```
smacc2::ISmaccClientBehavior
    stateMachine
    currentState
    currentOrthogonal
   ISmaccClientBehavior()
 +
    ~ISmaccClientBehavior()
 +
 + getStateMachine()
   getName()
 + requiresClient()
 +
   requiresComponent()
 + onEntry()
   onExit()
 + executeOnEntry()
   executeOnExit()
 # runtimeConfigure()
 # postEvent()
 # postEvent()
 # getCurrentState()
 # dispose()
 # getNode()
 # getLogger()
    onOrthogonalAllocation()
  smacc2::SmaccAsyncClient
           Behavior

    onEntryThread

onExitThread

    postFinishEventFn

 postSuccessEventFn

    postFailureEventFn

    onFinished

- onSuccess
onFailure
- isShutdownRequested
+ onOrthogonalAllocation()
+ ~SmaccAsyncClientBehavior()
+ onSuccess()
+ onFinished()
+ onFailure()
+ requestForceFinish()
+ executeOnEntry()
+ executeOnExit()
+ waitOnEntryThread()
+ onSuccess()
+ onFinished()
+ onFailure()
# postSuccessEvent()
# postFailureEvent()
# dispose()
# isShutdownRequested()

    waitFutureIfNotFinished()

    CbServiceCall< nav2
     _msgs::srv::SaveMap >
    resultFuture
    + result_
    + pollRate_
    # client_
    # serviceName
    # request_
    + CbServiceCall()
    + CbServiceCall()
    + onEntry()
    # onServiceResponse()
  cl_nav2z::CbSaveSlamMap
       CbSaveSlamMap()
   +
```

onExit()

+ getRequest()

+