

cl\_move\_group\_interface  
::CbExecuteLastTrajectory  
::onEntry

cl\_move\_group\_interface  
::CbMoveEndEffectorTrajectory  
::onEntry

cl\_move\_group\_interface  
::CbUndoLastTrajectory  
::onEntry

cl\_move\_group\_interface  
::CbMoveEndEffectorTrajectory  
::executeJointSpaceTrajectory

```
graph LR; A["cl_move_group_interface  
::CbExecuteLastTrajectory  
::onEntry"] --> D["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::executeJointSpaceTrajectory"]; B["cl_move_group_interface  
::CbMoveEndEffectorTrajectory  
::onEntry"] --> D; C["cl_move_group_interface  
::CbUndoLastTrajectory  
::onEntry"] --> D;
```

The diagram illustrates a mapping or inheritance relationship. Three source boxes on the left, each containing a function name and its entry point, have arrows pointing to a single target box on the right. The target box contains a function name and its implementation. The source boxes are: 1. cl\_move\_group\_interface::CbExecuteLastTrajectory::onEntry, 2. cl\_move\_group\_interface::CbMoveEndEffectorTrajectory::onEntry, and 3. cl\_move\_group\_interface::CbUndoLastTrajectory::onEntry. The target box is cl\_move\_group\_interface::CbMoveEndEffectorTrajectory::executeJointSpaceTrajectory.