

boost::statechart::  
event< EvWaypoint221  
< TSource, TOrthogonal > >

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvWaypoint221< TSource, TOrthogonal > >"]
    class cl_move_base_z_EvWaypoint221["cl_move_base_z::EvWaypoint221< TSource, TOrthogonal >"]
    cl_move_base_z_EvWaypoint221 --|> boost_statechart_event
```

The diagram consists of two class boxes. The top box is white with a black border and contains the text 'boost::statechart::event< EvWaypoint221 < TSource, TOrthogonal > >'. It has two empty rectangular compartments below the text. The bottom box is gray with a black border and contains the text 'cl\_move\_base\_z::EvWaypoint221 < TSource, TOrthogonal >' in its top compartment, '+ waypointIndex' in its middle compartment, and an empty compartment at the bottom. A blue arrow with an open triangular head points from the bottom box to the bottom edge of the top box.

cl\_move\_base\_z::EvWaypoint221  
< TSource, TOrthogonal >

+ waypointIndex