

boost::statechart::  
event< EvWaypoint170  
< TSource, TOrthogonal > >

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvWaypoint170< TSource, TOrthogonal > >"]
    class cl_move_base_z_EvWaypoint170["cl_move_base_z::EvWaypoint170< TSource, TOrthogonal >"]
    cl_move_base_z_EvWaypoint170 --|> boost_statechart_event
```

The diagram consists of two class boxes. The top box is white with a black border and contains the text 'boost::statechart::event< EvWaypoint170 < TSource, TOrthogonal > >'. It is divided into three horizontal compartments by two lines. The bottom compartment is empty. The bottom box is gray with a black border and contains the text 'cl\_move\_base\_z::EvWaypoint170 < TSource, TOrthogonal >' in the top compartment, '+ waypointIndex' in the middle compartment, and an empty compartment at the bottom. A blue arrow with an open triangular head points from the top of the bottom box to the bottom of the top box.

cl\_move\_base\_z::EvWaypoint170  
< TSource, TOrthogonal >

+ waypointIndex