

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::deactivate



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graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobalPlanner::deactivate"] --> B["cl_nav2z::undo_path  
_global_planner::UndoPathGlobalPlanner::clearGoalMarker"]
```

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::clearGoalMarker