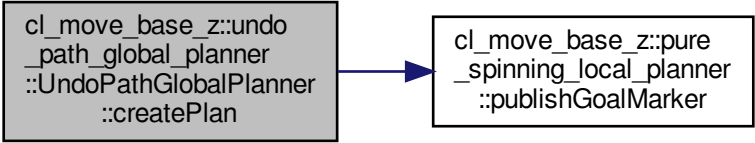


```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::createPlan
```



The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains the text 'cl_move_base_z::undo', '_path_global_planner', '::UndoPathGlobalPlanner', and '::createPlan' stacked vertically. The right box has a white background and contains the text 'cl_move_base_z::pure', '_spinning_local_planner', and '::publishGoalMarker' stacked vertically. The blue arrow originates from the right side of the left box and points to the left side of the right box.

```
cl_move_base_z::pure  
_spinning_local_planner  
::publishGoalMarker
```