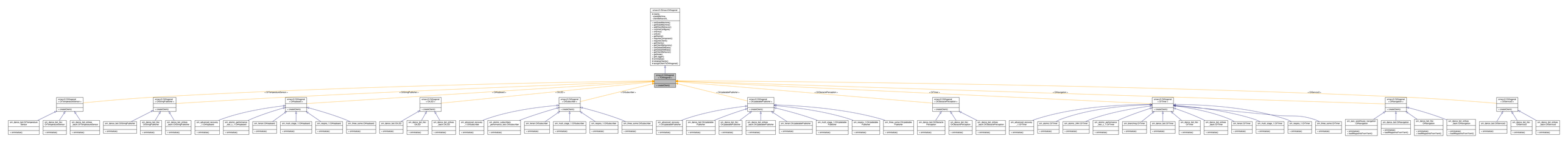

smacc2::ISmaccOrthogonal
# clients_
- stateMachine_
- clientBehaviors_
+ setStateMachine()
+ getStateMachine()
+ addClientBehavior()
+ runtimeConfigure()
+ onEntry()
+ onExit()
+ getName()
+ requiresComponent()
+ requiresClient()
+ getClients()
+ getClientBehaviors()
+ setGlobalSMData()
+ getGlobalSMData()
+ getClientBehavior()
+ getNode()
+ getLogger()
# onInitialize()
# initializeClients()
# assignClientToOrthogonal()
smacc2::Orthogonal < TOrthogonal >
+ createClient()
< OrTemperatureSensor >
< OrStringPublisher >
< OrKeyboard >
< OrLED >
< OrSubscriber >
< OrUpdatablePublisher >
< OrObstaclePerception >
< OrTimer >
< OrNavigation >
< OrService3 >
smacc2::Orthogonal < OrTemperatureSensor >
+ createClient()
sm_dance_bot::OrTemperature Sensor
+ onInitialize()
sm_dance_bot_lite:: OrTemperatureSensor
+ onInitialize()
sm_dance_bot_strikes _back::OrTemperatureSensor
+ onInitialize()
smacc2::Orthogonal < OrStringPublisher >
+ createClient()
sm_dance_bot::OrStringPublisher
+ onInitialize()
sm_dance_bot_lite:: OrStringPublisher
+ onInitialize()
sm_dance_bot_strikes _back::OrStringPublisher
+ onInitialize()
smacc2::Orthogonal < OrKeyboard >
+ createClient()
sm_advanced_recovery _1::OrKeyboard
+ onInitialize()
sm_atomic_performance _test_c_1::OrKeyboard
+ onInitialize()
sm_ferrari::OrKeyboard
+ onInitialize()
sm_multi_stage_1::OrKeyboard
+ onInitialize()
sm_respira_1::OrKeyboard
+ onInitialize()
sm_three_some::OrKeyboard
+ onInitialize()
smacc2::Orthogonal < OrLED >
+ createClient()
sm_dance_bot::OrLED
+ onInitialize()
sm_dance_bot_lite:: OrLED
+ onInitialize()
sm_dance_bot_strikes _back::OrLED
+ onInitialize()
smacc2::Orthogonal < OrSubscriber >
+ createClient()
sm_advanced_recovery _1::OrSubscriber
+ onInitialize()
sm_atomic_subscribers _performance_test::OrSubscriber
+ onInitialize()
sm_ferrari::OrSubscriber
+ onInitialize()
sm_multi_stage_1::OrSubscriber
+ onInitialize()
sm_respira_1::OrSubscriber
+ onInitialize()
sm_three_some::OrSubscriber
+ onInitialize()
smacc2::Orthogonal < OrUpdatablePublisher >
+ createClient()
sm_advanced_recovery _1::OrUpdatablePublisher
+ onInitialize()
sm_dance_bot::OrUpdatable Publisher
+ onInitialize()
sm_dance_bot_lite:: OrUpdatablePublisher
+ onInitialize()
sm_dance_bot_strikes _back::OrUpdatablePublisher
+ onInitialize()
sm_ferrari::OrUpdatablePublisher
+ onInitialize()
sm_multi_stage_1::OrUpdatable Publisher
+ onInitialize()
sm_respira_1::OrUpdatable Publisher
+ onInitialize()
sm_three_some::OrUpdatable Publisher
+ onInitialize()
smacc2::Orthogonal < OrObstaclePerception >
+ createClient()
sm_dance_bot::OrObstacle Perception
+ onInitialize()
sm_dance_bot_lite:: OrObstaclePerception
+ onInitialize()
sm_dance_bot_strikes _back::OrObstaclePerception
+ onInitialize()
smacc2::Orthogonal < OrTimer >
+ createClient()
sm_advanced_recovery _1::OrTimer
+ onInitialize()
sm_atomic::OrTimer
+ onInitialize()
sm_atomic_24hr::OrTimer
+ onInitialize()
sm_atomic_performance _test_c_1::OrTimer
+ onInitialize()
sm_branching::OrTimer
+ onInitialize()
sm_dance_bot::OrTimer
+ onInitialize()
sm_dance_bot_lite:: OrTimer
+ onInitialize()
sm_dance_bot_strikes _back::OrTimer
+ onInitialize()
sm_ferrari::OrTimer
+ onInitialize()
sm_multi_stage_1::OrTimer
+ onInitialize()
sm_respira_1::OrTimer
+ onInitialize()
sm_three_some::OrTimer
+ onInitialize()
smacc2::Orthogonal < OrNavigation >
+ createClient()
sm_aws_warehouse_navigation ::OrNavigation
+ onInitialize()
+ loadWaypointsFromYaml()
sm_dance_bot::OrNavigation
+ onInitialize()
+ loadWaypointsFromYaml()
sm_dance_bot_lite:: OrNavigation
+ onInitialize()
+ loadWaypointsFromYaml()
sm_dance_bot_strikes _back::OrNavigation
+ onInitialize()
+ loadWaypointsFromYaml()
smacc2::Orthogonal < OrService3 >
+ createClient()
sm_dance_bot::OrService3
+ onInitialize()
sm_dance_bot_lite:: OrService3
+ onInitialize()
sm_dance_bot_strikes _back::OrService3
+ onInitialize()