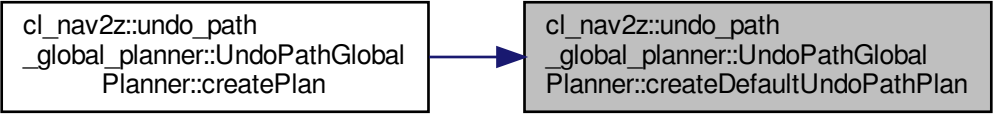


cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::createPlan



```
graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::createPlan"] --> B["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::createDefaultUndoPathPlan"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a white background and a black border, containing the text 'cl_nav2z::undo_path', '_global_planner::UndoPathGlobal', and 'Planner::createPlan' on three lines. The right box has a light gray background and a black border, containing the text 'cl_nav2z::undo_path', '_global_planner::UndoPathGlobal', and 'Planner::createDefaultUndoPathPlan' on three lines. A blue arrow points from the right side of the left box to the left side of the right box.

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::createDefaultUndoPathPlan