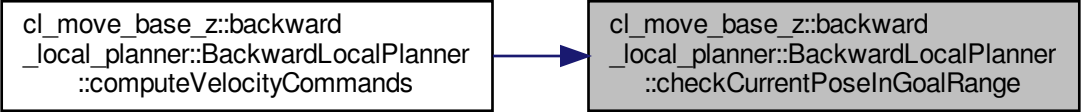


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a call sequence between two functions. On the left, a white box contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::computeVelocityCommands'. A blue arrow points from the right side of this box to the left side of a gray box on the right. The gray box contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::checkCurrentPoseInGoalRange'.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkCurrentPoseInGoalRange
```