

smacc2_sm_reference
_library/sm_dance_bot
_warehouse_2/include/sm
_dance_bot_warehouse_2/orthogonals
/or_obstacle_perception.hpp



```
graph BT; A["smacc2_sm_reference_library/sm_dance_bot_warehouse_2/src/sm_dance_bot_warehouse_2/sm_dance_bot_warehouse_2.cpp"] --> B["smacc2_sm_reference_library/sm_dance_bot_warehouse_2/include/sm_dance_bot_warehouse_2/sm_dance_bot_warehouse_2.hpp"]; B --> C["smacc2_sm_reference_library/sm_dance_bot_warehouse_2/include/sm_dance_bot_warehouse_2/orthogonals/or_obstacle_perception.hpp"];
```

The diagram illustrates the include chain for the file `sm_dance_bot_warehouse_2.cpp`. It starts at the bottom with the source file, which includes `sm_dance_bot_warehouse_2.hpp`. This header file then includes `orthogonals/or_obstacle_perception.hpp`. The boxes are arranged vertically, with arrows pointing upwards from the source file to the header, and from the header to the orthogonals header.

smacc2_sm_reference
_library/sm_dance_bot
_warehouse_2/include/sm
_dance_bot_warehouse_2/sm
_dance_bot_warehouse_2.hpp

smacc2_sm_reference
_library/sm_dance_bot
_warehouse_2/src/sm_dance
_bot_warehouse_2/sm_dance
_bot_warehouse_2.cpp