

sm\_fetch\_two\_table  
\_pick\_n\_place\_1::cl  
\_perception\_system::ClPerception  
System::decidePickCubePose

```
graph LR; A["sm_fetch_two_table  
_pick_n_place_1::cl  
_perception_system::ClPerception  
System::decidePickCubePose"] --> B["cl_move_base_z::Pose  
::toPoseStampedMsg"]; A --> C["cl_move_base_z::Pose  
::waitTransformUpdate"]
```

cl\_move\_base\_z::Pose  
::toPoseStampedMsg

cl\_move\_base\_z::Pose  
::waitTransformUpdate