

cl\_move\_base\_z::CbUndoPath  
Backwards2::onEntry



```
graph LR; A[cl_move_base_z::CbUndoPathBackwards2::onEntry] --> B[cl_move_base_z::odometerTracker::getPath];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'cl\_move\_base\_z::CbUndoPathBackwards2::onEntry'. The right box is light gray with a black border and contains the text 'cl\_move\_base\_z::odometerTracker::getPath'. A blue arrow points from the right side of the left box to the left side of the right box.

cl\_move\_base\_z::odometerTracker::getPath