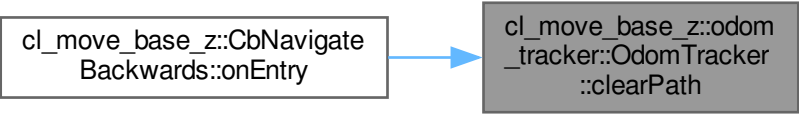


cl_move_base_z::CbNavigate
Backwards::onEntry



```
graph LR; A[cl_move_base_z::CbNavigateBackwards::onEntry] --> B[cl_move_base_z::odometer_tracker::OdomTracker::clearPath];
```

cl_move_base_z::odometer
_tracker::OdomTracker
::clearPath