

```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```



A diagram consisting of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains four lines of C++ code. The right box is gray with a black border and contains two lines of C++ code. A blue arrow points from the right side of the left box to the left side of the right box.

```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```