

cl\_nav2z::backward  
\_global\_planner::BackwardGlobal  
Planner::createPlan



```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createPlan"] --> B["cl_nav2z::pure_spinning  
_local_planner::publishGoalMarker"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and a black border, containing the text 'cl\_nav2z::backward', '\_global\_planner::BackwardGlobal', and 'Planner::createPlan' on three lines. The right box has a white background and a black border, containing the text 'cl\_nav2z::pure\_spinning' and '\_local\_planner::publishGoalMarker' on two lines. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_nav2z::pure\_spinning  
\_local\_planner::publishGoalMarker