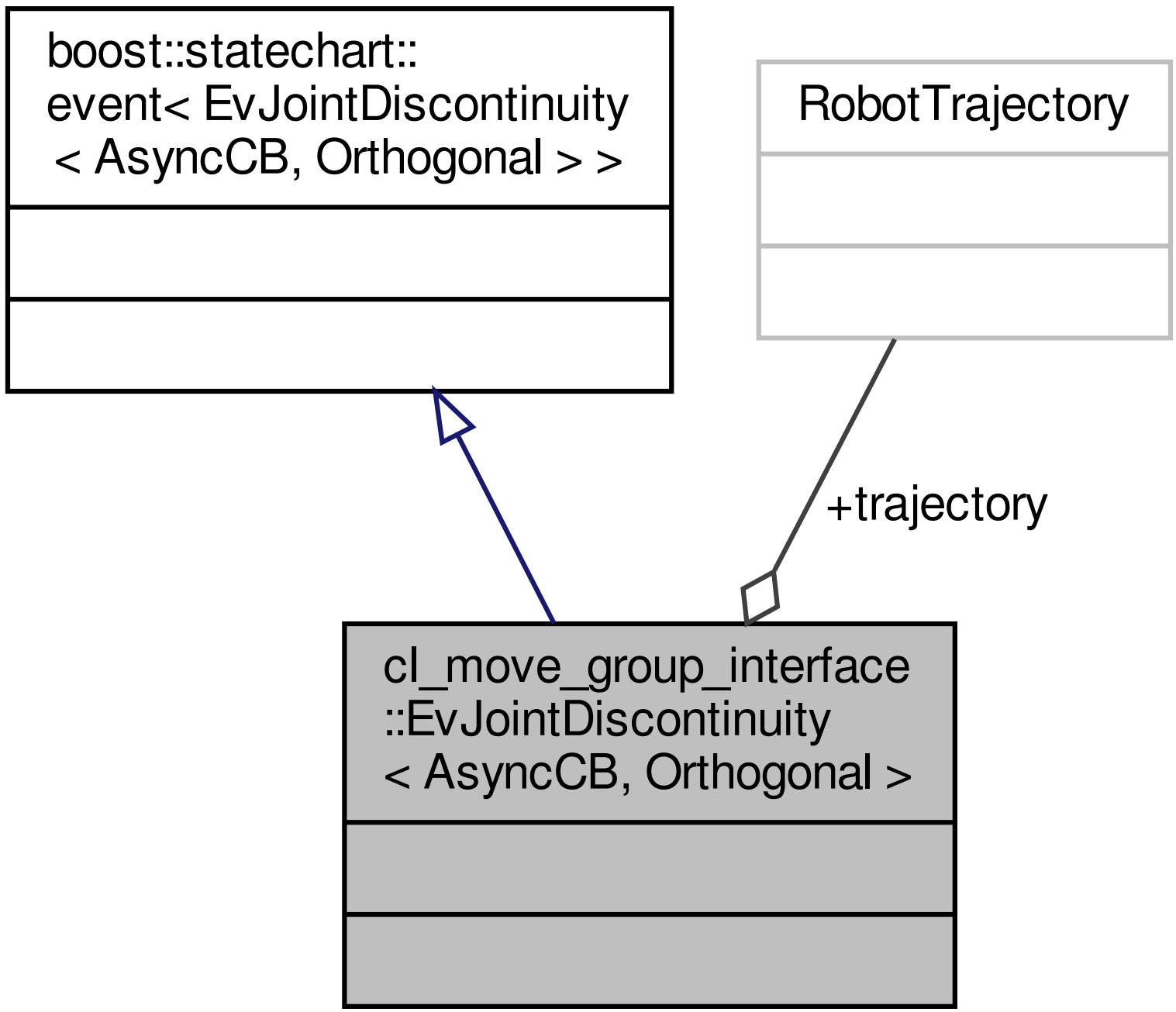
boost::statechart::
event< EvJointDiscontinuity
< AsyncCB, Orthogonal > >
RobotTrajectory
+trajectory
cl_move_group_interface
::EvJointDiscontinuity
< AsyncCB, Orthogonal >