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MIE1624H – Introduction to Data Science and Analytics Lecture 4 – Linear Algebra and Matrix Computations

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Lecture outline

Matrix computations

- Matrix operations
- Computing determinants and eigenvalues

Linear algebra

- Solving systems of linear equations
- Solving non-linear equations (Bisection method, Newton's method)
- Solving systems of non-linear equations
- Solving unconstrained non-linear optimization problems

Derivatives

- Gradients and Hessians
- Taylor series expansion

Functions and convexity

- Convex and concave functions
- Checking convexity
- Properties of convex functions

Systems of linear equations

System of linear equations

$$3 \cdot x_1 + 8 \cdot x_2 = 46$$

$$10 \cdot x_1 - 7 \cdot x_2 = -15$$

■ To solve this system of equations we express one of the variables through the other from one of the equations and plug into the other equation:

$$x_2 = \frac{46 - 3 \cdot x_1}{8}$$

$$10 \cdot x_1 - 7 \cdot \frac{46 - 3 \cdot x_1}{8} = -1.5$$

- Therefore $x_1 = 2, x_2 = 5$
- Matrix notation:

$$A = \begin{pmatrix} 3 & 8 \\ 10 & -7 \end{pmatrix}, \quad \boldsymbol{b} = \begin{pmatrix} 46 \\ -15 \end{pmatrix}, \quad \boldsymbol{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

System of linear equations in matrix form:

$$A \cdot \boldsymbol{x} = \boldsymbol{b}$$

Gaussian elimination

Gaussian elimination

System of equations	Row operations	Augmented matrix
2x + y - z = 8 $-3x - y + 2z = -11$ $-2x + y + 2z = -3$		$\left[\begin{array}{ccc ccc} 2 & 1 & -1 & 8 \\ -3 & -1 & 2 & -11 \\ -2 & 1 & 2 & -3 \end{array}\right]$
$2x + y - z = 8$ $\frac{1}{2}y + \frac{1}{2}z = 1$ $2y + z = 5$	$egin{aligned} L_2+rac{3}{2}L_1 ightarrow L_2 \ L_3+L_1 ightarrow L_3 \end{aligned}$	$\left[\begin{array}{ccc c} 2 & 1 & -1 & 8 \\ 0 & 1/2 & 1/2 & 1 \\ 0 & 2 & 1 & 5 \end{array}\right]$
$2x + y - z = 8$ $\frac{1}{2}y + \frac{1}{2}z = 1$ $-z = 1$	$L_3 + -4L_2 ightarrow L_3$	$\left[\begin{array}{ccc c} 2 & 1 & -1 & 8 \\ 0 & 1/2 & 1/2 & 1 \\ 0 & 0 & -1 & 1 \end{array}\right]$

The matrix is now in echelon form (also called triangular form)

Back substitution