

```
image_tools::ROSCvMatContainer  
::get_sensor_msgs_msg_image  
_pointer_copy
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'image\_tools::ROSCvMatContainer::get\_sensor\_msgs\_msg\_image\_pointer\_copy'. The right box is gray with a black border and contains the text 'image\_tools::ROSCvMatContainer::get\_sensor\_msgs\_msg\_image\_copy'.

```
image_tools::ROSCvMatContainer  
::get_sensor_msgs_msg_image_copy
```