

cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::setPlan



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::setPlan"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::resamplePrecisePlan"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl\_nav2z::backward', '\_local\_planner::BackwardLocal', and 'Planner::setPlan' on three lines. The right box is light gray with a black border and contains the text 'cl\_nav2z::backward', '\_local\_planner::BackwardLocal', and 'Planner::resamplePrecisePlan' on three lines.

cl\_nav2z::backward  
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