

cl_nav2z::CbRotateLookAt
::onEntry

cl_nav2z::CbWaitPose
::onEntry

cl_nav2z::Pose::waitTransform
Update

```
graph LR; A[cl_nav2z::CbRotateLookAt::onEntry] --> C[cl_nav2z::Pose::waitTransformUpdate]; B[cl_nav2z::CbWaitPose::onEntry] --> C;
```

The diagram illustrates a shared resource or function. On the left, two white rectangular boxes represent callback functions: 'cl_nav2z::CbRotateLookAt::onEntry' (top) and 'cl_nav2z::CbWaitPose::onEntry' (bottom). On the right, a gray rectangular box represents a shared function: 'cl_nav2z::Pose::waitTransformUpdate'. Two blue arrows point from each of the left boxes to the right box, indicating that both callbacks interact with or call the shared function.