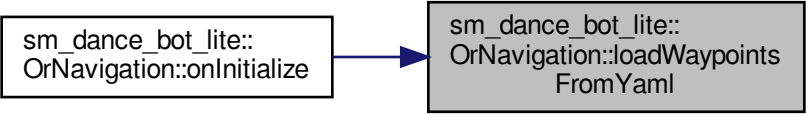


sm\_dance\_bot\_lite::  
OrNavigation::onInitialize



```
graph LR; A[sm_dance_bot_lite::OrNavigation::onInitialize] --> B[sm_dance_bot_lite::OrNavigation::loadWaypointsFromYaml];
```

A diagram showing a call from the `onInitialize` method of the `OrNavigation` class in the `sm_dance_bot_lite` namespace to the `loadWaypointsFromYaml` method of the same class. The source box is white with a black border, and the target box is gray with a black border. A blue arrow points from the source to the target.

sm\_dance\_bot\_lite::  
OrNavigation::loadWaypoints  
FromYaml