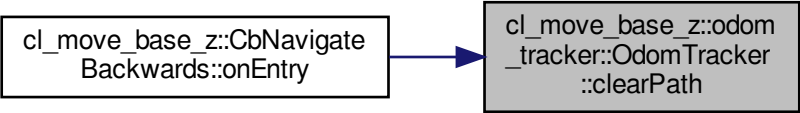


cl_move_base_z::CbNavigate
Backwards::onEntry



```
graph LR; A["cl_move_base_z::CbNavigateBackwards::onEntry"] --> B["cl_move_base_z::odometer_tracker::OdomTracker::clearPath"]
```

cl_move_base_z::odometer_tracker::OdomTracker
::clearPath