

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::deactivate



```
graph LR; A["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::deactivate"] --> B["cl_nav2z::undo_path  
_global_planner::UndoPathGlobal  
Planner::clearGoalMarker"]
```

cl_nav2z::undo_path
_global_planner::UndoPathGlobal
Planner::clearGoalMarker