

cl\_nav2z::WaypointNavigator  
::onGoalAborted



```
graph LR; A[cl_nav2z::WaypointNavigator  
::onGoalAborted] --> B[cl_nav2z::WaypointNavigator  
::stopWaitingResult]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray fill and a black border, containing the text 'cl\_nav2z::WaypointNavigator' on the top line and '::onGoalAborted' on the bottom line. The right box has a white fill and a black border, containing the text 'cl\_nav2z::WaypointNavigator' on the top line and '::stopWaitingResult' on the bottom line. A solid blue arrow points from the right side of the left box to the left side of the right box.

cl\_nav2z::WaypointNavigator  
::stopWaitingResult