nav2 core::GlobalPlanner cl nav2z::undo path global planner::UndoPathGlobal **Planner** - nh forwardPathSub - planPub - markersPub - lastForwardPathMsg - costmap ros -skip_straight_motion distance - puresSpinningRadStep - transform tolerance - name - tf + UndoPathGlobalPlanner() + ~UndoPathGlobalPlanner() + configure() + cleanup() + activate() + deactivate() + createPlan() - onForwardTrailMsg() publishGoalMarker() - clearGoalMarker() - createDefaultUndoPathPlan()