

nav2_core::GlobalPlanner



cl_move_base_z::forward
_global_planner::ForwardGlobal
Planner

- nh_
- planPub_
- costmap_ros_
- skip_straight_motion_
distance
- puresSpinningRadStep_
- name_
- transform_tolerance_
- tf_

- + ForwardGlobalPlanner()
- + ~ForwardGlobalPlanner()
- + configure()
- + cleanup()
- + activate()
- + deactivate()
- + createPlan()