```
{nav2 core::GlobalPlanner
               ||}
{cl nav2z::undo path
 global planner::UndoPathGlobal
            Planner
I-nh

    forwardPathSub

- planPub
- markersPub
- lastForwardPathMsq
- costmap ros
-skip straight motion
 distance
- puresSpinningRadStep
- transform tolerance
- name
- tf
I+ UndoPathGlobalPlanner()
+ ~UndoPathGlobalPlanner()
+ configure()
+ cleanup()
+ activate()
+ deactivate()
+ createPlan()
- onForwardTrailMsg()
publishGoalMarker()
- clearGoalMarker()
- createDefaultUndoPathPlan()
```