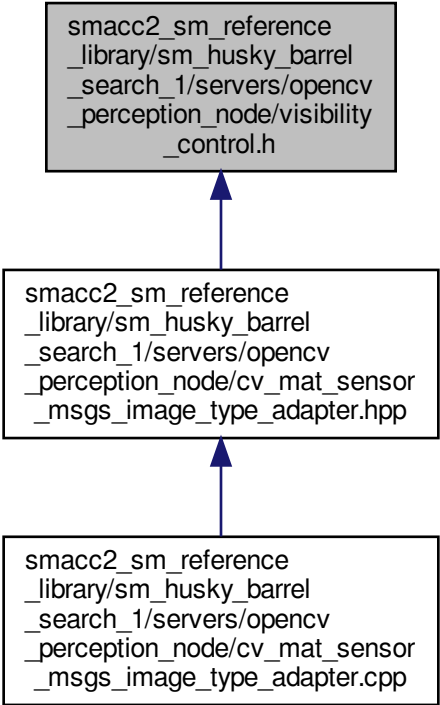


smacc2\_sm\_reference  
\_library/sm\_husky\_barrel  
\_search\_1/servers/opencv  
\_perception\_node/visibility  
\_control.h



```
graph BT; A["smacc2_sm_reference_library/sm_husky_barrel_search_1/servers/opencv_perception_node/cv_mat_sensor_msgs_image_type_adapter.cpp"] --> B["smacc2_sm_reference_library/sm_husky_barrel_search_1/servers/opencv_perception_node/cv_mat_sensor_msgs_image_type_adapter.hpp"]; B --> C["smacc2_sm_reference_library/sm_husky_barrel_search_1/servers/opencv_perception_node/visibility_control.h"];
```

smacc2\_sm\_reference  
\_library/sm\_husky\_barrel  
\_search\_1/servers/opencv  
\_perception\_node/cv\_mat\_sensor  
\_msgs\_image\_type\_adapter.hpp

smacc2\_sm\_reference  
\_library/sm\_husky\_barrel  
\_search\_1/servers/opencv  
\_perception\_node/cv\_mat\_sensor  
\_msgs\_image\_type\_adapter.cpp