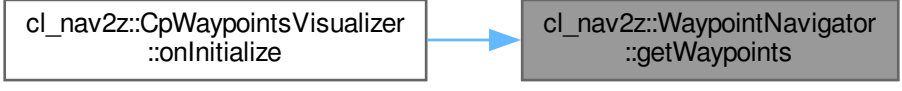
cl_nav2z::CpWaypointsVisualizer
::onInitialize
cl_nav2z::WaypointNavigator
::getWaypoints