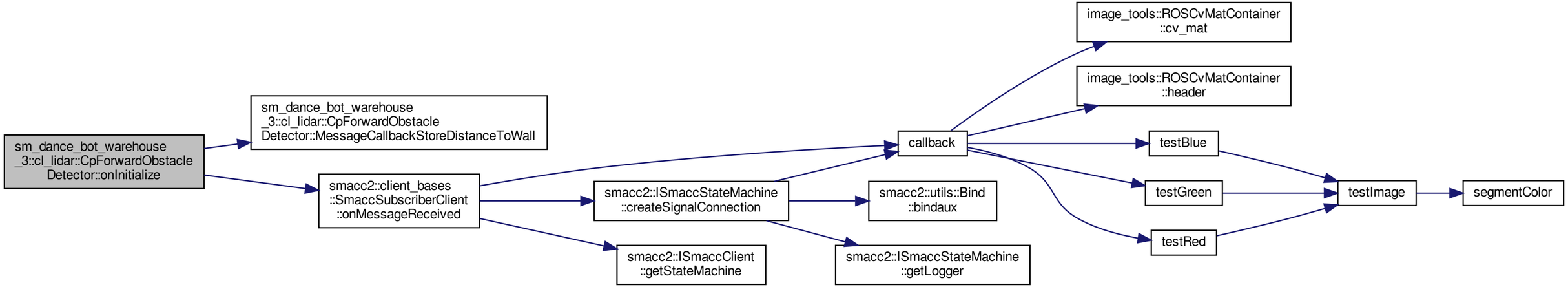
sm_dance_bot_warehouse
_3::cl_lidar::CpForwardObstacle
Detector::onInitialize
sm_dance_bot_warehouse
_3::cl_lidar::CpForwardObstacle
Detector::MessageCallbackStoreDistanceToWall
smacc2::client_bases
::SmaccSubscriberClient
::onMessageReceived
smacc2::ISmaccStateMachine
::createSignalConnection
smacc2::utils::Bind
::bindaux
smacc2::ISmaccClient
::getStateMachine
smacc2::ISmaccStateMachine
::getLogger
callback
image_tools::ROSCvMatContainer
::cv_mat
image_tools::ROSCvMatContainer
::header
testBlue
testGreen
testRed
testImage
segmentColor