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graph BT; A["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/sti_fpattern_rotate_1.h"] --> B["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/superstates/ss_f_pattern_1.h"]; B --> C["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/sm_dance_bot_strikes_back.h"]; C --> D["smacc_sm_reference_library/sm_dance_bot_strikes_back/src/sm_dance_bot_strikes_back.cpp"];
```

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/states/f_pattern_states/sti
_fpattern_rotate_1.h

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/superstates/ss_f_pattern_1.h

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/sm_dance_bot_strikes_back.h

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/src/sm_dance
_bot_strikes_back.cpp