```
                    rclcpp::Node



        LEDActionServer

    + as_
    + stateMarkerPublisher_
    + cmd
    + currentState_
    + as_
    + as_

    + LEDActionServer()
    + execute()
    + handle_goal()
    + handle_cancel()
    + handle_accepted()
    + run()
    + publishStateMarker()
    + LEDActionServer()
    + execute()
    + handle_goal()
    + handle_cancel()
    + handle_accepted()
    + run()
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    + run()
    + publishStateMarker()
```