

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains three lines of C++ code. The right box is white with a black border and contains three lines of C++ code. A blue arrow points from the right side of the left box to the left side of the right box, indicating a call or relationship between the two code blocks.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```