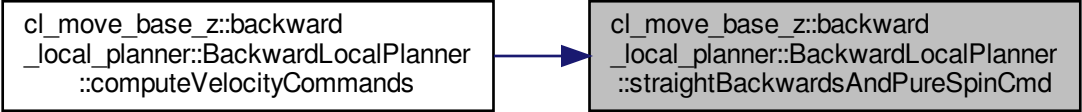


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a call to the `computeVelocityCommands` method of the `BackwardLocalPlanner` class. The call is represented by a box on the left with a black border and white background. A blue arrow points from this box to a box on the right with a black border and gray background, which represents the implementation of the method.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```