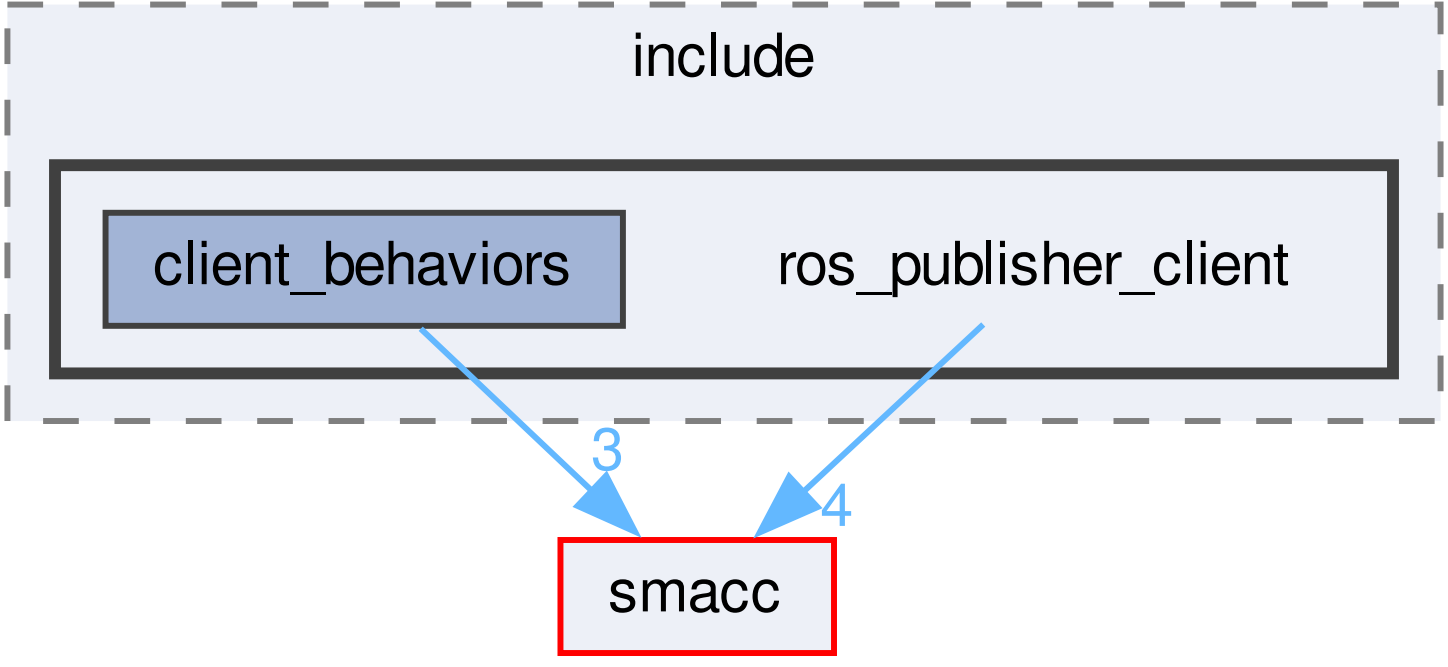
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client_behaviors
ros_publisher_client
3
4
smacc