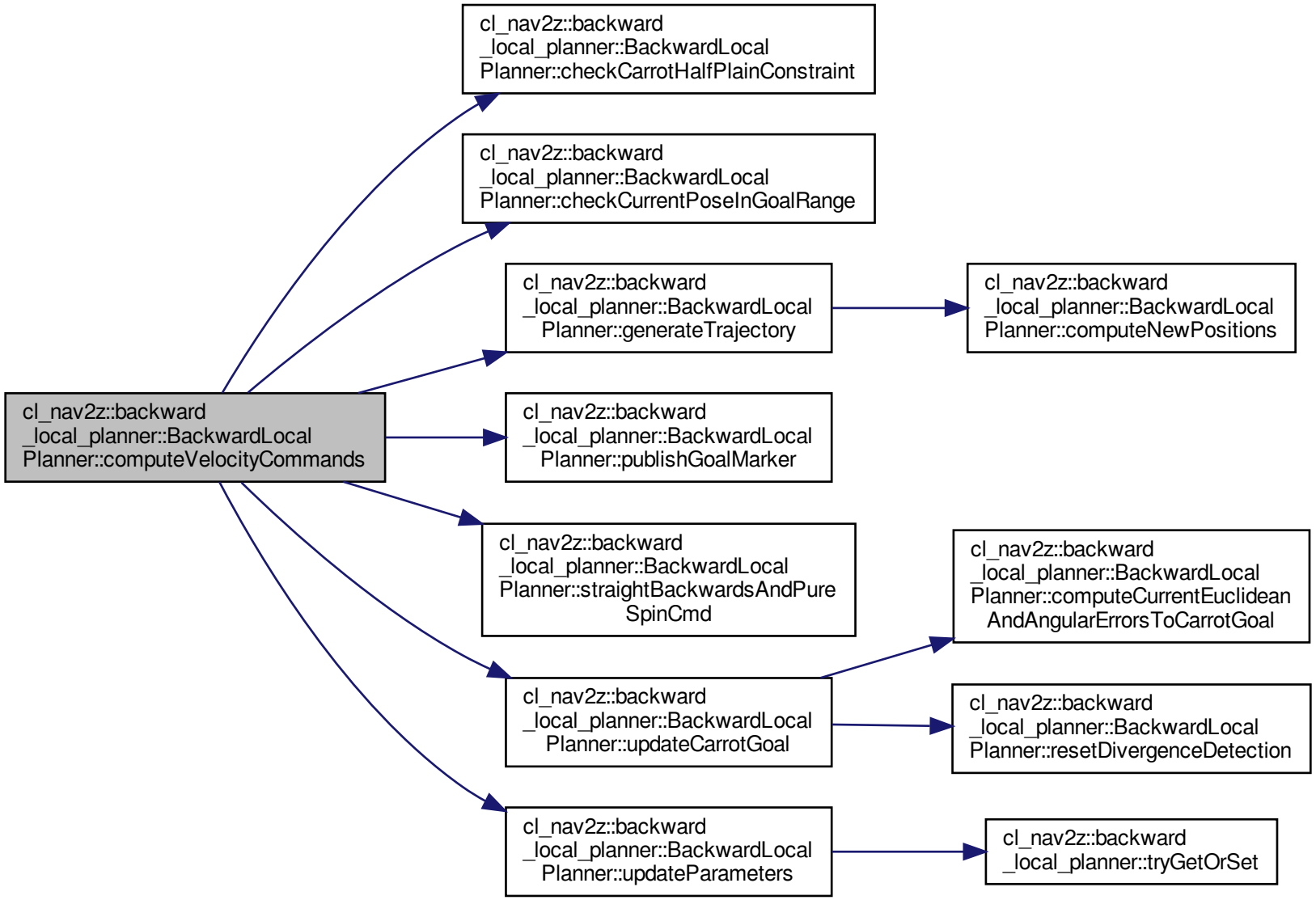
cl_nav2z::backward_local_planner::BackwardLocalPlanner::computeVelocityCommands
cl_nav2z::backward_local_planner::BackwardLocalPlanner::checkCarrotHalfPlainConstraint
cl_nav2z::backward_local_planner::BackwardLocalPlanner::checkCurrentPoseInGoalRange
cl_nav2z::backward_local_planner::BackwardLocalPlanner::generateTrajectory
cl_nav2z::backward_local_planner::BackwardLocalPlanner::computeNewPositions
cl_nav2z::backward_local_planner::BackwardLocalPlanner::publishGoalMarker
cl_nav2z::backward_local_planner::BackwardLocalPlanner::straightBackwardsAndPureSpinCmd
cl_nav2z::backward_local_planner::BackwardLocalPlanner::updateCarrotGoal
cl_nav2z::backward_local_planner::BackwardLocalPlanner::computeCurrentEuclideanAndAngularErrorsToCarrotGoal
cl_nav2z::backward_local_planner::BackwardLocalPlanner::resetDivergenceDetection
cl_nav2z::backward_local_planner::BackwardLocalPlanner::updateParameters
cl_nav2z::backward_local_planner::tryGetOrSet