

```
graph BT; A["smacc2_sm_reference_library/sm_test_moveit_ur5_sim/src/sm_test_moveit_ur5_sim/sm_test_moveit_ur5_sim_node.cpp"] --> B["smacc2_sm_reference_library/sm_test_moveit_ur5_sim/include/sm_test_moveit_ur5_sim/sm_test_moveit_ur5_sim/sm_test_move_joints.hpp"]; style A fill:#fff,stroke:#000; style B fill:#ccc,stroke:#000;
```

smacc2_sm_reference
_library/sm_test_moveit
_ur5_sim/include/sm_test
_moveit_ur5_sim/states/st
_move_joints.hpp

smacc2_sm_reference
_library/sm_test_moveit
_ur5_sim/include/sm_test
_moveit_ur5_sim/sm_test_moveit
_ur5_sim.hpp

smacc2_sm_reference
_library/sm_test_moveit
_ur5_sim/src/sm_test_moveit
_ur5_sim/sm_test_moveit_ur5
_sim_node.cpp