

cl_nav2z::WaypointNavigator
::onGoalAborted



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graph LR; A[cl_nav2z::WaypointNavigator::onGoalAborted] --> B[cl_nav2z::WaypointNavigator::stopWaitingResult]
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A diagram showing a call from the `onGoalAborted` method of the `cl_nav2z::WaypointNavigator` class to the `stopWaitingResult` method of the same class. The source box is shaded gray and the target box is white. A blue arrow points from the source to the target.

cl_nav2z::WaypointNavigator
::stopWaitingResult