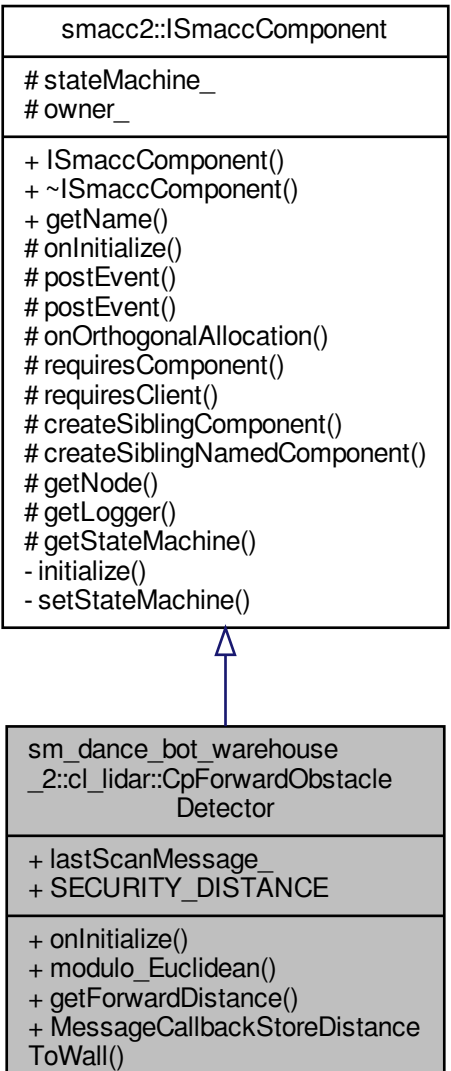
smacc2::ISmaccComponent
stateMachine_
owner_
+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresClient()
# createSiblingComponent()
# createSiblingNamedComponent()
# getNode()
# getLogger()
# getStateMachine()
- initialize()
- setStateMachine()
sm_dance_bot_warehouse_2::cl_lidar::CpForwardObstacleDetector
+ lastScanMessage_
+ SECURITY_DISTANCE
+ onInitialize()
+ modulo_Euclidean()
+ getForwardDistance()
+ MessageCallbackStoreDistanceToWall()