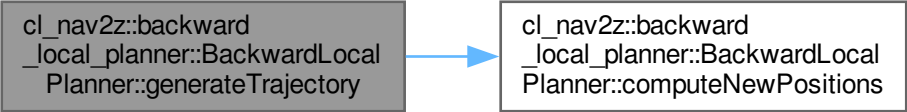


cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::generateTrajectory



cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::computeNewPositions