

smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/states/st\_navigate\_to\_waypoint\_1.hpp



```
graph BT; A["smacc2_sm_reference  
_library/sm_dance_bot  
_strikes_back/src/sm_dance_bot_strikes_back/sm_dance_bot_strikes_back.cpp"] --> B["smacc2_sm_reference  
_library/sm_dance_bot_strikes_back/include  
/sm_dance_bot_strikes_back  
/sm_dance_bot_strikes_back.hpp"]; B --> C["smacc2_sm_reference  
_library/sm_dance_bot_strikes_back/include  
/sm_dance_bot_strikes_back  
/states/st_navigate_to_waypoint_1.hpp"];
```

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\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/sm\_dance\_bot\_strikes\_back.hpp

smacc2\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/src/sm\_dance  
\_bot\_strikes\_back/sm\_dance  
\_bot\_strikes\_back.cpp