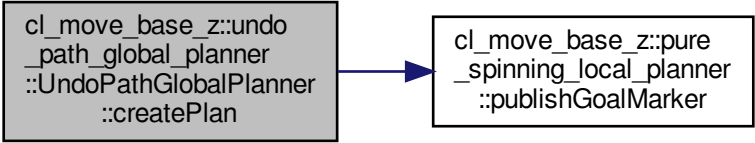


```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::createPlan
```



The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray background and a black border, containing the text 'cl_move_base_z::undo', '_path_global_planner', '::UndoPathGlobalPlanner', and '::createPlan'. The right box has a white background and a black border, containing the text 'cl_move_base_z::pure', '_spinning_local_planner', and '::publishGoalMarker'. A blue arrow points from the right side of the left box to the left side of the right box.

```
cl_move_base_z::pure  
_spinning_local_planner  
::publishGoalMarker
```