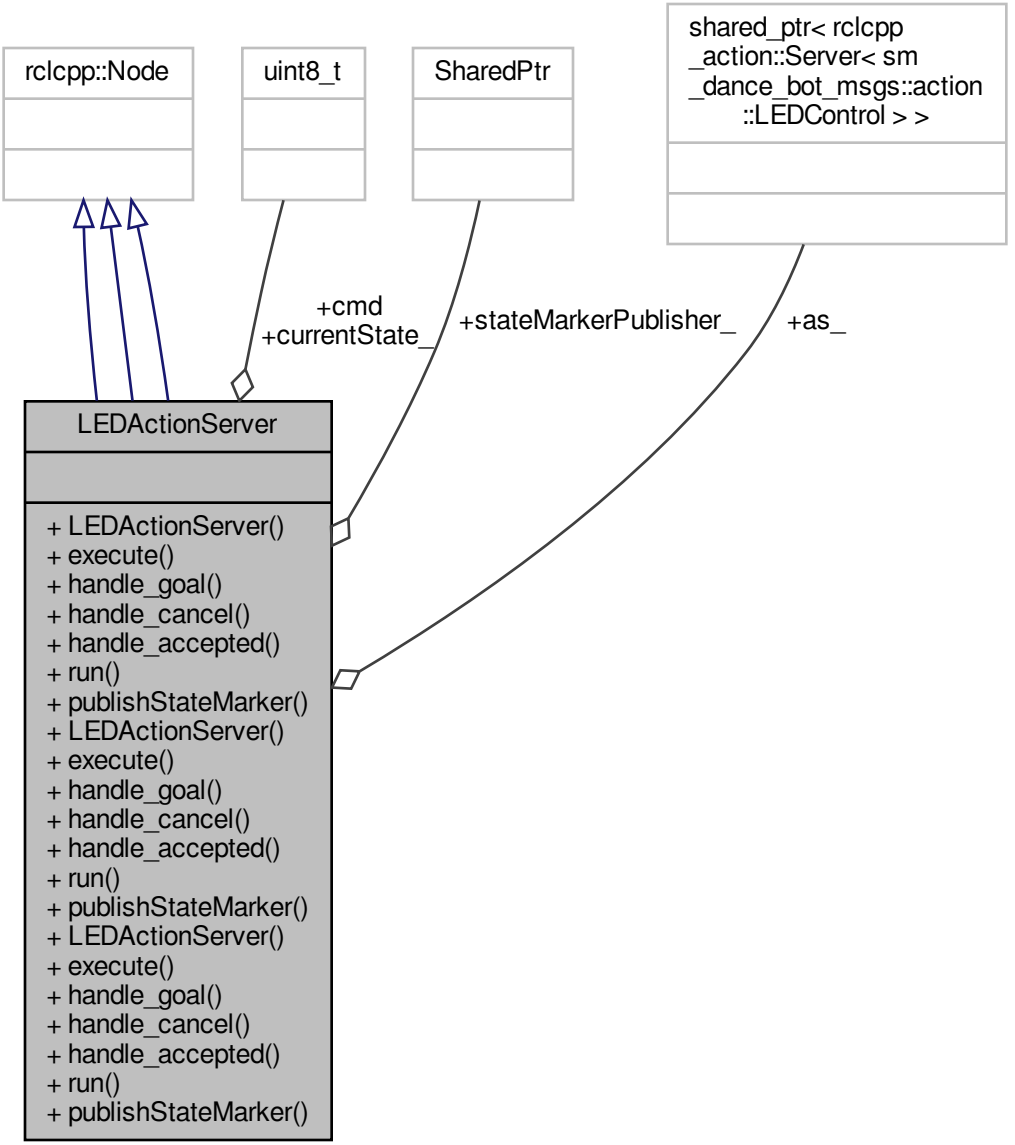
rclcpp::Node
uint8_t
SharedPtr
shared_ptr< rclcpp _action::Server< sm _dance_bot_msgs::action ::LEDControl > >
+cmd
+currentState_
+stateMarkerPublisher_
+as_
LEDActionServer
+ LEDActionServer()
+ execute()
+ handle_goal()
+ handle_cancel()
+ handle_accepted()
+ run()
+ publishStateMarker()
+ LEDActionServer()
+ execute()
+ handle_goal()
+ handle_cancel()
+ handle_accepted()
+ run()
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