

cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::createPlan



```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createPlan"] --> B["cl_nav2z::pure_spinning  
_local_planner::publishGoalMarker"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and a black border, containing the text 'cl_nav2z::backward', '_global_planner::BackwardGlobal', and 'Planner::createPlan' on three lines. The right box has a white background and a black border, containing the text 'cl_nav2z::pure_spinning' and '_local_planner::publishGoalMarker' on two lines.

cl_nav2z::pure_spinning
_local_planner::publishGoalMarker