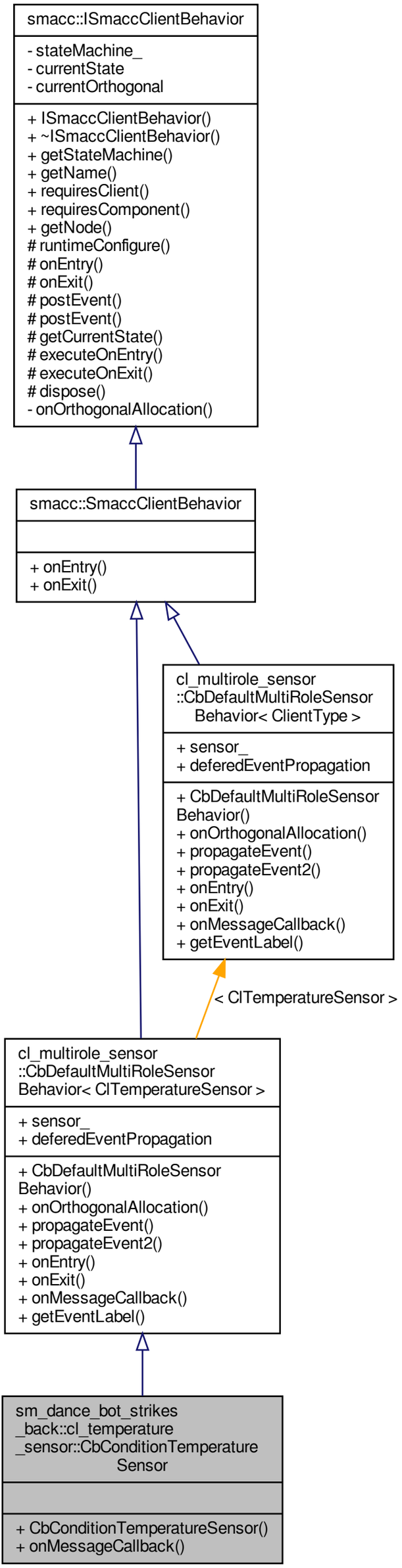
smacc::ISmaccClientBehavior
- stateMachine_
- currentState
- currentOrthogonal
+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
+ getNode()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
- onOrthogonalAllocation()
smacc::SmaccClientBehavior
+ onEntry()
+ onExit()
cl_multirole_sensor ::CbDefaultMultiRoleSensor Behavior< ClientType >
+ sensor_
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor Behavior()
+ onOrthogonalAllocation()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
< ClTemperatureSensor >
cl_multirole_sensor ::CbDefaultMultiRoleSensor Behavior< ClTemperatureSensor >
+ sensor_
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor Behavior()
+ onOrthogonalAllocation()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
sm_dance_bot_strikes _back::cl_temperature _sensor::CbConditionTemperature Sensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()