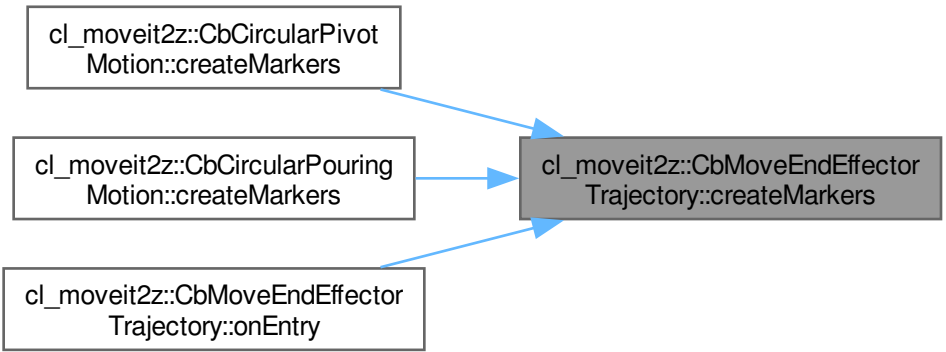


cl_moveit2z::CbCircularPivot
Motion::createMarkers

cl_moveit2z::CbCircularPouring
Motion::createMarkers

cl_moveit2z::CbMoveEndEffector
Trajectory::onEntry

cl_moveit2z::CbMoveEndEffector
Trajectory::createMarkers



```
graph LR; A["cl_moveit2z::CbCircularPivot<br/>Motion::createMarkers"] --> D["cl_moveit2z::CbMoveEndEffector<br/>Trajectory::createMarkers"]; B["cl_moveit2z::CbCircularPouring<br/>Motion::createMarkers"] --> D; C["cl_moveit2z::CbMoveEndEffector<br/>Trajectory::onEntry"] --> D;
```

The diagram illustrates a dependency or call relationship. Three source boxes on the left point via blue arrows to a single target box on the right. The target box is shaded gray, while the source boxes are white with black borders. The source boxes contain the following text: 1. 'cl_moveit2z::CbCircularPivot' followed by 'Motion::createMarkers' on a new line. 2. 'cl_moveit2z::CbCircularPouring' followed by 'Motion::createMarkers' on a new line. 3. 'cl_moveit2z::CbMoveEndEffector' followed by 'Trajectory::onEntry' on a new line. The target box contains: 'cl_moveit2z::CbMoveEndEffector' followed by 'Trajectory::createMarkers' on a new line.