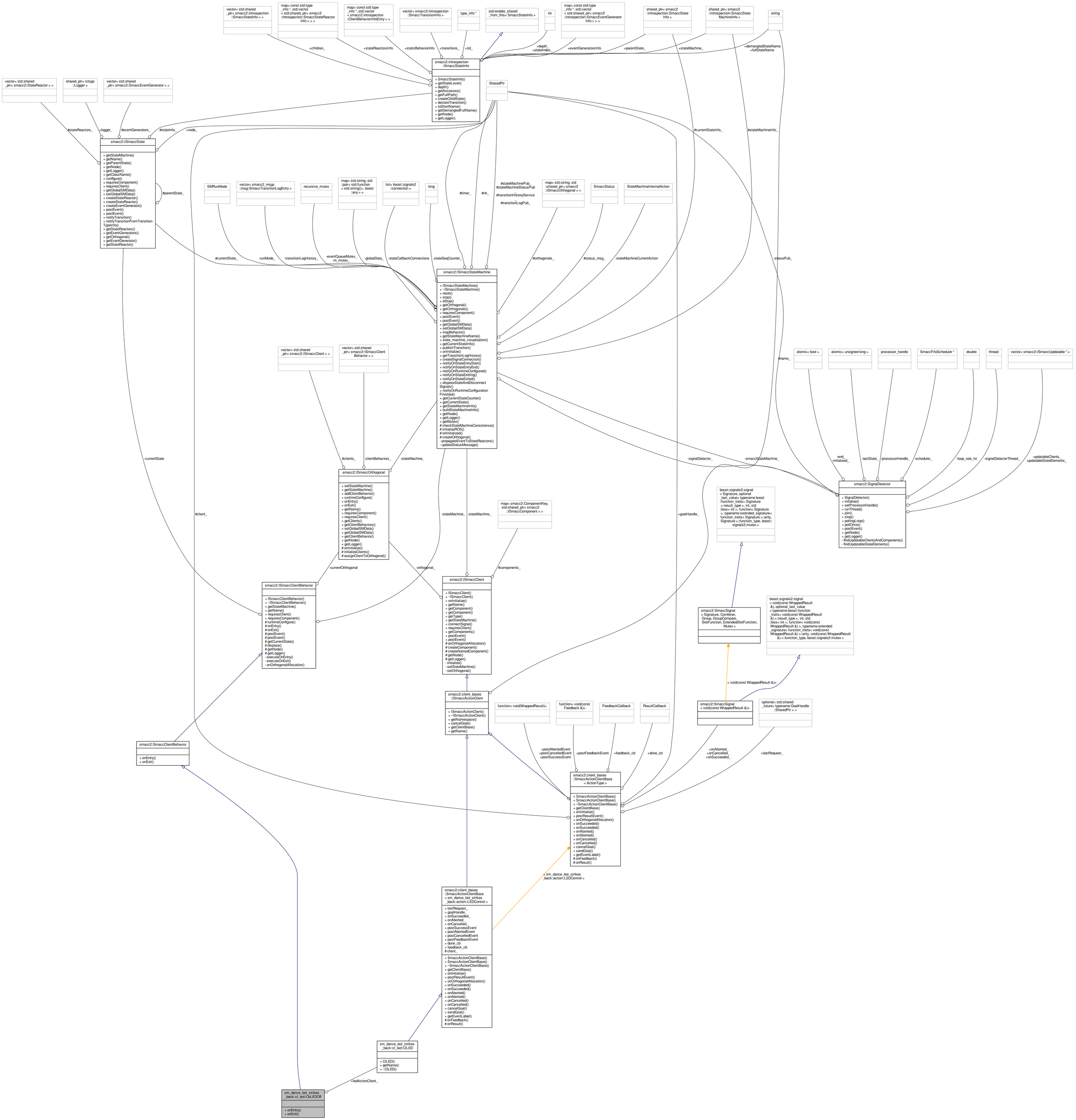
vector< std::shared _ptr< smacc2::introspection ::SmaccStateInfo > >
map< const std::type _info *, std::vector < std::shared_ptr< smacc2 ::introspection::SmaccStateReactor Info > > >
map< const std::type _info *, std::vector < smacc2::introspection ::ClientBehaviorInfoEntry > >
vector< smacc2::introspection ::SmaccTransitionInfo >
type_info *
std::enable_shared _from_this< SmaccStateInfo >
int
map< const std::type _info *, std::vector < std::shared_ptr< smacc2 ::introspection::SmaccEventGenerator Info > > >
shared_ptr< smacc2 ::introspection::SmaccState Info >
shared_ptr< smacc2 ::introspection::SmaccState MachineInfo >
string
+children_
+stateReactorsInfo
+staticBehaviorInfo
+transitions_
+tid_
+depth_
+stateIndex_
+eventGeneratorsInfo
+parentState_
+stateMachine_
+demangledStateName
+fullStateName
smacc2::introspection ::SmaccStateInfo
+ SmaccStateInfo()
+ getStateLevel()
+ depth()
+ getAncestors()
+ getFullPath()
+ createChildState()
+ declareTransition()
+ toShortName()
+ getDemangledFullName()
+ getNode()
+ getLogger()
vector< std::shared _ptr< smacc2::StateReactor > >
shared_ptr< rclcpp ::Logger >
vector< std::shared _ptr< smacc2::SmaccEventGenerator > >
SharedPtr
#stateReactors_
+logger_
#eventGenerators_
#stateInfo_
+node_
#currentStateInfo_
#stateMachineInfo_
smacc2::ISmaccState
+ getStateMachine()
+ getName()
+ getParentState()
+ getNode()
+ getLogger()
+ getClassName()
+ configure()
+ requiresComponent()
+ requiresClient()
+ getGlobalSMData()
+ setGlobalSMData()
+ createStateReactor()
+ createStateReactor()
+ createEventGenerator()
+ postEvent()
+ postEvent()
+ notifyTransition()
+ notifyTransitionFromTransition TypeInfo()
+ getStateReactors()
+ getEventGenerators()
+ getOrthogonal()
+ getEventGenerator()
+ getStateReactor()
#parentState_
SMRunMode
vector< smacc2_msgs ::msg::SmaccTransitionLogEntry >
recursive_mutex
map< std::string, std ::pair< std::function < std::string()>, boost ::any > >
list< boost::signals2 ::connection >
long
#timer_
#nh_
#stateMachinePub_
#stateMachineStatusPub
#transitionHistoryService
#transitionLogPub_
map< std::string, std ::shared_ptr< smacc2 ::ISmaccOrthogonal > >
SmaccStatus
StateMachineInternalAction
#currentState_
-runMode_
-transitionLogHistory_
-eventQueueMutex_
-m_mutex_
-globalData_
-stateCallbackConnections
-stateSeqCounter_
#orthogonals_
#status_msg_
-stateMachineCurrentAction
-statusPub_
smacc2::ISmaccStateMachine
+ ISmaccStateMachine()
+ ~ISmaccStateMachine()
+ reset()
+ stop()
+ eStop()
+ getOrthogonal()
+ getOrthogonals()
+ requiresComponent()
+ postEvent()
+ postEvent()
+ getGlobalSMData()
+ setGlobalSMData()
+ mapBehavior()
+ getStateMachineName()
+ state_machine_visualization()
+ getCurrentStateInfo()
+ publishTransition()
+ onInitialize()
+ getTransitionLogHistory()
+ createSignalConnection()
+ notifyOnStateEntryStart()
+ notifyOnStateEntryEnd()
+ notifyOnRuntimeConfigured()
+ notifyOnStateExitting()
+ notifyOnStateExited()
+ disposeStateAndDisconnect Signals()
+ notifyOnRuntimeConfiguration Finished()
+ getCurrentStateCounter()
+ getCurrentState()
+ getStateMachineInfo()
+ buildStateMachineInfo()
+ getNode()
+ getLogger()
+ getMutex()
# checkStateMachineConsistence()
# initializeROS()
# onInitialized()
# createOrthogonal()
- propagateEventToStateReactors()
- updateStatusMessage()
atomic< bool >
atomic< unsigned long >
processor_handle
SmaccFifoScheduler *
double
thread
vector< smacc2::ISmaccUpdatable * >
#name_
vector< std::shared _ptr< smacc2::ISmaccClient > >
vector< std::shared _ptr< smacc2::ISmaccClient Behavior > >
-currentState
#clients_
-clientBehaviors_
-stateMachine_
-signalDetector_
-smaccStateMachine_
-end_
-initialized_
-lastState_
-processorHandle_
-scheduler_
-loop_rate_hz
-signalDetectorThread_
-updatableClients_
-updatableStateElements_
smacc2::ISmaccOrthogonal
+ setStateMachine()
+ getStateMachine()
+ addClientBehavior()
+ runtimeConfigure()
+ onEntry()
+ onExit()
+ getName()
+ requiresComponent()
+ requiresClient()
+ getClients()
+ getClientBehaviors()
+ setGlobalSMData()
+ getGlobalSMData()
+ getClientBehavior()
+ getNode()
+ getLogger()
# onInitialize()
# initializeClients()
# assignClientToOrthogonal()
smacc2::SignalDetector
+ SignalDetector()
+ initialize()
+ setProcessorHandle()
+ runThread()
+ join()
+ stop()
+ pollingLoop()
+ pollOnce()
+ postEvent()
+ getNode()
+ getLogger()
- findUpdatableClientsAndComponents()
- findUpdatableStateElements()
#client_
-stateMachine_
-stateMachine_
map< smacc2::ComponentKey, std::shared_ptr< smacc2 ::ISmaccComponent > >
+goalHandle_
boost::signals2::signal < Signature, optional _last_value< typename boost ::function_traits< Signature >::result_type >, int, std ::less< int >, function< Signature >, typename extended_signature< function_traits< Signature >::arity, Signature >::function_type, boost:: signals2::mutex >
-currentOrthogonal
-orthogonal_
#components_
smacc2::ISmaccClientBehavior
+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# dispose()
# getNode()
# getLogger()
- executeOnEntry()
- executeOnExit()
- onOrthogonalAllocation()
smacc2::ISmaccClient
+ ISmaccClient()
+ ~ISmaccClient()
+ onInitialize()
+ getName()
+ getComponent()
+ getComponent()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
+ getComponents()
+ postEvent()
+ postEvent()
# onOrthogonalAllocation()
# createComponent()
# createNamedComponent()
# getNode()
# getLogger()
- initialize()
- setStateMachine()
- setOrthogonal()
smacc2::SmaccSignal < Signature, Combiner, Group, GroupCompare, SlotFunction, ExtendedSlotFunction, Mutex >
boost::signals2::signal < void(const WrappedResult &), optional_last_value < typename boost::function _traits< void(const WrappedResult &) >::result_type >, int, std ::less< int >, function< void(const WrappedResult &) >, typename extended _signature< function_traits< void(const WrappedResult &) >::arity, void(const WrappedResult &) >::function_type, boost::signals2::mutex >
< void(const WrappedResult &)>
smacc2::client_bases ::ISmaccActionClient
+ ISmaccActionClient()
+ ~ISmaccActionClient()
+ getNamespace()
+ cancelGoal()
+ getClientBase()
+ getName()
function< void(WrappedResult)>
function< void(const Feedback &)>
FeedbackCallback
ResultCallback
smacc2::SmaccSignal < void(const WrappedResult &)>
optional< std::shared _future< typename GoalHandle ::SharedPtr > >
+postAbortedEvent
+postCancelledEvent
+postSuccessEvent
+postFeedbackEvent
+feedback_cb
+done_cb
+onAborted_
+onCancelled_
+onSucceeded_
+lastRequest_
smacc2::SmaccClientBehavior
+ onEntry()
+ onExit()
smacc2::client_bases ::SmaccActionClientBase < ActionType >
+ SmaccActionClientBase()
+ SmaccActionClientBase()
+ ~SmaccActionClientBase()
+ getClientBase()
+ onInitialize()
+ postResultEvent()
+ onOrthogonalAllocation()
+ onSucceeded()
+ onSucceeded()
+ onAborted()
+ onAborted()
+ onCancelled()
+ onCancelled()
+ cancelGoal()
+ sendGoal()
+ getEventLabel()
# onFeedback()
# onResult()
< sm_dance_bot_strikes _back::action::LEDControl >
smacc2::client_bases ::SmaccActionClientBase < sm_dance_bot_strikes _back::action::LEDControl >
+ lastRequest_
+ goalHandle_
+ onSucceeded_
+ onAborted_
+ onCancelled
+ postSuccessEvent
+ postAbortedEvent
+ postCancelledEvent
+ postFeedbackEvent
+ done_cb
+ feedback_cb
# client_
+ SmaccActionClientBase()
+ SmaccActionClientBase()
+ ~SmaccActionClientBase()
+ getClientBase()
+ onInitialize()
+ postResultEvent()
+ onOrthogonalAllocation()
+ onSucceeded()
+ onSucceeded()
+ onAborted()
+ onAborted()
+ onCancelled()
+ onCancelled()
+ cancelGoal()
+ sendGoal()
+ getEventLabel()
# onFeedback()
# onResult()
sm_dance_bot_strikes _back::cl_led::CILED
+ CILED()
+ getName()
+ ~CILED()
+ledActionClient_
sm_dance_bot_strikes _back::cl_led::CbLEDOff
+ onEntry()
+ onExit()