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graph BT; A["smacc2_sm_reference_library/sm_test_moveit_ur5_sim/src/sm_test_moveit_ur5_sim/sm_test_moveit_ur5_sim_node.cpp"] --> B["smacc2_sm_reference_library/sm_test_moveit_ur5_sim/include/sm_test_moveit_ur5_sim/sm_test_moveit_ur5_sim.hpp"]; B --> C["smacc2_sm_reference_library/sm_test_moveit_ur5_sim/include/sm_test_moveit_ur5_sim/st_undo_last_trajectory.hpp"]
```

smacc2\_sm\_reference  
\_library/sm\_test\_moveit  
\_ur5\_sim/include/sm\_test  
\_moveit\_ur5\_sim/states/st  
\_undo\_last\_trajectory.hpp

smacc2\_sm\_reference  
\_library/sm\_test\_moveit  
\_ur5\_sim/include/sm\_test  
\_moveit\_ur5\_sim/sm\_test\_moveit  
\_ur5\_sim.hpp

smacc2\_sm\_reference  
\_library/sm\_test\_moveit  
\_ur5\_sim/src/sm\_test\_moveit  
\_ur5\_sim/sm\_test\_moveit\_ur5  
\_sim\_node.cpp