

smacc2_sm_reference
_library/sm_dance_bot
_warehouse_3/include/sm
_dance_bot_warehouse_3/orthogonals
/or_updatable_publisher.hpp



```
graph BT; A["smacc2_sm_reference_library/sm_dance_bot_warehouse_3/src/sm_dance_bot_warehouse_3.cpp"] --> B["smacc2_sm_reference_library/sm_dance_bot_warehouse_3/include/sm_dance_bot_warehouse_3/sm_dance_bot_warehouse_3.hpp"]; B --> C["smacc2_sm_reference_library/sm_dance_bot_warehouse_3/include/sm_dance_bot_warehouse_3/orthogonals/or_updatable_publisher.hpp"];
```

The diagram illustrates the compilation path for the `smacc2_sm_reference` library. It consists of three boxes connected by upward-pointing blue arrows. The bottom box contains the source file `sm_dance_bot_warehouse_3.cpp`. The middle box contains the corresponding header file `sm_dance_bot_warehouse_3.hpp`. The top box contains the header file `orthogonals/or_updatable_publisher.hpp`, which is included by the middle header file.

smacc2_sm_reference
_library/sm_dance_bot
_warehouse_3/include/sm
_dance_bot_warehouse_3/sm
_dance_bot_warehouse_3.hpp

smacc2_sm_reference
_library/sm_dance_bot
_warehouse_3/src/sm_dance
_bot_warehouse_3/sm_dance
_bot_warehouse_3.cpp