

sm\_dance\_bot\_warehouse  
\_3::radial\_motion\_states  
::StiRadialLoopStart::onEntry



```
graph LR; A["sm_dance_bot_warehouse_3::radial_motion_states::StiRadialLoopStart::onEntry"] --> B["sm_dance_bot_warehouse_3::radial_motion_states::StiRadialLoopStart::loopWhileCondition"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box is white with a black border and contains three lines of text. The right box is light gray with a black border and contains three lines of text. The arrow is a solid blue line with a triangular head pointing towards the right box.

sm\_dance\_bot\_warehouse  
\_3::radial\_motion\_states  
::StiRadialLoopStart::loopWhile  
Condition