

cl_moveit2z::CbExecuteLast
Trajectory::onEntry

cl_moveit2z::CbMoveEndEffector
Trajectory::onEntry

cl_moveit2z::CbUndoLastTrajectory
::onEntry

cl_moveit2z::CbMoveEndEffector
Trajectory::executeJointSpaceTrajectory

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graph LR; A[cl_moveit2z::CbExecuteLastTrajectory::onEntry] --> D[cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory]; B[cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry] --> D; C[cl_moveit2z::CbUndoLastTrajectory::onEntry] --> D;
```

The diagram illustrates a flow where three separate entry functions from the `cl_moveit2z` namespace are directed towards a single execution function. The source functions are `cl_moveit2z::CbExecuteLastTrajectory::onEntry`, `cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry`, and `cl_moveit2z::CbUndoLastTrajectory::onEntry`. These are represented by white boxes with black borders. Blue arrows point from each of these boxes to a central gray box with a black border, which represents the target function `cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory`.