

cl_nav2z::CpWaypointsVisualizer
::onInitialize



```
graph LR; A[cl_nav2z::CpWaypointsVisualizer::onInitialize] --> B[cl_nav2z::WaypointNavigator::getWaypointNames];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'cl_nav2z::CpWaypointsVisualizer' on the top line and '::onInitialize' on the bottom line. The right box is light gray with a black border and contains the text 'cl_nav2z::WaypointNavigator' on the top line and '::getWaypointNames' on the bottom line. A dark blue arrow points from the right side of the left box to the left side of the right box.

cl_nav2z::WaypointNavigator
::getWaypointNames