

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



A diagram showing a call sequence. A blue arrow points from the right side of the first box to the left side of the second box. The first box is shaded gray and contains the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::findInitialCarrotGoal'. The second box is white with a black border and contains the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::computeCurrentEuclideanAndAngularErrors ToCarrotGoal'.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```