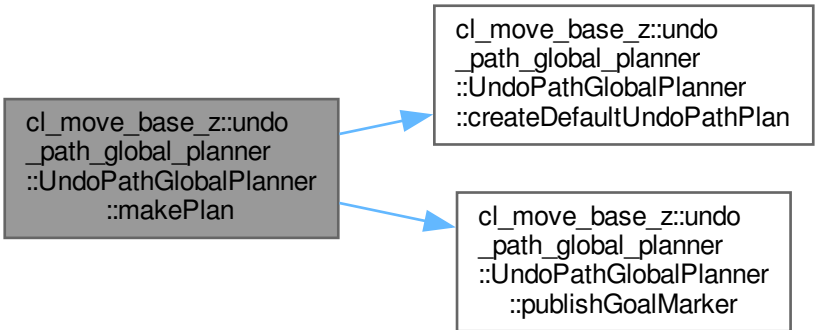


cl_move_base_z::undo
_path_global_planner
::UndoPathGlobalPlanner
::makePlan



```
graph LR; A["cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::makePlan"] --> B["cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::createDefaultUndoPathPlan"]; A --> C["cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::publishGoalMarker"]
```

cl_move_base_z::undo
_path_global_planner
::UndoPathGlobalPlanner
::createDefaultUndoPathPlan

cl_move_base_z::undo
_path_global_planner
::UndoPathGlobalPlanner
::publishGoalMarker