

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::divergenceDetectionUpdate
```



A diagram showing a call sequence. On the left, a gray-shaded rectangular box contains the text: `cl_move_base_z::backward`, `_local_planner::BackwardLocalPlanner`, and `::divergenceDetectionUpdate`. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text: `cl_move_base_z::backward`, `_local_planner::BackwardLocalPlanner`, `::computeCurrentEuclideanAndAngularErrors`, and `ToCarrotGoal`.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```