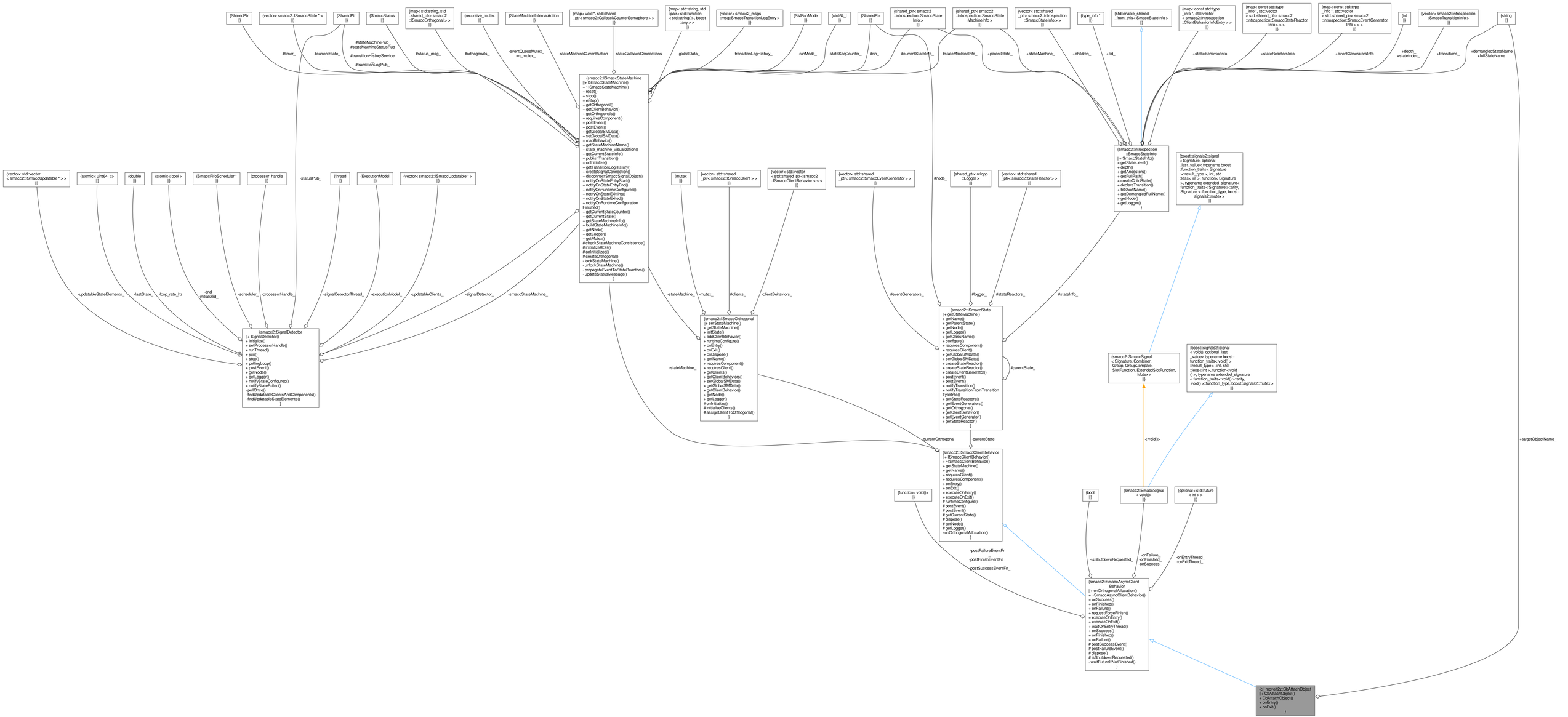
{SharedPtr }
{vector< smacc2::ISmaccState * > }
{SharedPtr }
{SmaccStatus }
{map< std::string, std ::shared_ptr< smacc2 ::ISmaccOrthogonal > > }
{recursive_mutex }
{StateMachineInternalAction }
{map< void *, std::shared _ptr< smacc2::CallbackCounterSemaphore > > }
{map< std::string, std ::pair< std::function < std::string()>, boost ::any > > }
{vector< smacc2_msgs ::msg::SmaccTransitionLogEntry > }
{SMRunMode }
{uint64_t }
{SharedPtr }
{shared_ptr< smacc2 ::introspection::SmaccState Info > }
{shared_ptr< smacc2 ::introspection::SmaccState MachineInfo > }
{vector< std::shared _ptr< smacc2::introspection ::SmaccStateInfo > > }
{type_info * }
{std::enable_shared _from_this< SmaccStateInfo > }
{map< const std::type _info *, std::vector < smacc2::introspection ::ClientBehaviorInfoEntry > > }
{map< const std::type _info *, std::vector < std::shared_ptr< smacc2 ::introspection::SmaccStateReactor Info > > }
{map< const std::type _info *, std::vector < std::shared_ptr< smacc2 ::introspection::SmaccEventGenerator Info > > }
{int }
{vector< smacc2::introspection ::SmaccTransitionInfo > }
{string }
#timer_
#currentState_
#stateMachinePub_
#stateMachineStatusPub
#transitionHistoryService
#transitionLogPub_
#status_msg_
#orthogonals_
-eventQueueMutex_
-m_mutex_
-stateMachineCurrentAction
-stateCallbackConnections
-globalData_
-transitionLogHistory_
-runMode_
-stateSeqCounter_
#rh_
#currentStateInfo_
#stateMachineInfo_
+parentState_
+stateMachine_
+children_
+tid_
+staticBehaviorInfo
+stateReactorsInfo
+eventGeneratorsInfo
+depth_
+stateIndex_
+transitions_
+demangledStateName
+fullStateName
+targetObjectName_
{smacc2::ISmaccStateMachine
|+ ISmaccStateMachine()
+ ~ISmaccStateMachine()
+ reset()
+ stop()
+ eStop()
+ getOrthogonal()
+ getClientBehavior()
+ getOrthogonals()
+ requiresComponent()
+ postEvent()
+ postEvent()
+ getGlobalSMData()
+ setGlobalSMData()
+ mapBehavior()
+ getStateMachineName()
+ state_machine_visualization()
+ getCurrentStateInfo()
+ publishTransition()
+ onInitialize()
+ getTransitionLogHistory()
+ createSignalConnection()
+ disconnectSmaccSignalObject()
+ notifyOnStateEntryStart()
+ notifyOnStateEntryEnd()
+ notifyOnRuntimeConfigured()
+ notifyOnStateExiting()
+ notifyOnStateExited()
+ notifyOnRuntimeConfiguration Finished()
+ getCurrentStateCounter()
+ getCurrentState()
+ getStateMachineInfo()
+ buildStateMachineInfo()
+ getNode()
+ getLogger()
+ getMutex()
# checkStateMachineConsistence()
# initializeROS()
# onInitialized()
# createOrthogonal()
- lockStateMachine()
- unlockStateMachine()
- propagateEventToStateReactors()
- updateStatusMessage()
}
{smacc2::introspection ::SmaccStateInfo
|+ SmaccStateInfo()
+ getStateLevel()
+ depth()
+ getAncestors()
+ getFullPath()
+ createChildState()
+ declareTransition()
+ toShortName()
+ getDemangledFullName()
+ getNode()
+ getLogger()
}
{boost::signals2::signal
< Signature, optional
_last_value< typename boost
::function_traits< Signature
>::result_type >, int, std
::less< int >, function< Signature
>, typename extended_signature<
function_traits< Signature >::arity,
Signature >::function_type, boost::
signals2::mutex >
|}
-statusPub_
{vector< std::vector
< smacc2::ISmaccUpdatable * > >
|}
{atomic< uint64_t > }
{double }
{atomic< bool > }
{SmaccFifoScheduler * }
{processor_handle }
{thread }
{ExecutionModel }
{vector< smacc2::ISmaccUpdatable * > }
-updatableStateElements_
-lastState_
-loop_rate_hz
-end_
_initialized_
-scheduler_
-processorHandle_
-signalDetectorThread_
-executionModel_
-updatableClients_
-signalDetector_
-smaccStateMachine_
{smacc2::ISmaccOrthogonal
|+ setStateMachine()
+ getStateMachine()
+ initState()
+ addClientBehavior()
+ runtimeConfigure()
+ onEntry()
+ onExit()
+ onDispose()
+ getName()
+ requiresComponent()
+ requiresClient()
+ getClients()
+ getClientBehaviors()
+ setGlobalSMData()
+ getGlobalSMData()
+ getClientBehavior()
+ getNode()
+ getLogger()
# onInitialize()
# initializeClients()
# assignClientToOrthogonal()
}
-stateMachine_
{mutex }
-mutex_
{vector< std::shared
_ptr< smacc2::ISmaccClient > >
|}
-clients_
{vector< std::vector
< std::shared_ptr< smacc2
::ISmaccClientBehavior > > >
|}
-clientBehaviors_
{vector< std::shared
_ptr< smacc2::SmaccEventGenerator > >
|}
#eventGenerators_
#node_
{shared_ptr< rclcpp
::Logger >
|}
#logger_
{vector< std::shared
_ptr< smacc2::StateReactor > >
|}
#stateReactors_
#stateInfo_
{smacc2::ISmaccState
|+ getStateMachine()
+ getName()
+ getParentState()
+ getNode()
+ getLogger()
+ getClassName()
+ configure()
+ requiresComponent()
+ requiresClient()
+ getGlobalSMData()
+ setGlobalSMData()
+ createStateReactor()
+ createStateReactor()
+ createEventGenerator()
+ postEvent()
+ postEvent()
+ notifyTransition()
+ notifyTransitionFromTransition TypeInfo()
+ getStateReactors()
+ getEventGenerators()
+ getOrthogonal()
+ getClientBehavior()
+ getEventGenerator()
+ getStateReactor()
}
#parentState_
{smacc2::SmaccSignal
< Signature, Combiner,
Group, GroupCompare,
SlotFunction, ExtendedSlotFunction,
Mutex >
|}
{boost::signals2::signal
< void(), optional_last
_value< typename boost::
function_traits< void() >
::result_type >, int, std
::less< int >, function< void
() >, typename extended_signature
< function_traits< void() >::arity,
void() >::function_type, boost::signals2::mutex >
|}
< void()>
-currentOrthogonal
-currentState
{smacc2::ISmaccClientBehavior
|+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
+ onEntry()
+ onExit()
+ executeOnEntry()
+ executeOnExit()
# runtimeConfigure()
# postEvent()
# postEvent()
# getCurrentState()
# dispose()
# getNode()
# getLogger()
- onOrthogonalAllocation()
}
{function< void()>
|}
{bool
|}
{smacc2::SmaccSignal
< void()>
|}
{optional< std::future
< int > >
|}
-postFailureEventFn
-postFinishEventFn
-postSuccessEventFn_
-isShutdownRequested_
-onFailure_
-onFinished_
-onSuccess_
-onEntryThread_
-onExitThread_
{smacc2::SmaccAsyncClient
Behavior
|+ onOrthogonalAllocation()
+ ~SmaccAsyncClientBehavior()
+ onSuccess()
+ onFinished()
+ onFailure()
+ requestForceFinish()
+ executeOnEntry()
+ executeOnExit()
+ waitOnEntryThread()
# onSuccess()
# onFinished()
# onFailure()
# postSuccessEvent()
# postFailureEvent()
# dispose()
# isShutdownRequested()
- waitFutureIfNotFinished()
}
{cl_moveit2c::CbAttachObject
|+ CbAttachObject()
+ CbAttachObject()
+ onEntry()
+ onExit()
}