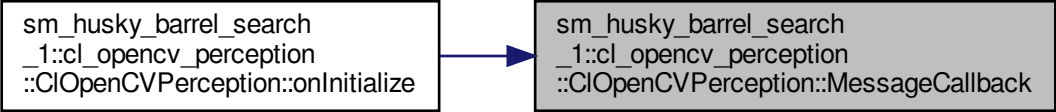


sm_husky_barrel_search
_1::cl_opencv_perception
::ClOpenCVPerception::onInitialize



```
graph LR; A["sm_husky_barrel_search_1::cl_opencv_perception::ClOpenCVPerception::onInitialize"] --> B["sm_husky_barrel_search_1::cl_opencv_perception::ClOpenCVPerception::MessageCallback"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a white background and a black border, containing the text 'sm_husky_barrel_search', '_1::cl_opencv_perception', and '::ClOpenCVPerception::onInitialize' on three lines. The right box has a gray background and a black border, containing the text 'sm_husky_barrel_search', '_1::cl_opencv_perception', and '::ClOpenCVPerception::MessageCallback' on three lines.

sm_husky_barrel_search
_1::cl_opencv_perception
::ClOpenCVPerception::MessageCallback