sm ferrari::cl subscriber ::CbMySubscriberBehavior ::onEntry sm pubsub 1::cl subscriber ::CbMySubscriberBehavior ::onEntry cl multirole sensor ::ClMultiroleSensor ::onInitialize sm dance bot strikes smacc2::client bases back::cl lidar::CpLidarSensor ::SmaccSubscriberClient Data::onInitialize ::onMessageReceived sm dance bot warehouse ::cl lidar::CpForwardObstacle Detector::onInitialize sm dance bot warehouse 2::cl lidar::CpForwardObstacle Detector::onInitialize sm dance bot warehouse 3::cl lidar::CpForwardObstacle Detector::onInitialize