

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::createPlan



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graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::createPlan"] --> B["cl_nav2z::pure_spinning  
_local_planner::publishGoalMarker"]
```

The diagram illustrates a function call sequence. On the left, a grey rectangular box contains the text 'cl_nav2z::undo_path', '_global_planner::UndoPathGlobal', and 'Planner::createPlan'. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text 'cl_nav2z::pure_spinning' and '_local_planner::publishGoalMarker'.

cl_nav2z::pure_spinning
_local_planner::publishGoalMarker