

cl_move_base_z::forward
_local_planner::ForwardLocal
Planner::computeVelocityCommands



```
graph LR; A["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands"] --> B["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::generateTrajectory"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box is white with a black border and contains three lines of text. The right box is light gray with a black border and also contains three lines of text. The arrow is a solid blue line with a triangular arrowhead.

cl_move_base_z::forward
_local_planner::ForwardLocal
Planner::generateTrajectory