


cl\_nav2z::pure\_spinning  
\_local\_planner::PureSpinning  
LocalPlanner::updateParameters



```
graph LR; A["cl_nav2z::pure_spinning  
_local_planner::PureSpinning  
LocalPlanner::updateParameters"] --> B["cl_nav2z::pure_spinning  
_local_planner::tryGetOrSet"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a gray background and contains the text 'cl\_nav2z::pure\_spinning', '\_local\_planner::PureSpinning', and 'LocalPlanner::updateParameters'. The right box has a white background and contains the text 'cl\_nav2z::pure\_spinning' and '\_local\_planner::tryGetOrSet'.

cl\_nav2z::pure\_spinning  
\_local\_planner::tryGetOrSet