

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::computeVelocityCommands



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeVelocityCommands"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::updateCarrotGoal"]
```

The diagram illustrates a function call sequence. A light gray box on the left contains the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', and 'Planner::computeVelocityCommands'. A blue arrow points from this box to a darker gray box on the right. The darker gray box contains the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', and 'Planner::updateCarrotGoal'.

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::updateCarrotGoal