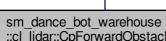
```
# stateMachine__
# owner__

+ ISmaccComponent()
+ ~ISmaccComponent()
+ qetName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresClient()
```

# createSiblingNamedComponent()
# getNode()
# getLogger()
- initialize()
- setStateMachine()

# createSiblingComponent()



::cl\_lidar::CpForwardObstacle Detector

- + lastScanMessage\_ + SECURITY\_DISTANCE
- + onInitialize() + modulo Euclidean()
- + getForwardDistance()
- + MessageCallbackStoreDistance ToWall()