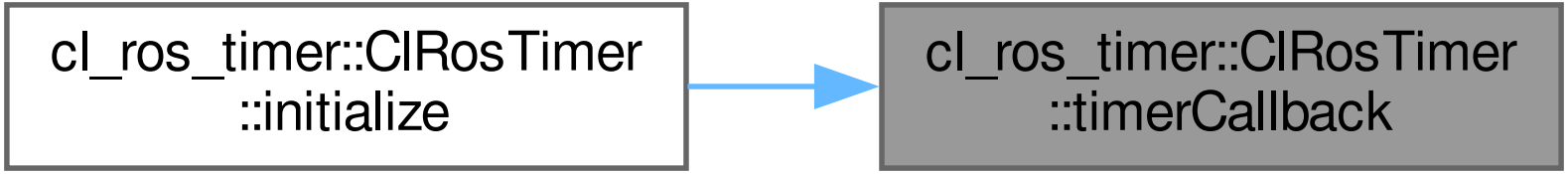
cl_ros_timer::ClRosTimer
::initialize
cl_ros_timer::ClRosTimer
::timerCallback