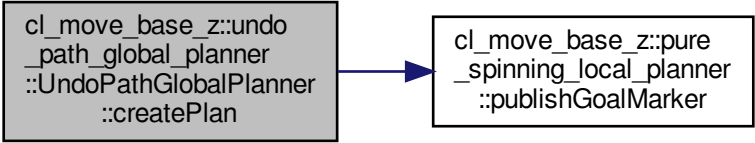


```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::createPlan
```



A diagram illustrating a function call sequence. A grey rectangular box on the left contains the code for the `undo` method of `cl_move_base_z::_path_global_planner::UndoPathGlobalPlanner`, specifically the `createPlan` function. A blue arrow points from this box to a white rectangular box on the right. The white box contains the code for the `publishGoalMarker` function in the `cl_move_base_z::pure_spinning_local_planner` namespace.

```
cl_move_base_z::pure  
_spinning_local_planner  
::publishGoalMarker
```