```
{nav_core::BaseGlobalPlanner
||}
```

```
{cl_move_base_z::backward
_global_planner::BackwardGlobal
            Planner
|- nh_
- planPub_
- markersPub_
- costmap_ros_
- skip_straight_motion
_distance_
- puresSpinningRadStep_
|+ BackwardGlobalPlanner()
+ ~BackwardGlobalPlanner()
+ makePlan()
+ makePlan()
+ createDefaultBackwardPath()
+ initialize()
- onForwardTrailMsg()
- publishGoalMarker()
            }
```