

```
smacc_client_library  
/move_base_z_client/custom  
_planners/forward_global  
_planner/include/forward_global  
_planner/move_base_z_client_tools.h
```

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graph TD; A["smacc_client_library<br>/move_base_z_client/custom<br>_planners/forward_global<br>_planner/include/forward_global<br>_planner/move_base_z_client_tools.h"] --> B["ros/ros.h"]; A --> C["geometry_msgs/PoseStamped.h"]
```

ros/ros.h

geometry_msgs/PoseStamped.h