```
smacc2"ISmaccClient
 # components
 - stateMachine

    orthogonal

 + ISmaccClient()
 + ~ISmaccClient()
 + onInitialize()
 + getName()
 + getComponent()
 + aetComponent()
 + getComponent()
 + getType()
 + getStateMachine()
 + connectSignal()
 + requiresClient()
 + getComponents()
 + iterateComponents()
 + postEvent()
 + postEvent()
 # onOrthogonalAllocation()
 # createComponent()
 # createNamedComponent()
 # getNode()
 # getLogger()
 initialize()
 - setStateMachine()
 setOrthogonal()
sm autoware avp::clients
         ::ClAutoware
```

+ cppubLocation_ + cpppubGoalPose_ + lastPose_ + lastGoal_ + goalToleranceMeters_ + postEvAutoLocalized

+ onOrthogonalAllocation() + onInitialize()

+ postEvGoalReached

- + checkGoalReached() + onNdtPoseReceived()
- + publishGoalPose()+ publishInitialPoseEstimation()