

```
sm_dance_bot_warehouse  
_2::StAcquireSensors::  
staticConfigure
```



```
graph LR; A["sm_dance_bot_warehouse_2::StAcquireSensors::staticConfigure"] --> B["smacc2::SmaccState< StAcquireSensors, MsDanceBotRunMode >::static_createStateReactor"]
```

```
smacc2::SmaccState  
< StAcquireSensors,  
MsDanceBotRunMode >  
::static_createStateReactor
```