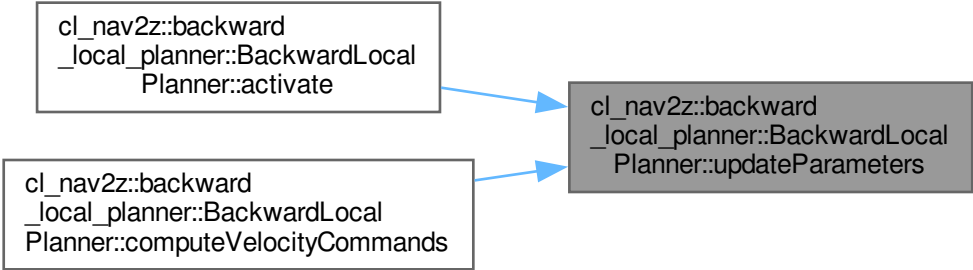


cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::activate

cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::computeVelocityCommands

cl\_nav2z::backward  
\_local\_planner::BackwardLocal  
Planner::updateParameters



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::activate"] --> C["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::updateParameters"]; B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::computeVelocityCommands"] --> C;
```