nav2_core::GlobalPlanner cl nav2z::backward global planner::BackwardGlobal **Planner** nh planPub markersPub costmap ros skip straight motion distance puresSpinningRadStep name tf transform tolerance + BackwardGlobalPlanner() + ~BackwardGlobalPlanner() + configure() + cleanup() + activate() + deactivate() + createPlan() onForwardTrailMsq() publishGoalMarker() cleanMarkers() createDefaultBackwardPath()