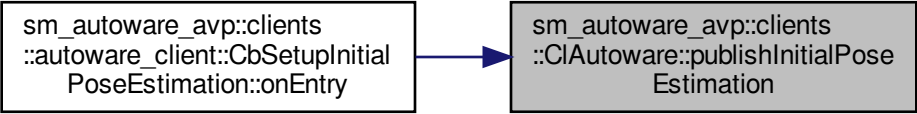


sm_aware_avp::clients
::aware_client::CbSetupInitial
PoseEstimation::onEntry



```
graph LR; A["sm_aware_avp::clients  
::aware_client::CbSetupInitial  
PoseEstimation::onEntry"] --> B["sm_aware_avp::clients  
::ClAware::publishInitialPose  
Estimation"]
```

sm_aware_avp::clients
::ClAware::publishInitialPose
Estimation