

nav2_core::GlobalPlanner



cl_move_base_z::backward
_global_planner::BackwardGlobal
Planner

- nh_
- planPub_
- markersPub_
- costmap_ros_
- skip_straight_motion_distance_
- puresSpinningRadStep_
- name_
- tf_
- transform_tolerance_

- + BackwardGlobalPlanner()
- + ~BackwardGlobalPlanner()
- + configure()
- + cleanup()
- + activate()
- + deactivate()
- + createPlan()
- onForwardTrailMsg()
- publishGoalMarker()
- cleanMarkers()
- createDefaultBackwardPath()