

sm_aws_warehouse_navigation
::StStartNavigation::sendInitial
PoseEstimation



```
graph LR; A["sm_aws_warehouse_navigation::StStartNavigation::sendInitialPoseEstimation"] --> B["smacc2::ISmaccState::getNode"]
```

A diagram showing a call from the `sm_aws_warehouse_navigation::StStartNavigation::sendInitialPoseEstimation` function to the `smacc2::ISmaccState::getNode` function. The call is represented by a blue arrow pointing from the left box to the right box.

smacc2::ISmaccState
::getNode