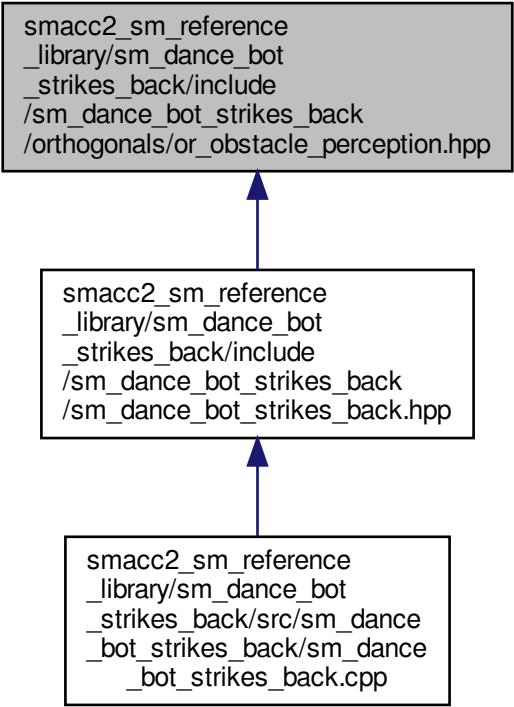


smacc2_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/orthogonals/or_obstacle_perception.hpp



smacc2_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/sm_dance_bot_strikes_back.hpp

smacc2_sm_reference
_library/sm_dance_bot
_strikes_back/src/sm_dance
_bot_strikes_back/sm_dance
_bot_strikes_back.cpp