

cl\_nav2z::CbRotateLookAt  
::onEntry

cl\_nav2z::CbWaitPose  
::onEntry

cl\_nav2z::Pose::waitTransform  
Update

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graph LR; A[cl_nav2z::CbRotateLookAt::onEntry] --> C[cl_nav2z::Pose::waitTransform Update]; B[cl_nav2z::CbWaitPose::onEntry] --> C;
```

The diagram illustrates a dependency or call relationship. Two white rectangular boxes on the left represent callback functions: 'cl\_nav2z::CbRotateLookAt::onEntry' (top) and 'cl\_nav2z::CbWaitPose::onEntry' (bottom). Two blue arrows originate from the right side of these boxes and point towards a single gray rectangular box on the right, labeled 'cl\_nav2z::Pose::waitTransform Update'. This indicates that both callback functions trigger or depend on the pose update process.