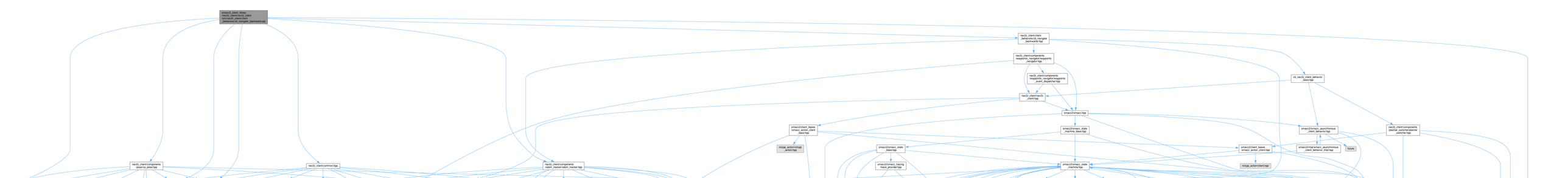
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/home/ros2_ws/src/ros2_smart
/opt/ros/jazzy/share
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