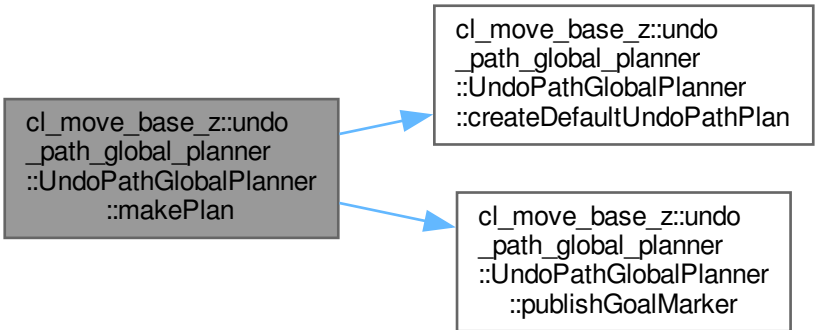


cl\_move\_base\_z::undo  
\_path\_global\_planner  
::UndoPathGlobalPlanner  
::makePlan



```
graph LR; A["cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::makePlan"] --> B["cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::createDefaultUndoPathPlan"]; A --> C["cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::publishGoalMarker"]
```

cl\_move\_base\_z::undo  
\_path\_global\_planner  
::UndoPathGlobalPlanner  
::createDefaultUndoPathPlan

cl\_move\_base\_z::undo  
\_path\_global\_planner  
::UndoPathGlobalPlanner  
::publishGoalMarker