

cl\_move\_base\_z::CbUndoPath  
Backwards2::publishMarkers



```
graph LR; A["cl_move_base_z::CbUndoPathBackwards2::publishMarkers"] --> B["cl_move_base_z::Pose::getReferenceFrame"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl\_move\_base\_z::CbUndoPathBackwards2::publishMarkers'. The right box is white and contains the text 'cl\_move\_base\_z::Pose::getReferenceFrame'. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_move\_base\_z::Pose  
::getReferenceFrame