

cl\_moveit2z::CbExecuteLast  
Trajectory::onEntry

cl\_moveit2z::CbMoveEndEffector  
Trajectory::onEntry

cl\_moveit2z::CbUndoLastTrajectory  
::onEntry

cl\_moveit2z::CbMoveEndEffector  
Trajectory::executeJointSpaceTrajectory

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graph LR; A[cl_moveit2z::CbExecuteLastTrajectory::onEntry] --> D[cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory]; B[cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry] --> D; C[cl_moveit2z::CbUndoLastTrajectory::onEntry] --> D;
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The diagram illustrates a call graph where three source functions point to a single target function. The source functions are arranged vertically on the left, and the target function is on the right. Blue arrows indicate the direction of the calls.