

cl_ros_publisher::CbPublish
Once::setMessage



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graph LR; A[cl_ros_publisher::CbPublishOnce::setMessage] --> B[cl_ros_publisher::ClRosPublisher::publish]
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The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl_ros_publisher::CbPublishOnce::setMessage'. The right box is white and contains the text 'cl_ros_publisher::ClRosPublisher::publish'. A blue arrow points from the right side of the left box to the left side of the right box.

cl_ros_publisher::ClRosPublisher
::publish