

sm\_dance\_bot\_warehouse  
\_2::radial\_motion\_states  
::StiRadialLoopStart::onEntry



```
graph LR; A["sm_dance_bot_warehouse_2::radial_motion_states::StiRadialLoopStart::onEntry"] --> B["sm_dance_bot_warehouse_2::radial_motion_states::StiRadialLoopStart::loopWhileCondition"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'sm\_dance\_bot\_warehouse', '\_2::radial\_motion\_states', and '::StiRadialLoopStart::onEntry' on three lines. The right box is gray with a black border and contains the text 'sm\_dance\_bot\_warehouse', '\_2::radial\_motion\_states', and '::StiRadialLoopStart::loopWhileCondition' on three lines. A blue arrow points from the right side of the left box to the left side of the right box.

sm\_dance\_bot\_warehouse  
\_2::radial\_motion\_states  
::StiRadialLoopStart::loopWhile  
Condition