

cl_nav2z::CbNavigateNamed
Waypoint::onEntry

cl_nav2z::CbSeekWaypoint
::onEntry

cl_nav2z::CpWaypointNavigator
Base::seekName

```
graph LR; A[cl_nav2z::CbNavigateNamedWaypoint::onEntry] --> C[cl_nav2z::CpWaypointNavigatorBase::seekName]; B[cl_nav2z::CbSeekWaypoint::onEntry] --> C;
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The diagram illustrates a mapping from two callback functions to a single target function. On the left, there are two white rectangular boxes with black borders. The top box contains the text 'cl_nav2z::CbNavigateNamedWaypoint::onEntry' and the bottom box contains 'cl_nav2z::CbSeekWaypoint::onEntry'. On the right, there is a gray rectangular box with a black border containing the text 'cl_nav2z::CpWaypointNavigatorBase::seekName'. Two blue arrows originate from the right side of the top white box and the right side of the bottom white box, both pointing towards the left side of the gray box.