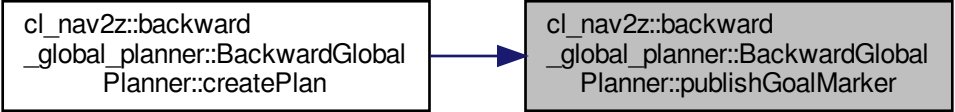


cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::createPlan



```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createPlan"] --> B["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::publishGoalMarker"]
```

A diagram showing a call from the `createPlan` method to the `publishGoalMarker` method. The left box is white with a black border, and the right box is gray with a black border. A blue arrow points from the right side of the left box to the left side of the right box.

cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::publishGoalMarker