smacc2::ISmaccClient

components_
- stateMachine_
- orthogonal_

+ ISmaccClient()
+ ~ISmaccClient()
+ onInitialize()
+ getName()
+ getComponent()
+ getComponent()
+ getComponent()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
+ getComponents()
+ postEvent()
+ postEvent()
# onOrthogonalAllocation()
# createComponent()
# createNamedComponent()
# getNode()
# getLogger()
- initialize()
- setStateMachine()
- setOrthogonal()

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smacc2::client_bases ::SmaccPublisherClient

+ topicName
+ queueSize
+ durability
+ reliability
+ pub_
- initialized_

+ SmaccPublisherClient()
+ ~SmaccPublisherClient()
+ configure()
+ publish()

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cl_ros_publisher::ClRosPublisher

+ ClRosPublisher()
+ ~ClRosPublisher()
+ configure()
+ publish()

---

sm_dance_bot::cl_string _publisher::ClStringPublisher

+ topicName_

+ ClStringPublisher()
+ onInitialize()

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sm_dance_bot_lite:: cl_string_publisher ::ClStringPublisher

+ topicName_

+ ClStringPublisher()
+ onInitialize()

---

sm_dance_bot_strikes _back::cl_string_publisher ::ClStringPublisher

+ topicName_

+ ClStringPublisher()
+ onInitialize()

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sm_dance_bot_warehouse ::cl_string_publisher ::ClStringPublisher

+ topicName_

+ ClStringPublisher()
+ onInitialize()

---

sm_dance_bot_warehouse _2::cl_string_publisher ::ClStringPublisher

+ topicName_

+ ClStringPublisher()
+ onInitialize()

---

sm_dance_bot_warehouse _3::cl_string_publisher ::ClStringPublisher

+ topicName_

+ ClStringPublisher()
+ onInitialize()