

```
boost::statechart::  
event< EvJointDiscontinuity  
< AsyncCB, Orthogonal > >
```

The diagram shows two class boxes. The top box is white and represents the base class `boost::statechart::event< EvJointDiscontinuity < AsyncCB, Orthogonal > >`. It has two empty compartments below the header. The bottom box is gray and represents the derived class `cl_move_group_interface::EvJointDiscontinuity < AsyncCB, Orthogonal >`. It has a header with the class name and template arguments, a compartment with the public member `+ trajectory`, and an empty compartment at the bottom. A blue arrow with an open triangular head points from the bottom box to the top box, indicating inheritance.

```
cl_move_group_interface  
::EvJointDiscontinuity  
< AsyncCB, Orthogonal >
```

```
+ trajectory
```