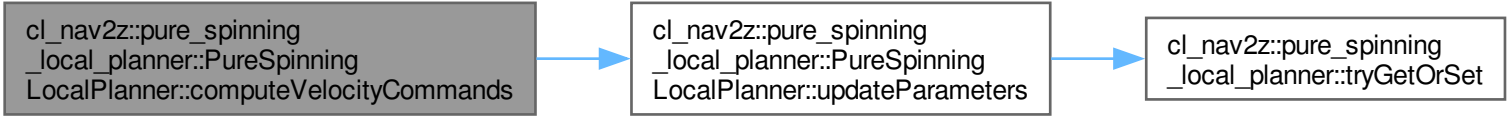


cl_nav2z::pure_spinning
_local_planner::PureSpinning
LocalPlanner::computeVelocityCommands



```
graph LR; A["cl_nav2z::pure_spinning  
_local_planner::PureSpinning  
LocalPlanner::computeVelocityCommands"] --> B["cl_nav2z::pure_spinning  
_local_planner::PureSpinning  
LocalPlanner::updateParameters"]; B --> C["cl_nav2z::pure_spinning  
_local_planner::tryGetOrSet"]
```

cl_nav2z::pure_spinning
_local_planner::PureSpinning
LocalPlanner::updateParameters

cl_nav2z::pure_spinning
_local_planner::tryGetOrSet