

sm\_dance\_bot::OrNavigation  
::loadWaypointsFromYaml

sm\_dance\_bot\_strikes  
\_back::OrNavigation::  
loadWaypointsFromYaml

cl\_nav2z::WaypointNavigator  
::loadWayPointsFromFile

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graph LR; A["sm_dance_bot::OrNavigation::loadWaypointsFromYaml"] --> C["cl_nav2z::WaypointNavigator::loadWayPointsFromFile"]; B["sm_dance_bot_strikes_back::OrNavigation::loadWaypointsFromYaml"] --> C;
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The diagram illustrates a dependency or call relationship. Two state machine actions, 'sm\_dance\_bot::OrNavigation::loadWaypointsFromYaml' and 'sm\_dance\_bot\_strikes\_back::OrNavigation::loadWaypointsFromYaml', are shown in white boxes on the left. Blue arrows from both boxes point to a gray box on the right labeled 'cl\_nav2z::WaypointNavigator::loadWayPointsFromFile', indicating that both state machine actions invoke this specific function.