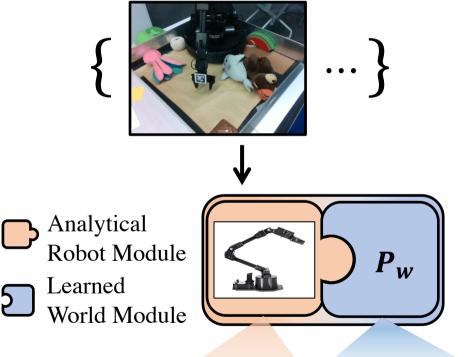
Robot-aware controllers transfer zero-shot to unseen robots!

Step 1: Learn robot-agnostic world model from videos of robot R1



 $P(o'|o,a) = P_{R1}(r'|r,a)P_{W}(o'_{W}|o_{W},r',a)$

Step 2: Zero-shot prediction / control with robot R2

