


```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::makePlan
```



```
graph LR; A["cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::makePlan"] --> B["cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::makePlan"]; B --> C["cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::publishGoalMarker"]
```

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