

sm_dance_bot_strikes
_back::cl_lidar::CpLidarSensor
Data::onInitialize

```
graph LR; A["sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::onInitialize"] --> B["sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::MessageCallbackStoreDistanceToWall"]
```

sm_dance_bot_strikes
_back::cl_lidar::CpLidarSensor
Data::MessageCallbackStoreDistanceToWall