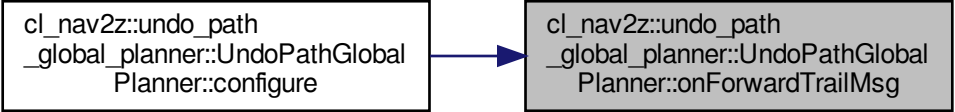


cl\_nav2z::undo\_path  
\_global\_planner::UndoPathGlobal  
Planner::configure



```
graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::configure"] --> B["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::onForwardTrailMsg"]
```

cl\_nav2z::undo\_path  
\_global\_planner::UndoPathGlobal  
Planner::onForwardTrailMsg