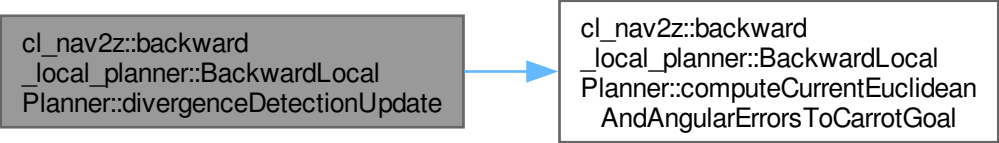


cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::divergenceDetectionUpdate



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::divergenceDetectionUpdate"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeCurrentEuclidean  
AndAngularErrorsToCarrotGoal"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a grey background and contains three lines of text. The right box has a white background and contains four lines of text.

cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::computeCurrentEuclidean  
AndAngularErrorsToCarrotGoal