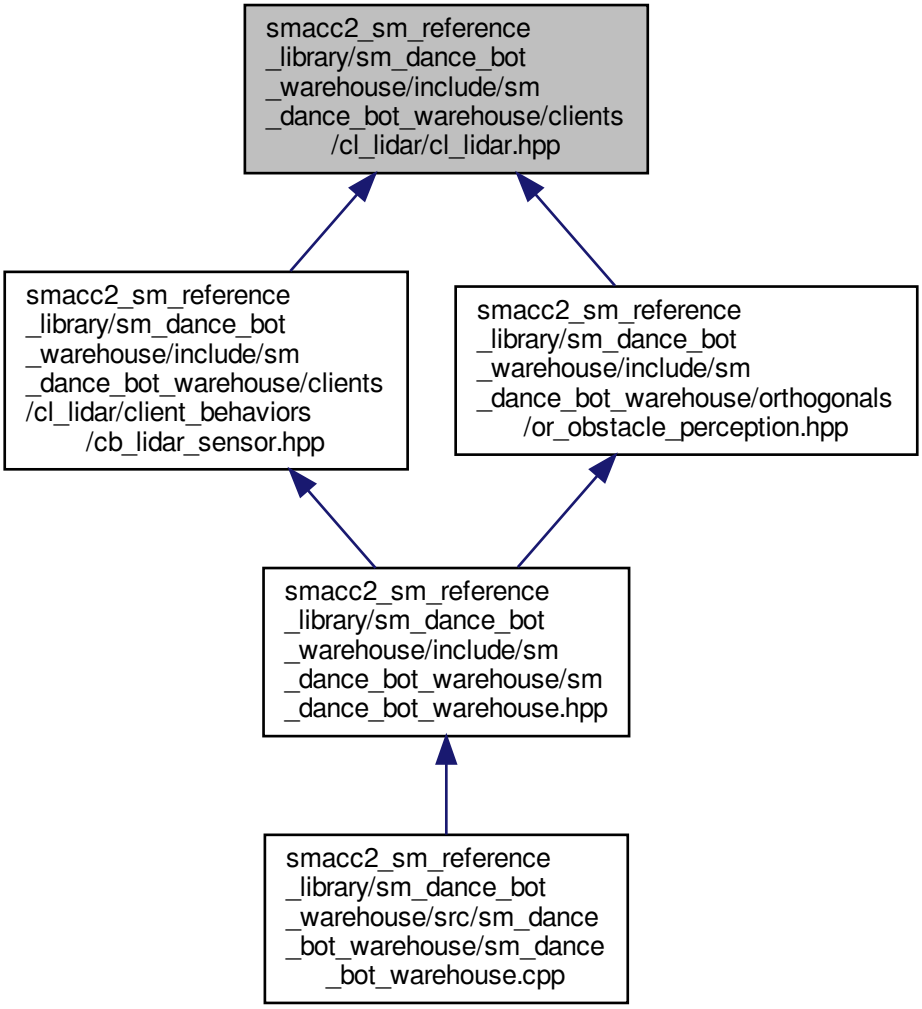
smacc2_sm_reference
_library/sm_dance_bot
_warehouse/include/sm
_dance_bot_warehouse/clients
/cl_lidar/cl_lidar.hpp
smacc2_sm_reference
_library/sm_dance_bot
_warehouse/include/sm
_dance_bot_warehouse/clients
/cl_lidar/client_behaviors
/cb_lidar_sensor.hpp
smacc2_sm_reference
_library/sm_dance_bot
_warehouse/include/sm
_dance_bot_warehouse/orthogonals
/or_obstacle_perception.hpp
smacc2_sm_reference
_library/sm_dance_bot
_warehouse/include/sm
_dance_bot_warehouse/sm
_dance_bot_warehouse.hpp
smacc2_sm_reference
_library/sm_dance_bot
_warehouse/src/sm_dance
_bot_warehouse/sm_dance
_bot_warehouse.cpp