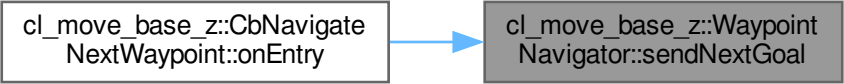


cl\_move\_base\_z::CbNavigate  
NextWaypoint::onEntry



```
graph LR; A[cl_move_base_z::CbNavigate  
NextWaypoint::onEntry] --> B[cl_move_base_z::Waypoint  
Navigator::sendNextGoal];
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl\_move\_base\_z::CbNavigate' and 'NextWaypoint::onEntry'. The right box is gray with a black border and contains the text 'cl\_move\_base\_z::Waypoint' and 'Navigator::sendNextGoal'.

cl\_move\_base\_z::Waypoint  
Navigator::sendNextGoal