```
{smacc2::ISmaccClientBehavior
I- stateMachine

    currentState

    currentOrthogonal

|+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
+ onEntry()
+ onExit()
+ executeOnEntry()
+ executeOnExit()
# runtimeConfigure()
# postEvent()
# postEvent()
# getCurrentState()
# dispose()
# aetNode()
# getLogger()
- onOrthogonalAllocation()
{smacc2::SmaccClientBehavior
||+ onEntry()
+ onExit()
 {cl ros publisher::CbPublish
    Once< RosMsgType >
  I- deferedPublishFn

    client

  |+ CbPublishOnce()
 + CbPublishOnce()
 + setMessage()
 + onEntry()
 + onExit()
```