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graph BT; A["smacc_sm_reference_library/sm_dance_bot_strikes_back/src/sm_dance_bot_strikes_back.cpp"] --> B["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/sm_dance_bot_strikes_back.h"]; B --> C["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/superstates/ss_s_pattern_1.h"]; C --> D["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/states/s_pattern_states/sti_spattern_rotate_3.h"]
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/states/s\_pattern\_states/sti  
\_spattern\_rotate\_3.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/superstates/ss\_s\_pattern\_1.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/sm\_dance\_bot\_strikes\_back.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/src/sm\_dance  
\_bot\_strikes\_back.cpp