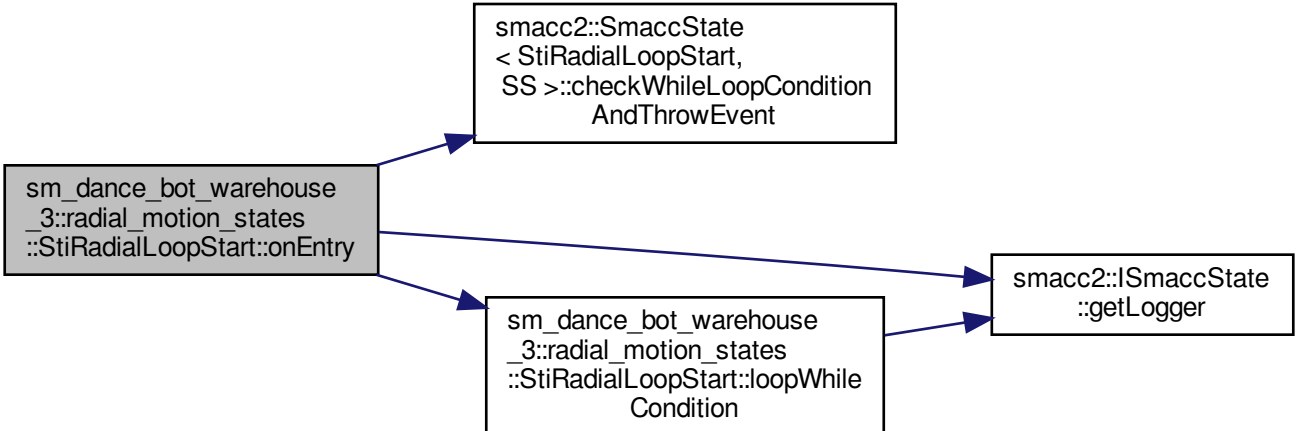
sm_dance_bot_warehouse
_3::radial_motion_states
::StiRadialLoopStart::onEntry
smacc2::SmaccState
< StiRadialLoopStart,
SS >::checkWhileLoopCondition
AndThrowEvent
sm_dance_bot_warehouse
_3::radial_motion_states
::StiRadialLoopStart::loopWhile
Condition
smacc2::ISmaccState
::getLogger