

cl_nav2z::CbRotateLookAt
::onEntry

cl_nav2z::CbWaitPose
::onEntry

cl_nav2z::Pose::waitTransform
Update

```
graph LR; A[cl_nav2z::CbRotateLookAt::onEntry] --> C[cl_nav2z::Pose::waitTransform Update]; B[cl_nav2z::CbWaitPose::onEntry] --> C;
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The diagram illustrates a dependency or call relationship. Two white rectangular boxes on the left represent callback functions: 'cl_nav2z::CbRotateLookAt::onEntry' (top) and 'cl_nav2z::CbWaitPose::onEntry' (bottom). Two blue arrows originate from the right side of these boxes and point towards a single gray rectangular box on the right, labeled 'cl_nav2z::Pose::waitTransform Update'. This indicates that both callback functions trigger or depend on the pose update process.