

smacc2::ISmaccComponent
stateMachine_ # owner_
+ ISmaccComponent() + ~ISmaccComponent() + getName() # onInitialize() # postEvent() # postEvent() # onOrthogonalAllocation() # requiresComponent() # requiresComponent() # requiresClient() # createSiblingComponent() # createSiblingNamedComponent() # getNode() # getLogger() # getStateMachine() - initialize() - setStateMachine()



cl_nitrosz::CpWaypointNavigatorBase
+ waypointsEventDispatcher + currentWaypoint_ # waypoints_ # waypointsNames_
+ CpWaypointNavigatorBase() + ~CpWaypointNavigatorBase() + onInitialize() + loadWayPointsFromFile() + loadWayPointsFromFile2() + setWaypoints() + setWaypoints() + getWaypoints() + getWaypointNames() + getNamedPose() + getPose() + getCurrentPose() + getCurrentWaypointIndex() + getCurrentWaypointName() + rewind() + forward() + seekName() + loadWaypointsFromYamlParameter() + notifyGoalReached() # insertWaypoint() # removeWaypoint()



cl_nitrosz::CpWaypointNavigator
+ client_ + onNavigationRequestSucceeded + onNavigationRequestAborted + onNavigationRequestCancelled - succeededNav2ZClientConnection_ - abortedNav2ZClientConnection_ - cancelledNav2ZClientConnection_
+ CpWaypointNavigator() + onInitialize() + onOrthogonalAllocation() + sendNextGoal() + stopWaitingResult() - onNavigationResult() - onGoalReached() - onGoalCancelled() - onGoalAborted()