


```
rcldcpp::TypeAdapter  
< image_tools::ROSCvMatContainer,  
  sensor_msgs::msg::Image >  
  ::convert_to_ros_message
```



A diagram illustrating a mapping between a C++ TypeAdapter and a ROS header. On the left, a white rectangular box with a black border contains the C++ code for a TypeAdapter. A blue arrow points from this box to a gray rectangular box on the right, which contains the corresponding ROS header name.

```
image_tools::ROSCvMatContainer  
  ::header
```