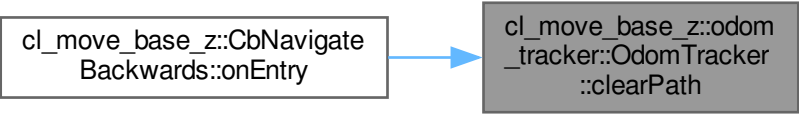


cl\_move\_base\_z::CbNavigate  
Backwards::onEntry



```
graph LR; A[cl_move_base_z::CbNavigateBackwards::onEntry] --> B[cl_move_base_z::odometer_tracker::OdomTracker::clearPath];
```

cl\_move\_base\_z::odometer\_tracker::OdomTracker  
::clearPath