

cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::configure



```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::configure"] --> B["declareOrSet"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is gray with a black border and contains three lines of text: 'cl_nav2z::backward', '_global_planner::BackwardGlobal', and 'Planner::configure'. The right box is white with a black border and contains the text 'declareOrSet'. A blue arrow points from the right side of the gray box to the left side of the white box.

declareOrSet