

cl\_move\_base\_z::PlannerSwitcher  
::setUndoPathPureSpinningPlannerConfiguration



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graph LR; A[cl_move_base_z::PlannerSwitcher::setUndoPathPureSpinningPlannerConfiguration] --> B[cl_move_base_z::PlannerSwitcher::updatePlanners];
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The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and contains the text 'cl\_move\_base\_z::PlannerSwitcher' followed by '::setUndoPathPureSpinningPlannerConfiguration' on the next line. The right box has a white background and contains the text 'cl\_move\_base\_z::PlannerSwitcher' followed by '::updatePlanners' on the next line. A dark blue arrow points from the right side of the left box to the left side of the right box.

cl\_move\_base\_z::PlannerSwitcher  
::updatePlanners