

boost::statechart::
event< EvWaypoint196
< TSource, TOrthogonal > >

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvWaypoint196< TSource, TOrthogonal > >"]
    class cl_move_base_z_EvWaypoint196["cl_move_base_z::EvWaypoint196< TSource, TOrthogonal >"]
    cl_move_base_z_EvWaypoint196 --|> boost_statechart_event
```

The diagram consists of two class boxes. The top box is white with a black border and contains the text 'boost::statechart::event< EvWaypoint196< TSource, TOrthogonal > >'. It is divided into three horizontal sections by two lines. The bottom section is empty. The bottom box is gray with a black border and contains the text 'cl_move_base_z::EvWaypoint196< TSource, TOrthogonal >' and '+ waypointIndex'. It is also divided into three horizontal sections by two lines. A blue arrow with an open triangular head points from the top section of the bottom box to the bottom section of the top box.

cl_move_base_z::EvWaypoint196
< TSource, TOrthogonal >

+ waypointIndex