

sm_aws_warehouse_navigation
::StAcquireSensors::sendInitial
PoseEstimation



```
graph LR; A["sm_aws_warehouse_navigation::StAcquireSensors::sendInitialPoseEstimation"] --> B["cl_move_base_z::Amcl::setInitialPose"]
```

A diagram showing a call from the `sm_aws_warehouse_navigation` package to the `cl_move_base_z` package. The call is represented by a blue arrow pointing from a grey box on the left to a white box on the right. The grey box contains the text `sm_aws_warehouse_navigation::StAcquireSensors::sendInitialPoseEstimation` and the white box contains the text `cl_move_base_z::Amcl::setInitialPose`.

cl_move_base_z::Amcl
::setInitialPose