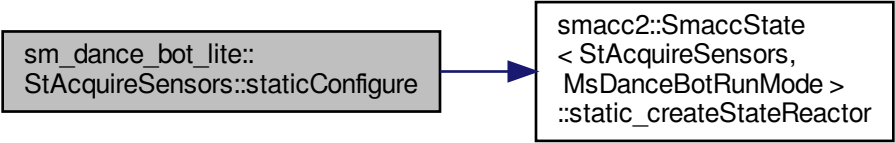


```
sm_dance_bot_lite::  
StAcquireSensors::staticConfigure
```



```
graph LR; A[sm_dance_bot_lite::StAcquireSensors::staticConfigure] --> B[smacc2::SmaccState< StAcquireSensors, MsDanceBotRunMode >::static_createStateReactor]
```

```
smacc2::SmaccState  
< StAcquireSensors,  
MsDanceBotRunMode >  
::static_createStateReactor
```