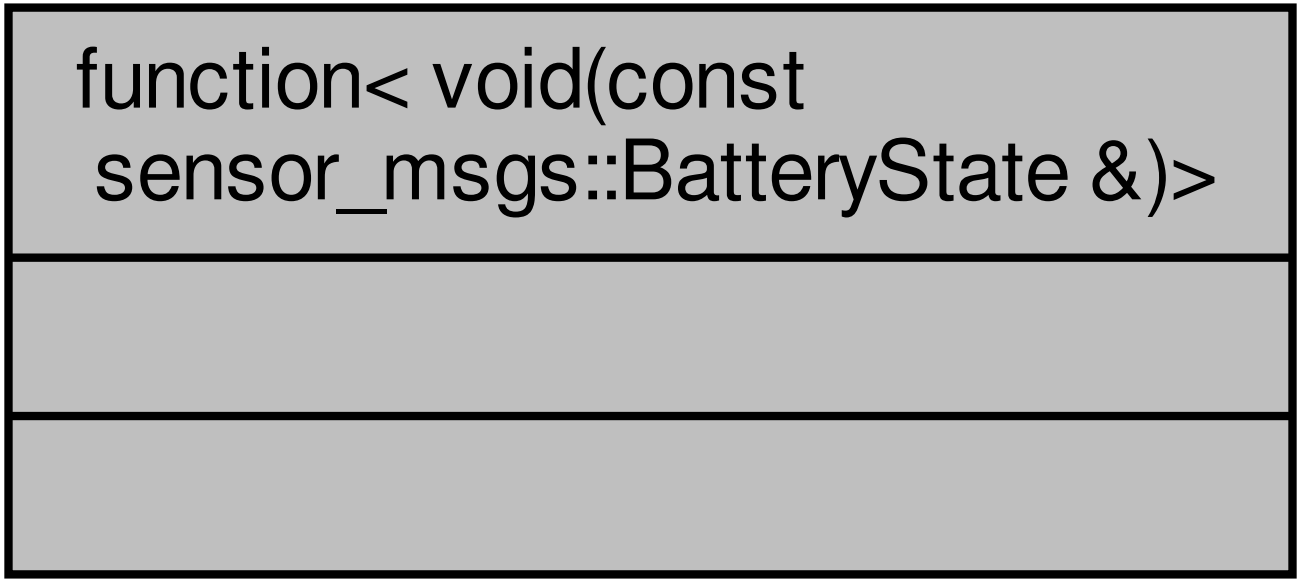
function< void(const
sensor_msgs::BatteryState &)>