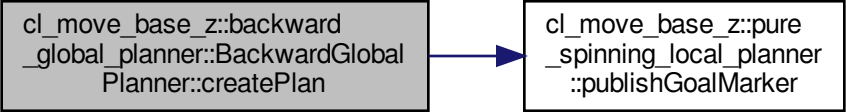


cl_move_base_z::backward
_global_planner::BackwardGlobal
Planner::createPlan



cl_move_base_z::pure
_spinning_local_planner
::publishGoalMarker