smacc2::ISmaccComponent # stateMachine # owner + ISmaccComponent() + ~ISmaccComponent() + getName() # onInitialize() # postEvent() # postEvent() # onOrthogonalAllocation() # requiresComponent() # requiresClient() # createSiblingComponent() # createSiblingNamedComponent() # getNode() # getLogger() # getStateMachine() initialize() setStateMachine() cl_nav2z::PlannerSwitcher desired planner desired controller - set planners mode flag - planner selector pub - controller selector pub - goal checker selector pub

- goal_checker_selector_pub_ + PlannerSwitcher() + onlnitialize() + setDesiredGlobalPlanner() + setDesiredController() + commitPublish() + setBackwardPlanner() + setUndoPathBackwardPlanner() + setForwardPlanner() + setPureSpinningPlanner()

+ setDefaultPlanners()