

cl_move_base_z::forward
_local_planner::ForwardLocal
Planner::generateTrajectory



```
graph LR; A["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::generateTrajectory"] --> B["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeNewPositions"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and contains the text 'cl_move_base_z::forward', '_local_planner::ForwardLocal', and 'Planner::generateTrajectory' on three lines. The right box has a white background and contains the text 'cl_move_base_z::forward', '_local_planner::ForwardLocal', and 'Planner::computeNewPositions' on three lines. A dark blue arrow points from the right side of the left box to the left side of the right box.

cl_move_base_z::forward
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Planner::computeNewPositions