```
smacc2::ISmaccClientBehavior
    - stateMachine
    - currentState

    currentOrthogonal

   + ISmaccClientBehavior()
   + ~ISmaccClientBehavior()
   + getStateMachine()
   + getName()
   + requiresClient()
   + requiresComponent()
   + onEntry()
   + onExit()
   + executeOnEntry()
   + executeOnExit()
   # runtimeConfigure()
   # postEvent()
   # postEvent()
   # getCurrentState()
   # dispose()
   # getNode()
   # getLogger()
    onOrthogonalAllocation()
                  Д
   smacc2::SmaccAsyncClient
               Behavior
   - onEntryThread
   - onExitThread

    postFinishEventFn

   - postSuccessEventFn
   postFailureEventFn

    onFinished

   - onSuccess_
   - onFailure

    isShutdownRequested

   + onOrthogonalAllocation()
   + ~SmaccAsyncClientBehavior()
   + onSuccess()
   + onFinished()
   + onFailure()
   + requestForceFinish()
   + executeOnEntry()
   + executeOnExit()
   + waitOnEntryThread()
   + onSuccess()
   + onFinished()
   + onFailure()
   # postSuccessEvent()
   # postFailureEvent()
   # dispose()
   #isShutdownRequested()
   - waitFutureIfNotFinished()
cl_nav2z::CbNav2ZClientBehaviorBase
# nav2zClient
# navigationResult
# goalHandleFuture
+ ~CbNav2ZClientBehaviorBase()
+ onOrthogonalAllocation()
# sendGoal()
#isOwnActionResponse()
# onNavigationActionSuccess()
# onNavigationActionAbort()
                  Д
   cl_nav2z::CbNavigateGlobal
               Position
    + goalYaw
   + options

    goalPosition

   + CbNavigateGlobalPosition()
   + CbNavigateGlobalPosition()
   + setGoal()
   + onEntry()
   + onExit()
   + execute()
    - readStartPoseFromParameter
   Server()
```