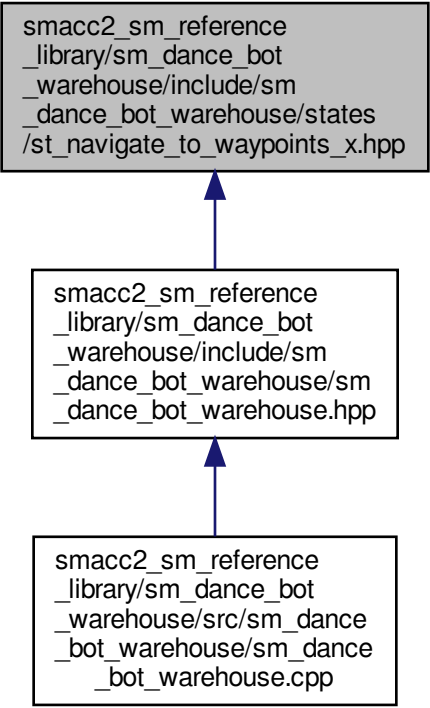


smacc2_sm_reference
_library/sm_dance_bot
_warehouse/include/sm
_dance_bot_warehouse/states
/st_navigate_to_waypoints_x.hpp



```
graph BT; A["smacc2_sm_reference_library/sm_dance_bot_warehouse/src/sm_dance_bot_warehouse/sm_dance_bot_warehouse.cpp"] --> B["smacc2_sm_reference_library/sm_dance_bot_warehouse/include/sm_dance_bot_warehouse/sm_dance_bot_warehouse.hpp"]; B --> C["smacc2_sm_reference_library/sm_dance_bot_warehouse/include/sm_dance_bot_warehouse/states/st_navigate_to_waypoints_x.hpp"];
```

smacc2_sm_reference
_library/sm_dance_bot
_warehouse/include/sm
_dance_bot_warehouse/sm
_dance_bot_warehouse.hpp

smacc2_sm_reference
_library/sm_dance_bot
_warehouse/src/sm_dance
_bot_warehouse/sm_dance
_bot_warehouse.cpp