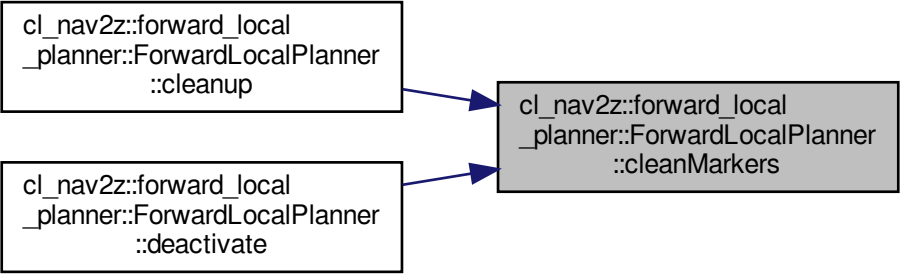


cl_nav2z::forward_local
_planner::ForwardLocalPlanner
::cleanup

cl_nav2z::forward_local
_planner::ForwardLocalPlanner
::deactivate

cl_nav2z::forward_local
_planner::ForwardLocalPlanner
::cleanMarkers



```
graph LR; A["cl_nav2z::forward_local_planner::ForwardLocalPlanner::cleanup"] --> C["cl_nav2z::forward_local_planner::ForwardLocalPlanner::cleanMarkers"]; B["cl_nav2z::forward_local_planner::ForwardLocalPlanner::deactivate"] --> C;
```

The diagram illustrates a call graph where two source functions, `cl_nav2z::forward_local_planner::ForwardLocalPlanner::cleanup` and `cl_nav2z::forward_local_planner::ForwardLocalPlanner::deactivate`, both point to a common target function, `cl_nav2z::forward_local_planner::ForwardLocalPlanner::cleanMarkers`. The source nodes are white boxes, and the target node is a gray box. Blue arrows indicate the direction of the calls.