

sm\_dance\_bot::radial  
\_motion\_states::StiRadialLoop  
Start::onEntry



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graph LR; A["sm_dance_bot::radial<br/>_motion_states::StiRadialLoop<br/>Start::onEntry"] --> B["sm_dance_bot::radial<br/>_motion_states::StiRadialLoop<br/>Start::loopWhileCondition"]
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\_motion\_states::StiRadialLoop  
Start::loopWhileCondition