

```
sm_dance_bot::StAcquireSensors  
::staticConfigure
```



```
graph LR; A[sm_dance_bot::StAcquireSensors::staticConfigure] --> B[smacc2::SmaccState< StAcquireSensors, MsDanceBotRunMode >::static_createStateReactor];
```

```
smacc2::SmaccState  
< StAcquireSensors,  
MsDanceBotRunMode >  
::static_createStateReactor
```