

cl_move_group_interface
::CbExecuteLastTrajectory
::onEntry

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::onEntry

cl_move_group_interface
::CbUndoLastTrajectory
::onEntry

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::executeJointSpaceTrajectory

```
graph LR; A["cl_move_group_interface  
::CbExecuteLastTrajectory  
::onEntry"] --> D["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::executeJointSpaceTrajectory"]; B["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::onEntry"] --> D; C["cl_move_group_interface  
::CbUndoLastTrajectory  
::onEntry"] --> D;
```

The diagram illustrates a mapping or inheritance relationship. Three source boxes on the left, each containing a function name and its entry point, have arrows pointing to a single target box on the right. The target box contains a function name and two entry points. The source boxes are: 1) 'cl_move_group_interface ::CbExecuteLastTrajectory ::onEntry', 2) 'cl_move_group_interface ::CbMoveEndEffectorTrajectory ::onEntry', and 3) 'cl_move_group_interface ::CbUndoLastTrajectory ::onEntry'. The target box is 'cl_move_group_interface ::CbMoveEndEffectorTrajectory ::executeJointSpaceTrajectory'.