```
smacc::ISmaccClientBehavior

    stateMachine

- currentState

    currentOrthogonal

+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
+ getNode()
# runtimeConfigure()
# onEntrv()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
- on Orthogonal Allocation()
smacc::SmaccClientBehavior
+ onEntry()
+ onExit()
 cl ros publisher::CbPublish
    Once< RosMsgType >

    deferedPublishFn

 - client
 + CbPublishOnce()
 + CbPublishOnce()
 + setMessage()
 + onEntry()
 + onExit()
```