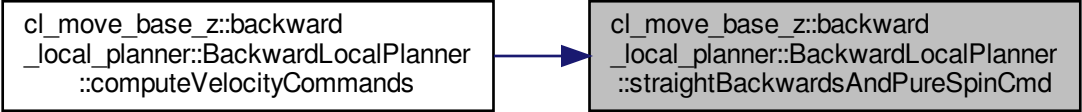


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a call sequence. A white box on the left contains the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::computeVelocityCommands'. A blue arrow points from the right side of this box to a grey box on the right. The grey box contains the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::straightBackwardsAndPureSpinCmd'.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```