

cl\_move\_group\_interface  
::CbCircularPouringMotion  
::createMarkers

cl\_move\_group\_interface  
::CbMoveCartesianRelative2  
::generateTrajectory

cl\_move\_group\_interface  
::CbCircularPouringMotion  
::generateTrajectory

cl\_move\_group\_interface  
::CbMoveEndEffectorTrajectory  
::getCurrentEndEffectorPose

```
graph LR; A["cl_move_group_interface  
::CbCircularPouringMotion  
::createMarkers"] --> D["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::getCurrentEndEffectorPose"]; B["cl_move_group_interface  
::CbMoveCartesianRelative2  
::generateTrajectory"] --> D; C["cl_move_group_interface  
::CbCircularPouringMotion  
::generateTrajectory"] --> D;
```

The diagram illustrates a mapping or inheritance relationship. Three source boxes on the left, each containing a namespace and two function names, have blue arrows pointing to a single target box on the right. The target box also contains a namespace and two function names. The source boxes are: 1) 'cl\_move\_group\_interface' with functions 'CbCircularPouringMotion::createMarkers' and 'CbCircularPouringMotion::generateTrajectory'; 2) 'cl\_move\_group\_interface' with functions 'CbMoveCartesianRelative2::generateTrajectory' and 'CbMoveCartesianRelative2::generateTrajectory'; 3) 'cl\_move\_group\_interface' with functions 'CbCircularPouringMotion::generateTrajectory' and 'CbCircularPouringMotion::generateTrajectory'. The target box is 'cl\_move\_group\_interface' with functions 'CbMoveEndEffectorTrajectory::getCurrentEndEffectorPose' and 'CbMoveEndEffectorTrajectory::getCurrentEndEffectorPose'.