

```
image_tools::ROSCvMatContainer  
::get_sensor_msgs_msg_image  
_pointer_copy
```



A diagram illustrating a pointer relationship. A blue arrow points from the left box to the right box. The left box is white with a black border, and the right box is gray with a black border. Both boxes contain text representing a C++ object and a method call.

```
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::get_sensor_msgs_msg_image_copy
```