

cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::createDefaultBackwardPath

cl_nav2z::forward_global
_planner::ForwardGlobalPlanner
::createPlan

cl_nav2z::makePureSpinning
SubPlan

```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createDefaultBackwardPath"] --> C["cl_nav2z::makePureSpinning  
SubPlan"]; B["cl_nav2z::forward_global  
_planner::ForwardGlobalPlanner  
::createPlan"] --> C;
```

The diagram illustrates a dependency or call relationship. Two source functions, one for backward planning and one for forward planning, both point to a common target function for creating a pure spinning subplan. The source functions are in white boxes, and the target function is in a grey box. Blue arrows indicate the direction of the relationship.