

```
sm_dance_bot::StAcquireSensors  
::staticConfigure
```



```
graph LR; A["sm_dance_bot::StAcquireSensors  
::staticConfigure"] --> B["smacc2::SmaccState  
< StAcquireSensors,  
MsDanceBotRunMode >  
::static_createStateReactor"]
```

```
smacc2::SmaccState  
< StAcquireSensors,  
MsDanceBotRunMode >  
::static_createStateReactor
```