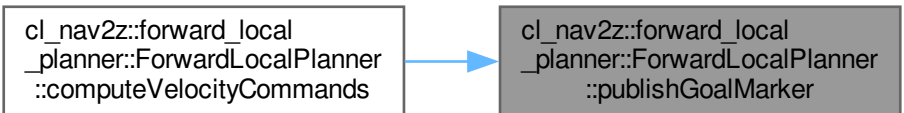
cl_nav2z::forward_local
_planner::ForwardLocalPlanner
::computeVelocityCommands
cl_nav2z::forward_local
_planner::ForwardLocalPlanner
::publishGoalMarker