

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/states/st_acquire_sensors.h"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"]
```

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/states/st_acquire_sensors.h

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
/src/sm_dance_bot.cpp