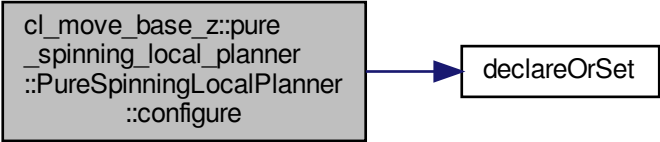


```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::configure
```



The diagram consists of two rectangular boxes connected by a blue arrow. The left box is light gray with a black border and contains four lines of C++ code. The right box is white with a black border and contains the text 'declareOrSet'. A blue arrow points from the right side of the left box to the left side of the right box.

declareOrSet