

cl\_nav2z::WaypointNavigator  
::onGoalAborted



```
graph LR; A[cl_nav2z::WaypointNavigator::onGoalAborted] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl\_nav2z::WaypointNavigator' on the first line and '::onGoalAborted' on the second line. The right box is white with a black border and contains the text 'cl\_nav2z::WaypointNavigator' on the first line and '::stopWaitingResult' on the second line. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_nav2z::WaypointNavigator  
::stopWaitingResult