



-alpha\_offset\_  
-beta\_offset\_  
-carrot\_angular\_distance\_  
-carrot\_distance\_  
-k\_alpha\_  
-k\_beta\_  
-k\_rho\_  
-max\_angular\_z\_speed\_  
-max\_linear\_x\_speed\_  
-xy\_goal\_tolerance\_  
-  
...

-goalReached\_  
-waiting\_

-currentPoseIndex\_  
-plan\_

-waitingTimeout\_  
-waitingStamp\_

