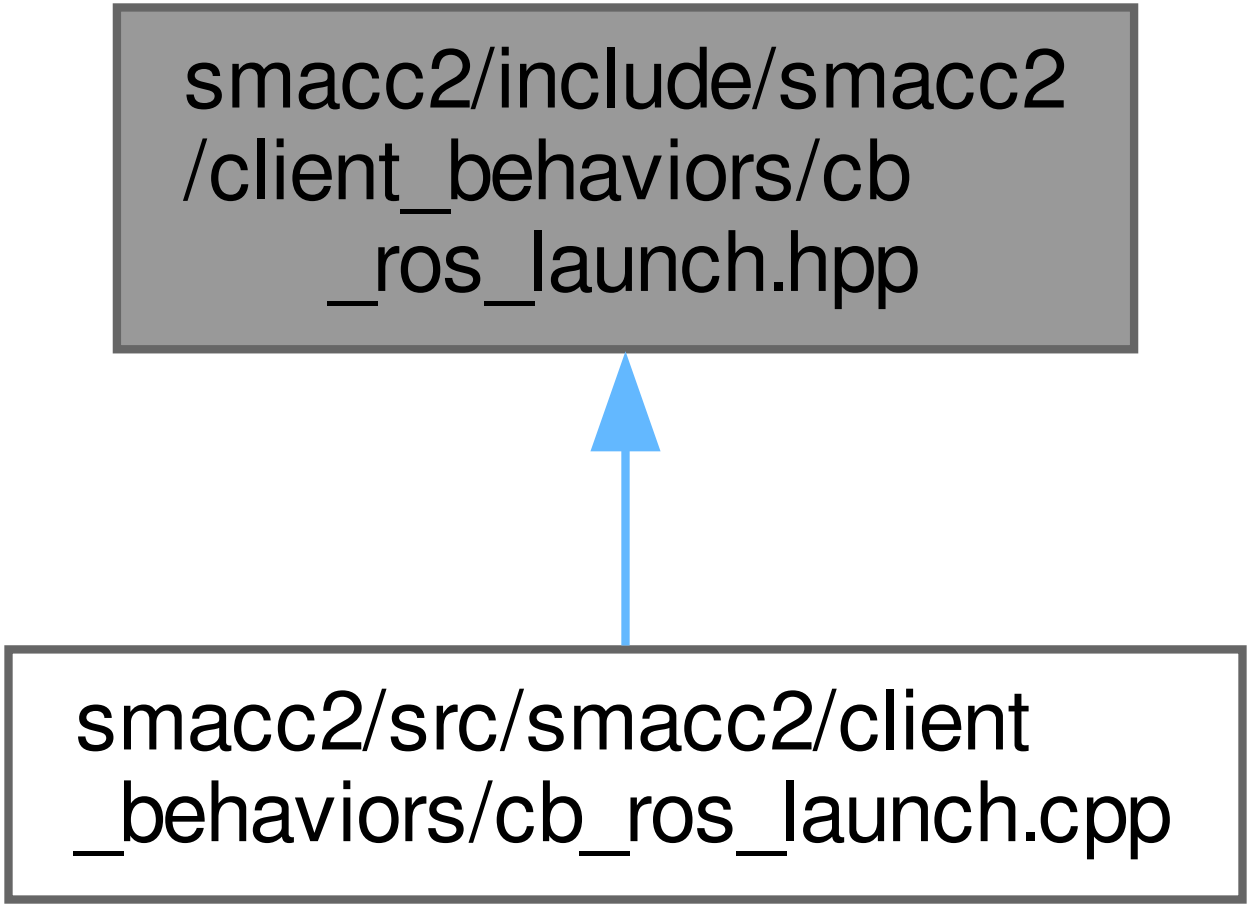
smacc2/include/smacc2
/client_behaviors/cb
_ros_launch.hpp
smacc2/src/smacc2/client
_behaviors/cb_ros_launch.cpp