

cl_moveit2z::CbExecuteLast
Trajectory::onEntry

cl_moveit2z::CbMoveEndEffector
Trajectory::onEntry

cl_moveit2z::CbUndoLastTrajectory
::onEntry

cl_moveit2z::CbMoveEndEffector
Trajectory::executeJointSpaceTrajectory

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graph LR; A[cl_moveit2z::CbExecuteLastTrajectory::onEntry] --> D[cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory]; B[cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry] --> D; C[cl_moveit2z::CbUndoLastTrajectory::onEntry] --> D;
```

The diagram illustrates a call graph where three functions from the `cl_moveit2z` namespace serve as entry points to a single target function. The source functions are `cl_moveit2z::CbExecuteLastTrajectory::onEntry`, `cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry`, and `cl_moveit2z::CbUndoLastTrajectory::onEntry`. Each of these functions is shown in a white box with a black border. Blue arrows originate from the right side of each source box and point towards the target box. The target box, `cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory`, is shaded gray and is positioned to the right of the source boxes. The arrows indicate that all three source functions eventually lead to the execution of the joint space trajectory.