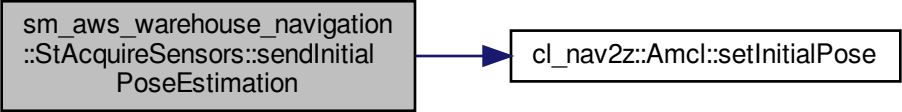


sm_aws_warehouse_navigation
::StAcquireSensors::sendInitial
PoseEstimation



```
graph LR; A["sm_aws_warehouse_navigation::StAcquireSensors::sendInitialPoseEstimation"] --> B["cl_nav2z::Amcl::setInitialPose"]
```

cl_nav2z::Amcl::setInitialPose