```
nav2 core::GlobalPlanner
cl move base z::forward
 global planner::ForwardGlobal
           Planner
- nh
- planPub
- costmap ros
- skip_straight_motion
distance
- puresSpinningRadStep
- name
- transform tolerance
- tf
+ ForwardGlobalPlanner()
+ ~ForwardGlobalPlanner()
+ configure()
+ cleanup()
+ activate()
+ deactivate()
+ createPlan()
```