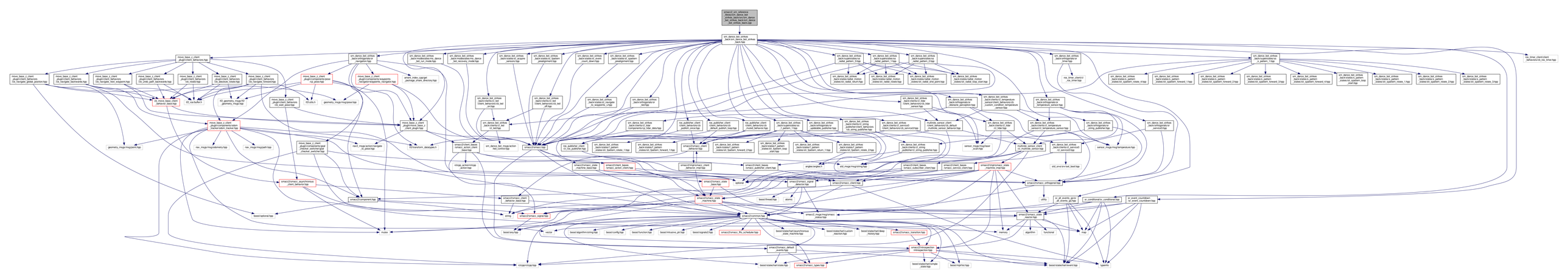
smacc2_sm_reference_library/src_dance_bot_strikes_back/src/sm_dance_bot_strikes_back/sm_dance_bot_strikes_back.cpp
sm_dance_bot_strikes_back/src/sm_dance_bot_strikes_back.cpp
move_base_z_client/plugin/client_behaviors/rtb_navigation.hpp
move_base_z_client/plugin/client_behaviors/rtb_navigation_global_position.hpp
move_base_z_client/plugin/client_behaviors/rtb_navigation_backwards.hpp
move_base_z_client/plugin/client_behaviors/rtb_navigation_rest_waypoints.hpp
move_base_z_client/plugin/client_behaviors/rtb_orbit_path_backwards.hpp
move_base_z_client/plugin/client_behaviors/rtb_absolute_rotate.hpp
move_base_z_client/plugin/client_behaviors/rtb_navigation_forward.hpp
move_base_z_client/plugin/components/pose_log_pose.hpp
move_base_z_client/plugin/components/waypoints_navigation/waypoints_navigation.hpp
smart_index_copy/ge_package_share_directory.hpp
sm_dance_bot_strikes_back/src/orthogonals/cr_navigation.hpp
sm_dance_bot_strikes_back/src/orthogonals/cr_navigation_global.hpp
sm_dance_bot_strikes_back/orthogonals/cr_navigation.hpp
sm_dance_bot_strikes_back