

cl_move_group_interface
::CbExecuteLastTrajectory
::onEntry

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::onEntry

cl_move_group_interface
::CbUndoLastTrajectory
::onEntry

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::executeJointSpaceTrajectory

```
graph LR; A["cl_move_group_interface  
::CbExecuteLastTrajectory  
::onEntry"] --> D["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::executeJointSpaceTrajectory"]; B["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::onEntry"] --> D; C["cl_move_group_interface  
::CbUndoLastTrajectory  
::onEntry"] --> D;
```

The diagram illustrates a mapping or inheritance relationship. Three source boxes on the left, each containing a function name and its entry point, have blue arrows pointing to a single target box on the right. The target box contains a function name and its implementation. The source boxes are: 1. cl_move_group_interface ::CbExecuteLastTrajectory ::onEntry, 2. cl_move_group_interface ::CbMoveEndEffectorTrajectory ::onEntry, and 3. cl_move_group_interface ::CbUndoLastTrajectory ::onEntry. The target box is: cl_move_group_interface ::CbMoveEndEffectorTrajectory ::executeJointSpaceTrajectory.