

smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_warehouse\_2/include/sm  
\_dance\_bot\_warehouse\_2/orthogonals  
/or\_obstacle\_perception.hpp



```
graph BT; A["smacc2_sm_reference_library/sm_dance_bot_warehouse_2/src/sm_dance_bot_warehouse_2/sm_dance_bot_warehouse_2.cpp"] --> B["smacc2_sm_reference_library/sm_dance_bot_warehouse_2/include/sm_dance_bot_warehouse_2/sm_dance_bot_warehouse_2.hpp"]; B --> C["smacc2_sm_reference_library/sm_dance_bot_warehouse_2/include/sm_dance_bot_warehouse_2/orthogonals/or_obstacle_perception.hpp"];
```

The diagram illustrates the include chain for a C++ source file. It consists of three rectangular boxes arranged vertically, connected by blue arrows pointing upwards. The bottom box contains the source file path. The middle box contains the header file path, which is included by the source file. The top box contains the header file path, which is included by the middle header file. The top box has a light gray background, while the middle and bottom boxes have white backgrounds.

smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_warehouse\_2/include/sm  
\_dance\_bot\_warehouse\_2/sm  
\_dance\_bot\_warehouse\_2.hpp

smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_warehouse\_2/src/sm\_dance  
\_bot\_warehouse\_2/sm\_dance  
\_bot\_warehouse\_2.cpp