

sm\_aws\_warehouse\_navigation  
::StAcquireSensors::sendInitial  
PoseEstimation



```
graph LR; A["sm_aws_warehouse_navigation::StAcquireSensors::sendInitialPoseEstimation"] --> B["cl_nav2z::Amcl::setInitialPose"]
```

A diagram showing a call from the `sm_aws_warehouse_navigation::StAcquireSensors::sendInitialPoseEstimation` function to the `cl_nav2z::Amcl::setInitialPose` function. The call is represented by a blue arrow pointing from the left box to the right box.

cl\_nav2z::Amcl::setInitialPose