

cl\_nav2z::CbRotateLookAt  
::onEntry

cl\_nav2z::CbWaitPose  
::onEntry

cl\_nav2z::Pose::waitTransform  
Update

```
graph LR; A[cl_nav2z::CbRotateLookAt::onEntry] --> C[cl_nav2z::Pose::waitTransformUpdate]; B[cl_nav2z::CbWaitPose::onEntry] --> C;
```

The diagram illustrates a control flow where two separate callback functions, `cl_nav2z::CbRotateLookAt::onEntry` and `cl_nav2z::CbWaitPose::onEntry`, both trigger a shared function `cl_nav2z::Pose::waitTransformUpdate`. The source functions are represented by white boxes, while the target function is in a gray box. Blue arrows indicate the direction of the call from each source to the target.