

cl_nav2z::backward
_global_planner::BackwardGlobal
Planner::createPlan



```
graph LR; A["cl_nav2z::backward  
_global_planner::BackwardGlobal  
Planner::createPlan"] --> B["cl_nav2z::pure_spinning  
_local_planner::publishGoalMarker"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl_nav2z::backward', '_global_planner::BackwardGlobal', and 'Planner::createPlan' on three lines. The right box is white with a black border and contains the text 'cl_nav2z::pure_spinning' and '_local_planner::publishGoalMarker' on two lines. A blue arrow points from the right side of the left box to the left side of the right box.

cl_nav2z::pure_spinning
_local_planner::publishGoalMarker