

cl_move_base_z::CbWaitPose
::onEntry



```
graph LR; A[cl_move_base_z::CbWaitPose::onEntry] --> B[cl_move_base_z::Pose::waitTransformUpdate];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'cl_move_base_z::CbWaitPose::onEntry'. The right box is gray with a black border and contains the text 'cl_move_base_z::Pose::waitTransformUpdate'. A blue arrow points from the right side of the left box to the left side of the right box.

cl_move_base_z::Pose
::waitTransformUpdate