

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::activate

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::computeVelocityCommands

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::updateParameters

```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::activate"] --> C["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::updateParameters"]; B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeVelocityCommands"] --> C;
```

The diagram illustrates a flow of control or data from two source functions to a target function. The source functions are 'cl_nav2z::backward _local_planner::BackwardLocal Planner::activate' and 'cl_nav2z::backward _local_planner::BackwardLocal Planner::computeVelocityCommands'. Both source functions have arrows pointing to the target function 'cl_nav2z::backward _local_planner::BackwardLocal Planner::updateParameters'. The target function box is shaded gray, while the source function boxes are white.