

```
image_tools::ROSCvMatContainer  
::get_sensor_msgs_msg_image  
_pointer_copy
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a white background and a black border, containing the text 'image_tools::ROSCvMatContainer::get_sensor_msgs_msg_image_pointer_copy'. The right box has a light gray background and a black border, containing the text 'image_tools::ROSCvMatContainer::get_sensor_msgs_msg_image_copy'.

```
image_tools::ROSCvMatContainer  
::get_sensor_msgs_msg_image_copy
```