```
smacc2::ISmaccClientBehavior
        stateMachine
        currentState
       currentOrthogonal
     + ISmaccClientBehavior()
       ~ISmaccClientBehavior()
     +
     + getStateMachine()
     + getName()
     + requiresClient()
     + requiresComponent()
     + onEntry()
     + onExit()
     + executeOnEntry()
     + executeOnExit()
     # runtimeConfigure()
     # postEvent()
     # postEvent()
     # getCurrentState()
     # dispose()
     # getNode()
     # getLogger()
        onOrthogonalAllocation()
     smacc2::SmaccAsyncClient
               Behavior

    onEntryThread_

    onExitThread

    postFinishEventFn_

    postSuccessEventFn

    postFailureEventFn

    onFinished

   - onSuccess_
   - onFailure_
    isShutdownRequested_
   + onOrthogonalAllocation()
   + ~SmaccAsyncClientBehavior()
   + onSuccess()
   + onFinished()
   + onFailure()
   + requestForceFinish()
   + executeOnEntry()
   + executeOnExit()
   + waitOnEntryThread()
   + onSuccess()
   + onFinished()
   + onFailure()
   # postSuccessEvent()
   # postFailureEvent()
   # dispose()
   # isShutdownRequested()
   - waitFutureIfNotFinished()
cl_nav2z::CbNav2ZClientBehaviorBase
 #
    nav2zClient_
 #
    navigationCallback_
 # navigationResult_
    goalHandleFuture_
 #
    ~CbNav2ZClientBehaviorBase()
 +
    onOrthogonalAllocation()
 +
 #
    sendGoal()
 # cancelGoal()
    isOwnActionResponse()
    onNavigationResult()
    onNavigationActionSuccess()
 #
 #
    onNavigationActionAbort()
     cl_nav2z::CbAbsoluteRotate
+ absoluteGoalAngleDegree
+ yawGoalTolerance
+ maxVelTheta
+ spinningPlanner

    oldYawTolerance

 oldMaxVelTheta
 oldMinVelTheta
+ CbAbsoluteRotate()
+ CbAbsoluteRotate()
+ onEntry()
+ onExit()
- updateTemporalBehaviorParameters()
      cl_nav2z::CbRotateLookAt
           listener
           lookAtPose_
        + CbRotateLookAt()
           CbRotateLookAt()
```

onEntry()