

cl\_nav2z::undo\_path  
\_global\_planner::UndoPathGlobal  
Planner::cleanup



```
graph LR; A["cl_nav2z::undo_path<br/>_global_planner::UndoPathGlobal<br/>Planner::cleanup"] --> B["cl_nav2z::undo_path<br/>_global_planner::UndoPathGlobal<br/>Planner::clearGoalMarker"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a gray background and a black border, containing three lines of text. The right box has a white background and a black border, also containing three lines of text. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_nav2z::undo\_path  
\_global\_planner::UndoPathGlobal  
Planner::clearGoalMarker