

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::setPlan



```
graph LR; A["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::setPlan"] --> B["cl_nav2z::backward  
_local_planner::BackwardLocal  
Planner::findInitialCarrotGoal"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a white background and a black border, containing the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', and 'Planner::setPlan' on three lines. The right box has a light gray background and a black border, containing the text 'cl_nav2z::backward', '_local_planner::BackwardLocal', and 'Planner::findInitialCarrotGoal' on three lines.

cl_nav2z::backward
_local_planner::BackwardLocal
Planner::findInitialCarrotGoal