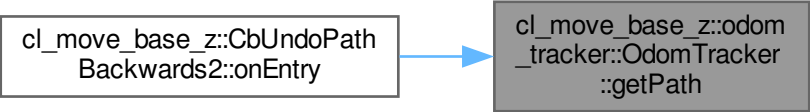


cl_move_base_z::CbUndoPath
Backwards2::onEntry



```
graph LR; A["cl_move_base_z::CbUndoPathBackwards2::onEntry"] --> B["cl_move_base_z::odometer::OdomTracker::getPath"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl_move_base_z::CbUndoPathBackwards2::onEntry'. The right box is gray with a black border and contains the text 'cl_move_base_z::odometer::OdomTracker::getPath'.

cl_move_base_z::odometer
::OdomTracker
::getPath