

cl_ros_publisher::CbPublish
Once::setMessage



```
graph LR; A[cl_ros_publisher::CbPublishOnce::setMessage] --> B[cl_ros_publisher::ClRosPublisher::publish];
```

A diagram showing a call from a callback function to a publisher's publish method. On the left, a gray rectangular box contains the text 'cl_ros_publisher::CbPublishOnce::setMessage'. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. This white box contains the text 'cl_ros_publisher::ClRosPublisher::publish'.

cl_ros_publisher::ClRosPublisher
::publish