

sm\_dance\_bot::OrNavigation  
::loadWaypointsFromYaml

sm\_dance\_bot\_strikes  
\_back::OrNavigation::  
loadWaypointsFromYaml

cl\_move\_base\_z::Waypoint  
Navigator::loadWayPointsFromFile

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graph LR; A[sm_dance_bot::OrNavigation::loadWaypointsFromYaml] --> C[cl_move_base_z::WaypointNavigator::loadWayPointsFromFile]; B[sm_dance_bot_strikes_back::OrNavigation::loadWaypointsFromYaml] --> C;
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The diagram illustrates a dependency or call relationship. Two source boxes on the left point via blue arrows to a single target box on the right. The top source box contains the text 'sm\_dance\_bot::OrNavigation::loadWaypointsFromYaml'. The bottom source box contains the text 'sm\_dance\_bot\_strikes\_back::OrNavigation::loadWaypointsFromYaml'. The target box, which has a gray background, contains the text 'cl\_move\_base\_z::WaypointNavigator::loadWayPointsFromFile'.