smacc2::ISmaccClient # components - stateMachine_ - orthogonal_ + ISmaccClient() + ~ISmaccClient() + onInitialize() + getName() + getComponent() + getComponent() + getComponent() + getType() + getStateMachine() + connectSignal() + requiresClient() + getComponents() + postEvent() + postEvent() # onOrthogonalAllocation() # createComponent() # createNamedComponent() #getNode() # getLogger() - initialize() - setStateMachine() - setOrthogonal() smacc2::client bases ::SmaccPublisherClient + topicName + queueSize + durability + reliability + pub - initialized + SmaccPublisherClient() + ~SmaccPublisherClient() + configure() + publish() cl ros publisher::ClRosPublisher sm dance bot strikes sm dance bot warehouse sm dance bot warehouse sm dance bot warehouse sm_dance_bot::cl_string _back::cl_string_publisher _2::cl_string_publisher _3::cl_string_publisher ::cl string publisher publisher::ClStringPublisher ::CIStringPublisher ::CIStringPublisher ::CIStringPublisher ::CIStringPublisher + topicName + CIRosPublisher() + topicName + topicName + topicName + topicName + ~ClRosPublisher() + CIStringPublisher() + configure() + CIStringPublisher() + CIStringPublisher() + CIStringPublisher() + CIStringPublisher() + onInitialize() + publish() + onInitialize() + onInitialize() + onInitialize() + onInitialize()