

cl_move_group_interface
::CbCircularPouringMotion
::createMarkers

cl_move_group_interface
::CbMoveCartesianRelative2
::generateTrajectory

cl_move_group_interface
::CbCircularPouringMotion
::generateTrajectory

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::getCurrentEndEffectorPose

```
graph LR; A["cl_move_group_interface  
::CbCircularPouringMotion  
::createMarkers"] --> D["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::getCurrentEndEffectorPose"]; B["cl_move_group_interface  
::CbMoveCartesianRelative2  
::generateTrajectory"] --> D; C["cl_move_group_interface  
::CbCircularPouringMotion  
::generateTrajectory"] --> D;
```

The diagram illustrates a mapping or inheritance relationship. Three source boxes on the left point via blue arrows to a single target box on the right. The target box is shaded gray, while the source boxes are white with black borders. The source boxes contain method names from the `cl_move_group_interface` namespace, specifically related to `CbCircularPouringMotion` and `CbMoveCartesianRelative2`. The target box contains methods from the `cl_move_group_interface` namespace, specifically related to `CbMoveEndEffectorTrajectory`.