```
smacc2::ISmaccClientBehavior
    -stateMachine
    - currentState
    - currentOrthogonal
    + ISmaccClientBehavior()
    + ~ISmaccClientBehavior()
    + getStateMachine()
    + getName()
    + requiresClient()
    + requiresComponent()
+ onEntry()
    + onExit()
    + executeOnEntry()
    + executeOnExit()
    # runtimeConfigure()
    # postEvent()
    # postEvent()
    # getCurrentState()
    # dispose()
    # getNode()
    # getLogger()
    - onOrthogonalAllocation()
                  Δ
   smacc2::SmaccAsyncClient
               Behavior
    onEntryThread
   - on Exit Thread
   - postFinishEventFn
   - postSuccessEventFn
   - postFailureEventFn_
    onFinished_
   - onSuccess

    onFailure

    isShutdownRequested_

   + onOrthogonalAllocation()
   + ~SmaccAsyncClientBehavior()
   + onSuccess()
   + onFinished()
   + onFailure()
   + requestForceFinish()
   + executeOnEntry()
   + executeOnExit()
   + waitOnEntryThread()
   + onSuccess()
   + onFinished()
   + onFailure()
   # postSuccessEvent()
   # postFailureEvent()
   # dispose()
   #isShutdownRequested()
   - waitFutureIfNotĖinisheď()
                   Δ
cl_nav2z::CbNav2ZClientBehaviorBase
# nav2zClient
# navigationResult
# goalHandleFuture
+ ~CbNav2ZClientBehaviorBase()
+ onOrthogonalAllocation()
# sendGoal()
# cancelGoal()
#isOwnActionResponse()
# onNavigationActionSuccess()
# onNavigationActionAbort()
                   Δ
  cl nav2z::CbUndoPathBackwards
  + goalChecker
   - listener

    odomTracker

  + onEntry()
  + onExit()
```