

cl_nav2z::CbNavigateNext
WaypointFree::onEntry



```
graph LR; A[cl_nav2z::CbNavigateNextWaypointFree::onEntry] --> B[cl_nav2z::CpWaypointNavigatorBase::getCurrentPose];
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl_nav2z::CbNavigateNextWaypointFree::onEntry'. The right box is gray with a black border and contains the text 'cl_nav2z::CpWaypointNavigatorBase::getCurrentPose'.

cl_nav2z::CpWaypointNavigator
Base::getCurrentPose