

cl_move_group_interface
::CbExecuteLastTrajectory
::onEntry

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::onEntry

cl_move_group_interface
::CbUndoLastTrajectory
::onEntry

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::executeJointSpaceTrajectory

```
graph LR; A["cl_move_group_interface  
::CbExecuteLastTrajectory  
::onEntry"] --> D["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::executeJointSpaceTrajectory"]; B["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::onEntry"] --> D; C["cl_move_group_interface  
::CbUndoLastTrajectory  
::onEntry"] --> D;
```

The diagram illustrates a mapping or inheritance relationship. On the left, there are three white rectangular boxes, each containing a function signature from the `cl_move_group_interface`. Blue arrows point from each of these three boxes to a single gray rectangular box on the right. The gray box contains a function signature that appears to be a more complete or final version of the functions in the white boxes, specifically for the `executeJointSpaceTrajectory` method.