

cl\_move\_base\_z::forward  
\_local\_planner::ForwardLocal  
Planner::computeVelocityCommands



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graph LR; A["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands"] --> B["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker"]
```

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