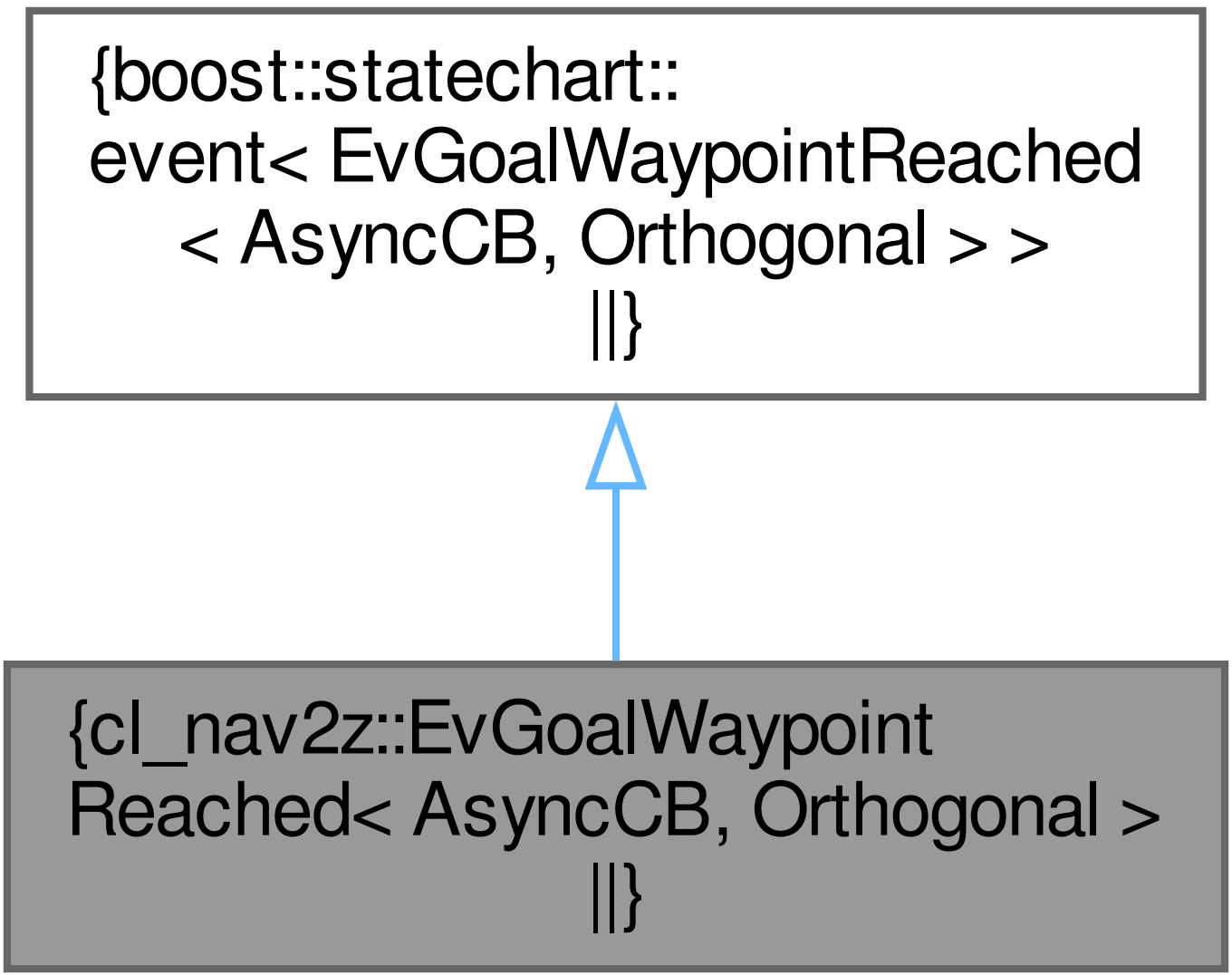
{boost::statechart::
event< EvGoalWaypointReached
< AsyncCB, Orthogonal > >
||}
{cl_nav2z::EvGoalWaypoint
Reached< AsyncCB, Orthogonal >
||}