

sm\_dance\_bot::cl\_lidar  
::CbLidarSensor::onEntry

sm\_dance\_bot\_2::cl  
\_lidar::CbLidarSensor  
::onEntry

sm\_dance\_bot\_strikes  
\_back::cl\_lidar::CbLidarSensor  
::onEntry

cl\_multirole\_sensor  
::CbDefaultMultiRoleSensor  
Behavior::onEntry

