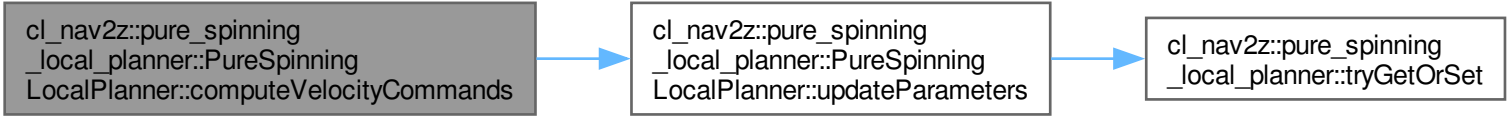


cl_nav2z::pure_spinning
_local_planner::PureSpinning
LocalPlanner::computeVelocityCommands



```
graph LR; A["cl_nav2z::pure_spinning  
_local_planner::PureSpinning  
LocalPlanner::computeVelocityCommands"] --> B["cl_nav2z::pure_spinning  
_local_planner::PureSpinning  
LocalPlanner::updateParameters"]; B --> C["cl_nav2z::pure_spinning  
_local_planner::tryGetOrSet"]
```

The diagram consists of three rectangular boxes connected by blue arrows pointing from left to right. The first box on the left has a gray background and contains the text 'cl_nav2z::pure_spinning', '_local_planner::PureSpinning', and 'LocalPlanner::computeVelocityCommands'. A blue arrow points from the right side of this box to the left side of the second box. The second box in the middle has a white background and contains the text 'cl_nav2z::pure_spinning', '_local_planner::PureSpinning', and 'LocalPlanner::updateParameters'. Another blue arrow points from the right side of this box to the left side of the third box. The third box on the right has a white background and contains the text 'cl_nav2z::pure_spinning' and '_local_planner::tryGetOrSet'.

cl_nav2z::pure_spinning
_local_planner::PureSpinning
LocalPlanner::updateParameters

cl_nav2z::pure_spinning
_local_planner::tryGetOrSet