

sm_dance_bot_warehouse
::cl_lidar::CpForwardObstacle
Detector::onInitialize



```
graph LR; A["sm_dance_bot_warehouse  
::cl_lidar::CpForwardObstacle  
Detector::onInitialize"] --> B["sm_dance_bot_warehouse  
::cl_lidar::CpForwardObstacle  
Detector::MessageCallbackStoreDistanceToWall"]
```

sm_dance_bot_warehouse
::cl_lidar::CpForwardObstacle
Detector::MessageCallbackStoreDistanceToWall