

cl_ros_publisher::CbPublish
Once::CbPublishOnce



```
graph LR; A[cl_ros_publisher::CbPublishOnce::CbPublishOnce] --> B[cl_ros_publisher::CbPublishOnce::setMessage]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl_ros_publisher::CbPublishOnce::CbPublishOnce'. The right box is gray with a black border and contains the text 'cl_ros_publisher::CbPublishOnce::setMessage'.

cl_ros_publisher::CbPublish
Once::setMessage