

cl\_nav2z::CpWaypointNavigator  
::onGoalAborted



```
graph LR; A[cl_nav2z::CpWaypointNavigator::onGoalAborted] --> B[cl_nav2z::CpWaypointNavigator::stopWaitingResult]
```

cl\_nav2z::CpWaypointNavigator  
::stopWaitingResult