```
# components
   stateMachine_

    orthogonal

   + ISmaccClient()
   + ~ISmaccClient()
   + onInitialize()
   + getName()
   + getComponent()
   + getComponent()
   + getComponent()
   + getType()
   + getStateMachine()
   + connectSignal()
   + requiresClient()
   + getComponents()
   + postEvent()
   + postEvent()
   # onOrthogonalAllocation()
   # createComponent()
   # createNamedComponent()
   # getNode()
   # getLogger()
   - initialize()
   setStateMachine()
   - setOrthogonal()
  smacc2::client_bases
   ::SmaccSubscriberClient
        < MessageType >
   + topicName
   + queueSize
   + onFirstMessageReceived_
   + onMessageReceived
   + postMessageEvent
   + postInitialMessageEvent
   - sub
   firstMessage_
   initialized_
   + SmaccSubscriberClient()
   + SmaccSubscriberClient()
   + ~SmaccSubscriberClient()
   + onMessageReceived()
   + onFirstMessageReceived()
   + onOrthogonalAllocation()
   # onInitialize()
   messageCallback()
                      cl_multirole_sensor
                      ::CIMultiroleSensor
                            < MessageType >
                      + onMessageTimeout_
                      + postTimeoutMessageEvent
                      + timeout
                      timeoutTimer_

    initialized

                      + CIMultiroleSensor()
                      + onMessageTimeout()
                      + onOrthogonalAllocation()
                      + onInitialize()
                      # resetTimer()
                       timeoutCallback()
                            < sensor_msgs::msg
                              ::Temperature >
cl_multirole_sensor
::CIMultiroleSensor
< sensor_msgs::msg::Temperature >
+ onMessageTimeout
+ postTimeoutMessageEvent
+ timeout
- timeoutTimer_

    initialized

+ CIMultiroleSensor()
+ onMessageTimeout()
+ onOrthogonalAllocation()
+ onInitialize()
# resetTimer()
timeoutCallback()
  sm_dance_bot::cl_temperature
   sensor::CITemperatureSensor
```

+ CITemperatureSensor()

smacc2::ISmaccClient