

```
sm_dance_bot_warehouse  
::StAcquireSensors::staticConfigure
```



```
graph LR; A[sm_dance_bot_warehouse::StAcquireSensors::staticConfigure] --> B[smacc2::SmaccState< StAcquireSensors, MsDanceBotRunMode >::static_createStateReactor]
```

```
smacc2::SmaccState  
< StAcquireSensors,  
  MsDanceBotRunMode >  
::static_createStateReactor
```