

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::divergenceDetectionUpdate
```



A diagram showing a call sequence. On the left, a gray-shaded rectangular box contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::divergenceDetectionUpdate'. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::computeCurrentEuclideanAndAngularErrors ToCarrotGoal'.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```