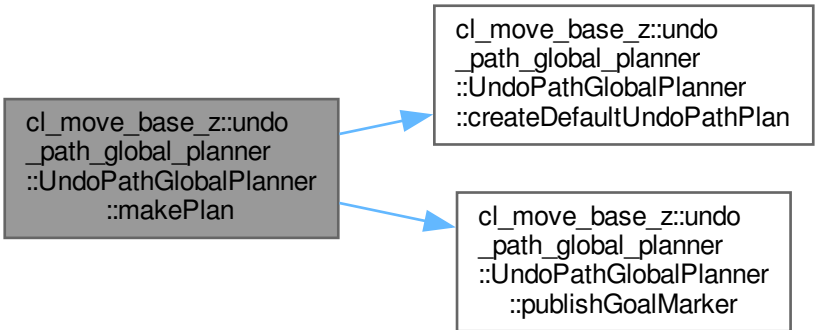


cl\_move\_base\_z::undo  
\_path\_global\_planner  
::UndoPathGlobalPlanner  
::makePlan



```
graph LR; A["cl_move_base_z::undo<br/>_path_global_planner<br/>::UndoPathGlobalPlanner<br/>::makePlan"] --> B["cl_move_base_z::undo<br/>_path_global_planner<br/>::UndoPathGlobalPlanner<br/>::createDefaultUndoPathPlan"]; A --> C["cl_move_base_z::undo<br/>_path_global_planner<br/>::UndoPathGlobalPlanner<br/>::publishGoalMarker"];
```

The diagram illustrates a function call sequence. A central grey box on the left contains the code for `cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::makePlan`. Two blue arrows originate from the right side of this box. The top arrow points to a white box containing `cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::createDefaultUndoPathPlan`. The bottom arrow points to another white box containing `cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::publishGoalMarker`.

cl\_move\_base\_z::undo  
\_path\_global\_planner  
::UndoPathGlobalPlanner  
::createDefaultUndoPathPlan

cl\_move\_base\_z::undo  
\_path\_global\_planner  
::UndoPathGlobalPlanner  
::publishGoalMarker