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                    ┌─────────────────────┐
                    │   rclcpp::Node      │
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LEDActionServer
+ as_
+ stateMarkerPublisher_
+ cmd
+ currentState_
+ as_
+ as_
+ as_
+ LEDActionServer()
+ execute()
+ handle_goal()
+ handle_cancel()
+ handle_accepted()
+ run()
+ publishStateMarker()
+ LEDActionServer()
+ execute()
+ handle_goal()
+ handle_cancel()
+ handle_accepted()
+ run()
+ publishStateMarker()
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