smacc2::ISmaccClient

\# components_
- stateMachine_
- orthogonal_

+ ISmaccClient()
+ ~ISmaccClient()
+ onInitialize()
+ getName()
+ getComponent()
+ getComponent()
+ getComponent()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
+ getComponents()
+ postEvent()
+ postEvent()
\# onOrthogonalAllocation()
\# createComponent()
\# createNamedComponent()
\# getNode()
\# getLogger()
- initialize()
- setStateMachine()
- setOrthogonal()

**smacc2::client_bases
::SmaccSubscriberClient
< MessageType >**

+ topicName
+ queueSize
+ onFirstMessageReceived_
+ onMessageReceived_
+ postMessageEvent
+ postInitialMessageEvent
- sub_
- firstMessage_
- initialized_

+ SmaccSubscriberClient()
+ SmaccSubscriberClient()
+ ~SmaccSubscriberClient()
+ onMessageReceived()
+ onFirstMessageReceived()
+ onOrthogonalAllocation()
\# onInitialize()
- messageCallback()

**smacc2::client_bases
::SmaccSubscriberClient
< MessageType >**

+ topicName
+ queueSize
+ onFirstMessageReceived_
+ onMessageReceived_
+ postMessageEvent
+ postInitialMessageEvent
- sub_
- firstMessage_
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+ SmaccSubscriberClient()
+ SmaccSubscriberClient()
+ ~SmaccSubscriberClient()
+ onMessageReceived()
+ onFirstMessageReceived()
+ onOrthogonalAllocation()
\# onInitialize()
- messageCallback()

**cl_multirole_sensor
::ClMultiroleSensor
< MessageType >**

+ onMessageTimeout_
+ postTimeoutMessageEvent
+ timeout_
- timeoutTimer_
- initialized_

+ ClMultiroleSensor()
+ onMessageTimeout()
+ onOrthogonalAllocation()
+ onInitialize()
\# resetTimer()
- timeoutCallback()

< sensor_msgs::msg
::Temperature >

**cl_multirole_sensor
::ClMultiroleSensor
< sensor_msgs::msg::Temperature >**

+ onMessageTimeout_
+ postTimeoutMessageEvent
+ timeout_
- timeoutTimer_
- initialized_

+ ClMultiroleSensor()
+ onMessageTimeout()
+ onOrthogonalAllocation()
+ onInitialize()
\# resetTimer()
- timeoutCallback()

**sm_dance_bot_strikes
_back::cl_temperature
_sensor::ClTemperatureSensor**

+ ClTemperatureSensor()