stateMachine_ # owner_

- + ISmaccComponent()
- + ~ISmaccComponent() + getName()
- # onInitialize()
- # postEvent()
- # postEvent()
- # onOrthogonalAllocation()
- # requiresComponent()
 # requiresClient()
- # createSiblingComponent()

createSiblingNamedComponent()

- # getNode()
- # getLogger()
- # getStateMachine()
 initialize()
 - setStateMachine()



sm_dance_bot_strikes _back::cl_lidar::CpLidarSensorData

- + lastMessage
- + forwardObstacleDistance
- + SECURITY_DISTANCE

+ onInitialize()

+ MessageCallbackStoreDistance ToWall()