

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::updateParameters



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::updateParameters"] --> B["cl_nav2z::backward  
_local_planner::tryGetOrSet"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and a black border, containing the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', and 'Planner::updateParameters' on three lines. The right box has a white background and a black border, containing the text 'cl_nav2z::backward' and '_local_planner::tryGetOrSet' on two lines. A blue arrow points from the right side of the left box to the left side of the right box.

cl_nav2z::backward
_local_planner::tryGetOrSet