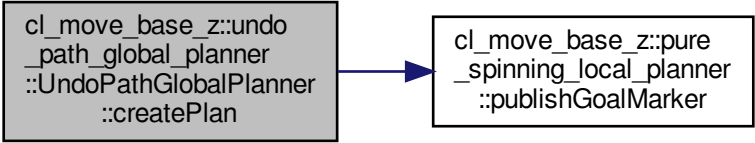


```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::createPlan
```



The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl_move_base_z::undo _path_global_planner ::UndoPathGlobalPlanner ::createPlan'. The right box is white and contains the text 'cl_move_base_z::pure _spinning_local_planner ::publishGoalMarker'. A blue arrow points from the right side of the left box to the left side of the right box.

```
cl_move_base_z::pure  
_spinning_local_planner  
::publishGoalMarker
```