

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal"]
```

The diagram illustrates a function call sequence. A grey box on the left contains the code for the `cl_move_base_z::backward` function, which calls `_local_planner::BackwardLocalPlanner::findInitialCarrotGoal`. A blue arrow points from this box to a white box on the right, which contains the code for `_local_planner::BackwardLocalPlanner::computeCurrentEuclideanAndAngularErrorsToCarrotGoal`.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```