smacc2\_sm\_reference \_library/sm\_dance\_bot \_warehouse\_2/include/sm \_dance\_bot\_warehouse\_2/orthogonals \_/or\_obstacle\_perception.hpp

smacc2\_sm\_reference \_library/sm\_dance\_bot \_warehouse\_2/include/sm \_dance\_bot\_warehouse\_2/sm \_dance\_bot\_warehouse\_2.hpp

smacc2\_sm\_reference \_library/sm\_dance\_bot \_warehouse\_2/src/sm\_dance \_bot\_warehouse\_2/sm\_dance \_bot\_warehouse\_2.cpp