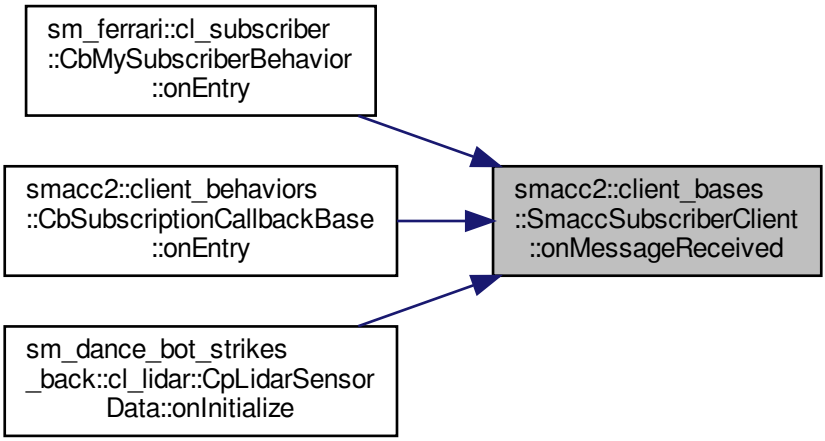


sm_ferrari::cl_subscriber
::CbMySubscriberBehavior
::onEntry

smacc2::client_behaviors
::CbSubscriptionCallbackBase
::onEntry

sm_dance_bot_strikes
_back::cl_lidar::CpLidarSensor
Data::onInitialize

smacc2::client_bases
::SmaccSubscriberClient
::onMessageReceived



```
graph LR; A["sm_ferrari::cl_subscriber  
::CbMySubscriberBehavior  
::onEntry"] --> D["smacc2::client_bases  
::SmaccSubscriberClient  
::onMessageReceived"]; B["smacc2::client_behaviors  
::CbSubscriptionCallbackBase  
::onEntry"] --> D; C["sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::onInitialize"] --> D;
```