

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::publishGoalMarker"]
```

A diagram showing a call sequence. A blue arrow points from the left box to the right box. The left box is white with a black border, and the right box is gray with a black border.

```
cl_move_base_z::backward  
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::publishGoalMarker
```