```
{nav_core::BaseGlobalPlanner
||}
```

```
{cl_move_base_z::forward
_global_planner::ForwardGlobal
                Planner
|- nh_
- planPub_
- costmap_ros_
- skip_straight_motion
_distance_
- puresSpinningRadStep_
|+ ForwardGlobalPlanner()
+ makePlan()
+ makePlan()
+ initialize()
                }
```