

cl_nav2z::WaypointNavigator
::onGoalCancelled



```
graph LR; A[cl_nav2z::WaypointNavigator::onGoalCancelled] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl_nav2z::WaypointNavigator::onGoalCancelled'. The right box is white and contains the text 'cl_nav2z::WaypointNavigator::stopWaitingResult'. A blue arrow points from the right side of the left box to the left side of the right box.

cl_nav2z::WaypointNavigator
::stopWaitingResult