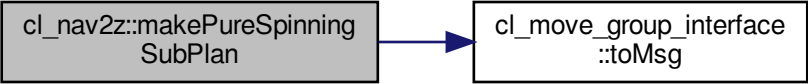


cl_nav2z::makePureSpinning
SubPlan



```
graph LR; A[cl_nav2z::makePureSpinningSubPlan] --> B[cl_move_group_interface::toMsg];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl_nav2z::makePureSpinningSubPlan'. The right box is white and contains the text 'cl_move_group_interface::toMsg'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

cl_move_group_interface
::toMsg