smacc2::ISmaccComponent

stateMachine_
owner_

+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresComponent()
# requiresClient()
# createSiblingComponent()
# createSiblingNamedComponent()
# getNode()
# getLogger()
# getStateMachine()
- initialize()
- setStateMachine()

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cl_nitrosz::CpWaypointNavigatorBase

+ waypointsEventDispatcher
+ currentWaypoint_
# waypoints_
# waypointsNames_

+ CpWaypointNavigatorBase()
+ ~CpWaypointNavigatorBase()
+ onInitialize()
+ loadWayPointsFromFile()
+ loadWayPointsFromFile2()
+ setWaypoints()
+ setWaypoints()
+ getWaypoints()
+ getWaypointNames()
+ getNamedPose()
+ getPose()
+ getCurrentPose()
+ getCurrentWaypointIndex()
+ getCurrentWaypointName()
+ rewind()
+ forward()
+ seekName()
+ loadWaypointsFromYamlParameter()
+ notifyGoalReached()
# insertWaypoint()
# removeWaypoint()

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cl_nitrosz::CpWaypointNavigator

+ client_
+ onNavigationRequestSucceded
+ onNavigationRequestAborted
+ onNavigationRequestCancelled
- succeddedNav2ZClientConnection_
- abortedNav2ZClientConnection_
- cancelledNav2ZClientConnection_

+ CpWaypointNavigator()
+ onInitialize()
+ onOrthogonalAllocation()
+ sendNextGoal()
+ stopWaitingResult()
- onNavigationResult()
- onGoalReached()
- onGoalCancelled()
- onGoalAborted()