

cl_nav2z::WaypointNavigator
::onGoalCancelled



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graph LR; A[cl_nav2z::WaypointNavigator::onGoalCancelled] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
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The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a gray background and contains the text 'cl_nav2z::WaypointNavigator::onGoalCancelled'. The right box has a white background and contains the text 'cl_nav2z::WaypointNavigator::stopWaitingResult'.

cl_nav2z::WaypointNavigator
::stopWaitingResult