smacc2::ISmaccComponent

stateMachine_ # owner

- + ISmaccComponent()
- + ~ISmaccComponent() + getName()
- # onInitialize()
- # postEvent()
- # postEvent()
- # onOrthogonalAllocation()
 # requiresComponent()
- # requires Component()
 # requires Client()
- # createSiblingComponent()
 # createSiblingNamedComponent()
- # getNode()
- # getLogger() # getStateMachine()
- initialize()
 - setStateMachine()



sm_dance_bot_warehouse _3::cl_lidar::CpForwardObstacle Detector

Detector

- + lastScanMessage_+ SECURITY DISTANCE
- + onInitialize() + modulo Euclidean()
- + getForwardDistance()
- + MessageCallbackStoreDistance ToWall()