

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::createPlan



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graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::createPlan"] --> B["cl_nav2z::pure_spinning  
_local_planner::publishGoalMarker"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and a black border, containing three lines of text. The right box has a white background and a black border, also containing two lines of text. The blue arrow originates from the right side of the left box and points to the left side of the right box.

cl_nav2z::pure_spinning
_local_planner::publishGoalMarker