smacc sm reference library/sm dance bot strikes back/include /sm dance bot strikes back /clients/cl lidar/components /cp lidar data.h smacc sm reference library/sm dance bot strikes back/include /sm dance bot strikes back /orthogonals/or obstacle perception.h smacc sm reference library/sm dance bot strikes back/include /sm dance bot strikes back /sm dance bot strikes back.h smacc sm reference library/sm dance bot strikes back/src/sm dance bot strikes back.cpp