smacc2::ISmaccComponent

stateMachine_
owner_

+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresComponent()
# requiresClient()
# createSiblingComponent()
# createSiblingNamedComponent()
# getNode()
# getLogger()
# getStateMachine()
- initialize()
- setStateMachine()

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sm_dance_bot_warehouse ::cl_nav2z::CpSquareShapeBoundary

+ squareLenghtMeters_
+ robotPose_

+ CpSquareShapeBoundary()
+ onInitialize()
+ getForwardDistance()