

boost::statechart::
event< EvWaypoint101
< TSource, TOrthogonal > >

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvWaypoint101 < TSource, TOrthogonal > >"]
    class cl_move_base_z_EvWaypoint101["cl_move_base_z::EvWaypoint101 < TSource, TOrthogonal >"]
    cl_move_base_z_EvWaypoint101 --|> boost_statechart_event
    class cl_move_base_z_EvWaypoint101 {
        + waypointIndex
```

The diagram consists of two class boxes. The top box is white with a black border and contains the text 'boost::statechart::event< EvWaypoint101 < TSource, TOrthogonal > >'. It is divided into three horizontal sections by two lines. The bottom section is empty. The bottom box is gray with a black border and contains the text 'cl_move_base_z::EvWaypoint101 < TSource, TOrthogonal >' in the top section, '+ waypointIndex' in the middle section, and an empty bottom section. A blue arrow with an open triangular head points from the top of the bottom box to the bottom of the top box.

cl_move_base_z::EvWaypoint101
< TSource, TOrthogonal >

+ waypointIndex