

cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::cleanup



```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::cleanup"] --> B["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::cleanMarkers"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and a black border. It contains the text 'cl_nav2z::backward' on the first line, '_global_planner::BackwardGlobal' on the second line, and 'Planner::cleanup' on the third line. The right box has a white background and a black border. It contains the text 'cl_nav2z::backward' on the first line, '_global_planner::BackwardGlobal' on the second line, and 'Planner::cleanMarkers' on the third line. A blue arrow points from the right side of the left box to the left side of the right box.

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