```
{smacc2::ISmaccClientBehavior
|- stateMachine
- currentState

    currentOrthogonal

|+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# dispose()
# getNode()
#getLogger()
- executeOnEntry()
executeOnExit()
- onOrthogonalAllocation()
               }
{smacc2::SmaccAsyncClient
           Behavior
|- onEntryThread
onExitThread

    postFinishEventFn

postSuccessEventFn

    postFailureEventFn

    onFinished

- onSuccess
- onFailure
- isShutdownRequested
|+ onOrthogonalAllocation()
+ ~SmaccAsyncClientBehavior()
+ onSuccess()
+ onFinished()
+ onFailure()
# postSuccessEvent()
# postFailureEvent()
# dispose()
#isShutdownRequested()
- waitFutureIfNotFinished()
executeOnEntry()
executeOnExit()
   {smacc2::client behaviors
        ::CbRosLaunch
   + packageName
   + launchFileName
  # result
  # client
   |+ CbRosLaunch()
   + ~CbRosLaunch()
   + onOrthogonalAllocation()
   + onEntry()
```