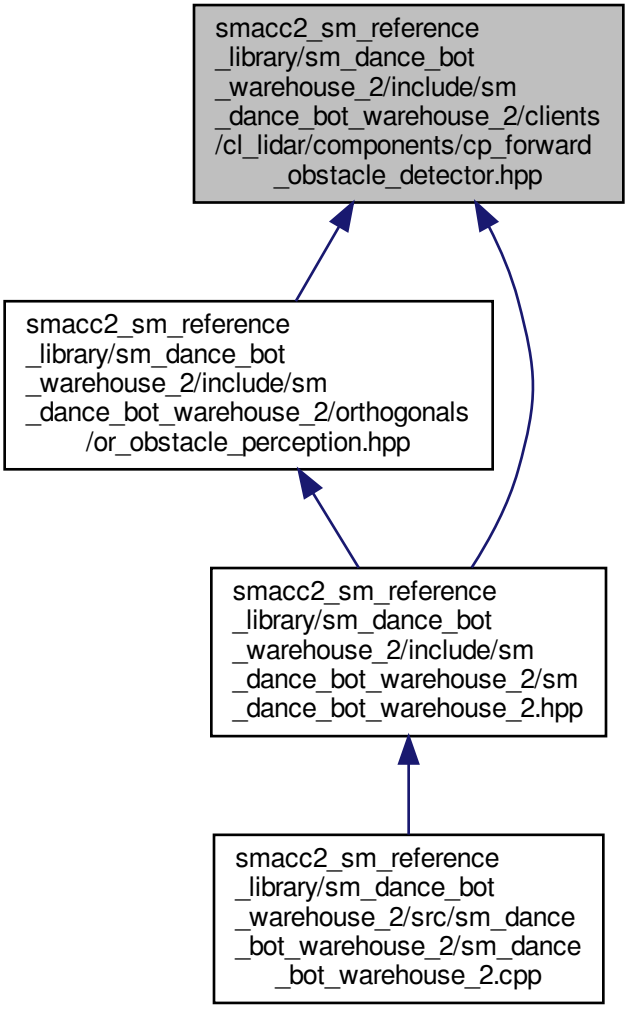
smacc2_sm_reference_library/sm_dance_bot_warehouse_2/include/sm_dance_bot_warehouse_2/clients/cl_lidar/components/cp_forward_obstacle_detector.hpp
smacc2_sm_reference_library/sm_dance_bot_warehouse_2/include/sm_dance_bot_warehouse_2/orthogonals/or_obstacle_perception.hpp
smacc2_sm_reference_library/sm_dance_bot_warehouse_2/include/sm_dance_bot_warehouse_2/sm_dance_bot_warehouse_2.hpp
smacc2_sm_reference_library/sm_dance_bot_warehouse_2/src/sm_dance_bot_warehouse_2/sm_dance_bot_warehouse_2.cpp