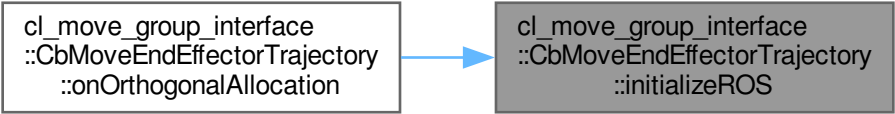


cl_move_group_interface
::CbMoveEndEffectorTrajectory
::onOrthogonalAllocation



```
graph LR; A["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::onOrthogonalAllocation"] --> B["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::initializeROS"]
```

cl_move_group_interface
::CbMoveEndEffectorTrajectory
::initializeROS