```
smacc2::ISmaccComponent
# stateMachine
# owner
+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresComponent()
# requiresClient()
# createSiblingComponent()
# createSiblingNamedComponent()
# aetNode()
# getLogger()
# getStateMachine()
- initialize()

    setStateMachine()

  cl nav2z::CpPlannerSwitcher
 - desired planner
 - desired controller

    set_planners_mode_flag_

 - planner selector pub
 - controller selector pub
 - goal checker selector pub
+ CpPlannerSwitcher()
+ onInitialize()
+ setDesiredGlobalPlanner()
+ setDesiredController()
+ commitPublish()
```

+ setBackwardPlanner()

+ setForwardPlanner()+ setPureSpinningPlanner()+ setDefaultPlanners()

+ setUndoPathBackwardPlanner()