

cl\_moveit2z::CbExecuteLast  
Trajectory::onEntry

cl\_moveit2z::CbMoveEndEffector  
Trajectory::onEntry

cl\_moveit2z::CbUndoLastTrajectory  
::onEntry

cl\_moveit2z::CbMoveEndEffector  
Trajectory::executeJointSpaceTrajectory

```
graph LR; A[cl_moveit2z::CbExecuteLastTrajectory::onEntry] --> D[cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory]; B[cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry] --> D; C[cl_moveit2z::CbUndoLastTrajectory::onEntry] --> D;
```

The diagram illustrates a call graph where three functions from the `cl_moveit2z` namespace serve as entry points to a single target function. The source functions are `cl_moveit2z::CbExecuteLastTrajectory::onEntry`, `cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry`, and `cl_moveit2z::CbUndoLastTrajectory::onEntry`. Each of these functions is shown in a white box with a black border. Blue arrows originate from the right side of each source box and point towards the target box. The target function, `cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory`, is located to the right of the source functions and is highlighted with a gray background and a black border.