

sm\_dance\_bot\_warehouse  
\_3::OrNavigation::onInitialize



```
graph LR; A[sm_dance_bot_warehouse_3::OrNavigation::onInitialize] --> B[sm_dance_bot_warehouse_3::OrNavigation::loadWaypointsFromYaml];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'sm\_dance\_bot\_warehouse' on the first line and '\_3::OrNavigation::onInitialize' on the second line. The right box is gray with a black border and contains the text 'sm\_dance\_bot\_warehouse' on the first line, '\_3::OrNavigation::loadWaypoints' on the second line, and 'FromYaml' on the third line. A blue arrow points from the right side of the left box to the left side of the right box.

sm\_dance\_bot\_warehouse  
\_3::OrNavigation::loadWaypoints  
FromYaml