

cl_nav2z::CbRotateLookAt
::onEntry

cl_nav2z::CbWaitPose
::onEntry

cl_nav2z::Pose::waitTransform
Update

```
graph LR; A[cl_nav2z::CbRotateLookAt::onEntry] --> C[cl_nav2z::Pose::waitTransformUpdate]; B[cl_nav2z::CbWaitPose::onEntry] --> C;
```

The diagram illustrates a shared resource or function. On the left, two separate boxes represent callback functions: 'cl_nav2z::CbRotateLookAt::onEntry' (top) and 'cl_nav2z::CbWaitPose::onEntry' (bottom). Both boxes have blue arrows pointing from their right sides to a single, larger box on the right. This box is shaded gray and contains the text 'cl_nav2z::Pose::waitTransformUpdate'. The arrows indicate that both callback functions interact with or call this shared function.