

boost::statechart::  
event< EvWaypoint166  
< TSource, TOrthogonal > >

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvWaypoint166 < TSource, TOrthogonal > >"]
    class cl_move_base_z_EvWaypoint166["cl_move_base_z::EvWaypoint166 < TSource, TOrthogonal >"]
    cl_move_base_z_EvWaypoint166 --|> boost_statechart_event
    class cl_move_base_z_EvWaypoint166 {
        + waypointIndex
```

The diagram consists of two class boxes. The top box is white with a black border and contains the text 'boost::statechart::event< EvWaypoint166 < TSource, TOrthogonal > >'. It is divided into three horizontal compartments by thin black lines. The bottom box is gray with a black border and contains the text 'cl\_move\_base\_z::EvWaypoint166 < TSource, TOrthogonal >' in the top compartment, '+ waypointIndex' in the middle compartment, and is empty in the bottom compartment. A blue arrow with an open triangular head points from the top of the gray box to the bottom of the white box.

cl\_move\_base\_z::EvWaypoint166  
< TSource, TOrthogonal >

+ waypointIndex