

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/superstates/ss_s_pattern_1.h"]; C --> D["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/states/s_pattern_states  
/sti_spattern_rotate_2.h"];
```

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/states/s_pattern_states
/sti_spattern_rotate_2.h

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/superstates/ss_s_pattern_1.h

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
/src/sm_dance_bot.cpp