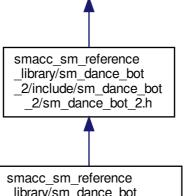
smacc\_sm\_reference
\_library/sm\_dance\_bot
\_2/include/sm\_dance\_bot
\_2/states/ms\_dance\_bot\_run
\_mode/st\_navigate\_to\_waypoints\_x.h



\_library/sm\_dance\_bot \_2/src/sm\_dance\_bot\_2.cpp