```
smacc2::ISmaccClientBehavior
        stateMachine
        currentState
       currentOrthogonal
    + ISmaccClientBehavior()
       ~ISmaccClientBehavior()
    + getStateMachine()
      getName()
    + requiresClient()
       requiresComponent()
    + onEntry()
       onExit()
    + executeOnEntry()
      executeOnExit()
    # runtimeConfigure()
     # postEvent()
    # postEvent()
    #
       getCurrentState()
    # dispose()
     #
       getNode()
     # getLogger()
        onOrthogonalAllocation()
     smacc2::SmaccAsyncClient
              Behavior

    onEntryThread_

    onExitThread

    postFinishEventFn_

    postSuccessEventFn_

    postFailureEventFn_

    onFinished

    onSuccess

    - onFailure
   - isShutdownRequested
   + onOrthogonalAllocation()
   + ~SmaccAsyncClientBehavior()
   + onSuccess()
   + onFinished()
   + onFailure()
   + requestForceFinish()
   + executeOnEntry()
   + executeOnExit()
   + waitOnEntryThread()
   + onSuccess()
   + onFinished()
   + onFailure()
   # postSuccessEvent()
   # postFailureEvent()
   # dispose()
   # isShutdownRequested()
   waitFutureIfNotFinished()
cl_nav2z::CbNav2ZClientBehaviorBase
 # nav2zClient
 #
    navigationCallback_
 # navigationResult_
 # goalHandleFuture
   ~CbNav2ZClientBehaviorBase()
 +
    onOrthogonalAllocation()
 +
 # sendGoal()
   cancelGoal()
 #
 # isOwnActionResponse()
 #
   onNavigationResult()
 # onNavigationActionSuccess()
 #
    onNavigationActionAbort()
     cl_nav2z::CbAbsoluteRotate
+ listener
+ absoluteGoalAngleDegree
+ yawGoalTolerance
+ maxVelTheta
+ spinningPlanner
- oldYawTolerance
- oldMaxVelTheta
- oldMinVelTheta
+ CbAbsoluteRotate()
+ CbAbsoluteRotate()
+ onEntry()
+ onExit()
- updateTemporalBehaviorParameters()
      cl_nav2z::CbRotateLookAt
           listener
           lookAtPose
```

+ CbRotateLookAt() CbRotateLookAt()

+ onEntry()

+