smacc2::ISmaccComponent # stateMachine # owner + ISmaccComponent() + ~ISmaccComponent() + getName() # onInitialize() # postEvent() # postEvent() # onOrthogonalAllocation() # requiresComponent() # requiresClient()

- # createSiblingComponent() # createSiblingNamedComponent()
- # getNode() # getLogger()
- # getStateMachine()
 - initialize()
- setStateMachine()

cl_nav2z::PlannerSwitcher

- desired global planner - desired local planner - set planners mode flag
- planner selector pub controller selector pub
 - goal checker selector pub
 - + PlannerSwitcher()
 - + setBackwardPlanner()
 - + setUndoPathBackwardPlanner()
 - + setForwardPlanner() + setPureSpinningPlanner()
- + onInitialize()
- + setDefaultPlanners()
 - updatePlanners()