

sm\_dance\_bot\_warehouse  
::radial\_motion\_states  
::StiRadialLoopStart::onEntry



```
graph LR; A["sm_dance_bot_warehouse  
::radial_motion_states  
::StiRadialLoopStart::onEntry"] --> B["sm_dance_bot_warehouse  
::radial_motion_states  
::StiRadialLoopStart::loopWhile  
Condition"]
```

sm\_dance\_bot\_warehouse  
::radial\_motion\_states  
::StiRadialLoopStart::loopWhile  
Condition