smacc2::ISmaccClient #components_ stateMachine orthogonal + ISmaccClient() + ~ISmaccClient() + onInitialize() + getName() + getComponent() + getComponent() + getType() + getStateMachine() + connectSignal() + requiresClient() + getComponents() + postEvent() + postEvent() # onOrthogonalAllocation() # createComponent() # createNamedComponent() # getNode() # getLogger() - initialize() - setStateMachine() - setOrthogonal() smacc2::client bases ::SmaccPublisherClient + topicName + queueSize + pub initialized + SmaccPublisherClient() + ~SmaccPublisherClient() + configure() + publish() cl_ros_publisher::ClRosPublisher sm dance bot strikes sm dance bot::cl string _back::cl_string_publisher publisher::CIStringPublisher ::CIStringPublisher + topicName + CIRosPublisher() + topicName + ~ClRosPublisher() + CIStringPublisher() + configure() + CIStringPublisher() + onInitialize() + publish() + onInitialize()