```
smacc2::ISmaccClientBehavior
   stateMachine
   currentState
  currentOrthogonal
   ISmaccClientBehavior()
+
   ~ISmaccClientBehavior()
+ getStateMachine()
 + getName()
+ requiresClient()
   requiresComponent()
+ onEntry()
+ onExit()
+ executeOnEntry()
   executeOnExit()
#
   runtimeConfigure()
# postEvent()
# postEvent()
# getCurrentState()
# dispose()
# getNode()
# getLogger()
   onOrthogonalAllocation()
smacc2::SmaccClientBehavior
           onEntry()
           onExit()
    cl ros_timer::CbTimer

    timerClient

    postTimerEvent

+ onEntry()
```

+ onEntry()

+ onEntry() + onExit()

+ onOrthogonalAllocation()+ onClientTimerTickCallback()

+ onOrthogonalAllocation()+ onClientTimerTickCallback()