nav2 core::GlobalPlanner cl nav2z::backward global planner::BackwardGlobal **Planner** - nh - planPub - markersPub - costmap ros -skip straight motion distance - puresSpinningRadStep - name - tf - transform tolerance + BackwardGlobalPlanner() + ~BackwardGlobalPlanner() + configure() + cleanup() + activate() + deactivate() + createPlan() - onForwardTrailMsq() publishGoalMarker() - cleanMarkers() - createDefaultBackwardPath()