

```
graph BT; A["smacc2_sm_reference  
_library/sm_test_moveit  
_ur5_sim/src/sm_test_moveit  
_ur5_sim/sm_test_moveit_ur5  
_sim_node.cpp"] --> B["smacc2_sm_reference  
_library/sm_test_moveit  
_ur5_sim/include/sm_test  
_moveit_ur5_sim/sm_test_moveit  
_ur5_sim.hpp"]; B --> C["smacc2_sm_reference  
_library/sm_test_moveit  
_ur5_sim/include/sm_test  
_moveit_ur5_sim/states/st  
_undo_last_trajectory.hpp"];
```

smacc2_sm_reference
_library/sm_test_moveit
_ur5_sim/include/sm_test
_moveit_ur5_sim/states/st
_undo_last_trajectory.hpp

smacc2_sm_reference
_library/sm_test_moveit
_ur5_sim/include/sm_test
_moveit_ur5_sim/sm_test_moveit
_ur5_sim.hpp

smacc2_sm_reference
_library/sm_test_moveit
_ur5_sim/src/sm_test_moveit
_ur5_sim/sm_test_moveit_ur5
_sim_node.cpp