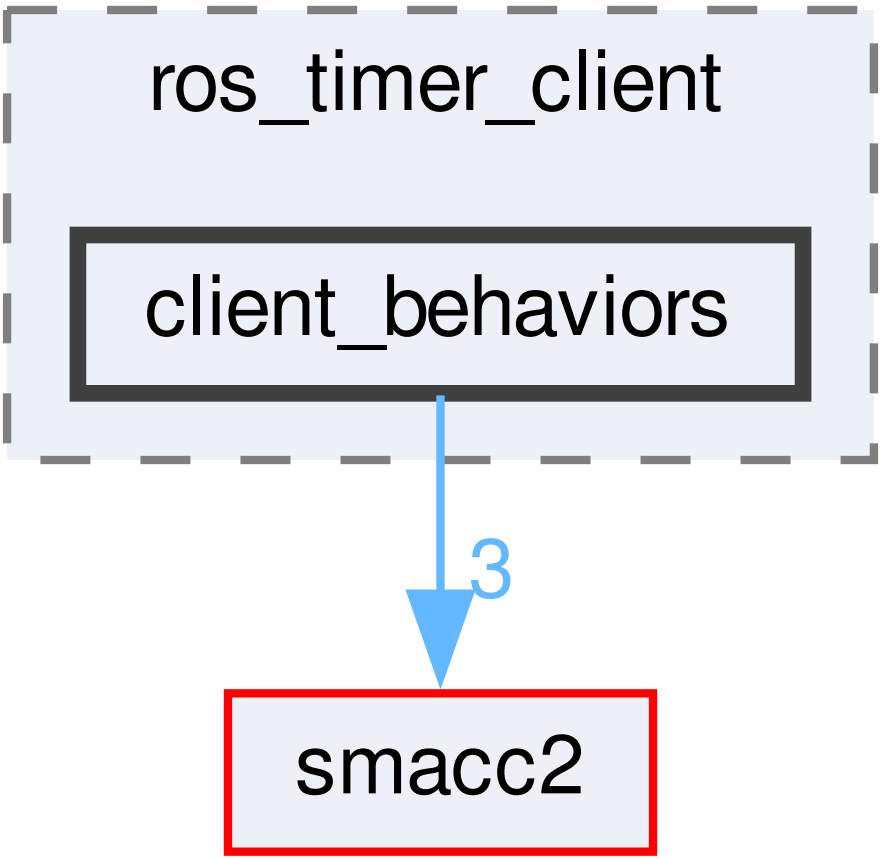
ros_timer_client
client_behaviors
3
smacc2