

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::onOrthogonalAllocation



```
graph LR; A["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::onOrthogonalAllocation"] --> B["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::initializeROS"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box is white with a black border and contains three lines of text: 'cl_move_group_interface', '::CbMoveEndEffectorTrajectory', and '::onOrthogonalAllocation'. The right box is light gray with a black border and contains three lines of text: 'cl_move_group_interface', '::CbMoveEndEffectorTrajectory', and '::initializeROS'. The arrow originates from the right side of the first box and points to the left side of the second box.

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::initializeROS