

```
sm_dance_bot_warehouse  
::OrNavigation::onInitialize
```



```
graph LR; A[sm_dance_bot_warehouse::OrNavigation::onInitialize] --> B[sm_dance_bot_warehouse::OrNavigation::loadWaypointsFromYaml];
```

A diagram showing a call from the `onInitialize` method to the `loadWaypointsFromYaml` method. The source box is white with a black border, and the target box is gray with a black border. A blue arrow points from the source to the target.

```
sm_dance_bot_warehouse  
::OrNavigation::loadWaypoints  
FromYaml
```