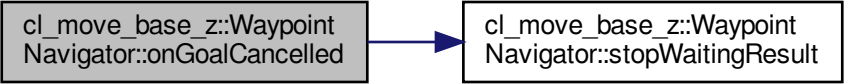


cl\_move\_base\_z::Waypoint  
Navigator::onGoalCancelled



```
graph LR; A[cl_move_base_z::Waypoint Navigator::onGoalCancelled] --> B[cl_move_base_z::Waypoint Navigator::stopWaitingResult]
```

cl\_move\_base\_z::Waypoint  
Navigator::stopWaitingResult