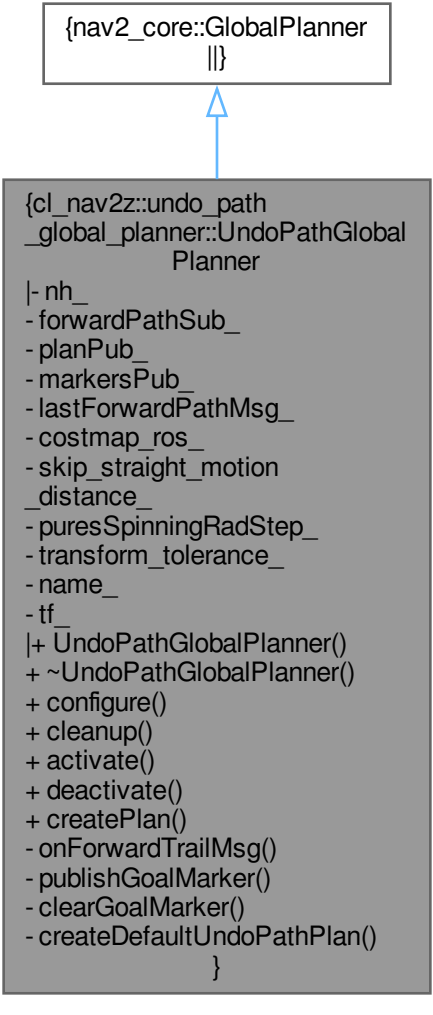
{nav2_core::GlobalPlanner
||}
{cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner
|- nh_
- forwardPathSub_
- planPub_
- markersPub_
- lastForwardPathMsg_
- costmap_ros_
- skip_straight_motion
distance
- puresSpinningRadStep_
- transform_tolerance_
- name_
- tf_
|+ UndoPathGlobalPlanner()
+ ~UndoPathGlobalPlanner()
+ configure()
+ cleanup()
+ activate()
+ deactivate()
+ createPlan()
- onForwardTrailMsg()
- publishGoalMarker()
- clearGoalMarker()
- createDefaultUndoPathPlan()
}