

nav2\_core::GlobalPlanner



cl\_move\_base\_z::backward  
\_global\_planner::BackwardGlobal  
Planner

- nh\_
- planPub\_
- markersPub\_
- costmap\_ros\_
- skip\_straight\_motion\_distance\_
- puresSpinningRadStep\_
- name\_
- tf\_
- transform\_tolerance\_

- + BackwardGlobalPlanner()
- + ~BackwardGlobalPlanner()
- + configure()
- + cleanup()
- + activate()
- + deactivate()
- + createPlan()
- onForwardTrailMsg()
- publishGoalMarker()
- createDefaultBackwardPath()