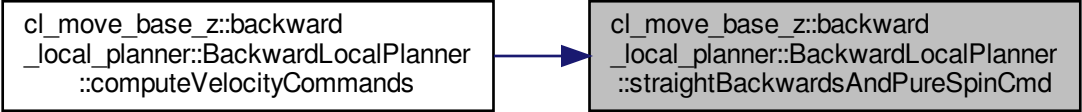
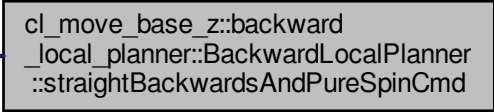


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A rectangular box with a black border containing three lines of C++ code. The first line is `cl_move_base_z::backward`, the second is `_local_planner::BackwardLocalPlanner`, and the third is `::computeVelocityCommands`. A blue arrow points from the right side of this box to the left side of the box on the right.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```



A rectangular box with a black border and a light gray fill, containing three lines of C++ code. The first line is `cl_move_base_z::backward`, the second is `_local_planner::BackwardLocalPlanner`, and the third is `::straightBackwardsAndPureSpinCmd`. A blue arrow points from the left side of this box to the right side of the box on the left.