

```
sm_dance_bot_strikes  
_back::radial_motion  
_states::StiRadialLoopStart  
::loopWhileCondition
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is light gray with a black border and contains four lines of C++ code. The right box is white with a black border and contains two lines of C++ code. The arrow originates from the right side of the left box and points to the left side of the right box.

```
smacc2::ISmaccState  
::getLogger
```