```
smacc2::ISmaccClientBehavior
   stateMachine
   currentState
 - currentOrthogonal
   ISmaccClientBehavior()
   ~ISmaccClientBehavior()
+ getStateMachine()
   getName()
+
+ requiresClient()
   requiresComponent()
+
   onEntrv()
+
+ onExit()
+ executeOnEntry()
+ executeOnExit()
#
   runtimeConfigure()
#
   postEvent()
#
   postEvent()
# getCurrentState()
#
   dispose()
# getNode()
#
   getLogger()
   onOrthogonalAllocation()
smacc2::SmaccClientBehavior
           onEntry()
    +
           onExit()
    +
 cl ros publisher::CbPublish
    Once< RosMsgType >
       deferedPublishEn
       client
       CbPublishOnce()
       CbPublishOnce()
       setMessage()
       onEntry()
      onExit()
```