

```
sm_dance_bot_strikes  
_back::radial_motion  
_states::StiRadialLoopStart  
::loopWhileCondition
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and contains four lines of C++ code. The right box has a white background and contains two lines of C++ code, representing the function being called.

```
smacc2::ISmaccState  
::getLogger
```