

sm\_aws\_warehouse\_navigation  
::StAcquireSensors::sendInitial  
PoseEstimation



```
graph LR; A["sm_aws_warehouse_navigation  
::StAcquireSensors::sendInitial  
PoseEstimation"] --> B["cl_move_base_z::Amcl  
::setInitialPose"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box is white with a black border and contains the text 'sm\_aws\_warehouse\_navigation', '::StAcquireSensors::sendInitial', and 'PoseEstimation' on three lines. The right box is gray with a black border and contains the text 'cl\_move\_base\_z::Amcl' and '::setInitialPose' on two lines. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_move\_base\_z::Amcl  
::setInitialPose