Hom	rework I					Madalera Yang 11020
1.	D]	y,	42	Your	Φ(y1,42) = y1	× y2 Radalera Kota 1103!
	KA	2	2	3,5	4	
	u ₂	1	1	1,0	1	OLS closed form solution
	43	3	2	3,8	6	$W = (x^{T}x)^{-1}x^{T} \neq$
	MA	6	3	10,1	18	
	Ms-	8	1	8,5	8	
	[1	47		(3,5	
	$X = \begin{cases} 1 \\ 1 \\ 1 \\ 1 \end{cases}$	1 6		₹=	318	W=[1,46136 0,52955]T
	1	18			101 8,5	(calculated in code)
	1	8			8,5	

2. This time, we'll leave a Ridge regression, so the weights | Ridge are given by $W = (X^TX + \lambda I)^T X^T + WHA \lambda = 1$ peralty factor $W = (X^TX + \lambda I)^T X^T + WHA \lambda = 1$ peralty factor $W = (X^TX + \lambda I)^T X^T + WHA \lambda = 1$ peralty factor $W = (X^TX + \lambda I)^T + WHA \lambda = 1$

A flexible model is very susceptible to noise, which means it fits the traing data well but fails to generalize. Regularization helps prevent overfitting by restricting the model, penalizing large and unstable coefficients. This results in more generalized, well-fitted and robust models.

At expected, after adding fidge regularization, the slope barely changed and the intersect decreased from 1.46136 to 0.97319. This is because fidge peralizes large coefficients to reduce evertiting and to prevent them from influencing predictions too heavily composed to other work important ares.

In conclusion, the results obtained with regularization were expected 2 larger coefficients shrunk so they don't influence the predictions as heavily, and the importance of each was calibrated.

3. OLS model: W= [1,46136 0,52955] T

Ei 2 wo + will

1, = 1,46136 + 0,52955 W

0	ya.	72	youn	Yn x Ya	2i = wo + wn ki	
ka	2	2	3,5	4	3,57956	
nz	1	1	1,0	1	1,99091	
113	3	2	3(8	6	4,63866	TRAIN
me ₍	6	3	1011	18	10,99326	
ks-	8	1	8,5	8	5,69776	
u ₆	0	2	110	0	1,46136	
hz	.3	4	612	12	7,81596	711-
ng	5	1	3,6	5	4,10911	TEST
-T.					,	

· Train MAE : 1=5 scorples

$$MA6_{oustean} = \frac{1}{5} (|3,57956-3,5| + |1,99091-1,0| + |4,63866-3,8| + |10,99326-10,1| + |15,69776-8,5|) × 1,12093$$

* Test MAE; n=3 camples

MAEter = 3(11.46136-10)+ 17,81596-6021+ 14,10911-3061) ~ 0,8.62 14

Røge !	model: w	= [0197319 0,56	921]7	1 = 0,97349 + 0,56921 ki	
0	y1 x 92	2;			
KA	4	3,25003			
kz	1	1,54240			
k3	6	4,38845			
My	V.8	11,21897			
k5	8	5,52687			
M6	0	0,97319			
ид	12	7,80371			
kg	5	3,81924			

 $M = \{a(z^0) = \text{sgroid}(z^0) = T(z^0) = \frac{1}{1+e^{-20}} = \begin{cases} 0.62146 \\ 0.64566 \\ 0.66819 \end{cases}$

$$\frac{1}{10} = \frac{1}{10} \cdot \frac{1}{10} = \frac{1}{10} = \frac{1}{10} \cdot \frac{1}{10} = \frac{1}{10} = \frac{1}{10} \cdot \frac{1}{10} = \frac{1}{10}$$

9E = 9E 9E = 80

$$b^{3} = b^{3} - \eta \frac{\partial E}{\partial b^{3}} = b^{3} - \eta \frac{\partial E}{\partial b^{3}} = b^{3} - \eta \frac{\partial E}{\partial b^{3}} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} - 0.5 \begin{bmatrix} -0.43865 \\ 0.272777 \\ 0.15088 \end{bmatrix} = \begin{bmatrix} 1.219.33 \\ 0.175612 \\ 0.18088 \end{bmatrix}$$

$$w^{(2)} = w^{(2)} - \eta \frac{\partial E}{\partial w^{3}} = w^{(3)} - \eta \frac{\partial E}{\partial w^{3}} = \begin{bmatrix} 0.1 \\ 0.1 \end{bmatrix} - 0.5 \begin{bmatrix} 0.272777 \\ 0.03452 \\ 0.29725 \end{bmatrix} = \begin{bmatrix} 0.1 \\ 0.13452 \\ 0.29725 \end{bmatrix}$$

$$b^{(3)} = b^{3} - \eta \frac{\partial E}{\partial w^{3}} = b^{3} - \eta \frac{\partial E}{\partial w^{3}} = \begin{bmatrix} 0.1 \\ 0.1 \end{bmatrix} - 0.5 \begin{bmatrix} 0.02452 \\ -0.09452 \end{bmatrix} = \begin{bmatrix} 0.1 \\ 0.01726 \\ 0.14863 \end{bmatrix}$$

Explanation:

A model with no activation fuction simply outputs a linear combination of its inputs, since each layer only perfecens a linear transformation. As a perult, the arreal model can only represent lipear pelationships and fails to capture more complex, notified patterns in the data.

By contrast, a signoid actuation function introduces renlinearity, enabling the neutral network to learn more complex functions and nonlinear decision boundaries.

Additionally, the signoid function squeezes in futs into the (0,1) range, effectively regularizing the output. This allows the model to interpret the output as a probability, which makes classification more intuitive and the results everier to interpret. The compression effect of the signoid also smooths the influence of extreme inputs, making the model's output more stable and less souther to very large values or even outviers.

Exercise 1

```
X = np.matrix([
       [1, 4],
       [1, 1],
       [1, 6],
       [1, 18],
       [1, 8]
   ])
   z = np.array([3.5, 1, 3.8, 10.1, 8.5])
   # Calculate weights vector
   beta ols = np.linalg.inv(X.T @ X) @ X.T @ z
   beta_ols = np.array(beta_ols).flatten()
   # Extract intercept and slope
   w0, w1 = beta_ols
   print(f"Intercept (w0): {w0:.5f}")
   print(f"Slope (w1): {w1:.5f}")
 ✓ 0.0s
Intercept (w0): 1.46136
Slope (w1): 0.52955
```

Exercise 2