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cl_ros_publisher::CbDefault
PublishLoop
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- deferedPublishFn_- client
- + CbDefaultPublishLoop() + CbDefaultPublishLoop()
- + setMessage()
- + onEntry()
- + update()
- + onExit()

smacc2::event_generators ::EgConditionalGenerator

- + mode
- postEventFalseupdatePredicate

- postEventTrue

- + EgConditionalGenerator()
- + ~ EgConditionalGenerator() + onEntry()
- + onStateAllocation()
- + update()
- + setPredicateFunction()
 checkPredicateAndPost()

smacc2::state_reactors ::EgRandomGenerator

- + mode_
- postEventApostEventB
- postEventC
- evAMin_ - evAMax
- evBMin_
- evBMax_evCMin_
- evCMax_ - minValue
- maxValue
- + EgRandomGenerator() + onEntry()
- + onStateAllocation()
- + postRandomEvents()
 + update()