

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::computeVelocityCommands



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeVelocityCommands"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::generateTrajectory"]
```

A diagram showing a call from the `computeVelocityCommands` method to the `generateTrajectory` method. The call is represented by a blue arrow pointing from the left box to the right box.

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::generateTrajectory