

cl\_move\_base\_z::CbNavigate  
Backwards::onEntry

sm\_dance\_bot::radial  
\_motion\_states::StiRadialReturn  
::onExit

cl\_move\_base\_z::odom  
\_tracker::OdomTracker  
::clearPath



```
graph LR; A["cl_move_base_z::CbNavigate Backwards::onEntry"] --> C["cl_move_base_z::odom_tracker::OdomTracker::clearPath"]; B["sm_dance_bot::radial _motion_states::StiRadialReturn::onExit"] --> C;
```

The diagram illustrates a control flow or data dependency. Two source nodes on the left are connected by blue arrows to a single target node on the right. The top source node is labeled 'cl\_move\_base\_z::CbNavigate Backwards::onEntry'. The bottom source node is labeled 'sm\_dance\_bot::radial \_motion\_states::StiRadialReturn::onExit'. The target node is labeled 'cl\_move\_base\_z::odom\_tracker::OdomTracker::clearPath' and has a light gray background.