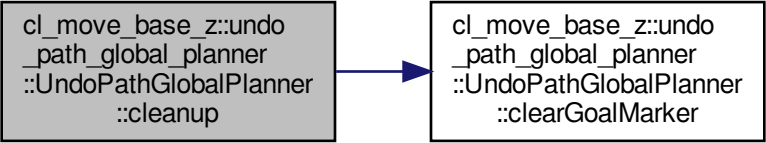


```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::cleanup
```



```
graph LR; A["cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::cleanup"] --> B["cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::clearGoalMarker"]
```

```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::clearGoalMarker
```