


cl_ros_publisher::CbDefault
PublishLoop::CbDefaultPublishLoop



```
graph LR; A["cl_ros_publisher::CbDefault  
PublishLoop::CbDefaultPublishLoop"] --> B["cl_ros_publisher::CbDefault  
PublishLoop::setMessage"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl_ros_publisher::CbDefault' and 'PublishLoop::CbDefaultPublishLoop'. The right box is gray with a black border and contains the text 'cl_ros_publisher::CbDefault' and 'PublishLoop::setMessage'.

cl_ros_publisher::CbDefault
PublishLoop::setMessage