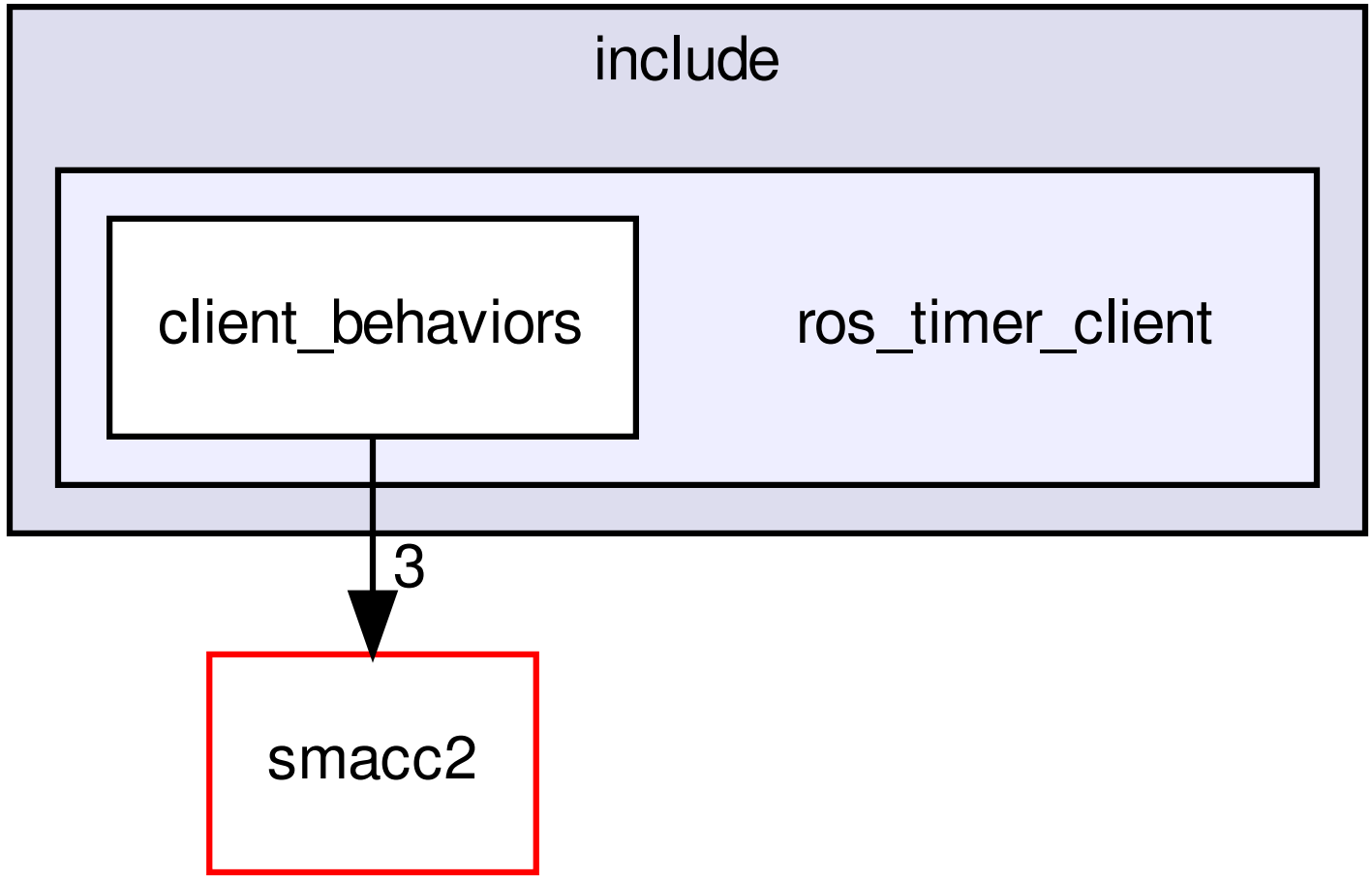
include
client_behaviors
ros_timer_client
3
smacc2