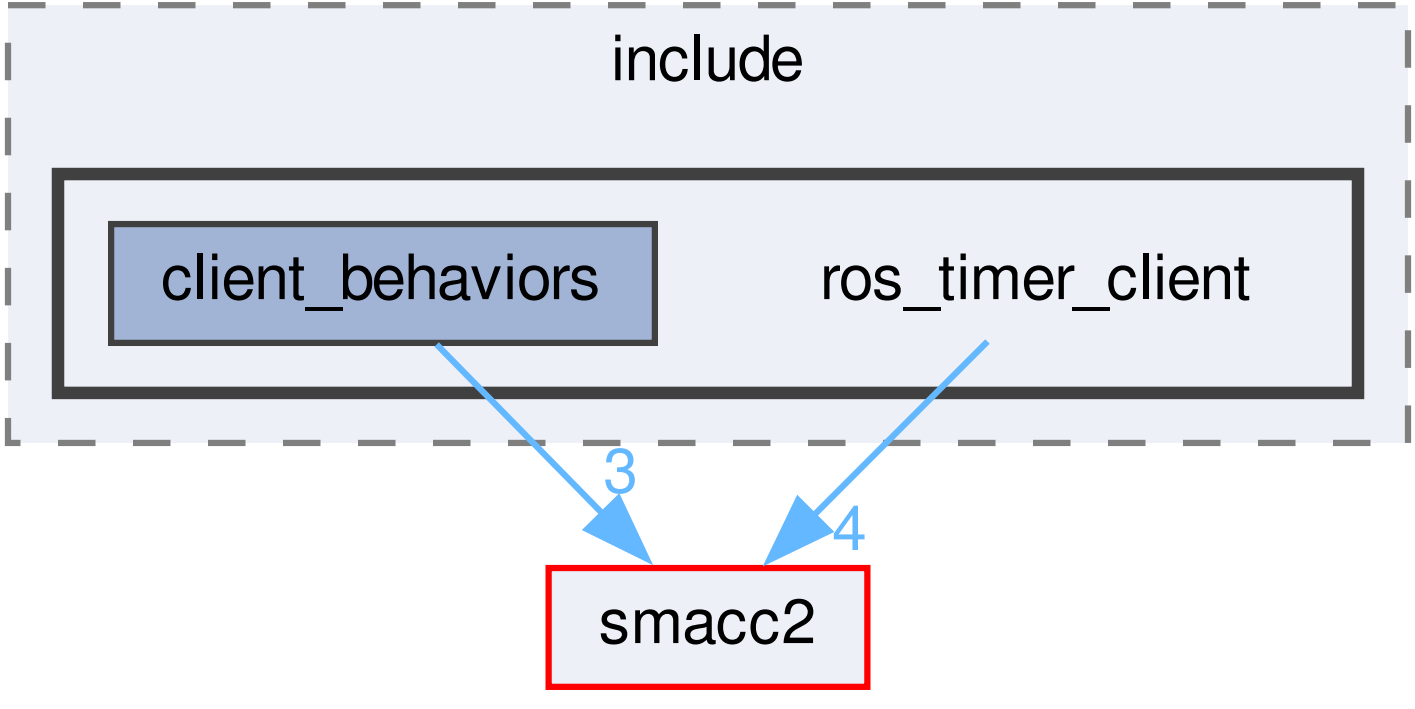
include
client_behaviors
ros_timer_client
3
4
smacc2