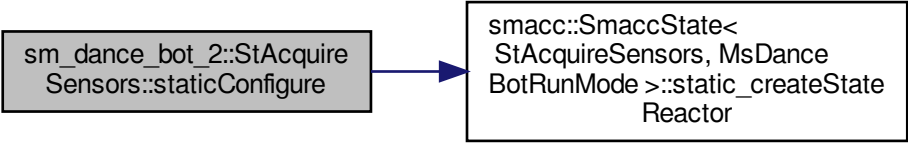


sm\_dance\_bot\_2::StAcquire  
Sensors::staticConfigure



```
graph LR; A["sm_dance_bot_2::StAcquire  
Sensors::staticConfigure"] --> B["smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static_createState  
Reactor"]
```

smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static\_createState  
Reactor