

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::findInitialCarrotGoal



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::findInitialCarrotGoal"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeCurrentEuclidean  
AndAngularErrorsToCarrotGoal"]
```

The diagram illustrates a function call sequence. A grey box on the left represents the caller, containing the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', and 'Planner::findInitialCarrotGoal'. A blue arrow points from this box to a white box on the right, which represents the callee. The white box contains the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', and 'Planner::computeCurrentEuclidean AndAngularErrorsToCarrotGoal'.

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::computeCurrentEuclidean
AndAngularErrorsToCarrotGoal