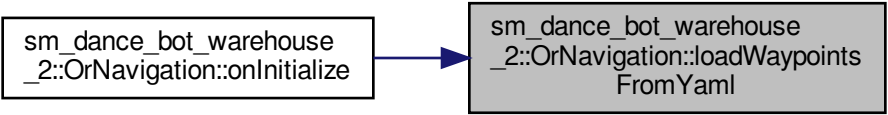


sm\_dance\_bot\_warehouse  
\_2::OrNavigation::onInitialize



```
graph LR; A[sm_dance_bot_warehouse_2::OrNavigation::onInitialize] --> B[sm_dance_bot_warehouse_2::OrNavigation::loadWaypointsFromYaml];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box is white with a black border and contains the text 'sm\_dance\_bot\_warehouse\_2::OrNavigation::onInitialize'. The right box is gray with a black border and contains the text 'sm\_dance\_bot\_warehouse\_2::OrNavigation::loadWaypointsFromYaml'. The arrow is a solid blue line with a triangular head pointing towards the right box.

sm\_dance\_bot\_warehouse  
\_2::OrNavigation::loadWaypoints  
FromYaml