## smacc2::ISmaccComponent

# stateMachine_
# owner_

+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresClient()
# createSiblingComponent()
# createSiblingNamedComponent()
# getNode()
# getLogger()
- initialize()
- setStateMachine()

## cl_nav2z::PlannerSwitcher

- desired_global_planner_
- desired_local_planner_
- set_planners_mode_flag_
- planner_selector_pub_
- controller_selector_pub_
- goal_checker_selector_pub_

+ PlannerSwitcher()
+ setBackwardPlanner()
+ setUndoPathBackwardPlanner()
+ setForwardPlanner()
+ setPureSpinningPlanner()
+ onInitialize()
+ setDefaultPlanners()
- updatePlanners()