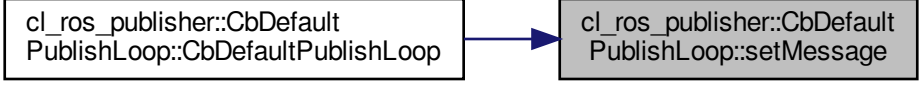
cl_ros_publisher::CbDefaultPublishLoop::CbDefaultPublishLoop
cl_ros_publisher::CbDefaultPublishLoop::setMessage