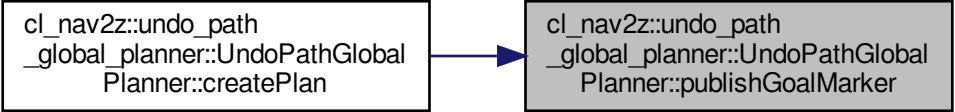


cl\_nav2z::undo\_path  
\_global\_planner::UndoPathGlobal  
Planner::createPlan



```
graph LR; A["cl_nav2z::undo_path<br/>_global_planner::UndoPathGlobal<br/>Planner::createPlan"] --> B["cl_nav2z::undo_path<br/>_global_planner::UndoPathGlobal<br/>Planner::publishGoalMarker"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains three lines of text. The right box is gray with a black border and also contains three lines of text. A blue arrow points from the right side of the white box to the left side of the gray box.

cl\_nav2z::undo\_path  
\_global\_planner::UndoPathGlobal  
Planner::publishGoalMarker