```
smacc::ISmaccClientBehavior

    stateMachine

    currentState

- currentOrthogonal
+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
+ aetNode()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
- on Orthogonal Allocation()
smacc::SmaccClientBehavior
+ onEntry()
+ onExit()
 cl ros publisher::CbMuted
  Behavior< RosMsgType >
 + onEntry()
 + onExit()
```