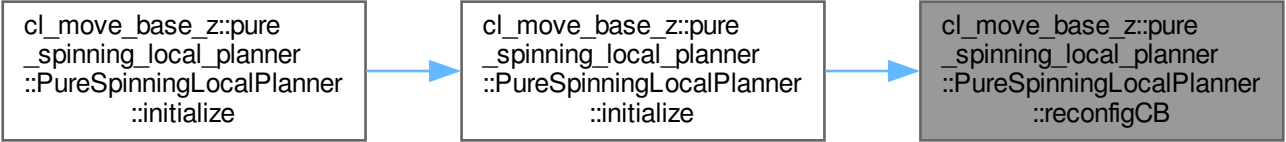


```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::initialize
```



```
graph LR; A["cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::initialize"] --> B["cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::initialize"]; B --> C["cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::reconfigCB"]
```

The diagram consists of three rectangular boxes arranged horizontally, connected by blue arrows pointing from left to right. The first and second boxes are white with a black border, while the third box is gray with a black border. Each box contains C++ code for the `PureSpinningLocalPlanner` class. The first box shows the `initialize` method, the second box also shows the `initialize` method, and the third box shows the `reconfigCB` method.

```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::initialize
```

```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::reconfigCB
```