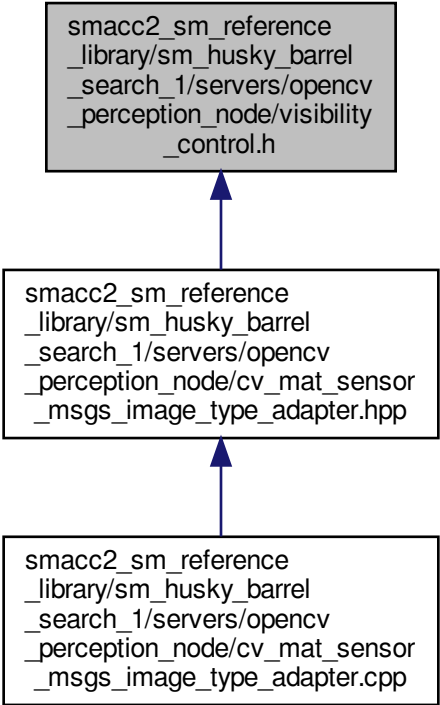


smacc2_sm_reference
_library/sm_husky_barrel
_search_1/servers/opencv
_perception_node/visibility
_control.h



```
graph BT; A["smacc2_sm_reference_library/sm_husky_barrel_search_1/servers/opencv_perception_node/cv_mat_sensor_msgs_image_type_adapter.cpp"] --> B["smacc2_sm_reference_library/sm_husky_barrel_search_1/servers/opencv_perception_node/cv_mat_sensor_msgs_image_type_adapter.hpp"]; B --> C["smacc2_sm_reference_library/sm_husky_barrel_search_1/servers/opencv_perception_node/visibility_control.h"];
```

smacc2_sm_reference
_library/sm_husky_barrel
_search_1/servers/opencv
_perception_node/cv_mat_sensor
_msgs_image_type_adapter.hpp

smacc2_sm_reference
_library/sm_husky_barrel
_search_1/servers/opencv
_perception_node/cv_mat_sensor
_msgs_image_type_adapter.cpp