


```
rcldcpp::TypeAdapter  
< image_tools::ROSCvMatContainer,  
  sensor_msgs::msg::Image >  
  ::convert_to_ros_message
```



A diagram illustrating a function call. On the left, a white rectangular box with a black border contains the text: `rcldcpp::TypeAdapter`, `< image_tools::ROSCvMatContainer,`, `sensor_msgs::msg::Image >`, and `::convert_to_ros_message`. A blue arrow points from the right side of this box to the right side of a gray rectangular box with a black border on the right. The gray box contains the text: `image_tools::ROSCvMatContainer` and `::header`.

```
image_tools::ROSCvMatContainer  
  ::header
```