

cl_ros_publisher::CbDefault
PublishLoop::CbDefaultPublishLoop



```
graph LR; A[cl_ros_publisher::CbDefault  
PublishLoop::CbDefaultPublishLoop] --> B[cl_ros_publisher::CbDefault  
PublishLoop::setMessage];
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a white background and a black border, containing the text 'cl_ros_publisher::CbDefault' and 'PublishLoop::CbDefaultPublishLoop'. The right box has a gray background and a black border, containing the text 'cl_ros_publisher::CbDefault' and 'PublishLoop::setMessage'.

cl_ros_publisher::CbDefault
PublishLoop::setMessage