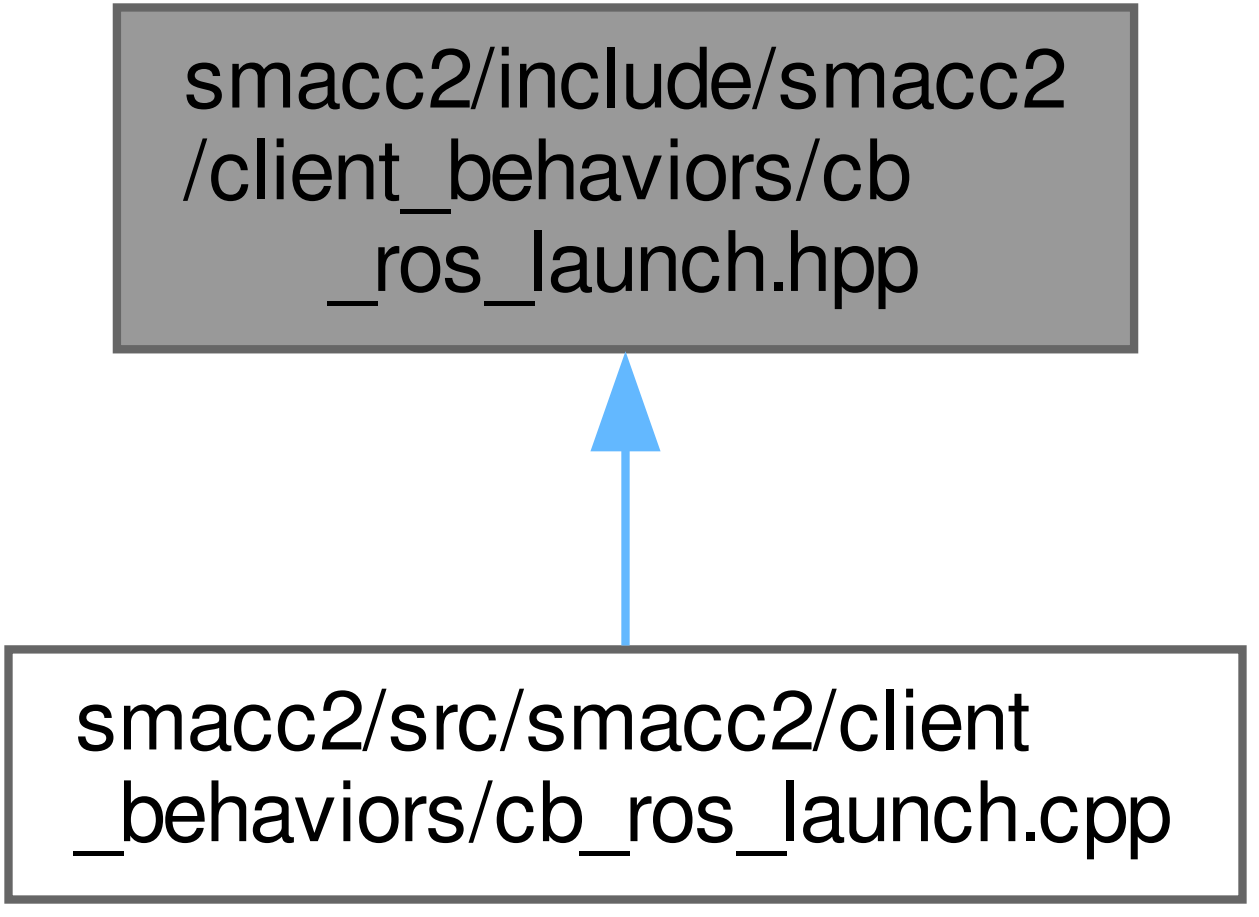
smacc2/include/smacc2/client_behaviors/cb_ros_launch.hpp
smacc2/src/smacc2/client_behaviors/cb_ros_launch.cpp