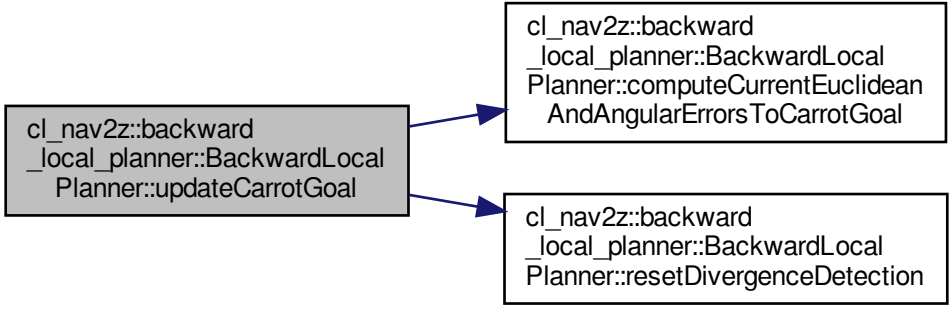
cl_nav2z::backward
_local_planner::BackwardLocal
Planner::updateCarrotGoal
cl_nav2z::backward
_local_planner::BackwardLocal
Planner::computeCurrentEuclidean
AndAngularErrorsToCarrotGoal
cl_nav2z::backward
_local_planner::BackwardLocal
Planner::resetDivergenceDetection