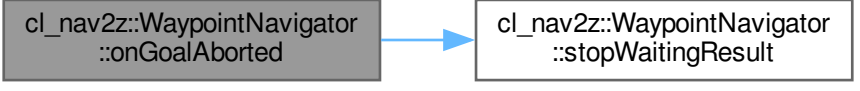
cl_nav2z::WaypointNavigator
::onGoalAborted
cl_nav2z::WaypointNavigator
::stopWaitingResult