

sm\_aws\_warehouse\_navigation  
::StStartNavigation::sendInitial  
PoseEstimation



```
graph LR; A["sm_aws_warehouse_navigation::StStartNavigation::sendInitialPoseEstimation"] --> B["smacc2::ISmaccState::getNode"]
```

A diagram showing a call from the `sm_aws_warehouse_navigation::StStartNavigation::sendInitialPoseEstimation` function to the `smacc2::ISmaccState::getNode` function. The first box is shaded gray and the second is white. A blue arrow points from the first box to the second.

smacc2::ISmaccState  
::getNode