

cl_nav2z::CpWaypointNavigator
::onGoalCancelled



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graph LR; A[cl_nav2z::CpWaypointNavigator::onGoalCancelled] --> B[cl_nav2z::CpWaypointNavigator::stopWaitingResult];
```

cl_nav2z::CpWaypointNavigator
::stopWaitingResult