

cl_nav2z::WaypointNavigator
::onGoalAborted



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graph LR; A[cl_nav2z::WaypointNavigator::onGoalAborted] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
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The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray background and a black border, containing the text 'cl_nav2z::WaypointNavigator' on the top line and '::onGoalAborted' on the bottom line. The right box has a white background and a black border, containing the text 'cl_nav2z::WaypointNavigator' on the top line and '::stopWaitingResult' on the bottom line. A blue arrow points from the right side of the left box to the left side of the right box.

cl_nav2z::WaypointNavigator
::stopWaitingResult