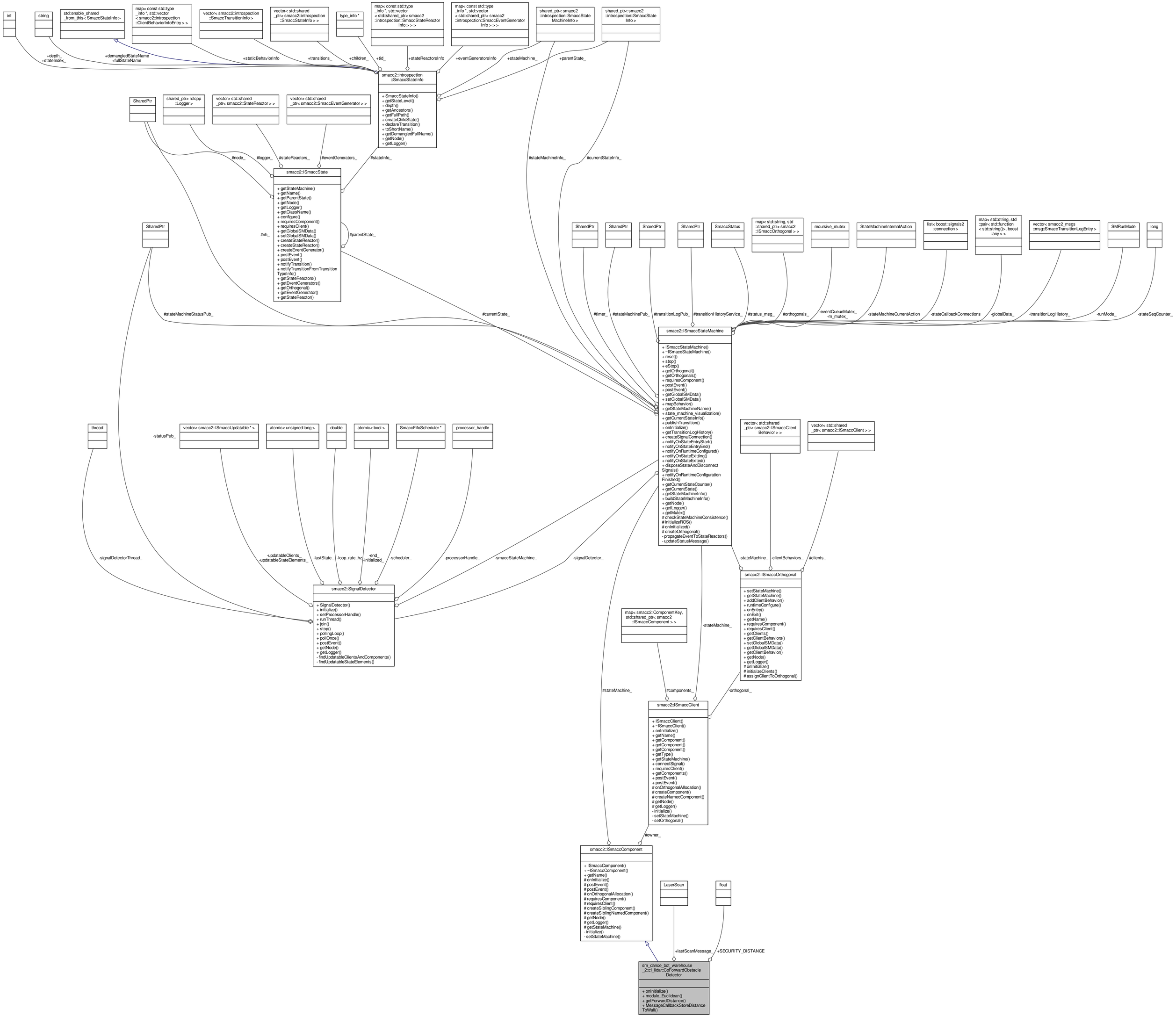
int
string
std::enable_shared
_from_this< SmaccStateInfo >
map< const std::type
_info *, std::vector
< smacc2::introspection
::ClientBehaviorInfoEntry > >
vector< smacc2::introspection
::SmaccTransitionInfo >
vector< std::shared
_ptr< smacc2::introspection
::SmaccStateInfo > >
type_info *
map< const std::type
_info *, std::vector
< std::shared_ptr< smacc2
::introspection::SmaccStateReactor
Info > > >
map< const std::type
_info *, std::vector
< std::shared_ptr< smacc2
::introspection::SmaccEventGenerator
Info > > >
shared_ptr< smacc2
::introspection::SmaccState
MachineInfo >
shared_ptr< smacc2
::introspection::SmaccState
Info >
+depth_
+stateIndex_
+demangledStateName
+fullStateName
+staticBehaviorInfo
+transitions_
+children_
+tid_
+stateReactorsInfo
+eventGeneratorsInfo
+stateMachine_
+parentState_
smacc2::introspection
::SmaccStateInfo
+ SmaccStateInfo()
+ getStateLevel()
+ depth()
+ getAncestors()
+ getFullPath()
+ createChildState()
+ declareTransition()
+ toShortName()
+ getDemangledFullName()
+ getNode()
+ getLogger()
SharedPtr
shared_ptr< rclcpp
::Logger >
vector< std::shared
_ptr< smacc2::StateReactor > >
vector< std::shared
_ptr< smacc2::SmaccEventGenerator > >
#node_
#logger_
#stateReactors_
#eventGenerators_
#stateInfo_
#stateMachineInfo_
#currentStateInfo_
smacc2::ISmaccState
+ getStateMachine()
+ getName()
+ getParentState()
+ getNode()
+ getLogger()
+ getClassName()
+ configure()
+ requiresComponent()
+ requiresClient()
+ getGlobalSMData()
+ setGlobalSMData()
+ createStateReactor()
+ createStateReactor()
+ createEventGenerator()
+ postEvent()
+ postEvent()
+ notifyTransition()
+ notifyTransitionFromTransition
TypeInfo()
+ getStateReactors()
+ getEventGenerators()
+ getOrthogonal()
+ getEventGenerator()
+ getStateReactor()
SharedPtr
#nh_
#parentState_
SharedPtr
SharedPtr
SharedPtr
SharedPtr
SmaccStatus
map< std::string, std
::shared_ptr< smacc2
::ISmaccOrthogonal > >
recursive_mutex
StateMachineInternalAction
list< boost::signals2
::connection >
map< std::string, std
::pair< std::function
< std::string()>, boost
::any > >
vector< smacc2_msgs
::msg::SmaccTransitionLogEntry >
SMRunMode
long
#stateMachinePub_
#currentState_
#timer_
#stateMachinePub_
#transitionLogPub_
#transitionHistoryService_
#status_msg_
#orthogonals_
-eventQueueMutex_
-m_mutex_
-stateMachineCurrentAction
-stateCallbackConnections
-globalData_
-transitionLogHistory_
-runMode_
-stateSeqCounter_
smacc2::ISmaccStateMachine
+ ISmaccStateMachine()
+ ~ISmaccStateMachine()
+ reset()
+ stop()
+ eStop()
+ getOrthogonal()
+ getOrthogonals()
+ requiresComponent()
+ postEvent()
+ postEvent()
+ getGlobalSMData()
+ setGlobalSMData()
+ mapBehavior()
+ getStateMachineName()
+ state_machine_visualization()
+ getCurrentStateInfo()
+ publishTransition()
+ onInitialize()
+ getTransitionLogHistory()
+ createSignalConnection()
+ notifyOnStateEntryStart()
+ notifyOnStateEntryEnd()
+ notifyOnRuntimeConfigured()
+ notifyOnStateExiting()
+ notifyOnStateExited()
+ disposeStateAndDisconnect
Signals()
+ notifyOnRuntimeConfiguration
Finished()
+ getCurrentStateCounter()
+ getCurrentState()
+ getStateMachineInfo()
+ buildStateMachineInfo()
+ getNode()
+ getLogger()
+ getMutex()
# checkStateMachineConsistence()
# initializeROS()
# onInitialized()
# createOrthogonal()
- propagateEventToStateReactors()
- updateStatusMessage()
thread
-statusPub_
vector< smacc2::ISmaccUpdatable * >
atomic< unsigned long >
double
atomic< bool >
SmaccFifoScheduler *
processor_handle
vector< std::shared
_ptr< smacc2::ISmaccClient
Behavior > >
vector< std::shared
_ptr< smacc2::ISmaccClient > >
-signalDetectorThread_
-updatableClients_
-updatableStateElements_
-lastState_
-loop_rate_hz
-end_
-initialized_
-scheduler_
-processorHandle_
-smaccStateMachine_
-signalDetector_
smacc2::SignalDetector
+ SignalDetector()
+ initialize()
+ setProcessorHandle()
+ runThread()
+ join()
+ stop()
+ pollingLoop()
+ pollOnce()
+ postEvent()
+ getNode()
+ getLogger()
- findUpdatableClientsAndComponents()
- findUpdatableStateElements()
-stateMachine_
-clientBehaviors_
#clients_
smacc2::ISmaccOrthogonal
+ setStateMachine()
+ getStateMachine()
+ addClientBehavior()
+ runtimeConfigure()
+ onEntry()
+ onExit()
+ getName()
+ requiresComponent()
+ requiresClient()
+ getClients()
+ getClientBehaviors()
+ setGlobalSMData()
+ getGlobalSMData()
+ getClientBehavior()
+ getNode()
+ getLogger()
# onInitialize()
# initializeClients()
# assignClientToOrthogonal()
map< smacc2::ComponentKey,
std::shared_ptr< smacc2
::ISmaccComponent > >
-stateMachine_
#stateMachine_
#components_
-orthogonal_
smacc2::ISmaccClient
+ ISmaccClient()
+ ~ISmaccClient()
+ onInitialize()
+ getName()
+ getComponent()
+ getComponent()
+ getComponent()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
+ getComponents()
+ postEvent()
+ postEvent()
# onOrthogonalAllocation()
# createComponent()
# createNamedComponent()
# getNode()
# getLogger()
- initialize()
- setStateMachine()
- setOrthogonal()
#owner_
smacc2::ISmaccComponent
+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresClient()
# createSiblingComponent()
# createSiblingNamedComponent()
# getNode()
# getLogger()
# getStateMachine()
- initialize()
- setStateMachine()
LaserScan
float
+lastScanMessage_
+SECURITY_DISTANCE
sm_dance_bot_warehouse
_2::cl_lidar::CpForwardObstacle
Detector
+ onInitialize()
+ modulo_Euclidean()
+ getForwardDistance()
+ MessageCallbackStoreDistance
ToWall()