

cl\_nav2z::WaypointNavigator  
::onGoalCancelled



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graph LR; A[cl_nav2z::WaypointNavigator::onGoalCancelled] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a gray background and contains the text 'cl\_nav2z::WaypointNavigator' on the first line and '::onGoalCancelled' on the second line. The right box has a white background and contains the text 'cl\_nav2z::WaypointNavigator' on the first line and '::stopWaitingResult' on the second line.

cl\_nav2z::WaypointNavigator  
::stopWaitingResult