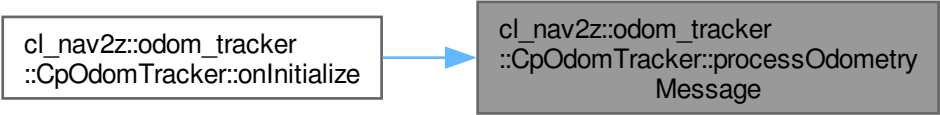


cl\_nav2z::odom\_tracker  
::CpOdomTracker::onInitialize



```
graph LR; A[cl_nav2z::odom_tracker::CpOdomTracker::onInitialize] --> B[cl_nav2z::odom_tracker::CpOdomTracker::processOdometryMessage];
```

cl\_nav2z::odom\_tracker  
::CpOdomTracker::processOdometry  
Message