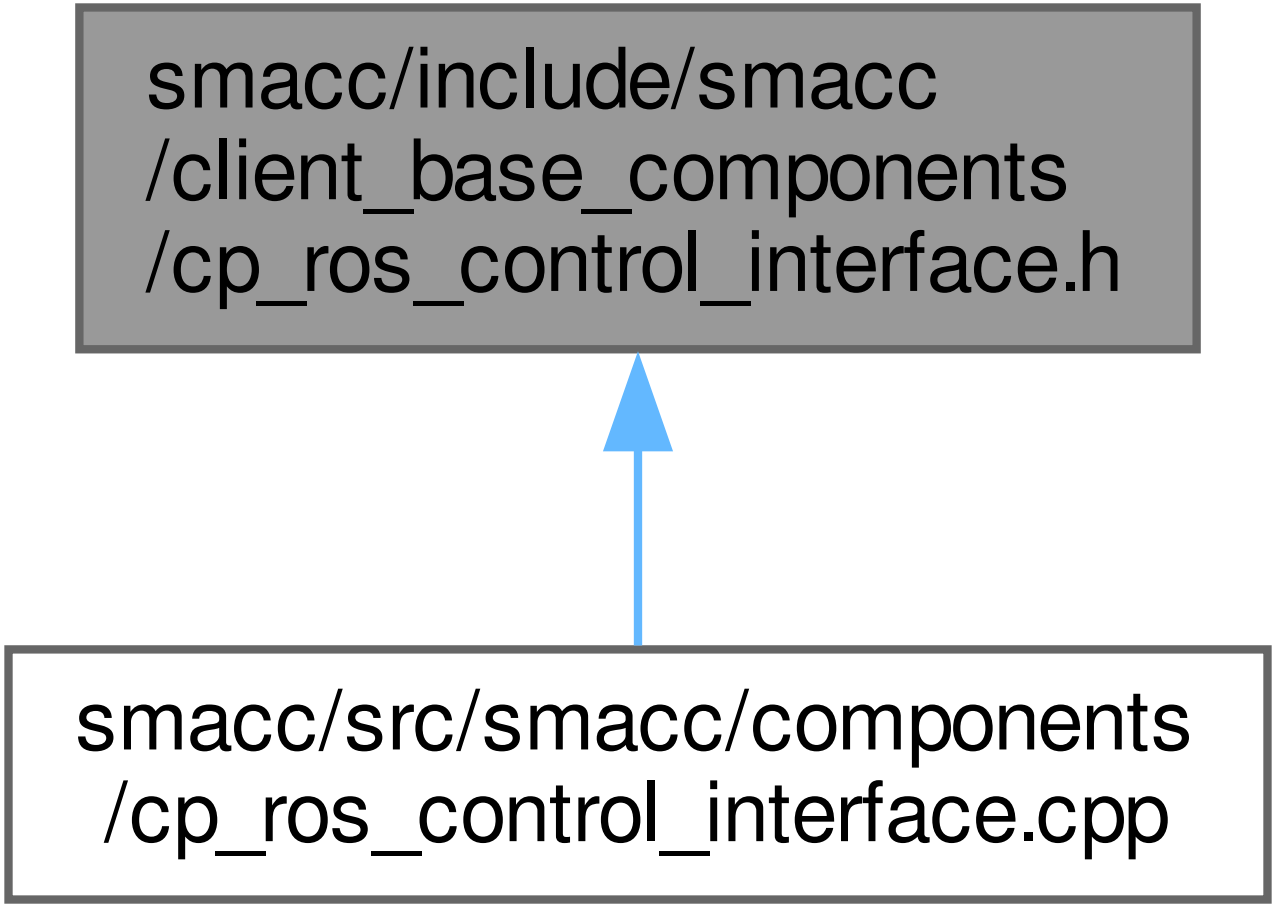
smacc/include/smacc
/client_base_components
/cp_ros_control_interface.h
smacc/src/smacc/components
/cp_ros_control_interface.cpp