

sm\_dance\_bot\_warehouse  
\_3::OrNavigation::onInitialize



```
graph LR; A[sm_dance_bot_warehouse_3::OrNavigation::onInitialize] --> B[sm_dance_bot_warehouse_3::OrNavigation::loadWaypointsFromYaml];
```

A diagram showing a call from the `onInitialize` method to the `loadWaypointsFromYaml` method. The source box is white with a black border, and the target box is gray with a black border. A blue arrow points from the source to the target.

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\_3::OrNavigation::loadWaypoints  
FromYaml