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-name\_

-backwardsPlanPath\_

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-goalMarkerPublisher  
-planPub\_  
-tf\_

-alpha\_offset\_  
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-carrot\_distance  
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-k\_alpha\_  
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-linear\_mode\_rho  
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-waitingTimeout\_

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-enable\_obstacle\_checking  
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-inGoalPureSpinningState  
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-currentCarrotPoseIndex\_

