

sm\_dance\_bot\_warehouse  
::radial\_motion\_states  
::StiRadialLoopStart::loopWhile  
Condition



```
graph LR; A["sm_dance_bot_warehouse  
::radial_motion_states  
::StiRadialLoopStart::loopWhile  
Condition"] --> B["smacc2::ISmaccState  
::getLogger"]
```

smacc2::ISmaccState  
::getLogger