

cl\_nav2z::CbNavigateBackwards  
::onEntry

cl\_nav2z::CbNavigateForward  
::onEntry

cl\_nav2z::odom\_tracker  
::CpOdomTracker::setStartPoint

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graph LR; A[cl_nav2z::CbNavigateBackwards::onEntry] --> C[cl_nav2z::odom_tracker::CpOdomTracker::setStartPoint]; B[cl_nav2z::CbNavigateForward::onEntry] --> C;
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