

sm\_aws\_warehouse\_navigation  
::StAcquireSensors::sendInitial  
PoseEstimation



```
graph LR; A["sm_aws_warehouse_navigation::StAcquireSensors::sendInitialPoseEstimation"] --> B["cl_nav2z::Amcl::setInitialPose"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'sm\_aws\_warehouse\_navigation::StAcquireSensors::sendInitialPoseEstimation' on three lines. The right box is gray with a black border and contains the text 'cl\_nav2z::Amcl::setInitialPose' on one line. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_nav2z::Amcl::setInitialPose