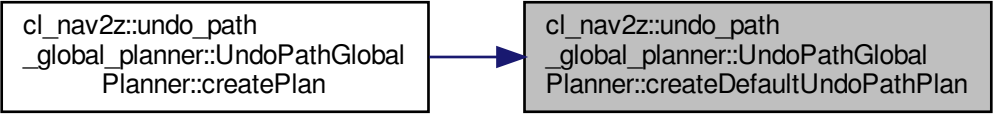


cl\_nav2z::undo\_path  
\_global\_planner::UndoPathGlobal  
Planner::createPlan



```
graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::createPlan"] --> B["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::createDefaultUndoPathPlan"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a white background and a black border, containing the text 'cl\_nav2z::undo\_path', '\_global\_planner::UndoPathGlobal', and 'Planner::createPlan' on three lines. The right box has a light gray background and a black border, containing the text 'cl\_nav2z::undo\_path', '\_global\_planner::UndoPathGlobal', and 'Planner::createDefaultUndoPathPlan' on three lines. The blue arrow originates from the right side of the left box and points to the left side of the right box.

cl\_nav2z::undo\_path  
\_global\_planner::UndoPathGlobal  
Planner::createDefaultUndoPathPlan