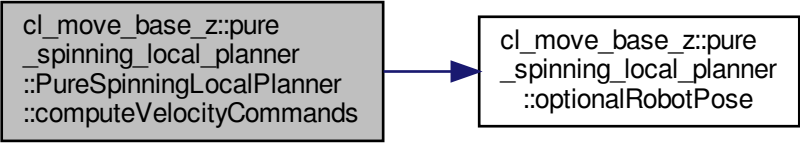


```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```



A diagram illustrating a function call. A grey rectangular box on the left contains the text 'cl\_move\_base\_z::pure', '\_spinning\_local\_planner', '::PureSpinningLocalPlanner', and '::computeVelocityCommands'. A blue arrow points from the right side of this box to a white rectangular box on the right. The white box contains the text 'cl\_move\_base\_z::pure', '\_spinning\_local\_planner', and '::optionalRobotPose'.

```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```