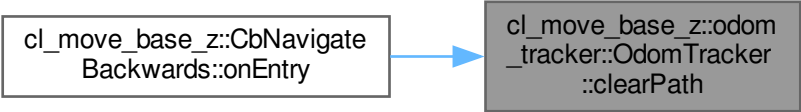


cl\_move\_base\_z::CbNavigate  
Backwards::onEntry



```
graph LR; A[cl_move_base_z::CbNavigateBackwards::onEntry] --> B[cl_move_base_z::odometer_tracker::OdomTracker::clearPath];
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'cl\_move\_base\_z::CbNavigateBackwards::onEntry'. The right box is gray with a black border and contains the text 'cl\_move\_base\_z::odometer\_tracker::OdomTracker::clearPath'.

cl\_move\_base\_z::odometer\_tracker::OdomTracker  
::clearPath