

cl\_move\_group\_interface  
::CbExecuteLastTrajectory  
::onEntry

cl\_move\_group\_interface  
::CbMoveEndEffectorTrajectory  
::onEntry

cl\_move\_group\_interface  
::CbUndoLastTrajectory  
::onEntry

cl\_move\_group\_interface  
::CbMoveEndEffectorTrajectory  
::executeJointSpaceTrajectory

```
graph LR; A["cl_move_group_interface  
::CbExecuteLastTrajectory  
::onEntry"] --> D["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::executeJointSpaceTrajectory"]; B["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::onEntry"] --> D; C["cl_move_group_interface  
::CbUndoLastTrajectory  
::onEntry"] --> D;
```

The diagram illustrates a mapping or inheritance relationship. On the left, there are three white rectangular boxes, each containing a function signature from the `cl_move_group_interface`. Arrows from each of these boxes point to a single gray rectangular box on the right, which contains a function signature. The gray box represents the target or implementation of the functions listed in the white boxes.