```
# components

    stateMachine

   - orthogonal
   + ISmaccClient()
   + ~ISmaccClient()
   + onInitialize()
   + getName()
   + getComponent()
   + getComponent()
   + getComponent()
   + getType()
   + getStateMachine()
   + connectSignal()
   + requiresClient()
   + getComponents()
   + postEvent()
   + postEvent()
   # onOrthogonalAllocation()
   # createComponent()
   # createNamedComponent()
   # getNode()
   # getLogger()
   initialize()
   setStateMachine()
   - setOrthogonal()
  smacc2::client_bases
  ::SmaccSubscriberClient
        < MessageType >
  + topicName
  + queueSize
  + onFirstMessageReceived_
  + onMessageReceived_
  + postMessageEvent
  + postInitialMessageEvent
  - sub
  firstMessage_

    initialized

  + SmaccSubscriberClient()
  + SmaccSubscriberClient()
  + ~SmaccSubscriberClient()
  + onMessageReceived()
  + onFirstMessageReceived()
  + onOrthogonalAllocation()
  # onInitialize()
   messageCallback()
                      cl_multirole_sensor
                      ::CIMultiroleSensor
                            < MessageType >
                      + onMessageTimeout
                      + postTimeoutMessageEvent
                      + timeout
                      timeoutTimer_

    initialized

                      + CIMultiroleSensor()
                      + onMessageTimeout()
                      + onOrthogonalAllocation()
                      + onInitialize()
                      # resetTimer()
                      timeoutCallback()
                            < sensor_msgs::msg
                              ::Temperature >
cl_multirole_sensor
::CIMultiroleSensor
< sensor_msgs::msg::Temperature >
+ onMessageTimeout
+ postTimeoutMessageEvent
+ timeout
- timeoutTimer_

    initialized

+ CIMultiroleSensor()
+ onMessageTimeout()
+ onOrthogonalAllocation()
+ onInitialize()
# resetTimer()
timeoutCallback()
  sm_dance_bot_strikes
   back::cl_temperature
   sensor::CITemperatureSensor
```

+ CITemperatureSensor()

smacc2::ISmaccClient