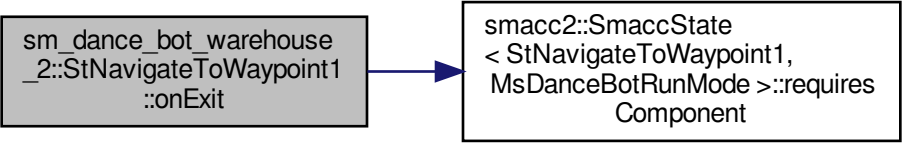


```
sm_dance_bot_warehouse  
_2::StNavigateToWaypoint1  
::onExit
```



```
graph LR; A["sm_dance_bot_warehouse  
_2::StNavigateToWaypoint1  
::onExit"] --> B["smacc2::SmaccState  
< StNavigateToWaypoint1,  
MsDanceBotRunMode >::requires  
Component"]
```

```
smacc2::SmaccState  
< StNavigateToWaypoint1,  
MsDanceBotRunMode >::requires  
Component
```