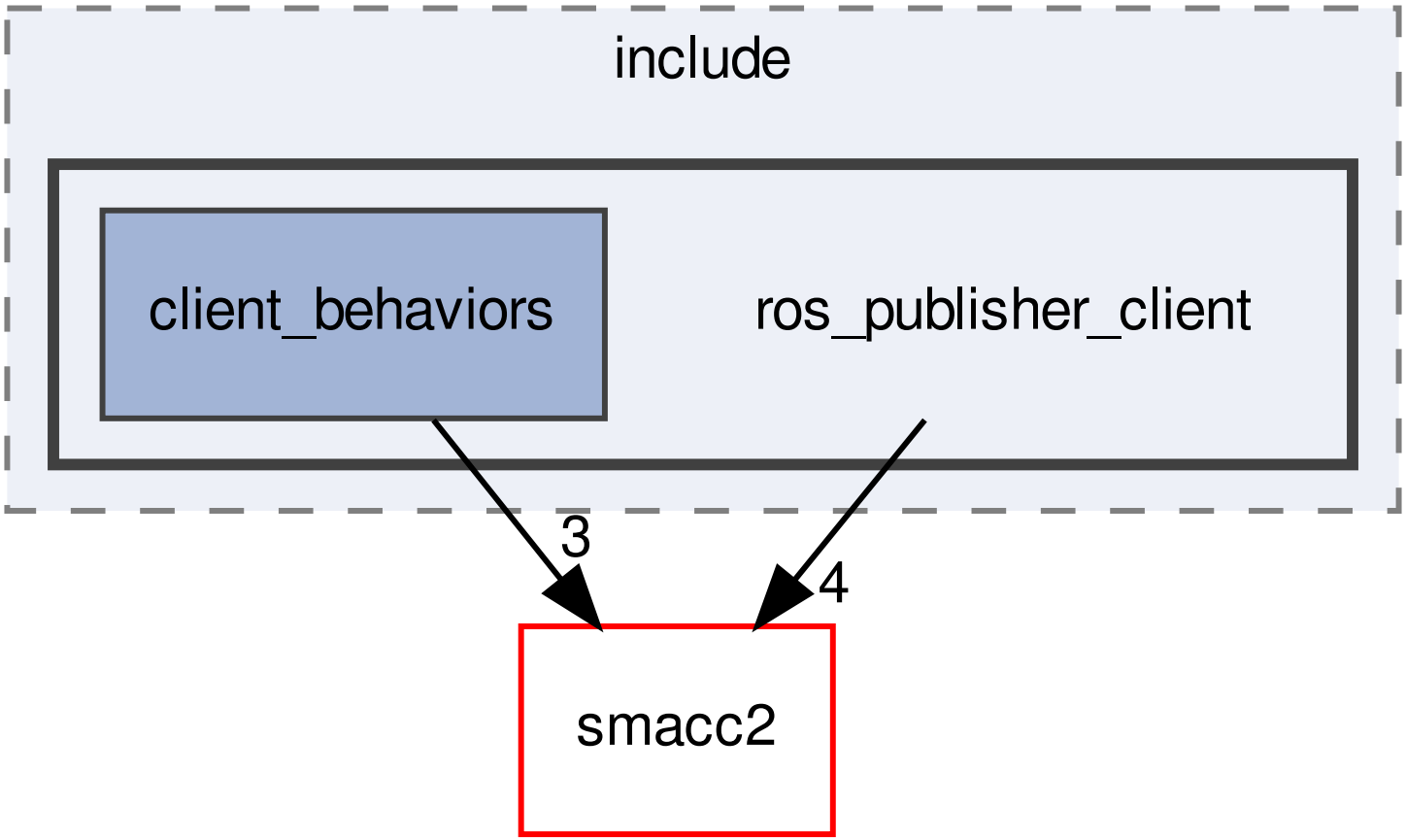
include
client_behaviors
ros_publisher_client
3
4
smacc2