

```
sm_dance_bot::StAcquireSensors  
::staticConfigure
```



```
graph LR; A["sm_dance_bot::StAcquireSensors  
::staticConfigure"] --> B["smacc2::SmaccState  
< StAcquireSensors,  
MsDanceBotRunMode >  
::static_createStateReactor"]
```

A diagram showing a call from the function `sm_dance_bot::StAcquireSensors::staticConfigure` to the `smacc2::SmaccState` constructor. The call is represented by a blue arrow pointing from the left box to the right box.

```
smacc2::SmaccState  
< StAcquireSensors,  
MsDanceBotRunMode >  
::static_createStateReactor
```