



-alpha_offset_
-beta_offset_
-carrot_angular_distance_
-carrot_distance_
-k_alpha_
-k_beta_
-k_rho_
-max_angular_z_speed_
-max_linear_x_speed_
-xy_goal_tolerance_
-
...

-goalReached_
-waiting_

-currentPoseIndex_
-plan_

-waitingTimeout_
-waitingStamp_

