

cl_nav2z::CpWaypointNavigator
Base::loadWaypointsFromYamlParameter



```
graph LR; A["cl_nav2z::CpWaypointNavigator  
Base::loadWaypointsFromYamlParameter"] --> B["cl_nav2z::CpWaypointNavigator  
Base::loadWayPointsFromFile"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl_nav2z::CpWaypointNavigator' and 'Base::loadWaypointsFromYamlParameter'. The right box is gray with a black border and contains the text 'cl_nav2z::CpWaypointNavigator' and 'Base::loadWayPointsFromFile'.

cl_nav2z::CpWaypointNavigator
Base::loadWayPointsFromFile