

Homework 3

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1.1 $M_1 = \begin{bmatrix} 1 & 0 & 3 \\ 1 & 1 & 0 \\ 1 & 0 & 3 \end{bmatrix} \rightarrow \det M_1 = 0 \therefore M_1 \text{ is singular}$

1.2 $M_2 = \begin{bmatrix} 1 & 0 & 3 \\ 1 & 1 & 0 \\ 1 & 2 & 1 \end{bmatrix} \rightarrow \det M_2 = 4 \Rightarrow M_2 \text{ is invertible}$

2 Case $n=2$ $M = \begin{bmatrix} a_1 & b_1 \\ 0 & a_2 \end{bmatrix} \Rightarrow \det M = a_1 a_2$

Case $n=3$ $M = \begin{bmatrix} a_1 & \times & b_1 \\ 0 & a_2 & b_2 \\ 0 & 0 & a_3 \end{bmatrix} \Rightarrow \det M = a_1 \begin{vmatrix} a_2 & b_2 \\ 0 & a_3 \end{vmatrix} - \begin{vmatrix} \times & b_1 \\ 0 & a_3 \end{vmatrix} + \begin{vmatrix} \times & b_1 \\ 0 & a_2 \end{vmatrix}$
 $= a_1 \begin{vmatrix} a_2 & b_1 \\ 0 & a_3 \end{vmatrix} = a_1 a_2 a_3$

Continuing we can prove that if

$M = \begin{bmatrix} a_1 & \dots & b_1 \\ 0 & a_2 & \dots & b_2 \\ \dots & \dots & \dots & b_n \\ 0 & \dots & \dots & a_n \end{bmatrix} \Rightarrow \det M = a_1 \begin{bmatrix} a_2 & \dots & b_2 \\ \vdots & \ddots & \vdots \\ 0 & \dots & a_n \end{bmatrix} + \sum 0$
 $= a_1 (a_2 \dots a_n) \text{ (by recursion)}$
 $= a_1 \dots a_n$

Case A $\det A \neq 0$

3. Nonsingular matrix is product of elementary matrices

$$\therefore A = E_1 \dots E_k$$

Lemma: $\det(A.A) = \det(E_1 \dots E_k.A) = \det(E_1) \dots \det(E_k) \det(A)$

Proof: We know,

- 1) If A is a square matrix & B is a matrix obtained by swapping rows or columns of A then $\det(A) = -\det(B)$
- 2) If A is square matrix & B is a matrix obtained by adding a scalar multiple of a row/column to another row/column, then $\det(A) = \det(B)$

Using this $\det(E_k A) = \det(E_k) \det(A)$

$$\begin{aligned} \therefore \det(A.A) &= \det(E_1) \dots \det(E_k) \det(A) \\ &= \det(E_1 \dots E_k) \det(A) = \det(A)^2 \end{aligned}$$

Case 2 $\det A = 0 \Rightarrow A$ is singular $\Rightarrow A.B$ is singular ($\forall B$)
 $\Rightarrow A^2$ is singular $\Rightarrow \det(A^2) = 0 = \det(A)$

4) Using 1) & 2) from lemma above, any square matrix A can be transformed into a UTH such that $\det(A) = \det(M) = m_1 \dots m_n$ where $M = \begin{pmatrix} m_1 & & 0 \\ & \ddots & \\ 0 & & m_n \end{pmatrix}$

Using the same transformation

$$\begin{aligned} \det(2A) &= \det(2M) = (2m_1) \dots (2m_n) \\ &= 2^n (m_1 \dots m_n) = 2^n \det(A) \end{aligned}$$

5. $A \cdot x = \lambda \cdot x$

$$A^2 \cdot x = A \cdot (A \cdot x) = A(\lambda x) = \lambda(A \cdot x) = \lambda(\lambda \cdot x) = \lambda^2 \cdot x$$

\therefore eigenvalues of A^2 are λ^2 & eigenvectors are x .

6. $Q^T = Q^{-1}$ let $Q = \begin{bmatrix} q_{11} & \dots & q_{1n} \\ \vdots & & \vdots \\ q_{m1} & \dots & q_{mn} \end{bmatrix}$

$$(QQ^T)_{ij} = \sum_{k=1}^m q_{ik} q_{kj}$$

(1) $\|q_i\|^2 = \sum_{j=1}^m (QQ^T)_{ij} = \sum_{j=1}^m I_{ij} = 1$

2) $q_i^T q_j = \sum_{k=1}^m q_{ik} q_{kj} = (QQ^T)_{ij} = I_{ij} = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$

Since given $i \neq j \Rightarrow q_i^T q_j = 0$

3) $Q = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \quad QQ^T = \begin{bmatrix} \cos^2 \theta + \sin^2 \theta & 0 \\ 0 & \cos^2 \theta + \sin^2 \theta \end{bmatrix}$

$$= I_2$$

$$7. \quad M = \begin{bmatrix} 0.3 & 0.5 & 0.1 \\ 0.3 & 0.4 & 0.2 \\ 0.4 & 0.1 & 0.7 \end{bmatrix}$$

$$\begin{bmatrix} x & y & z \end{bmatrix} \begin{bmatrix} 0.3 & 0.5 & 0.1 \\ 0.3 & 0.4 & 0.2 \\ 0.4 & 0.1 & 0.7 \end{bmatrix} = \begin{bmatrix} x & y & z \end{bmatrix}$$

$$x + y + z = 1$$

$$0.3x + 0.3y + 0.4z = x$$

$$0.5x + 0.4y + 0.1z = y$$

$$0.1x + 0.2y + 0.7z = z$$

$$\Rightarrow 3x + 3y + 4z = 10x \Rightarrow 7x - 3y - 4z = 0$$

$$5x + 4y + z = 10y \Rightarrow 5x - 6y + z = 0$$

$$x + 2y + 7z = 10z \Rightarrow x + 2y - 3z = 0$$

$$\Rightarrow 35x - 18y + 3z = 0$$

$$16x - 16y = 0$$

$$\Rightarrow x = y$$

$$-y + z = 0 \Rightarrow y = z$$

$$x = y = z = \frac{1}{3}$$

\therefore Steady state of M is $\left[\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right]$

$$8. \quad M = \begin{vmatrix} 4 & 3 & 2 \\ 1 & 2 & 6 \\ 5 & 8 & 1 \end{vmatrix}$$

$$\begin{vmatrix} 4-\lambda & 3 & 2 \\ 1 & 2-\lambda & 6 \\ 5 & 8 & 1-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (4-\lambda) \begin{vmatrix} 2-\lambda & 6 \\ 8 & 1-\lambda \end{vmatrix} - 3 \begin{vmatrix} 1 & 6 \\ 5 & 1-\lambda \end{vmatrix} + 2 \begin{vmatrix} 1 & 2-\lambda \\ 5 & 8 \end{vmatrix}$$

$$\Rightarrow 4-\lambda \left[(2-\lambda)(1-\lambda) - 48 \right] - 3(1-\lambda - 30) + 2(8 - 5(2-\lambda))$$

$$= (4-\lambda) \left[2 - 3\lambda + \lambda^2 - 48 \right] - 3(1-\lambda - 30) + 2(8 - 10 + 5\lambda)$$

$$= 8 - 2\lambda - 12\lambda + 3\lambda^2 + 4\lambda^2 - \lambda^3 - 84 + 42\lambda - 3 + 3\lambda + 90$$

$$+16 - 20 + 10\lambda$$

$$\Rightarrow -\lambda^3 + 7\lambda^2 + 47\lambda - 101$$

$$\lambda = \begin{cases} 1.792828 \\ -5.34086 \\ 10.548032 \end{cases}$$

Case 1 $\lambda = 1.792828$

The equations are

$$\begin{aligned} 4x_1 + 3x_2 + 2x_3 &= 1.7928x_1 \\ x_1 + 2x_2 + 6x_3 &= 1.79 \dots x_2 \\ 5x_1 + 8x_2 + x_3 &= 1.79 \dots x_3 \end{aligned}$$

This corresponds to

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -0.548449 \\ -0.53469985 \\ -0.63554801 \end{bmatrix}$$

Case 2

$$\lambda = -5.34086$$

$$\begin{bmatrix} -0.69903638 \\ 0.18092837 \\ 0.7710746 \end{bmatrix}$$

Case 3

$$\lambda = 10.548032$$

$$\begin{bmatrix} -0.46313273 \\ -0.83634467 \\ 0.03902155 \end{bmatrix}$$