

cl\_nav2z::WaypointNavigator  
::onGoalAborted



```
graph LR; A[cl_nav2z::WaypointNavigator::onGoalAborted] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
```

A diagram showing a call from the `onGoalAborted` method to the `stopWaitingResult` method. The source box is shaded gray and the target box is white. A blue arrow points from the source to the target.

cl\_nav2z::WaypointNavigator  
::stopWaitingResult