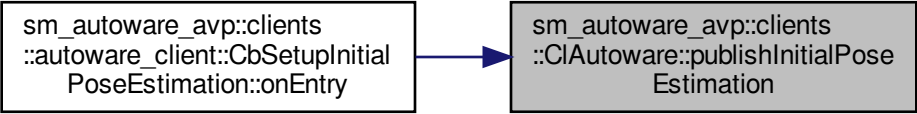


sm\_aware\_avp::clients  
::aware\_client::CbSetupInitial  
PoseEstimation::onEntry



```
graph LR; A["sm_aware_avp::clients  
::aware_client::CbSetupInitial  
PoseEstimation::onEntry"] --> B["sm_aware_avp::clients  
::ClAware::publishInitialPose  
Estimation"]
```

sm\_aware\_avp::clients  
::ClAware::publishInitialPose  
Estimation