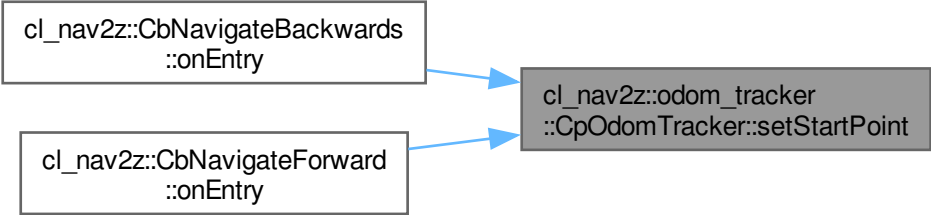


cl\_nav2z::CbNavigateBackwards  
::onEntry

cl\_nav2z::CbNavigateForward  
::onEntry

cl\_nav2z::odom\_tracker  
::CpOdomTracker::setStartPoint



```
graph LR; A[cl_nav2z::CbNavigateBackwards::onEntry] --> C[cl_nav2z::odom_tracker::CpOdomTracker::setStartPoint]; B[cl_nav2z::CbNavigateForward::onEntry] --> C;
```

The diagram illustrates a callout structure. On the left, there are two white rectangular boxes with black borders. The top box contains the text 'cl\_nav2z::CbNavigateBackwards::onEntry' and the bottom box contains 'cl\_nav2z::CbNavigateForward::onEntry'. On the right, there is a gray rectangular box with a black border containing the text 'cl\_nav2z::odom\_tracker::CpOdomTracker::setStartPoint'. Two blue arrows point from the right side of the top white box and the right side of the bottom white box to the left side of the gray box, indicating that both functions call the 'setStartPoint' method of the 'CpOdomTracker' class within the 'odom\_tracker' namespace of 'cl\_nav2z'.