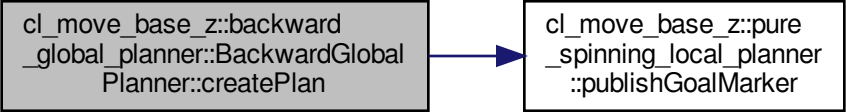


cl_move_base_z::backward
_global_planner::BackwardGlobal
Planner::createPlan



```
graph LR; A["cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::createPlan"] --> B["cl_move_base_z::pure  
_spinning_local_planner  
::publishGoalMarker"]
```

cl_move_base_z::pure
_spinning_local_planner
::publishGoalMarker