```
smacc2::ISmaccClientBehavior
    stateMachine
    currentState

    currentOrthogonal

   ISmaccClientBehavior()
   ~ISmaccClientBehavior()
   getStateMachine()
   getName()
 +
   requiresClient()
 +
   requiresComponent()
 +
   onEntry()
 +
 + onExit()
   executeOnEntry()
 +
   executeOnExit()
 +
 #
   runtimeConfigure()
 #
   postEvent()
   postEvent()
 #
 # getCurrentState()
   dispose()
 #
 # getNode()
 #
    aetLoager()
    onOrthogonalAllocation()
smacc2::SmaccClientBehavior
     +
           onEntry()
           onExit()
 cl ros publisher::CbPublish
    Once< RosMsgType >
       deferedPublishFn
       client
       CbPublishOnce()
       CbPublishOnce()
       setMessage()
       onEntry()
       onExit()
   +
```