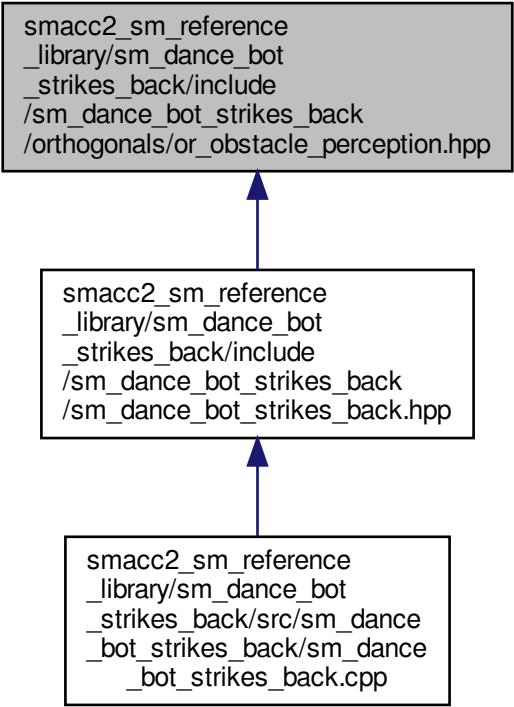


smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/orthogonals/or\_obstacle\_perception.hpp



smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/sm\_dance\_bot\_strikes\_back.hpp

smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/src/sm\_dance  
\_bot\_strikes\_back/sm\_dance  
\_bot\_strikes\_back.cpp