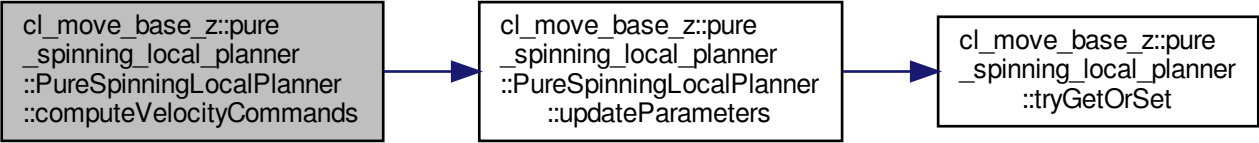


cl_move_base_z::pure
_spinning_local_planner
::PureSpinningLocalPlanner
::computeVelocityCommands



```
graph LR; A["cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands"] --> B["cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::updateParameters"]; B --> C["cl_move_base_z::pure  
_spinning_local_planner  
::tryGetOrSet"]
```

cl_move_base_z::pure
_spinning_local_planner
::PureSpinningLocalPlanner
::updateParameters

cl_move_base_z::pure
_spinning_local_planner
::tryGetOrSet