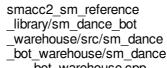
smacc2_sm_reference
_library/sm_dance_bot
_warehouse/include/sm
_dance_bot_warehouse/orthogonals
_/or_obstacle_perception.hpp

smacc2_sm_reference _library/sm_dance_bot _warehouse/include/sm _dance_bot_warehouse/sm

_dance_bot_warehouse.hpp



_bot_warehouse.cpp