

cl\_nav2z::CpWaypointNavigator  
::onGoalCancelled



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graph LR; A[cl_nav2z::CpWaypointNavigator::onGoalCancelled] --> B[cl_nav2z::CpWaypointNavigator::stopWaitingResult]
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cl\_nav2z::CpWaypointNavigator  
::stopWaitingResult