

cl\_nav2z::undo\_path  
\_global\_planner::UndoPathGlobal  
Planner::createPlan



```
graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::createPlan"] --> B["cl_nav2z::pure_spinning  
_local_planner::publishGoalMarker"]
```

The diagram illustrates a function call sequence. On the left, a grey rectangular box contains the text 'cl\_nav2z::undo\_path', '\_global\_planner::UndoPathGlobal', and 'Planner::createPlan'. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text 'cl\_nav2z::pure\_spinning' and '\_local\_planner::publishGoalMarker'.

cl\_nav2z::pure\_spinning  
\_local\_planner::publishGoalMarker