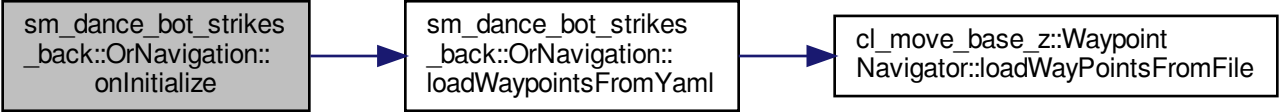


sm_dance_bot_strikes
_back::OrNavigation::
onInitialize



```
graph LR; A[sm_dance_bot_strikes  
_back::OrNavigation::  
onInitialize] --> B[sm_dance_bot_strikes  
_back::OrNavigation::  
loadWaypointsFromYaml]; B --> C[cl_move_base_z::Waypoint  
Navigator::loadWayPointsFromFile];
```

sm_dance_bot_strikes
_back::OrNavigation::
loadWaypointsFromYaml

cl_move_base_z::Waypoint
Navigator::loadWayPointsFromFile