```
cl_move_base_z::undo
_path_global_planner
::UndoPathGlobalPlanner
::makePlan
```

```
cl_move_base_z::undo
_path_global_planner
::UndoPathGlobalPlanner
::createDefaultUndoPathPlan
```

```
cl_move_base_z::undo
_path_global_planner
::UndoPathGlobalPlanner
::publishGoalMarker
```