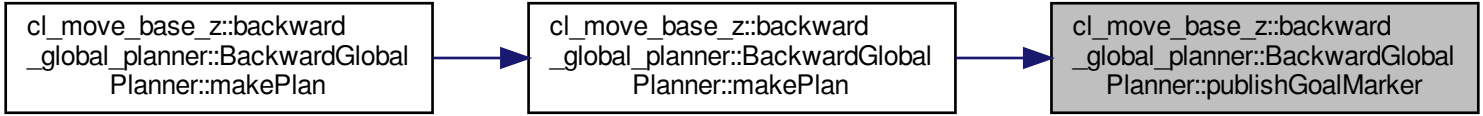
cl_move_base_z::backward
_global_planner::BackwardGlobal
Planner::makePlan
cl_move_base_z::backward
_global_planner::BackwardGlobal
Planner::makePlan
cl_move_base_z::backward
_global_planner::BackwardGlobal
Planner::publishGoalMarker