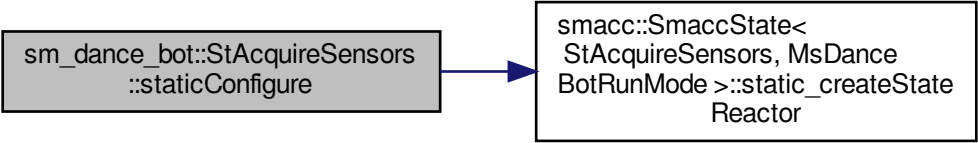


```
sm_dance_bot::StAcquireSensors  
::staticConfigure
```



```
graph LR; A["sm_dance_bot::StAcquireSensors  
::staticConfigure"] --> B["smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static_createState  
Reactor"]
```

```
smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static_createState  
Reactor
```