

cl\_nav2z::pure\_spinning  
\_local\_planner::PureSpinning  
LocalPlanner::computeVelocityCommands



```
graph LR; A["cl_nav2z::pure_spinning  
_local_planner::PureSpinning  
LocalPlanner::computeVelocityCommands"] --> B["cl_nav2z::pure_spinning  
_local_planner::PureSpinning  
LocalPlanner::updateParameters"]; B --> C["cl_nav2z::pure_spinning  
_local_planner::tryGetOrSet"]
```

The diagram consists of three rectangular boxes connected by blue arrows pointing from left to right. The first box on the left has a gray background and contains the text 'cl\_nav2z::pure\_spinning', '\_local\_planner::PureSpinning', and 'LocalPlanner::computeVelocityCommands'. The middle box has a white background and contains 'cl\_nav2z::pure\_spinning', '\_local\_planner::PureSpinning', and 'LocalPlanner::updateParameters'. The third box on the right also has a white background and contains 'cl\_nav2z::pure\_spinning', '\_local\_planner::tryGetOrSet'. All boxes have a thin black border.

cl\_nav2z::pure\_spinning  
\_local\_planner::PureSpinning  
LocalPlanner::updateParameters

cl\_nav2z::pure\_spinning  
\_local\_planner::tryGetOrSet