

cl\_nav2z::CbRotateLookAt  
::onEntry

cl\_nav2z::CbWaitPose  
::onEntry

cl\_nav2z::Pose::waitTransform  
Update

```
graph LR; A[cl_nav2z::CbRotateLookAt::onEntry] --> C[cl_nav2z::Pose::waitTransform Update]; B[cl_nav2z::CbWaitPose::onEntry] --> C;
```

The diagram illustrates a dependency or call sequence. Two white rectangular boxes on the left represent callback functions: 'cl\_nav2z::CbRotateLookAt::onEntry' (top) and 'cl\_nav2z::CbWaitPose::onEntry' (bottom). Blue arrows point from each of these boxes to a single gray rectangular box on the right, labeled 'cl\_nav2z::Pose::waitTransform Update'. This indicates that both callbacks trigger or depend on the same pose update process.