sm dance bot warehouse 2::s pattern states:: StiSPatternForward1::runtimeConfigure sm dance bot warehouse 2::s pattern states:: StiSPatternForward2::runtimeConfigure sm dance bot warehouse 2::s pattern states:: StiSPatternForward3::runtimeConfigure

sm_dance_bot_warehouse
_2::s_pattern_states::
StiSPatternForward4::runtimeConfigure

sm_dance_bot_warehouse
_2::cl_lidar::CpForwardObstacle
Detector::getForwardDistance