

cl\_nav2z::WaypointNavigator  
::onGoalCancelled



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graph LR; A[cl_nav2z::WaypointNavigator::onGoalCancelled] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
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The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a gray background and contains the text 'cl\_nav2z::WaypointNavigator' followed by '::onGoalCancelled' on a new line. The right box has a white background and contains the text 'cl\_nav2z::WaypointNavigator' followed by '::stopWaitingResult' on a new line. The blue arrow originates from the right side of the left box and points towards the left side of the right box.

cl\_nav2z::WaypointNavigator  
::stopWaitingResult