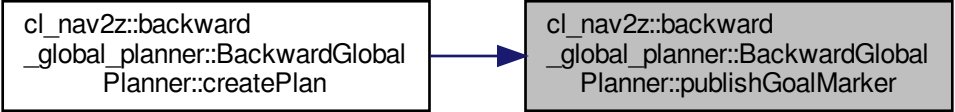


cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::createPlan



cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::publishGoalMarker