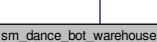
## smacc2::ISmaccComponent

# stateMachine\_ # owner

- + ISmaccComponent()
- + ~ISmaccComponent()
- + getName()
- # onInitialize()
  # postEvent()
- # postEvent()
- # onOrthogonalAllocation()
- # requiresComponent()
  # requiresClient()
- # createSiblingComponent()
- # createSiblingNamedComponent()
  # getNode()
- # getLogger()
  - # getStateMachine()
     initialize()
  - setStateMachine()



::cl\_lidar::CpForwardObstacle
Detector

- + lastScanMessage\_
- + SECURITY\_DISTANCE
- + onInitialize() + modulo Euclidean()
- + getForwardDistance()
- + MessageCallbackStoreDistance ToWall()