

cl\_nav2z::WaypointNavigator  
::onGoalAborted



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graph LR; A[cl_nav2z::WaypointNavigator::onGoalAborted] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
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The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl\_nav2z::WaypointNavigator' followed by '::onGoalAborted' on a new line. The right box is white with a black border and contains the text 'cl\_nav2z::WaypointNavigator' followed by '::stopWaitingResult' on a new line. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_nav2z::WaypointNavigator  
::stopWaitingResult