

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::cleanup



```
graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::cleanup"] --> B["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::clearGoalMarker"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a gray background and a black border, containing the text 'cl_nav2z::undo_path', '_global_planner::UndoPathGlobal', and 'Planner::cleanup' on three lines. The right box has a white background and a black border, containing the text 'cl_nav2z::undo_path', '_global_planner::UndoPathGlobal', and 'Planner::clearGoalMarker' on three lines. A blue arrow points from the right side of the left box to the left side of the right box.

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::clearGoalMarker