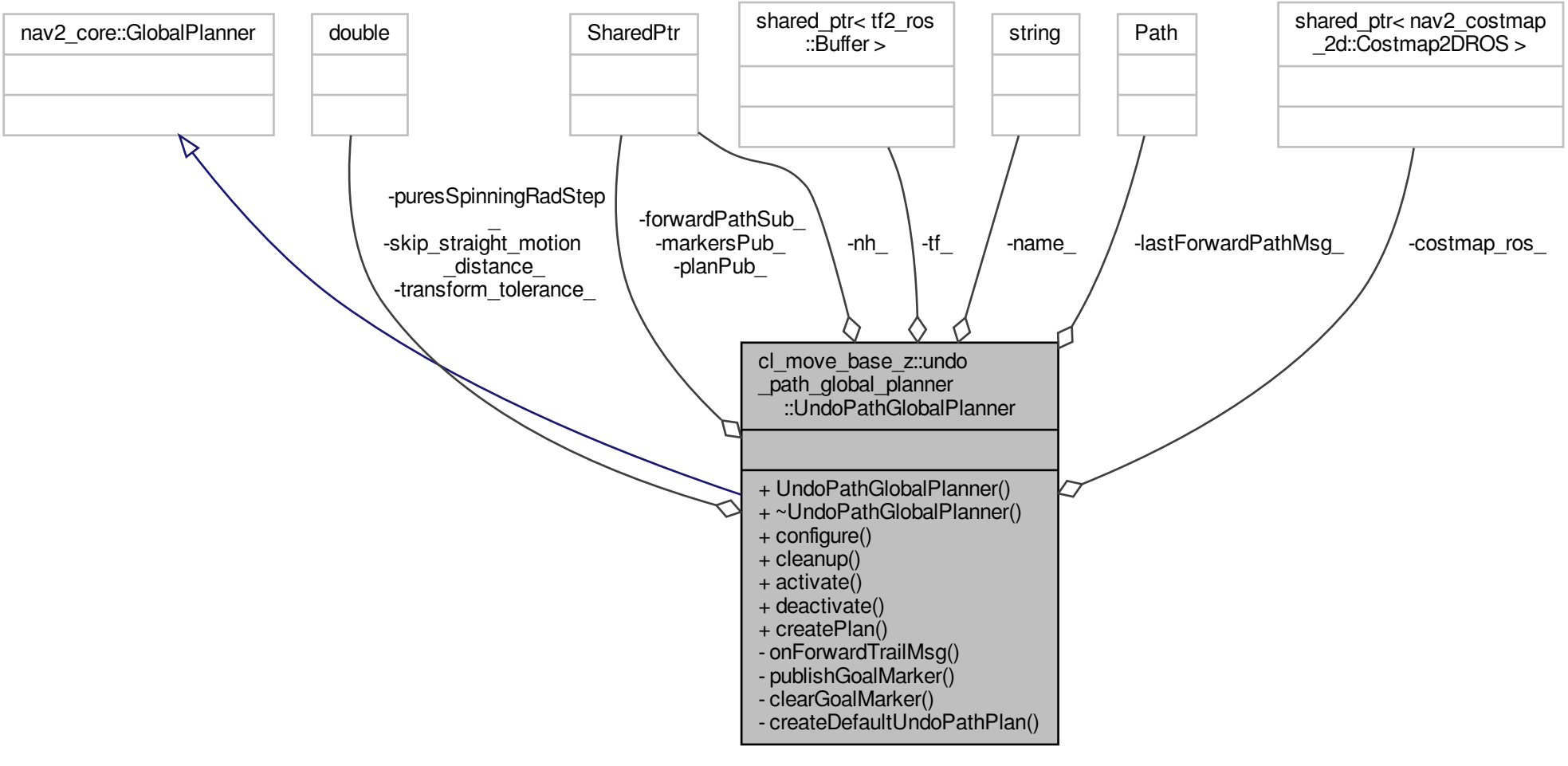
nav2_core::GlobalPlanner
double
SharedPtr
shared_ptr< tf2_ros ::Buffer >
string
Path
shared_ptr< nav2_costmap _2d::Costmap2DROS >
-puresSpinningRadStep _
-skip_straight_motion _distance_
-transform_tolerance_
-forwardPathSub_
-markersPub_
-planPub_
-nh_
-tf_
-name_
-lastForwardPathMsg_
-costmap_ros_
cl_move_base_z::undo _path_global_planner ::UndoPathGlobalPlanner
+ UndoPathGlobalPlanner()
+ ~UndoPathGlobalPlanner()
+ configure()
+ cleanup()
+ activate()
+ deactivate()
+ createPlan()
- onForwardTrailMsg()
- publishGoalMarker()
- clearGoalMarker()
- createDefaultUndoPathPlan()