

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::activate



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graph LR; A[cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::activate] --> B[cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::updateParameters]; B --> C[cl_nav2z::backward  
_local_planner::tryGetOrSet];
```

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::updateParameters

cl_nav2z::backward
_local_planner::tryGetOrSet