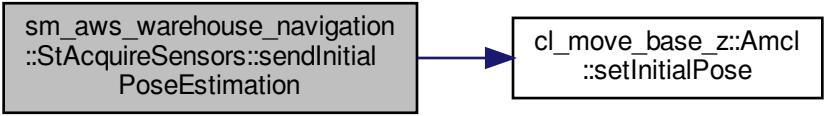
sm_aws_warehouse_navigation
::StAcquireSensors::sendInitial
PoseEstimation
cl_move_base_z::Amcl
::setInitialPose