

cl\_nav2z::WaypointNavigator  
::setWaypoints



```
graph LR; A[cl_nav2z::WaypointNavigator::setWaypoints] --> B[cl_move_group_interface::toMsg];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl\_nav2z::WaypointNavigator' on the top line and '::setWaypoints' on the bottom line. The right box is white and contains the text 'cl\_move\_group\_interface' on the top line and '::toMsg' on the bottom line. A dark blue arrow points from the right side of the left box to the left side of the right box.

cl\_move\_group\_interface  
::toMsg