

cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::computeVelocityCommands



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeVelocityCommands"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::generateTrajectory"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'cl\_nav2z::backward', '\_local\_planner::BackwardLocal', and 'Planner::computeVelocityCommands' on three lines. The right box is gray with a black border and contains the text 'cl\_nav2z::backward', '\_local\_planner::BackwardLocal', and 'Planner::generateTrajectory' on three lines. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::generateTrajectory