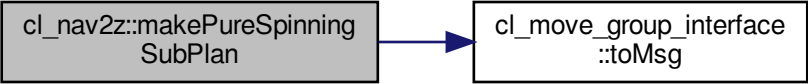


cl_nav2z::makePureSpinning
SubPlan



```
graph LR; A[cl_nav2z::makePureSpinningSubPlan] --> B[cl_move_group_interface::toMsg];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray fill and a black border, containing the text 'cl_nav2z::makePureSpinningSubPlan' in two lines. The right box has a white fill and a black border, containing the text 'cl_move_group_interface::toMsg' in two lines. A dark blue arrow points from the right side of the left box to the left side of the right box.

cl_move_group_interface
::toMsg