models
dynamic_obstacle copy