

```
{nav_core::BaseGlobalPlanner  
  ||}
```



```
{cl_move_base_z::backward  
_global_planner::BackwardGlobal  
  Planner
```

```
| - nh_  
| - planPub_  
| - markersPub_  
| - costmap_ros_  
| - skip_straight_motion_  
| - distance_  
| - puresSpinningRadStep_  
| + BackwardGlobalPlanner()  
| + ~BackwardGlobalPlanner()  
| + makePlan()  
| + makePlan()  
| + createDefaultBackwardPath()  
| + initialize()  
| - onForwardTrailMsg()  
| - publishGoalMarker()  
  }
```