

boost::statechart::  
event< EvGoalWaypointReached  
< AsyncCB, Orthogonal > >

The diagram consists of two rectangular boxes. The top box is white with a black border and contains the text 'boost::statechart::' followed by 'event< EvGoalWaypointReached' and '< AsyncCB, Orthogonal > >' on separate lines. The bottom box is gray with a black border and contains the text 'cl\_nav2z::EvGoalWaypointReached< AsyncCB, Orthogonal >' on a single line. A blue arrow points from the top of the gray box to the bottom of the white box, indicating a generalization relationship where the gray box is a specialization of the white box.

cl\_nav2z::EvGoalWaypoint  
Reached< AsyncCB, Orthogonal >