


cl\_nav2z::CbNavigateNext  
WaypointUntilReached::  
onExit



```
graph LR; A["cl_nav2z::CbNavigateNext  
WaypointUntilReached::  
onExit"] --> B["cl_nav2z::CbNavigateNext  
Waypoint::onExit"]; B --> C["cl_nav2z::CpWaypointNavigator  
::stopWaitingResult"]
```

cl\_nav2z::CbNavigateNext  
Waypoint::onExit

cl\_nav2z::CpWaypointNavigator  
::stopWaitingResult