

boost::statechart::  
event< EvWaypoint207  
< TSource, TOrthogonal > >

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvWaypoint207< TSource, TOrthogonal > >"]
    class cl_move_base_z_EvWaypoint207["cl_move_base_z::EvWaypoint207< TSource, TOrthogonal >"]
    cl_move_base_z_EvWaypoint207 --|> boost_statechart_event
```

The diagram consists of two class boxes. The top box is white with a black border and contains the text 'boost::statechart::event< EvWaypoint207< TSource, TOrthogonal > >'. It has two empty rectangular compartments below the text. The bottom box is gray with a black border and contains the text 'cl\_move\_base\_z::EvWaypoint207< TSource, TOrthogonal >' followed by a compartment containing '+ waypointIndex' and another empty compartment. A blue arrow with an open triangular head points from the bottom box to the top box.

cl\_move\_base\_z::EvWaypoint207  
< TSource, TOrthogonal >

+ waypointIndex