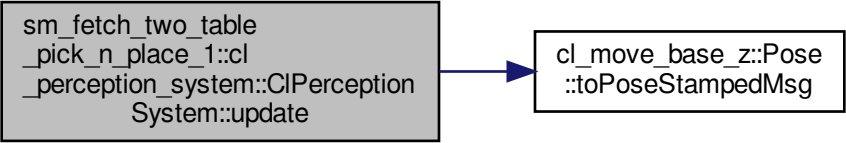


sm_fetch_two_table
_pick_n_place_1::cl
_perception_system::ClPerception
System::update



```
graph LR; A["sm_fetch_two_table  
_pick_n_place_1::cl  
_perception_system::ClPerception  
System::update"] --> B["cl_move_base_z::Pose  
::toPoseStampedMsg"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and a black border, containing four lines of text. The right box has a white background and a black border, containing two lines of text. The blue arrow originates from the right side of the left box and points to the left side of the right box.

cl_move_base_z::Pose
::toPoseStampedMsg