

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::divergenceDetectionUpdate



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::divergenceDetectionUpdate"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeCurrentEuclidean  
AndAngularErrorsToCarrotGoal"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a grey background and a black border, containing three lines of text. The right box has a white background and a black border, containing four lines of text. The arrow is a solid blue line with a triangular arrowhead.

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::computeCurrentEuclidean
AndAngularErrorsToCarrotGoal