

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::activate

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::computeVelocityCommands

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::updateParameters

```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::activate"] --> C["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::updateParameters"]; B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeVelocityCommands"] --> C;
```

The diagram illustrates a call graph where two functions from the `cl_nav2z::backward_local_planner::BackwardLocalPlanner` namespace point to a single function in the same namespace. The source functions are `activate` and `computeVelocityCommands`, while the target function is `updateParameters`. The target function box is shaded gray, indicating it is the final destination of the calls.