

boost::statechart::
event< EvGoalWaypointReached
 < AsyncCB, Orthogonal > >

The diagram consists of two rectangular boxes. The top box is white with a black border and contains the text 'boost::statechart::' followed by 'event< EvGoalWaypointReached' on the next line and '< AsyncCB, Orthogonal > >' on the third line. The bottom box is gray with a black border and contains the text 'cl_nav2z::EvGoalWaypointReached< AsyncCB, Orthogonal >'. A blue arrow points from the top of the gray box to the bottom of the white box, indicating a generalization relationship where the gray box is a specialization of the white box.

cl_nav2z::EvGoalWaypoint
Reached< AsyncCB, Orthogonal >