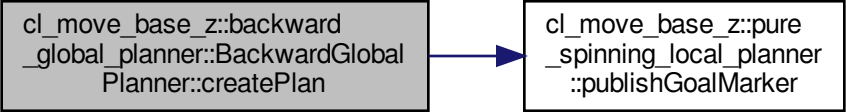


cl\_move\_base\_z::backward  
\_global\_planner::BackwardGlobal  
Planner::createPlan



```
graph LR; A["cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::createPlan"] --> B["cl_move_base_z::pure  
_spinning_local_planner  
::publishGoalMarker"]
```

cl\_move\_base\_z::pure  
\_spinning\_local\_planner  
::publishGoalMarker