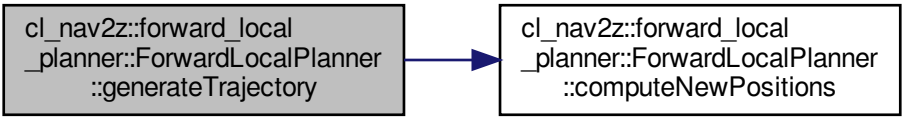
cl_nav2z::forward_local
_planner::ForwardLocalPlanner
::generateTrajectory
cl_nav2z::forward_local
_planner::ForwardLocalPlanner
::computeNewPositions