

sm_dance_bot::radial
_motion_states::StiRadialLoop
Start::onEntry



```
graph LR; A["sm_dance_bot::radial  
_motion_states::StiRadialLoop  
Start::onEntry"] --> B["sm_dance_bot::radial  
_motion_states::StiRadialLoop  
Start::loopWhileCondition"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box is white with a black border and contains three lines of text. The right box is light gray with a black border and also contains three lines of text. The arrow is a solid blue line with a triangular head pointing towards the right box.

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