

```
sm_dance_bot_warehouse  
_2::StNavigateToWaypoint1  
::onExit
```



A diagram showing a transition from a state machine state to a state machine definition. A grey box on the left contains the state name and its exit action. A blue arrow points from this box to a white box on the right, which contains the state machine definition.

```
smacc2::SmaccState  
< StNavigateToWaypoint1,  
  MsDanceBotRunMode >::requires  
  Component
```