

cl_ros_publisher::CbDefault
PublishLoop::CbDefaultPublishLoop



```
graph LR; A[cl_ros_publisher::CbDefault  
PublishLoop::CbDefaultPublishLoop] --> B[cl_ros_publisher::CbDefault  
PublishLoop::setMessage];
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl_ros_publisher::CbDefault' on the first line and 'PublishLoop::CbDefaultPublishLoop' on the second line. The right box is gray with a black border and contains the text 'cl_ros_publisher::CbDefault' on the first line and 'PublishLoop::setMessage' on the second line.

cl_ros_publisher::CbDefault
PublishLoop::setMessage