smacc2::ISmaccClientBehavior stateMachine_ currentState currentOrthogonal + ISmaccClientBehavior() + ~ISmaccClientBehavior() + getStateMachine() + getName() + requiresClient() + requiresComponent() + onEntry() + onExit() + executeOnEntry() + executeOnExit() # runtimeConfigure() # postEvent() # postEvent() # getCurrentState() # dispose() # getNode() # getLogger() onOrthogonalAllocation() smacc2::SmaccAsyncClient Behavior onEntryThread_ onExitThread_ postFinishEventFn_ - postSuccessEventFn postFailureEventFn_ onFinished - onSuccess - onFailure_ - isShutdownRequested_ smacc2::ISmaccUpdatable + onOrthogonalAllocation() - periodDuration_ + ~SmaccAsyncClientBehavior() - lastUpdate_ + onSuccess() + ISmaccUpdatable() + onFinished() + ISmaccUpdatable() + onFailure() + executeUpdate() + requestForceFinish() + setUpdatePeriod() + executeOnEntry() # update() + executeOnExit() + waitOnEntryThread() + onSuccess() + onFinished() + onFailure() # postSuccessEvent() # postFailureEvent() # dispose() # isShutdownRequested() waitFutureIfNotFinished() cl_moveit2z::CbMoveEndEffector rajectory + group_ + tipLink + allowInitialTrajectoryState JointDiscontinuity_ # endEffectorTrajectory_ # movegroupClient_ # beahiorMarkers_ markersPub markersInitialized_ iksrv_ - m_mutex_ postJointDiscontinuityEvent postIncorrectInitialState Event - postMotionExecutionFailure **Events** autocleanmarkers + CbMoveEndEffectorTrajectory() + CbMoveEndEffectorTrajectory() + onOrthogonalAllocation() + onEntry()

+ onExit()
+ update()

computeJointSpaceTrajectory()
executeJointSpaceTrajectory()

getCurrentEndEffectorPose()

cl_moveit2z::CbCircularPivot Motion

+ angularSpeed_rad_s_+ linearSpeed_m_s_+ relativeInitialPose_# planePivotPose_# deltaRadians

+ CbCircularPivotMotion()
 + CbCircularPivotMotion()
 + CbCircularPivotMotion()
 + generateTrajectory()
 + createMarkers()

 computeCurrentEndEffector PoseRelativeToPivot()

cl_moveit2z::CbEndEffector Rotate

+ CbEndEffectorRotate()+ ~CbEndEffectorRotate()

+ tipLink

+ onEntry()

generateTrajectory()
createMarkers()

initializeROS()