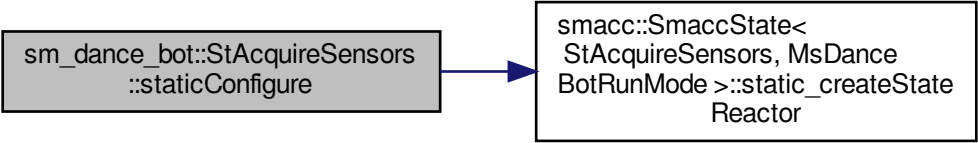


```
sm_dance_bot::StAcquireSensors  
::staticConfigure
```



```
graph LR; A[sm_dance_bot::StAcquireSensors::staticConfigure] --> B[smacc::SmaccState<StAcquireSensors, MsDanceBotRunMode>::static_createStateReactor]
```

```
smacc::SmaccState<  
  StAcquireSensors, MsDance  
  BotRunMode >::static_createState  
  Reactor
```