

cl\_nav2z::backward  
\_global\_planner::BackwardGlobal  
Planner::createPlan



```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createPlan"] --> B["cl_nav2z::pure_spinning  
_local_planner::publishGoalMarker"]
```

A diagram showing a call from a global planner to a local planner. A grey box on the left contains the text 'cl\_nav2z::backward', '\_global\_planner::BackwardGlobal', and 'Planner::createPlan'. A blue arrow points from this box to a white box on the right. The white box contains the text 'cl\_nav2z::pure\_spinning' and '\_local\_planner::publishGoalMarker'.

cl\_nav2z::pure\_spinning  
\_local\_planner::publishGoalMarker