

cl_nav2z::pure_spinning
_local_planner::PureSpinning
LocalPlanner::updateParameters



```
graph LR; A["cl_nav2z::pure_spinning  
_local_planner::PureSpinning  
LocalPlanner::updateParameters"] --> B["cl_nav2z::pure_spinning  
_local_planner::tryGetOrSet"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and a black border, containing three lines of text. The right box has a white background and a black border, containing two lines of text. The arrow is a solid blue line with a triangular arrowhead.

cl_nav2z::pure_spinning
_local_planner::tryGetOrSet