

sm_husky_barrel_search
_1::StFire::getLookAtPosition

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graph LR; A[sm_husky_barrel_search_1::StFire::getLookAtPosition] --> B[cl_nav2z::WaypointNavigator::getNamedPose]; A --> C[cl_nav2z::Pose::toPoseStampedMsg];
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The diagram consists of three rectangular boxes. The leftmost box is shaded gray and contains the text 'sm_husky_barrel_search_1::StFire::getLookAtPosition'. Two blue arrows originate from the right side of this box. The top arrow points to the top-left corner of a white box containing 'cl_nav2z::WaypointNavigator::getNamedPose'. The bottom arrow points to the top-left corner of another white box containing 'cl_nav2z::Pose::toPoseStampedMsg'.

cl_nav2z::WaypointNavigator
::getNamedPose

cl_nav2z::Pose::toPoseStampedMsg