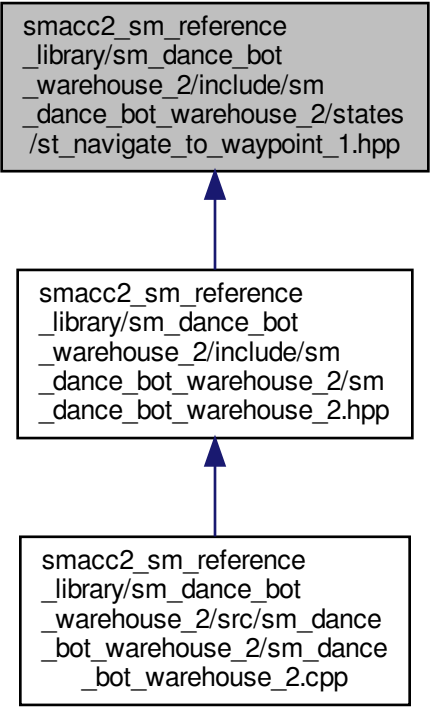


smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_warehouse\_2/include/sm  
\_dance\_bot\_warehouse\_2/states  
/st\_navigate\_to\_waypoint\_1.hpp



```
graph BT; A["smacc2_sm_reference_library/sm_dance_bot_warehouse_2/src/sm_dance_bot_warehouse_2.cpp"] --> B["smacc2_sm_reference_library/sm_dance_bot_warehouse_2/sm_dance_bot_warehouse_2.hpp"]; B --> C["smacc2_sm_reference_library/sm_dance_bot_warehouse_2/include/sm_dance_bot_warehouse_2/states/st_navigate_to_waypoint_1.hpp"];
```

smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_warehouse\_2/include/sm  
\_dance\_bot\_warehouse\_2/sm  
\_dance\_bot\_warehouse\_2.hpp

smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_warehouse\_2/src/sm\_dance  
\_bot\_warehouse\_2/sm\_dance  
\_bot\_warehouse\_2.cpp