

cl\_moveit2z::CbExecuteLast  
Trajectory::onEntry

cl\_moveit2z::CbMoveEndEffector  
Trajectory::onEntry

cl\_moveit2z::CbUndoLastTrajectory  
::onEntry

cl\_moveit2z::CbMoveEndEffector  
Trajectory::executeJointSpaceTrajectory

```
graph LR; A[cl_moveit2z::CbExecuteLastTrajectory::onEntry] --> D[cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory]; B[cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry] --> D; C[cl_moveit2z::CbUndoLastTrajectory::onEntry] --> D;
```

The diagram illustrates a call graph where three functions from the `cl_moveit2z` namespace serve as entry points to a single target function. The source functions are `cl_moveit2z::CbExecuteLastTrajectory::onEntry`, `cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry`, and `cl_moveit2z::CbUndoLastTrajectory::onEntry`. All three point to the target function `cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory`. The target function box is shaded gray, while the source boxes are white with black borders.