smacc2::ISmaccClientBehavior - stateMachine - currentState currentOrthogonal + ISmaccClientBehavior() + ~ISmaccClientBehavior() + getStateMachine() + getName() + requiresClient() + requiresComponent() # runtimeConfigure() # onEntry() # onExit() # postEvent() # postEvent() # getCurrentState() # dispose() #getNode() # getLogger() executeOnEntry() executeOnExit() - onOrthogonalAllocation() Δ smacc2::SmaccAsyncClient Behavior - onEntryThread_ onExitThread postFinishEventFn -postSuccessEventFn_ postFailureEventFn smacc2::ISmaccUpdatable onFinished_ -onSuccess_ - periodDuration_ - onFailure lastUpdate isShutdownRequested_ + ISmaccUpdatable() + onOrthogonalAllocation() + ISmaccUpdatable() + ~SmaccAsyncClientBehavior() + executeUpdate() + onSuccess() + setUpdatePeriod() + onFinished() # update() + onFailure() # postSuccessEvent() # postFailureEvent() # dispose() # isShutdownRequested() -waitFutureIfNotFinished() executeOnEntry() executeOnExit() cl_move_group_interface ::CbMoveEndEffectorTrajectory + group + tipLink + allowInitialTrajectoryState JointDiscontinuity_ # endEffectorTrajectory_ # movegroupClient_ # beahiorMarkers_ markersPub - markers Initialized_ - iksrv - m_mutex - postJointDiscontinuityEvent - postIncorrectInitialState Event postMotionExecutionFailure **Events** autocleanmarkers + CbMoveEndEffectorTrajectory() + CbMoveEndEffectorTrajectory() + onOrthogonalAllocation() + onEntry() + onExit() + update() # computeJointSpaceTrajectory() # executeJointSpaceTrajectory() # generateTrajectory() # createMarkers() # getCurrentEndEffectorPose() initializeROS() cl_move_group_interface ::CbMoveCartesianRelative2 + offset + linearSpeed_m_s_ - globalFrame_

+ CbMoveCartesianRelative2()+ CbMoveCartesianRelative2()+ ~CbMoveCartesianRelative2()

+ generateTrajectory()