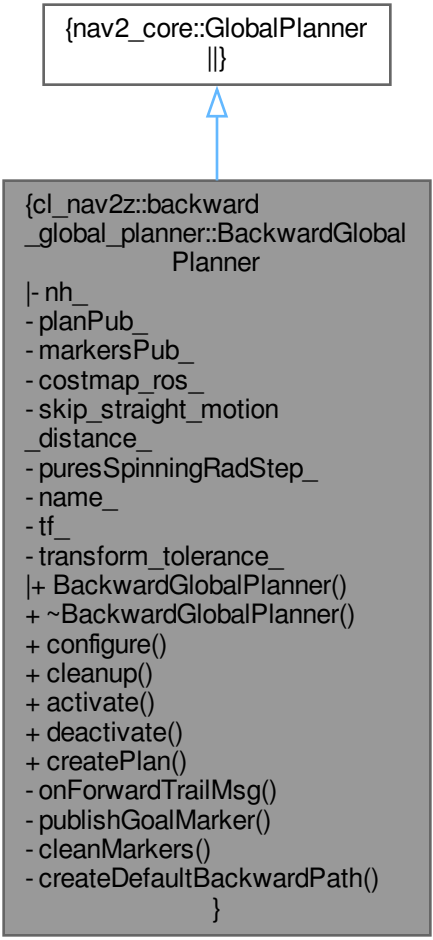
{nav2_core::GlobalPlanner
||}
{cl_nav2z::backward
_global_planner::BackwardGlobal
Planner
|- nh_
- planPub_
- markersPub_
- costmap_ros_
- skip_straight_motion
distance
- puresSpinningRadStep_
- name_
- tf_
- transform_tolerance_
|+ BackwardGlobalPlanner()
+ ~BackwardGlobalPlanner()
+ configure()
+ cleanup()
+ activate()
+ deactivate()
+ createPlan()
- onForwardTrailMsg()
- publishGoalMarker()
- cleanMarkers()
- createDefaultBackwardPath()
}