

sm_dance_bot_strikes
_back::cl_lidar::CpLidarSensor
Data::onInitialize



```
graph LR; A["sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::onInitialize"] --> B["sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::MessageCallbackStoreDistanceToWall"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box is white with a black border and contains three lines of text. The right box is light gray with a black border and contains three lines of text. The text in both boxes is left-aligned.

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