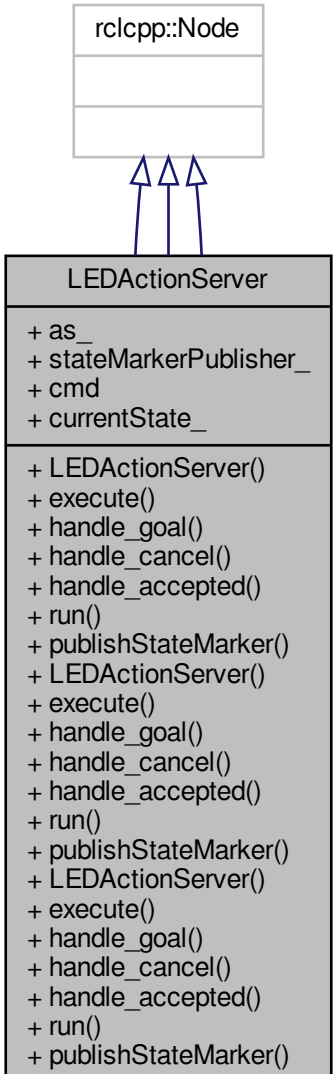
rclcpp::Node
LEDActionServer
+ as_
+ stateMarkerPublisher_
+ cmd
+ currentState_
+ LEDActionServer()
+ execute()
+ handle_goal()
+ handle_cancel()
+ handle_accepted()
+ run()
+ publishStateMarker()
+ LEDActionServer()
+ execute()
+ handle_goal()
+ handle_cancel()
+ handle_accepted()
+ run()
+ publishStateMarker()
+ LEDActionServer()
+ execute()
+ handle_goal()
+ handle_cancel()
+ handle_accepted()
+ run()
+ publishStateMarker()