

sm\_aws\_warehouse\_navigation  
::StAcquireSensors::sendInitial  
PoseEstimation



```
graph LR; A["sm_aws_warehouse_navigation  
::StAcquireSensors::sendInitial  
PoseEstimation"] --> B["cl_move_base_z::Amcl  
::setInitialPose"]
```

cl\_move\_base\_z::Amcl  
::setInitialPose