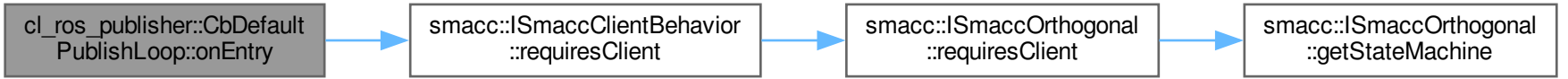
cl_ros_publisher::CbDefault
PublishLoop::onEntry
smacc::ISmaccClientBehavior
::requiresClient
smacc::ISmaccOrthogonal
::requiresClient
smacc::ISmaccOrthogonal
::getStateMachine