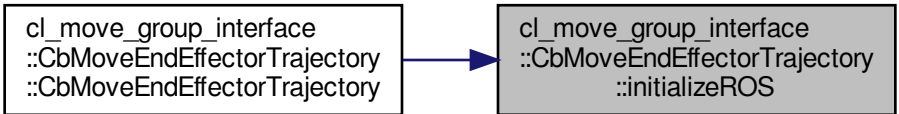
cl_move_group_interface
::CbMoveEndEffectorTrajectory
::CbMoveEndEffectorTrajectory
cl_move_group_interface
::CbMoveEndEffectorTrajectory
::initializeROS