```
smacc2::ISmaccClientBehavior
       stateMachine
       currentState
       currentOrthogonal
    + ISmaccClientBehavior()
    +
       ~ISmaccClientBehavior()
      getStateMachine()
    + getName()
    + requiresClient()
      requiresComponent()
      onEntry()
    + onExit()
      executeOnEntry()
    + executeOnExit()
    # runtimeConfigure()
    # postEvent()
    #
       postEvent()
    # getCurrentState()
    #
       dispose()
    # getNode()
    # getLogger()
       onOrthogonalAllocation()
     smacc2::SmaccAsyncClient
              Behavior

    onEntryThread

    onExitThread

    postFinishEventFn_

    postSuccessEventFn

    postFailureEventFn

    onFinished

   - onSuccess_
   - onFailure_
    isShutdownRequested_
   + onOrthogonalAllocation()
   + ~SmaccAsyncClientBehavior()
   + onSuccess()
   + onFinished()
   + onFailure()
   + requestForceFinish()
   + executeOnEntry()
   + executeOnExit()
   + waitOnEntryThread()
   + onSuccess()
   + onFinished()
   + onFailure()
   # postSuccessEvent()
   # postFailureEvent()
   # dispose()
   # isShutdownRequested()

    waitFutureIfNotFinished()

cl_nav2z::CbNav2ZClientBehaviorBase
 #
    nav2zClient_
 #
    navigationCallback_
 #
    navigationResult
    goalHandleFuture_
 #
    ~CbNav2ZClientBehaviorBase()
 +
    onOrthogonalAllocation()
 +
    sendGoal()
 #
 # cancelGoal()
 #
    isOwnActionResponse()
 # onNavigationResult()
 #
    onNavigationActionSuccess()
 #
    onNavigationActionAbort()
     cl_nav2z::CbNavigateGlobal
              Position
   + goalYaw
   + options
   + goalPosition
   + CbNavigateGlobalPosition()
   + CbNavigateGlobalPosition()
   + setGoal()
   + onEntry()
   + onExit()
   + execute()
     readStartPoseFromParameter
     Server()
     cl_nav2z::CbStopNavigation
          CbStopNavigation()
```

onEntry() onExit()