

cl\_ros\_timer::CbTimer  
::onEntry



```
graph LR; A[cl_ros_timer::CbTimer::onEntry] --> B[cl_ros_timer::CbTimer::onClientTimerTickCallback];
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl\_ros\_timer::CbTimer' on the top line and '::onEntry' on the bottom line. The right box is gray with a black border and contains the text 'cl\_ros\_timer::CbTimer' on the top line and '::onClientTimerTickCallback' on the bottom line. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_ros\_timer::CbTimer  
::onClientTimerTickCallback