smacc2::ISmaccComponent

stateMachine_
owner_

+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresComponent()
# requiresClient()
# createSiblingComponent()
# createSiblingNamedComponent()
# getNode()
# getLogger()
# getStateMachine()
- initialize()
- setStateMachine()

sm_dance_bot_warehouse ::cl_lidar::CpForwardObstacle Detector

+ lastScanMessage_
+ SECURITY_DISTANCE

+ onInitialize()
+ modulo_Euclidean()
+ getForwardDistance()
+ MessageCallbackStoreDistance ToWall()