```
smacc2::ISmaccClientBehavior
        stateMachine
        currentState
       currentOrthogonal
    + ISmaccClientBehavior()
       ~ISmaccClientBehavior()
    + getStateMachine()
      getName()
    + requiresClient()
      requiresComponent()
    + onEntry()
       onExit()
    + executeOnEntry()
       executeOnExit()
    # runtimeConfigure()
       postEvent()
     # postEvent()
     #
       getCurrentState()
     # dispose()
     #
       getNode()
     # getLogger()
        onOrthogonalAllocation()
     smacc2::SmaccAsyncClient
              Behavior

    onEntryThread_

    onExitThread

   - postFinishEventFn_

    postSuccessEventFn_

    postFailureEventFn_

    onFinished

    onSuccess

    - onFailure
   - isShutdownRequested
   + onOrthogonalAllocation()
   + ~SmaccAsyncClientBehavior()
   + onSuccess()
   + onFinished()
   + onFailure()
   + requestForceFinish()
   + executeOnEntry()
   + executeOnExit()
   + waitOnEntryThread()
   + onSuccess()
   + onFinished()
   + onFailure()
   # postSuccessEvent()
   # postFailureEvent()
   # dispose()
   # isShutdownRequested()
   waitFutureIfNotFinished()
      cl nitrosz::CbNav2ZClient
            BehaviorBase
  # nitroszClient_
  # navigationCallback_
  # navigationResult_
  # goalHandleFuture
  + ~CbNav2ZClientBehaviorBase()
  + onOrthogonalAllocation()
  # sendGoal()
  # cancelGoal()
  # isOwnActionResponse()
  # onNavigationResult()
  # onNavigationActionSuccess()
  # onNavigationActionAbort()
     cl_nitrosz::CbAbsoluteRotate
+ listener
+ absoluteGoalAngleDegree
+ yawGoalTolerance
+ maxVelTheta
+ spinningPlanner

    oldYawTolerance

 oldMaxVelTheta
 oldMinVelTheta
+ CbAbsoluteRotate()
+ CbAbsoluteRotate()
+ onEntry()
+ onExit()
 updateTemporalBehaviorParameters()
      cl_nitrosz::CbRotateLookAt
          listener
          lookAtPose
          CbRotateLookAt()
```

CbRotateLookAt()

+ onEntry()