

cl_nav2z::WaypointNavigator
::onGoalCancelled



```
graph LR; A[cl_nav2z::WaypointNavigator::onGoalCancelled] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a gray background and contains the text 'cl_nav2z::WaypointNavigator' followed by '::onGoalCancelled' on a new line. The right box has a white background and contains the text 'cl_nav2z::WaypointNavigator' followed by '::stopWaitingResult' on a new line. The blue arrow originates from the right side of the left box and points to the left side of the right box.

cl_nav2z::WaypointNavigator
::stopWaitingResult