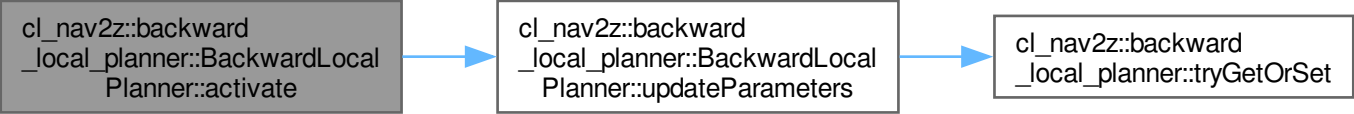


cl_nav2z::backward
_local_planner::BackwardLocal
Planner::activate



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::activate"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::updateParameters"]; B --> C["cl_nav2z::backward  
_local_planner::tryGetOrSet"]
```

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::updateParameters

cl_nav2z::backward
_local_planner::tryGetOrSet