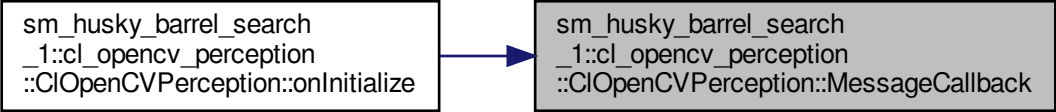


sm\_husky\_barrel\_search  
\_1::cl\_opencv\_perception  
::ClOpenCVPerception::onInitialize



```
graph LR; A["sm_husky_barrel_search_1::cl_opencv_perception::ClOpenCVPerception::onInitialize"] --> B["sm_husky_barrel_search_1::cl_opencv_perception::ClOpenCVPerception::MessageCallback"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a white background and contains the text 'sm\_husky\_barrel\_search', '\_1::cl\_opencv\_perception', and '::ClOpenCVPerception::onInitialize' stacked vertically. The right box has a light gray background and contains the text 'sm\_husky\_barrel\_search', '\_1::cl\_opencv\_perception', and '::ClOpenCVPerception::MessageCallback' stacked vertically.

sm\_husky\_barrel\_search  
\_1::cl\_opencv\_perception  
::ClOpenCVPerception::MessageCallback