smacc::ISmaccClientBehavior

- stateMachine_
- currentState
- currentOrthogonal

+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
+ getNode()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
- onOrthogonalAllocation()

smacc::SmaccClientBehavior

+ onEntry()
+ onExit()

cl_ros_timer::CbTimer

- timerClient_
- postTimerEvent_
- c_

+ onEntry()
+ onExit()
+ onOrthogonalAllocation()
+ onClientTimerTickCallback()