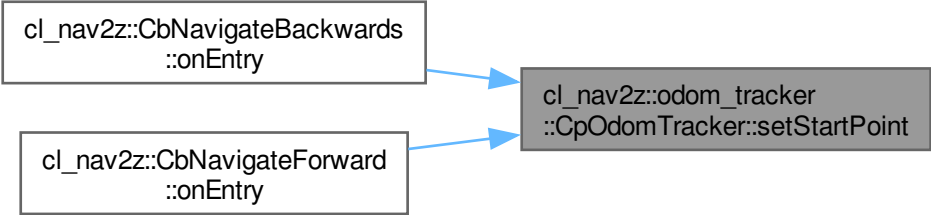


cl_nav2z::CbNavigateBackwards
::onEntry

cl_nav2z::CbNavigateForward
::onEntry

cl_nav2z::odom_tracker
::CpOdomTracker::setStartPoint



```
graph LR; A[cl_nav2z::CbNavigateBackwards::onEntry] --> C[cl_nav2z::odom_tracker::CpOdomTracker::setStartPoint]; B[cl_nav2z::CbNavigateForward::onEntry] --> C;
```