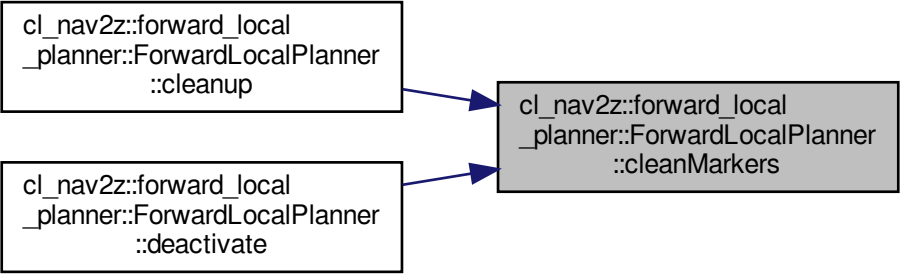


cl\_nav2z::forward\_local  
\_planner::ForwardLocalPlanner  
::cleanup

cl\_nav2z::forward\_local  
\_planner::ForwardLocalPlanner  
::deactivate

cl\_nav2z::forward\_local  
\_planner::ForwardLocalPlanner  
::cleanMarkers



```
graph LR; A["cl_nav2z::forward_local_planner::ForwardLocalPlanner::cleanup"] --> C["cl_nav2z::forward_local_planner::ForwardLocalPlanner::cleanMarkers"]; B["cl_nav2z::forward_local_planner::ForwardLocalPlanner::deactivate"] --> C;
```

The diagram illustrates a call graph with two source nodes on the left and one target node on the right. The top source node, labeled 'cl\_nav2z::forward\_local\_planner::ForwardLocalPlanner::cleanup', has a blue arrow pointing to the target node. The bottom source node, labeled 'cl\_nav2z::forward\_local\_planner::ForwardLocalPlanner::deactivate', also has a blue arrow pointing to the same target node. The target node is labeled 'cl\_nav2z::forward\_local\_planner::ForwardLocalPlanner::cleanMarkers' and is shaded gray, while the source nodes are white with black borders.