

sm\_dance\_bot::OrNavigation  
::loadWaypointsFromYaml

sm\_dance\_bot\_strikes  
\_back::OrNavigation::  
loadWaypointsFromYaml

cl\_move\_base\_z::Waypoint  
Navigator::loadWayPointsFromFile

```
graph LR; A["sm_dance_bot::OrNavigation::loadWaypointsFromYaml"] --> C["cl_move_base_z::WaypointNavigator::loadWayPointsFromFile"]; B["sm_dance_bot_strikes_back::OrNavigation::loadWaypointsFromYaml"] --> C;
```

The diagram illustrates a dependency or call relationship. Two source boxes on the left point via blue arrows to a single target box on the right. The top source box contains the text 'sm\_dance\_bot::OrNavigation::loadWaypointsFromYaml'. The bottom source box contains the text 'sm\_dance\_bot\_strikes\_back::OrNavigation::loadWaypointsFromYaml'. The target box, which has a gray background, contains the text 'cl\_move\_base\_z::WaypointNavigator::loadWayPointsFromFile'.