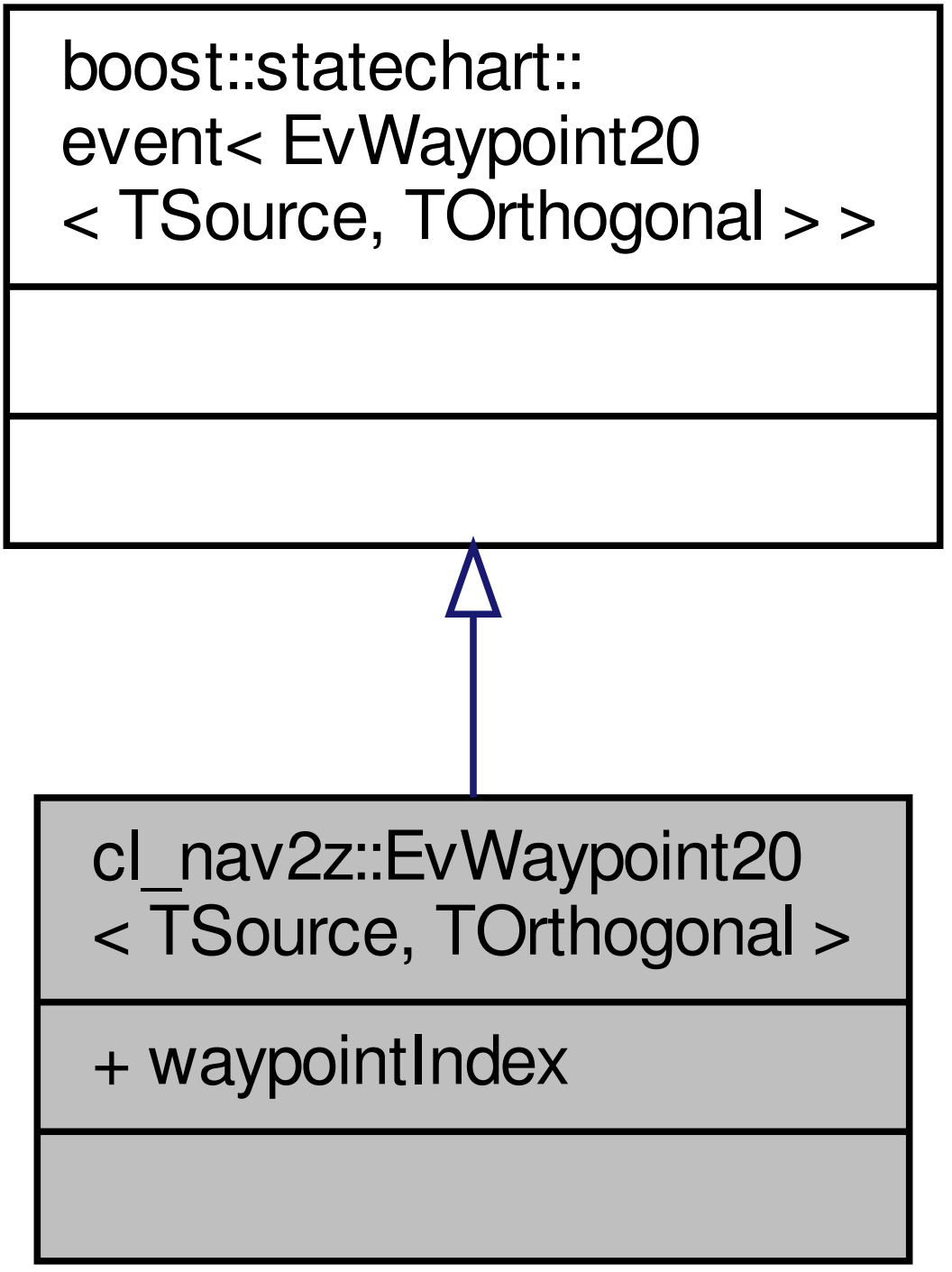
boost::statechart::
event< EvWaypoint20
< TSource, TOrthogonal > >
cl_nav2z::EvWaypoint20
< TSource, TOrthogonal >
+ waypointIndex