

cl\_nav2z::backward  
\_global\_planner::BackwardGlobal  
Planner::createDefaultBackwardPath

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graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createDefaultBackwardPath"] --> B["cl_nav2z::makePureSpinning  
SubPlan"]; A --> C["cl_nav2z::makePureStraight  
SubPlan"]
```

cl\_nav2z::makePureSpinning  
SubPlan

cl\_nav2z::makePureStraight  
SubPlan