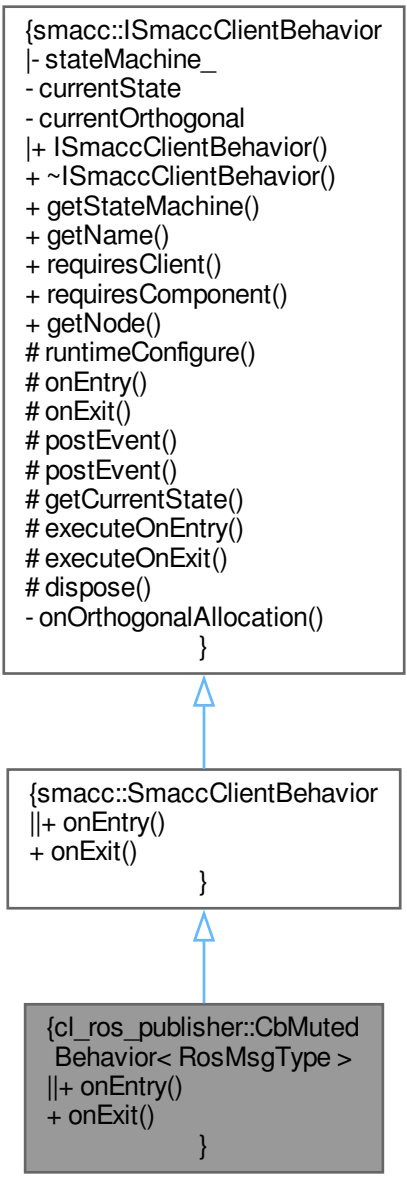
{smacc::ISmaccClientBehavior
|- stateMachine_
- currentState
- currentOrthogonal
|+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
+ getNode()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
- onOrthogonalAllocation()
}
{smacc::SmaccClientBehavior
||+ onEntry()
+ onExit()
}
{cl_ros_publisher::CbMuted
Behavior< RosMsgType >
||+ onEntry()
+ onExit()
}