

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::findInitialCarrotGoal



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::findInitialCarrotGoal"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeCurrentEuclidean  
AndAngularErrorsToCarrotGoal"]
```

The diagram illustrates a function call sequence. A gray box on the left contains the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', and 'Planner::findInitialCarrotGoal'. A blue arrow points from this box to a white box on the right. The white box contains the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', 'Planner::computeCurrentEuclidean', and 'AndAngularErrorsToCarrotGoal'.

cl_nav2z::backward
_local_planner::BackwardLocal
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