

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::cleanup



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graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::cleanup"] --> B["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::clearGoalMarker"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a gray background and a black border, containing three lines of text. The right box has a white background and a black border, also containing three lines of text. A blue arrow points from the right side of the left box to the left side of the right box.

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