```
nav2 core::GlobalPlanner
cl_nav2z::forward_global
 planner::ForwardGlobalPlanner
- nh
- planPub
- costmap ros
- skip_straight_motion
distance
- puresSpinningRadStep
- name
- transform tolerance
- tf
+ ForwardGlobalPlanner()
+ ~ForwardGlobalPlanner()
+ configure()
+ cleanup()
+ activate()
+ deactivate()
+ createPlan()
```