

cl_moveit2z::CbExecuteLast
Trajectory::onEntry

cl_moveit2z::CbMoveEndEffector
Trajectory::onEntry

cl_moveit2z::CbUndoLastTrajectory
::onEntry

cl_moveit2z::CbMoveEndEffector
Trajectory::executeJointSpaceTrajectory

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graph LR; A[cl_moveit2z::CbExecuteLastTrajectory::onEntry] --> D[cl_moveit2z::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory]; B[cl_moveit2z::CbMoveEndEffectorTrajectory::onEntry] --> D; C[cl_moveit2z::CbUndoLastTrajectory::onEntry] --> D;
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The diagram illustrates a flow where three distinct entry points on the left converge into a single execution block on the right. The left side contains three white rectangular boxes with black borders, each representing a different callback function. Blue arrows originate from the bottom-right corner of the top box, the right side of the middle box, and the top-right corner of the bottom box, all pointing towards the left side of the target box. The target box is a single, wider gray rectangle with a black border, positioned to the right of the three source boxes. It represents the final stage where these three different paths or conditions lead to the same execution of the joint space trajectory.