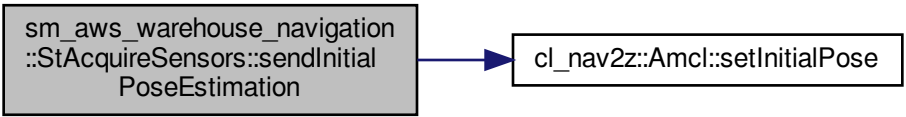
sm_aws_warehouse_navigation
::StAcquireSensors::sendInitial
PoseEstimation
cl_nav2z::Amcl::setInitialPose