

```
graph BT; A["smacc2_sm_reference  
_library/sm_test_moveit  
_ur5_sim/include/sm_test  
_moveit_ur5_sim/states/st  
_undo_last_trajectory.hpp"] <-- B["smacc2_sm_reference  
_library/sm_test_moveit  
_ur5_sim/include/sm_test  
_moveit_ur5_sim/sm_test_moveit  
_ur5_sim.hpp"]; B <-- C["smacc2_sm_reference  
_library/sm_test_moveit  
_ur5_sim/src/sm_test_moveit  
_ur5_sim/sm_test_moveit_ur5  
_sim_node.cpp"]
```

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_library/sm_test_moveit
_ur5_sim/include/sm_test
_moveit_ur5_sim/states/st
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_library/sm_test_moveit
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_library/sm_test_moveit
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