

cl_nav2z::CbSeekWaypoint
::onEntry

cl_nav2z::CbNavigateNext
WaypointFree::onSucessCallback

cl_nav2z::CpWaypointNavigator
Base::forward

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graph LR; A[cl_nav2z::CbSeekWaypoint::onEntry] --> C[cl_nav2z::CpWaypointNavigatorBase::forward]; B[cl_nav2z::CbNavigateNextWaypointFree::onSucessCallback] --> C;
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The diagram illustrates a function call or dependency relationship. Two source functions, 'cl_nav2z::CbSeekWaypoint::onEntry' and 'cl_nav2z::CbNavigateNextWaypointFree::onSucessCallback', are shown in white boxes on the left. Two blue arrows point from these source functions to a single target function, 'cl_nav2z::CpWaypointNavigatorBase::forward', which is shown in a gray box on the right.